

Lecture Note of Innovative Ship and Offshore Plant Design

# Innovative Ship and Offshore Plant Design

## Part I. Ship Design

### Ch. 10 Structural Design

Spring 2019

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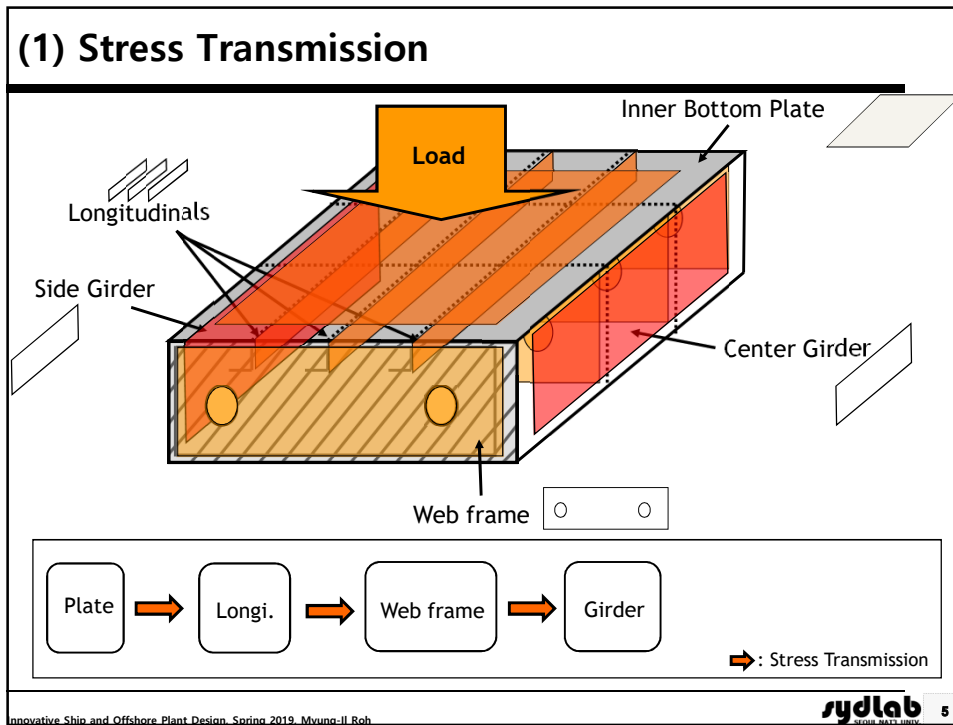
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## Ch. 10 Structural Design

## 1. General & Materials

- (1) Stress Transmission
- (2) Principal Dimensions
- (3) Criteria for the Selection of Plate Thickness,  
Grouping of Longitudinal Stiffener
- (4) Material Factors



### (2) Principal Dimensions

DNV Rules, Jan. 2004, Pt. 3 Ch. 1 Sec. 1 101

The following principal dimensions are used in accordance with DNV rule.

#### 1) Rule length (L or L<sub>s</sub>)

: Length of a ship used for rule scantling procedure

$$0.96 \cdot L_{WL} < L < 0.97 \cdot L_{WL}$$

- Distance on the summer load waterline ( $L_{WL}$ ) from the fore side of the stem to the axis of the rudder stock
- Not to be taken less than 96%, and need not be taken greater than 97%, of the extreme length on the summer load waterline ( $L_{WL}$ )
- Starting point of rule length: F.P

Ex.

	$L_{BP}$	$L_{WL}$	$0.96 \cdot L_{WL}$	$0.97 \cdot L_{WL}$	L
	250	261	250.56	253.17	250.56
	250	258	247.68	250.26	250.00
	250	255	244.80	247.35	247.35

#### 2) Breadth

: Greatest moulded breadth in [m], measured at the summer load waterline

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**(DNV Pt.3 Ch.1 Sec.1 B101), 2011****B. Definitions****B 100 Symbols**

101 The following symbols are used:

L = length of the ship in m defined as the distance on the summer load waterline from the fore side of the stem to the axis of the rudder stock.

L shall not be taken less than 96%, and need not to be taken greater than 97%, of the extreme length on the summer load waterline. For ships with unusual stern and bow arrangement, the length L will be especially considered.

F.P. = the forward perpendicular is the perpendicular at the intersection of the summer load waterline with the fore side of the stem. For ships with unusual bow arrangements the position of the F.P. will be especially considered.

A.P. = the after perpendicular is the perpendicular at the after end of the length L.

L<sub>F</sub> = length of the ship as defined in the International Convention of Load Lines:

The length shall be taken as 96 per cent of the total length on a waterline at 85 per cent of the least moulded depth measured from the top of the keel, or as the length from the fore side of the stem to the axis of the rudder stock on that waterline, if that be greater. In ships designed with a rake of keel the waterline on which this length is measured shall be parallel to the designed waterline.

B = greatest moulded breadth in m, measured at the summer waterline.

D = moulded depth defined as the vertical distance in m from baseline to moulded deckline at the uppermost continuous deck measured amidships.

D<sub>F</sub> = least moulded depth taken as the vertical distance in m from the top of the keel to the top of the freeboard deck beam at side.

In ships having rounded gunwales, the moulded depth shall be measured to the point of intersection of the moulded lines of the deck and side shell plating, the lines extending as though the gunwale was of angular design.

Where the freeboard deck is stepped and the raised part of the deck extends over the point at which the moulded depth shall be determined, the moulded depth shall be measured to a line of reference

**(DNV Pt.3 Ch.1 Sec.1 B101), 2011**

extending from the lower part of the deck along a line parallel with the raised part.

T = mean moulded summer draught in m.

Δ = moulded displacement in t in salt water (density 1.025 t/m<sup>3</sup>) on draught T.

C<sub>B</sub> = block coefficient,

$$= \frac{\Delta}{1.025 L B T}$$

For barge rigidly connected to a push-tug C<sub>B</sub> shall be calculated for the combination barge/ push-tug.

C<sub>BF</sub> = block coefficient as defined in the International Convention of Load Lines:

$$= \frac{\nabla}{L_F B T_F}$$

∇ = volume of the moulded displacement, excluding bossings, taken at the moulded draught T<sub>F</sub>.

T<sub>F</sub> = 85% of the least moulded depth.

V = maximum service speed in knots, defined as the greatest speed which the ship is designed to maintain in service at her deepest seagoing draught.

g<sub>0</sub> = standard acceleration of gravity

= 9.81 m/s<sup>2</sup>.

f<sub>1</sub> = material factor depending on material strength group. See Sec.2.

f<sub>k</sub> = corrosion addition as given in Sec.2 D200 and D300, as relevant.

x = axis in the ship's longitudinal direction.

y = axis in the ship's athwartships direction.

z = axis in the ship's vertical direction.

E = modulus of elasticity of the material

= 2.06 · 10<sup>5</sup> N/mm<sup>2</sup> for steel

= 0.69 · 10<sup>5</sup> N/mm<sup>2</sup> for aluminium alloy.

C<sub>w</sub> = wave load coefficient given in Sec.4 B200.

Amidships = the middle of the length L.

DNV Rules, Jan. 2004, Pt. 3 Ch. 1 Sec. 1 101

## (2) Principal Dimensions

### 3) Depth (D)

: Moulded depth defined as the vertical distance in [m] from baseline to moulded deck line at the uppermost continuous deck measured amidships

### 4) Draft (T)

: Mean moulded summer draft (**scantling draft**) in [m]

### 5) Brock coefficient ( $C_B$ )

: To be calculated based on the rule length

$$C_B = \frac{\Delta}{1.025 \cdot L \cdot B \cdot T} \quad , (\Delta : \text{moulded displacement in salt water on draft } T)$$

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DNV Rules, Jan. 2004, Pt. 3 Ch. 1 Sec. 1 101

## (3) Criteria for the Selection of Plate Thickness, Grouping of Longitudinal Stiffener

### 1) Criteria for the selection of plate thickness

➔ When selecting plate thickness, use the provided plate thickness.

<p>(1) 0.5 mm interval</p> <p>(2) Above 0.25 mm: 0.5 mm</p> <p>(3) Below 0.25 mm: 0.0 mm</p>	<p>Ex) 15.75 mm ➔ 16.0 mm</p> <p>15.74 mm ➔ 15.5 mm</p>
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### 2) Grouping of longitudinal stiffener

For the efficiency of productivity, each member is arranged by grouping longitudinal stiffeners. The grouping members should satisfy the following rule.

Average value but not to be taken less than 90% of the largest individual requirement (DNV).

Ex) The longitudinal stiffeners have design thickness of 100, 90, 80, 70, 60 mm. The average thickness is given by  $80 \text{ mm} \times 5$ . However, the average value is less than  $100 \text{ mm} \times 90\% = 90 \text{ mm}$  of the largest individual requirement, 100 mm. Therefore, the average value should be taken  $90 \text{ mm} \times 5$ .

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## (4) Material Factors

<sup>1)</sup> DNV Rules, Jan. 2004, Pt. 3 Ch. 1 Sec.2

<sup>2)</sup> James M. Gere, Mechanics of Materials 7th Edition, Thomson, Chap.1, pp.15~26

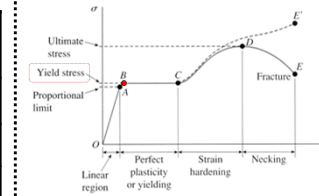
- The material factor  $f_1$  is included in the various formulae for scantlings and in expressions giving allowable stresses.<sup>1)</sup>

Material Designation	Yield Stress (N/mm <sup>2</sup> )	$\frac{\sigma}{\sigma_{NV-NS}}$	Material Factor ( $f_1$ )
NV-NS	235	235/235 = 1.00	1.00
NV-27	265	265/235 = 1.13	1.08
NV-32	315	315/235 = 1.34	1.28
NV-36	355	355/235 = 1.51	1.39
NV-40	390	390/235 = 1.65	1.47

\* NV-NS: Normal Strength Steel (Mild Steel)

\* NV-XX: High Tensile Steel

\* High tensile steel: A type of alloy steel that provides better mechanical properties or greater resistance to corrosion than carbon steel. They have a carbon content between 0.05-0.25% to retain formability and weldability, including up to 2.0% manganese, and other elements are added for strengthening purposes.



\* Yield Stress ( $\sigma_y$ ) [N/mm<sup>2</sup>] or [MPa]: The magnitude of the load required to cause yielding in the beam.<sup>2)</sup>

\* A: 'A' grade 'Normal Strength Steel'

\* AH: 'A' grade 'High Tensile Steel'

## 2. Global Hull Girder Strength (Longitudinal Strength)

- Generals
- Still Water Bending Moment ( $M_s$ )
- Vertical Wave Bending Moment ( $M_w$ )
- Section Modulus

## Interest of "Ship Structural Design"

### • Ship Structural Design



What is designer's **major** interest?

#### • Safety:

*Won't it fail under the load?*

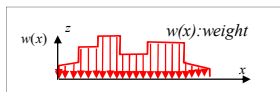


Let's consider the safety of the ship from the point of global strength first.

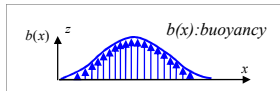
## Dominant Forces Acting on a Ship



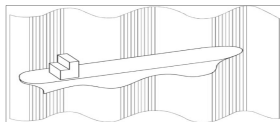
What are dominant forces acting on a ship in view of the longi. strength?



weight of light ship, weight of cargo, and consumables



hydrostatic force (buoyancy) on the submerged hull

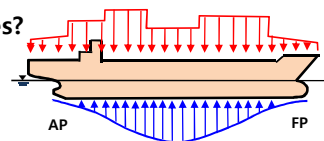


hydrodynamic force induced by the wave



What is the direction of the dominant forces?

The forces act in **vertical (lateral)** direction along the ship's length.



## Longitudinal Strength

: Overall strength of ship's hull which **resists** the bending moment, shear force, and torsional moment acting on a hull girder.

### Longitudinal strength loads

: Load concerning the overall strength of the ship's hull, such as the bending moment, shear force, and torsional moment acting on a hull girder

#### longitudinal loads



Loads are caused by  
in longitudinal direction in the still water  
condition

#### longitudinal loads



Loads are induced by

<sup>1)</sup> Okumoto, Y., Design of Ship Hull Structures, Springer, 2009, P.17

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## Idealization of the Ship Hull Girder Structure



How can we idealize a ship as a structural member?

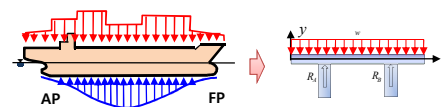
### Structural member according to the types of loads

- ① **Axially loaded bar**: structural member which supports forces directed along the axis of the bar
- ② **Bar in torsion**: structural member which supports torques (or couples) having their moment about the longitudinal axis
- ③ **Beam**: structural members subjected to **lateral loads**, that is, forces or moments perpendicular to the axis of the bar

Since a ship has a **slender shape** and **subject to lateral loads**, it will behave like a **beam** from the point view of structural member.



Ship is regarded as a



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## Applying Beam Theory to a Ship

If there are supports at the ends, deflection and slope of the beam occur.

Idealize

Actually, there are no supports at the ends of the ship. However, the deflection and slope could occur due to inequality of the buoyancy and the weight of a ship. For this problem, we assume that there are simple supports at the A.P and the F.P.

\* James M. Gere, Mechanics of Materials, 6th Edition, Thomson, Ch. 4, p. 292

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## Correction of a Bending Moment Curve

What if the bending moment is not zero at FP?  
 ➔ The deflection and slope of the beam occur at FP.  
 ➔ Thus, we correct the bending moment curve to have 0 at AP and FP.

\* James M. Gere, Mechanics of Materials, 6th Edition, Thomson, Ch. 4, p. 292

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## Actual Stress $\leq$ Allowable Stress - Bending Stress and Allowable Bending Stress

1) DNV Rules, Pt. 3 Ch. 1 Sec. 5, Jan. 2004

The  $(\sigma_{act.})$  shall not be greater than the  $(\sigma_l)$ .

$M_S$  : Largest SWBM among all loading conditions and class rule

$M_W$  : Calculated by class rule or direct calculation

$$\sigma_{act.} = \frac{|M_S + M_W|}{Z} 10^3 \text{ [kg / cm}^2\text{]}$$

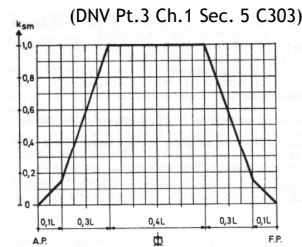


Fig. 2  
Stillwater bending moment

$$\sigma_l = \sigma_{allow} = 175 f_1 \text{ [N / mm}^2\text{]} \text{ within 0.4L amidship}$$

$$= 125 f_1 \text{ [N / mm}^2\text{]} \text{ within 0.1L from A.P. or F.P.}$$

( $f_1$ : Material factor. Ex. Mild steel 1.0, HT-32 1.28, HT-36 1.39)

## (DNV Pt.3 Ch.1 Sec.5 C303), 2011

303 The section modulus requirements about the transverse neutral axis based on cargo and ballast conditions are given by:

$$Z_O = \frac{|M_S + M_W|}{\sigma_l} 10^3 \text{ (cm}^3\text{)}$$

$$\sigma_l = 175 f_1 \text{ N/mm}^2 \text{ within 0.4 L amidship}$$

$$= 125 f_1 \text{ N/mm}^2 \text{ within 0.1 L from A.P. or F.P.}$$

Between specified positions  $\sigma_l$  shall be varied linearly.

**(DNV Pt.3 Ch.1 Sec.5 C304), 2011**

304 The midship section modulus about the vertical neutral axis (centre line) is normally not to be less than:

$$Z_{OH} = \frac{5}{f_1} L^{9/4} (T + 0.3B) C_B \quad (\text{cm}^3)$$

The above requirement may be disregarded provided the combined effects of vertical and horizontal bending stresses at bilge and deck corners are proved to be within  $195 f_1 \text{ N/mm}^2$ .

The combined effect may be taken as:

$$\sigma_s + \sqrt{\sigma_w^2 + \sigma_{wh}^2}$$

$\sigma_s$  = stress due to  $M_S$

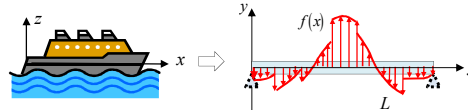
$\sigma_w$  = stress due to  $M_W$

$\sigma_{wh}$  = stress due to  $M_{WH}$ , the horizontal wave bending moment as given in B205.

**Criteria of Structural Design (1/2)**

● Ship Structural Design

a ship



The **actual bending stress** ( $\sigma_{act.}$ ) shall not be greater than the **allowable bending stress** ( $\sigma_l$ ).

$$\sigma_{act.} \leq \sigma_l, \quad \sigma_{act.} = \frac{M}{I_{N.A.}/y} = \frac{|M_S + M_W|}{I_{N.A.}/y}$$

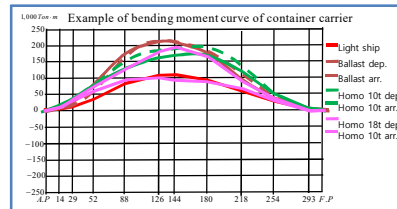
$M_S$ : Largest SWBM among all loading conditions and class rule  
 $M_W$ : WWBM calculated by class rule or direct calculation

$\sigma_l$ : allowable stress

For instance, allowable bending stresses by DNV rule are given as follows:

$$\sigma_l = 175 f_1 \quad [N/mm^2] \quad \text{within } 0.4L \text{ amidship}$$

$$= 125 f_1 \quad [N/mm^2] \quad \text{within } 0.1L \text{ from A.P. or F.P.}$$



Actual bending moments at aft and forward area are smaller than that at the midship.

What is, then, the  $f_1$ ?

## Criteria of Structural Design (2/2)

$$\sigma_{act.} \leq \sigma_l$$

$$\sigma_{act.} = \frac{M}{I_{N.A} / y} = \frac{|M_S + M_W|}{I_{N.A} / y}$$

- (1) Still Water Bending Moment ( $M_S$ )
- (2) Vertical Wave Bending Moment ( $M_W$ )
- (3) Section Modulus ( $I_{N.A}/y$ )

## (1) Still Water Bending Moment ( $M_S$ )

## Still Water Bending Moment (Ms)

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$\sigma_{act.} \leq \sigma_l$

$\sigma_{act.} = \frac{M}{I_{N.A.} / y} = \frac{M_S + M_W}{I_{N.A.} / y}$

$\left\{ \begin{array}{l} M_S: \text{ Still water bending moment} \\ M_W: \text{ Vertical wave bending moment} \end{array} \right.$

---

**Hydrostatic loads along ship's length**  
 caused by the weight & the buoyancy

STATIC HEAVE FORCE COMPONENTS  
 WAVE CREST AMIDSHIPS  
 LBP = 520 ft, T = 10 s, h<sub>w</sub> = 20 ft

$f_s(x)$  : distributed loads in longitudinal direction in still water  
 $\downarrow$   
 $V_s(x)$  : still water shear force  
 $V_s(x) = \int_0^x f_s(x) dx$   
 $\downarrow$   
 $M_s(x)$  : still water bending moment  
 $M_s(x) = \int_0^x V_s(x) dx$

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## Distributed Loads in Longitudinal Direction

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$f(x) = f_s(x) + f_w(x)$

$f(x)$ : Distributed loads in longitudinal direction

$f_s(x)$ : **Static longitudinal loads** in longitudinal direction

$f_w(x)$ : **Hydrodynamic longitudinal loads** induced by wave

**In still water**

$f_s(x) = b(x) + w(x)$

+

=

:

$f_s(x) = b(x) + w(x)$  : Load

$b(x)$ : Distributed buoyancy in longitudinal direction  
 $w(x) = LWT(x) + DWT(x)$   
 -  $w(x)$ : Weight distribution in longitudinal direction  
 -  $LWT(x)$ : Lightweight distribution  
 -  $DWT(x)$ : Deadweight distribution

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### Distributed Loads in Still Water

Load Curve,  $f_s(x)$  → Actual Still Water Shear Force,  $V_s(x)$  → Actual Still Water Bending Moment,  $M_s(x)$   
 $V_s(x) = \int_0^x f_s(x) dx$       $M_s(x) = \int_0^x V_s(x) dx$

Weight,  $w(x)$   
 Buoyancy,  $b(x)$

✓ Example of a 3,700 TEU Container Ship in Homogeneous 10 ton Scantling Condition

- Principal Dimensions & Plans

Principal dimension	
LENGTH O. A.	257.368 M
LENGTH B. P.	245.240 M
BREADTH MOULDED	32.20 M
DEPTH MOULDED	19.30 M
DESIGNED DRAUGHT MOULDED	10.10 M
SCANTLING DRAUGHT MOULDED	12.60 M

- Loading Condition: Homogeneous 10 ton Scantling Condition (Sailing state)

SAILING STATE		* Frame space: 800mm	
DRAUGHT F.P.	= 12.260 M	K.M.T.	= 14.889 M
DRAUGHT MIDSHIP	= 12.457 M	KG (SOLID)	= 13.586 M
DRAUGHT A.P.	= 12.654 M	GM (SOLID)	= 1.303 M
TRIM BY STEAM	= .394 M	FREE SURF CORR. (GG0)	= .059 M
PROPELLER T/D	= 160.3 %	G0M (FLUID)	= 1.244 M
DISPLACEMENT	= 66813.6 T	KG0 ACTUAL (FLUID)	= 13.645 M
DRAUGHT AT LCF	= 12.483 M	TRIM (DIS*) / (MTC*100)	= .394 M
LCB FROM A.P.	= 115.677 M	FREE SURF. MOM.	= 3921 T-M
LCG FROM A.P.	= 115.045 M	M.T.C.	= 1072.0 T-M
TRIM LEVER : A	= 632 M	LCF FROM A.P.	= 106.275 M
DEGREE	= 0    5.0    10.0    15.0    20.0    30.0    40.0    50.0    60.0    75.0		
KN	= 0.00    1.296    2.591    3.882    5.168    6.454    7.740    9.026    10.312    11.598		
KG0xSIN0	= 0.00    1.189    2.369    3.532    4.667    5.802    6.937    8.072    9.207    10.342		
GZ	= 0.00    .107    .222    .350    .501    .671    .821    .972    1.123    1.274		

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### Distributed Loads in Still Water - Lightweight

Load Curve,  $f_s(x)$  → Actual Still Water Shear Force,  $V_s(x)$  → Actual Still Water Bending Moment,  $M_s(x)$   
 $V_s(x) = \int_0^x f_s(x) dx$       $M_s(x) = \int_0^x V_s(x) dx$

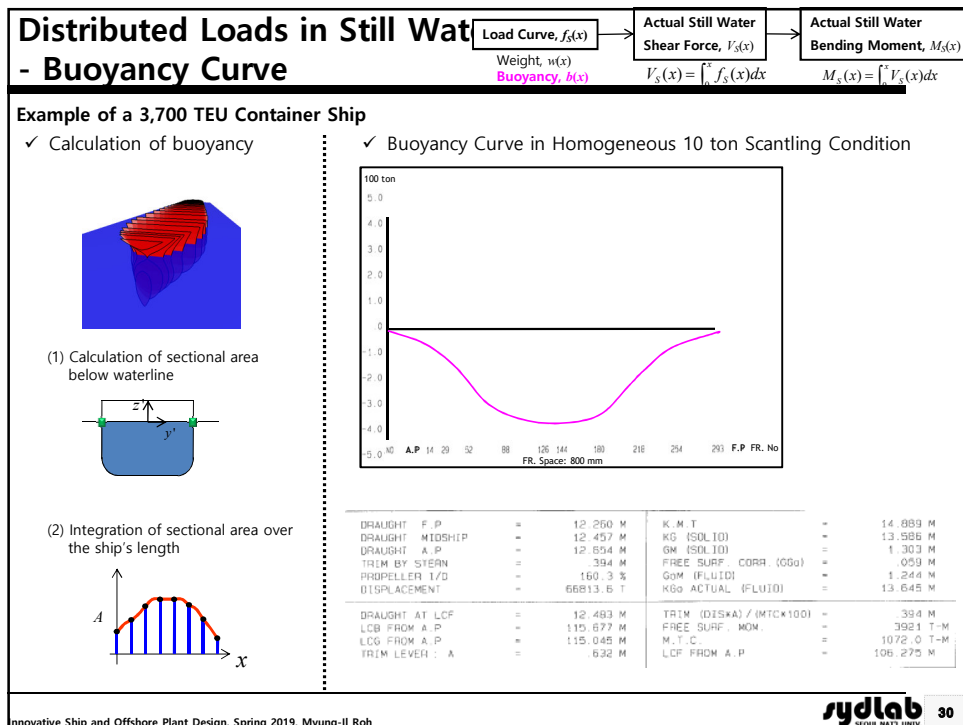
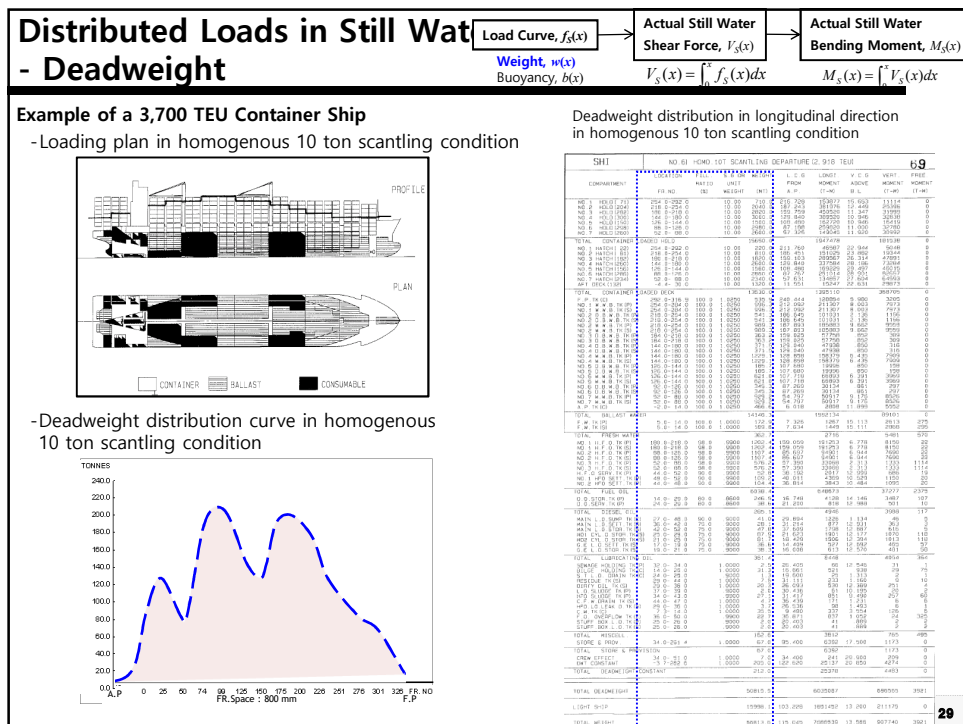
Weight,  $w(x)$   
Buoyancy,  $b(x)$

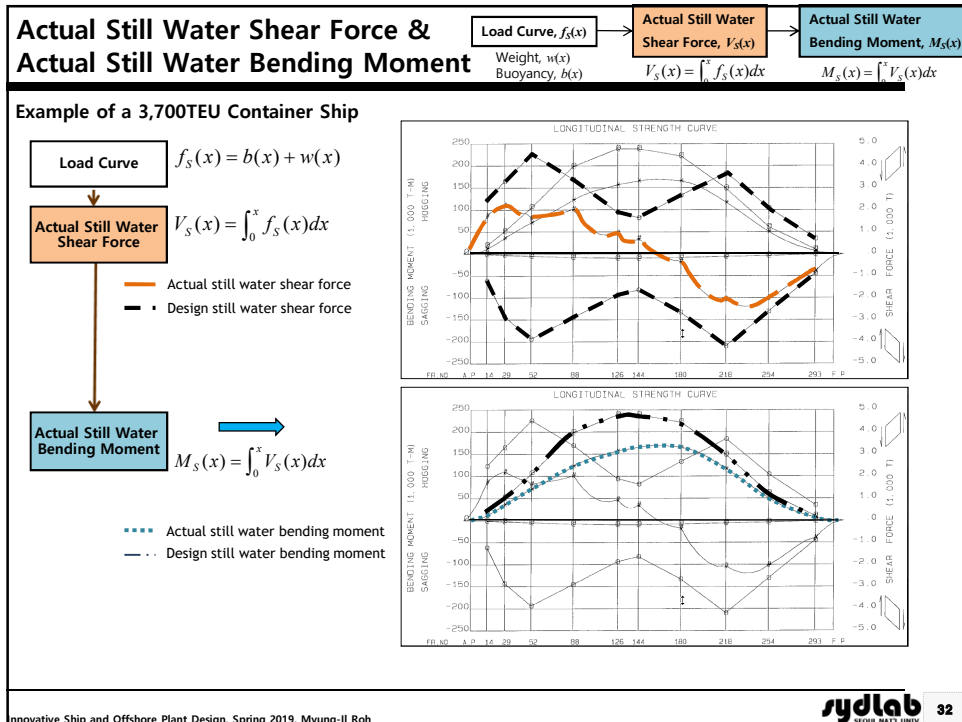
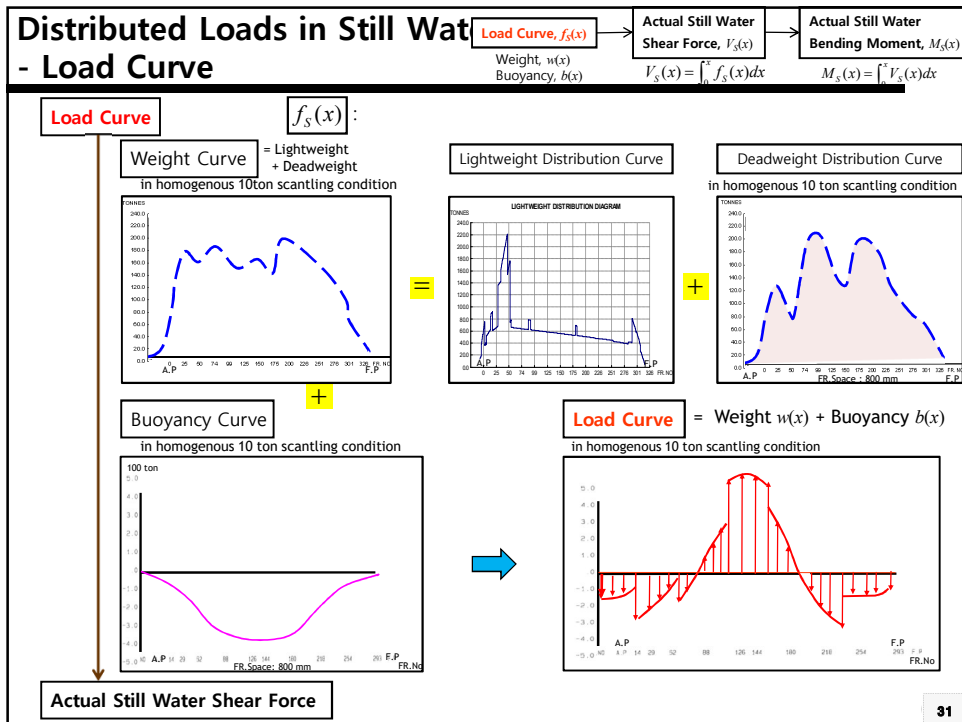
Example of a 3,700 TEU Container Ship

LIGHT WEIGHT SUMMARY

Hull No. :	1329, 3,700 TEU CONTAINER VESSEL					
NO	AFT END	FORE END	WEIGHT	L.C.C	MOMENT	
1	-5.000	14.350	616.00	7.000	4312.0	
2	14.350	43.400	1387.10	31.400	43554.9	
3	43.400	232.320	7591.50	128.620	976418.7	
4	232.320	252.240	732.30	239.280	175224.7	
5	27.200	41.600	476.40	35.800	17055.1	
6	5.000	245.240	30.00	122.620	3678.6	
7	43.400	232.320	340.00	134.200	45628.0	
8	-3.600	232.320	119.00	114.400	13613.6	
9	-3.450	2.400	151.90	.000	.000	
10	.000	252.240	224.00	120.000	26880.0	
11	202.240	232.320	137.90	217.000	29924.3	
12	43.400	202.240	1053.00	121.700	128150.1	
13	143.280	146.680	55.00	144.980	7973.9	
14	70.480	73.880	55.00	72.180	3969.9	
15	14.350	232.320	115.90	114.360	13254.3	
16	-3.600	232.320	128.00	114.360	14638.1	
17	232.320	245.240	118.30	238.600	28226.4	
18	36.000	170.000	3.00	81.000	243.0	
19	-5.000	4.000	50.00	-5.000	-25.0	
20	29.000	41.600	15.50	37.100	575.0	
21	-3.500	4.000	19.20	.000	.0	
22	4.000	11.200	34.30	7.600	260.7	
23	41.600	173.900	62.50	105.760	6610.0	
24	226.160	232.320	20.40	229.240	4676.5	
25	239.000	243.000	5.40	241.000	1301.4	
26	11.200	232.320	39.20	121.700	4770.6	
27	11.200	232.320	191.30	121.700	32381.2	
28	27.200	41.600	214.50	36.000	7722.0	
29	23.230	37.600	979.00	30.400	29761.6	
30	11.200	41.600	289.50	22.000	6369.0	
31	5.000	23.230	111.30	11.200	1246.6	
32	12.000	41.600	150.70	28.000	4219.6	
33	11.200	41.600	158.60	28.000	4440.8	
34	11.200	41.600	95.90	28.000	2685.2	
35	11.200	218.480	165.00	114.240	18849.6	
36	27.200	41.600	8.50	36.000	306.0	
37	11.200	41.600	43.00	30.000	1290.0	
38	27.200	41.600	4.30	36.000	154.8	
39	27.200	41.600	5.70	36.000	205.2	
LIGHT SHIP TOTAL =			15998.10	103.228	1651446.5	

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## Rule Still Water Bending Moment by the Classification Rule

Recently, **actual still water bending moment based on the loading conditions is used** for still water bending moment, because the rule still water bending moment is only for the tanker.

- The **design still water bending moments** to be taken less than

$$M_S = M_{SO} \text{ [kNm]} \quad (\text{rule still water bending moment}) \quad (\text{DNV Pt. 3 Ch. 1 Sec. 5 A105})$$

$$M_{SO} = -0.065 C_{WU} L^2 B (C_B + 0.7) \quad \text{[kNm] in sagging}$$

$$= C_{WU} L^2 B (0.1225 - 0.015 C_B) \quad \text{[kNm] in hogging}$$

$C_{WU}$ : Wave coefficient for unrestricted service

The design still water bending moment **shall not be less than the large of**: the **largest actual still water bending moment based on the loading conditions** and the **rule still water bending moment**.

$$\text{Design SWBM} = \text{Max}(\text{Actual SWBM, Rule SWBM}) + \text{margin}$$

## (DNV Pt.3 Ch.1 Sec. 5 A106), 2011

106 The design stillwater bending moments amidships (sagging and hogging) are normally not to be taken less than:

$$M_S = M_{SO} \text{ (kNm)}$$

$$M_{SO} = -0.065 C_{WU} L^2 B (C_B + 0.7) \text{ (kNm) in sagging}$$

$$= C_{WU} L^2 B (0.1225 - 0.015 C_B) \text{ (kNm) in hogging}$$

$C_{WU} = C_W$  for unrestricted service.

Larger values of  $M_{SO}$  based on cargo and ballast conditions shall be applied when relevant, see 102.

For ships with arrangement giving small possibilities for variation of the distribution of cargo and ballast,  $M_{SO}$  may be dispensed with as design basis.

## (DNV Pt.3 Ch.1 Sec. 5 B107), 2011

107 When required in connection with stress analysis or buckling control, the stillwater bending moments at arbitrary positions along the length of the ship are normally not to be taken less than:

$$M_S = k_{sm} M_{SO} \quad (\text{kNm})$$

$M_{SO}$  = as given in 106

$k_{sm}$  = 1.0 within 0.4 L amidships  
 = 0.15 at 0.1 L from A.P. or F.P.  
 = 0.0 at A.P. and F.P.

Between specified positions  $k_{sm}$  shall be varied linearly.

Values of  $k_{sm}$  may also be obtained from Fig.3.

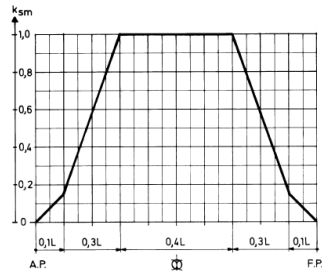


Fig. 3  
Stillwater bending moment

The extent of the constant design bending moments amidships may be adjusted after special consideration.

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## Rule Still Water Shear Force by the Classification Rule

• The **design values of still water shear forces** along the length of the ship are normally not to be taken less than

(Dnv Pt.3 Ch.1 Sec. 5 B107)

$$Q_S = k_{sq} Q_{SO} \quad (\text{kN})$$

$$Q_{SO} = 5 \frac{M_{SO}}{L} \quad (\text{kN})$$

$k_{sq}$  = 0 at A.P. and F.P.  
 = 1.0 between 0.15L and 0.3L from A.P.  
 = 0.8 between 0.4L and 0.6L from A.P.  
 = 1.0 between 0.7L and 0.85L from A.P.

$M_{SO} = -0.065 C_{wU} L^2 B (C_B + 0.7)$  [kNm] in sagging  
 =  $C_{wU} L^2 B (0.1225 - 0.015 C_B)$  [kNm] in hogging

$C_{wU}$ : wave coefficient for unrestricted service

The design still water shear force shall not be less than the large of: the largest actual still water shear forces based on loading conditions and the rule still water shear force.

$$\text{Design SWSF} = \text{Max}(\text{Actual SWSF, Rule SWSF}) + \text{margin}$$

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## (DNV Pt.3 Ch.1 Sec. 5 B108), 2011

**108** The design values of stillwater shear forces along the length of the ship are normally not to be taken less than:

$$Q_S = k_{sq} Q_{SO} \quad (\text{kN})$$

$$Q_{SO} = 5 \frac{M_{SO}}{L} \quad (\text{kN})$$

$M_{SO}$  = design stillwater bending moments (sagging or hogging) given in 106.

Larger values of  $Q_S$  based on load conditions ( $Q_S = Q_{SL}$ ) shall be applied when relevant, see 102. For ships with arrangement giving small possibilities for variation in the distribution of cargo and ballast,  $Q_{SO}$  may be dispensed with as design basis

$k_{sq} = 0$  at A.P. and F.P.

= 1.0 between 0.15 L and 0.3 L from A.P.

= 0.8 between 0.4 L and 0.6 L from A.P.

= 1.0 between 0.7 L and 0.85 L from A.P.

Between specified positions  $k_{sq}$  shall be varied linearly.

Sign convention to be applied:

- when sagging condition positive in forebody, negative in afterbody
- when hogging condition negative in forebody, positive in afterbody.

## (2) Vertical Wave Bending Moment (Mw)

## Vertical Wave Bending Moment (M<sub>w</sub>)

$$\sigma_{act.} \leq \sigma_l, \quad \sigma_{act.} = \frac{M}{Z} = \frac{M_s + M_w}{Z}$$

$M_s$ : Still water bending moment  
 $M_w$ : Vertical wave bending moment

**Hydrodynamic loads induced by waves along ship's length**

$f_w(x)$  : distributed loads induced by waves  
 = Froude-Krylov force + diffraction force  
 + added mass force + damping force

$$M\ddot{r} = \sum F = (Body\ Force) + (Surface\ Force)$$

$$= F_{gravity}(r) + F_{fluid}(r, \dot{r}, \ddot{r})$$

$$= F_{gravity} + F_{buoyancy}(r) + F_{F.K.}(r) + F_D(r) + F_{R,Damping}(r, \dot{r}) + F_{R,Mass}(r, \dot{r})$$

$V_w(x)$  : vertical wave shear force  
 $V_w(x) = \int_0^x f_w(x) dx$

$M_w(x)$  : vertical wave bending moment  
 $M_w(x) = \int_0^x V_w(x) dx$

**DYNAMIC HEAVE FORCE COMPONENTS**  
 WAVE CREST AMIDSHIPS  
 LBP = 520 ft, T = 10 s, h<sub>w</sub> = 20 ft

added mass force  
 potential damping  
 diffraction  
 dyn. Froude-Krylov  
 mass inertia

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## Dynamic Longitudinal Loads

**In still water**

$$f_s(x) = b(x) + w(x)$$

$f(x)$ : Distributed loads in longitudinal direction  
 $f_s(x)$ : **Static longitudinal loads** in longitudinal direction  
 $f_w(x)$ : **Hydrodynamic longitudinal loads** induced by wave

+

**In wave**

✓ Dynamic longitudinal loads  
 : Loads are induced by waves

Vertical bending due to waves

Hogging

Sagging


Hogging and sagging

Ship in oblique waves

**40**

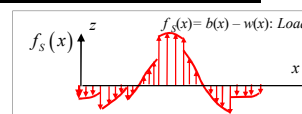
## Dynamic Longitudinal Loads - Direct Calculation of Dynamic Longitudinal Loads (1/2)

**In still water**



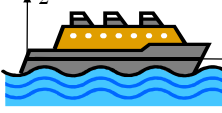
$f_S(x) = b(x) + w(x)$

$f(x)$ : Distributed loads in longitudinal direction  
 $f_S(x)$ : **Static longitudinal loads** in longitudinal direction  
 $f_w(x)$ : **Hydrodynamic longitudinal loads** induced by wave



+

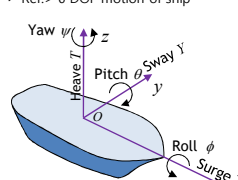
**In wave**



- ✓ Dynamic longitudinal loads : Loads are induced by waves
- ✓ Direct calculation of dynamic longitudinal loads
  - from 6DOF motion of ship

$\mathbf{x} = [X, Y, T, \phi, \theta, \psi]^T$

✓ Ref. > 6 DOF motion of ship



where,

$$f(x) = f_S(x) + f_W(x)$$

$$= b(x) + w(x) + f_{F.K}(x) + f_D(x) + f_R(x)$$

↑ additional loads in wave

$f_R(x) = -a(x)\ddot{x} - b(x)\dot{x}$

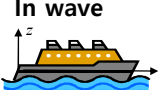
$f_D(x)$ : Diffraction force at x  
 $f_R(x)$ : Radiation force at x by damping and added mass  
 $f_{F.K}(x)$ : Froude-Krylov force at x

In order to calculate loads in waves, first we have to determine  $\zeta_3, \zeta_3$ .

**How to determine  $\zeta_3, \zeta_3$ ?**

## Dynamic Longitudinal Loads - Direct Calculation of Dynamic Longitudinal Loads (2/2)

**In wave** ✓ Direct calculation of dynamic longitudinal loads



Load induced by Wave

↓

Actual Vertical Wave Shear Force

↓


Actual Vertical Wave Bending Moment

$f_W(x) = f_{F.K}(x) + f_D(x) + f_R(x)$

where,  $f_R(x) = -a(x)\ddot{x} - b(x)\dot{x}$

$Q_W(x) = \int_0^x f_W(x) dx$

$M_W(x) = \int_0^x Q_W(x) dx$

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## Rule Values of Vertical Wave Bending Moments

✓ Direct calculation of dynamic longitudinal loads

- Loads are induced by waves

Actual Vertical Wave Shear Force

↓

Actual Vertical Wave Bending Moment

$$Q_w(x) = \int_0^x f_w(x) dx$$

$$M_w(x) = \int_0^x Q_w(x) dx$$

Recently, rule values of vertical wave moments are used, because of the uncertainty of the direct calculation values of vertical wave bending moments.

Design VWBM = Min(Actual VWBM, Rule VWBM) + margin.....

The rule vertical wave bending moments amidships are given by:

$$M_w = M_{wO} \quad [kNm]$$

$$M_{wO} = -0.11\alpha C_w L^2 B(C_B + 0.7) \quad [kNm] \text{ in sagging}$$

$$= 0.19\alpha C_w L^2 B C_B \quad [kNm] \text{ in hogging}$$

$\alpha = 1.0$  for seagoing condition  
 $= 0.5$  for harbor and sheltered water conditions (enclosed fiords, lakes, rivers)  
 $C_w$ : wave coefficient  
 $C_B$ : block coefficient, not be taken less than 0.6

(DNV Pt.3 Ch.1 Sec.5 B201)

$L$	$C_w$
$L \leq 100$	$0.0792 \cdot L$
$100 < L < 300$	$10.75 - [(300 - L)/100]^{3/2}$
$300 \leq L \leq 350$	$10.75$
$L > 350$	$10.75 - [(L - 350)/150]^{3/2}$

Direct calculation values of vertical wave bending moments can be used for design vertical wave bending moment instead of the rule values of vertical wave moments, if the value of the direct calculation is smaller than that of the rule value.

## Rule Values of Vertical Wave Shear Forces

✓ Direct calculation of dynamic longitudinal loads

- Loads are induced by waves

Load induced by Wave

↓

Actual Vertical Wave Shear Force

$$f_w(x) = f_D(x) + f_{F,K}(x) + f_R(x)$$

where,  $f_R(x) = -a(x) \ddot{x} - b(x) \dot{x}$

$$Q_w(x) = \int_0^x f_w(x) dx$$

Design VWSF = Min(Actual VWSF, Rule VWSF) + margin .....

The rule values of vertical wave shear forces along the length of the ship are given by:

Positive shear force:  $Q_{WP} = 0.3\beta k_{wqp} C_w LB(C_B + 0.7)$

Negative shear force:  $Q_{WN} = -0.3\beta k_{wqn} C_w LB(C_B + 0.7)$

(DNV Pt.3 Ch.1 Sec.5 B203)

$\beta$ : coefficient according to operating condition  
 $k_{wqp}, k_{wqn}$ : coefficients according to location in lengthwise  
 $C_w$ : wave coefficient

Direct calculation values of vertical wave shear forces can be used for vertical wave shear force instead of the rule values of vertical shear forces, if the value of the direct calculation is smaller than that of the rule value.

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### [Example] Rule Values of Still Water Bending Moments (Ms) and Vertical Wave Bending Moment (Mw)

Calculate  $L_s$ ,  $C_{B,SCANT}$ , and vertical wave bending moment ( $M_w$ ) at amidships (0.5L) of a ship in hogging condition for sea going condition.

Given:  $L_{OA} = 332.0\text{ m}$ ,  $L_{BP} = 317.2\text{ m}$ ,  $L_{EXT} = 322.85\text{ m}$ ,  $B = 43.2\text{ m}$ ,  $T_s = 14.5\text{ m}$ ,  $\Delta = 140,960\text{ ton}$

(Sol.)  $L_s = 0.97 \times L_{EXT} = 0.97 \times 322.85 = 313.16$   
 $C_{B,SCANT} = \Delta / (1.025 \times L_s \times B \times T_s) = \frac{140,906}{1.025 \times 313.16 \times 43.2 \times 14.5} = 0.701$

$\alpha = 1.0$ , for sea going condition,  
 $C_w = 10.75$ , if  $300 \leq L \leq 350$  (wave coefficient)  
 $k_{wm} = 1.0$  between 0.4L and 0.65 L from A.P(=0.0) and F.P

$M_{w0} = 0.19 \times \alpha \times C_w \times L^2 \times B \times C_{B,SCANT} \text{ (kNm)}$   
 $= 0.19 \times 1.0 \times 10.75 \times 313.16^2 \times 43.2 \times 0.701 = 6,066,303 \text{ (kNm)}$

at 0.5L,  $k_{wm} = 1.0$

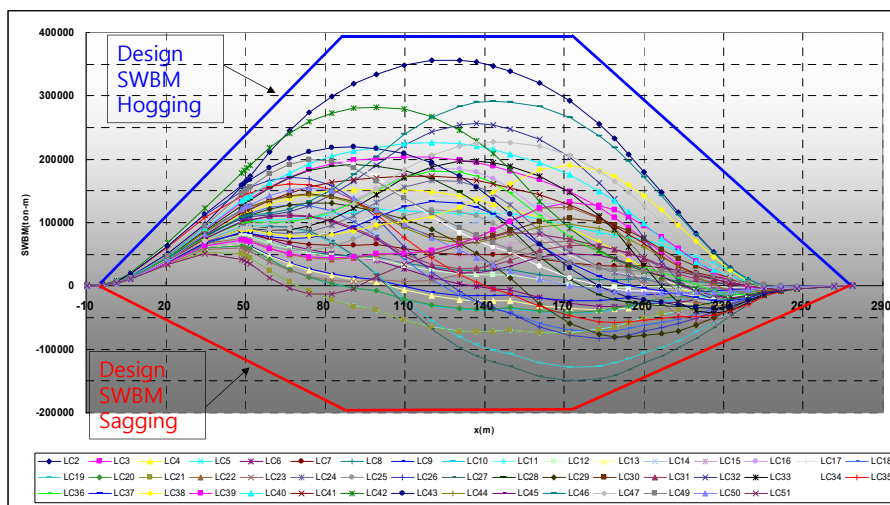
$M_w = 1.0 \times M_{w0}$

So,  $M_w = 1.0 \times M_{w0} = 6,066,303 \text{ (kNm)}$

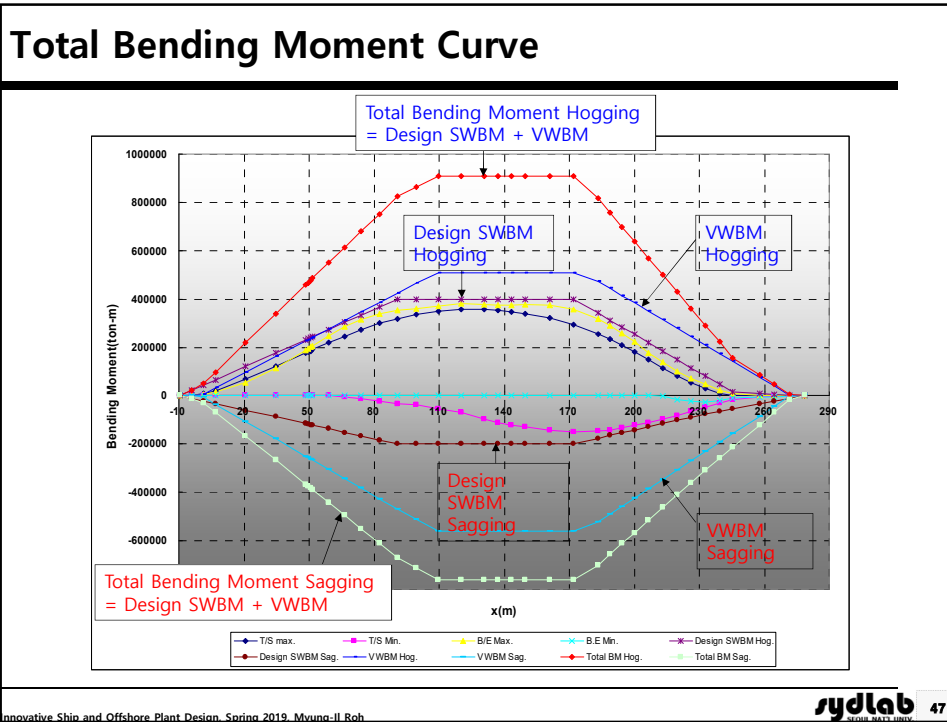
$M_s = M_{s0} \text{ (kNm)}$   
 $M_{s0} = -0.065 C_w L^2 B (C_B + 0.7)$ , (in sagging)  
 $= C_w L^2 B (0.1225 - 0.015 C_B)$ , (in hogging)  
 $M_w = M_{w0} \text{ (kNm)}$   
 $M_{w0} = -0.11 \alpha C_w L^2 B (C_B + 0.7)$ , (in sagging)  
 $= 0.19 \alpha C_w L^2 B C_{B^*}$ , (in hogging)

1) DSME, Ship Structural Design, 5-2 Load on Hull Structure, Example 4, 2005  
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### Still Water Bending Moment Curve (T&S Booklet)



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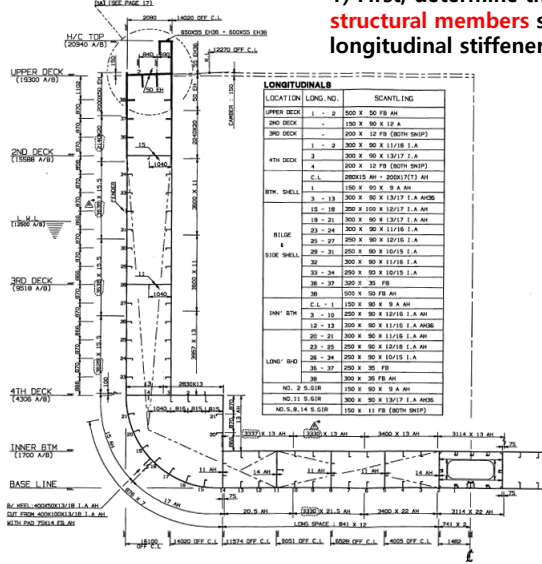
### (3) Section Modulus

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## Example of Midship Section of a 3,700 TEU Container Ship

1) First, determine the dimensions of the **longitudinal structural members** such as longitudinal plates and longitudinal stiffeners by rule **local scantling**.



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## Vertical Location of Neutral Axis about Baseline

2) Second, calculate the moment of sectional area about the base line.

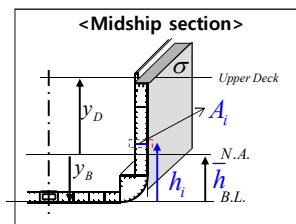
$$\sum h_i A_i$$

$h_i$  : vertical center of structural member  
 $A_i$  : area of structural member

3) Vertical location of neutral axis from base line ( $\bar{h}$ ) is, then, calculated by dividing the moment of area by the total sectional area.

$$\bar{h} = \frac{\sum h_i A_i}{A}$$

$\bar{h}$  : vertical location of neutral axis  
 $A$  : total area



By definition, neutral axis pass through the centroid of the cross section.

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## Midship Section Moment of Inertia about N.A

- The midship section moment of inertia about base line ( $I_{B.L.}$ )

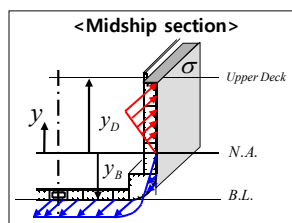
$$I_{B.L.} = I_{N.A.} + A \bar{h}^2$$

- then calculate the midship section moment of inertia about neutral axis ( $I_{N.A.}$ ) using  $I_{B.L.}$ .

$$I_{N.A.} = I_{B.L.} - A \bar{h}^2$$

$$\sigma \leq \sigma_l, \sigma = \frac{M}{I_{N.A.} / y} = \frac{M}{Z}$$

## Calculation of Section Modulus and Actual Stress at Deck and Bottom



$\sigma$ : bending stress  
 $M$ : Total bending moment  
 $A$ : Total Area  
 $I_{N.A.}$ : Inertia moment of the midship section area about neutral axis (N.A.)  
 B.L.: Base Line

### Section modulus

$$\frac{I_{N.A.}}{y_D} = Z_D, \quad \frac{I_{N.A.}}{y_B} = Z_B$$

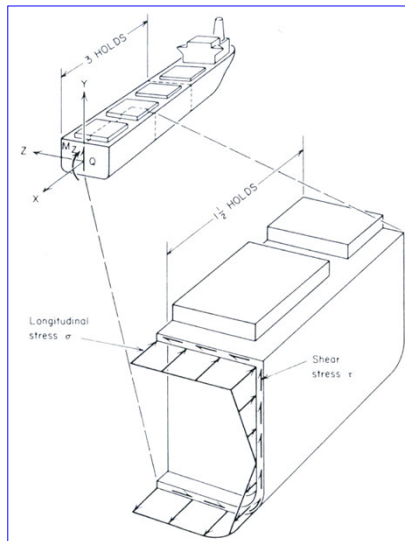
### Calculation of Actual Stress at Deck and Bottom

$$\sigma_{Deck} = \frac{M}{I_{N.A.} / y_D} = \frac{M}{Z_D}$$

$$\sigma_{Bottom} = \frac{M}{I_{N.A.} / y_B} = \frac{M}{Z_B}$$

$$\sigma \leq \sigma_l, \sigma = \frac{M}{I_{N.A.} / y} = \frac{M}{Z}$$

## Global Hull Girder Strength (Longitudinal Strength) - Definition of the Longitudinal Strength Members



Application of hull girder load effects

### ※ Example of Requirement for Longitudinal Structural Member

DNV Rules for Classification of Ships  
Part 3 Chapter 1 HULL STRUCTURE DESIGN SHIPS WITH  
LENGTH 100 METERS AND ABOVE

Sec. 5 Longitudinal Strength

C 300 Section modulus

301 The requirements given in 302 and 303 will normally be satisfied when calculated for the midship section only, provided the following rules for tapering are complied with:

- Scantlings of all continuous longitudinal strength members shall be maintained within 0.4 L amidships.
- Scantlings outside 0.4 L amidships are gradually reduced to the local requirements at the ends, and the same material strength group is applied over the full length of the ship.

The section modulus at other positions along the length of the ship may have to be specially considered for ships with small block coefficient, high speed and large flare in the fore body or when considered necessary due to structural arrangement, see A106.

\* Hughes, Ship Structural Design, John Wiley & Sons, 1983

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## (DNV Pt.3 Ch.1 Sec. 5 C300), 2011

### C 300 Section modulus

301 The requirements given in 302 and 303 will normally be satisfied when calculated for the midship section only, provided the following rules for tapering are complied with:

- Scantlings of all continuous longitudinal strength members shall be maintained within 0.4 L amidships.  
In special cases, based on consideration of type of ship, hull form and loading conditions, the scantlings may be gradually reduced towards the ends of the 0.4 L amidship part, bearing in mind the desire not to inhibit the vessel's loading flexibility.
- Scantlings outside 0.4 L amidships are gradually reduced to the local requirements at the ends, and the same material strength group is applied over the full length of the ship.

The section modulus at other positions along the length of the ship may have to be specially considered for ships with small block coefficient, high speed and large flare in the forebody or when considered necessary due

to structural arrangement, see A106.

In particular this applies to ships of length  $L > 120$  m and speed  $V > 17$  knots.

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## The Minimum Required Midship Section Modulus and Inertia Moment by DNV Rule

DNV Rules, Jan. 2004, Pt.3 Ch.1 Sec.5

The **midship section modulus** about the transverse neutral axis **shall not be less than:**  
(Pt.3 Ch.1 Sec.5 C302)

$$Z_O = \frac{C_{WO}}{f_1} L^2 B (C_B + 0.7) \quad [cm^3]$$

$C_{WO}$ : wave coefficient

$L$	$C_{WO}$
$L < 300$	$10.75 - [(300 - L)/100]^{3/2}$
$300 \leq L \leq 350$	10.75
$L > 350$	$10.75 - [(L - 350)/150]^{3/2}$

$C_B$  is in this case not to be taken less than 0.60.

The **midship section moment of inertia** about the transverse neutral axis **shall not be less than:**  
(Pt.3 Ch.1 Sec.5 C400)

$$I_{ship} = 3C_W L^3 B (C_B + 0.7) \quad [cm^4]$$

\* DNV Rules, Jan. 2004, Pt.3 Ch.1 Sec.5

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## (DNV Pt.3 Ch.1 Sec.5 C302), 2011

302 The midship section modulus about the transverse neutral axis shall not be less than:

$$Z_O = \frac{C_{WO}}{f_1} L^2 B (C_B + 0.7) \quad (cm^3)$$

$$\begin{aligned} C_{WO} &= 10.75 - [(300 - L)/100]^{3/2} \quad \text{for } L < 300 \\ &= 10.75 \quad \text{for } 300 \leq L \leq 350 \\ &= 10.75 - [(L - 350)/150]^{3/2} \quad \text{for } L > 350 \end{aligned}$$

Values of  $C_{WO}$  are also given in Table C1.

$C_B$  is in this case not to be taken less than 0.60.

$L$	$C_{WO}$	$L$	$C_{WO}$	$L$	$C_{WO}$
		160	9.09	260	10.50
		170	9.27	280	10.66
		180	9.44	300	10.75
		190	9.60	350	10.75
100	7.92	200	9.75	370	10.70
110	8.14	210	9.90	390	10.61
120	8.34	220	10.03	410	10.50
130	8.53	230	10.16	440	10.29
140	8.73	240	10.29	470	10.03
150	8.91	250	10.40	500	9.75

For ships with restricted service,  $C_{WO}$  may be reduced as follows:

- service area notation **R0**: No reduction
- service area notation **R1**: 5%
- service area notation **R2**: 10%
- service area notation **R3**: 15%
- service area notation **R4**: 20%
- service area notation **RE**: 25%.

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## (DNV Pt.3 Ch.1 Sec.5 C401), 2011

### C 400 Moment of inertia

401 The midship section moment of inertia about the transverse neutral axis shall not be less than:

$$I = 3 C_W L^3 B (C_B + 0.7) \text{ (cm}^4\text{)}$$

## Material Factors ( $f_1$ )

<sup>1)</sup> DNV Rules, Jan. 2004, Pt.3 Ch.1 Sec.2

<sup>2)</sup> James M. Gere, Mechanics of Materials 7th Edition, Thomson, Chap.1, pp.15~26

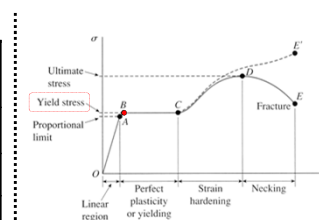
- The material factor  $f_1$  is included in the various formulae for scantlings and in expressions giving allowable stresses.<sup>1)</sup>

Material Designation	Yield Stress (N/mm <sup>2</sup> )	$\frac{\sigma}{\sigma_{NV-NS}}$	Material Factor ( $f_1$ )
NV-NS	235	235/235 = 1.00	1.00
NV-27	265	265/235 = 1.13	1.08
NV-32	315	315/235 = 1.34	1.28
NV-36	355	355/235 = 1.51	1.39
NV-40	390	390/235 = 1.65	1.47

\* NV-NS: Normal Strength Steel (Mild Steel)

\* NV-XX: High Tensile Steel

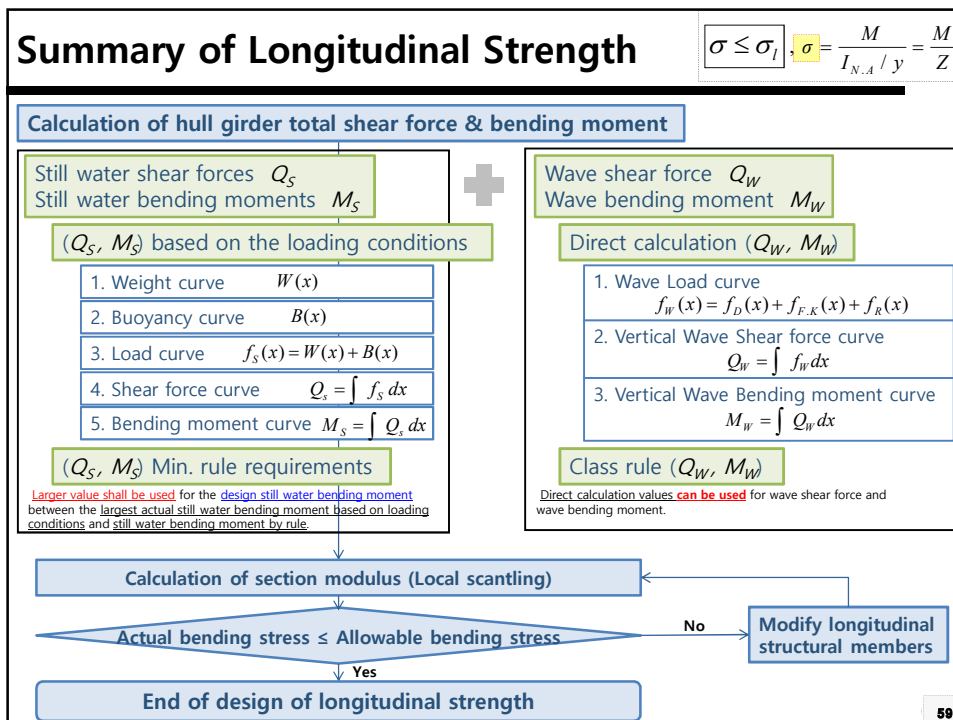
\* High tensile steel: A type of alloy steel that provides better mechanical properties or greater resistance to corrosion than carbon steel. They have a carbon content between 0.05-0.25% to retain formability and weldability, including up to 2.0% manganese, and other elements are added for strengthening purposes.



\* Yield Stress ( $\sigma_y$ ) [N/mm<sup>2</sup>] or [MPa]: The magnitude of the load required to cause yielding in the beam.<sup>2)</sup>

\* A: 'A' grade 'Normal Strength Steel'

\* AH: 'A' grade 'High Tensile Steel'

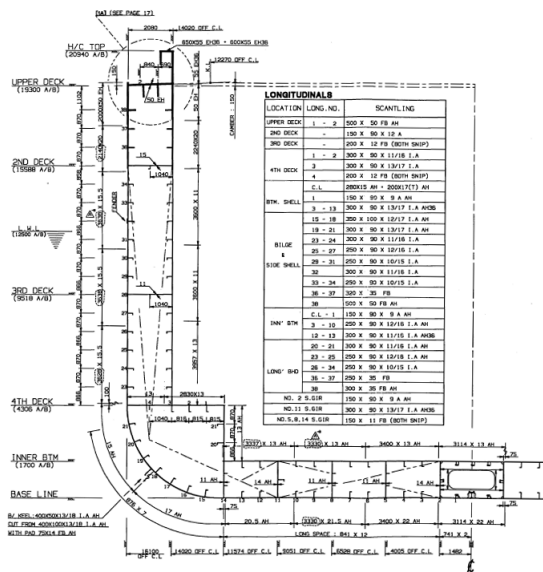


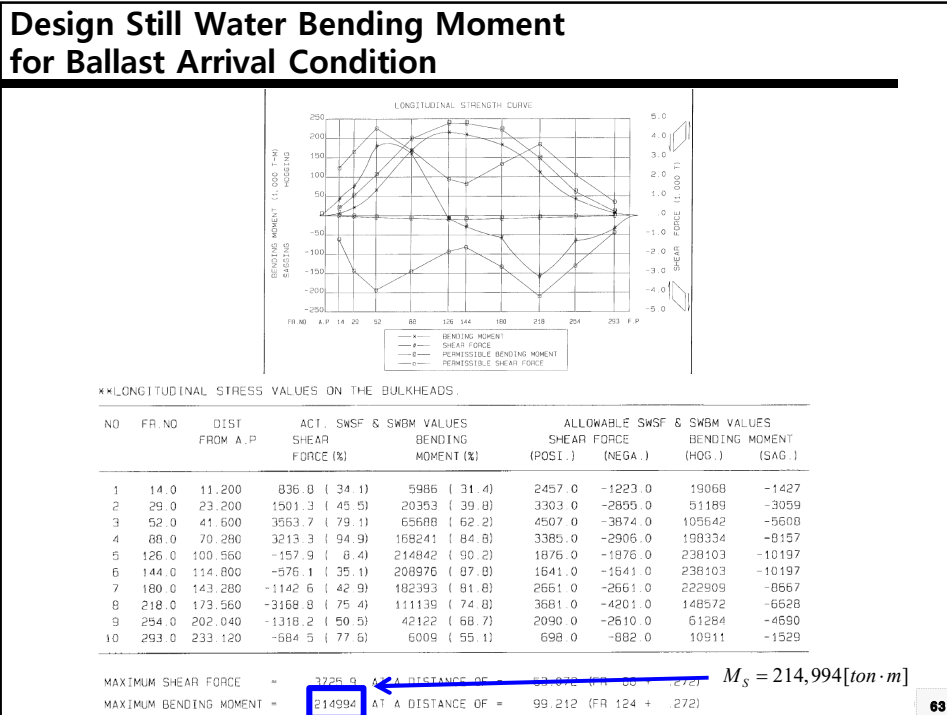
## 3. Structural Design of Midship Section of a 3,700 TEU Container Ship

- (1) Data for Structural Design
- (2) Longitudinal Strength

# (1) Data for Structural Design

## Midship Section for 3,700 TEU Container Ship





### Design Still Water Bending Moment

**NOTES**

- DESIGN STILL WATER BENDING MOMENT IN SEAGOING CONDITION. HOGGING CONDITION : 238,000 TON-M (2,335,000 KN-M) From ballast arrival condition,  $M_s = 214,994[ton \cdot m]$
- MIN. LEG LENGTH OF FILLET WELDING 4.5 EXCEPT AS SHOWN.
- BOTH SIDES ARE SYMMETRICAL UNLESS OTHERWISE SHOWN.
- SECTIONS ARE SHOWN IN LOOKING FORWARD AND ELEVATIONS ARE SHOWN TO PORT.
- THE DETAILS NOT SHOWN IN THIS DRAWING ARE REFERRED TO "STRUCTURAL DETAILS FOR HULL" (DWG. NO. SF091.20)

By calculating the section modulus and stress factor of the basis ship, we can assume the stress factor for the design ship.



## (2) Longitudinal Strength

### Example of Midship Scantling - Midship Scantling for 3,700 TEU Container Ship

#### <Calculation of Design Bending Moment (Hogging)>

- Still water bending moment
  - **Larger value shall be used** for **still water bending moment** between the **largest actual still water bending moment based on loading conditions** and **design still water bending moment by rule**

#### ✓ Design still water bending moment by rule<sup>1)</sup>

$$\begin{aligned}
 C_{wu} &= C_w \\
 &= 10.75 - [(300 - L) / 100]^{3/2} \\
 &= 10.75 - [(300 - 247.64) / 100]^{3/2} \\
 &= 10.37 \\
 M_{so} &= C_{wu} L^2 B (0.1225 - 0.015 C_b) \\
 &= 10.37 \times 247.64^2 \times 32.2 \\
 &\quad \times (0.1225 - 0.015 \times 0.6581) \\
 &= \boxed{2,364,171.77 \text{ (kN} \cdot \text{m)}} \\
 M_s &= k_{sm} M_{so} \\
 &= 1.0 \times 2,364,171.77 \\
 &= \boxed{2,364,171.77 \text{ (kN} \cdot \text{m)}}
 \end{aligned}$$

#### ✓ Largest actual still water bending moment based on the loading conditions

- At ballast arrival condition

$$\begin{aligned}
 M_s &= \boxed{2,109,290 \text{ (kN} \cdot \text{m)}} \\
 &= 214,994 \text{ (ton} \cdot \text{m)}
 \end{aligned}$$

- Wave bending moment<sup>2)</sup>

$$\begin{aligned}
 M_{wo} &= 0.19 \alpha C_{wu} L^2 B C_b \\
 &= 0.19 \times 1.0 \times 10.37 \times 247.64^2 \times 32.2 \times 0.6581 \\
 &= 2,560,481.90 \text{ (kN} \cdot \text{m)}
 \end{aligned}$$

$$\begin{aligned}
 M_w &= k_{wm} M_{wo} \\
 &= 1.0 \times 2,560,481.90 \\
 &= 2,560,481.90 \text{ (kN} \cdot \text{m)}
 \end{aligned}$$

$$\begin{aligned}
 \therefore M_s &= 2,364,171.77 \text{ (kNm)} \quad \Rightarrow \quad M = M_s + M_w \\
 &= 2,364,171.77 + 2,560,481.90 \\
 &=
 \end{aligned}$$

#### <Calculation of Design Bending Moment (Sagging)>

- Design bending moment at sagging condition is calculated in the same way.

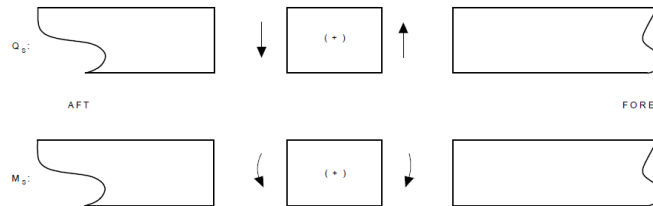
$$\begin{aligned}
 M_s &= -1,807,679.05 \text{ (kN} \cdot \text{m)} & M &= M_s + M_w \\
 M_w &= -3,059,149.16 \text{ (kN} \cdot \text{m)} & &= -1,807,679.05 - 3,059,149.16 =
 \end{aligned}$$

**(DNV Pt. 3 Ch. 1 Sec. 5 B101), 2011****B. Still Water and Wave Induced Hull Girder Bending Moments and Shear Forces****B 100 Stillwater conditions**

101 The design stillwater bending moments,  $M_S$ , and stillwater shear forces,  $Q_S$ , shall be calculated along the ship length for design cargo and ballast loading conditions as specified in 102.

For these calculations, downward loads are assumed to be taken as positive values, and shall be integrated in the forward direction from the aft end of L. The sign conventions of  $Q_S$  and  $M_S$  are as shown in Fig. 1.

(IACS UR S11.2.1.1 Rev.5)



**Fig. 1**  
Sign Conventions of  $Q_S$  and  $M_S$

102 In general, the following design cargo and ballast loading conditions, based on amount of bunker, fresh water and stores at departure and arrival, shall be considered for the  $M_S$  and  $Q_S$  calculations. Where the amount and disposition of consumables at any intermediate stage of the voyage are considered more severe, calculations for such intermediate conditions shall be submitted in addition to those for departure and arrival conditions. Also, where any ballasting and or deballasting is intended during voyage, calculations of the

**(DNV Pt. 3 Ch. 1 Sec. 5 B201), 2011****B 200 Wave load conditions**

201 The rule vertical wave bending moments amidships are given by:

$$M_W = M_{W0} \text{ (kNm)}$$

$$M_{W0} = -0.11 \alpha C_W L^2 B (C_B + 0.7) \text{ (kNm) in sagging}$$

$$= 0.19 \alpha C_W L^2 B C_B \text{ (kNm) in hogging}$$

$$\alpha = 1.0 \text{ for seagoing conditions}$$

$$= 0.5 \text{ for harbour and sheltered water conditions (enclosed fjords, lakes, rivers).}$$

$C_B$  is not be taken less than 0.6.

### Example of Midship Scantling - Midship Scantling for 3,700 TEU Container Ship

**Plates at Bottom Structure**

IBP2 area =  $3400 \times 1.35 = 459 \text{ cm}^2$

IBP (inner bottom plate) area ( $A$ ) = Width of IBP X Thickness of IBP  
 Ex. Area of IBP2 =  $340 \times 1.35 = 459 \text{ cm}^2$

1<sup>st</sup> moment of IBP area about base line = Area of IBP ( $A$ ) X Vertical center of IBP ( $b$ )  
 Ex. 1<sup>st</sup> moment of Area of IBP2 =  $459 \times 170 = 78,030 \text{ cm}^3$

2<sup>nd</sup> moment of IBP area about base line = Area of IBP ( $A$ ) X Vertical center of IBP ( $b$ )<sup>2</sup>  
 Ex. 2<sup>nd</sup> moment of Area of IBP2 =  $459 \times 170^2 = 1.327 \times 10^7 \text{ cm}^4$

Moment of inertia of IBP area ( $I_x$ )  
 Ex. Moment of inertia of IBP2 area

$$I_x = \frac{LB^3}{12} = \frac{340 \times 1.35^3}{12} = 6.971 \times 10^1 \text{ cm}^4$$

Moment of inertia of IBP area about base line ( $I_{x'}$ ) is obtained by using the parallel-axis theorem.

$$I_{x'} = I_x + b^2 A$$

Bottom Structure Plates								
Plate	Name	Width (cm)	Thickness (cm)	Area (cm <sup>2</sup> )	Vertical center of IBP (cm)	1st moment of IBP area about base line (cm <sup>3</sup> )	2nd moment of IBP area about base line (cm <sup>4</sup> )	Moment of inertia of IBP area (cm <sup>4</sup> )
	IBP1	340.00	1.35	459	170.0	78,030	1.327E+07	6.971E+01
	IBP2	340.00	1.35	459	170.0	78,030	1.327E+07	6.971E+01
	IBP3	333.00	1.35	450	170.0	76,424	1.299E+07	6.628E+01
	IBP4	326.20	1.35	440	170.0	74,863	1.273E+07	6.688E+01

Bottom Structure Girders								
Girder	Name	Width (cm)	Thickness (cm)	Area (cm <sup>2</sup> )	Vertical center of IBP (cm)	1st moment of IBP area about base line (cm <sup>3</sup> )	2nd moment of IBP area about base line (cm <sup>4</sup> )	Moment of inertia of IBP area (cm <sup>4</sup> )
L0	L0	1.10	170.00	187	85.0	15,895	1.351E+06	4.504E+05
L2	L2	1.40	170.00	238	85.0	20,230	1.720E+06	5.732E+05
L5	L5	1.25	170.00	213	85.0	18,063	1.539E+06	5.118E+05
L8	L8	1.25	170.00	213	85.0	18,063	1.539E+06	5.118E+05
L11	L11	1.25	170.00	213	85.0	18,063	1.539E+06	5.118E+05
L14	L14	1.25	170.00	213	85.0	18,063	1.539E+06	5.118E+05

### Example of Midship Scantling - Midship Scantling for 3,700 TEU Container Ship

**Stiffeners at Bottom Structure**

Actual Bending Stress < Allowable Bending Stress  
 End of Design of Longitudinal Strength

For convenience of calculation of moment of inertia of the stiffener area about base line, we consider that the stiffener is actually composed of flange and web plate and thus the stiffener is assumed as the flange and web plate.

Neutral axis of bottom structure = Total 1<sup>st</sup> moment of area about base line / Total area

$$= \frac{590,637}{7,519} = 78.55 \text{ [cm]}$$

Bottom Structure Stiffener Web Plate								
Stiffener	Name	Width (cm)	Thickness (cm)	Area (cm <sup>2</sup> )	Vertical center of IBP (cm)	1st moment of IBP area about base line (cm <sup>3</sup> )	2nd moment of IBP area about base line (cm <sup>4</sup> )	Moment of inertia of IBP area (cm <sup>4</sup> )
L1	L1	1.20	45.00	54	22.5	1.215	2.736E+04	9.113E+03
L3	L3	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L4	L4	1.30	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L6	L6	1.30	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L7	L7	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L9	L9	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L10	L10	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L12	L12	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L13	L13	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L19	L19	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L20	L20	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04
L21	L21	1.20	55.00	66	27.5	1.815	4.991E+04	1.664E+04

Bottom Structure Stiffener Flange								
Stiffener	Name	Width (cm)	Thickness (cm)	Area (cm <sup>2</sup> )	Vertical center of IBP (cm)	1st moment of IBP area about base line (cm <sup>3</sup> )	2nd moment of IBP area about base line (cm <sup>4</sup> )	Moment of inertia of IBP area (cm <sup>4</sup> )
L1	L1	10.00	1.50	15	45.0	6.75	3.033E+04	2.813E+00
L3	L3	50.00	1.50	75	55.0	4.125	2.269E+05	1.409E+01
L4	L4	50.00	1.50	75	55.0	4.125	2.269E+05	1.409E+01
L6	L6	50.00	1.50	75	55.0	4.125	2.269E+05	1.409E+01
L7	L7	50.00	1.50	75	55.0	4.125	2.269E+05	1.409E+01
L9	L9	50.00	1.50	75	55.0	4.125	2.269E+05	1.409E+01
L10	L10	10.00	1.50	15	55.0	6.05	4.939E+04	2.813E+00
L12	L12	10.00	1.50	15	55.0	6.05	4.939E+04	2.813E+00
L13	L13	10.00	1.50	15	55.0	6.05	4.939E+04	2.813E+00
L19	L19	10.00	1.50	15	55.0	6.05	4.939E+04	2.813E+00
L20	L20	10.00	1.50	15	55.0	6.05	4.939E+04	2.813E+00
L21	L21	10.00	1.50	15	55.0	6.05	4.939E+04	2.813E+00

Bottom Structure Stiffener Flange								
Stiffener	Name	Width (cm)	Thickness (cm)	Area (cm <sup>2</sup> )	Vertical center of IBP (cm)	1st moment of IBP area about base line (cm <sup>3</sup> )	2nd moment of IBP area about base line (cm <sup>4</sup> )	Moment of inertia of IBP area (cm <sup>4</sup> )
L15	L15	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03
L16	L16	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03
L17	L17	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03
L18	L18	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03
L19	L19	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03
L20	L20	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03
L21	L21	1.20	45.00	54	30.5	25.013	9.007E+04	9.113E+03

### Example of Midship Scantling - Midship Scantling for 3,700 TEU Container Ship

Calculation of moment of inertia of sectional area from neutral axis  
 Area, neutral axis, 1<sup>st</sup> moment & 2<sup>nd</sup> moment about baseline, and moment of inertia of side structure, bulkhead structure, deck structure are calculated in the same way and the results are as follows:

Structure	Area	Neutral axis	1st moment of area about baseline	2nd moment of area about baseline	Moment of inertia of area
Bottom	7,519	79	5.90E+05	8.75E+08	2.527E+09
Side	8,135	1,158	3.630E+06	4.202E+09	1.261E+09
Bulkhead	5,273	1,250	6.592E+06	8.242E+09	2.472E+09
Deck	2,200	2,130	5.015E+06	1.205E+10	3.694E+09
<b>Total</b>	<b>18,127</b>		<b>1.583E+07</b>	<b>2.540E+10</b>	<b>7.620E+09</b>

Vertical location of neutral axis of midship section from baseline ( $\bar{h}$ ) is calculated by using the above table.

$$\bar{h} = \frac{\text{Total 1st moment of area about baseline}}{\text{Total area}} = \frac{1.583e^{07}}{18,127} = 873.2 [cm]$$

Moment of inertia of area about neutral axis of midship section:

(Parallel-axis theorem)

$$I_{Base,Total} = I_{N.A.,Total} + \bar{h}^2 \sum A_i \iff I_{N.A.,Total} = I_{Base,Total} - \bar{h}^2 \sum A_i$$

$$= \sum (I_{Local,i} + A_i h_i^2) - \bar{h}^2 \sum A_i \iff I_{Base,Total} = \sum (I_{Local,i} + A_i h_i^2)$$

$$= \sum I_{Local,i} + \sum A_i h_i^2 - \bar{h}^2 \sum A_i$$

$$= (7.620e^{09} + 2.540e^{10}) - 873.2^2 \times 18,127 = 1.234e^{10} [cm^4]$$

$I_{N.A.}$  : moment of inertia of midship section area about neutral axis (cm<sup>4</sup>)  
 $I_{Base}$  : moment of inertia of midship section area about base line (cm<sup>4</sup>)  
 $h_i$  : vertical center of structural member (cm)  
 $A_i$  : area of structural member (cm)

**sydlab** 71

### Example of Midship Scantling - Midship Scantling for 3,700 TEU Container Ship

$$f_{2b,2d} = \frac{5.7(M_S + M_W)}{Z_{b,d}}$$

<p>① Assume section modulus</p> <ul style="list-style-type: none"> <li>Bottom stress factor of the basis ship  <math>Z_B = 2.595e^7 \text{ cm}^3</math></li> </ul>	<ul style="list-style-type: none"> <li>Deck stress factor of the basis ship  <math>Z_D = 2.345e^7 \text{ cm}^3</math></li> </ul>
<p>② Actual section modulus</p> <ul style="list-style-type: none"> <li>Bottom section modulus  <math>Z_B = 2 \times I / y_B</math> (port &amp; starboard)  <math>= 2 \times 1.234e^{10} / 873.2</math>  <math>= 2.826e^7 [cm^3]</math>                      (<math>y_B</math>: Vertical distance from N.A to bottom = 873.2cm)</li> </ul> <p>Because the section modulus at bottom is larger than that of the basis ship, the stress factor should be decreased.</p> <ul style="list-style-type: none"> <li>Bottom Stress Factor  <math>f_{2b} = \frac{5.7(M_S + M_W)}{f_1 \times Z_B}</math>  <math>= \frac{5.7 \times 4,924,653.67}{1.0 \times 2.826e^7} =</math></li> </ul>	<ul style="list-style-type: none"> <li>Deck section modulus  <math>Z_D = 2 \times I / y_D</math> (port &amp; starboard)  <math>= 2 \times 1.234e^{10} / 1,226.8</math>  <math>= 2.012e^7 [cm^3]</math>                      (<math>y_D</math>: Vertical distance from N.A to deck = 2094 - 873.2 = 1,226.8 cm)</li> </ul> <p>Because the section modulus at deck is smaller than that of the basis ship, the stress factor will be increased. However, if HT-36 is used, then the stress factor can be decreased.</p> <ul style="list-style-type: none"> <li>Deck Stress Factor  <math>f_{2d} = \frac{5.7(M_S + M_W)}{f_1 \times Z_D}</math>  <math>= \frac{5.7 \times 4,924,653.67}{1.39 \times 2.012e^7} =</math></li> </ul>
<p>③ Because the stress factor (<math>f_{2b}</math>) is decreased, the allowable stress is increased.</p> $\sigma = 225 f_1 - 130 f_{2b} - 0.7 \sigma_{db}$ <p>e.g., Allowable stress for longitudinals at inner bottom</p>	<p>④ Because the allowable stress is increased, the required section modulus is decreased. So, we can reduce the size of the structure member.</p> $Z = \frac{83 l^2 s p w_k}{\sigma} [cm^3]$ <p>e.g., Required section modulus for longitudinals at inner bottom</p>

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