

# **System Control Review**

Fall 2014

**Professor Kyongsu Yi**

©201 VDCL

**Vehicle Dynamics and Control Laboratory  
Seoul National University**

# Review (1)

## 1. Some examples of control systems

## 2. Key concepts

Systems, control, dynamic system, linear/nonlinear

Analysis, design, synthesis

Openloop control, feedback control systems

## 3. Laplace Transformation

## 4. System representations

Block diagram, signal flow graph

Mason's gain rule

## 5. System responses

Transient response, steady state response, pole/zero,

System types, static error/velocity error/acceleration error constants ,

Stability, Routh stability tests

## 6. Basic control algorithms

On-off control, PID control, openloop/closed loop control and modeling error

## 7. Root Locus analysis and design method

lead-lag compensator

parameter variations

# Review (2)

## 8. Frequency response method

Bode plots, Nyquist plot, Nyquist stability criterion  
Gain margin, phase margin,  
Robustness to model uncertainties

## 9. State space method

state feedback and pole placements  
solution of state equation, state transition matrix  
(discrete systems)  
Regulator  
reference tracking  
integral control  
Controllability, observability, Cayley-Hamilton theorem  
Observer design, observer-controller,  
Separation property

## 10. Design Examples (state space design)

Inverted bar(pendulum) control, PID  
(Vehicle control systems) (path tracking)