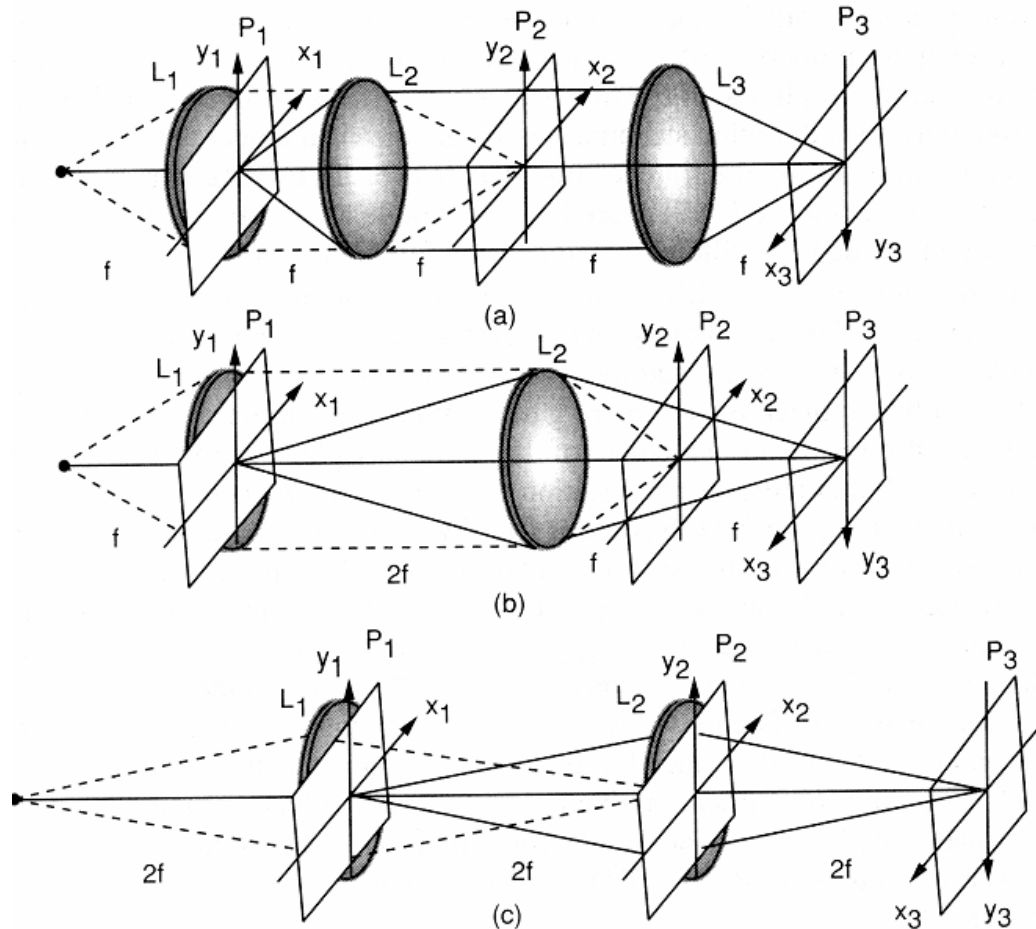
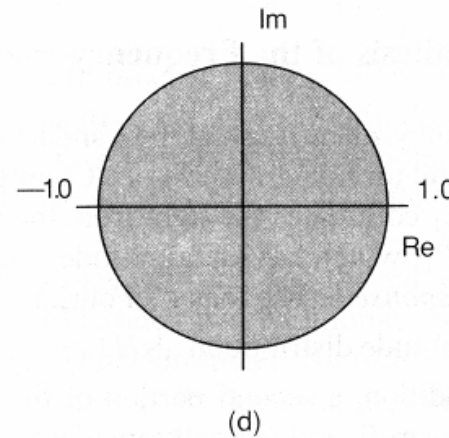
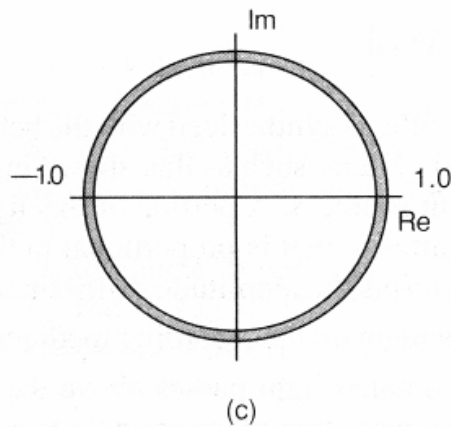
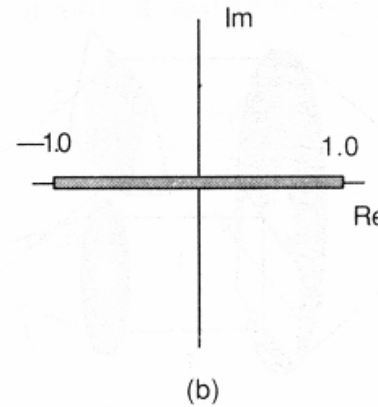
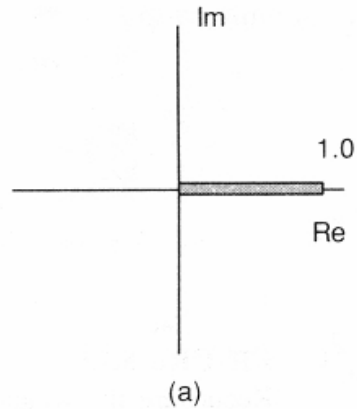


Coherent Optical Processing



Filter Realization



VanderLugt Filter - Recording (I)

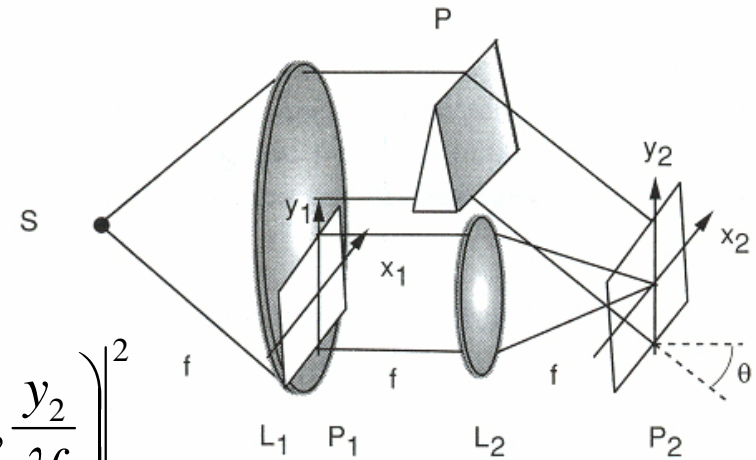
$$U_r(x_2, y_2) = r_o \exp(-j2\pi\alpha y_2)$$

$$\alpha = \frac{\sin\theta}{\lambda}$$

$$I(x_2, y_2) = \left| r_o \exp(-j2\pi\alpha y_2) + \frac{1}{\lambda f} H\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) \right|^2$$

$$= r_o^2 + \frac{1}{\lambda^2 f^2} \left| H\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) \right|^2 + \frac{r_o}{\lambda f} H\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) \exp(j2\pi\alpha y_2)$$

$$+ \frac{r_o}{\lambda f} H^*\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) \exp(-j2\pi\alpha y_2)$$



VanderLugt Filter - Recording (II)

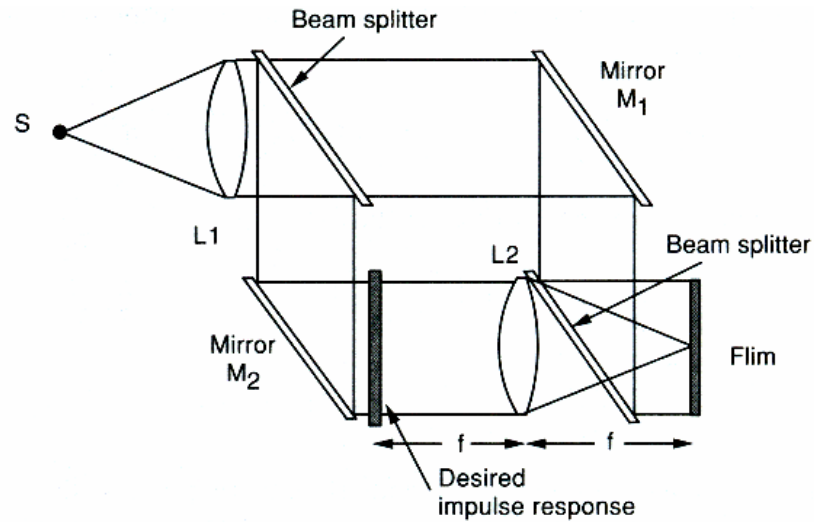
$$H \left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f} \right) = A \left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f} \right) \exp \left[j \psi \left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f} \right) \right]$$

$$I(x_2, y_2) = r_0^2 + \frac{1}{\lambda^2 f^2} A^2 \left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f} \right) + \frac{2r_0}{\lambda f} A \left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f} \right) \cos \left[2\pi\alpha y_2 + \psi \left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f} \right) \right]$$

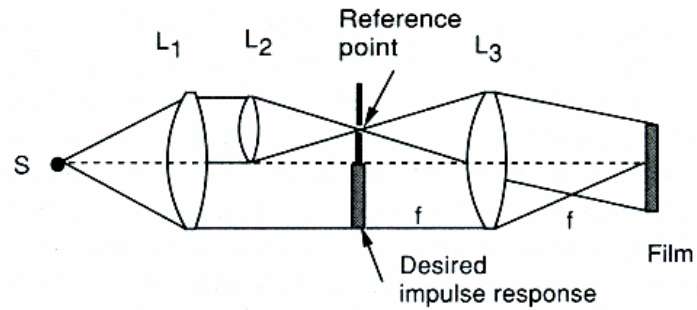
$$t_A(x_2, y_2) \propto r_0^2 + \frac{1}{\lambda^2 f^2} |H|^2 + \frac{r_0}{\lambda f} H \exp(j 2\pi\alpha y_2) + \frac{r_0}{\lambda f} H^* \exp(-j 2\pi\alpha y_2)$$



VanderLugt Filter - Recording (III)



(a)



(b)

VanderLugt Filter - Processing (I)

$$U_2 \propto \frac{r_0^2 G}{\lambda f} + \frac{1}{\lambda^3 f^3} |H|^2 G + \frac{r_0^2}{\lambda^2 f^2} HG \exp(j2\pi\alpha y_2) \\ + \frac{r_0}{\lambda^2 f^2} H^* G \exp(-j2\pi\alpha y_2)$$

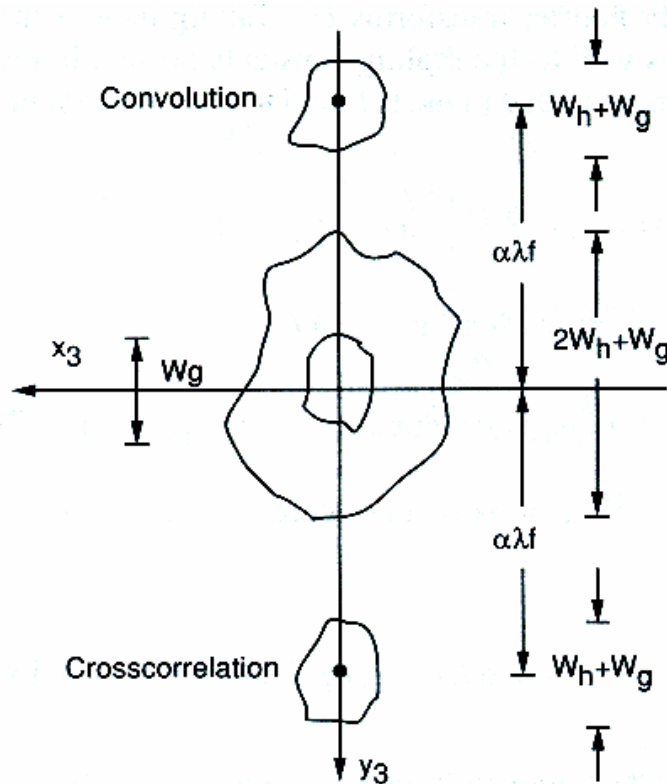
$$U_3(x_3, y_3) \propto r_0^2 g(x_3, y_3) + \frac{1}{\lambda^2 f^2} [h(x_3, y_3) \otimes h^*(-x_3, -y_3) \otimes g(x_3, y_3)] \\ + \frac{r_0}{\lambda f} [h(x_3, y_3) \otimes g(x_3, y_3) \otimes \delta(x_3, y_3 + \alpha\lambda f)] \\ + \frac{r_0}{\lambda f} [h^*(-x_3, -y_3) \otimes g(x_3, y_3) \otimes \delta(x_3, y_3 - \alpha\lambda f)]$$

Third term : Convolution of g and h centered at $(0, -\alpha\lambda f)$

Fourth term : Crosscorrelation of g and h centered at $(0, \alpha\lambda f)$



VanderLugt Filter - Processing (II)



$$\alpha > \frac{1}{\lambda f} \left(\frac{3W_h}{2} + W_g \right)$$

$$\theta > \frac{3W_h}{2f} + \frac{W_g}{f}$$

with $\sin \theta \approx \theta$

VanderLugt Filter – Processing (III)

Crosscorrelation term

$$\begin{aligned} h^*(-x_3, -y_3) \otimes g(x_3, y_3) \otimes \delta(x_3, y_3 - \alpha\lambda f) \\ = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(\xi, \eta) h^*(\xi - x_3, \eta - y_3 + \alpha\lambda f) d\xi d\eta \end{aligned}$$

If the input object function is translated to a new location, the crosscorrelation result is also translated.

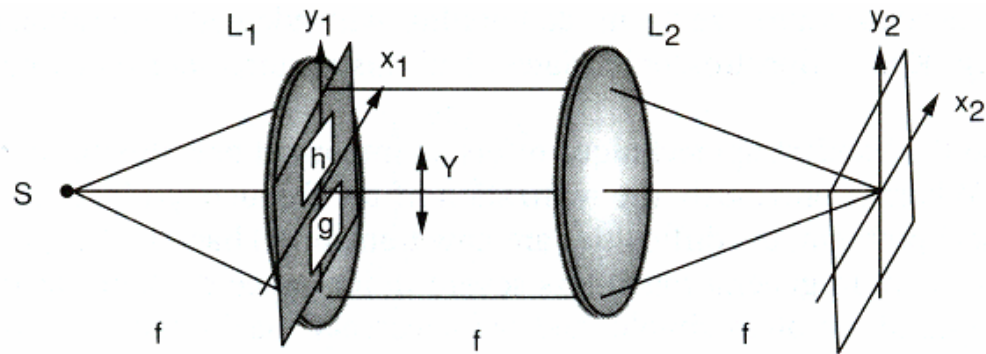


VanderLugt Filter - Advantages

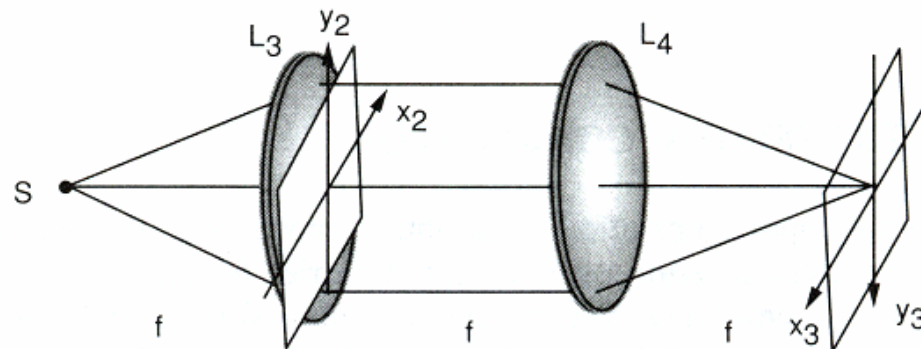
- Impulse response is **optically** Fourier transformed.
- Generally complicated **complex-valued** transfer function is synthesized with a **single absorbing mask**.



Joint Transform Correlator (JTC) (I)



(a)



(b)

JTC (II)

$$U_1(x_1, y_1) = h(x_1, y_1 - Y/2) + g(x_1, y_1 + Y/2)$$

$$U_2(x_2, y_2) = \frac{1}{\lambda f} H\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) e^{-j\pi y_2 Y / \lambda f} + \frac{1}{\lambda f} G\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) e^{+j\pi y_2 Y / \lambda f}$$

$$I(x_2, y_2) = \frac{1}{\lambda^2 f^2} \left[\left| H\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) \right|^2 + \left| G\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) \right|^2 \right. \\ \left. + H\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) G^*\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) e^{-j\pi y_2 Y / \lambda f} \right. \\ \left. + H^*\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) G\left(\frac{x_2}{\lambda f}, \frac{y_2}{\lambda f}\right) e^{+j\pi y_2 Y / \lambda f} \right]$$



JTC (III)

$$U_3(x_3, y_3) = \frac{1}{\lambda f} \left[h(x_3, y_3) \otimes h^*(-x_3, -y_3) + g(x_3, y_3) \otimes g^*(-x_3, -y_3) \right. \\ \left. + h(x_3, y_3) \otimes g^*(-x_3, -y_3) \otimes \delta(x_3, y_3 - Y) \right. \\ \left. + h^*(-x_3, -y_3) \otimes g(x_3, y_3) \otimes \delta(x_3, y_3 + Y) \right]$$

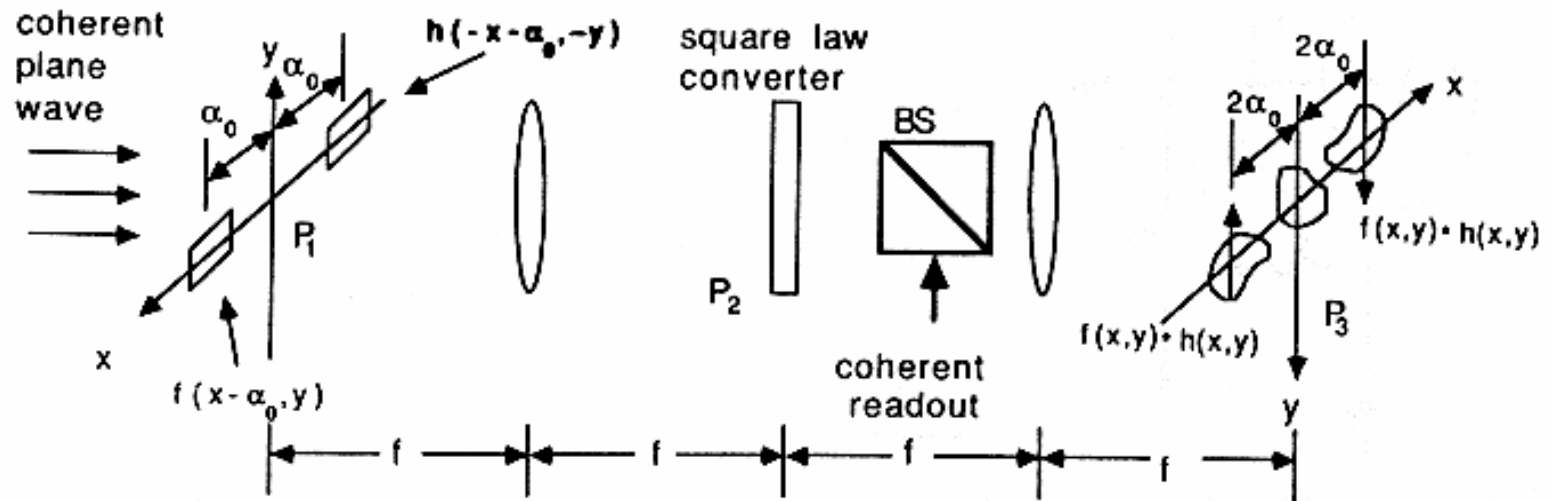
Third term : Crosscorrelation of g and h centered at $(0, Y)$

Fourth term : Crosscorrelation of g and h centered at $(0, -Y)$

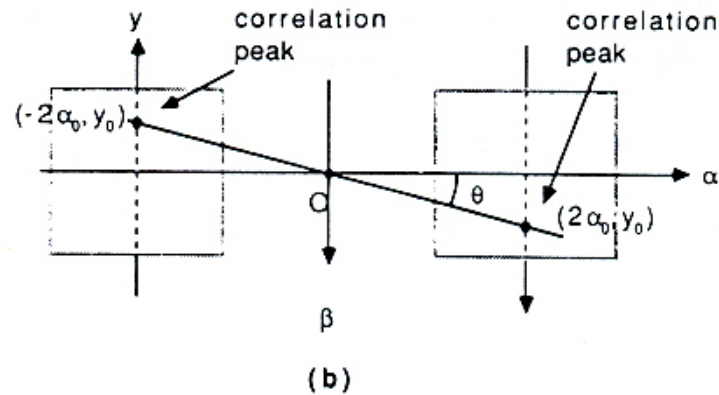
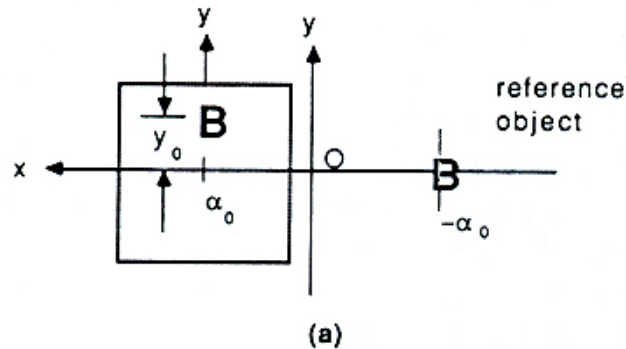
To obtain convolution : One of g and h should be introduced in the processor with a mirror reflection about its own origin.



JTC (IV)



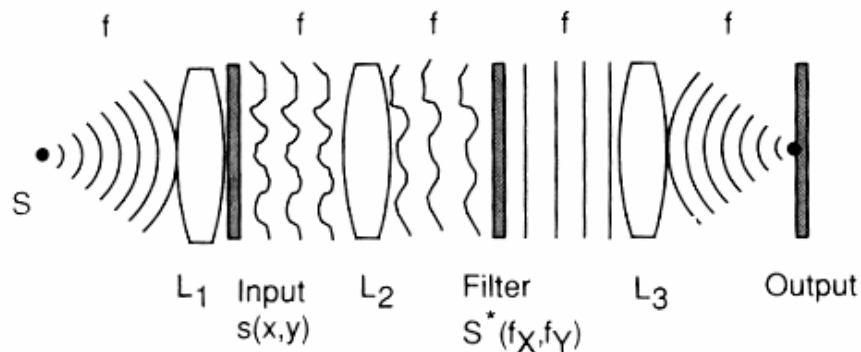
JTC (V) – Space Invariant Property



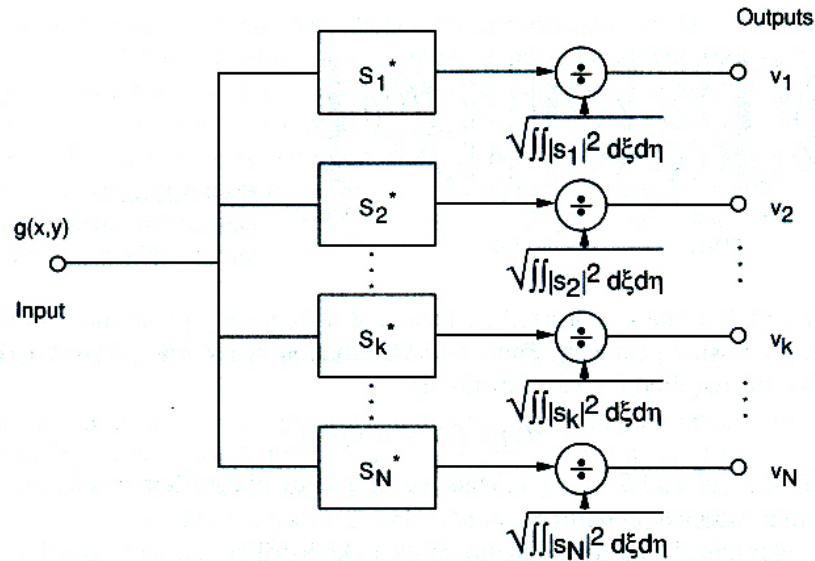
Matched Filter (I)

$$h(x, y) = s^*(-x, -y)$$

$$\begin{aligned} v(x, y) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(x - \xi, y - \eta) g(\xi, \eta) d\xi d\eta \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(\xi, \eta) s^*(\xi - x, \eta - y) d\xi d\eta \end{aligned}$$



Matched Filter (II)

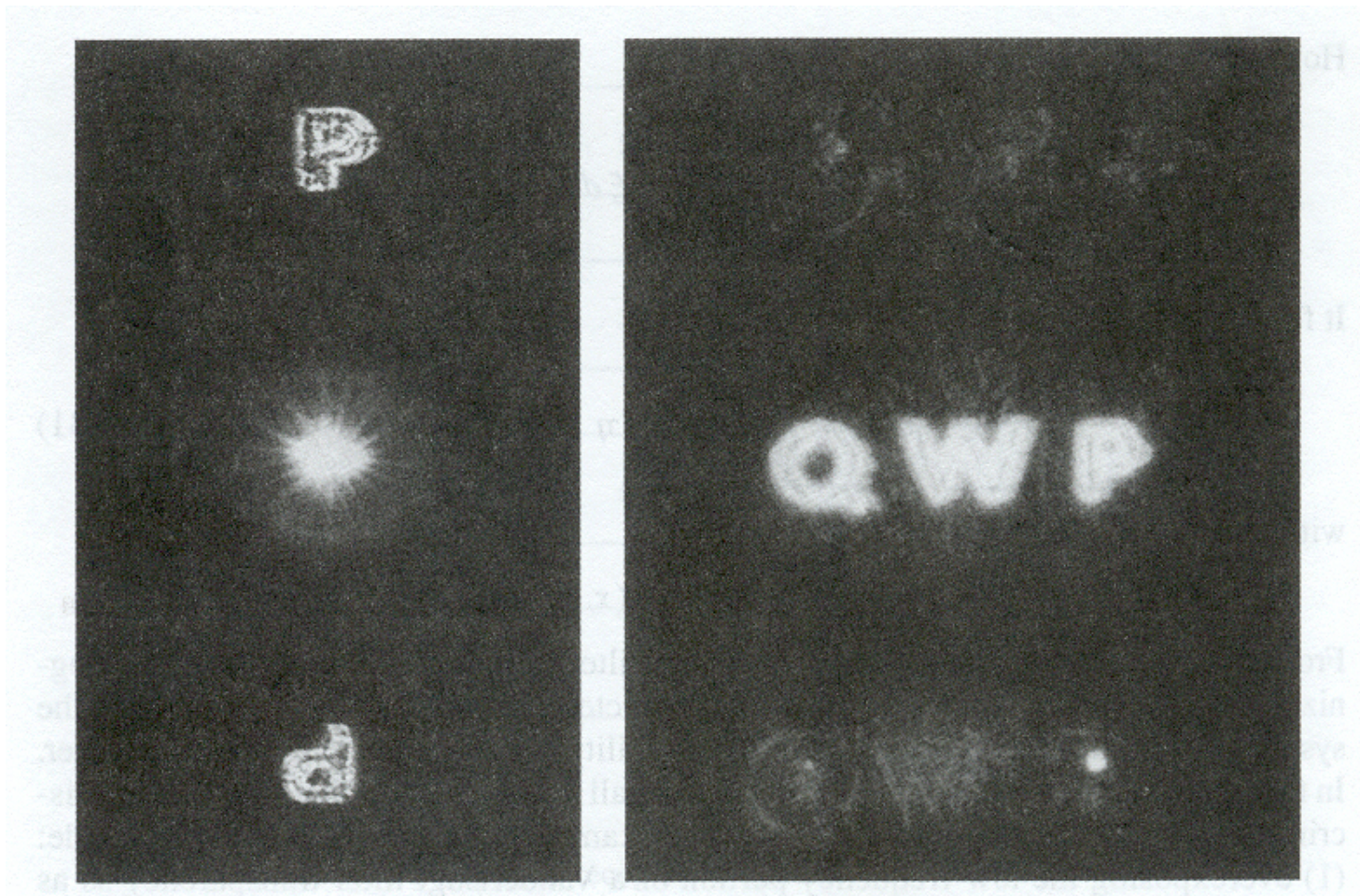


For $g(x, y) = s_k(x, y)$,

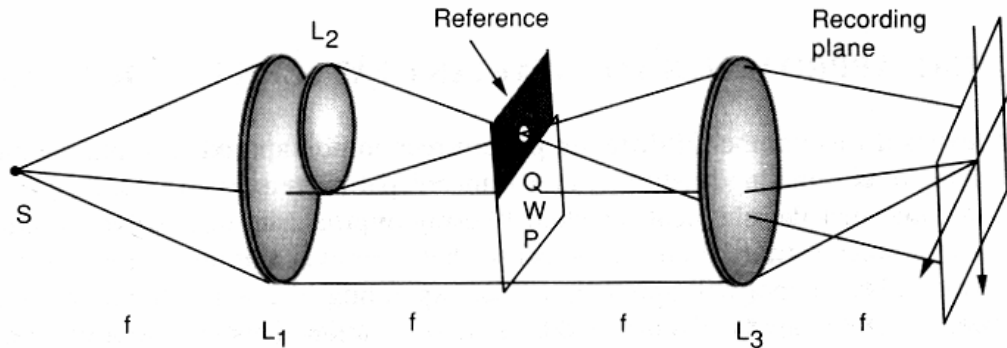
$$|v_n|^2 \leq \int_{-\infty}^{\infty} \int |s_k|^2 d\xi d\eta = |v_k|^2$$

with equality if and only if
 $s_n(x, y) = \kappa s_k(x, y)$

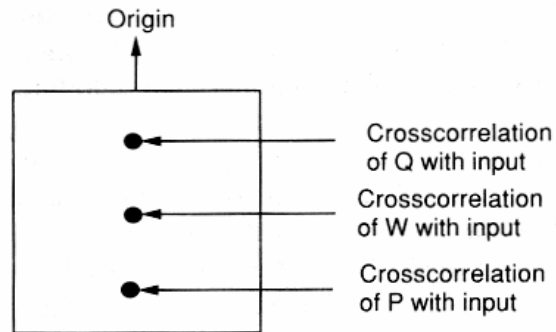
Character Recognition (I)



Character Recognition (II)

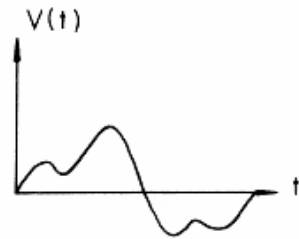


(a)

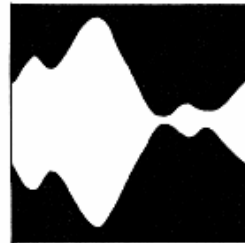


(b)

Area Modulation



UNILATERAL

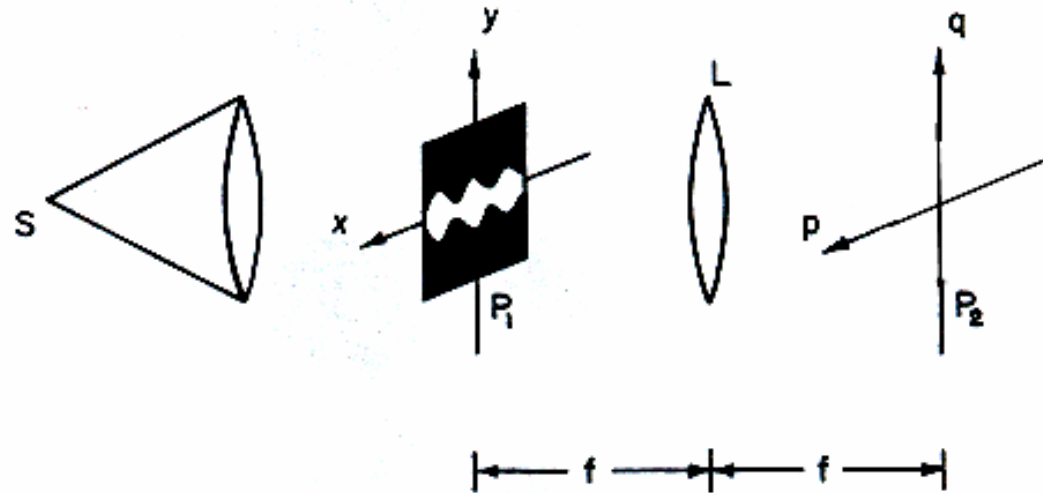


BILATERAL

Bilateral :
$$T_1(x, y) = \text{rect}\left(\frac{x}{L}\right) \text{rect}\left\{\frac{y}{2[B + f(x)]}\right\}$$

Unilateral :
$$T_2(x, y) = \text{rect}\left(\frac{x}{L}\right) \text{rect}\left\{\frac{y - [f(x) + B]/2}{B + f(x)}\right\}$$

Spectrum Analysis with Area Modulation (I)



$$G(p, q) = C \iint T(x, y) \exp[-i(px + qy)] dx dy$$

Spectrum Analysis with Area Modulation (II)

For a bilateral area-modulated signal

$$\begin{aligned} G_1(p,0) &= 2C \int \text{rect}\left(\frac{x}{L}\right) [B + f(x)] \exp(-ipx) dx \\ &= 2C \left[\int_{-L/2}^{L/2} B \exp(-ipx) dx + \int_{-L/2}^{L/2} f(x) \exp(-ipx) dx \right] \end{aligned}$$

For a unilateral area-modulated signal

$$G_2(p,0) = \frac{1}{2} G_1(p,0)$$

