Finite element modeling and analysis





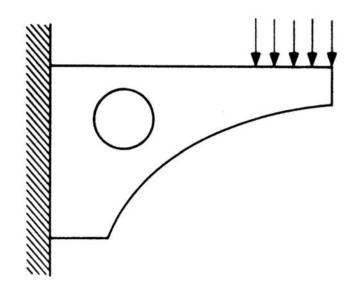
- Structural problems
 - stress, strain distribution
- Heat transfer problems
 - temperature distribution
- Electrostatic potential problems
- Fluid mechanics problems
- Vibration analysis problems

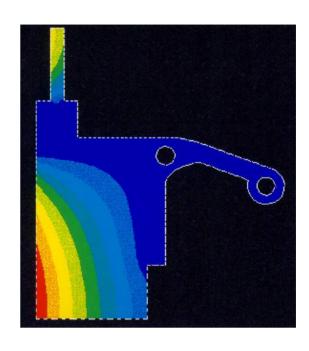


- When geometry of problem domain is complicated, analytic solution can not be derived
 - Numerical approximate solution

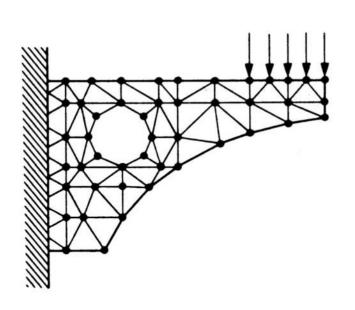
 Even for simple geometry, analytic solution cannot be obtained if the object is composed of composite material

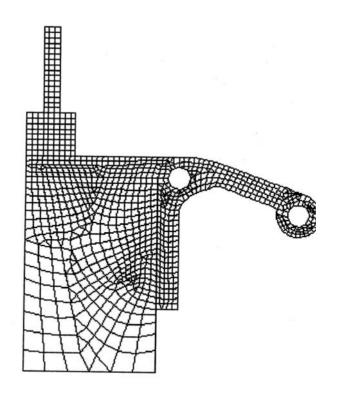
Problems which cannot be solved analytically











Choice of element

- Select element type among those supported by the FEM package in use
- Select element type mostly suitable for the given problem ← know-how
- Determining element size is also a know-how
- Use small elements where rapid change in stress or strain is expected

Analysis procedure

- Input material properties and boundary condition after elements are generated
 - -> Specify B.C at element nodes

B.C known displacement

known external force

known temperature

 Pre-processor: generate meshes automatically and allow the interactive input of B.C's

Analysis procedure – cont'

- System equations are composed by FEM package
- System equation
 - Relation between B.C. and unknown (displacement, temperature, ...) at every node
 - -> By solving system equation, unknowns at each node is obtained.

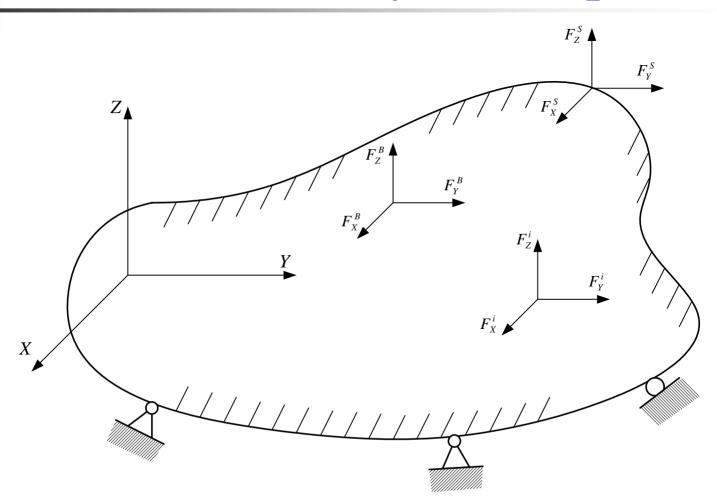
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Analysis procedure – cont'

 Unknown values (displacement, temperature, stress, strain, ...) at arbitrary location is obtained by interpolating the values at nodes

 Post-processor displays color coding or contour plot

Formulation of system equation





f^S: external surface tractions

f^B : body forces
Fⁱ . concentrates

Fi : concentrated external forces

Only displacement at any X,Y,Z
U^T = [U(X,Y,Z), V(X,Y,Z), W(X,Y,Z)]
needs to be solved

ightarrow Strain and stress are derived from U

$$\boldsymbol{\epsilon}^{\mathrm{T}} = \left[\boldsymbol{\epsilon}_{\mathrm{XX}} \; \boldsymbol{\epsilon}_{\mathrm{YY}} \; \boldsymbol{\epsilon}_{\mathrm{ZZ}} \; \; \boldsymbol{\gamma}_{\mathrm{XY}} \; \boldsymbol{\gamma}_{\mathrm{YZ}} \; \boldsymbol{\gamma}_{\mathrm{ZX}}\right]$$
$$\boldsymbol{\tau}^{\mathrm{T}} = \left[\boldsymbol{\tau}_{\mathrm{XX}} \; \boldsymbol{\tau}_{\mathrm{YY}} \; \boldsymbol{\tau}_{\mathrm{ZZ}} \; \; \boldsymbol{\tau}_{\mathrm{XY}} \; \boldsymbol{\tau}_{\mathrm{YZ}} \; \boldsymbol{\tau}_{\mathrm{ZX}}\right]$$

Formulation of system eq. – cont'

- Principle of virtual displacement
 - total external virtual work
 - = total internal virtual work

$$\int_{V} \overline{\varepsilon}^{T} \tau \, dv = \int_{V} \overline{\mathbf{U}}^{T} \mathbf{f}^{B} dV + \int_{S} \overline{\mathbf{U}}^{S^{T}} \, \mathbf{f}^{S} dS + \sum_{i} \overline{\mathbf{U}}^{i^{T}} \mathbf{F}^{i}$$

' - 'indicates the quantities caused by virtual displacement

Formulation of system eq. – cont'

Let displacement of all the nodes $\widehat{\mathbf{U}}$

$$\begin{split} \widehat{\mathbf{U}}^{T} = & \left[\mathbf{u}_{1} \ \mathbf{v}_{1} \ \mathbf{w}_{1} \ \mathbf{u}_{2} \ \mathbf{v}_{2} \ \mathbf{w}_{2} \cdots \mathbf{u}_{N} \ \mathbf{v}_{N} \ \mathbf{w}_{N} \right] \\ = & \left[\mathbf{U}_{1} \ \mathbf{U}_{2} \ \mathbf{U}_{3} \ \cdots \cdot \mathbf{U}_{n} \right] \\ & \text{N} : \text{no. of nodes} \\ & \text{n=3N} : \text{degree of freedom} \end{split}$$



- Displcament at arbitrary location in an element:
- -> Is approximated by proper shape function that interpolates the displacements at nodes of the element
- -> Thus $\widehat{\mathbf{U}}^{\mathrm{T}}$ is the unknown to be solved

Formulation of system eq. – cont'

 $\mathbf{u}^{(m)}(x,y,z) = \mathbf{H}^{(m)}(x,y,z) \widehat{\mathbf{U}}$: displacement at arbitrary x,y,z in m-element

 $\epsilon^{(m)}(x,y,z) = \mathbf{B}^{(m)}(x,y,z) \, \widehat{\mathbf{U}}$:Strain is obtained by differentiating displacement

 $\tau^{(m)} = \mathbf{C}^{(m)} \epsilon^{(m)} + \tau^{I(m)} : \text{stress} - \text{strain relation}$ element ihitial stress

$$\sum_{m} \int_{V^{(m)}} \overline{\boldsymbol{\varepsilon}}^{(m)^{T}} \boldsymbol{\tau}^{(m)} dV^{(m)} = \sum_{m} \int_{V^{(m)}} \overline{\mathbf{u}}^{(m)^{T}} \mathbf{f}^{B(m)} dV^{(m)}
+ \sum_{m} \int_{S^{(m)}} \overline{\mathbf{u}}^{S(m)^{T}} \mathbf{f}^{S(m)} dS^{(m)} + \sum_{i} \overline{\mathbf{U}}^{i^{T}} \mathbf{f}^{i}
\overline{\hat{\mathbf{U}}}^{T} \left[\sum_{m} \int_{V^{(m)}} \mathbf{B}^{(m)^{T}} \mathbf{C}^{(m)} \mathbf{B}^{(m)} dV^{(m)} \right] \widehat{\mathbf{U}} = \overline{\hat{\mathbf{U}}}^{T} \left[\left\{ \sum_{m} \int_{V^{(m)}} \mathbf{H}^{(m)^{T}} \mathbf{f}^{B(m)} dV^{(m)} \right\}
+ \left\{ \sum_{m} \int_{S^{(m)}} \mathbf{H}^{S(m)^{T}} \mathbf{f}^{S(m)} dS^{(m)} \right\}
- \left\{ \sum_{m} \int_{V^{(m)}} \mathbf{B}^{(m)^{T}} \boldsymbol{\tau}^{I(m)} dV^{(m)} \right\} + \mathbf{F} \right]$$

-> Virtual nodal displacement

$$\left[\sum_{m} \int_{V^{(m)}} \mathbf{B}^{(m)^{T}} \mathbf{C}^{(m)} \mathbf{B}^{(m)} dV^{(m)}\right] \widehat{\mathbf{U}} = \sum_{m} \int_{V^{(m)}} \mathbf{H}^{(m)^{T}} \mathbf{f}^{B(m)} dV^{(m)}$$

$$+ \sum_{m} \int_{S^{(m)}} \mathbf{H}^{S(m)^{T}} \mathbf{f}^{S(m)} dS^{(m)}$$

$$- \sum_{m} \int_{V^{(m)}} \mathbf{B}^{(m)^{T}} \boldsymbol{\tau}^{I(m)} dV^{(m)} + \mathbf{F}$$

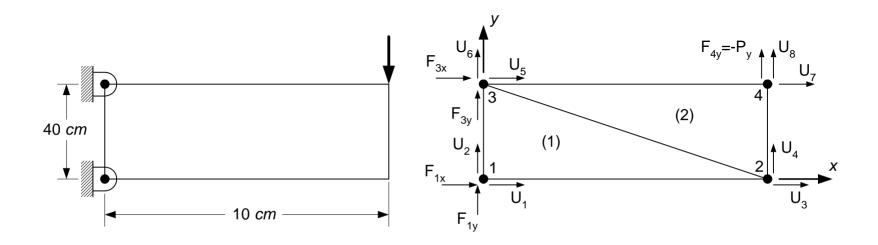
$$\mathbf{K} \widehat{\mathbf{U}} = \mathbf{R}$$



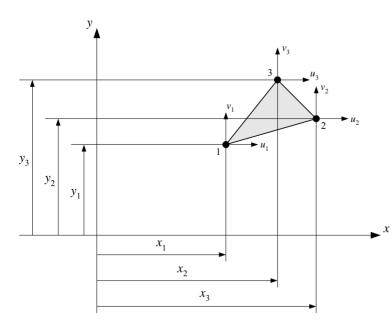
- Role of FEM package is to evaluate the integrals for K, R
- -> Solve for displacements at all the nodes
- -> Evaluate displacement, stress, strain at any location in each element using shape function



- Derive the system equations of the plate using a two-element model
- Thickness 1 cm. Load P_y is applied very slowly so that inertial effect is ignored



 Deriving the displacement transformation matrix $\mathbf{H}^{(i)}$ of any element



$$u = \alpha_1 + \alpha_2 x + \alpha_3 y$$
$$v = \beta_1 + \beta_2 x + \beta_3 y$$

the displacements of each node

$$u_{1} = \alpha_{1} + \alpha_{2}x_{1} + \alpha_{3}y_{1} \qquad v_{1} = \beta_{1} + \beta_{2}x_{1} + \beta_{3}y_{1}$$

$$u_{2} = \alpha_{1} + \alpha_{2}x_{2} + \alpha_{3}y_{2} \qquad v_{2} = \beta_{1} + \beta_{2}x_{2} + \beta_{3}y_{2}$$

$$u_{3} = \alpha_{1} + \alpha_{2}x_{3} + \alpha_{3}y_{3} \qquad v_{3} = \beta_{1} + \beta_{2}x_{3} + \beta_{3}y_{3}$$

• the constants α_i , β_i can be determined in terms of u_i , v_i and x_i , y_i

$$\alpha_{1} = \frac{a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}}{2a}$$

$$\beta_{1} = \frac{a_{1}v_{1} + a_{2}v_{2} + a_{3}v_{3}}{2a}$$

$$\alpha_{2} = \frac{b_{1}u_{1} + b_{2}u_{2} + b_{3}u_{3}}{2a}$$

$$\beta_{2} = \frac{b_{1}v_{1} + b_{2}v_{2} + b_{3}v_{3}}{2a}$$

$$\beta_{3} = \frac{c_{1}u_{1} + c_{2}u_{2} + c_{3}u_{3}}{2a}$$

$$\beta_{3} = \frac{c_{1}v_{1} + c_{2}v_{2} + c_{3}v_{3}}{2a}$$

$$a_1 = x_2 y_3 - x_3 y_2$$
 $b_1 = y_2 - y_3$ $c_1 = x_3 - x_2$ $2a = a_1 + a_2 + a_3$
 $a_2 = x_3 y_1 - x_1 y_3$ $b_2 = y_3 - y_1$ $c_2 = x_1 - x_3$
 $a_3 = x_1 y_2 - x_2 y_1$ $b_3 = y_1 - y_2$ $c_3 = x_2 - x_1$

Substituting the values of $x_1, x_2, x_3, y_1, y_2, y_3$ of element 1 into the previous equations

$$u = u_1 + \left(-\frac{1}{10}u_1 + \frac{1}{10}u_2\right)x + \left(-\frac{1}{4}u_1 + \frac{1}{4}u_3\right)y$$
$$v = v_1 + \left(-\frac{1}{10}v_1 + \frac{1}{10}v_2\right)x + \left(-\frac{1}{4}v_1 + \frac{1}{4}v_3\right)y$$

$$\begin{bmatrix} u \\ v \end{bmatrix}^{(1)} = \begin{bmatrix} (1 - \frac{1}{10}x - \frac{1}{4}y) & 0 & \frac{1}{10}x & 0 & \frac{1}{4}y & 0 & 0 & 0 \\ 0 & (1 - \frac{1}{10}x - \frac{1}{4}y) & 0 & \frac{1}{10}x & 0 & \frac{1}{4}y & 0 & 0 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \\ U_6 \\ U_7 \\ U_8 \end{bmatrix}$$

$$\begin{bmatrix} u \\ v \end{bmatrix}^{(2)} = \begin{bmatrix} 0 & 0 & (1 - \frac{y}{4}) & 0 & (1 - \frac{x}{10}) & 0 & (-1 + \frac{x}{10} + \frac{y}{4}) & 0 \\ 0 & 0 & 0 & (1 - \frac{y}{4}) & 0 & (1 - \frac{x}{10}) & 0 & (-1 + \frac{x}{10} + \frac{y}{4}) \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \\ U_6 \\ U_7 \\ U \end{bmatrix}$$

Determining the strains or the matrix B^(m)
using the following two-dimensional
strain-displacement relations

$$\varepsilon_{x} = \frac{\partial u}{\partial x}$$

$$\varepsilon_{y} = \frac{\partial v}{\partial y}$$

$$\gamma_{xy} = \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}$$

$$\boldsymbol{\varepsilon}^{(1)} = \begin{bmatrix} \varepsilon_{x} \\ \varepsilon_{y} \\ \gamma_{xy} \end{bmatrix}^{(1)} = \begin{bmatrix} -\frac{1}{10} & 0 & \frac{1}{10} & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{4} & 0 & 0 & 0 & \frac{1}{4} & 0 & 0 \\ -\frac{1}{4} & -\frac{1}{10} & 0 & \frac{1}{10} & \frac{1}{4} & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_{1} \\ U_{2} \\ U_{3} \\ U_{4} \\ U_{5} \\ U_{6} \\ U_{7} \\ U_{8} \end{bmatrix}$$

$$\boldsymbol{\varepsilon}^{(2)} = \begin{bmatrix} \varepsilon_{x} \\ \varepsilon_{y} \\ \gamma_{xy} \end{bmatrix}^{(2)} = \begin{bmatrix} 0 & 0 & 0 & 0 & -\frac{1}{10} & 0 & \frac{1}{10} & 0 \\ 0 & 0 & 0 & -\frac{1}{4} & 0 & 0 & 0 & \frac{1}{4} \\ 0 & 0 & -\frac{1}{4} & 0 & 0 & -\frac{1}{10} & \frac{1}{4} & \frac{1}{10} \end{bmatrix} \begin{bmatrix} \upsilon_{1} \\ \upsilon_{2} \\ \upsilon_{3} \\ \upsilon_{4} \\ \upsilon_{5} \\ \upsilon_{6} \\ \upsilon_{7} \\ \upsilon_{8} \end{bmatrix}$$

$$= \mathbf{B}^{(2)}\mathbf{U}$$

 $=\mathbf{B}^{(1)}\mathbf{U}$

 The stress-strain relations for a homogeneous, isotropic plane-stress element are given by

$$\boldsymbol{\tau}^{(m)} = \begin{bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{bmatrix} = \frac{E}{1 - v^2} \begin{bmatrix} 1 & v & 0 \\ v & 1 & 0 \\ 0 & 0 & \frac{1}{2} (1 - v) \end{bmatrix} \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{bmatrix}$$



- We assumed that there is no initial stress on the structure
- The stiffness matrix of each element is derived as follows by substituting the previous results
- Since two elements are made of the same material, the expression for $\mathbf{C}^{(m)}$ in Equation $\boldsymbol{\tau}^{(m)}$ can be used for both the elements

$$\mathbf{K}^{(1)} = \int_{V^{(1)}} \mathbf{B}^{(1)^{T}} \mathbf{C}^{(1)} \mathbf{B}^{(1)} dV^{(1)}$$

$$= \int_{A^{(1)}} \mathbf{B}^{(1)^{T}} \mathbf{C}^{(1)} \mathbf{B}^{(1)} dA^{(1)}$$

$$= \int_{0}^{10} \mathbf{B}^{(1)^{T}} \mathbf{C}^{(1)} \mathbf{B}^{(1)} (4 - \frac{4}{10}x) dx$$

$$= \frac{E}{1 - v^2} \int_0^{10} \begin{bmatrix} -\frac{1}{10} & 0 & \frac{1}{10} & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{4} & 0 & 0 & 0 & \frac{1}{4} & 0 & 0 \\ -\frac{1}{4} & -\frac{1}{10} & 0 & \frac{1}{10} & \frac{1}{4} & 0 & 0 & 0 \end{bmatrix}^T \begin{bmatrix} 1 & v & 0 \\ v & 1 & 0 \\ 0 & 0 & \frac{1-v}{2} \end{bmatrix}$$

$$\begin{bmatrix} -\frac{1}{10} & 0 & \frac{1}{10} & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{4} & 0 & 0 & 0 & \frac{1}{4} & 0 & 0 \\ -\frac{1}{4} & -\frac{1}{10} & 0 & \frac{1}{10} & \frac{1}{4} & 0 & 0 & 0 \end{bmatrix} (4 - \frac{4}{10}x) dx$$

$$\mathbf{K}^{(2)} = \int_{V^{(2)}} \mathbf{B}^{(2)^{T}} \mathbf{C}^{(2)} \mathbf{B}^{(2)} dV^{(2)}$$

$$= \int_{A^{(2)}} \mathbf{B}^{(2)^{T}} \mathbf{C}^{(2)} \mathbf{B}^{(2)} dA^{(2)}$$

$$= \int_{0}^{10} \mathbf{B}^{(2)^{T}} \mathbf{C}^{(2)} \mathbf{B}^{(2)} \frac{4}{10} x dx$$

$$\mathbf{K}^{(2)} = \frac{20E}{1-\nu^2} \begin{bmatrix} \frac{1}{100} + \frac{1-\nu}{32} & \frac{1+\nu}{80} & -\frac{1}{100} & -\frac{1-\nu}{80} & -\frac{1-\nu}{32} & -\frac{\nu}{40} & 0 & 0\\ \frac{1+\nu}{80} & \frac{1}{16} + \frac{1-\nu}{200} & -\frac{\nu}{40} & -\frac{1-\nu}{200} & -\frac{1-\nu}{80} & -\frac{1}{16} & 0 & 0\\ -\frac{1}{100} & -\frac{\nu}{40} & \frac{1}{100} + \frac{1-\nu}{32} & 0 & 0 & \frac{1+\nu}{80} & -\frac{1-\nu}{32} & -\frac{1-\nu}{80}\\ -\frac{1-\nu}{80} & -\frac{1-\nu}{200} & 0 & \frac{1}{16} + \frac{1-\nu}{200} & \frac{1+\nu}{80} & 0 & -\frac{\nu}{40} & -\frac{1}{16}\\ -\frac{1-\nu}{32} & -\frac{1-\nu}{80} & 0 & \frac{1+\nu}{80} & \frac{1}{100} + \frac{1-\nu}{32} & 0 & -\frac{1}{100} & \frac{\nu}{40}\\ -\frac{\nu}{40} & -\frac{1}{16} & \frac{1+\nu}{80} & 0 & 0 & \frac{1}{16} + \frac{1-\nu}{200} & \frac{1-\nu}{80} & -\frac{1-\nu}{200}\\ 0 & 0 & -\frac{1-\nu}{32} & -\frac{\nu}{40} & -\frac{1}{100} & -\frac{1-\nu}{80} & \frac{1}{100} + \frac{1-\nu}{32} & \frac{1+\nu}{80}\\ 0 & 0 & -\frac{1-\nu}{80} & -\frac{1}{16} & -\frac{\nu}{40} & -\frac{1-\nu}{200} & \frac{1+\nu}{80} & \frac{1}{16} + \frac{1-\nu}{200} \end{bmatrix}$$

lacktriangle The load vector R is equal to $R_{\rm C}$ because there are only concentrated forces on the nodes

$$\mathbf{R} = \begin{bmatrix} F_{1x} \\ F_{1y} \\ 0 \\ 0 \\ F_{3x} \\ F_{3y} \\ 0 \\ -P_{y} \end{bmatrix}$$

 Solving for the unknown nodal point displacements from the following equation

$$\begin{bmatrix} k_{11} & k_{12} & k_{13} & \cdot & \cdot & \cdot & k_{17} & k_{18} \\ k_{21} & k_{22} & k_{23} & \cdot & \cdot & \cdot & k_{27} & k_{28} \\ \cdot & U_{3} \\ \cdot & U_{4} \\ \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & U_{5} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & U_{5} \\ k_{71} & k_{72} & k_{73} & \cdot & \cdot & \cdot & k_{77} & k_{78} \\ k_{81} & k_{82} & k_{83} & \cdot & \cdot & \cdot & k_{87} & k_{88} \end{bmatrix} \begin{bmatrix} U_{1} \\ U_{2} \\ U_{3} \\ U_{4} \\ U_{5} \\ U_{6} \\ U_{7} \\ U_{8} \end{bmatrix} = \begin{bmatrix} F_{1x} \\ F_{1y} \\ 0 \\ 0 \\ F_{3x} \\ F_{3y} \\ 0 \\ -P_{y} \end{bmatrix}$$

 Applying the boundary conditions as below

$$\begin{bmatrix} k_{11} & k_{12} & k_{13} & \cdot & \cdot & \cdot & k_{17} & k_{18} \\ k_{21} & k_{22} & k_{23} & \cdot & \cdot & \cdot & k_{27} & k_{28} \\ \cdot & U_{3} \\ \cdot & U_{4} \\ \cdot & U_{4} \\ \cdot & U_{4} \\ \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & \cdot & \cdot & \cdot & U_{4} \\ \cdot & U_{5} \\ \cdot & \cdot & U_{7} \\ \cdot & U_{8} \end{bmatrix} = \begin{bmatrix} F_{1x} \\ F_{1y} \\ 0 \\ 0 \\ F_{3x} \\ F_{3y} \\ 0 \\ -P_{y} \end{bmatrix}$$

Partitioned into two parts as follows

$$\begin{bmatrix} k_{33} & k_{34} & k_{37} & k_{38} \\ k_{43} & k_{44} & k_{47} & k_{48} \\ k_{73} & k_{74} & k_{77} & k_{78} \\ k_{83} & k_{84} & k_{87} & k_{88} \end{bmatrix} \begin{bmatrix} U_3 \\ U_4 \\ U_7 \\ U_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -P_y \end{bmatrix}$$

$$\begin{bmatrix} k_{13} & k_{14} & k_{17} & k_{18} \\ k_{23} & k_{24} & k_{27} & k_{28} \\ k_{53} & k_{54} & k_{57} & k_{58} \\ k_{63} & k_{64} & k_{67} & k_{68} \end{bmatrix} \begin{bmatrix} U_3 \\ U_4 \\ U_7 \\ U_8 \end{bmatrix} = \begin{bmatrix} F_{1x} \\ F_{1y} \\ F_{3x} \\ F_{3y} \end{bmatrix}$$



Finite Element Modeling

- Preparing data to do finite element analysis
- Building geometry, generating meshes, applying boundary conditions and loads, providing material properties, specifying analysis type
- Done by using preprocessor



Finite Element Modeling – cont'

1. Export CAD data to pre-processor through IGES file or CAD file directly

"Defeaturing" geometry may be necessary to hide features that do not affect the accuracy



Finite Element Modeling – cont'

2. Generate meshes and nodes Automatic tetrahedral meshing for solid geometry

Quadrilateral or triangular elements for 3D surface, shell, 2D geometry.

Mesh density can be controlled

Finite Element Modeling – cont'

- 3. Select type of analysis (static/dynamic, linear/non-linear, plane stress, plane strain)
- 4. Assign boundary conditions: B.C.'s at arbitrary locations can be converted to equivalent B.C's at nodes
- 5. Assign material properties: Different properties for each element can be assigned
- 6. Activate analysis code
- 7. Output results using post-processor