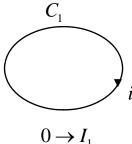
# Magnetic energy

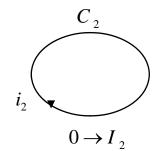
- ❖ Steady d.c current → inductors appear as short circuits
- **❖** Alternating currents → effects of inductances on circuits and magnetic fields
- **❖** Assuming quasi-static conditions → currents vary very slowly in time
  - → imply that dimensions of the circuits are very small in comparison to the wavelength
  - → enough to ignore retardation and radiation effect
  - *cf* ) ➤ Electrostatic energy : work to assemble charges
    - Magnetostatic energy: work to send current into conducting loops
    - $\triangleright$  Genarator is connected to the loop  $\rightarrow$  current i increases from 0 to  $I_1$ 
      - $\Rightarrow$  current change  $\Rightarrow$  emf will be induced in the loop to oppose the change of magnetic flux(*i.e.* the change of current)
      - $\Rightarrow$  work will be done to overcome this induced emf let  $v_1 = L_1 \frac{di_1}{dt} \Rightarrow$  voltage across the inductance

# Magnetic energy

• Work, 
$$W_1 = \int v_1 i_1 dt = L_1 \int_0^{I_1} i_1 di_1 = \frac{1}{2} L_1 I_1^2$$

$$\therefore W_1 = \frac{1}{2} L_1 I_1^2 = \frac{1}{2} I_1 \Phi_1 \quad \text{: stored as magnetic energy}$$





- Two circuit cases
  - ① let  $i_2 = 0$ ,  $i_1 = 0 \rightarrow I_1$  $\Rightarrow$  work  $W_1$  in loop  $C_1$ , no work in loop  $C_2$  (::  $i_2 = 0$ )
  - ② keep  $i_1$  at  $I_1, i_2 = 0 \rightarrow I_2$

induced emf that must be overcome by an external source

$$v_{21} = L_{21} \frac{di_2}{dt}$$
 in order to keep  $i_1$  constant at its value  $I_1$ 

$$W_{21} = \int v_{21} I_1 dt = L_{21} I_1 \int_0^{I_2} di_2 = L_{21} I_1 I_2$$

# Magnetic energy

In loop 
$$C_2 \Rightarrow W_{22} = \frac{1}{2}L_2I_2^2$$

 $\therefore$  total work done in raising the currents in loops  $C_1$  and  $C_2$  from zeros to  $I_1$  and  $I_2$ 

$$W_2 = \frac{1}{2}L_1I_1^2 + L_{21}I_1I_2 + \frac{1}{2}L_2I_2^2 = \frac{1}{2}\sum_{j=1}^2\sum_{k=1}^2L_{jk}I_jI_k \quad \because L_{12} = L_{21}$$

Generalization

N loops carrying 
$$I_1, I_2, I_3 .... I_n$$
 
$$W_m = \frac{1}{2} \sum_{j=1}^{N} \sum_{k=1}^{N} L_{jk} I_j I_k [J]$$

Energy stored in the magnetic field

for a current flowing in a single inductor  $W_m = \frac{1}{2}LI^2$ 

$$W_m = \frac{1}{2}LI^2$$

 $\bullet$  The work done to k-th loops in time dt

$$dW_k = v_k i_k dt = i_k d\phi_k \quad cf)v_k = \frac{d\phi_k}{dt}$$

$$dW_m = \sum_{k=1}^N dW_k = \sum_{k=1}^N i_k d\phi_k$$

$$\therefore W_m = \int dW_m = \sum_{k=1}^N I_k \phi_k \int_0^1 \alpha d\alpha = \frac{1}{2} \sum_{k=1}^N I_k \phi_k \quad cf) i_k = \alpha I_k, \phi_k = \alpha \Phi_k, \alpha = 0 \to 1$$

## Magnetic energy in terms of field quantities

- ❖ A single current-carrying loop ⇒ large number (N) of contiguous filamentary current elements of closed paths  $C_k$  ⇒ each path with a current  $\Delta I_k$  flowing in an infinitesimal cross-sectional area  $\Delta a_k$ 
  - $\Rightarrow$  linking with magnetic flux  $\Phi_{k}$

$$\Phi_k = \int_{S_k} \vec{B} \cdot \hat{n} ds_k = \oint_{C_k} \vec{A} \cdot \vec{dl}_k \quad (S_k: \text{ surface boundary by } C_k)$$

$$W_m = \frac{1}{2} \sum_{k=1}^{N} \Delta I_k \Phi_k = \frac{1}{2} \sum_{k=1}^{N} \Delta I_k \oint_{C_k} \overrightarrow{A} \cdot \overrightarrow{dl_k}$$

where 
$$\Delta I_k \overrightarrow{dl_k} = J(\Delta a_k) \overrightarrow{dl_k} = \overrightarrow{J} \Delta v_k$$
 when  $N \to \infty$ ,  $\Delta v_k \to dv' \Rightarrow \sum_{k=1}^N \oint_{C_k} \Delta I_k \overrightarrow{dl_k} \to \int_{V'} \overrightarrow{J} dv'$ 

$$W_{m} = \frac{1}{2} \int_{V'} \overrightarrow{A} \cdot \overrightarrow{J} dv' \qquad cf) W_{e} = \frac{1}{2} \int_{V'} \rho V dv'$$

ightharpoonup How to express  $W_m$  in terms of  $\overrightarrow{B}$  and  $\overrightarrow{H}$ 

$$\vec{A} \cdot \vec{J} = \vec{A} \cdot (\nabla \times \vec{H})$$

Using vector identity and  $\nabla \times \vec{A} = \vec{B}$ ,  $\nabla \cdot (\vec{A} \times \vec{H}) = \vec{H} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{H})$ 

$$\therefore \vec{A} \cdot \vec{J} = \vec{H} \cdot \vec{B} - \nabla \cdot (\vec{A} \times \vec{H})$$

## Magnetic energy in terms of field quantities

$$W_{m} = \frac{1}{2} \int_{V'} \overrightarrow{H} \cdot \overrightarrow{B} dv' - \frac{1}{2} \oint_{S'} (\overrightarrow{A} \times \overrightarrow{H}) \cdot \widehat{n} ds'$$

$$cf) |\overrightarrow{A}| \propto \frac{1}{R} \text{ and } \rangle |\overrightarrow{H}| \propto \frac{1}{R^{2}} \text{ but } S' \propto R^{2} \qquad \therefore R \to \infty, \quad \oint_{S'} (\overrightarrow{A} \times \overrightarrow{H}) \cdot \widehat{n} ds \to 0$$

$$\vdots W_{m} = \frac{1}{2} \int_{V'} \overrightarrow{H} \cdot \overrightarrow{B} dv' = \frac{1}{2} \int_{V'} \frac{B^{2}}{\mu} dv' = \frac{1}{2} \int_{V'} \mu H^{2} dv' \qquad cf) W_{e} = \frac{1}{2} \int_{V'} \overrightarrow{E} \cdot \overrightarrow{D} dv'$$
Assuming linear medium

❖ Defining a magnetic energy density W<sub>m</sub>

$$W_m = \int_{V'} w_m dv' \quad \text{where} \quad w_m = \frac{1}{2} \overrightarrow{H} \cdot \overrightarrow{B} = \frac{B^2}{2\mu} = \frac{1}{2} \mu H^2 \quad [J/m^3]$$

$$note) \quad W_m = \frac{1}{2} L I^2 \quad \therefore \quad L = \frac{2W_m}{I^2}$$

## Ex 6-20) The inductance of an air coaxial cable

By using stored magnetic energy, determine the inductance per unit length of an air coaxial cable

sol) the magnetic energy per unit length



$$\begin{array}{c}
\downarrow \\
b \\
\downarrow \\
a
\end{array}$$



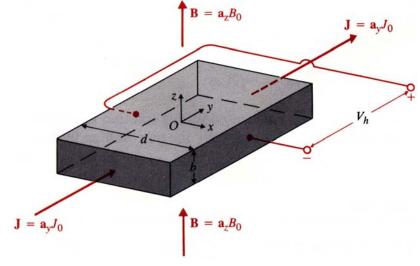
$$W'_{m1} = \frac{1}{2\mu_0} \int_0^a B_{\phi 1}^2 2\pi r dr = \frac{1}{2\mu_0} \int_0^a (\frac{\mu_0 r I}{2\pi a^2})^2 \cdot 2\pi r dr$$
$$= \frac{\mu_0 I^2}{4\pi a^4} \int_0^a r^3 dr = \frac{\mu_0 I^2}{16\pi} [J/m]$$

➤ In the region between two conductors :

$$W'_{m2} = \frac{1}{2\mu_0} \int_a^b B_{\phi 2}^2 2\pi r dr = \frac{1}{2\mu_0} \int_a^b (\frac{\mu_0 I}{2\pi r})^2 \cdot 2\pi r dr$$
$$= \frac{\mu_0 I^2}{4\pi} \int_a^b \frac{1}{r} dr = \frac{\mu_0 I^2}{4\pi} \ln \frac{b}{a} \quad [J/m]$$
$$\therefore L' = \frac{2W'_m}{I^2} = \frac{\mu_0}{8\pi} + \frac{\mu_0}{2\pi} \ln \frac{b}{a}$$

# Magnetic forces and torques

- Lorentz force equation
  - $ightharpoonup \vec{F} = q(\vec{E} + \vec{u} \times \vec{B}) \Rightarrow \text{Magnetic force} : \text{experimental law } \vec{F_m} = q\vec{u} \times \vec{B}$
- Hall effect



- > Assuming n-type semiconductor or conducting material
  - $\Rightarrow$  electrons : charge carriers  $\rightarrow$  move into  $-\hat{y}$  direction
  - $\Rightarrow$  magnetic forces act on carriers in the positive x direction
  - ⇒ Transverse electric field to reach the equilibrium
  - $\Rightarrow$  No net force in the steady state

# Magnetic forces and torques

$$\begin{array}{ll} \blacktriangleright \overrightarrow{E_h} + \overrightarrow{u} \times \overrightarrow{B} = 0 & \therefore \overrightarrow{E_h} = -\overrightarrow{u} \times \overrightarrow{B} \Longrightarrow \text{Hall effect,} \\ \overrightarrow{E_h} : \text{Hall field} \\ \overrightarrow{E_h} = -(-\hat{y}u_0) \times \hat{z}B_0 = \hat{x}u_0B_0 \end{array}$$

$$V_h = -\int_0^d E_h dx = u_0 B_0 d$$
 for electron carriers,  $V_h$ : Hall voltage

$$\frac{E_x}{J_y B_z} = \frac{1}{Nq} : \text{Hall coefficient}, \quad \frac{E_x}{J_y B_z} = \frac{u_0 B_0}{Nq u_0 B_0} = \frac{1}{Nq}$$

 $\Rightarrow$  can be used to measure B field and type of charge carriers or carrier density

### Forces and torques on current-carrying conductors

- $\diamond$  consider an element of conductor  $\overrightarrow{dl}$  with a cross-sectional area S
- ❖ N charge carriers/unit volume
- Assuming electrons

$$d\overrightarrow{F_m} = -NeS \left| \overrightarrow{dl} \right| \overrightarrow{u} \times \overrightarrow{B} = -NeS \left| \overrightarrow{u} \right| \overrightarrow{dl} \times \overrightarrow{B} = I \overrightarrow{dl} \times \overrightarrow{B}$$

 $\Rightarrow$  Magnetic force on a complete(closed) circuit of contour C carrying a current I in a magnetic field  $\overrightarrow{B}$ 

$$\overrightarrow{F_m} = I \oint_C \overrightarrow{dl} \times \overrightarrow{B} \quad [N]$$

 $\it cf$  ) two circuits carrying currents  $\it I_1$  and  $\it I_2$ 

 $\Rightarrow \overrightarrow{B_{21}}$  caused by the current  $I_2$  in  $C_2$ , the force  $\overrightarrow{F_{21}}$  on circuit  $C_1$ 

$$\overrightarrow{F_{21}} = I_1 \oint_{C_1} \overrightarrow{dl}_1 \times \overrightarrow{B_{21}}, \text{ where } \overrightarrow{B_{21}} = \frac{\mu_0 I_2}{4\pi} \oint_{C_2} \frac{\overrightarrow{dl}_2 \times \widehat{R_{21}}}{R_{21}^2}$$

$$\overrightarrow{F_{21}} = \frac{\mu_0 I_1 I_2}{4\pi} \oint_{C_1} \oint_{C_2} \frac{\overrightarrow{dl_1} \times (\overrightarrow{dl_2} \times \widehat{R_{21}})}{R_{21}^2} \quad [N] \quad : \text{ Ampere's law of force}$$

### Forces and torques on current-carrying conductors

$$\overrightarrow{F_{12}} = \frac{\mu_0 I_1 I_2}{4\pi} \oint_{C_2} \oint_{C_1} \frac{\overrightarrow{dl}_2 \times (\overrightarrow{dl_1} \times \widehat{R_{12}})}{R_{12}^2}$$

• Question  $\overrightarrow{F_{12}} = -\overrightarrow{F_{21}}$  or not ? since  $\overrightarrow{dl}_2 \times (\overrightarrow{dl_1} \times \widehat{R_{12}}) \neq -\overrightarrow{dl}_1 \times (\overrightarrow{dl_2} \times \widehat{R_{21}})$ 

$$\frac{\overrightarrow{dl}_{1} \times (\overrightarrow{dl}_{2} \times \widehat{R}_{21})}{R_{21}^{2}} = \frac{\overrightarrow{dl}_{2}(\overrightarrow{dl}_{1} \bullet \widehat{R}_{21})}{R_{21}^{2}} - \frac{\widehat{R}_{21}(\overrightarrow{dl}_{2} \bullet \overrightarrow{dl}_{1})}{R_{21}^{2}}$$

$$\oint_{C_{1}} \oint_{C_{2}} \frac{\overrightarrow{dl}_{2}(\overrightarrow{dl}_{1} \bullet \widehat{R}_{21})}{R_{21}^{2}} = \oint_{C_{2}} \overrightarrow{dl}_{2} \oint_{C_{1}} \frac{\overrightarrow{dl}_{1} \bullet \widehat{R}_{21}}{R_{21}^{2}} = \oint_{C_{2}} \overrightarrow{dl}_{2} \oint_{C_{1}} \overrightarrow{dl}_{1} \bullet (-\nabla_{1} \frac{1}{R_{21}})$$

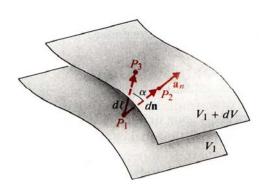
$$cf) \nabla_{1} \frac{1}{R_{21}} = -\frac{\widehat{R}_{21}}{R_{21}^{2}} \quad i.e) \nabla'(\frac{1}{R}) = \frac{\widehat{R}}{R^{2}}, \quad \nabla(\frac{1}{R}) = -\frac{\widehat{R}}{R^{2}}, \quad R_{21} = \sqrt{(x_{1} - x_{2})^{2} + (y_{1} - y_{2})^{2} + (z_{1} - z_{2})^{2}}$$

$$cf)\nabla V \triangleq \hat{n}\frac{dV}{dn}$$

$$\frac{dV}{dl} = \frac{dV}{dn}\frac{dn}{dl} = \frac{dV}{dn}\cos\alpha = \frac{dV}{dn}\hat{n} \cdot \hat{l} = (\nabla V) \cdot \hat{l} \quad \because dV = (\nabla V) \cdot \hat{l}dl = \nabla V \cdot \vec{dl}$$

$$\therefore \vec{dl} \cdot (-\nabla \frac{1}{R_{cl}}) = -d(\frac{1}{R_{cl}}) \text{ and } \oint_{C_1} d(\frac{1}{R_{cl}}) = 0$$

$$\therefore \overrightarrow{F_{21}} = -\frac{\mu_0}{4\pi} I_1 I_2 \oint_{C_1} \oint_{C_2} \frac{\widehat{R_{21}}(\overrightarrow{dl}_1 \bullet \overrightarrow{dl}_2)}{R_{21}^2} = -\overrightarrow{F_{12}}$$



### Ex 6-21) Force between two parallel current-carrying wires

Determine the force per unit length between two infinitely long parallel conducting wire carrying  $I_1$  and  $I_2$  in the same direction

sol) 
$$\overrightarrow{F_{12}} = I_2(\widehat{z} \times \overrightarrow{B_{12}}),$$

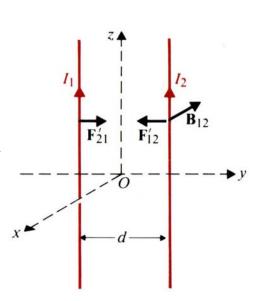
 $\overrightarrow{F_{12}}$ : force per unit length

 $\overrightarrow{B_{12}}$ : magnetic flux density at wire2 by the current  $I_1$   $\Rightarrow$  constant over wire2 and  $-\hat{x}$  direction

$$\overrightarrow{B_{12}} = -\hat{x} \frac{\mu_0 I_1}{2\pi d}$$

$$\therefore \overrightarrow{F_{12}} = -\hat{y} \frac{\mu_0 I_1 I_2}{2\pi d} \Rightarrow \text{ attraction force}$$

$$\overrightarrow{F}_{21} = \hat{y} \frac{\mu_0 I_1 I_2}{2\pi d} \Rightarrow \text{ attraction force}$$



# Torque

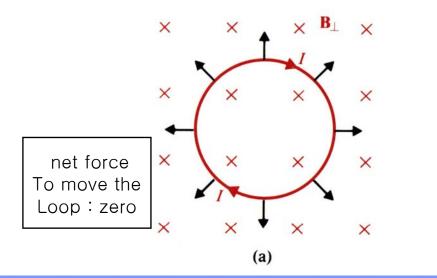
- ❖ A small current loop with radius *b*
- $\stackrel{\bullet}{\bullet}$   $\vec{B}$  field is decomposed into  $B_{\perp}$  and  $B_{\parallel}$

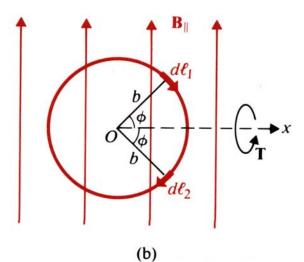
$$i.e)\overrightarrow{B} = \overrightarrow{B_{\perp}} + \overrightarrow{B_{\parallel}}$$

 $\overrightarrow{B_{\perp}}$  is perpendicular to the plane of loop ,  $\overrightarrow{B_{\parallel}}$  is parallel to the plane of loop

then  $I\overrightarrow{dl} \times \overrightarrow{B_{\perp}}$ : expansion or extraction of the loop

 $I\overrightarrow{dl} \times \overrightarrow{B_i}$ : rotational force





# Torque

- Net force to move the loop : zero but net force to rotate the loop ≠ zero → Torque
  - ⇒ In the direction to align the magnetic field due to the loop current with

$$\therefore d\overrightarrow{T} = \hat{x}(dF)2b\sin\phi = \boxed{2\overrightarrow{l}\times\overrightarrow{F}} = \hat{x}(IdlB_{\parallel}\sin\phi)2b\sin\phi = \hat{x}2Ib^{2}B_{\parallel}\sin^{2}\phi d\phi$$
where  $dF = \left|d\overrightarrow{F_{1}}\right| = \left|d\overrightarrow{F_{2}}\right|, \quad \left|\overrightarrow{dl}\right| = \left|\overrightarrow{dl_{1}}\right| = \left|\overrightarrow{dl_{2}}\right| = bd\phi$ 

$$\vec{T} = \int d\vec{T} = \hat{x} 2Ib^2 B_{\parallel} \int_0^{\pi} \sin^2 \phi d\phi = \hat{x} I(\pi b^2) B_{\parallel}$$

$$\vec{T} = \vec{m} \times \vec{B} \quad cf) \vec{m} \times \vec{B} = \vec{m} \times (\vec{B}_{\perp} + \vec{B}_{\parallel}) = \vec{m} \times \vec{B}_{\parallel}$$

Valid only for uniform  $\vec{B}$ 

### Ex 6-22) A rectangular loop in a uniform magnetic field

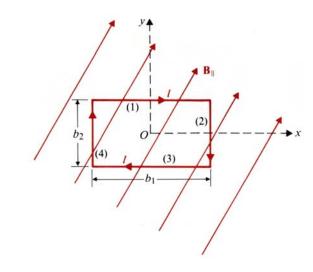
#### Rectangular current loop

→ Determine the force and forque on the loop

$$\triangleright \vec{B} = \hat{x}B_x + \hat{y}B_y + \hat{z}B_z$$

$$\triangleright \overrightarrow{B_{\perp}} = \widehat{z}B_{z}$$

$$\triangleright \overrightarrow{B_{\parallel}} = \hat{x}B_x + \hat{y}B_y$$



- 1 force due to perpendicular  $\overrightarrow{B_{\perp}}$ 
  - side1,  $\hat{x}Ib_1 \times \hat{z}B_z = -\hat{y}Ib_1B_z$  side3,  $-\hat{x}Ib_1 \times \hat{z}B_z = \hat{y}Ib_1B_z$  no net force but contraction side2,  $-\hat{y}Ib_2 \times \hat{z}B_z = -\hat{x}Ib_2B_z$  side4,  $\hat{y}Ib_2 \times \hat{z}B_z = \hat{x}Ib_2B_z$

### Ex 6-22) A rectangular loop in a uniform magnetic field

 $\ \ \,$  ② force due to parallel  $\overrightarrow{B_{\parallel}}$ 

• side1, 
$$\hat{x}Ib_1 \times (\hat{x}B_x + \hat{y}B_y) = \hat{z}Ib_1B_y$$
 • side3,  $-\hat{x}Ib_1 \times (\hat{x}B_x + \hat{y}B_y) = -\hat{z}Ib_1B_y$ 

: no net force but torque  $\vec{T_1} = \hat{x}b_2Ib_1B_y = \hat{x}Ib_1b_2B_y$   $cf)Ib_1b_2 = |\vec{m}|, \vec{m} = -Ib_1b_2\hat{z}$ 

• side2, 
$$-\hat{y}Ib_2 \times (\hat{x}B_x + \hat{y}B_y) = \hat{z}Ib_2B_y$$
, • side4,  $\hat{y}Ib_2 \times (\hat{x}B_x + \hat{y}B_y) = -\hat{z}Ib_1B_y$ 

: no net force but torque  $\overrightarrow{T_2} = -\hat{y}b_1Ib_2B_x = -\hat{y}Ib_1b_2B_x$   $cf)Ib_1b_2 = |\overrightarrow{m}|$ 

$$\vec{T} = \vec{T}_1 + \vec{T}_2 = \vec{m} \times \vec{B}$$

### Forces and torques in terms of stored magnetic energy

- \* Find magnetic forces and torques based on the principle of virtual displacement
  - ① A system of circuits with constant magnetic flux linkage
  - ② A system of circuits with constant currents
- 1. constant flux linkages
  - Assuming that no changes in flux linkages result from a virtual differential displacement *dl* of one of current carrying circuits
  - $\Rightarrow$  no induced emf's  $\Rightarrow$  the source will supply no energy to the system
  - ⇒ mechanical work done by the system is at the expense of a decrease in the stored magnetic energy

$$cf$$
)emf= $L\frac{di}{dt}$  or  $\frac{d\Phi}{dt}$ 

$$\overrightarrow{F_{\Phi}} \bullet \overrightarrow{dl} = -dW_m = -(\nabla W_m) \bullet \overrightarrow{dl}$$

$$\therefore \overrightarrow{F_{\Phi}} = -\nabla W_m, \ (F_{\Phi})_x = -\frac{\partial W_m}{\partial x}, (F_{\Phi})_y = -\frac{\partial W_m}{\partial y}, (F_{\Phi})_z = -\frac{\partial W_m}{\partial z}$$

if the circuit is constrained to rotate about an axis(z-axis) the mechanical work done by the system will be  $(T_{\Phi})_z d\phi$ 

$$\left(T_{\Phi}\right)_{z} = -\frac{\partial W_{m}}{\partial \phi}$$

### Forces and torques in terms of stored magnetic energy

#### 2. constant currents

 $\triangleright$  circuit connected to current sources  $\Rightarrow$  counteract the induced emf's resulting from changes in flux linkages by a virtual displacement dl.

the work done or energy supplied by the source

$$dW_s = \sum_k I_k d\Phi_k$$

this energy be equal to the sum of the mechanical work done by the system

 $dW = \overrightarrow{F_I} \cdot \overrightarrow{dl}$  and the increase in the stored magnetic energy  $dW_m$ 

$$dW_{s} = dW + dW_{m}, \quad dW_{m} = \frac{1}{2} \sum_{k} I_{k} d\Phi_{k} = \frac{1}{2} dW_{s}$$

$$dW = \overrightarrow{F} \cdot \overrightarrow{dl} = dW_m = (\nabla W_m) \cdot \overrightarrow{dl}$$

$$\therefore \overrightarrow{F_I} = \nabla W_m$$
,  $(T_I)_z = \frac{\partial W_m}{\partial \phi}$  with a constraint. sign difference  $\rightarrow$  different constraint

#### Forces and torques in terms of mutual inductance

for two circuits,

$$W_m = \frac{1}{2}L_1I_1^2 + \frac{1}{2}L_2I_2^2 + L_{12}I_1I_2$$

under the conditions of constant current, assume one of circuits has a virtual displacement

$$\Rightarrow$$
 change in  $W_{\scriptscriptstyle m}$ ,  $\overrightarrow{F_{\scriptscriptstyle I}} = I_{\scriptscriptstyle 1} I_{\scriptscriptstyle 2} \nabla L_{\scriptscriptstyle 12}$ 

Torque 
$$(T_I)_z = I_1 I_2 \frac{\partial L_{12}}{\partial \phi}$$