



Induction Variables and Strength Reduction

- * Overview of Optimization
- * Algorithms to find induction variables
- * Summary: 14.1



A Strength Reduction Example

```
FOR i = 0 to 100  
  A[i] = 0;
```

$i = 0$

$t2' = 4 * 0 + \&A = \&A$

$t3 = 4 * 100 + \&A$

L2: if ($i \geq 100$) goto L1

L2: if ($t2' \geq t3$)

$t1 = 4 * i$

$t2 = \&A + t1 \implies$

$*t2 = 0$

$*t2' = 0$

$i = i + 1$

goto L2

L1:

$t2' = t2' + 4$

goto L2

L1:



Definitions

- * A **basic induction variable (BIV)** is a variable X
 - * whose only definitions within the loop are assignments of the form $X = X + c$ or $X = X - c$, where c is either a constant or a loop-invariant variable
- * An **induction variable** is
 - * a basic induction variable
 - * a variable defined once within the loop, whose value is a linear function of some basic induction variable at the time of definition
$$A = c1 \times B + c2$$
- * The **family of a basic induction variable** B
 - * the set of induction variables A such that each time A is assigned in the loop, the value of A is a linear function of B



Strength Reduction

- * Strength Reduction

Let A be an induction variable in a family of basic induction variable B

(i.e., $A = c1 \times B + c2$)

- * Create a new variable: A'
- * Initialization in preheader: $A' = c1 \times B + c2$
- * Track value of B : add after $B = B + x$: $A' = A' + x \times c1$
- * Replace assignment to A : $A = A'$



A Strength Reduction Example

- * There are two induction variables in the example below

* $t1 = 4 * i$ (create $t1' = 4 * i$)

* $t2 = 4 * i + \&A$ (create $t2' = 4 * i + \&A$)

$i = 0$

L2: if ($i \geq 100$) goto L1

$t1 = 4 * i$

$t2 = \&A + t1$

$*t2 = 0$

$i = i + 1$

goto L2

L1:



Strength Reduction Example

```
FOR i = 0 to 100  
  A[i] = 0;
```

```
      i = 0  
L2: if (i >= 100) goto L1  
    t1 = 4 * i  
    t2 = &A + t1    ==>  
    *t2 = 0  
    i = i + 1  
    goto L2  
L1:
```

```
      i = 0          /* Deleted */  
    t1' = 4 * i = 0 /* Deleted */  
    t2' = 4 * i + &A = &A  
    t3 = 4*100 + &A  
L2: if (t2' >= t3)  
    t1 = t1'        /* Deleted (dead)*/  
    t2 = t2'        /* Propagated into */  
    *t2 = 0         /* *t2' = 0 */  
    i = i + 1      /* Deleted (dead) */  
    t1' = t1' + 4  /* Deleted (dead) */  
    t2' = t2' + 4  
    goto L2  
L1:
```



Follow-up Optimizations

- * Optimizing non-basic induction variables
 - * Copy propagation (e.g., t_2)
 - * Dead code elimination (e.g., t_1)
- * Optimizing basic induction variables (e.g., i) eliminates BIVs used only for calculating other induction variables and loop tests
 - * Select an induction variable A in the family of B , preferably with simple constants (e.g., $A = c_1 \times B + c_2$)
 - * Replace a comparison such as “if $B > x$ goto L_1 ” by “if $(A' > c_1 \times x + c_2)$ goto L_1 ”, assuming c_1 is positive
 - * Called linear function test replacement (LFTR)
 - * If B is live at any exit from the loop, recompute it from A' after the exit, $B = (A' - c_2)/c_1$



Strength Reduction with non-trivial BIVs

- * When there are multiple definitions for a BIV

Example:

```
k = 0;
for (i = 0; i < n; i++) {
    k = k + 3;
    .. = m;
    if (x < y)
        k = k + 4;
    if (a < b)
        m = 2 * k;
    k = k - 2;
    .. = m;
}
```

Each iteration may execute a different number of increments/decrements



Strength Reduction with non-trivial BIVs

We can still do strength reduction, removing multiplication

```
k = 0;
m' = 2 * k = 0;
for (i = 0; i < n; i++) {
    k = k + 3;
    m' = m' + 6;
    .. = m;
    if (x < y) {
        k = k + 4;
        m' = m' + 8;
    }

    if (a < b)
        m = m';
    k = k - 2;
    m' = m' - 4;
    .. = m;
}
```