



# Modulo Scheduling

\*Modulo Scheduling



# Modulo Scheduling

- \* **Most popular** software pipelining technique
  - \* Originally developed by B. Rau, later simplified by M. Lam
  - \* **All** commercial compilers include this technique
    - \* Another commercial technique is EPS
- \* Trial-and-error method to get a pipelined schedule
  - \* Compute the **minimum initiation interval ( $MII$ )** based on both precedence constraints (**precedence  $MII$** ) and resource constraints (**resource  $MII$** )
  - \* Try to obtain a schedule with such an  $MII$ 
    - \* Based on instruction placement, not code motion
  - \* If cannot find a schedule, try with  $MII + 1$ , and continue

# Determining *MII* : Resource Constraints

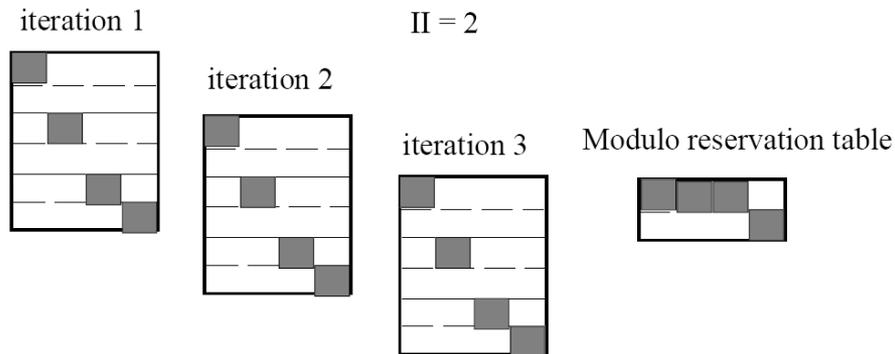
- \* Representation of resource constraints:  
**reservation table**

cycles	issue slot	ALU	multiplier		r1	r2	r3
0	█		█		█	█	█
1			█				█
2							█

**A reservation table for "MUL r1 r2 r3"**

# Resource Constraints and the $\Pi$

- \* If an instruction is scheduled at cycle  $x$ , it will also execute at cycle  $x + \Pi$ ,  $x + 2 \times \Pi$ , and so on
- \* The resource requirements of a single iteration should not exceed the available resources
- \* The available resources of the kernel increase as the  $\Pi$  increases





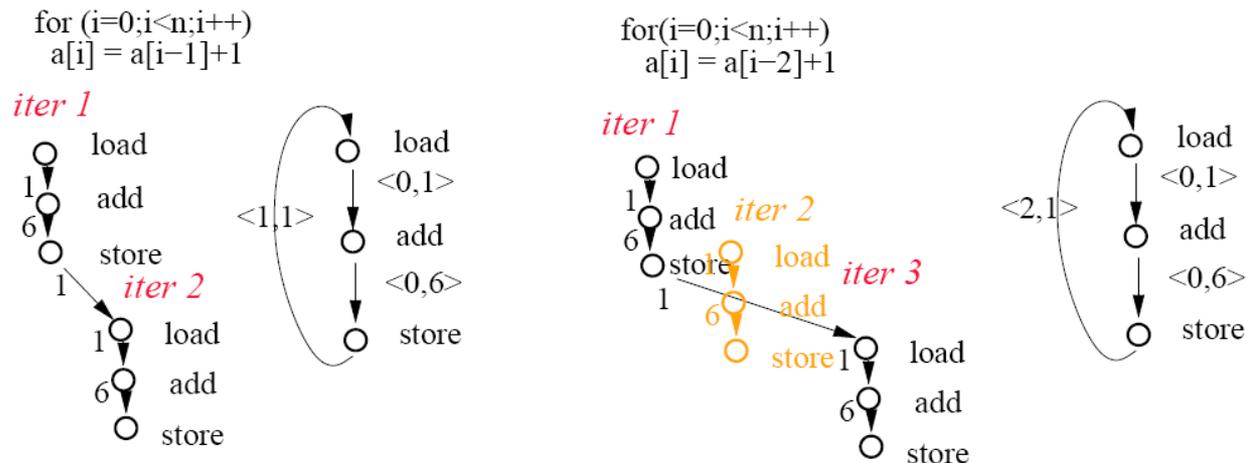
# Resource MII (*RMII*)

- \* For all resources  $i$ ,
  - \* Number of units required by one iteration:  $r_i$
  - \* Number of units in system:  $R_i$
  - \*  $RMII = \max_i \left\lceil \frac{r_i}{R_i} \right\rceil$
- \* If the ratio is not integral, unrolling can improve the lower bound (e.g., 3 mem refs / 2mem ports = 1.5)



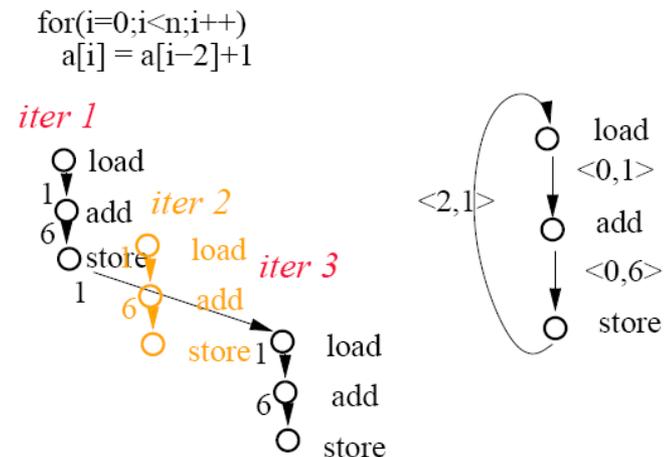
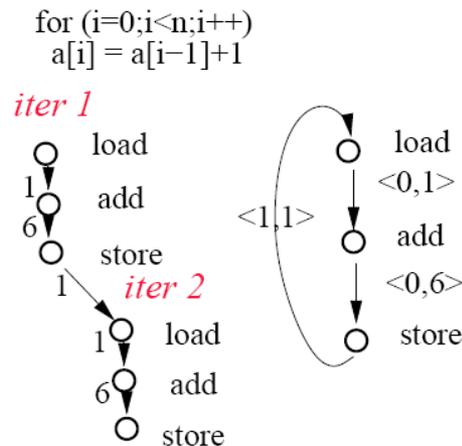
# Determining *MII* : Precedence Constraints

- \* Representation of precedence constraints: **data dependence graph**
  - \* **Node**: instruction, **Edge**: dependence relationship
- \* Observation of dependence relationship
  - \* Must show **iteration difference** as well as **delay**



# Determining $MII$ : Precedence Constraints

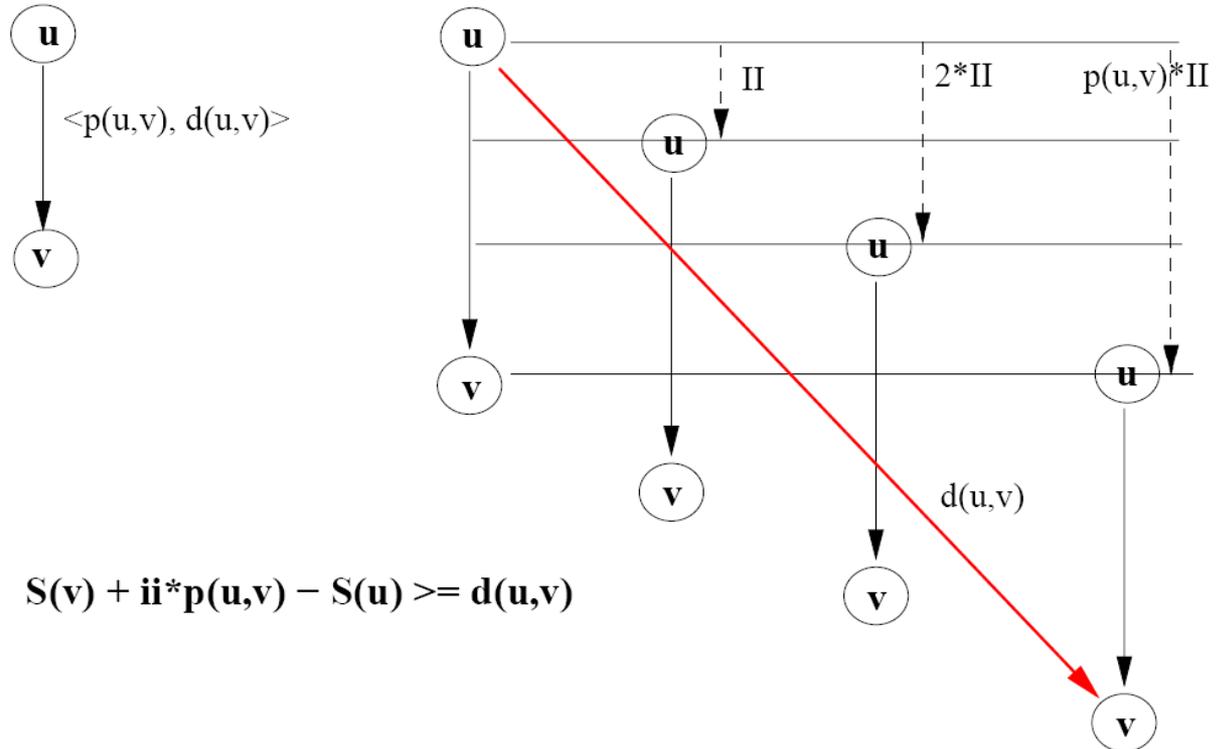
- \* An edge  $u \rightarrow v$  in data dependence graph has  $\langle p, d \rangle$ 
  - \*  $d$  : a delay value
    - \*  $V$  can start no earlier than  $d$  cycles after node  $u$  starts
  - \*  $p$  : a value representing minimum iteration distances
    - \*  $p = 0$  : intra-iteration dependence,  $p > 0$  : loop-carried dependence
- \* Some observation of precedence  $MII$ 
  - \* **8 cycles** in the left example but **4 cycles** in the right example



# II and the Schedule

- \* Given an initiation interval  $II$  and  $S(x)$  is the cycle where  $x$  is scheduled,

$$S(v) - S(u) \geq d(u, v) - II \times p(u, v)$$





# Precedence MII (PMII)

For all cycles  $c$  in the data dependence graph

$$PMII = \max_c \frac{\text{cycle\_length}}{\text{iteration\_differences}}$$

- \* Why? For each dependence edge in the cycle,
  - \* Represent  $S(v) - S(u) \geq d(u, v) - p(u, v) * II$
  - \* Then, sum them up, which will make
    - \*  $0 \geq \text{sum}(d) - \text{sum}(p) * II$ , meaning  $II \geq \text{sum}(d)/\text{sum}(p)$
- \* If the PMII ratio is not integral, unrolling can improve the lower bound



# Modulo Scheduling

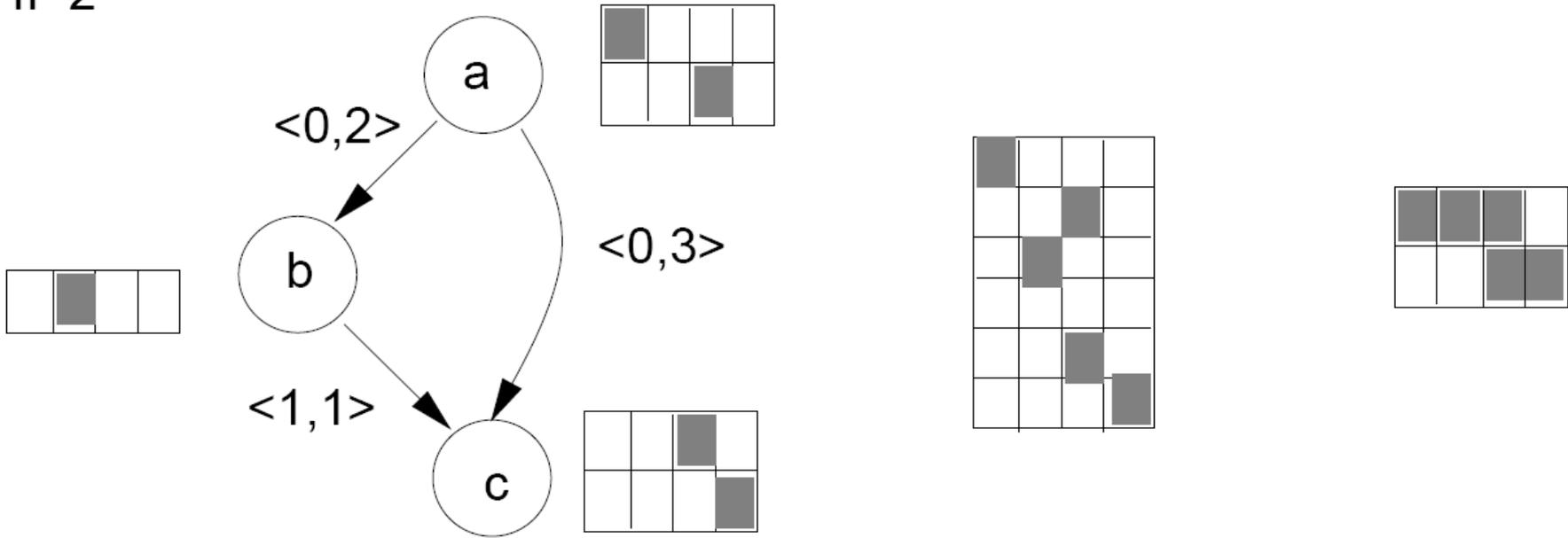
- \* Determining Minimum Initiation Interval (MII)
  - \*  $MII = \min(RMII, PMII)$
- \* Interdependence between // and constraints
  - \* Constraints determine the minimum //
  - \* // affects modulo reservation tables, scheduling functions,  $S(x)$ , etc
  - \* Minimizing // is NP-complete
- \* Goal of scheduling
  - \* Determine //
  - \* Solve the scheduling function  $S(x)$  for each instruction in the loop



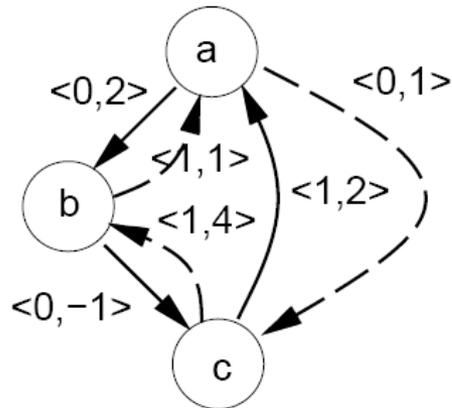
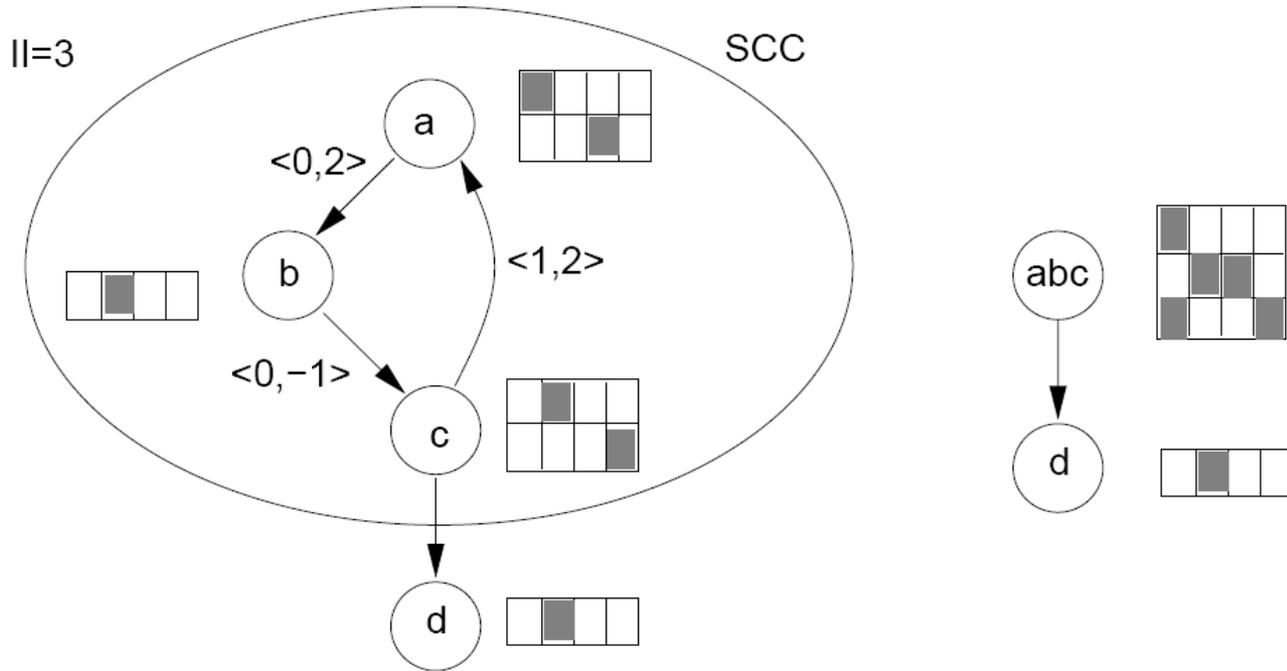
# Generating Pipelined Schedules

## \* Scheduling Acyclic Data Dependence Graph: List Scheduling

II=2



# Scheduling Cyclic Graph



$$S(b) \geq S(a) + 2$$

$$S(a) + ii \geq S(b) + 1$$

$$S(a) + ii - 1 \geq S(b) \geq S(a) + 2$$



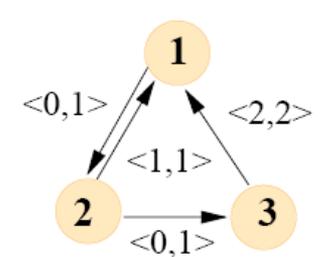
# Cyclic Precedence Constraints

- \* Observation: scheduling a node make the schedules of all other nodes from above and below
  - \* Depends on the II
- \* Implementation: pre-compute **longest path lengths** between all points based on II value
  - \* Once for all II by using a symbolic value for II
  - \* Why longest paths? Meeting worst-case constraints



# Why Longest Path? An Example

- (1)  $a[i] = c[i] + b[i]$        $T(2) - T(1) \geq 1$
- (2)  $b[i-1] = a[i]$        $T(1) + ii - T(2) \geq 1$        $T(1) - T(2) \geq 1 - ii$
- (3)  $c[i-2] = b[i-1]$        $T(1) + 2*ii - T(2) \geq 3$        $T(1) - T(2) \geq 3 - 2*ii$



longest path from 2 to 1      when  $ii = 2$       when  $ii = 3$

bigger one between  $1-ii$  and  $3-2ii$

$T(1) = 0$        $T(1) = 0$

$T(2) = 1$        $T(2) \leq 2$  or  $T(2) \leq 3$

$ii=3 \quad T(2) \leq 2$

$ii=3 \quad T(2) \leq 3$

0	$a[i] = c[i] + b[i]$	$a[i] = c[i] + b[i]$
1		
2	$b[i-1] = a[i]$	
3	$c[i-2] = b[i-1] \quad a[i] = c[i] + b[i]$	$b[i-1] = a[i] \quad a[i] = c[i] + b[i]$
4		$c[i-2] = b[i-1]$
5	$b[i-1] = a[i]$	
6	$c[i-2] = b[i-1] \quad a[i] = c[i] + b[i]$	$b[i-1] = a[i]$
7		$c[i-2] = b[i-1]$

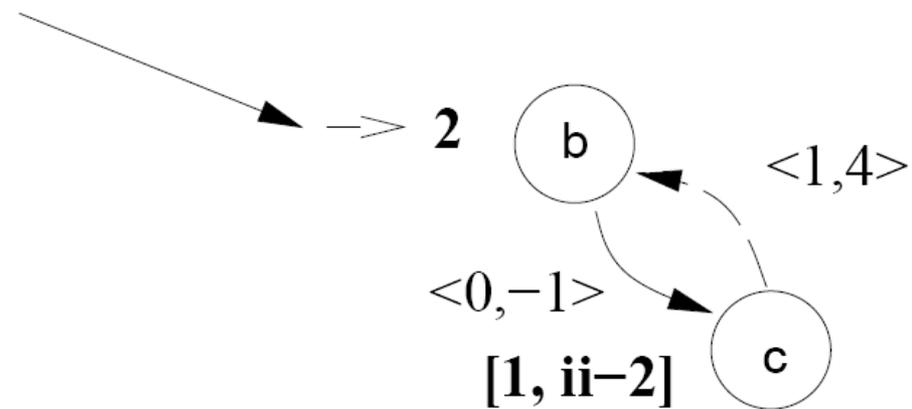
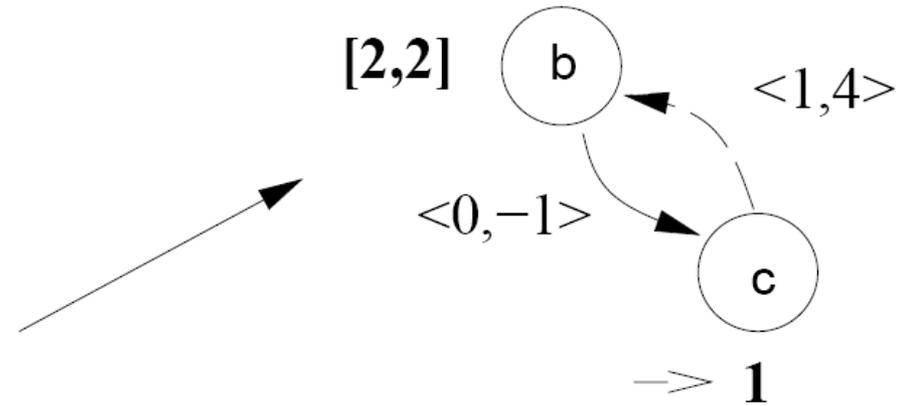
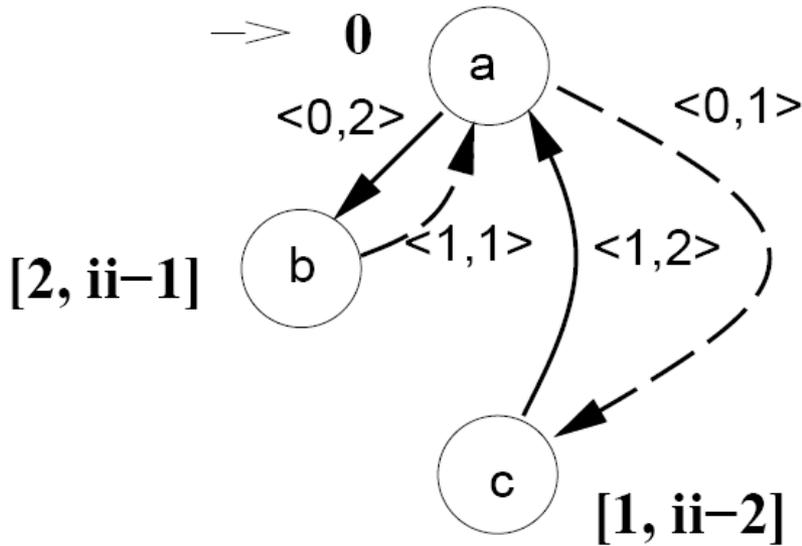


# Longest Paths

- \* The closure of the cost of a path  $e$ 
  - \*  $d(e) - \text{ii} \times p(e)$
  - \* To capture all possible maximum costs between two nodes, the longest path is represented as a set

# Scheduling Order

$ii \geq 3$



- \* Topological ordering on intra-iteration constraints
- \* Upper bounds increases with //

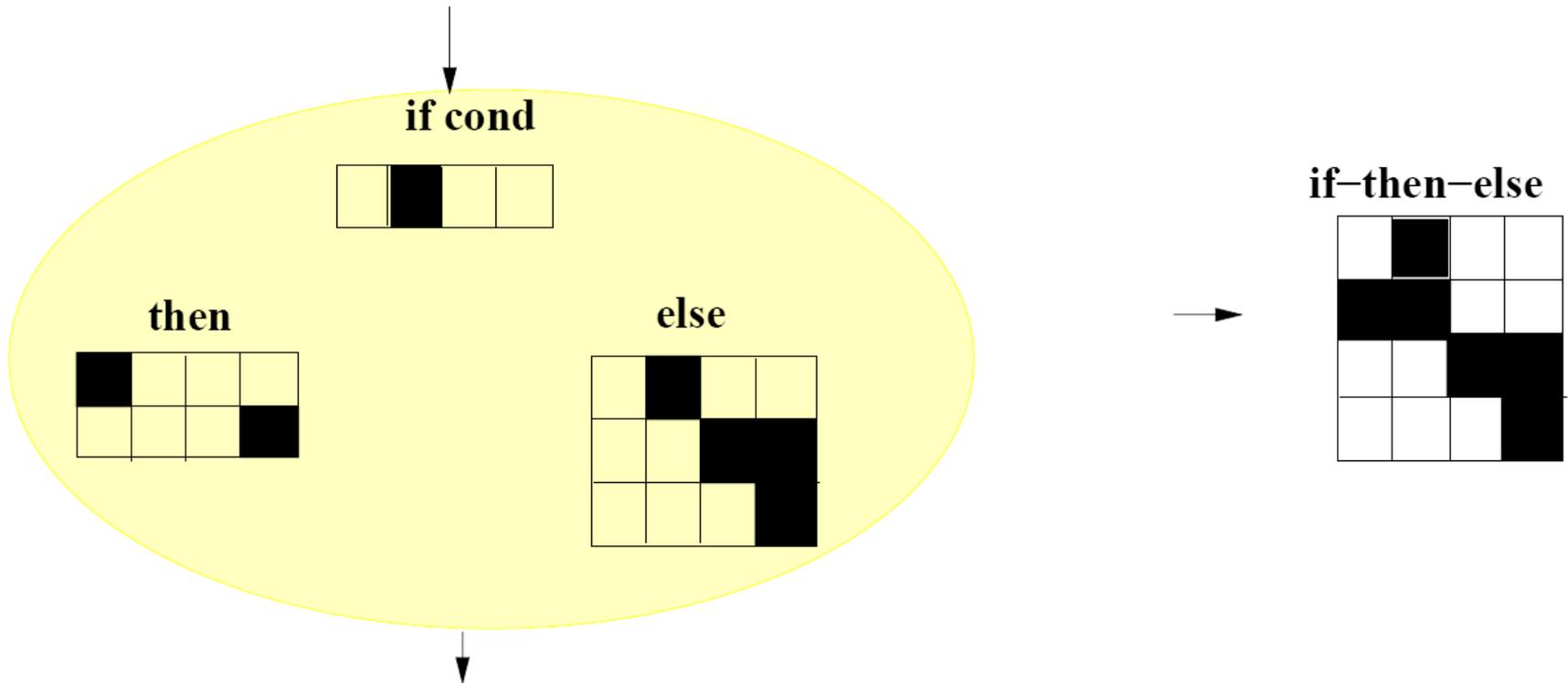


# Scheduling Algorithm Summary

- \* Given  $//$ , Schedule SCCs first
  - \* Scheduling a node bounds rest nodes from below and above
  - \* Satisfy precedence constraints
    - \* Pre-compute all-points longest paths
    - \* Allow fast update on the range of each node
  - \* Satisfy resource constraints
    - \* Topological ordering on intra-iteration edges
    - \* Upper bounds increases with initiation interval
  - \* Schedule reduced acyclic graphs
    - \* Schedule node in topological ordering
    - \* Find conflict slots within initiation window

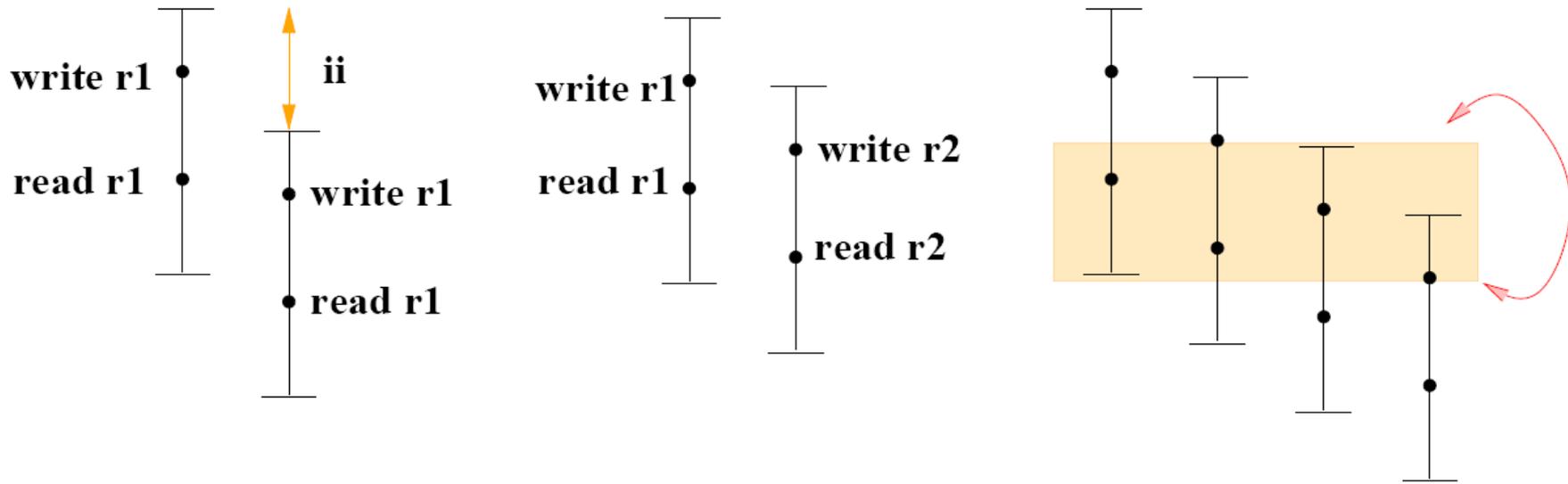
# Hierarchical Reduction

- \* For hammock-type conditional statements
  - \* Union both resource and precedence constraints





# Modulo Variable Expansion





# Modulo Variable Expansion Algorithm

- \* Schedule without considering cross-iteration anti-dependences
- \* lifetime  $> //$  : multiple registers are needed
- \* Assign registers
  - \*  $L(v)$  = lifetime of variable  $v$
  - \*  $//$  = initiation interval
  - \* Suppose  $L(u) = 3 \times //$  and  $L(v) = 2 \times //$
  - \* Unroll three times, use three registers for each  $u$  and  $v$
  - \* If only two registers for  $v$ , unroll 6 times



# Rotating Register (RR)

- \* Can use rotating registers instead of unrolling
  - \* Architectural mechanism for renaming
  - \* Employed in Intel's P6 Itanium processors
  - \* Composed of  $n$  registers ( $RR(0) \sim RR(n)$ )
  - \* Includes a `brtop` (or `brexit`) instruction
    - \* If a `brtop` is taken,  $RR(i)$  is accessible via  $RR((i+1)\%n)$
    - \* That is, a block shift of registers,  $RR(i+1) = RR(i)$ , occur
- \* We allocate RR to those whose lifetime  $> II$ , we can avoid cross-iteration register overwrites