Monte Carlo Perturbation Techniques

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Background of MC Perturbation Techniques

The two conventional MC perturbation techniques - the correlated sampling and differential operator sampling (DOS) methods - have been applied [1] to estimate the temperature coefficient of the coolant in a D₂O test reactor.

([1] H. Rief, "Generalized Monte Carlo Perturbation Algorithms for Correlated Sampling and a Second-Order Taylor Series Approach," *Ann. Nucl. Energy*, **11**, 455 (1984).)

 Nagaya and Mori [2] strengthened the two conventional methods by taking into account the fission source perturbation (FSP).

([2] Y. Nagaya, T. Mori, "Impact of Perturbed Fission Source on the Effective Multiplication Factor in Monte Carlo Perturbation Calculations," *J. Nucl. Sci. Technol.*, **42**[5], 428 (2005).

Recently, the MC perturbation techniques based on the adjoint flux estimated in the MC forward calculations have been developed and successfully applied for the density perturbation problems [3] and the nuclear data sensitivity and uncertainty (S/U) analyses [4].

([3] B. Kiedrowski, F. B. Brown, P. P. H. Wilson, "Adjoint-Weighted Tallies for k-Eigenvalue Calculations with Continuous-Energy Monte Carlo," *Nucl. Sci. Eng.*, **168**, 226 (2011).)

([4] H. J. Shim, C. H. Kim, "Adjoint Sensitivity and Uncertainty Analyses in Monte Carlo Forward Calculations," *J. Nucl. Sci. Technol.*, **48**[12], 1453 (2011).)

• It is notable that the first-order DOS method with FSP (DOS/FSP method hereafter) is equivalent to the first-order adjoint weighted perturbation (AWP) method [4].

A. Steady-State Boltzmann Transport Equation

 The steady-state Boltzmann transport equation can be written in an operator notation as

$$\mathbf{T}\boldsymbol{\phi} = \frac{1}{k}\mathbf{F}\boldsymbol{\phi} \qquad \qquad (A.1)$$

• The net loss operator **T** and the fission production operator **F** are defined by

$$\mathbf{T}\phi = \left[\mathbf{\Omega}\cdot\nabla + \Sigma_t(\mathbf{r}, E)\right]\phi(\mathbf{r}, E, \mathbf{\Omega}) - \int dE' \int d\mathbf{\Omega}' \Sigma_s(\mathbf{r}; E', \mathbf{\Omega}' \to E, \mathbf{\Omega})\phi(\mathbf{r}, E', \mathbf{\Omega}') \quad \dots \quad (A.2)$$

 Σ_t, Σ_s , and Σ_f are the total, scattering and fission cross-sections, respectively. ν is the mean number of fission neutrons produced from a fission reaction. *c* is the energy spectrum of fission neutrons.

A. Steady-State BTE (Contd.)

By operating λFT⁻¹ on its both sides of Eq. (A.1), it can be expressed as the following eigenvalue equation.

$$S = \frac{1}{k} \mathbf{H} S \tag{A.4}$$

where the fission source density (FSD) S and the fission operator H are defined as

Note that *S* satisfies $\int S(\mathbf{P})d\mathbf{P} = 1$ where **P** denotes the state vector of a neutron in the six-dimensional phase space, (**r**, E, Ω).

• **H**S in Eq. (A.4) implies

$$\mathbf{H}S = \int d\mathbf{P}' H(\mathbf{P}' \to \mathbf{P}) S(\mathbf{P}') \qquad \qquad (A.7)$$

where $H(\mathbf{P'} \rightarrow \mathbf{P})$ means the number of first-generation fission neutrons born per unit phase space volume about \mathbf{P} , due to a parent neutron born at $\mathbf{P'}$.



In order to derive an MC perturbation algorithm, we apply the solution of the collision density equation to the perturbation formulation.

B. Collision Density Equation

The integral equation for the collision density ψ(P) defined by Σ_t(r,E)φ(P) can be written as

$$\psi(\mathbf{P}) = \int d\mathbf{r}' T(E, \mathbf{\Omega}; \mathbf{r}' \to \mathbf{r}) S(\mathbf{r}', E, \mathbf{\Omega}) + \int d\mathbf{P}' K_s(\mathbf{P}' \to \mathbf{P}) \psi(\mathbf{P}') \quad \text{(B.1)}$$

 K_s is defined by the product of the scattering collision kernel, C_s and the transition kernel [B.1] (or the free flight kernel), *T*:

$$K_{s}(\mathbf{P}' \to \mathbf{P}) = T(E, \mathbf{\Omega}; \mathbf{r}' \to \mathbf{r}) \cdot C_{s}(\mathbf{r}'; E', \mathbf{\Omega}' \to E, \mathbf{\Omega}); \qquad (B.2)$$

$$C_{s}(\mathbf{r}'; E', \mathbf{\Omega}' \to E, \mathbf{\Omega}) = \sum_{r \neq fis.} \nu_{r} \frac{\Sigma_{r}(\mathbf{r}'; E', \mathbf{\Omega}')}{\Sigma_{t}(\mathbf{r}', E')} f_{r}(E', \mathbf{\Omega}' \to E, \mathbf{\Omega})$$
(B.3)

$$T(E, \mathbf{\Omega}; \mathbf{r}' \to \mathbf{r}) = \frac{\Sigma_t(\mathbf{r}, E)}{\left|\mathbf{r} - \mathbf{r}'\right|^2} \exp\left[-\int_0^{|\mathbf{r} - \mathbf{r}'|} \Sigma_t(\mathbf{r} - s\frac{\mathbf{r} - \mathbf{r}'}{\left|\mathbf{r} - \mathbf{r}'\right|}, E)ds\right] \delta\left(\mathbf{\Omega} \cdot \frac{\mathbf{r} - \mathbf{r}'}{\left|\mathbf{r} - \mathbf{r}'\right|} - 1\right) \quad (B.4)$$

 v_r is the average number of neutrons produced from a reaction type r and f_r is the probability that a collision of type r by a neutron of direction Ω' and energy E' will produce a neutron in direction interval $d\Omega$ about Ω with energy in dE about E.

([B.1] I. Lux, L. Koblinger, "Monte Carlo Particle Transport Methods: Neutron and Photon Calculations," CRC Press (1991).)

B. Collision Density Equation (Contd.)

• For further derivations, we define the fission collision kernel by

$$C_f(\mathbf{r}; E', \mathbf{\Omega}' \to E, \mathbf{\Omega}) = \frac{\chi(E' \to E)}{4\pi} \cdot \frac{\nu(E')\Sigma_f(\mathbf{r}, E')}{\Sigma_t(\mathbf{r}, E')}$$
(B.5)

• From the Neumann series solution of Eq. (B.1) [B.1], the angular flux $\phi(\mathbf{P})$ can be expressed as

$$\psi_{j}(\mathbf{P}) = \int d\mathbf{P}_{0} K_{s,j}(\mathbf{P}_{0} \to \mathbf{P}) \int d\mathbf{r}' T(E', \mathbf{\Omega}'; \mathbf{r}' \to \mathbf{r}_{0}) S(\mathbf{r}', E', \mathbf{\Omega}'), \quad ---- \quad (B.7)$$

where the *j*-th scattering transport kernel, $K_{s,j}$ is defined by

$$\begin{split} K_{s,0}(\mathbf{P}_0 \to \mathbf{P}) &= \delta(\mathbf{P}_0 - \mathbf{P}), \\ K_{s,1}(\mathbf{P}_0 \to \mathbf{P}) &= K_s(\mathbf{P}_0 \to \mathbf{P}), \\ K_{s,j}(\mathbf{P}_0 \to \mathbf{P}) &= \int d\mathbf{P}_{j-1} \cdots \int d\mathbf{P}_1 K_s(\mathbf{P}_{j-1} \to \mathbf{P}) \cdots K_s(\mathbf{P}_0 \to \mathbf{P}_1); j = 2, 3, \cdots, \end{split}$$

and $E_0 = E', \ \mathbf{\Omega}_0 = \mathbf{\Omega}'. \end{split}$

B. Collision Density Equation (Contd.)

 By inserting Eq. (B.6) into Eq. (A.3), the definition of S of Eq. (A.5) can be written as

$$\mathbf{F}\phi = \int dE' \int d\mathbf{\Omega}' \frac{\chi(E' \to E)}{4\pi} v(E') \Sigma_f(\mathbf{r}, E') \phi(\mathbf{r}, E', \mathbf{\Omega}')$$

$$\phi(\mathbf{P}) = \frac{1}{\Sigma_t(\mathbf{r}, E)} \sum_{j=0}^{\infty} \psi_j(\mathbf{P});$$

$$S = \frac{1}{k} \mathbf{F}\phi \quad \longrightarrow \quad S(\mathbf{P}) = \frac{1}{k} \int dE'' \int d\mathbf{\Omega}'' C_f(\mathbf{r}; E'', \mathbf{\Omega}'' \to E, \mathbf{\Omega}) \sum_{j=0}^{\infty} \psi_j(\mathbf{r}, E'', \mathbf{\Omega}'') \quad (B.9)$$

• Insertion of Eq. (B.7) into Eq. (B.9) leads to

$$\mathbf{H}S = \int d\mathbf{P}' H(\mathbf{P}' \to \mathbf{P}) S(\mathbf{P}'); \qquad (B.10)$$

 $H(\mathbf{P}' \to \mathbf{P})S(\mathbf{P}') =$

$$\sum_{j=0}^{\infty} \int dE'' \int d\Omega'' C_f(\mathbf{r}; E'', \Omega'' \to E, \Omega) \int d\mathbf{P}_0 K_{s,j}(\mathbf{P}_0 \to \mathbf{r}, E'', \Omega'') \int d\mathbf{r}' T(E', \Omega'; \mathbf{r}' \to \mathbf{r}_0) S(\mathbf{P}')$$
(B.11)

Perturbation of a Tally *Q*

• By Taylor's series expansion, the variation of a tally Q due to a deviation of a input parameter α , denoted by $\Delta \alpha$, can be expressed as

$$Q(\alpha + \Delta \alpha) - Q(\alpha) \equiv \delta Q(\alpha) = \sum_{n=1}^{\infty} \frac{1}{n!} \frac{d^n Q}{d\alpha^n} (\Delta \alpha)^n = \sum_{n=1}^{\infty} \frac{1}{n!} U_n (\Delta \alpha)^n \quad (1)$$

where

$$U_n = \frac{d^n Q}{d\alpha^n} \tag{2}$$

• And the tally Q can be written using the corresponding detector response g and the collision density Ψ in the MC simulation as follows:

$$Q = \int g(\mathbf{P}) \Psi(\mathbf{P}) d\mathbf{P}$$
 (3)

where **P** denotes the six-dimensional phase space vector (\mathbf{r}, E, Ω).

Perturbation of a Tally Q (Contd)

• Using the Neumann series solution of the collision density equation, the first order sensitivity U_1 can be expressed as

$$U_{1} = \frac{dQ}{dx} = \sum_{j} U_{1,j};$$
 (4)

$$U_{1,j} = \frac{\partial}{\partial x} \left[\int d\mathbf{P}g(\mathbf{P}) \psi_j(\mathbf{P}) \right]$$

= $\frac{\partial}{\partial x} \left[\int d\mathbf{P}g(\mathbf{P}) \left(\int d\mathbf{P}_0 K_{s,j}(\mathbf{P}_0 \to \mathbf{P}) \int d\mathbf{r}' T(E', \mathbf{\Omega}'; \mathbf{r}' \to \mathbf{r}_0) S(\mathbf{r}', E', \mathbf{\Omega}') \right) \right] \quad ---- (5)$

Differential Operator Sampling (DOS) + Perturbed Source Effect (PSE)

 In the differential operator sampling (DOS) method augmented by the fission source perturbation method, Eq. (5) can be written as

$$U_{1,j} = \int d\mathbf{P} \cdots \int d\mathbf{P}_0 \int d\mathbf{r}' \begin{cases} \frac{1}{q(\mathbf{P})} \frac{\partial q(\mathbf{P})}{\partial x} + \sum_{k=1}^j \frac{1}{K_s(\mathbf{P}_{k-1} \to \mathbf{P}_k)} \frac{\partial K_s(\mathbf{P}_{k-1} \to \mathbf{P}_k)}{\partial x} \\ + \frac{1}{T(E', \mathbf{\Omega}'; \mathbf{r}' \to \mathbf{r}_0)} \frac{\partial T(E', \mathbf{\Omega}'; \mathbf{r}' \to \mathbf{r}_0)}{\partial x} + \frac{1}{S(\mathbf{P}')} \frac{\partial S(\mathbf{P}')}{\partial x} \end{cases} \\ \cdot \left\{ q(\mathbf{P}) K_s(\mathbf{P}_{j-1} \to \mathbf{P}) \cdots K_s(\mathbf{P}_0 \to \mathbf{P}_1) T(E', \mathbf{\Omega}'; \mathbf{r}' \to \mathbf{r}_0) S(\mathbf{P}') \right\} \\ = \int d\mathbf{P} \cdots \int d\mathbf{P}_0 \int d\mathbf{r}' \left\{ u^{1q}(\mathbf{P}) + \sum_{k=0}^j u^{1K}(\mathbf{P}_{k-1} \to \mathbf{P}_k) + u^{1S}(\mathbf{P}') \right\} \\ \cdot \left\{ q(\mathbf{P}) K_s(\mathbf{P}_{j-1} \to \mathbf{P}) \cdots K_s(\mathbf{P}_0 \to \mathbf{P}_1) T(E', \mathbf{\Omega}'; \mathbf{r}' \to \mathbf{r}_0) S(\mathbf{P}') \right\} \end{cases}$$

(6)

First Order DOS + PSE (Contd.)

where

= first order sensitivity response of fission source distribution

and $\mathbf{P}_j = \mathbf{P}$.

Cf. k Sensitivity Formulation

 In the MC adjoint-weighted perturbation method, the variation of k due to a change of parameter x is expressed by

$$\frac{\Delta k_0}{k_0} \approx \frac{\langle \phi_0^{\dagger}, \Delta \mathbf{H} S_0 \rangle}{\langle \phi_0^{\dagger}, \mathbf{H} S_0 \rangle}$$
(C.1)

 Using the iterated fission probability concept for the adjoint flux, Eq. (C.1) is written as

$$\Delta k_0 \cong \frac{1}{k_0^n} < \mathbf{H}^n, \Delta \mathbf{H} S_0 > \tag{C.2}$$

Cf. k Sensitivity Formulation (Contd)

• Now, consider an MC algorithm for how to calculate (Δk_0) in the course of the cycle-by-cycle FSD and eigenvalue estimates. To do so, note that, when expressed explicitly in terms of the transport kernels, **H**S of Eq. (C.2) is given by

$$\mathbf{H}S = \sum_{j=0}^{\infty} \int dE'' \int d\mathbf{\Omega}'' C_f(\mathbf{r}; E'', \mathbf{\Omega}'' \to E, \mathbf{\Omega}) \int d\mathbf{P}_0 K_{s,j}(\mathbf{P}_0 \to \mathbf{r}, E'', \mathbf{\Omega}'') \int d\mathbf{r}' T(E_0, \mathbf{\Omega}_0; \mathbf{r}' \to \mathbf{r}_0) S(\mathbf{r}', E_0, \mathbf{\Omega}_0)$$
(B.11)

• Then Δ **H***S* in Eq. (C.2) can be expressed as

$$\Delta \mathbf{H}S = \left(\Delta \mathbf{x} \frac{\partial \mathbf{H}}{\partial \mathbf{x}}\right)S$$

$$= \Delta \mathbf{x} \sum_{p=0}^{\infty} \int dE'' \int d\mathbf{\Omega}'' \int d\mathbf{P}_{p-1} \cdots \int d\mathbf{P}_{0} \int d\mathbf{r}'$$

$$\otimes \frac{\partial}{\partial \mathbf{x}} \left\{ C_{f}(\mathbf{r}; E'', \mathbf{\Omega}'' \to E, \mathbf{\Omega}) K_{s}(\mathbf{P}_{p-1} \to \mathbf{r}, E'', \mathbf{\Omega}'') \cdots K_{s}(\mathbf{P}_{0} \to \mathbf{P}_{1}) T(E_{0}, \mathbf{\Omega}_{0}; \mathbf{r}' \to \mathbf{r}_{0}) \right\} S(\mathbf{r}', E_{0}, \mathbf{\Omega}_{0})$$

$$= \Delta \mathbf{x} \sum_{p=0}^{\infty} \int dE'' \int d\mathbf{\Omega}'' \int d\mathbf{P}_{p-1} \cdots \int d\mathbf{P}_{0} \int d\mathbf{r}' \ u^{p}(\mathbf{r}', E_{0}, \mathbf{\Omega}_{0} \to \mathbf{P})$$

$$\otimes \left\{ C_{f}(\mathbf{r}; E'', \mathbf{\Omega}'' \to E, \mathbf{\Omega}) K_{s}(\mathbf{P}_{p-1} \to \mathbf{r}, E'', \mathbf{\Omega}'') \cdots K_{s}(\mathbf{P}_{0} \to \mathbf{P}_{1}) T(E_{0}, \mathbf{\Omega}_{0}; \mathbf{r}' \to \mathbf{r}_{0}) \right\} S(\mathbf{r}', E_{0}, \mathbf{\Omega}_{0});$$

$$(C.3)$$

Cf. k Sensitivity Formulation (Contd)

$$u^{p}(\mathbf{r}', E_{0}, \mathbf{\Omega}_{0} \rightarrow \mathbf{P}) = u_{f}(\mathbf{r}; E'', \mathbf{\Omega}'' \rightarrow E, \mathbf{\Omega})$$

$$+ u_{K}(\mathbf{P}_{p-1} \rightarrow \mathbf{r}, E'', \mathbf{\Omega}'') + \sum_{k=0}^{p-2} u_{K}(\mathbf{P}_{k} \rightarrow \mathbf{P}_{k+1}) + u_{T}(E_{0}, \mathbf{\Omega}_{0}; \mathbf{r}' \rightarrow \mathbf{r}_{0}), \qquad (C.4)$$

$$u_{f}(\mathbf{r}; E'', \mathbf{\Omega}'' \rightarrow E, \mathbf{\Omega}) = \frac{1}{C_{f}(\mathbf{r}; E'', \mathbf{\Omega}'' \rightarrow E, \mathbf{\Omega})} \frac{\partial C_{f}(\mathbf{r}; E'', \mathbf{\Omega}'' \rightarrow E, \mathbf{\Omega})}{\partial x} \qquad (C.5)$$

$$u_{K}(\mathbf{P}_{k} \rightarrow \mathbf{P}_{k+1}) = \frac{1}{K_{s}(\mathbf{P}_{k} \rightarrow \mathbf{P}_{k+1})} \frac{\partial K_{s}(\mathbf{P}_{k} \rightarrow \mathbf{P}_{k+1})}{\partial x} \qquad (C.6)$$

$$u_{T}(E_{0}, \mathbf{\Omega}_{0}; \mathbf{r}' \rightarrow \mathbf{r}_{0}) = \frac{1}{T(E_{0}, \mathbf{\Omega}_{0}; \mathbf{r}' \rightarrow \mathbf{r}_{0})} \frac{\partial T(E_{0}, \mathbf{\Omega}_{0}; \mathbf{r}' \rightarrow \mathbf{r}_{0})}{\partial x} \qquad (C.7)$$

Algorithm of the First Order DOS + PSE Method

In Monte Carlo random walk process, when the k-th track starts with a neutron undergoing reaction type "a" with isotope i' at energy E_{k-1} and Ω_{k-1} is scattered to E_k and Ω_k, and continues for a track length λ_k and collides, the sampled scattering collision kernel and the sampled free flight kernel can be written as

Using Eqs. (10) and (11), the first order sensitivity of the transport kernel of Eq. (8) for the *k*-th track can be calculated by

$$u_{k}^{1K} = \begin{cases} \frac{1}{C_{s,k}} \frac{\partial C_{s,k}}{\partial x} + \frac{1}{T_{k}} \frac{\partial T_{k}}{\partial x} & (k = 1, 2, \cdots) \\ \frac{1}{T_{k}} \frac{\partial T_{k}}{\partial x} & (k = 0) \end{cases}$$
(12)

First Order DOS + PSE Algorithm (Contd.)

• For a deviation of a capture xs of nuclide i, Eq. (12) can be calculated using

$$\frac{1}{C_{s,k}} \frac{\partial C_{s,k}}{\partial \alpha} = \frac{1}{v_a^{i'} \frac{N^{i'} \sigma_a^{i'}(E_{k-1})}{\Sigma_t(E_{k-1})} f_a^{i'}(E_{k-1}, \Omega_{k-1} \to E_k, \Omega_k)} \\ \otimes \begin{pmatrix} v_a^{i'} \frac{N^{i'} \delta_{ii'} \delta_{a\gamma}}{\Sigma_t(E_{k-1})} f_a^{i'}(E_{k-1}, \Omega_{k-1} \to E_k, \Omega_k) \\ -v_a^{i'} N^{i} \frac{N^{i'} \sigma_a^{i'}(E_{k-1})}{\Sigma_t(E_{k-1})^2} f_a^{i'}(E_{k-1}, \Omega_{k-1} \to E_k, \Omega_k) \end{pmatrix} = \frac{1}{\sigma_a^{i}(E_{k-1})} \delta_{ii'} \delta_{a\gamma} - \frac{N^{i}}{\Sigma_t(E_{k-1})}$$
(13)
$$\frac{1}{T_k} \frac{\partial T_k}{\partial \alpha} = \frac{1}{\frac{\Sigma_t(E_k)}{\lambda_k^2}} \exp\left[-\Sigma_t(E_k)\lambda_k\right] \begin{pmatrix} \frac{N^i}{\lambda_k^2} \exp\left[-\Sigma_t(E_k)\lambda_k\right] \\ -\lambda_k N^i \frac{\Sigma_t(E_k)}{\lambda_k^2} \exp\left[-\Sigma_t(E_k)\lambda_k\right] \end{pmatrix} = \frac{N^i}{\Sigma_t(E_k)} - \lambda_k N^i$$
(14)

• For a deviation of v_f of nuclide *i* in the MC eigenvalue calculations, u^{1K} becomes zero.

First Order DOS + PSE Algorithm (Contd.)

• For $q_f(P) (=v\Sigma_f/\Sigma_t)$ which denotes a response function for the collision estimator of k_{eff} , the first order sensitivity u^{lqf} from the *k*-th track can be calculated by

$$u_k^{1q_f} = \frac{\Sigma_t(\mathbf{r}_k, E_k)}{\nu_f(\mathbf{r}_k, E_k)\Sigma_f(\mathbf{r}_k, E_k)} \frac{\partial}{\partial x} \left(\frac{\nu_f(\mathbf{r}_k, E_k)\Sigma_f(\mathbf{r}_k, E_k)}{\Sigma_t(\mathbf{r}_k, E_k)} \right)$$
(15a)

• For a deviation of a capture xs of nuclide *i*, Eq. (15) can be written as

$$u_k^{1q_f} = -\frac{N^i}{\Sigma_t(\mathbf{r}_k, E_k)}$$
(15b)

• And for a deviation of v_f of nuclide *i*, u^{1qf} can be calculated by

$$u_k^{1q_f} = \frac{1}{\nu_f^i(\mathbf{r}_k, E_k)}$$
(15c)

Source Perturbation Algorithm

• In the MC power method, S for the next cycle i, S_i is updated as

$$S_{i} = \frac{1}{k_{i-1}} \mathbf{H} S_{i-1}; \qquad (16)$$

$$k_{i-1} = \langle \mathbf{H} S_{i-1} \rangle \qquad (17)$$

• From Eqs. (16) and (17), the sensitivity of S_i to the parameter x can be written as

$$\frac{\partial S_{i}}{\partial x} = \frac{1}{k_{i-1}} \left(\frac{\partial \mathbf{H}}{\partial x} S_{i-1} + \mathbf{H} \frac{\partial S_{i-1}}{\partial x} \right) - \frac{\mathbf{H} S_{i-1}}{k_{i-1}^{2}} \left(< \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > + < \mathbf{H} \frac{\partial S_{i-1}}{\partial x} > \right)$$
$$= \frac{1}{k_{i-1}} \left\{ \frac{\partial \mathbf{H}}{\partial x} S_{i-1} + \mathbf{H} \frac{\partial S_{i-1}}{\partial x} - S_{i} \left(< \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > + < \mathbf{H} \frac{\partial S_{i-1}}{\partial x} > \right) \right\} \qquad (18)$$

Source Perturbation Algorithm (Contd)

• Then u^{1S} in Eq. (9) can be written as

$$\frac{1}{S_{i}} \frac{\partial S_{i}}{\partial x} = \frac{1}{k_{i-1} \cdot S_{i}} \left(\frac{\partial \mathbf{H}}{\partial x} S_{i-1} + \mathbf{H} \frac{\partial S_{i-1}}{\partial x} \right) - \frac{1}{k_{i-1}} \left(< \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > + < \mathbf{H} \frac{\partial S_{i-1}}{\partial x} > \right)$$

$$= \frac{1}{k_{i-1}} \frac{1}{k_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} + \mathbf{H} \frac{\partial S_{i-1}}{\partial x} - \frac{1}{k_{i-1}} \left(< \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > + < \mathbf{H} \frac{\partial S_{i-1}}{\partial x} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$+ \left(\frac{1}{\mathbf{H}S_{i-1}} \mathbf{H} \frac{1}{S_{i-1}} \frac{\partial S_{i-1}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$+ \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$+ \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{\partial \mathbf{H}}{\partial x} S_{i-1} > \right)$$

$$= \left(\frac{1}{\mathbf{H}S_{i-1}} \frac{\partial \mathbf{H}}{\partial x} S_{i-1} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} - \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} < \frac{1}{\langle \mathbf{H}S_{i-1} \rangle} - \frac{1}{\langle \mathbf{H}S_{i-1$$

SNU Monte Carlo Lab.

Dr. Nagaya's Algorithm



Correlated Sampling Method

• Recall that **H**S is given by

• Then **H***S* for a perturbed system can be expressed as

• From Eqs. (B.11) and (20), Δ **H***S* can be calculated by

 $\Delta \mathbf{H}S = \mathbf{H}^*S - \mathbf{H}S$

$$=\sum_{j=0}^{\infty}\int dE''\int d\mathbf{\Omega}''\int d\mathbf{P}_{0}\int d\mathbf{r}' \left(\frac{C_{f}^{*}(\mathbf{r};E'',\mathbf{\Omega}''\to E,\mathbf{\Omega})}{C_{f}(\mathbf{r};E'',\mathbf{\Omega}''\to E,\mathbf{\Omega})}\cdot\prod_{p=0}^{j-1}\frac{K_{s}^{*}(\mathbf{P}_{p}\to\mathbf{P}_{p+1})}{K_{s}(\mathbf{P}_{p}\to\mathbf{P}_{p+1})}\cdot\frac{T^{*}(E_{0},\mathbf{\Omega}_{0};\mathbf{r}'\to\mathbf{r}_{0})}{T(E_{0},\mathbf{\Omega}_{0};\mathbf{r}'\to\mathbf{r}_{0})}-1\right)$$
$$\otimes C_{f}(\mathbf{r};E'',\mathbf{\Omega}''\to E,\mathbf{\Omega})K_{s,j}(\mathbf{P}_{0}\to\mathbf{r},E'',\mathbf{\Omega}'')T\ (E_{0},\mathbf{\Omega}_{0};\mathbf{r}'\to\mathbf{r}_{0})S(\mathbf{r}',E_{0},\mathbf{\Omega}_{0})$$
(21)

U²³⁵ Number Density Perturbation for Godiva Problems

- In order to investigate the accuracy of the new MC perturbation techniques, their results were compared with those calculated by direct subtractions for Godiva critical assembly problems.
- The Godiva geometry is a bare uranium sphere with a radius of 8.741 cm. The original density is 18.74 g/cm³ and the composition is 94.73 wt% U²³⁵ and 5.27 wt% U²³⁸.



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Number Density Perturbation of Godiva

(b) Central perturbation



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