



Ch.13 Priority Queues

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BIRD'S-EYE VIEW (0)

- Chapter 12: Binary Tree
- Chapter 13: Priority Queue
 - Heap and Leftiest Tree
- Chapter 14: Tournament Trees
 - Winner Tree and Loser Tree



BIRD'S-EYE VIEW (1)

- A priority queue is efficiently implemented with the heap data structure
- Priority data structure
 - Heap
 - Leftist tree
- Priority Queue Applications
 - Heap sort
 - Use heap for an $O(n \cdot \log n)$ sorting method
 - Machine scheduling
 - Use the heap data structure to obtain an efficient implementation
 - The generation of Huffman codes



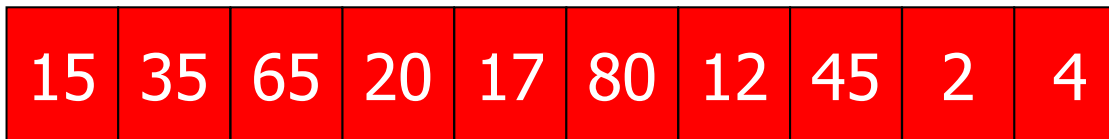
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- Linear Lists for Priority Queue
- Heaps for Priority Queue
- Leftist Trees for Priority Queue
- Priority Queue Applications
 - Heap Sort
 - Machine Scheduling
 - Huffman code



Definition

- A **priority queue** is
 - Collection of zero or more elements with priority
- A **min priority queue** is
 - Find the element with minimum priority
 - Then, Remove the element
- A **max priority queue** is
 - Find the element with maximum priority
 - Then, Remove the element
- Priority queue is a conceptual queue where **the output element has a certain property** (i.e., priority)





Priority Queue Applications

- Priority queues in the machine shop simulation
 - Min priority queue
 - One machine, many jobs with priority (time requirement of each job), a fixed rate of payment
 - To maximize the earning from the machine
 - When a machine is ready for a new job, it selects the waiting job with minimum priority (time requirement)
 - getMin() & removeMin()
 - Max priority queue
 - Same duration jobs with priority (the amount of payment)
 - To maximize the earning from the machine
 - When a machine is ready for a new job, it selects the waiting job with maximum priority (the amount of payment)
 - getMax() & removeMax()



The ADT MaxPriorityQueue

AbstractDataType MaxPriorityQueue {

instances

finite collection of elements, each has a priority

operations

`isEmpty()` : return true if the queue is empty
`size()` : return number of elements in the queue
`getMax()` : return element with maximum priority
`put(x)` : insert the element x into the queue
`removeMax()` : remove the element with largest priority
from the queue and return this element;

}



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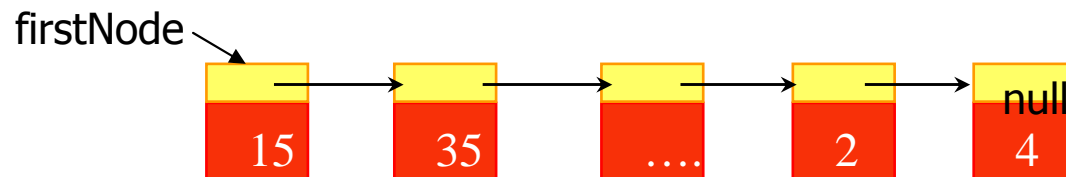
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Linear Lists for Priority Queue (1)

- Suppose Linear List for max priority queue with n elements
- Unordered linear list for a max queue
 - Array
 - Insert() or Put() : $\Theta(1)$ // put the new element the right end of the array
 - RemoveMax(): $\Theta(n)$ // find the max among n elements

15	35	65	20	17	80	12	45	2	4
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- Linked List
 - Insert() or Put() : $\Theta(1)$ // put the new element at the front of the chain
 - RemoveMax(): $\Theta(n)$ // find the max among n elements

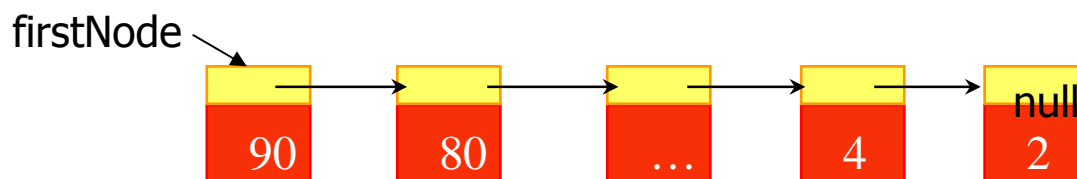


Linear Lists for Priority Queue (2)

- Ordered linear list for a max queue
 - Array
 - location(i) = i (i.e., array-based) where the max element is located in the last address (i.e., the nondecreasing order)
 - Insert() or Put() : $\Theta(n)$
 - RemoveMax() : $\Theta(1)$



- Linked List
 - chain (i.e., linked) where the max element is located in the head of chain (i.e., the nonincreasing order)
 - Insert() or Put() : $\Theta(n)$
 - RemoveMax() : $\Theta(1)$





Why HEAP?

- $O(\log N)$ for Insert() or Put()
- $O(\log N)$ for RemoveMax()

- Simple Array Implementation!



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Max Tree & Max Heap

- A max tree is a tree in which the value in each node is greater than or equal to those in its children

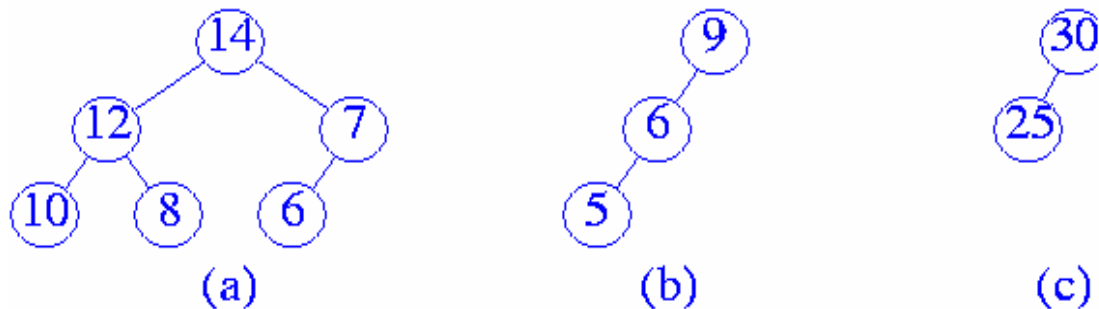


Figure 13.1 Max trees

- A max heap is
 - A max tree that is also a complete binary tree
 - Figure 13.1(b) : not CBT, so not max heap

Min Tree & Min Heap

- A **min tree** is a tree in which the value in each node is **less** than or equal to those in its children

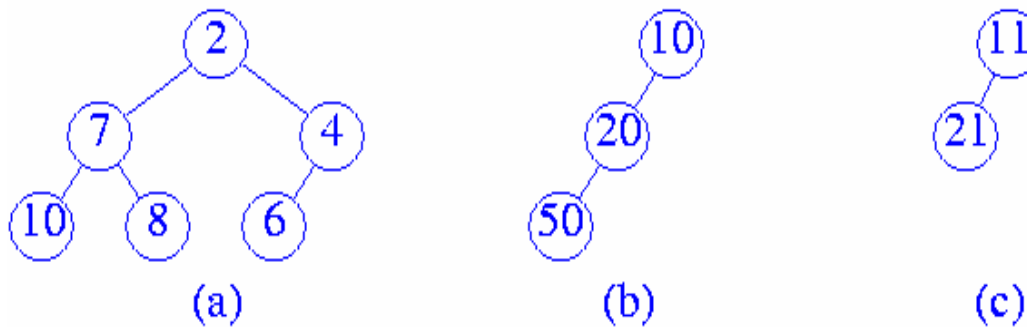


Figure 13.2 Min trees

- A **min heap** is
 - A **min tree** that is also a **complete binary tree**
 - Figure 13.2(b) : not CBT, so not min heap



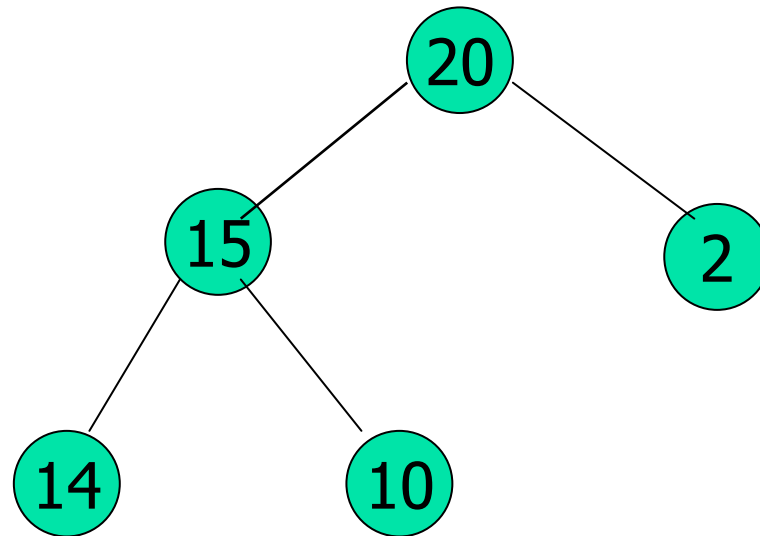
Heap Height

- Heap is a complete binary tree
 - **A heap with n elements has height $\lceil \log_2(n+1) \rceil$**
- $\text{put}()$: $O(\text{height}) \rightarrow O(\log n)$
 - Increase array size if necessary
 - Find place for the new element
 - The new element is located as a leaf
 - Then moves up the tree for finding home
- $\text{removeMax}()$: $O(\text{height}) \rightarrow O(\log n)$
 - Remove $\text{heap}[1]$, so the root is empty
 - Move the last element in the heap to the root
 - Reheapify



Put into Max Heap (1)

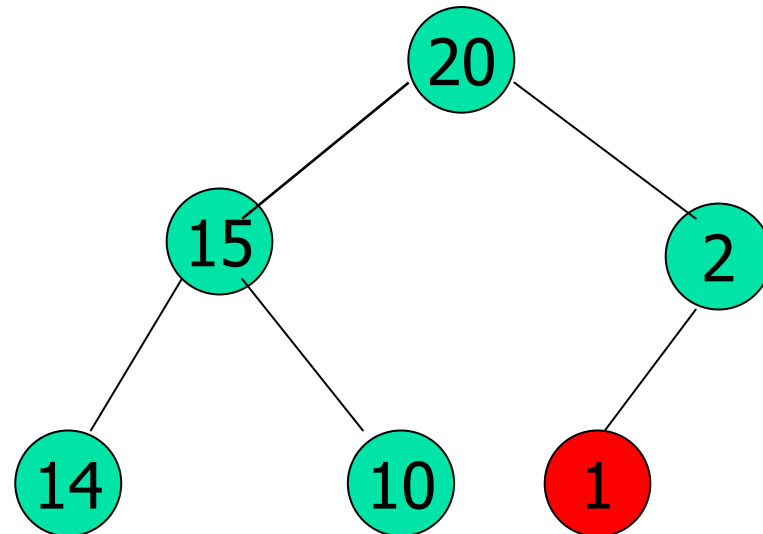
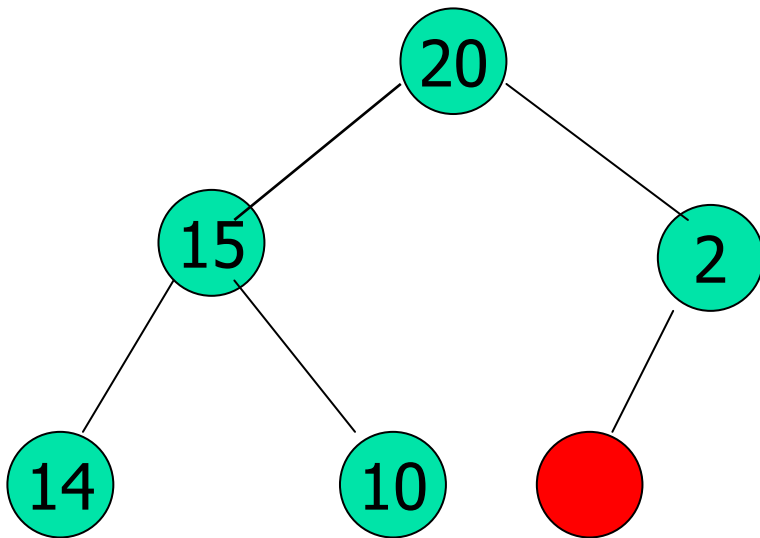
- Max heap with five elements



Put into Max Heap (2)

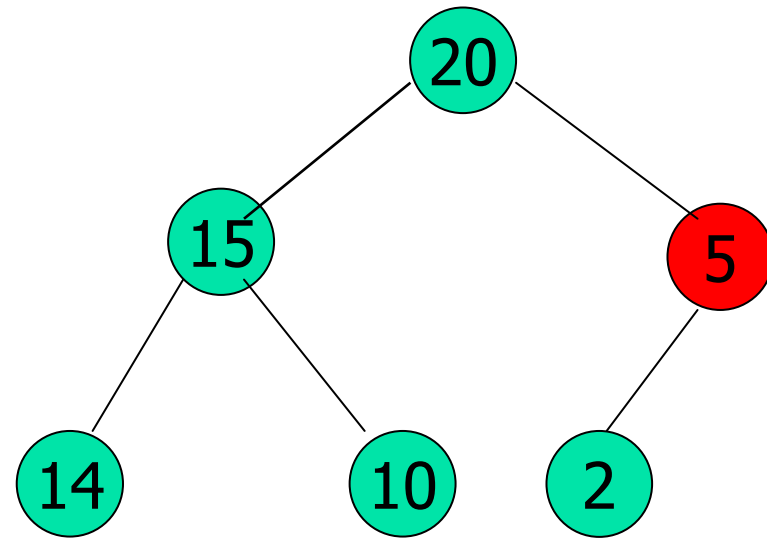
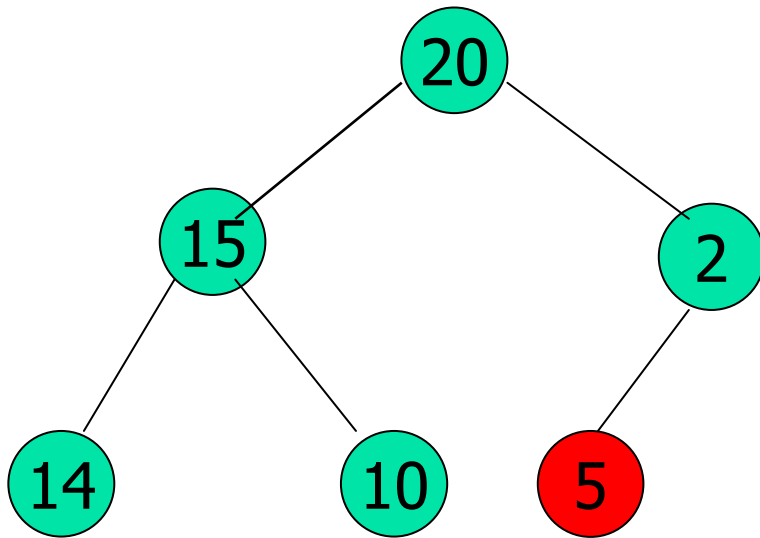
- When an element is added to this heap, the location for a new element is **the red zone**

- Suppose the element to be inserted has value **1**, the following placement is fine



Put into Max Heap (3)

- Suppose the element to be inserted has value 5
- The elements 2 and 5 must be swapped for maintaining the heap property

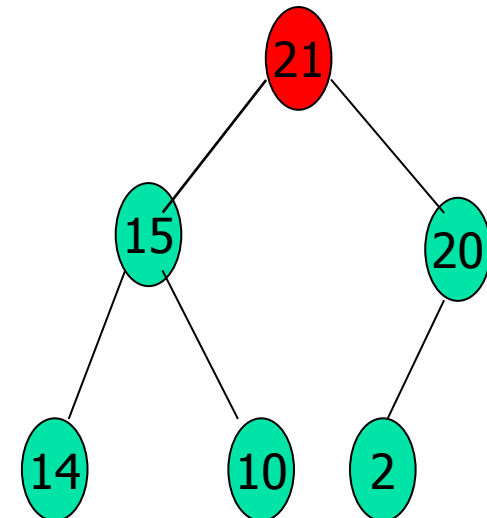
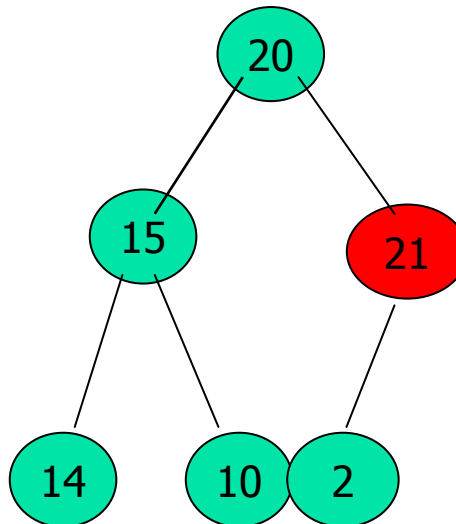
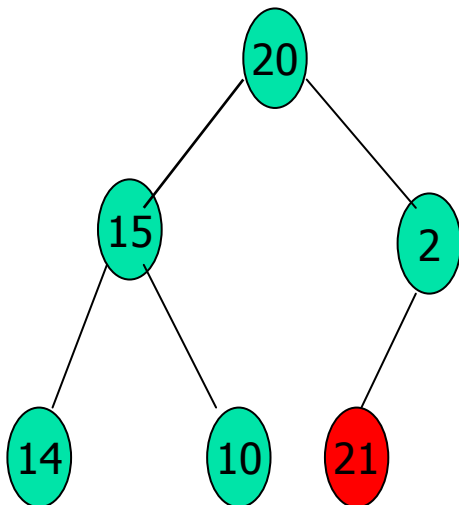


Put into Max Heap (4)

Suppose the element to be inserted has value 21

- The new element 21 will find its position by continuous swapping with the existing elements for maintaining the heap property

- Finally the new element 21 goes to the top





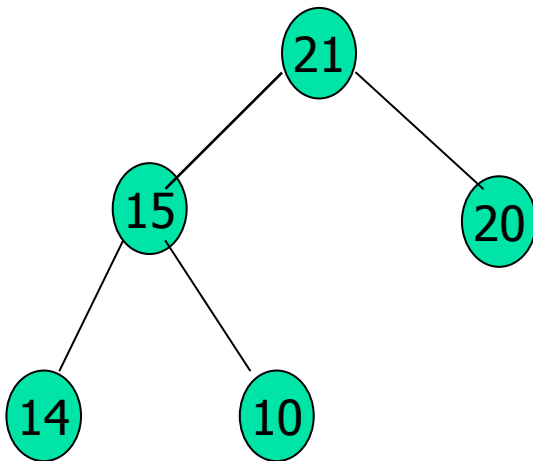
put() in MaxHeap

```
public void put ( Comparable theElement ) {  
    if ( size == heap.length - 1 ) // increase array size if necessary  
        heap=(Comparable []) ChangeArrayLength.changeLengthID (heap, 2 * heap.length);  
  
    // find the place for theElement. currentNode starts at new leaf and moves up tree  
    int currentNode = ++size;  
    while (currentNode != 1 && heap[currentNode / 2].compareTo(theElement) < 0) {  
        // cannot put theElement in heap[currentNode], So move element down  
        heap[currentNode] = heap[currentNode / 2];  
        currentNode /= 2; // move to parent  
    }  
  
    heap[currentNode] = theElement;  
}
```

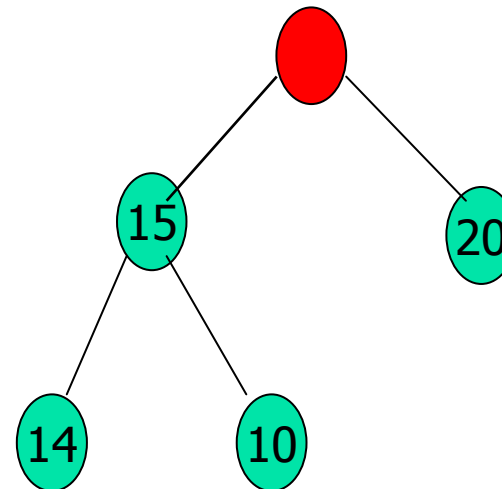
■ At each level : $\Theta(1)$ So, Total complexity: $O(\text{height}) = O(\log n)$

removeMax() from a MaxHeap (1)

- The Max element "21" is in the root

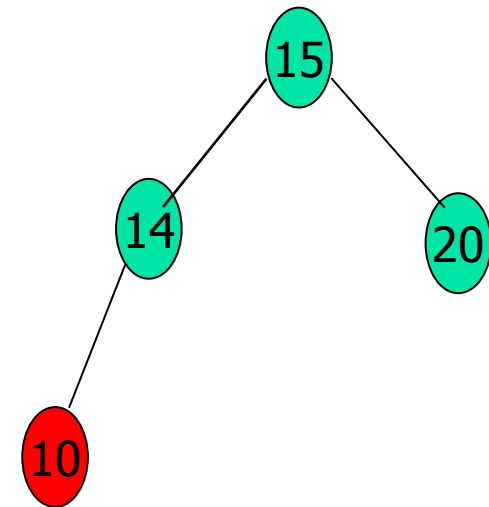
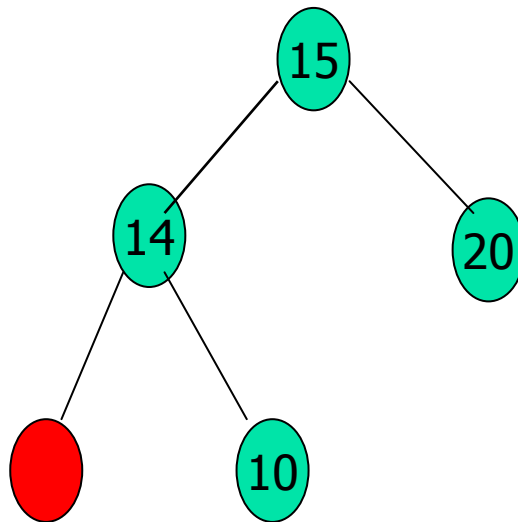
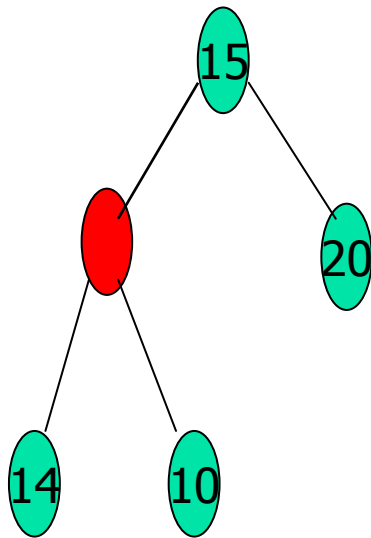


- After the max element "21" is removed



removeMax() from a MaxHeap (2)

- The element 15 will go to the top by swapping
- The element 14 is also swapped to one level up
- Even the element 10 needs to be relocated for maintaining the complete binary tree property





removeMax() in MaxHeap

```
public Comparable removeMax() {
    if (size == 0) return null; // if heap is empty return null
    Comparable maxElement = heap[1]; // max element
    Comparable lastElement = heap[size--]; // reheapify
    // find place for lastElement starting at root
    int currentNode = 1, child = 2; // child of currentNode
    while (child <= size) { // heap[child] should be larger child of currentNode
        if (child < size && heap[child].compareTo(heap[child + 1]) < 0) child++;
        // can we put lastElement in heap[currentNode]?
        if (lastElement.compareTo(heap[child]) >= 0) break; // yes
        heap[currentNode] = heap[child]; // no // move child up
        currentNode = child; // move down a level
        child *= 2; }
    heap[currentNode] = lastElement;
    return maxElement;
}
```

** At each level $\Theta(1)$, So complexity: $O(\text{height}) = O(\log n)$

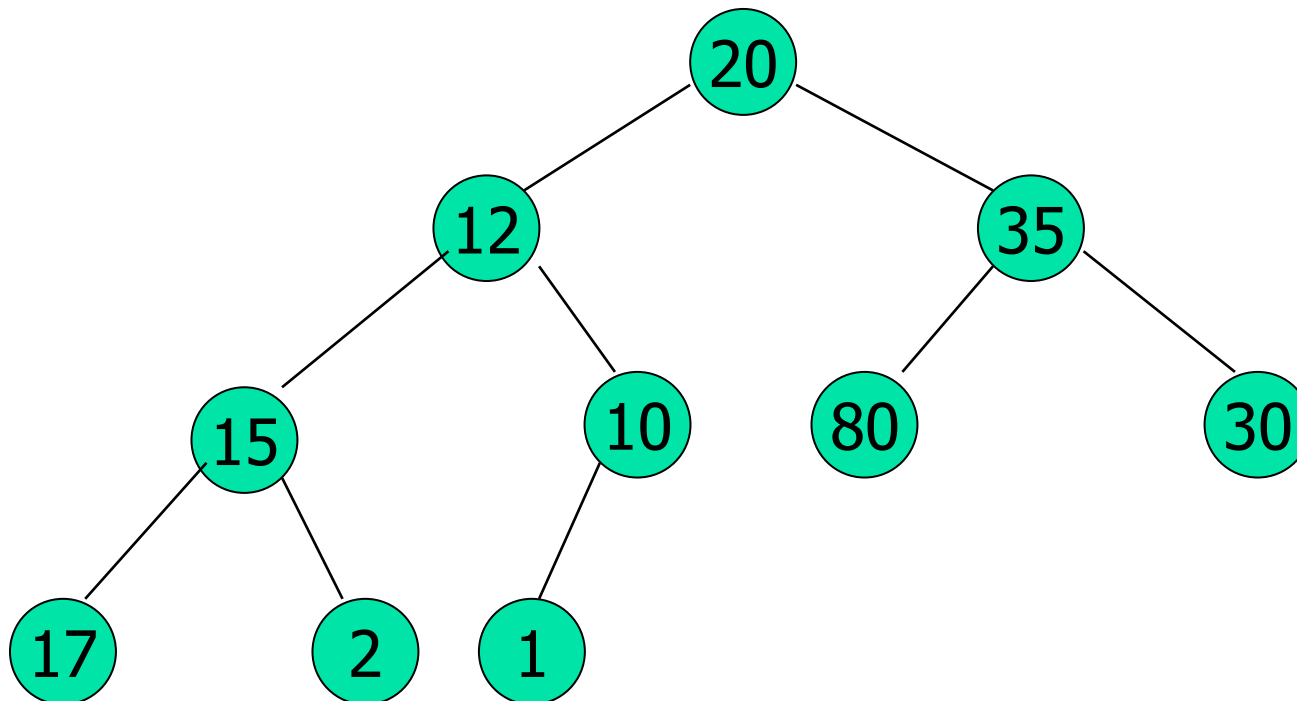


MaxHeap Initialization

- **Steps**
 - **Allocate the elements in an array**
 - **Form a complete binary tree**
 - **In the array, start with the rightmost node having a child**
 - **node number $\rightarrow n/2$**
 - **Fix the heap in the node**
 - **Reverse back to the first node in the array**

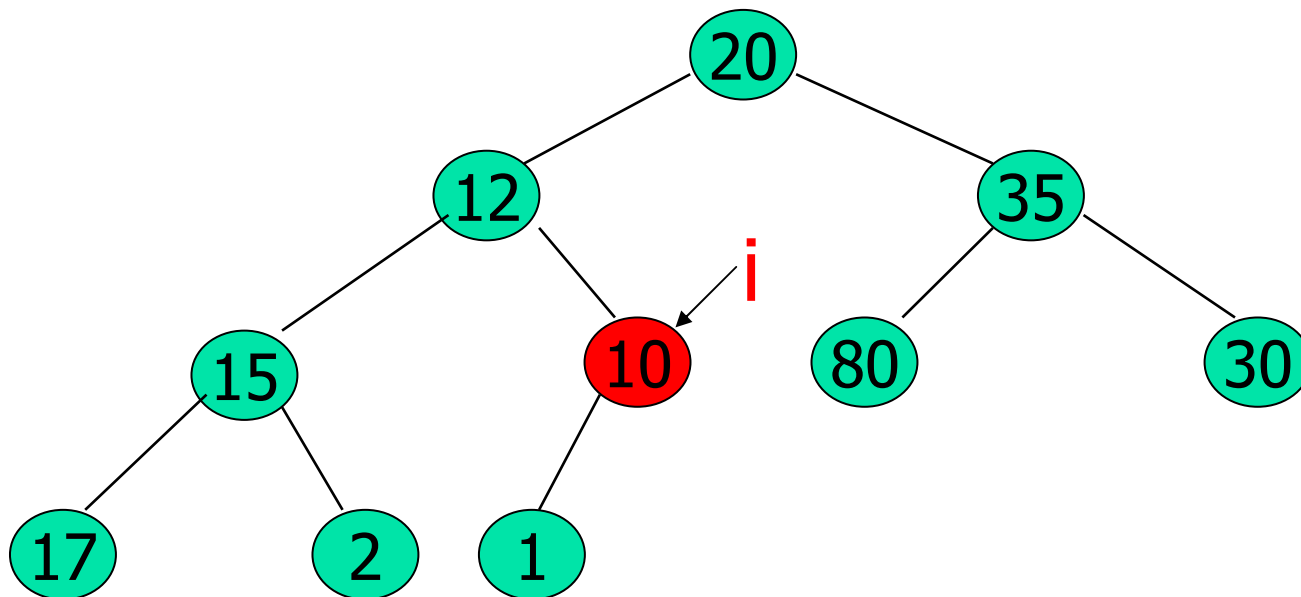
MaxHeap Initialization (1)

- Input array = [20, 12, 35, 15, 10, 80, 30, 17, 2, 1]
- Just make a complete binary tree



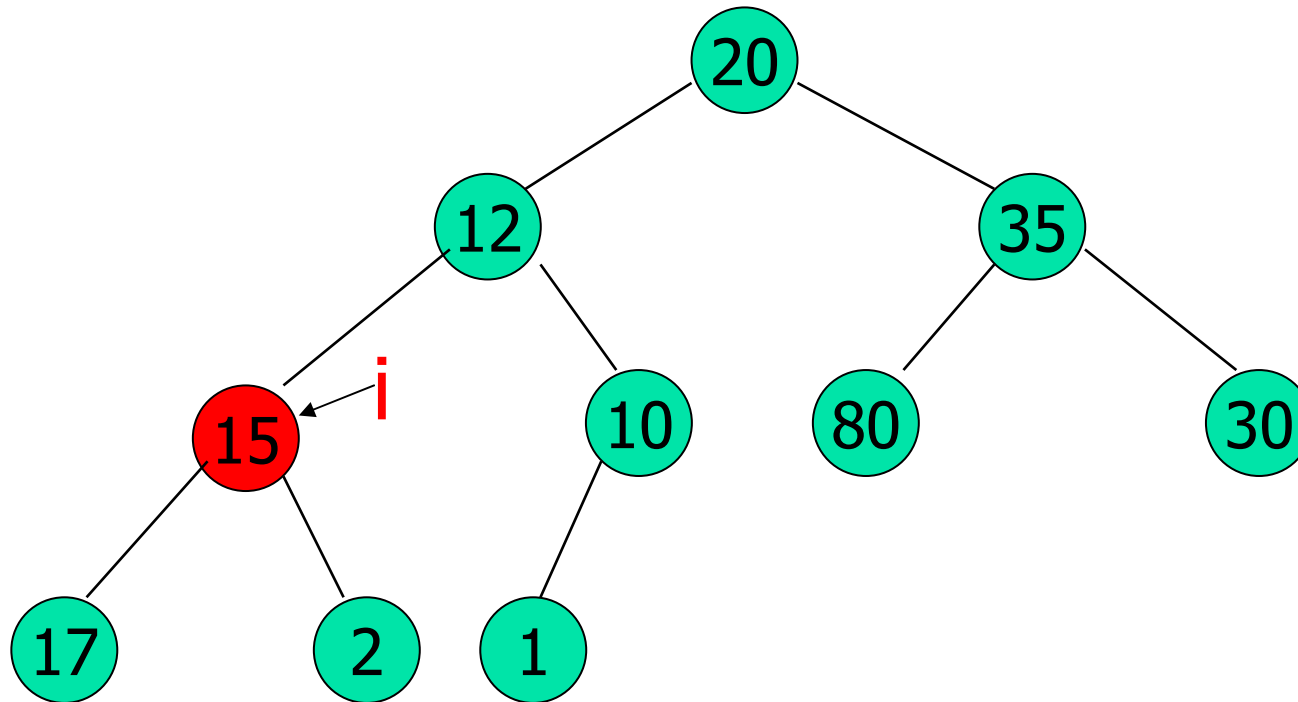
MaxHeap Initialization (2)

- Start at rightmost array position that has a child.
- Index i is $(n/2)^{\text{th}}$ of the array.



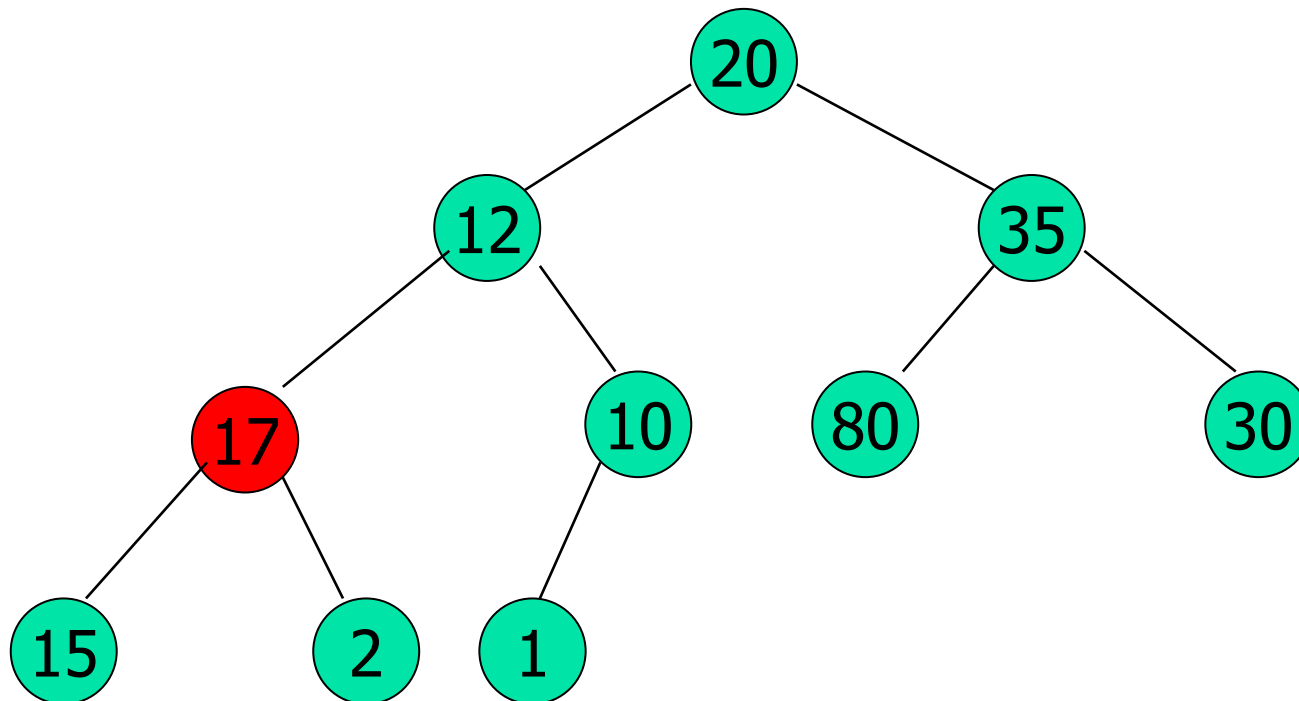
MaxHeap Initialization (3)

- Move to next lower array position.



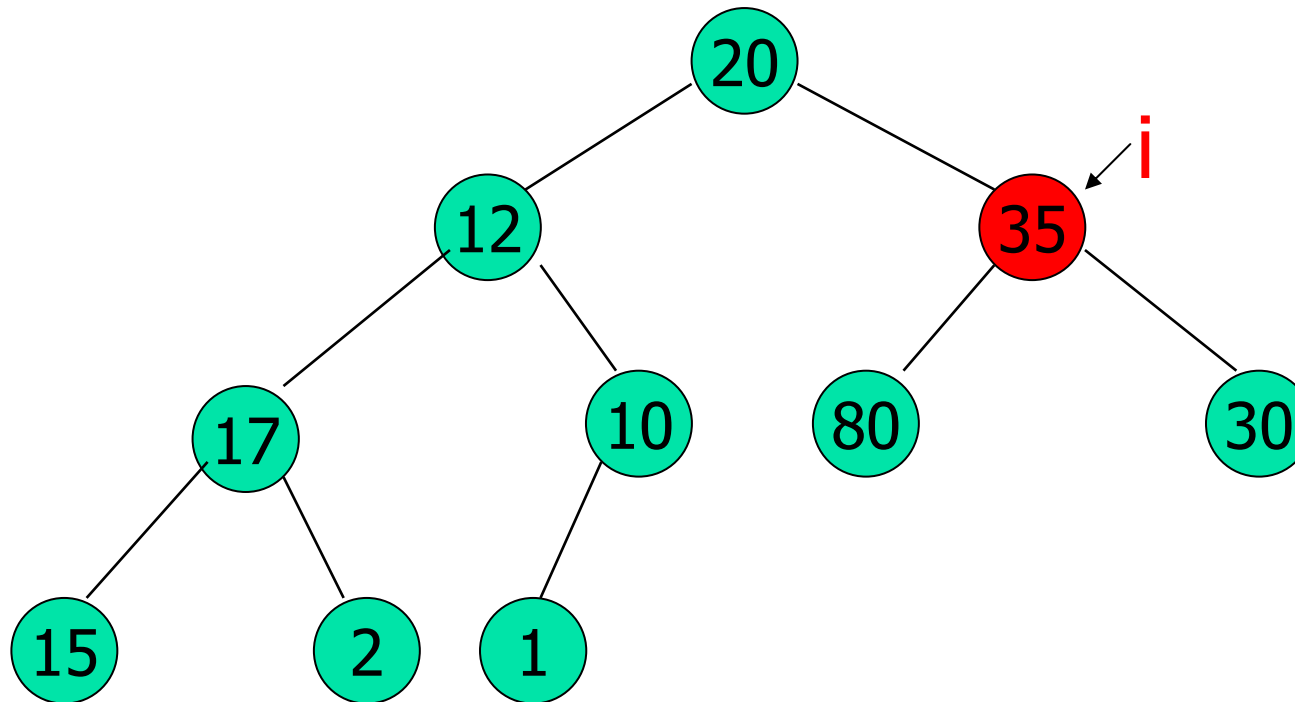
MaxHeap Initialization (4)

- Find a home for 15



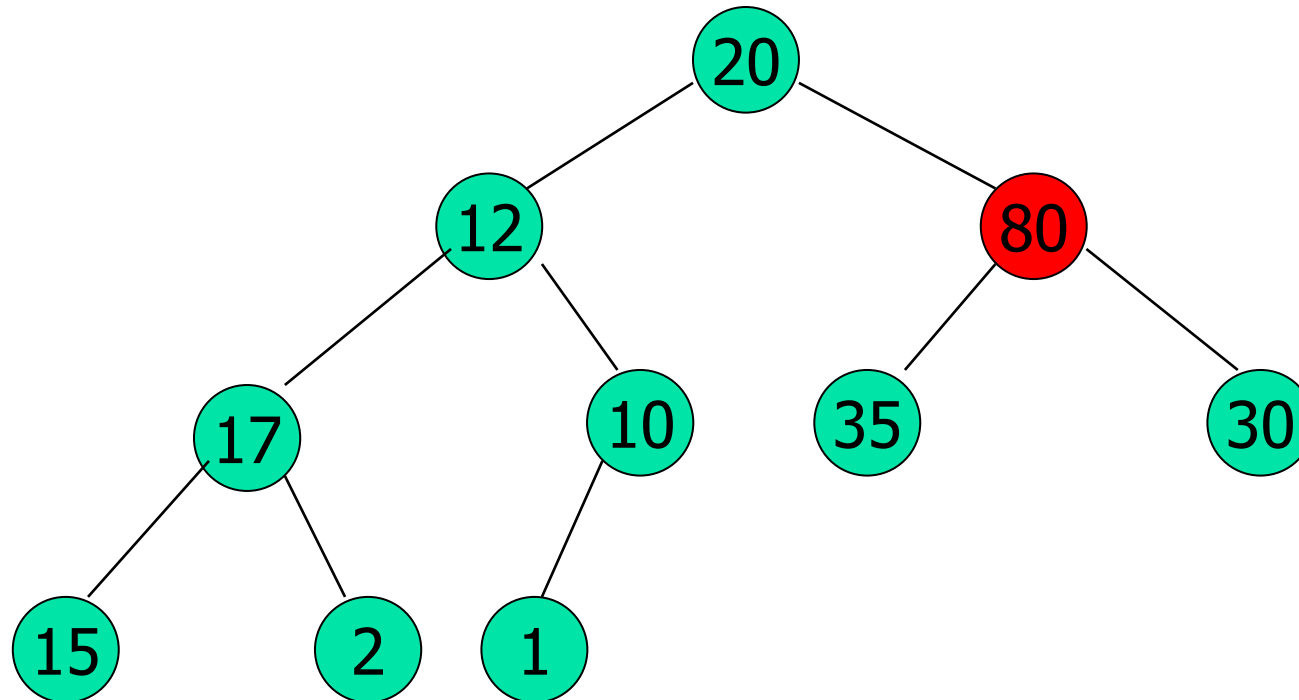
MaxHeap Initialization (5)

- Move to next lower array position.



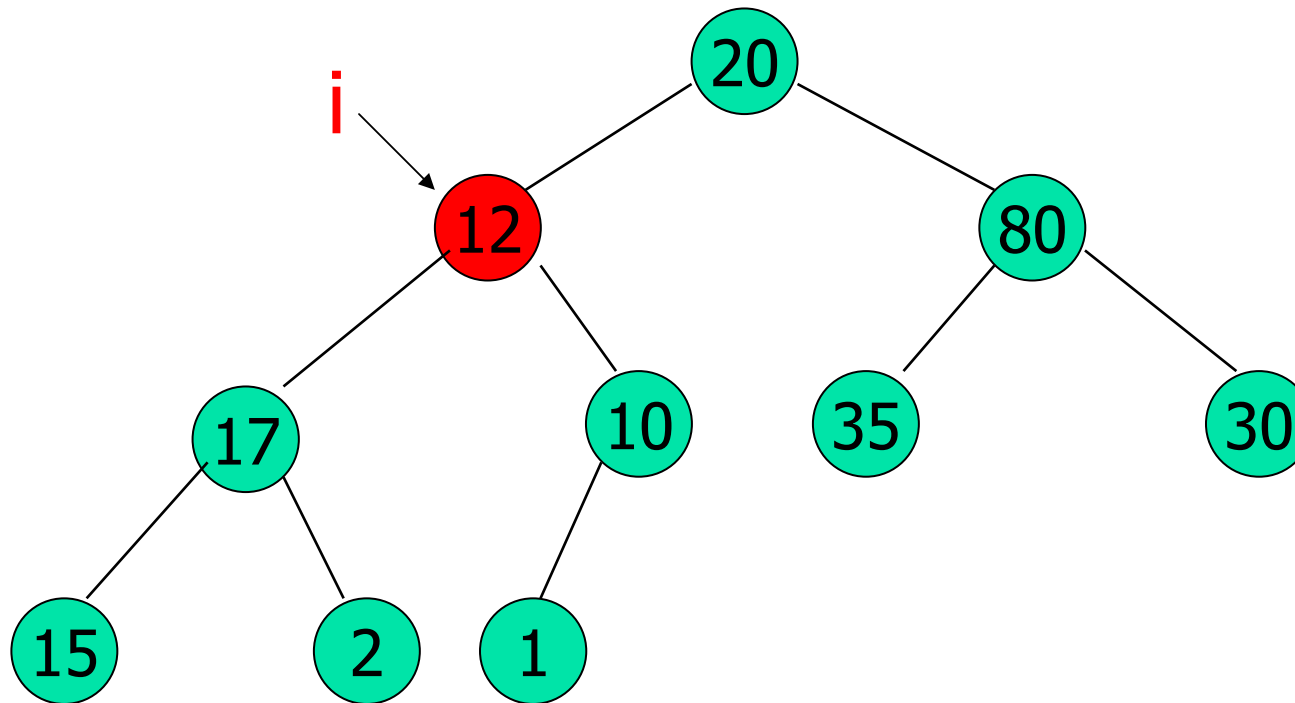
MaxHeap Initialization (6)

- Find a home for 35



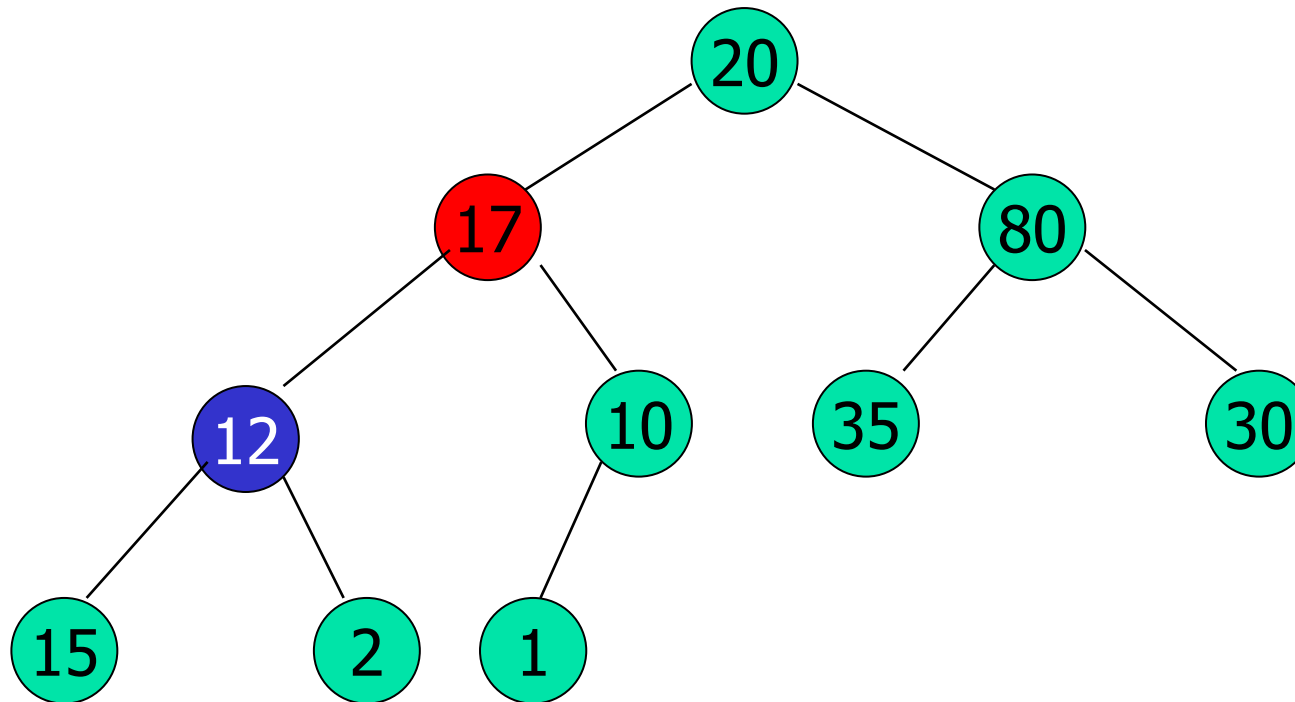
MaxHeap Initialization (7)

- Move to next lower array position.



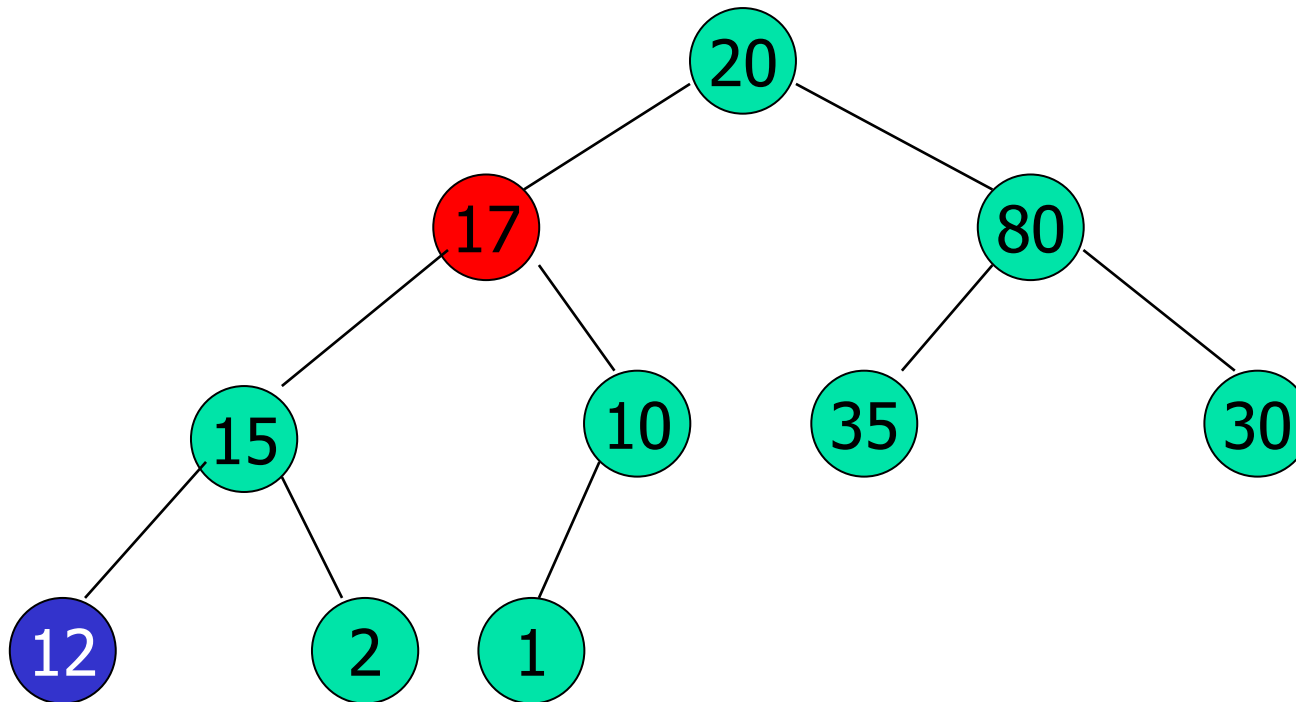
MaxHeap Initialization (8)

- Find a home for 12



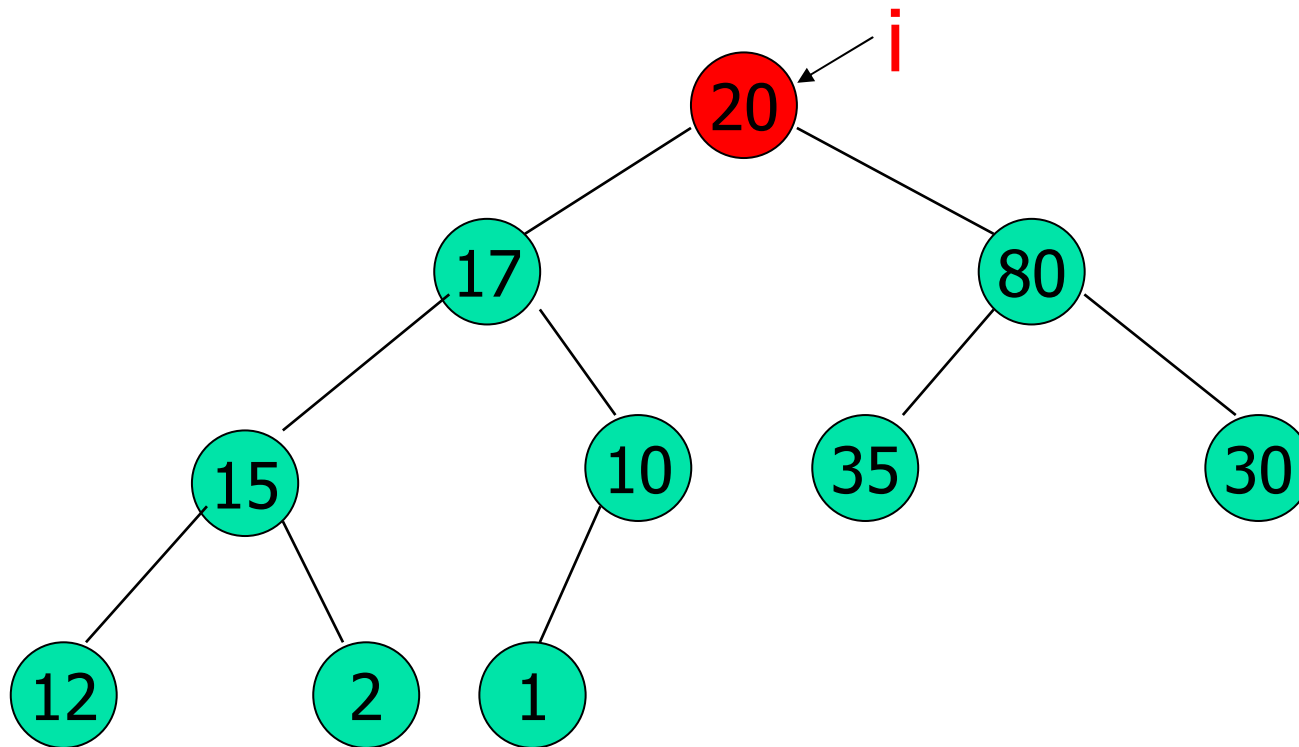
MaxHeap Initialization (9)

- Find a home for 12



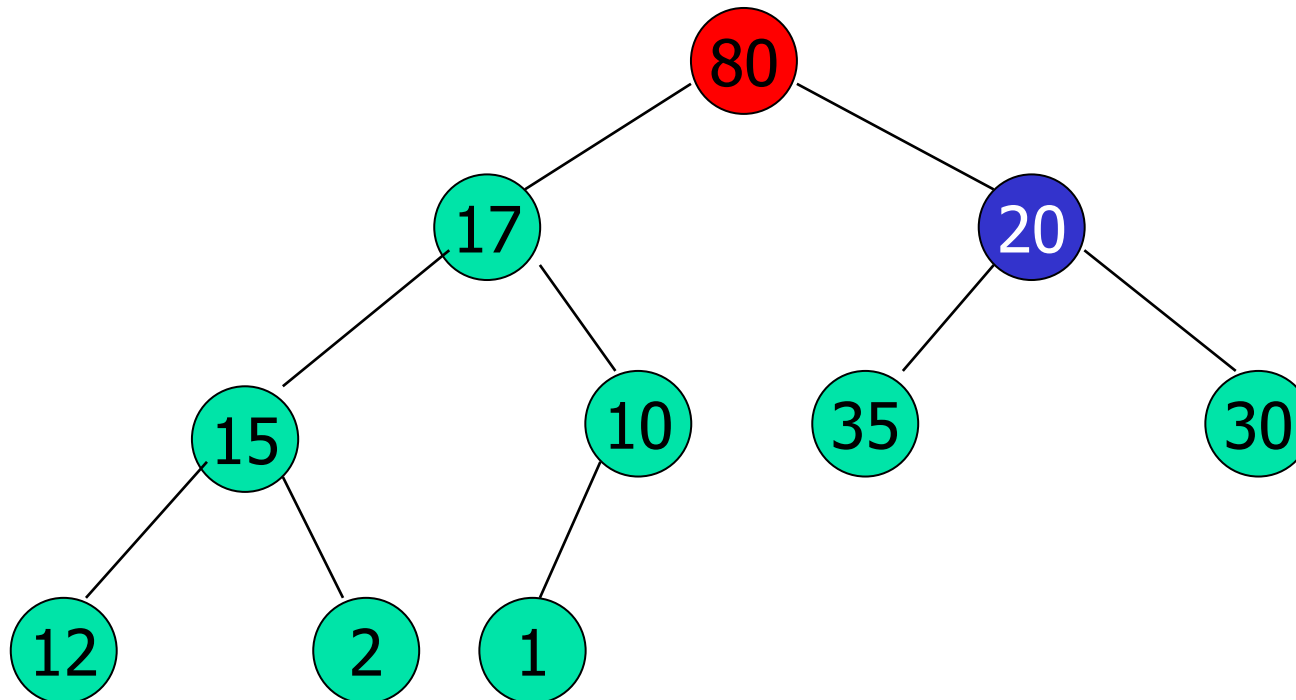
MaxHeap Initialization (10)

- Move to next lower array position.



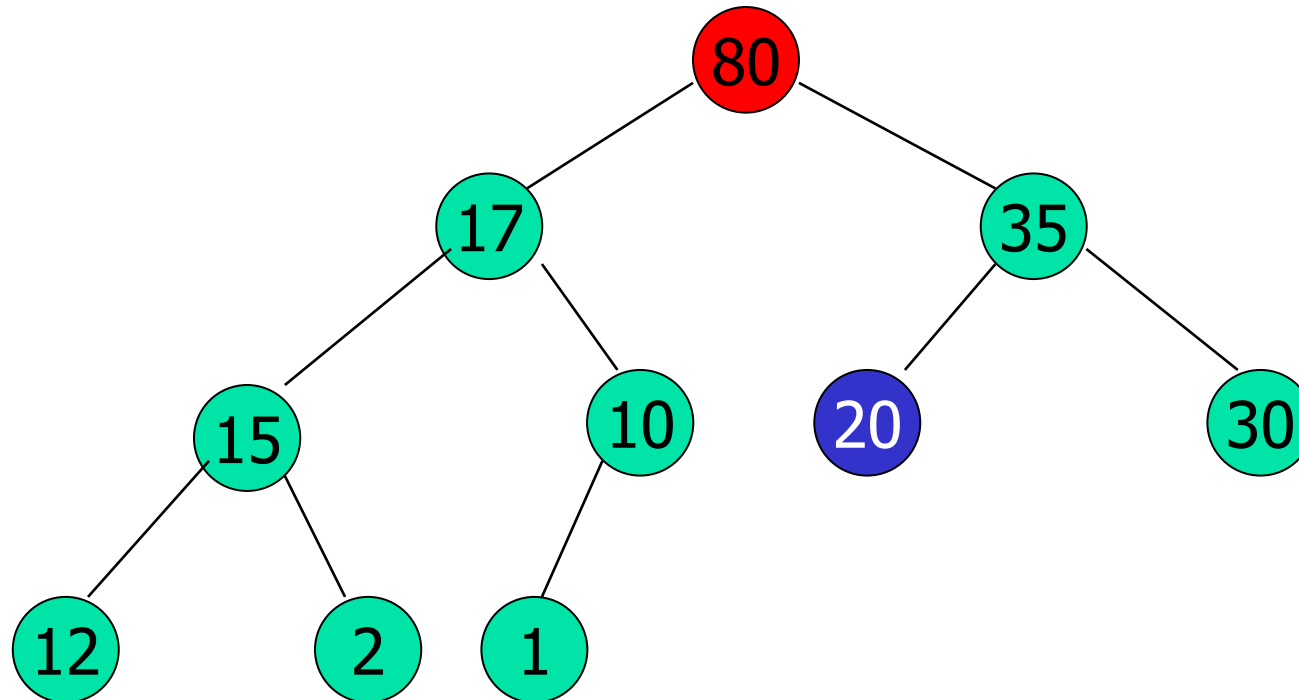
MaxHeap Initialization (11)

- Find a home for 20



MaxHeap Initialization (12)

- Result the max heap





initialize() in MaxHeap

```
public void initialize(Comparable [] theHeap, int theSize) {
heap = theHeap;
size = theSize;
for (int root = size / 2; root >= 1; root--) { // heapify
    Comparable rootElement = heap[root];
    // find place to put rootElement
    int child = 2 * root; // parent of child is target location for rootElement
    while (child <= size) { // heap[child] should be larger sibling
        if (child < size && heap[child].compareTo(heap[child + 1]) < 0) child++;
        // can we put rootElement in heap[child/2]?
        if (rootElement.compareTo(heap[child]) >= 0) break; // yes
        heap[ child / 2 ] = heap[ child ]; // no // move child up
        child *= 2; // move down a level
    }
    heap[ child / 2 ] = rootElement;
}
}
```



Complexity of Heap Initialization

- Rough Analysis
 - for each element $n/2$, for-loop $O(\log n) \rightarrow O(n * \log n)$
- Careful Analysis
 - Height of heap = h
 - Height of each subtree at level $j = h' = h - j + 1$
 - Num of nodes at level $j \leq 2^{j-1}$
 - Time for each subtree at level $j = O(h') = O(h-j+1)$
 - Time for all nodes at level $j \leq 2^{j-1} * (h-j+1) = t(j)$
 - Total time for all level is $t(1) + t(2) + \dots + t(h-1) = O(n)$
- No more than n swappings!

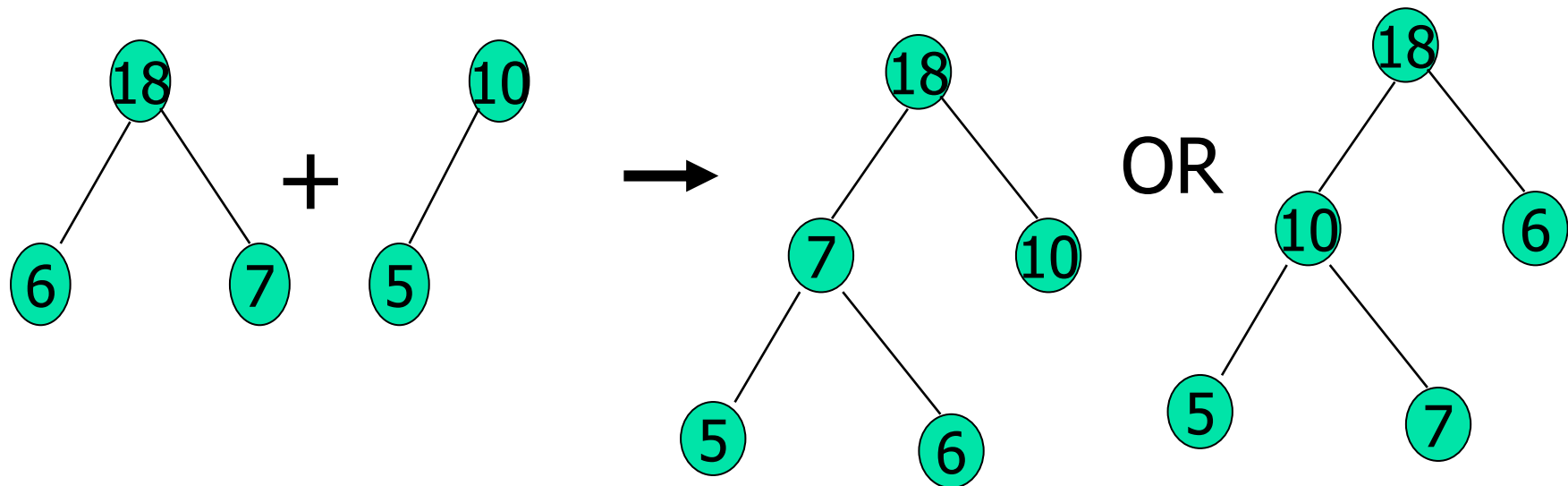


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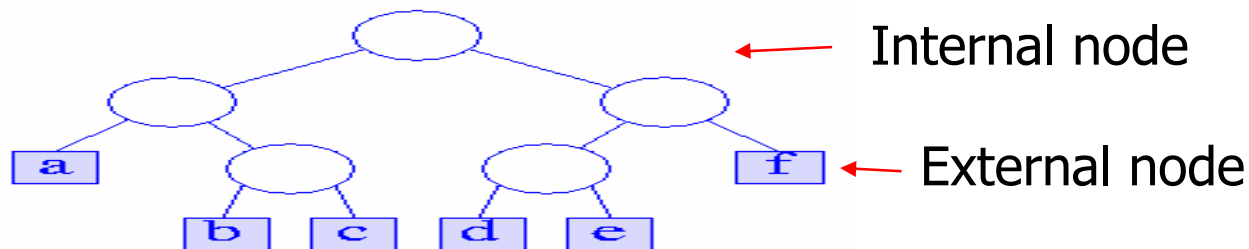
Merging Two Priority Queues

- Heap is efficient for priority queue
- Some applications require **merging two or more priority queues**
- Heap is not suitable for merging two or more priority queues
- **Leftiest tree is powerful in** merging two or more priority queues

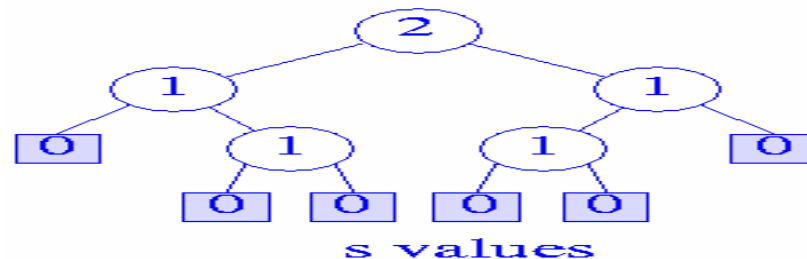


Height-Biased Leftist Tree (HBLT)

- Extended Binary Tree: Add an external node replaces each empty subtree.

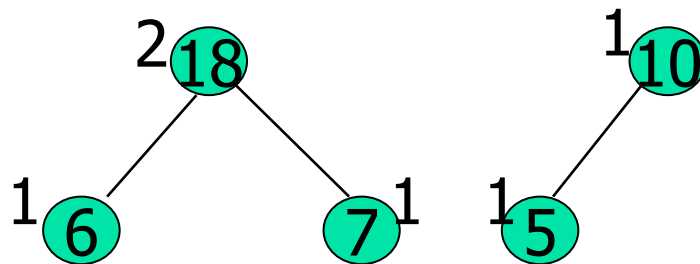


- Let $s(x)$ be the length of a shortest path from node x to an external node in its subtree.



Height-Biased Leftist Tree (HBLT)

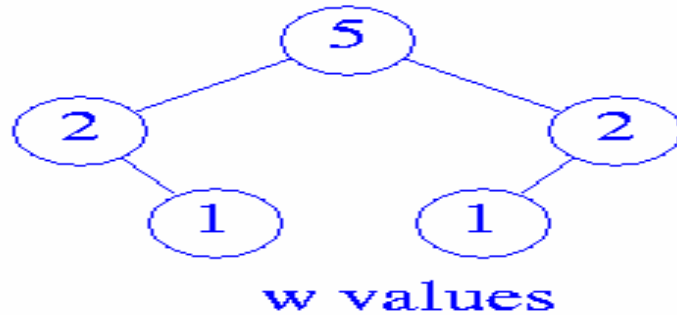
- A binary tree is a height-biased leftist tree (HBLT) iff at every internal node, the s value of the left child is greater than or equal to the s value of the right child.
 - A max HBLT is an HBLT that is also a max tree.
 - A min HBLT is an HBLT that is also a min tree.



- S values in HBLT contributes to make complete binary tree!!!!!!
- [Theorem] Let x be any internal node of an HBLT
 - The number of nodes in the subtree with root x is at least $2^{s(x)} - 1$
 - If the subtree with root x has m nodes, $s(x)$ is at most $\log_2(m+1)$
 - The length of the right-most path from x to an external node is $s(x)$

Weight Biased Leftist Tree (WBLT)

- Let $w(x)$ be the weight from node x to be the number of internal nodes in the subtree with root x



- A binary tree is weight-biased leftist tree (WBLT) iff at every internal node the w value of the left child is greater than or equal to the w value of the right child
 - A max WBLT is a max tree that is also a WBLT
 - A min WBLT is a min tree that is also a WBLT



Put a Max Element into a HBLT

- Create a new max HBLT
- Meld this max HBLT and the original

```
public void put (Comparable theElement) {  
    HbltNode q = new HbltNode (theElement, 1);  
    // meld q and original tree  
    root = meld (root, q);  
    size++;  
}
```



Remove a Max element from a HBLT

- Delete the root
- Meld its two subtrees

```
public Comparable removeMax() {  
    if (size == 0) return null; // tree is empty  
  
    // tree not empty  
    Comparable x = root.element; // save max element  
    root = meld (root.leftChild, root.rightChild);  
    size--;  
    return x;  
}
```



Meld Two HBLTs

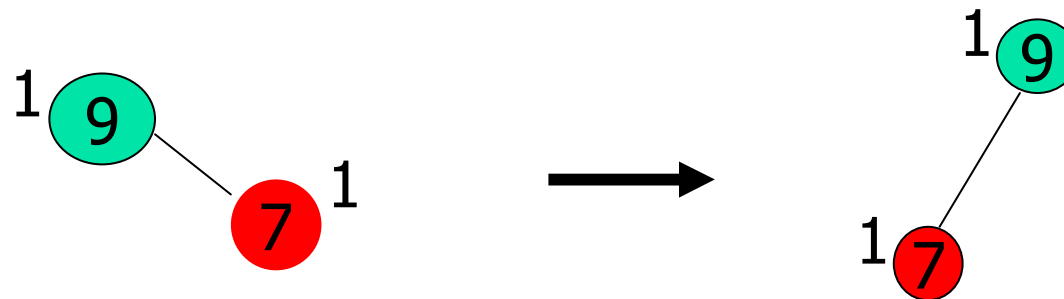
- Let A & B be the two HBLTs
- Compare the root of A & B
- The bigger value is the new root for the melded tree
 - Assume the root of A is bigger & A has left subtree L
- Meld the right subtree and B → result C
- A has the left subtree L and the right subtree C
- Compare the S values of L & C
- Swap if necessary

Melding 2 HBLTs: Ex 1

- Consider the two max HBLTs

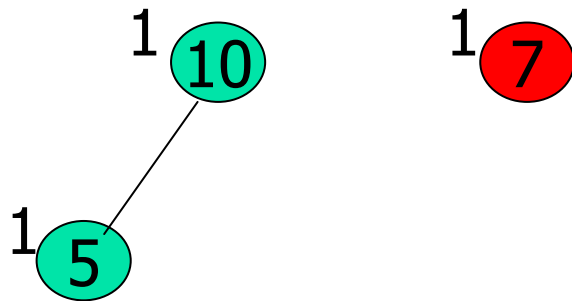


- $9 > 7$, so 9 is root.
- The s value of the left subtree of 9 is 0 while the s value of the right subtree is 1 → Swap the left subtree and the right subtree

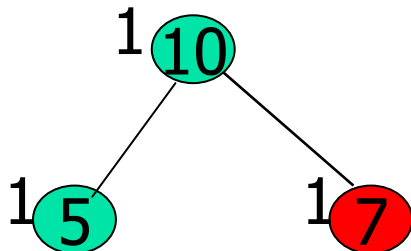


Melding 2 HBLTs: Ex 2

- Consider the two max HBLTs



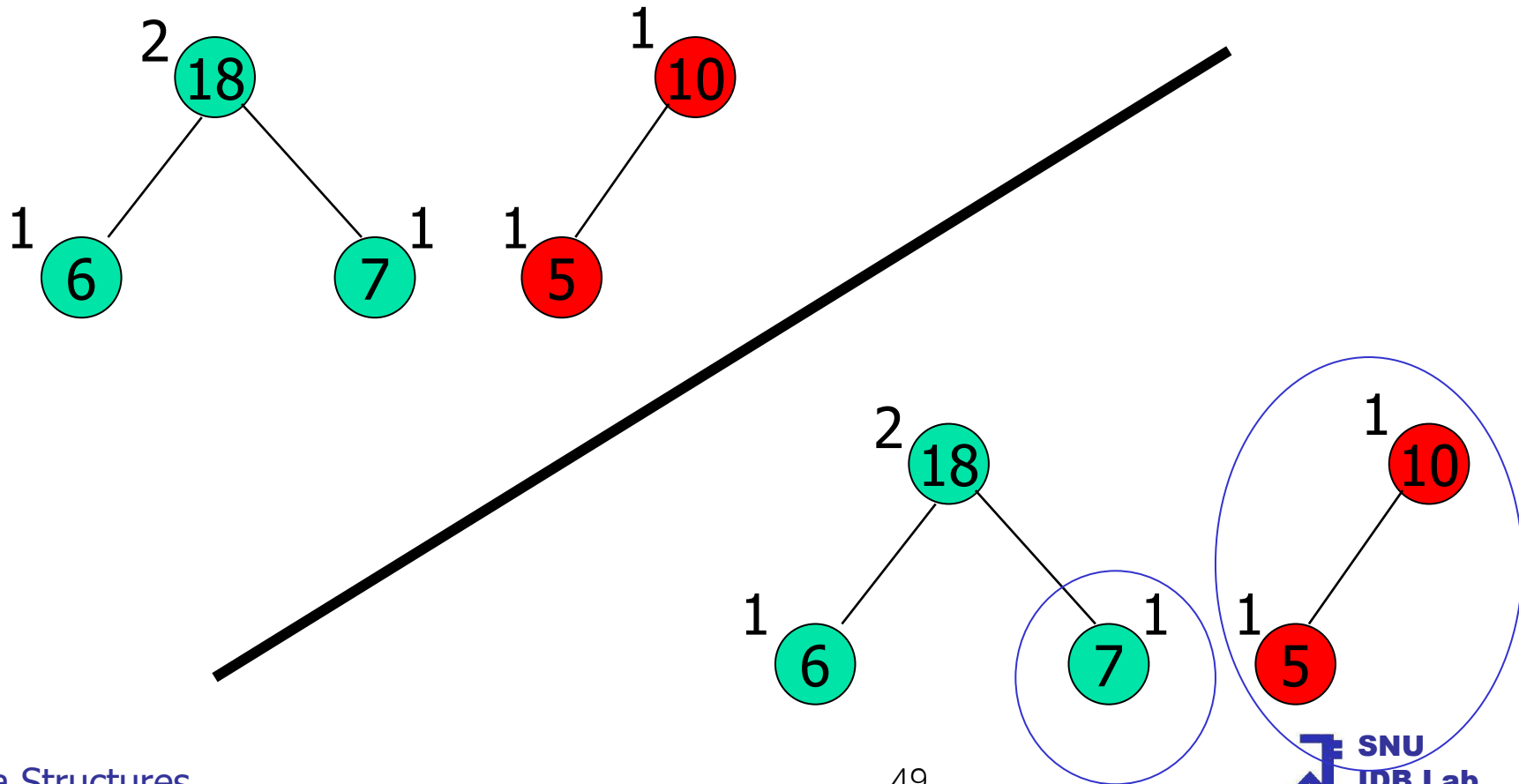
- $10 > 7$, so root is 10



- Comparing the s values of the left and right children of 10, a swap is not necessary

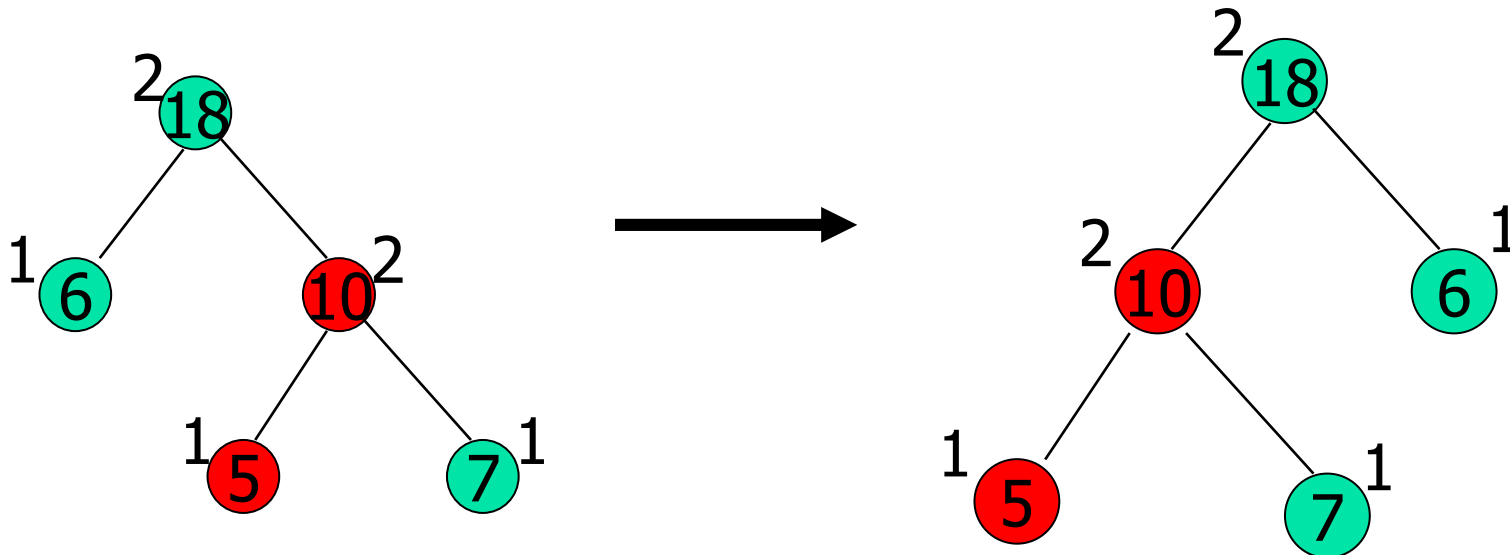
Melding 2 HBLTs: Ex 3 (1)

- Consider the two max HBLTs



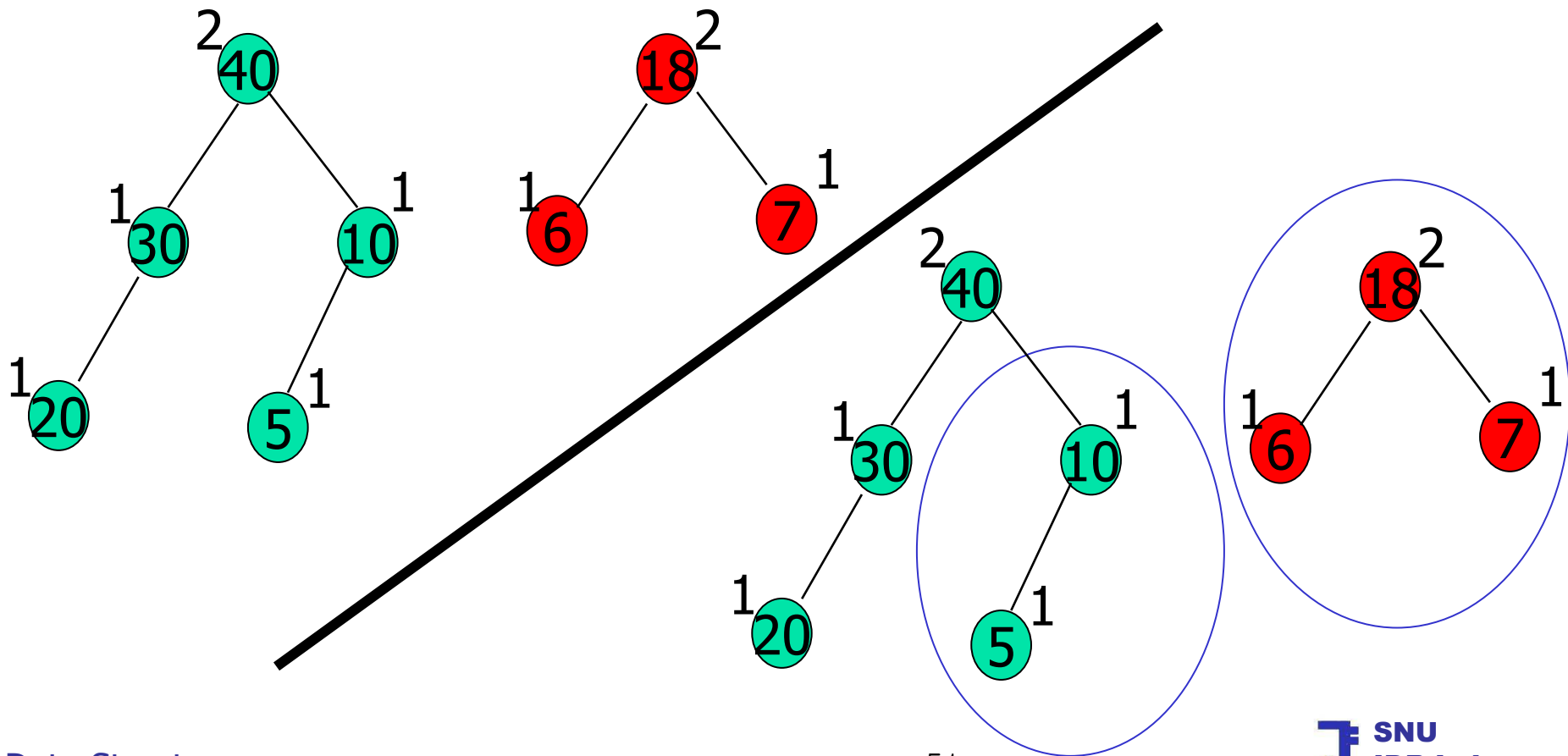
Melding 2 HBLTs: Ex 3 (2)

- $18 > 10$, root is 18
- Meld the right subtree of 18
- $s(\text{left}) < s(\text{right})$, swap left and right subtree



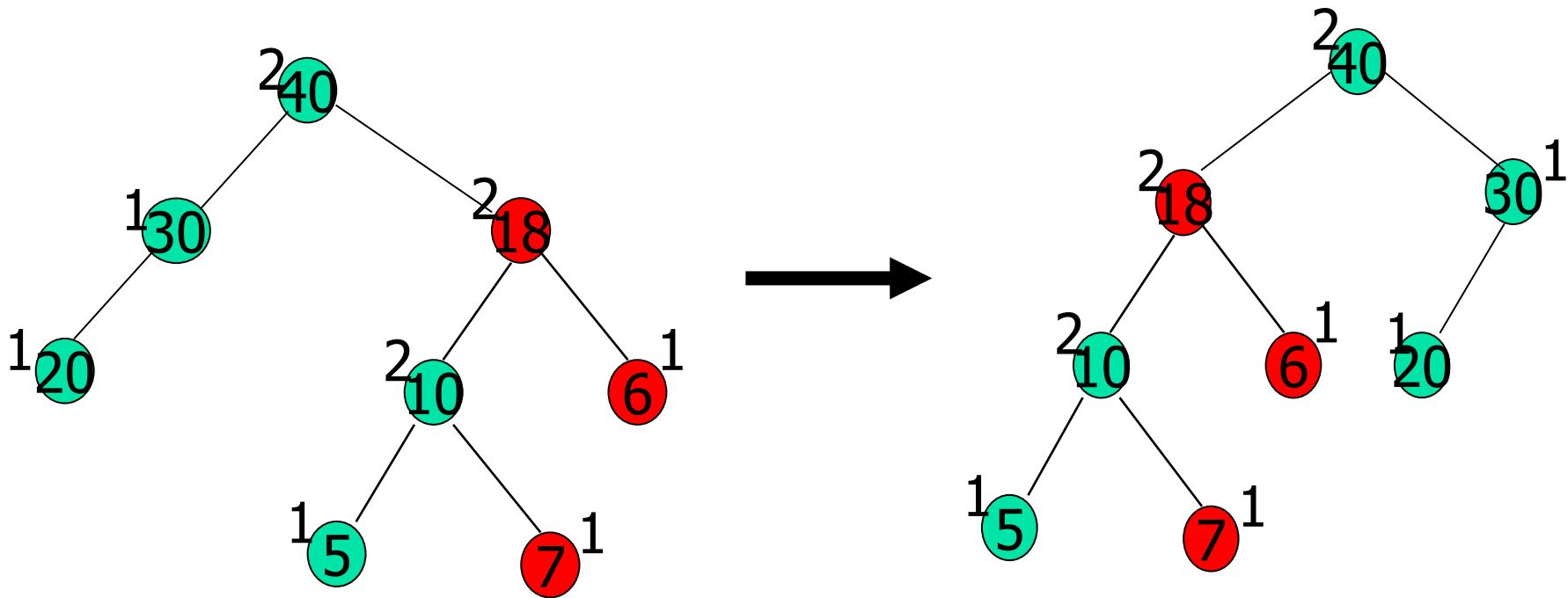
Melding 2 HBLTs: Ex 4 (1)

- Consider the two max HBLTs



Melding 2 HBLTs: Ex 4 (2)

- $40 > 18$, root is 40
- Meld the right subtree of 40
- $s(\text{left}) < s(\text{right})$, swap left and right subtree



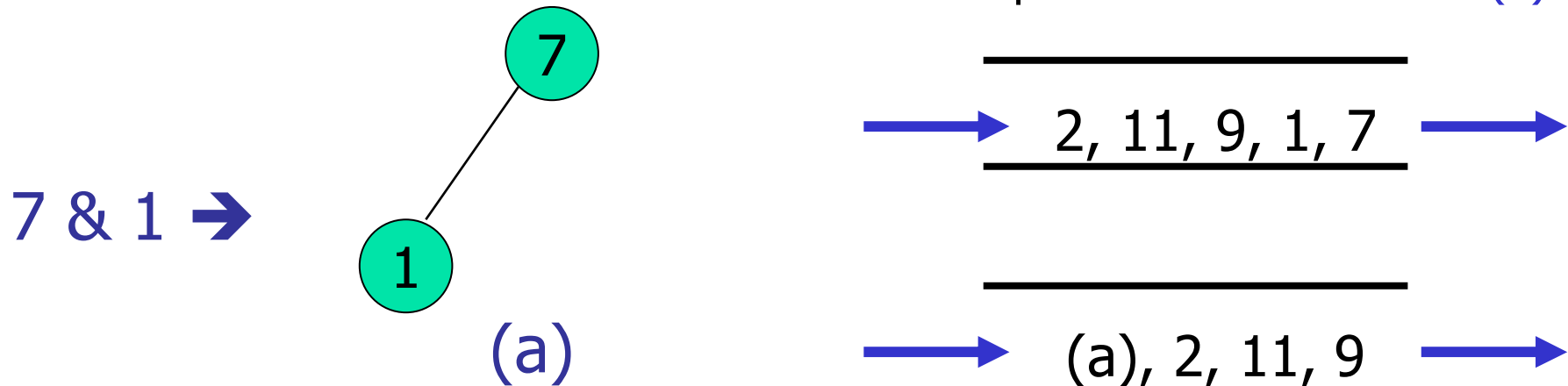


meld() in HBLT

```
private static HbltNode meld (HbltNode x, HbltNode y) {
    if (y == null)    return x;  // y is empty
    if (x == null)    return y;  // x is empty
    // neither is empty, swap x and y if necessary
    if (x.element.compareTo(y.element) < 0) { // swap x and y
        HbltNode t = x;  x = y; y = t; } // now x.element >= y.element
    x.rightChild = meld (x.rightChild, y);
    if (x.leftChild == null) { // left subtree is empty, swap the subtrees
        x.leftChild = x.rightChild; x.rightChild = null; x.s = 1; }
    else { // swap only if left subtree has a smaller s value
        if (x.leftChild.s < x.rightChild.s) { // swap subtrees
            HbltNode t = x.leftChild; x.leftChild = x.rightChild; x.rightChild = t; }
        x.s = x.rightChild.s + 1; // update s value
    }
    return x;
}
```

Initializing a Max HBLT (1)

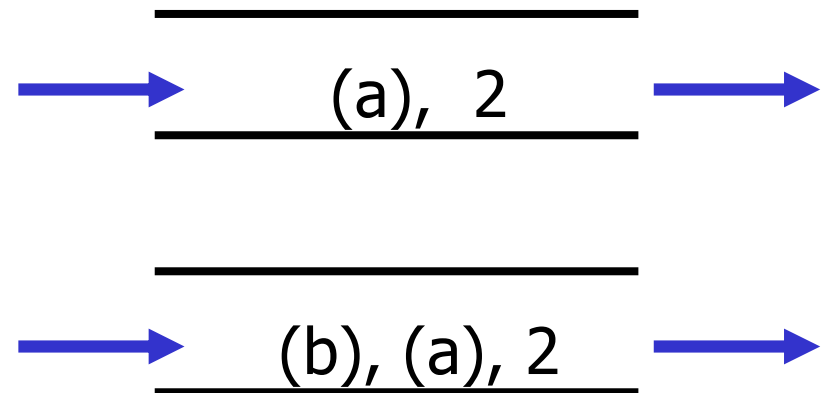
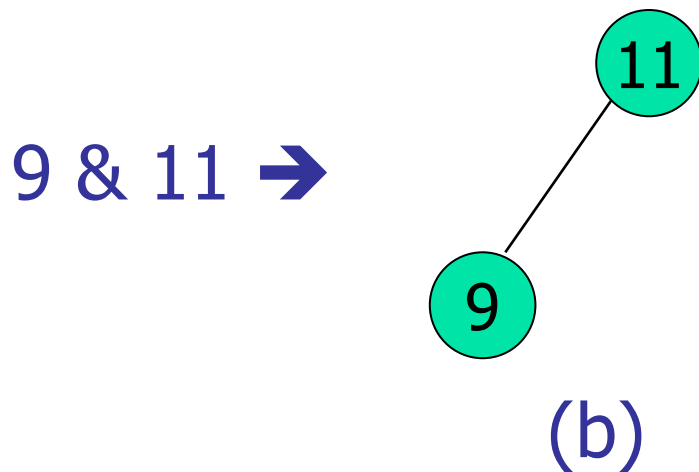
- Create a max HBLT with the five elements 7, 1, 9, 11, and 2
- Five single-element max HBLTs are created and placed in a FIFO queue
- The max HBLTs 7 and 1 are deleted from the queue and melded into (a)



- The result (a) is added to the queue

Initializing a Max HBLT (2)

- The max HBLTs 9 and 11 are deleted from the queue and melded into (b)

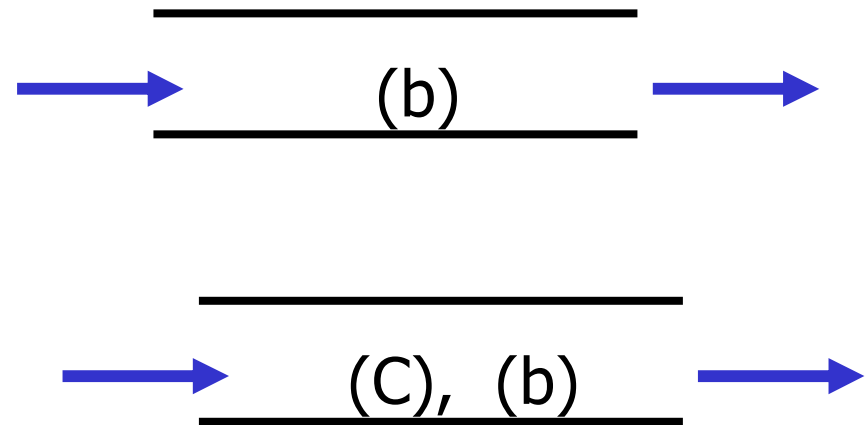
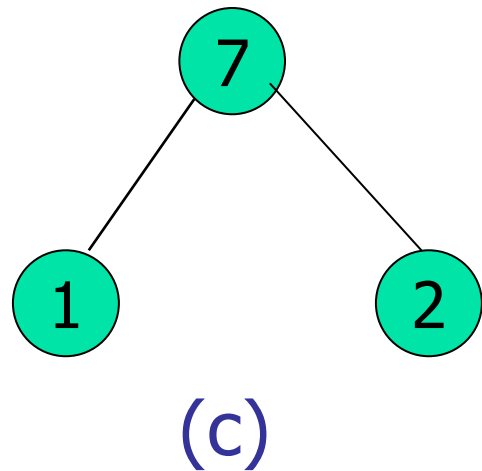


- The result (b) is added to the queue

Initializing a Max HBLT (3)

- The max HBLTs 2 and (a) are deleted from the queue and melded into (c)

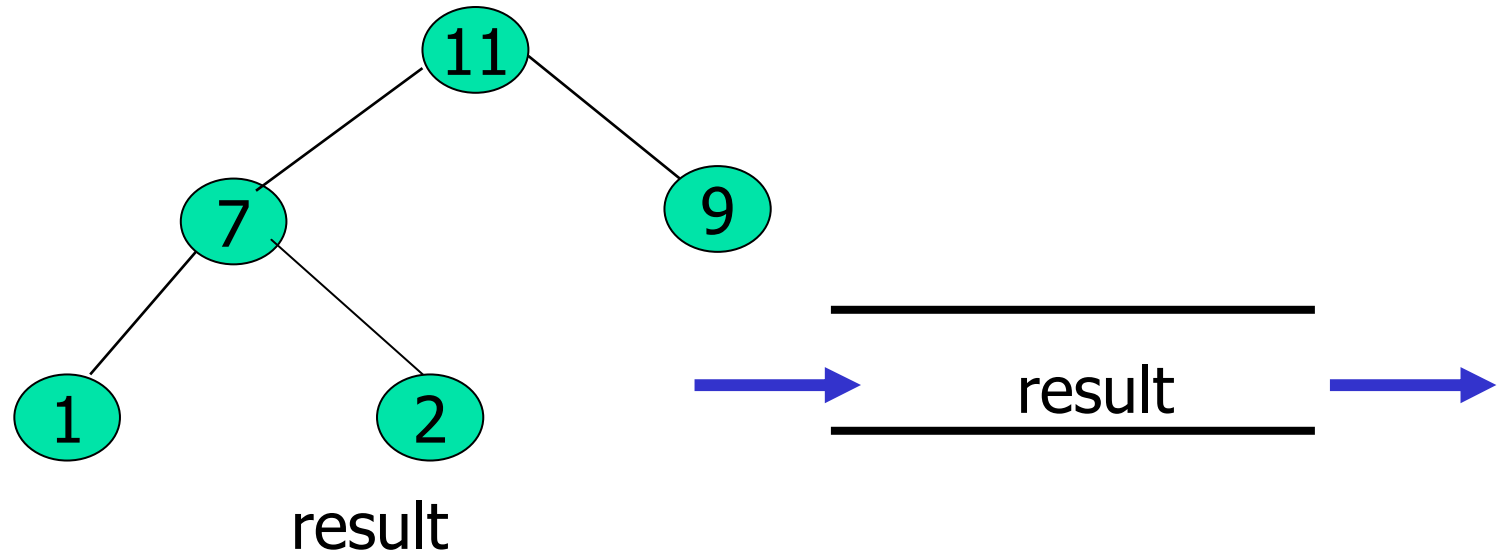
2 & (a) →



- The result (c) is added to the queue

Initializing a Max HBLT (4)

- The max HBLTs (b) and (c) are deleted from the queue and melded into the result



- The result is added to the queue
- The queue now has just **one max HBLT**, and we are done with the initialization



initialize() in HBLT

```
public void initialize(Comparable [] theElements, int theSize) {
    size = theSize;
    ArrayQueue q = new ArrayQueue(size);
    // initialize queue of trees
    for (int i = 1; i <= size; i++) // create trees with one node each
        q.put(new HbltNode(theElements[i], 1));
    // repeatedly meld from queue q
    for (int i = 1; i <= size - 1; i++) { // remove and meld two trees from the queue
        HbltNode b = (HbltNode) q.remove();
        HbltNode c = (HbltNode) q.remove();
        b = meld(b, c);
        // put melded tree on queue
        q.put(b);
    }
    if (size > 0) root = (HbltNode) q.remove();
}
```



Complexity Analysis of HBLT

- getMax
 - $\Theta(1)$
- The complexity of put() and removeMax() is the same as that of = meld()
 - put() and removeMax() are used for meld()
- meld()
 - Root x and y
 - $O(s(x) + s(y))$ where $s(x)$ and $s(y)$ are at most $\log(m+1)$ and $\log(n+1)$
 - m and n are the number of elements in the max HBLTs with root x and y
 - $O(\log(m) + \log(n)) = O(\log(m*n))$



Complexity of Initialize HBLT

- n = size of a power of 2
- The first $n/2$ melds involve max HBLTs with **one** element each
- The next $n/4$ melds involve max HBLTs with **two** elements each
- The next $n/8$ melds involve max HBLTs with **four** elements each
- And so on

- Meld two trees with 2^i elements each
 - $O(i+1)$
- Total time
 - $O(n/2 + 2*(n/4) + 3*(n/8) + \dots) = O(n)$



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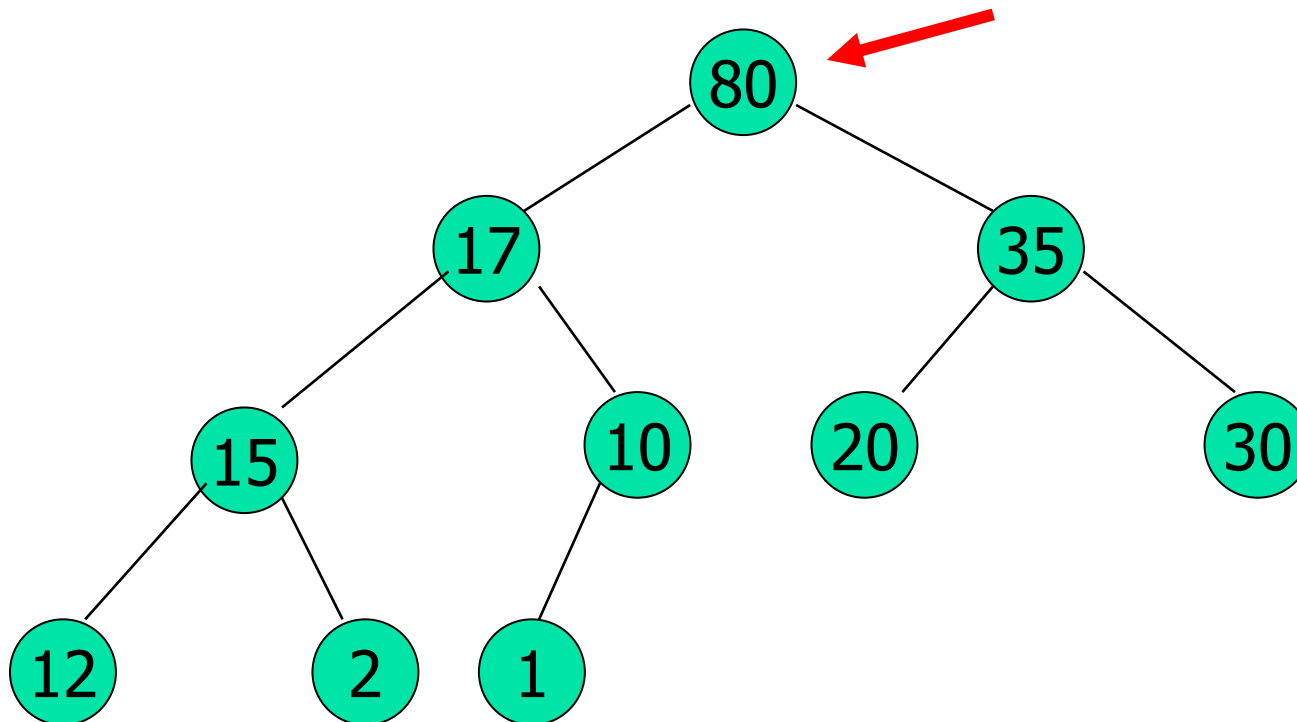
Heap Sort

```
public static void heapSort (Comparable [] a)    {  
  
    //create a max heap of the elements  
    MaxHeap h = new MaxHeap();  
    h.initialize(a, a.length - 1);  
  
    //extract one by one from the max heap  
    for (int i = a.length - 2; i >= 1; i--)  
        a[i + 1] = h.removeMax() ;  
}
```

MaxHeap class: initialize(), removeMax()

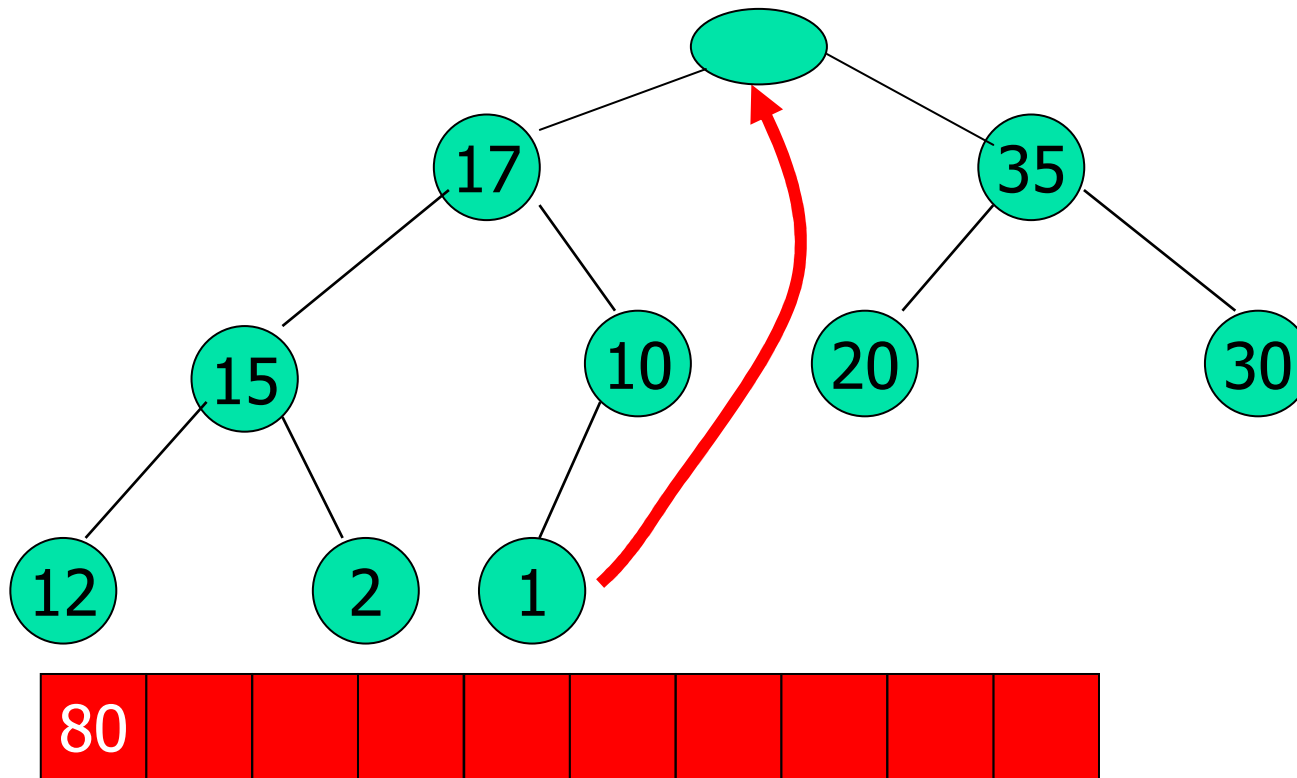
Heap Sort Ex (1)

- This sorting loop begins with the max heap



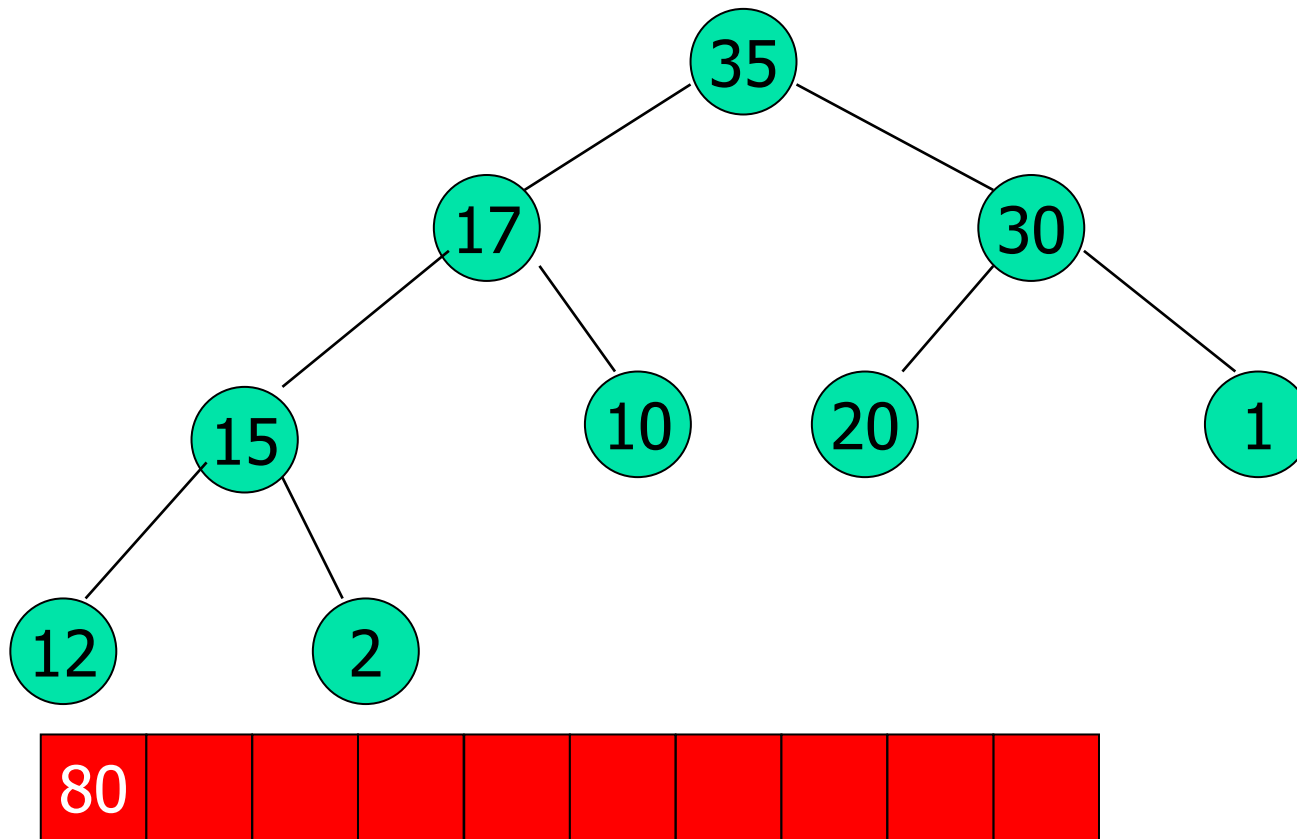
Heap Sort Ex (2)

- Remove Max & move the last element "1" to the root



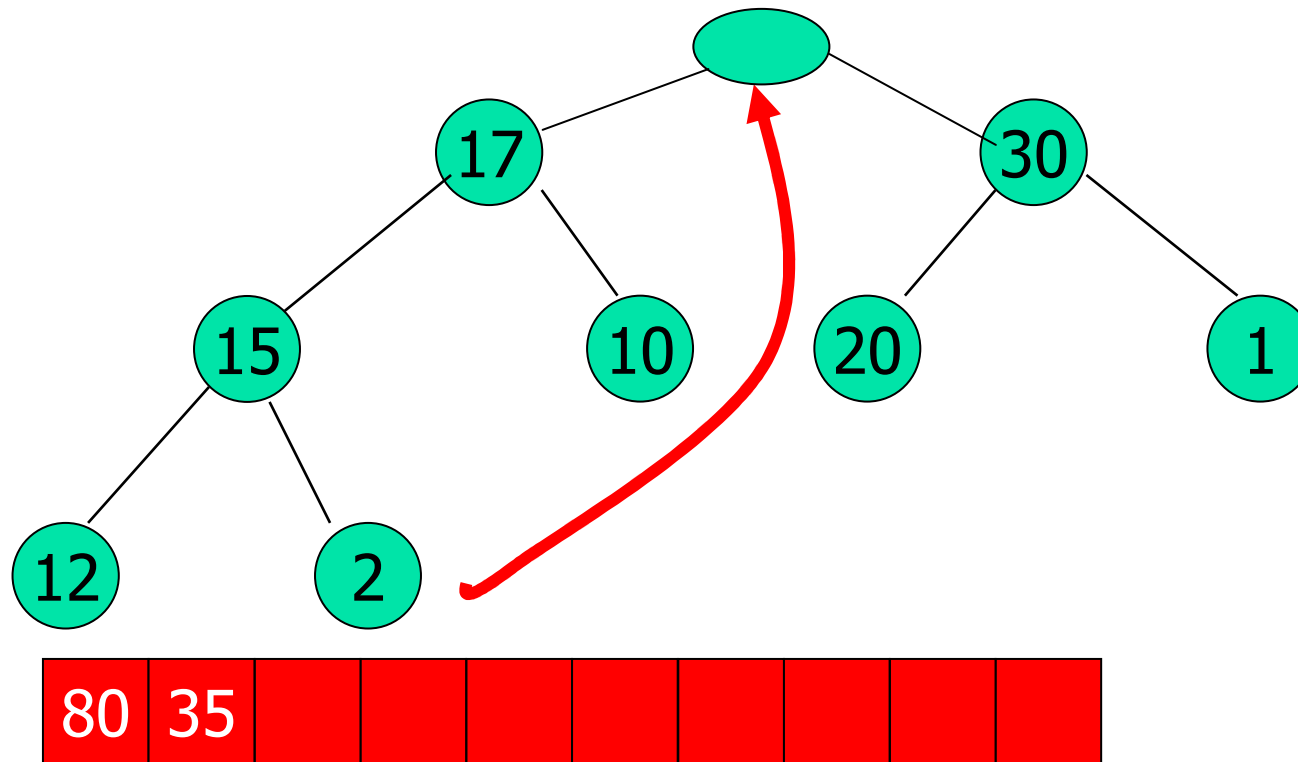
Heap Sort Ex (3)

- Reheapify: Meld root.leftChild and root.rightChild



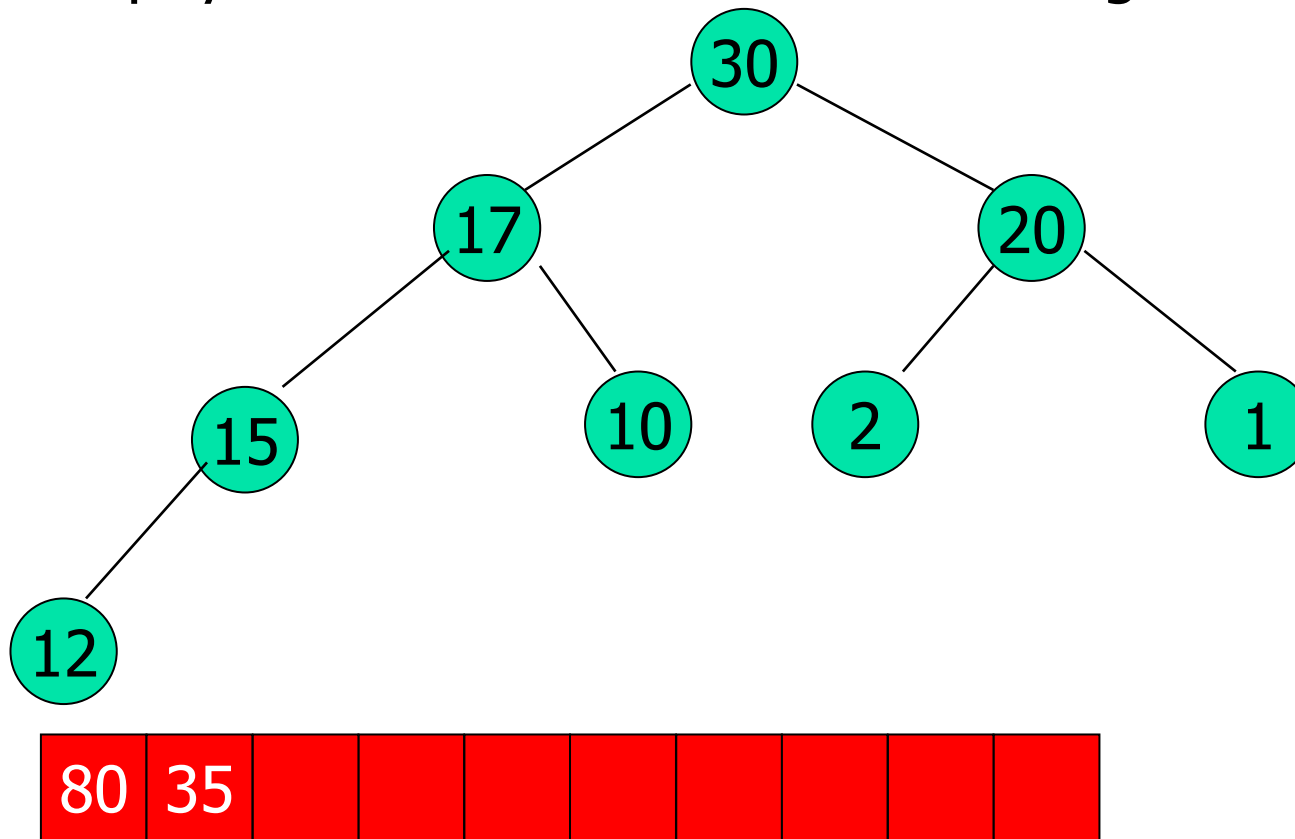
Heap Sort Ex (4)

- Remove Max & move the last element "2" to the root



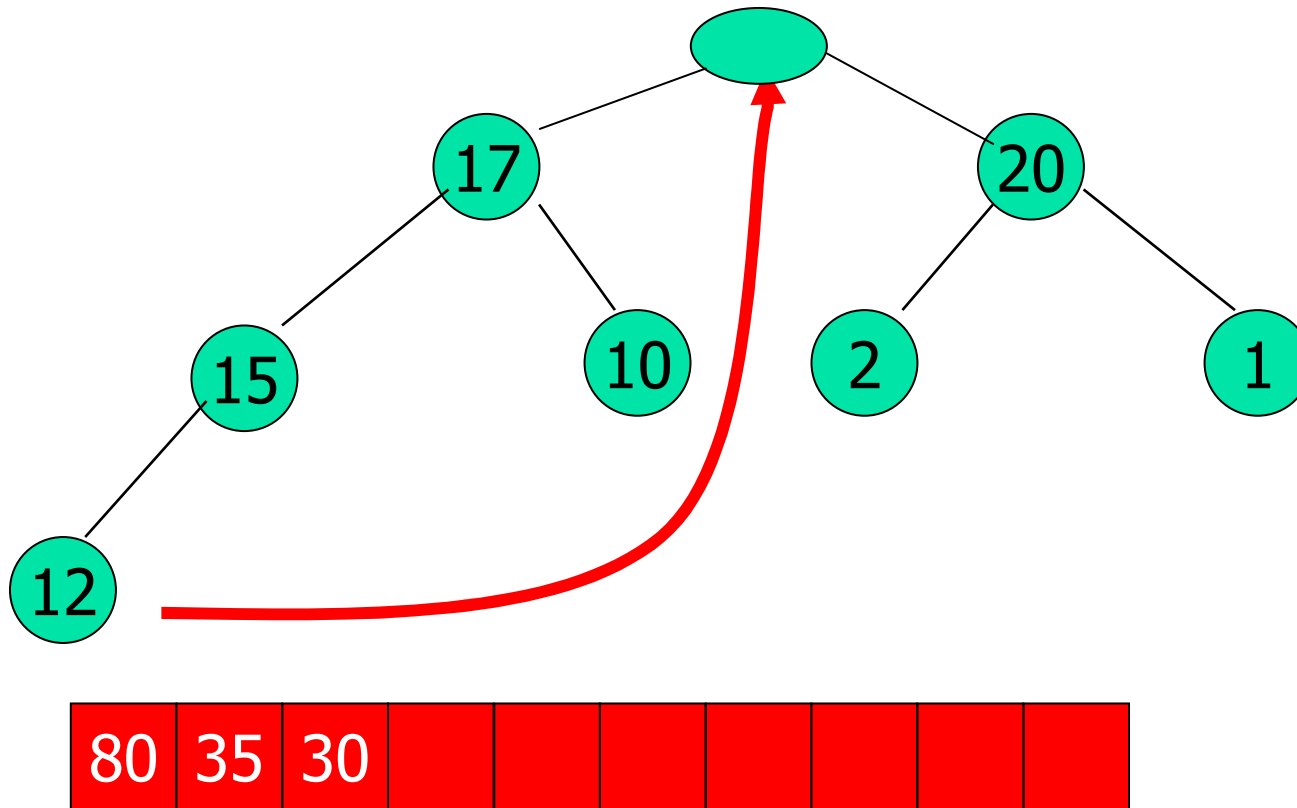
Heap Sort Ex (5)

- Reheapify: Meld root.leftChild and root.rightChild



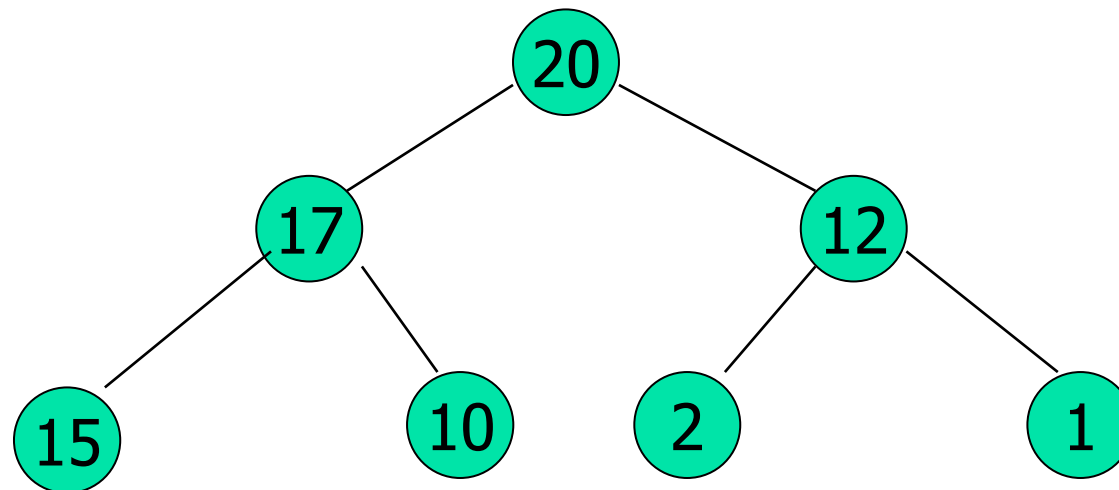
Heap Sort (6)

- Remove Max & move the last element "12" to the root



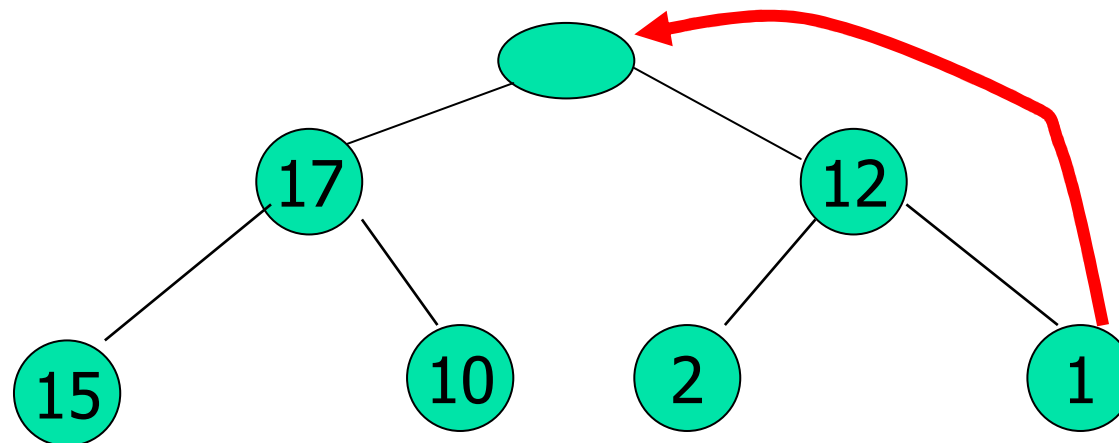
Heap Sort Ex (7)

- Reheapify: Meld root.leftChild and root.rightChild



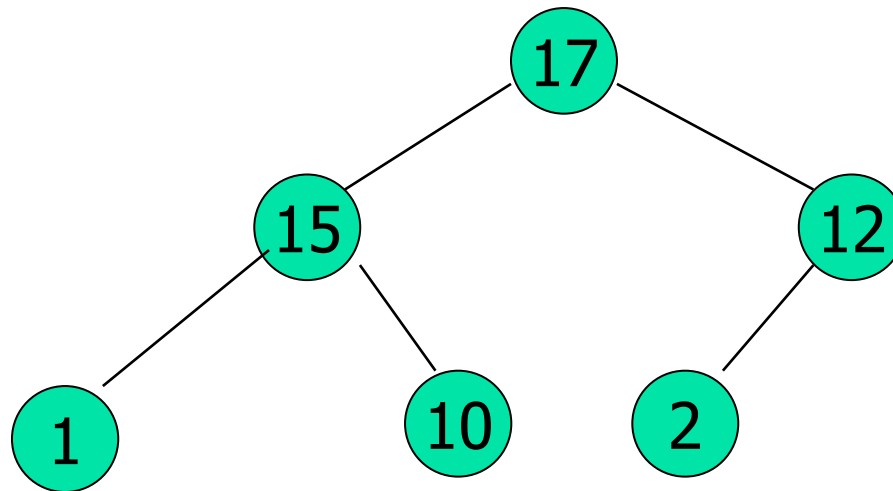
Heap Sort Ex (8)

- Remove Max & move the last element "1" to the root



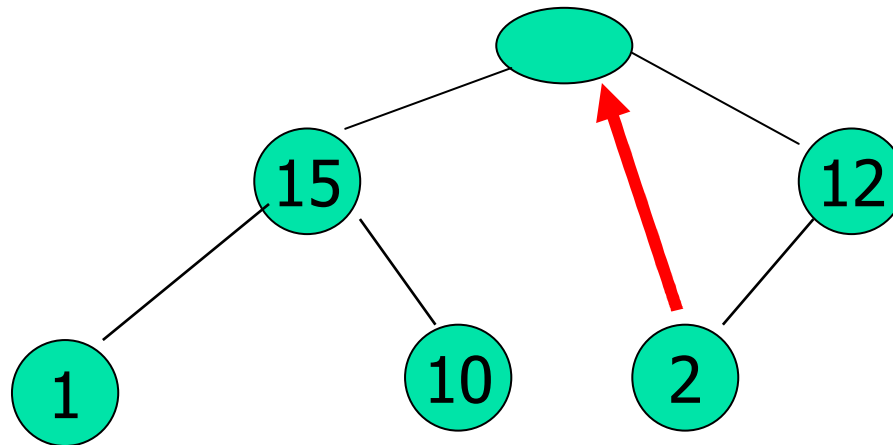
Heap Sort Ex (9)

- Reheapify: Meld root.leftChild and root.rightChild



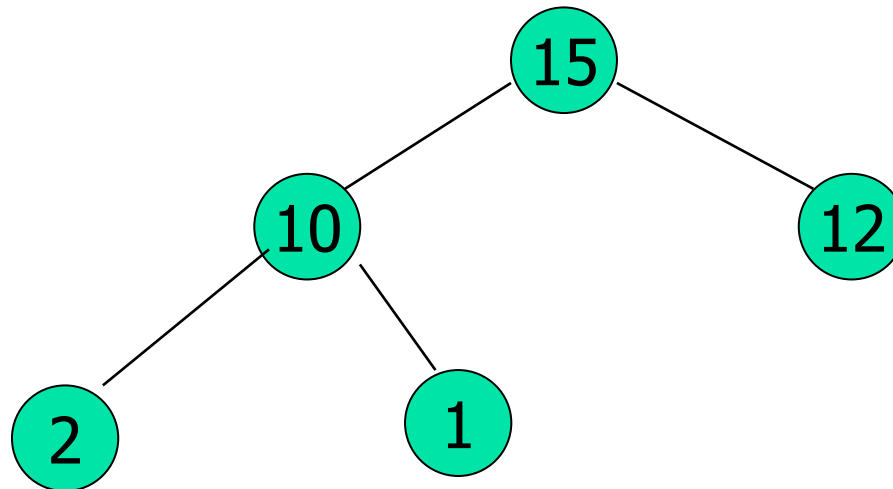
Heap Sort Ex (10)

- Remove Max & move the last element "2" to the root



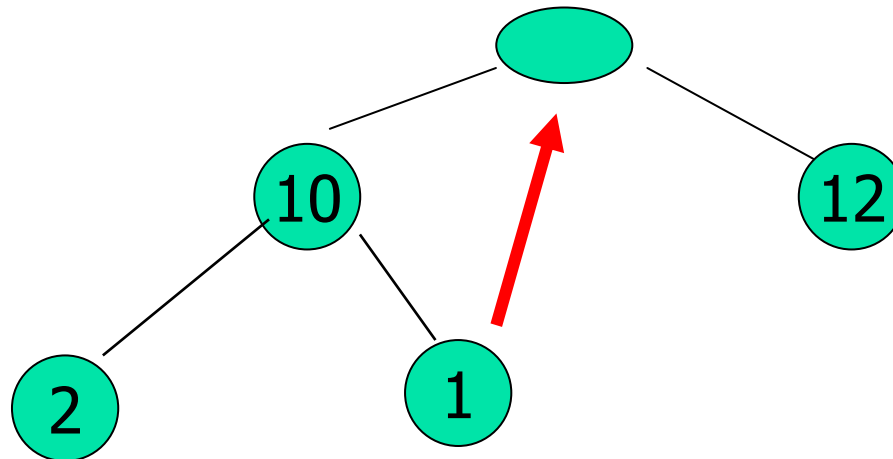
Heap Sort Ex (11)

- Reheapify: Meld root.leftChild and root.rightChild



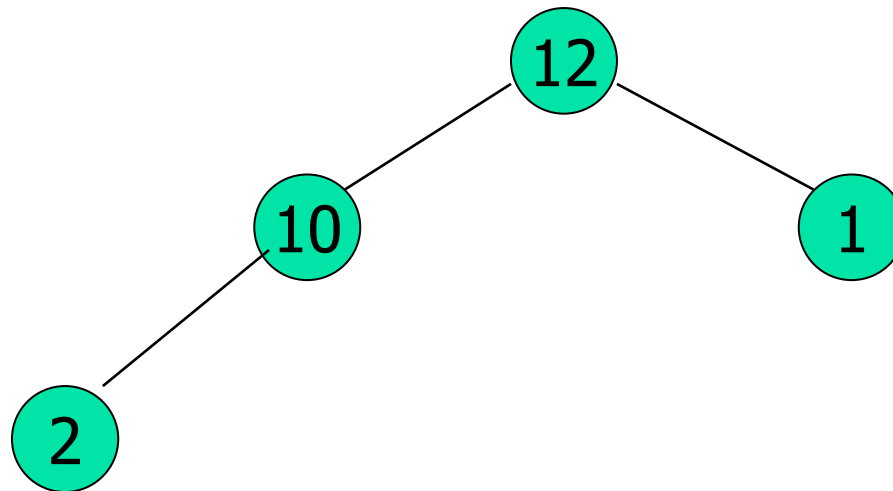
Heap Sort Ex (12)

- Remove Max & move the last element "1" to the root



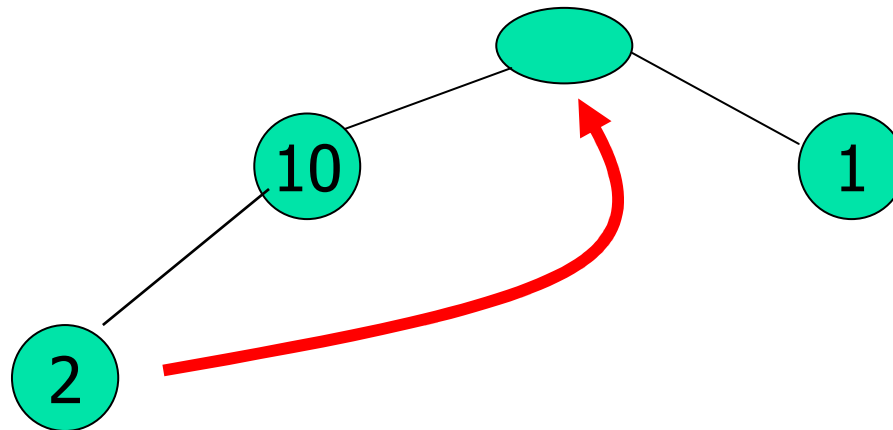
Heap Sort Ex (13)

- Reheapify: Meld root.leftChild and root.rightChild



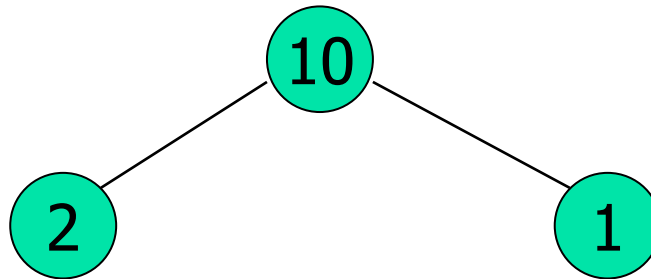
Heap Sort Ex (14)

- Remove Max & move the last element "2" to the root



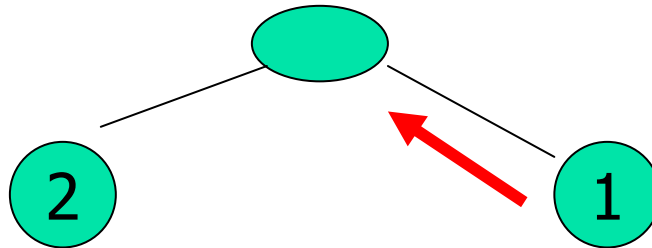
Heap Sort Ex (15)

- Reheapify: Meld root.leftChild and root.rightChild



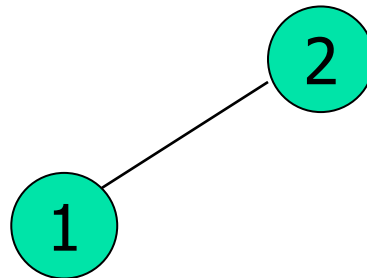
Heap Sort Ex (16)

- Remove Max & move the last element "1" to the root



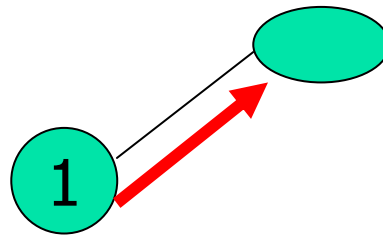
Heap Sort Ex (17)

- Reheapify: Meld root.leftChild and root.rightChild



Heap Sort Ex (18)

- Remove Max & move the last element "1" to the root





Heap Sort Ex (19)

- Reheapify: Meld root.leftChild and root.rightChild

1

80	35	30	20	17	15	12	10	2	
----	----	----	----	----	----	----	----	---	--



Heap Sort Ex (20)

- Remove Max & we are done!

80	35	30	20	17	15	12	10	2	1
----	----	----	----	----	----	----	----	---	---

- Complexity of Heap Sort : $O(n * \log n)$
 - Initialization : $O(n)$
 - Deletion : $O(\log n)$
 - Sort \rightarrow deletion n times $\rightarrow o(n * \log n)$



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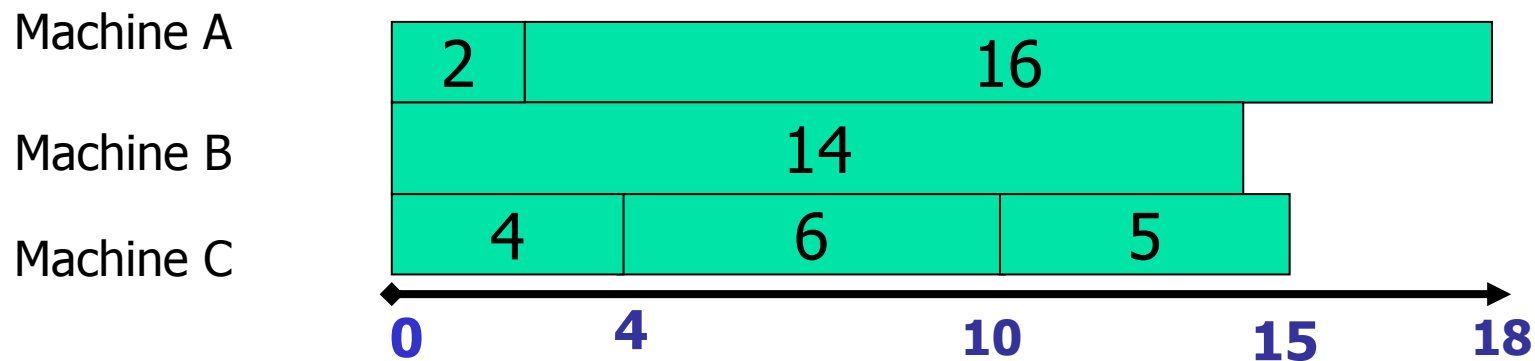


Machine Scheduling

- A **schedule** is an assignment of jobs to time intervals on machines
 - No machine processes more than one job at any time.
 - No job is processed by more than one machine at any time.
 - Each job i is assigned for a total of t_i units of processing.
- The **finish time** or **length** is
 - The time at which all jobs have completed
 - Start time : s_i
 - Completion time : $s_i + t_i$

Three-machine schedule

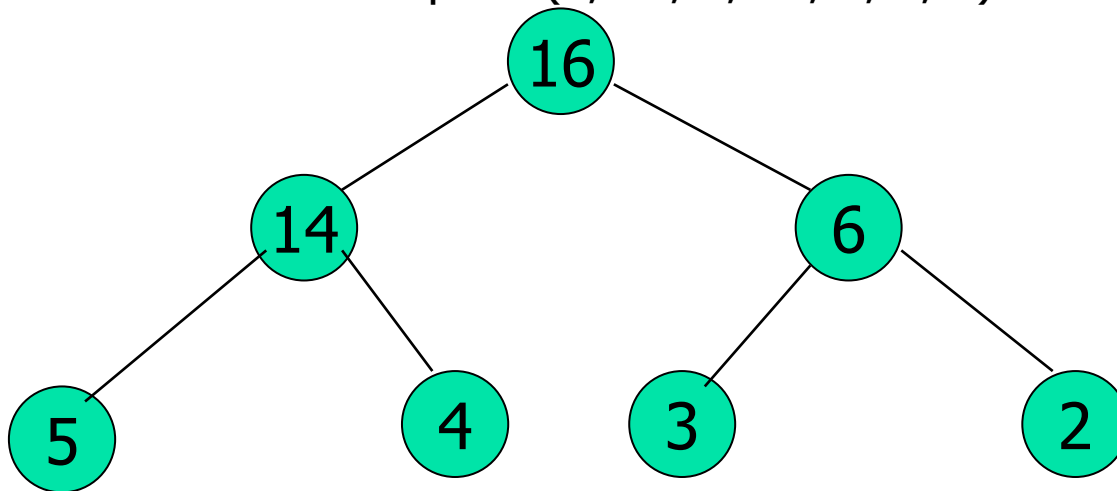
- Seven jobs with processing requirements (2, 14, 4, 16, 6, 5, 3)



- Finish time : 18
- Objective: Find schedules with **minimum finish time**

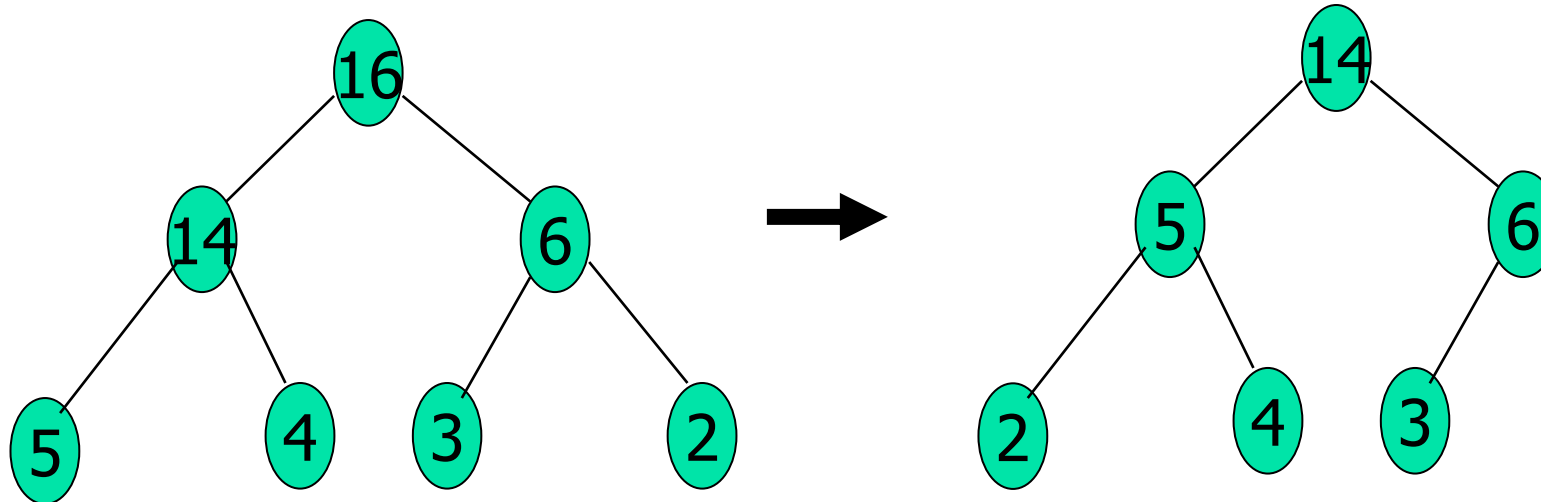
LPT Schedule (1)

- Longest Processing Time first.
 - Jobs are scheduled in the order: 16, 14, 6, 5, 4, 3, 2
 - Each job is scheduled on the machine on which it finishes earliest.
- Use MaxHeap for LPT Schedule
 - Construct a MaxHeap for (2, 14, 4, 16, 6, 5, 3)



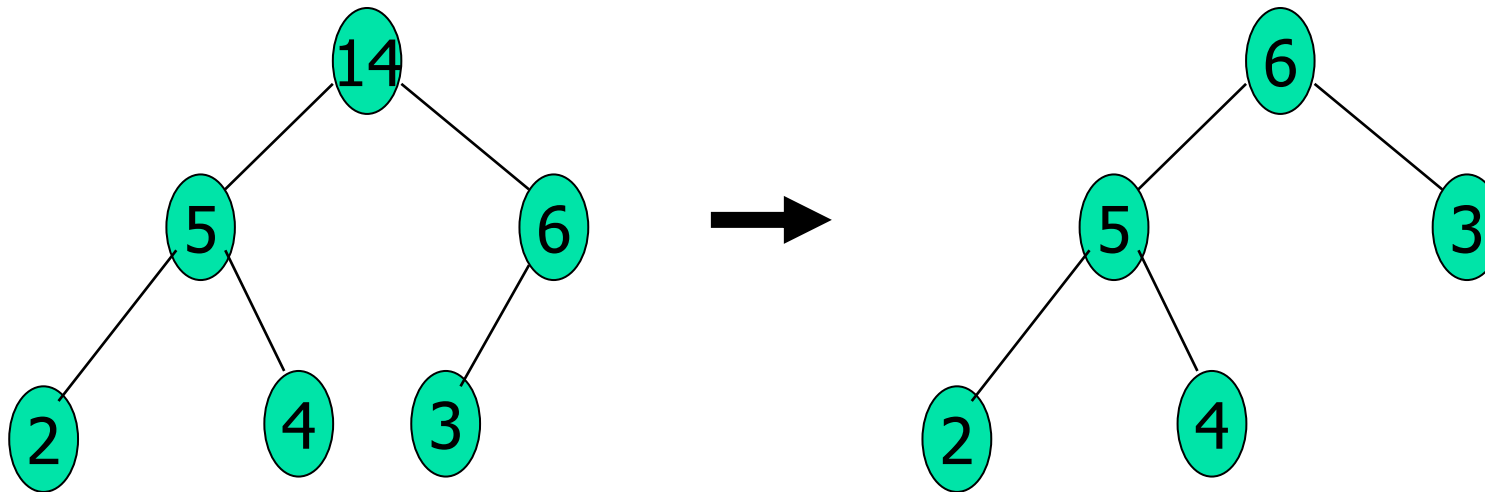
LPT Schedule (2)

- MaxHeap for LPT Schedule
 - First, place a job with priority 16 in Machine A which is free
 - ReHeapify



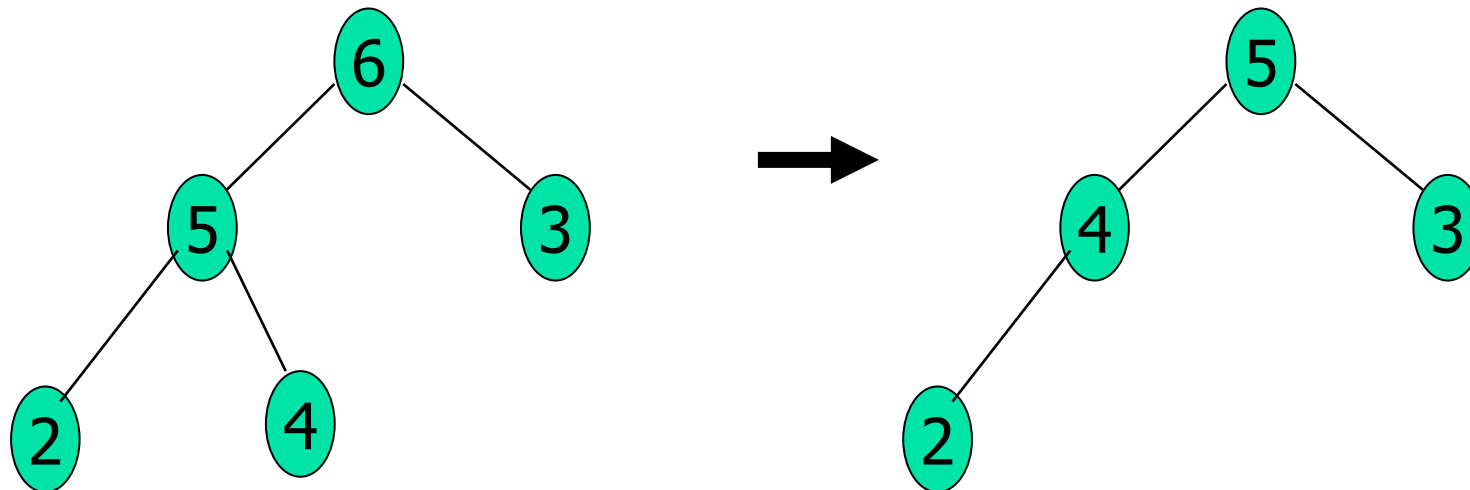
LPT Schedule (3)

- MaxHeap for LPT Schedule
 - Place a job with priority 14 in Machine B which is free
 - ReHeapify



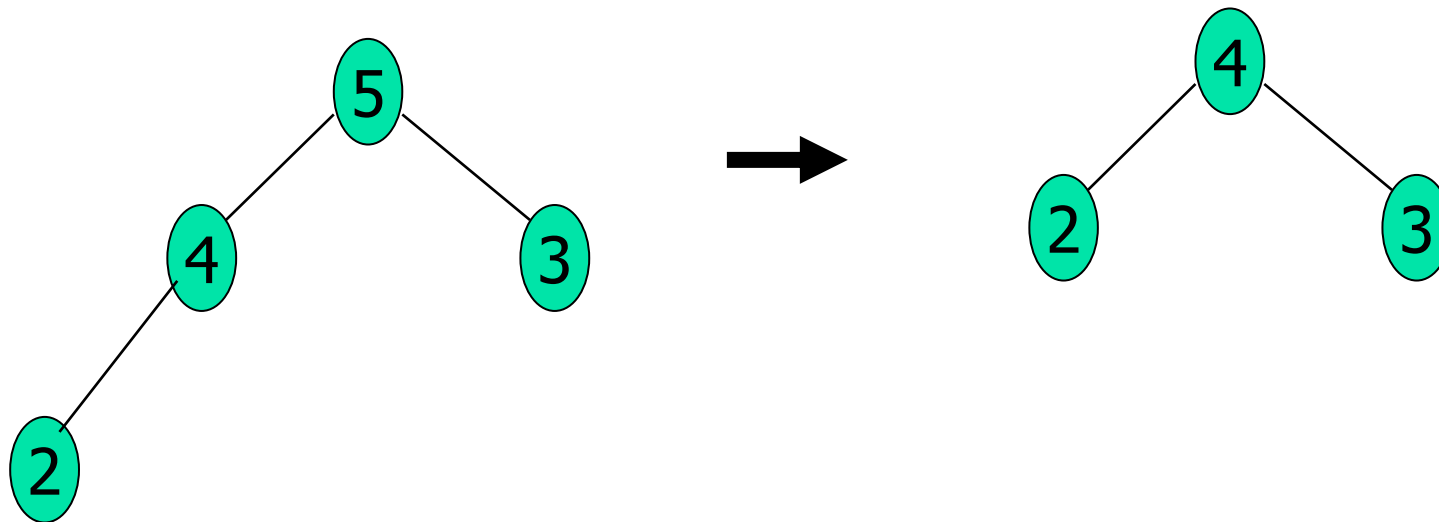
LPT Schedule (4)

- MaxHeap for LPT Schedule
 - Place a job with priority 6 in Machine C which will finish this job in the earliest time
 - ReHeapify



LPT Schedule (5)

- MaxHeap for LPT Schedule
 - Place a job with priority 5 in Machine C which will finish this job in the earliest time
 - ReHeapify

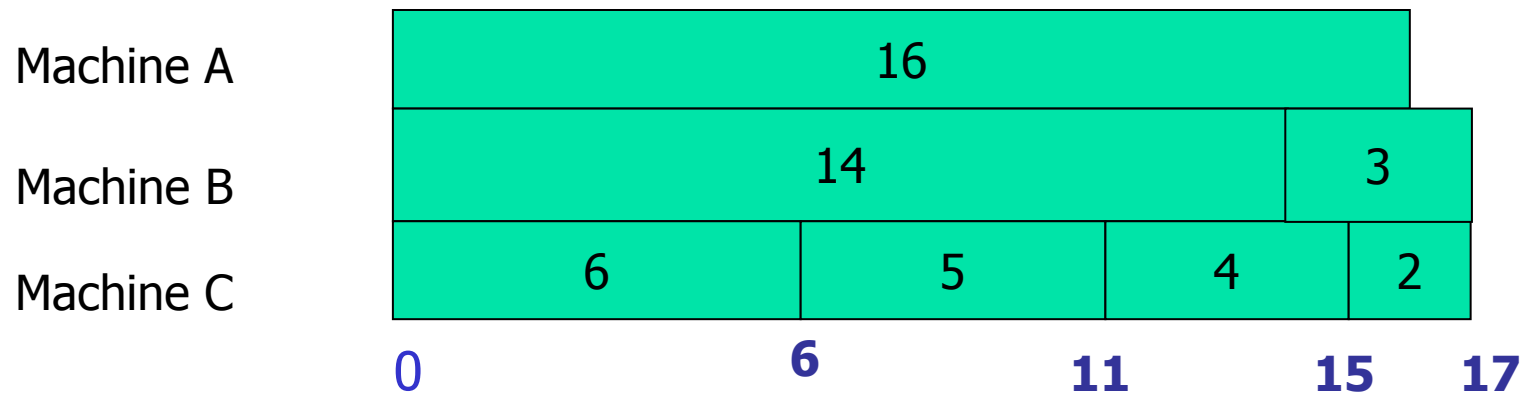


** Keep Going until No element is left in the Heap



LPT Schedule (6)

- The generated schedule by LPT algorithm



- Finish time : 17



Analysis on LPT

- **Minimum finish time scheduling** is NP-hard
 - Finding optimal solutions are generally NP
- LPT is **an Approximation Algorithm**
 - much closer to minimum finish time
- **Proved By Graham**
 - $(\text{LPT Finish Time}) / (\text{Minimum Finish Time}) \leq 4/3 - 1/(3m)$ where m is number of machines.
- **Sort jobs into decreasing order of task time**
 - $O(n \cdot \log n)$ time (n is number of jobs)
- **Schedule jobs in this order**
 - assign job to machine that becomes available first
 - must find minimum of m (m is number of machines) finish times

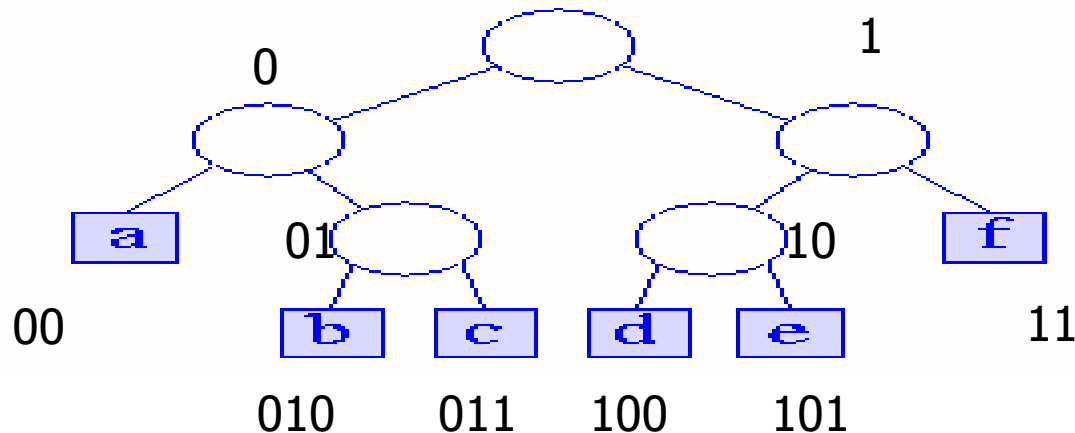


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Huffman code

- **Text compression:** Suppose the codes for the paths to the nodes (a, b, c, d, e, f) are (00, 010, 011, 100, 101, 11)
 - Use **extended binary trees** to derive a special class of variable-length codes



- Let $F(x)$ be the frequency of the symbol $x \in \{a, b, c, d, e, f\}$
- Length of the original string (by the number of bytes): $4 \times \text{number of chars}$
- Length of encoded string (by the number of bits)
 - $2 \cdot F(a) + 3 \cdot F(b) + 3 \cdot F(c) + 3 \cdot F(d) + 3 \cdot F(e) + 2 \cdot F(f)$



Huffman code encoding

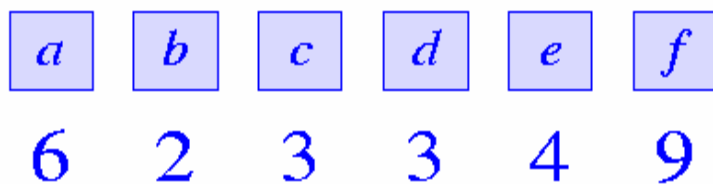
- To Encode a string using Huffman codes,
 - 1. Determine the different symbols in the string and their **frequencies**
 - 2. Construct a binary tree with **minimum WEP** (Weighted External Path length)
 - The external nodes of this tree are labeled by the symbols in the string
 - The weight of each external node is the frequency of the symbol that is its label
 - 3. Traverse **the root-to-external-node paths** and obtain the codes
 - 4. Replace the symbols in the string by their codes

- 각 심볼을 bit code로 변환할 때, 빈번히 출현하는 심볼일 수록 최대한 짧은 bit code를 가져야 한다.

Constructing a Huffman tree (1)

Extended Binary Tree: A binary tree with external nodes added

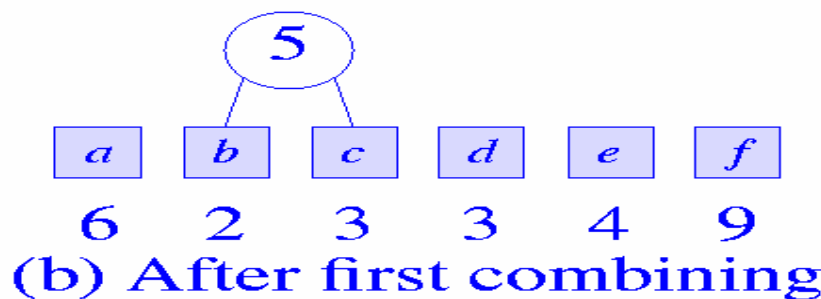
MinHeap: complete binary tree & the value in each node is less than or equal to those in its children



Each element has weight which is frequency

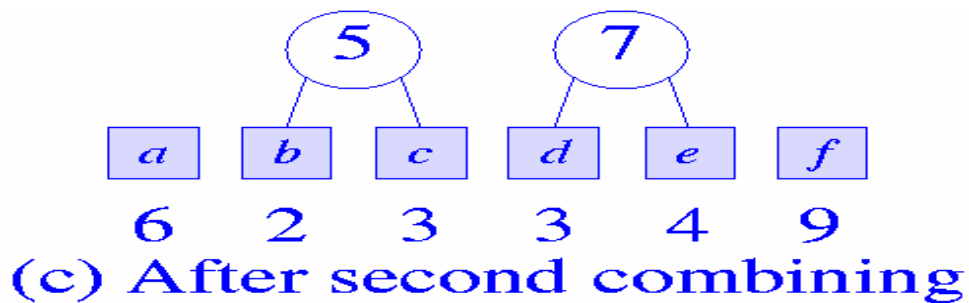
Build a MinHeap (6,2,3,3,4,9)

(a) Initial collection of trees

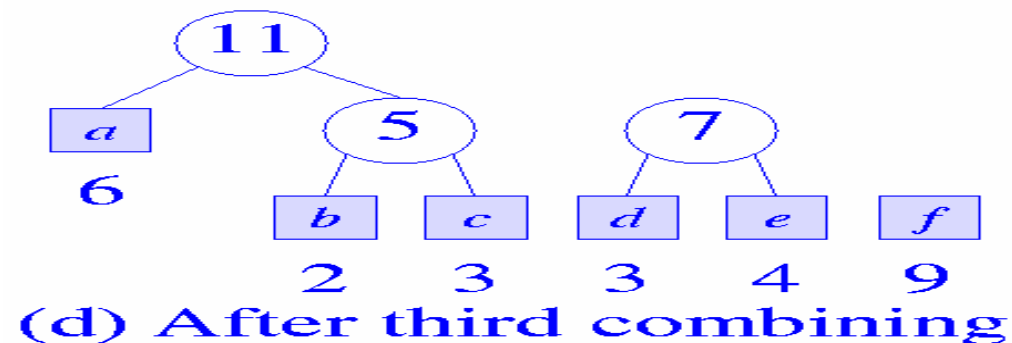


1. Remove two elements of lowest weight from a MinHeap (6,2,3,3,4,9)
2. Insert 5 & Reheapify (6,5,3,4,9)
3. Build a tree in the left

Constructing a Huffman tree (2)

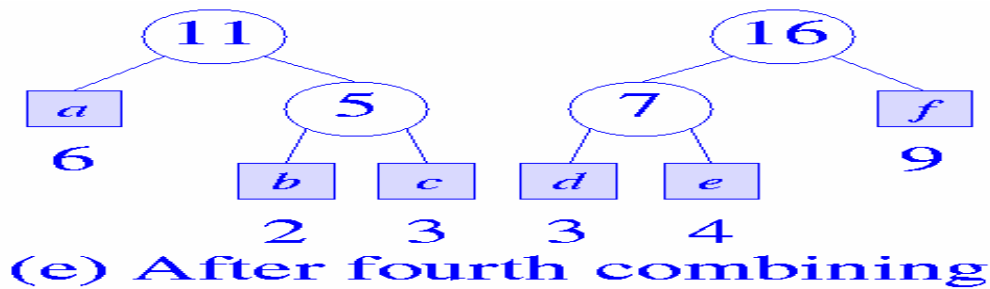


1. Remove two elements of lowest weight from a MinHeap (6,5,3,4,9)
2. Insert 7 & Reheapify (6,5,7,9)
3. Build a tree in the left

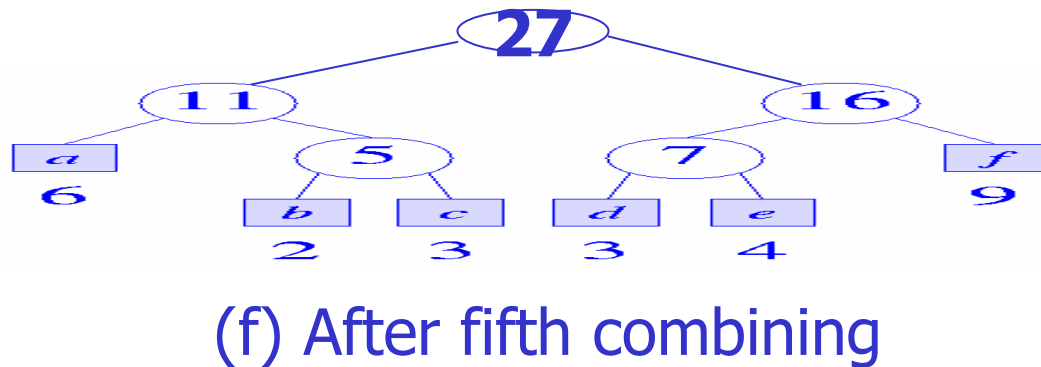


1. Remove two subelements of lowest weight from a MinHeap (6,5,7,9)
2. Insert 11 & Reheapify (11,7,9)
3. Build a tree in the left

Constructing a Huffman tree (3)



1. Remove two elements of lowest weight from a MinHeap (11,7,9)
2. Insert 16 & Reheap (11,16)
3. Build a tree in the left



1. Remove two elements of lowest weight from a MinHeap (11,16)
2. Insert 27 & Reheapify (27)
3. Build a tree in the left

Then, Assign huffman code from root to leaf nodes



huffmanTree ()

```
/** @return Huffman tree with weights w[0:a.length-1] */
public static LinkedBinaryTree huffmanTree(Operable [] w) { // create an array of single-node trees
    HuffmanNode[] hNode = new HuffmanNode[w.length+1];
    LinkedBinaryTree emptyTree = new LinkedBinaryTree();
    for (int i = 0; i < w.length; i++) {
        LinkedBinaryTree x = new LinkedBinaryTree();
        x.makeTree(new MyInteger(i), emptyTree, emptyTree);
        hNode[i + 1] = new HuffmanNode(x, w[i]); }
    MinHeap h = new MinHeap(); // make node array into a min heap
    h.initialize(hNode, w.length);
    // repeatedly combine pairs of trees from min heap until only one tree remains
    for (int i = 1; i < w.length; i++) { // remove two lightest trees from the min heap
        HuffmanNode x = (HuffmanNode) h.removeMin();
        HuffmanNode y = (HuffmanNode) h.removeMin();
        LinkedBinaryTree z = new LinkedBinaryTree(); //combine them into a single tree t
        z.makeTree(null, x.tree, y.tree);
        HuffmanNode t = new HuffmanNode(z, (Operable) x.weight.add(y.weight));
        h.put(t); // put new tree into the min heap }
    return ((HuffmanNode) h.removeMin()).tree; // final tree
}
```



Summary

- A **priority queue** is efficiently implemented with the heap data structure.
- Priority data structure
 - Heap
 - Leftist tree: HBLT, WBLT
- **Priority Queue Applications**
 - Heap sort: Use heap to develop an $O(n \log n)$ sort
 - Machine scheduling
 - Use the heap data structure to obtain an efficient implementation
 - The generation of Huffman codes

Sahni class:

dataStructures.MaxPriorityQueue (p.504)

```
public interface MaxPriorityQueue {  
    methods
```

```
    boolean isEmpty(): Returns true if empty, false otherwise
```

```
    public int size(): Returns the number of elements in the queue
```

```
    public Comparable getMax(): Returns element with maximum priority
```

```
    public void put(Comparable obj): Inserts obj into the queue
```

```
    public Comparable removeMax(): Removes and returns element with  
        maximum priority
```

```
}
```

Sahni class:

dataStructures.MinPriorityQueue (p.503)

```
public interface MinPriorityQueue {  
    methods
```

```
        boolean isEmpty(): Returns true if empty, false otherwise
```

```
        public int size(): Returns the number of elements in the queue
```

```
        public Comparable getMin(): Returns element with minimum priority
```

```
        public void put(Comparable obj): Inserts obj into the queue
```

```
        public Comparable removeMin(): Removes and returns element with  
        minimum priority
```

```
}
```