



Ch 17. Graphs

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Bird's-Eye View (0)

- Chapter 5-8: Linear List
- Chapter 9-11: Stack & Queue
- Chapter 12-16: Tree
- Chapter 17: Graph



Bird's eye review (1)

- Graphs
 - Used to model and solve many real-world problems
- In this chapter
 - Graph terminology
 - Different types of graphs
 - Common graph representations
 - Standard graph search methods
 - Algorithms to find a path in a graph
 - Specifying an abstract data type as an abstract class



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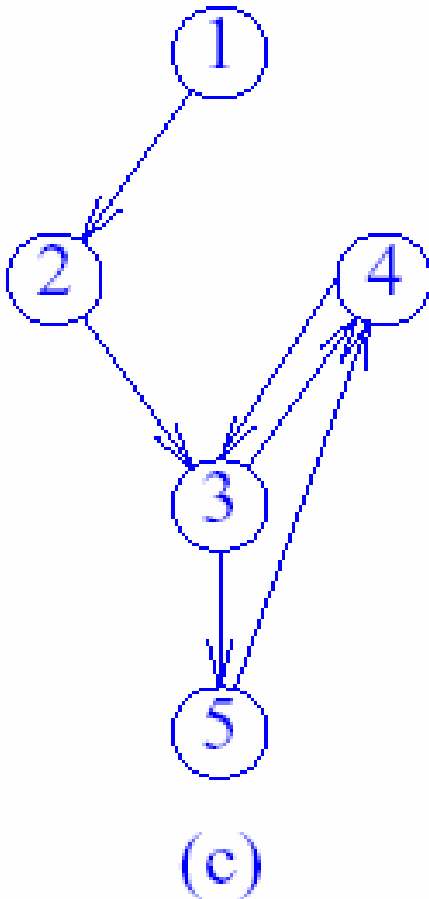
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- Representation of Unweighted Graphs
- Representation of Weighted Graphs
- Class Implementations
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 - Find a path in a Digraph
 - Connected Graph in a Graph
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 - Spanning Tree in a Graph



Graph Definition (1)

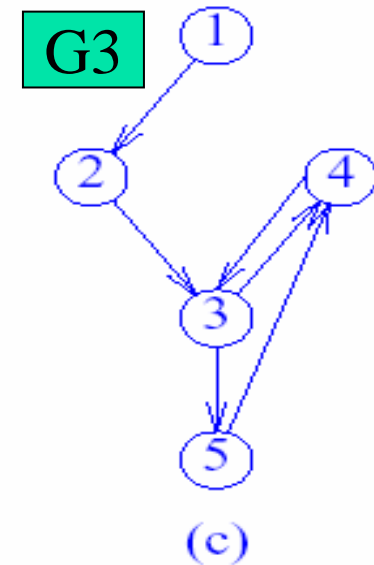
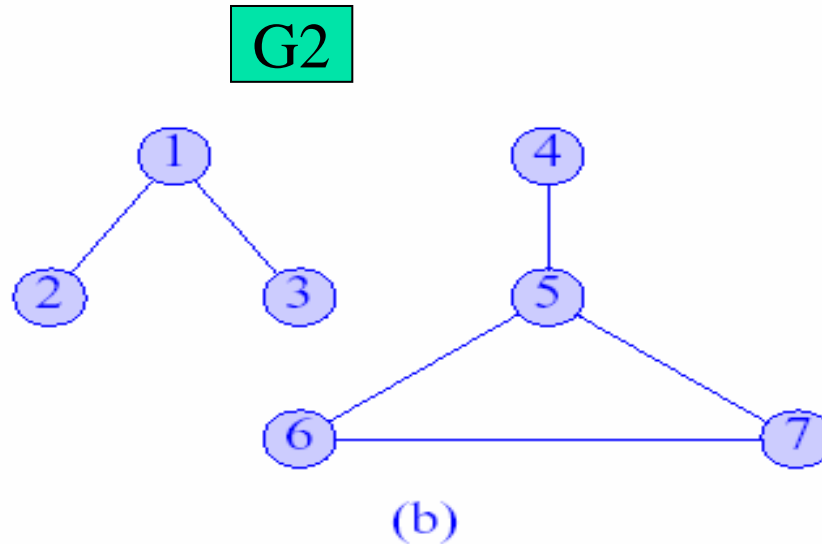
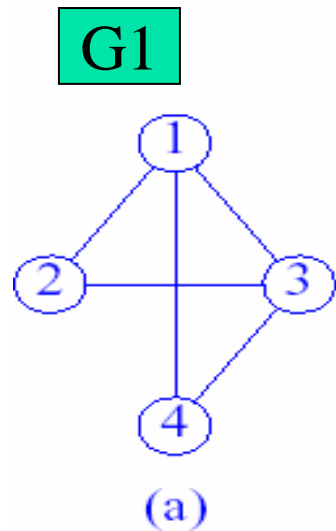
- Graph $G = (V, E)$
 - Finite set V (=vertices, nodes, points)
 - Finite set E (=edges, arcs, lines)
- **Directed edge**: orientation
- **Undirected edge**: no orientation
- Vertices i and j are **adjacent** vertices iff (i,j) is an edge in the graph
- Edge (i,j) is **incident** on the vertices i and j

Graph Definition (2)



- Vertex 2 is adjacent from vertex 1, while vertex 1 is **adjacent** to vertex 2
- Edge(1,2) is **incident** from vertex 1 and **incident** to vertex 2
- Vertex 4 is both **adjacent** to and from vertex 3
- Edge(3,4) is **incident** from vertex 3 and **incident** to vertex 4

Graph Definition (3)



- $G_1 = (V_1, E_1)$: $V_1 = \{1, 2, 3, 4\}$, $E_1 = \{(1,2), (1,3), (2,3), (1,4), (3,4)\}$
- $G_2 = (V_2, E_2)$:
 $V_2 = \{1, 2, 3, 4, 5, 6, 7\}$, $E_2 = \{(1,2), (1,3), (4,5), (5,6), (5,7), (6,7)\}$
- $G_3 = (V_3, E_3)$:
 $V_3 = \{1, 2, 3, 4, 5\}$, $E_3 = \{(1,2), (2,3), (3,4), (4,3), (3,5), (5,4)\}$



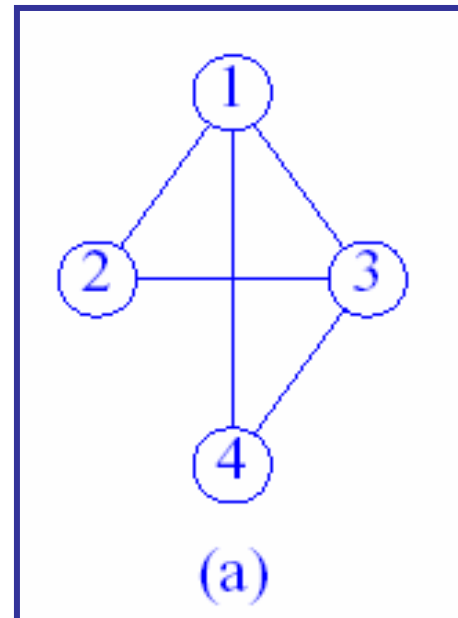
Graph Definition (4)

- Directed Graph
 - All the edge are directed (=digraph)
 - Self-edges (loop) are not allowed: (i, i) , (j, j)
 - Directed Acyclic Graph (DAG): No cycle in digraph
- Weights can be assigned to edges
 - weighted undirected graph
 - weighted directed graph (digraph)
- Graph == Network (synonym)

Graph Definition (5)

- Definition: Degree d_i of vertex i of an undirected graph is the number of edges incident on vertex i
- Example:

- $d_1 = 3$
- $d_2 = 2$
- $d_3 = 3$
- $d_4 = 2$

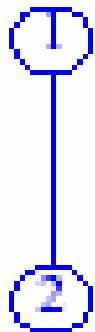


Edges in Undirected Graph

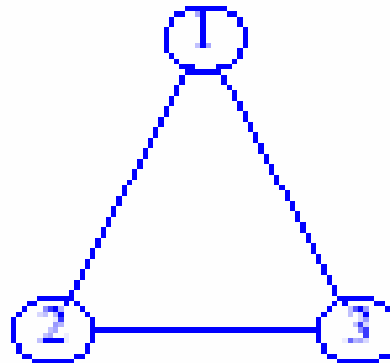
- Let $G=(V,E)$ be an undirected graph and
Let $n=|V|$ and $e=|E|$
 - $\sum_{i=1}^n d_i = 2e$
 - $0 \leq e \leq n(n-1)/2$
- A complete undirected graph has $n*(n-1) / 2$ edges



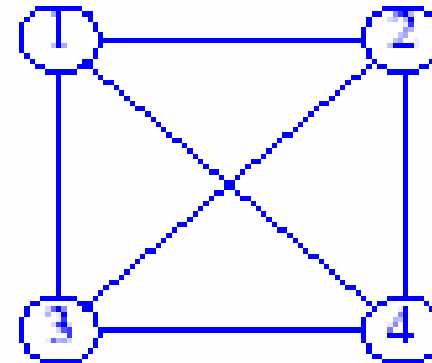
(a) K_1



(b) K_2



(c) K_3



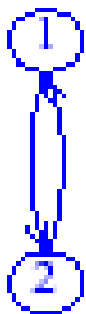
(d) K_4

Edges in Directed Graph

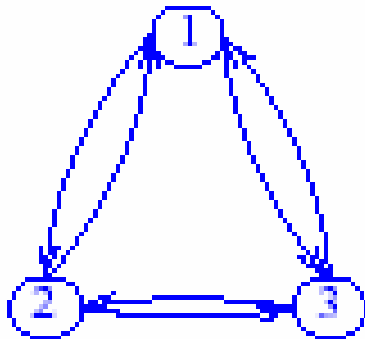
- Let $G=(V,E)$ be a directed graph
Let $n = |V|$ and $e = |E|$
 - $0 \leq e \leq n(n-1)$
 - $\sum_{i=1}^n d_i^{\text{in}} = \sum_{i=1}^n d_i^{\text{out}} = e$
- A complete directed graph has $n * (n-1)$ edges



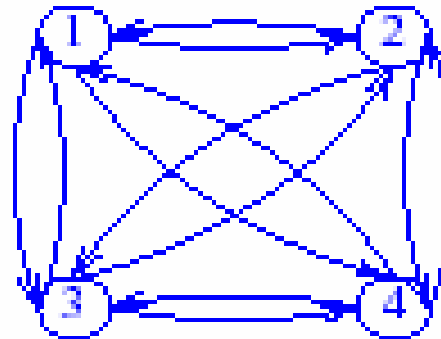
(a) K_1



(b) K_2



(c) K_3



(d) K_4



Graph Terms

- $G=(V,E)$
- A graph G is a **connected graph** IFF there is a **path** between every pair of vertices
- A graph H is a **subgraph** of another graph G IFF vertex and edge sets of H are subsets of those of graph G respectively
- **Simple path** is a path in which **all vertices**, except possibly the first and last, **are different**
 - A cycle is a **simple path** with same start and end vertex in a graph
- A spanning tree is a **tree and a subgraph** of G that contains all the vertices of G

Graph Application:

Path Problems

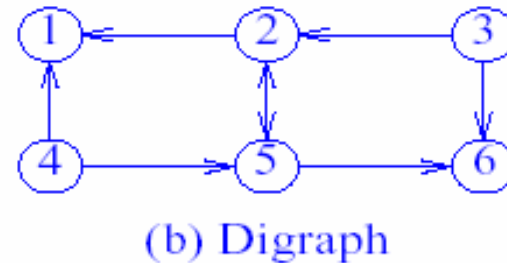
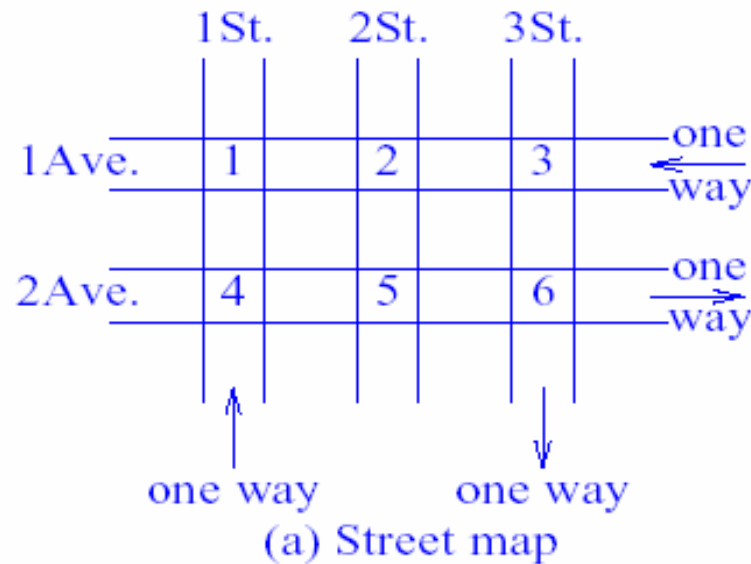
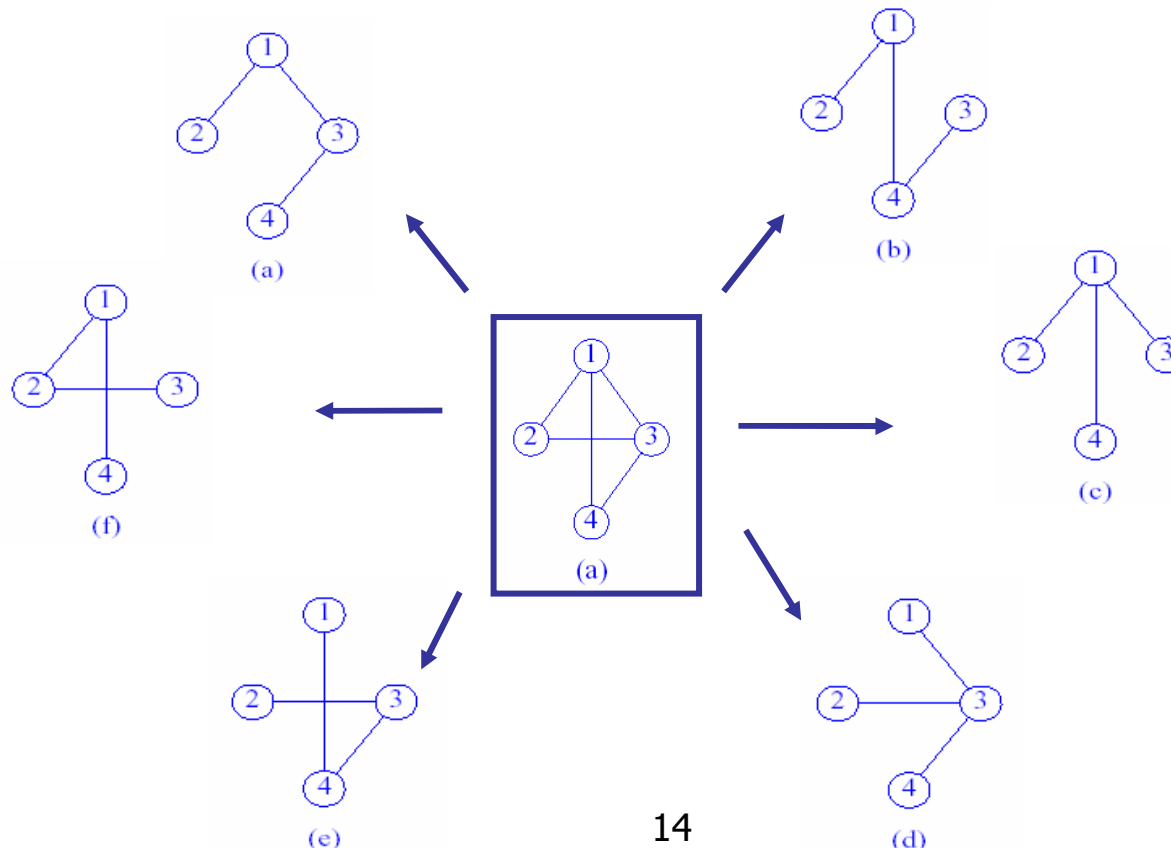


Figure 17.2 Street map and corresponding digraph

- **Simple path:** Path in which **all vertices**, except possibly the first and last, are different → 5,2,1 (yes) 2,5,2,1 (no)
- **Length:** Each edge in a graph may have an associated length

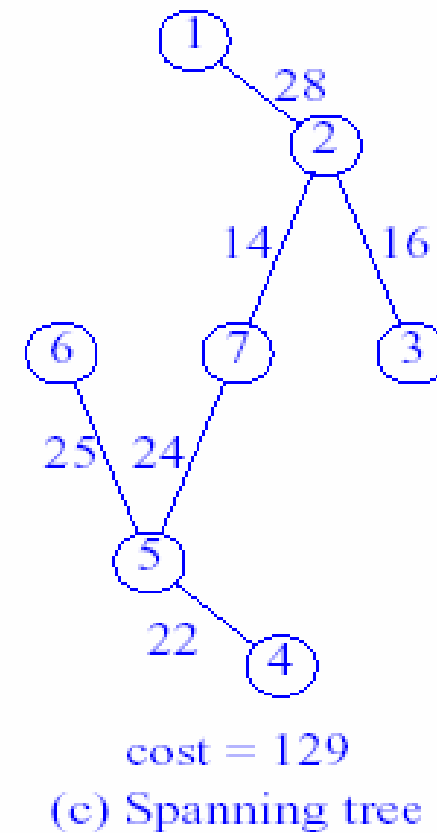
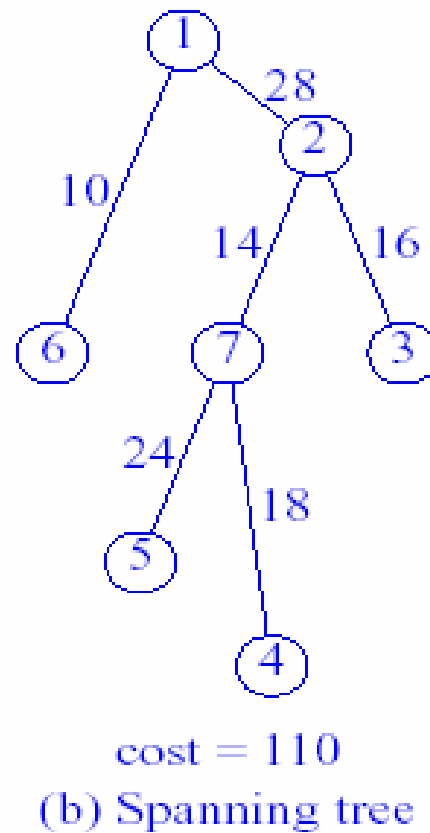
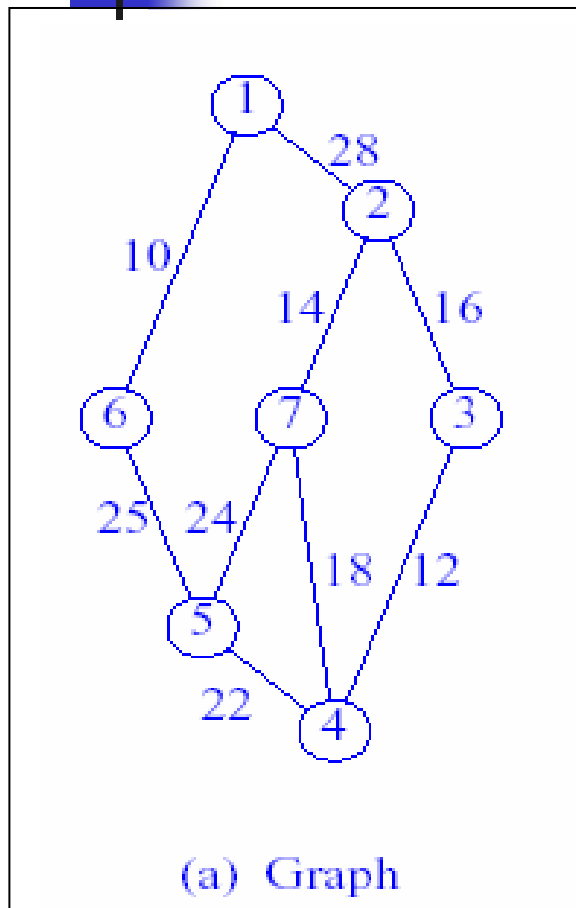
Graph Application: Spanning Trees

- A spanning tree is a tree and a subgraph of G that contains all the vertices of G



Graph Application:

Weighted Graph and its Spanning Trees



Graph Application:

Bipartite Graphs

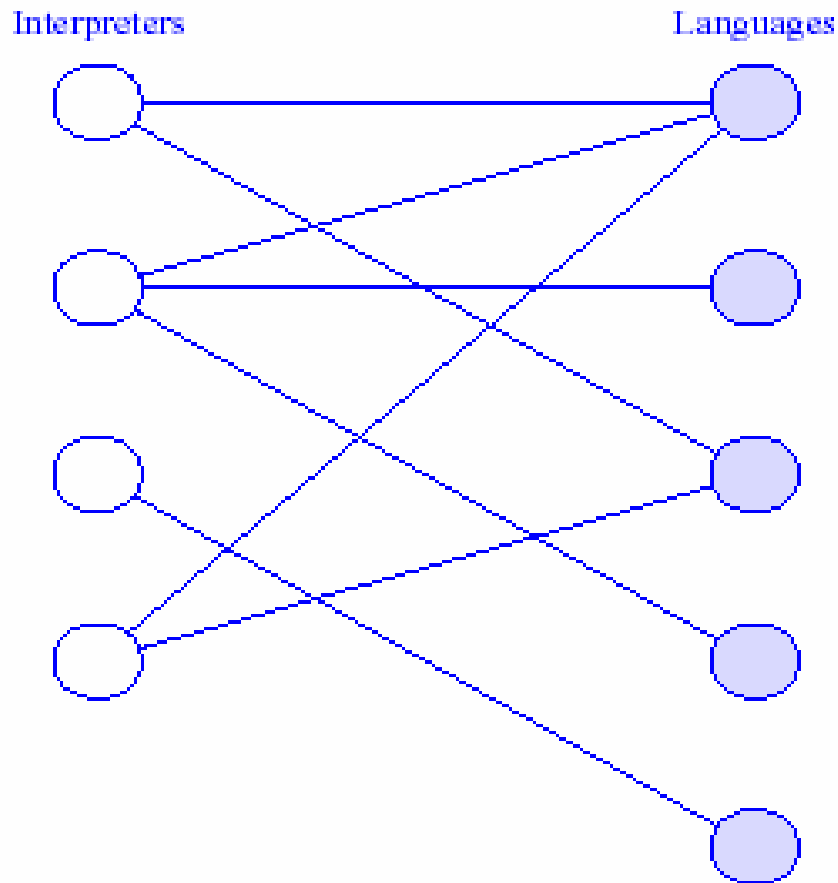


Figure 17.5 Interpreters and languages

Bipartite graphs

- Partition the vertex set into two subsets, A (the interpreter vertices) and B (the language vertices), so that every edge has one endpoint in A and the other in B .



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The ADT Graph

AbstractDataType Graph {

instances

a set V of vertices and a set E of edges

operations

vertices(), edges(), existsEdge(i, j),
putEdge(i, j), removeEdge(i, j), degree(i),
inDegree(i), outDegree(i)

}

- ADT graph refers to all varieties of graphs
whether directed, undirected, weighted, or unweighted



The abstract class Graph

```
public abstract class Graph {  
  
    //ADT method  
    public abstract int     vertices();  
    public abstract int     edges();  
    public abstract boolean existEdge(int i, int j);  
    public abstract void    putEdge(Object theEdge);  
    public abstract void    removeEdge(int i, int j);  
    public abstract int     degree(int i);  
    public abstract int     inDegree(int i);  
    public abstract int     outDegree(int i);  
  
    //create an iterator for vertex i  
    public abstract iterator iterator(int i);  
}
```

Class derivation hierarchy for Graph

* Left side: array-based vs Right-side: linked-based

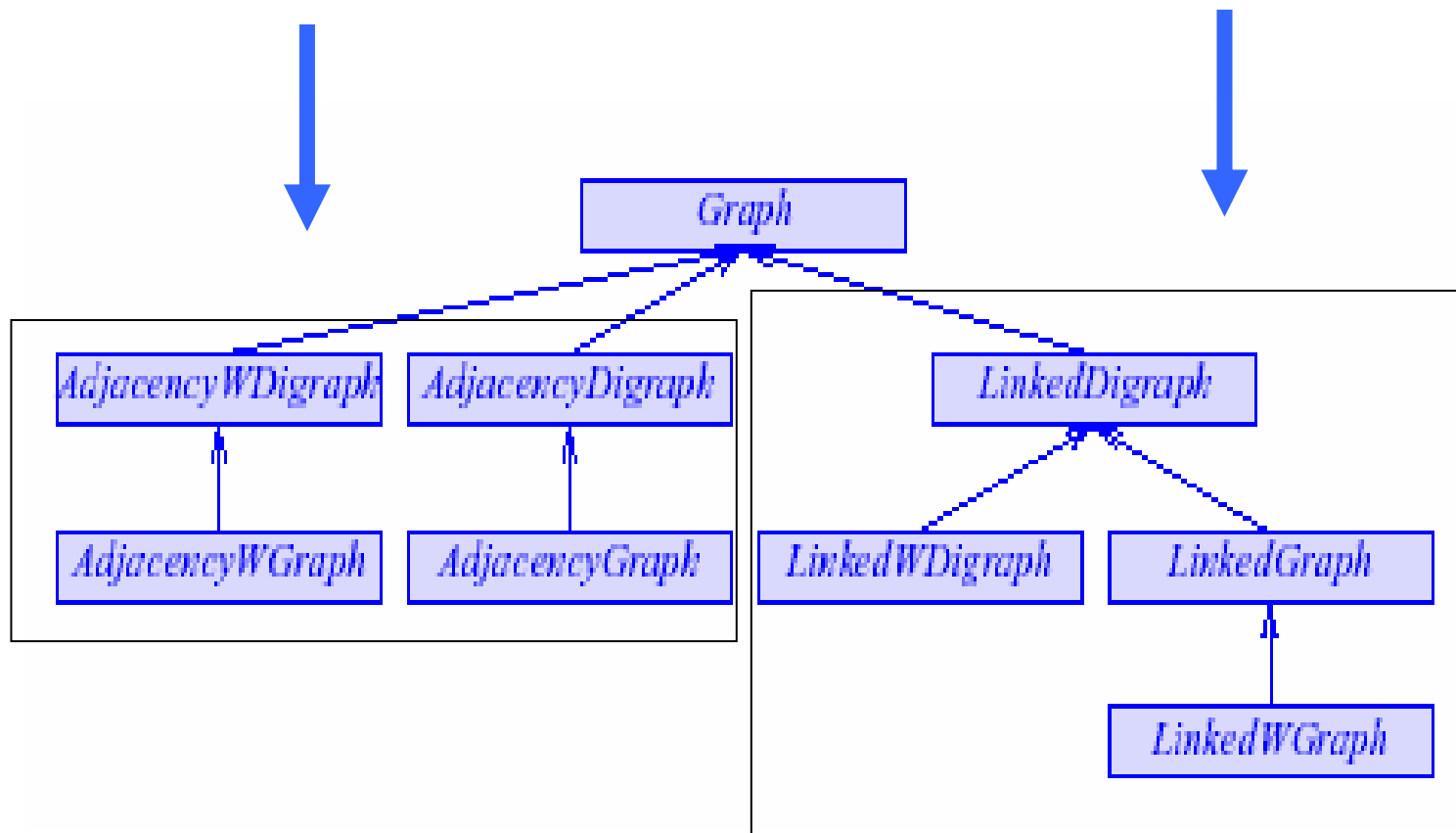




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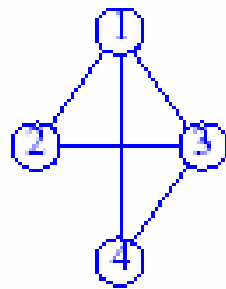
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Adjacency Matrix for Unweighted Graph (1)

- The **adjacency matrix** of an n -vertex graph $G=(V,E)$ is an $n \times n$ matrix A
 - Each element of A is either 0 or 1
 - $V=\{1, 2, \dots, n\}$
- G is an undirected Graph
 - $A(i, j) = \begin{cases} 1 & \text{If } (i, j) \in E \text{ or } (j, i) \in E \\ 0 & \text{otherwise} \end{cases}$
- G is a directed graph
 - $A(i, j) = \begin{cases} 1 & \text{If } (i, j) \in E \\ 0 & \text{otherwise} \end{cases}$

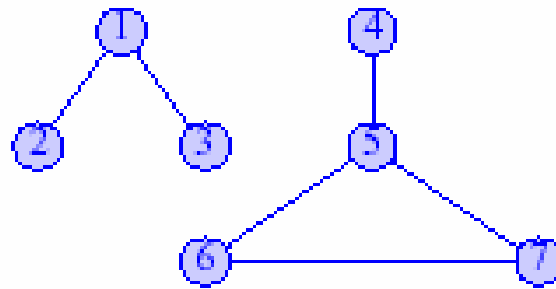
Adjacency Matrix for Unweighted Graph (2)



(a)

$$\begin{array}{c}
 1 \\
 2 \\
 3 \\
 4
 \end{array}
 \begin{array}{c}
 1 \\
 2 \\
 3 \\
 4
 \end{array}
 \begin{bmatrix}
 0 & 1 & 1 & 1 \\
 1 & 0 & 1 & 0 \\
 1 & 1 & 0 & 1 \\
 1 & 0 & 1 & 0
 \end{bmatrix}$$

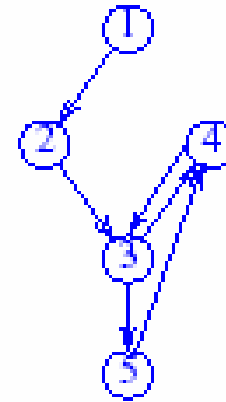
(a)



(b)

$$\begin{array}{c}
 1 \\
 2 \\
 3 \\
 4 \\
 5 \\
 6 \\
 7
 \end{array}
 \begin{array}{c}
 1 \\
 2 \\
 3 \\
 4 \\
 5 \\
 6 \\
 7
 \end{array}
 \begin{bmatrix}
 0 & 1 & 1 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 1 & 0 & 1 & 1 \\
 0 & 0 & 0 & 0 & 1 & 0 & 1 \\
 0 & 0 & 0 & 0 & 1 & 1 & 0
 \end{bmatrix}$$

(b)



(c)

$$\begin{array}{c}
 1 \\
 2 \\
 3 \\
 4 \\
 5
 \end{array}
 \begin{array}{c}
 1 \\
 2 \\
 3 \\
 4 \\
 5
 \end{array}
 \begin{bmatrix}
 0 & 1 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 1 & 1 \\
 0 & 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 1 & 0
 \end{bmatrix}$$

(c)

Data

Adjacency Matrix for Unweighted Graph (3)

- An $n \times n$ adjacency matrix can be mapped into array
 - $(n+1) \times (n+1)$ array: $(n+1)^2 = n^2 + 2n + 1$ bits
 - $n \times n$ array: n^2 bits
 - The diagonal may be eliminated
 - $(n - 1) \times n$ matrix: $(n^2 - n)/2$ bits
 - But, potential mismatch in coding
- Array-based AM is simple
 - But you have to check every item in a row if you want to do something with adjacent nodes
 - $O(n)$ to determine the set of vertices adjacent to or from any given vertex
- Later we use the irregular array instead!

Adjacency Matrix for Unweighted Graph (4)

	1	2	3	4
1	0	1	1	1
2	1	0	1	0
3	1	1	0	1
4	1	0	1	0

(a)

	1	2	3	4	5	6	7
1	0	1	1	0	0	0	0
2	1	0	0	0	0	0	0
3	1	0	0	0	0	0	0
4	0	0	0	0	1	0	0
5	0	0	0	1	0	1	1
6	0	0	0	0	1	0	1
7	0	0	0	0	1	1	0

(b)

	1	2	3	4	5
1	0	1	0	0	0
2	0	0	1	0	0
3	0	0	0	1	1
4	0	0	1	0	0
5	0	0	0	1	0

(c)

	1	2	3	4
1	1	1	1	1
2	1	1	1	0
3	1	0	1	1

(a)

	1	2	3	4	5	6	7
1	1	1	1	0	0	0	0
2	1	0	0	0	0	0	0
3	0	0	0	0	0	0	0
4	0	0	0	1	1	0	0
5	0	0	0	0	1	1	1
6	0	0	0	0	1	1	1

(b)

	1	2	3	4	5
1	0	1	0	0	0
2	0	0	1	0	0
3	0	0	0	1	1
4	0	0	0	1	0

(c)

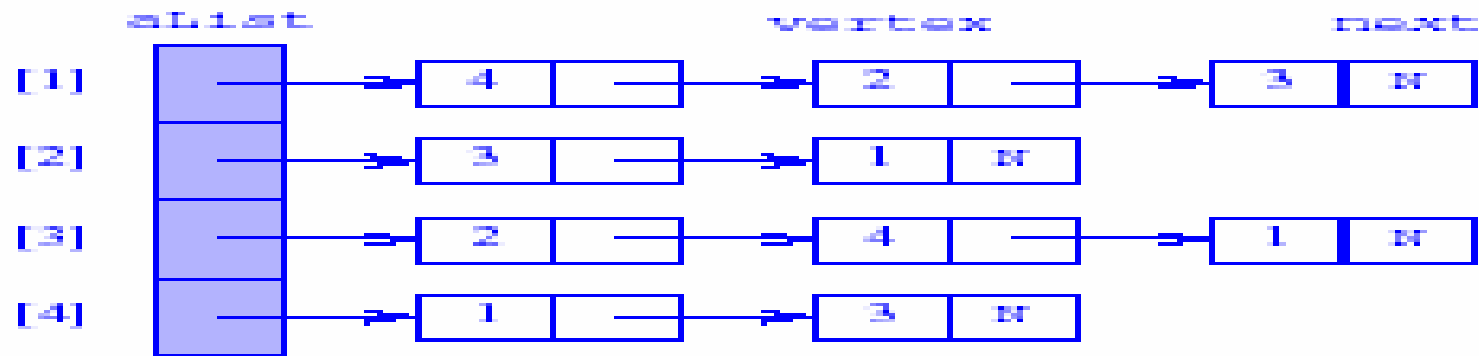
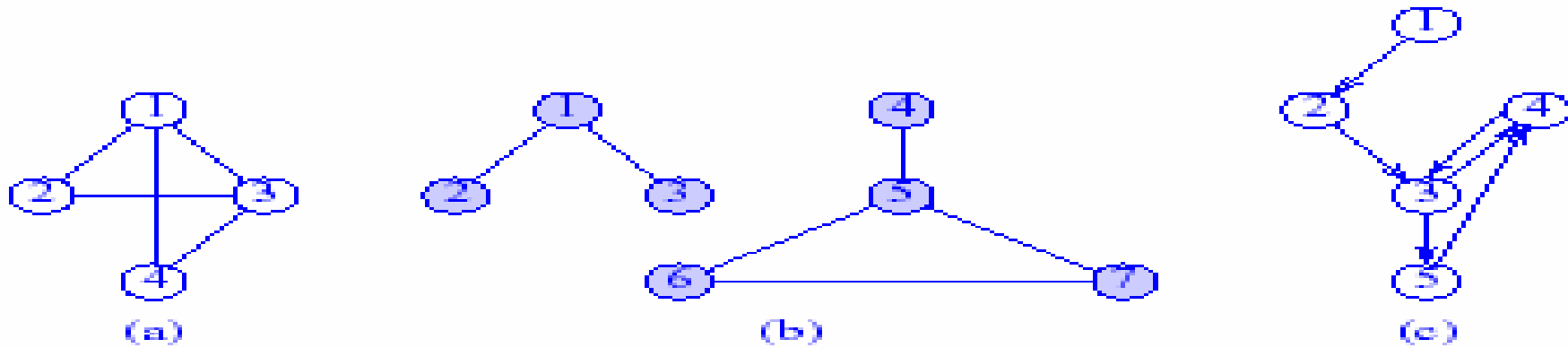
Figure 17.10 Adjacency matrices of Figure 17.9 with diagonals eliminated



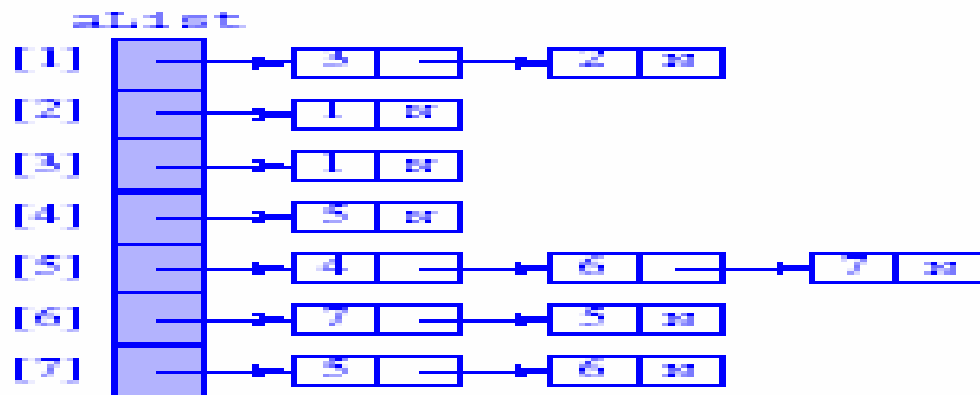
Linked Adjacency Lists for Unweighted Graph (1)

- An adjacency list for vertex i is a linear list that includes all vertices adjacent from the vertex i
 - $aList[i].firstNode$ pointer is pointing to the first node
 - If x points to a node in the chain $aList[i]$, $(i, x.element.vertex)$ is an edge of the graph
- Space requirement for n vertex graph
 - $4*(n+1)$: for the array $aList$
 - + $4*n$: for the n $firstNode$ pointers
 - + $4*3*m$: for m chain nodes (next, element, vertex of element)
 - ➔ $4(2n+3m+1)$
- Undirected graph : $m = 2e$ & Digraph graph : $m = e$ where e is the number of edges

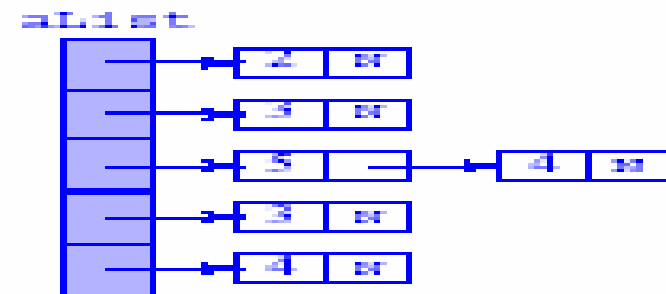
Linked Adjacency Lists for Unweighted Graph (2)



(a)



(b)



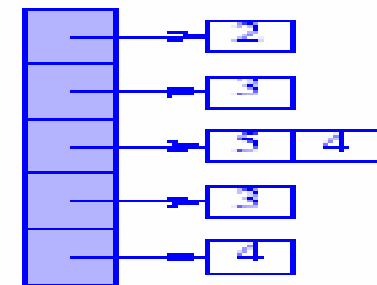
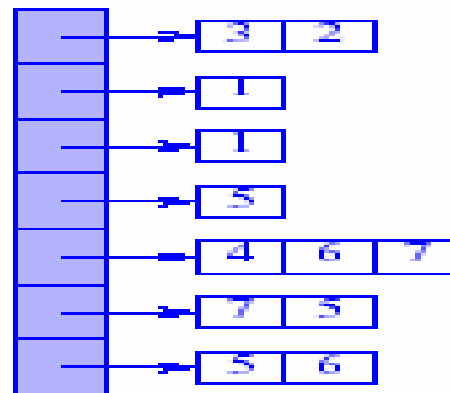
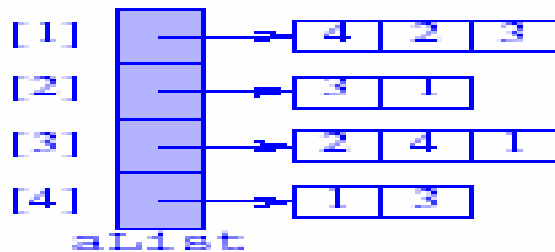
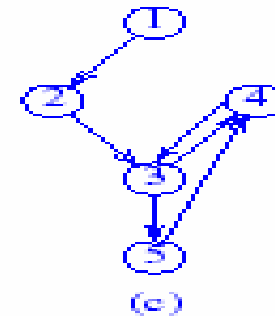
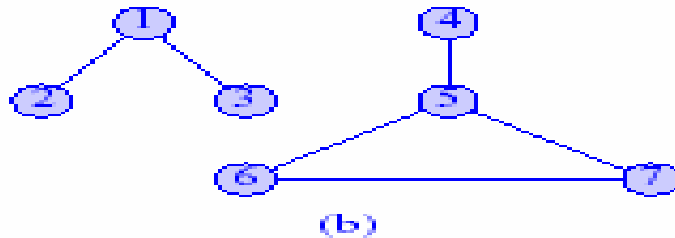
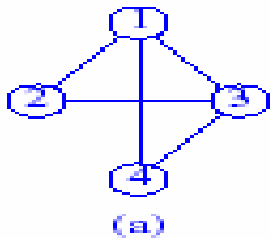
(c)

N denotes a null link

2D Irregular Array

for Adjacency Lists of Unweighted Graph

- 2D irregular array-based linear list representation rather than a chain
- Space requirement
 - $4*m$ bytes less than that of linked adjacency lists because we do not have m "next" pointers



(a)

(b)

(c)



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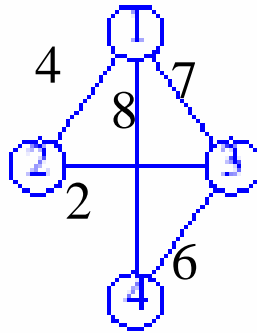
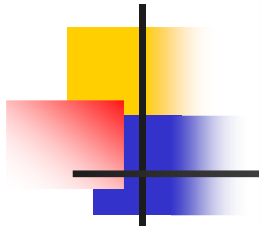
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Representation of Weighted Graphs

- **Cost-adjacency-matrix**
 - Use a matrix C
 - $A(i, j)$ is 1 \rightarrow $C(i, j)$ is cost (weight)
 - $A(i, j)$ is 0 \rightarrow $C(i, j)$ is null
- **Linked Adjacency-list representation**
 - Chain (see the next page)
 - Elements have the two fields vertex and weight
- **Array Adjacency-list representation**
 - Easily derived from that of unweighted graph
 - But determining the adjacent nodes is $O(n)$

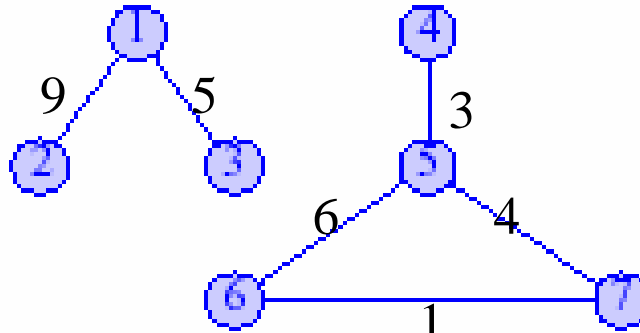
Cost-adjacency matrices for Weighted Graph



(a)

$$\begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} - & 4 & 7 & 8 \\ 4 & - & 2 & - \\ 7 & 2 & - & 6 \\ 8 & - & 6 & - \end{bmatrix} \end{matrix}$$

(a)

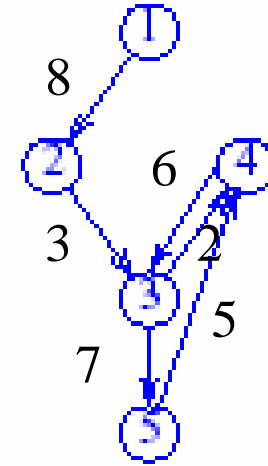


(b)

$$\begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \end{matrix} & \begin{bmatrix} - & 9 & 5 & - & - & - & - \\ 9 & - & - & - & - & - & - \\ 5 & - & - & - & - & - & - \\ - & - & - & - & 3 & - & - \\ - & - & - & 3 & - & 6 & 4 \\ - & - & - & - & 6 & - & 1 \\ - & - & - & - & 4 & 1 & - \end{bmatrix} \end{matrix}$$

(b)

- denotes a null value

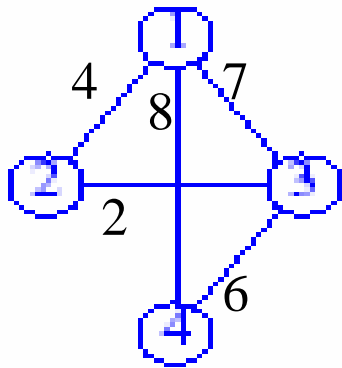


(c)

$$\begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} - & 8 & - & - & - \\ - & - & 3 & - & - \\ - & - & - & 2 & 7 \\ - & - & 6 & - & - \\ - & - & - & 5 & - \end{bmatrix} \end{matrix}$$

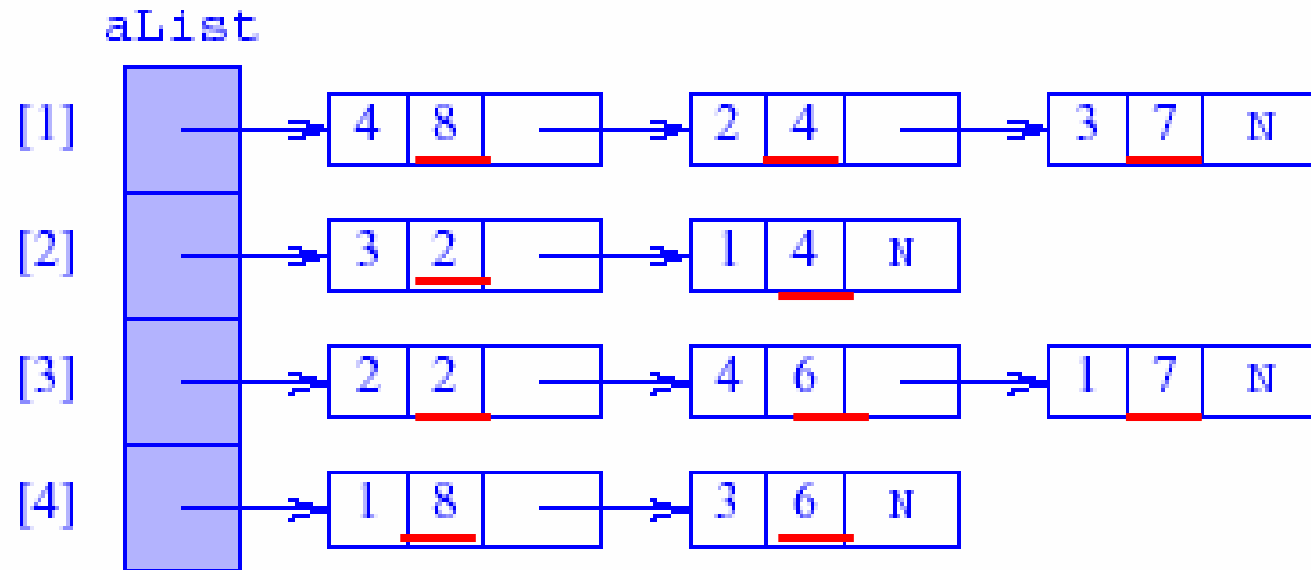
(c)

Linked adjacency list for weighted graph



	1	2	3	4
1	-	4	7	8
2	4	-	2	-
3	7	2	-	6
4	8	-	6	-

(a)



N denotes a null link



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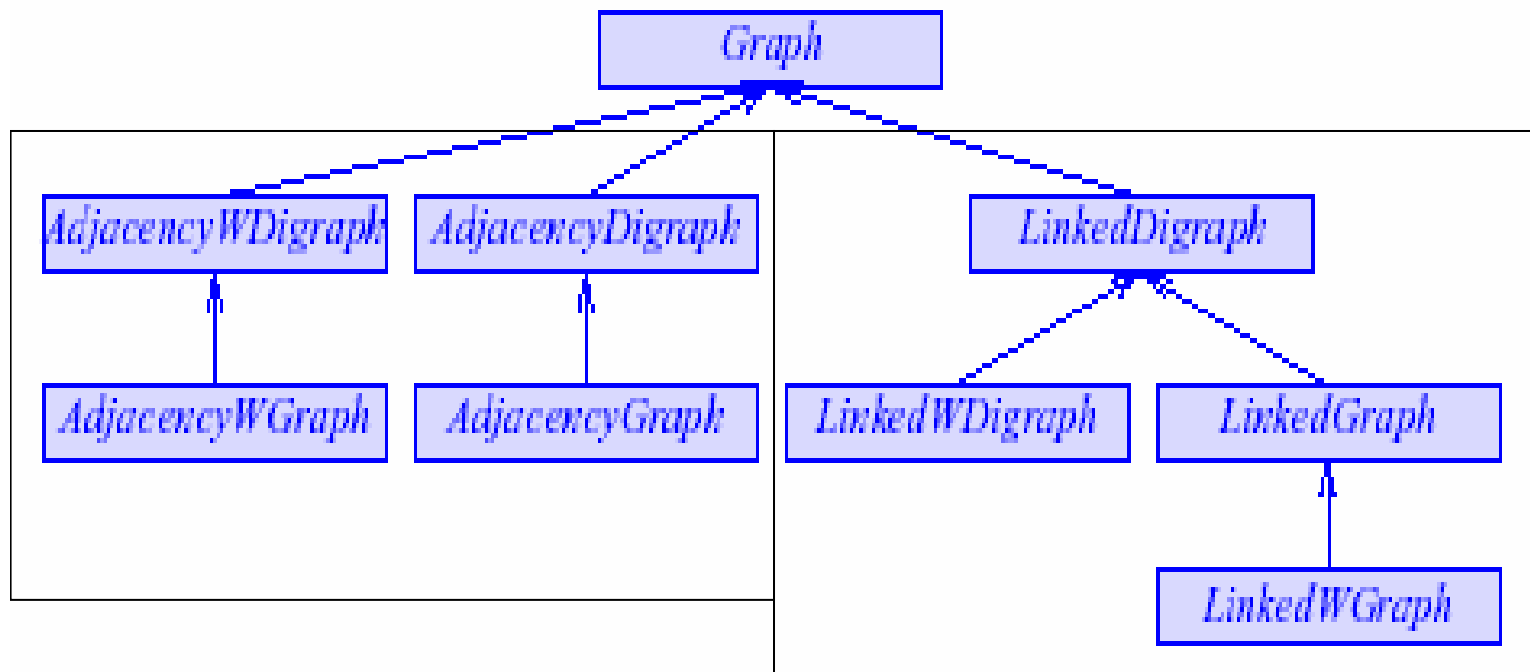


The Different Classes for Graph

- Four graph types
 - unweighted undirected graph
 - weighted undirected graph
 - unweighted directed graph
 - weighted directed graph
- Three representations
 - matrix
 - Array
 - linked list
- Several pairs of 4 graph types have “IsA” relationship

Class derivation hierarchy for Graph

* Left side: array-based vs Right-side: linked-based





Array-based Adjacency-Matrix Classes for Graph

- Weighted-edge classes: 2D array of type **Object**
 - The class `AdjacencyWDigraph` & `AdjacencyWGraph`
- Unweighted-edge classes: 2D array of type **boolean**
 - The class `AdjacencyDigraph` & `AdjacencyGraph`
- We describe only `AdjacencyWDigraph` and `AdjacencyWGraph` here



Remember: The abstract class Graph

```
public abstract class Graph
{
    //ADT method
    public abstract int vertices();
    public abstract int edges();
    public abstract boolean existEdge(int i, int j);
    public abstract void putEdge(Object theEdge);
    public abstract void removeEdge(int i, int j);
    public abstract int degree(int i);
    public abstract int inDegree(int i);
    public abstract int outDegree(int i);

    //create an iterator for vertex i
    public abstract iterator iterator(int i);
}
```



The Class AdjacencyWDigraph (1)

```
public class AdjacencyWDigraph extends Graph {
    // data members
    int n;           // number of vertices
    int e;           // number of edges
    Object [][] a;  // adjacency array

    // constructors
    public AdjacencyWDigraph(int theVertices) {
        // validate theVertices
        if (theVertices < 0)
            throw new IllegalArgumentException ("no of vertices must be >= 0");
        n = theVertices;
        a = new Object [n + 1] [n + 1];
        // default values are e = 0 and a[i][j] = null
    }
    // default is a 0 vertex graph
    public AdjacencyWDigraph() { this(0); }
}
```

The Class AdjacencyWDigraph (2)

```
/** add edge e into the digraph; if already there, update its weight e.weight
 * @throws IllegalArgumentException when theEdge is invalid */
public void putEdge(Object theEdge) {
    WeightedEdge edge = (WeightedEdge) theEdge;
    int v1 = edge.vertex1;
    int v2 = edge.vertex2;
    if (v1 < 1 || v2 < 1 || v1 > n || v2 > n || v1 == v2) throw new
        IllegalArgumentException("(" + v1 + "," + v2 + ") is not a permissible edge");
    if (a[v1][v2] == null) e++; // new edge
    a[v1][v2] = edge.weight;
}

/** remove the edge (i,j) */
public void removeEdge (int i, int j) {
    if (i >= 1 && j >= 1 && i <= n && j <= n && a[i][j] != null) {
        a[i][j] = null;
        e--; }
}
```



The Class AdjacencyWDigraph (3)

```
/** this method is undefined for directed graphs */
public int degree (int i) { throw new NoSuchElementException();}

/** @return out-degree of vertex i
 * @throws IllegalArgumentException when i is not a valid vertex */
public int outDegree(int i) {
    if (i < 1 || i > n)
        throw new IllegalArgumentException("no vertex " + i);
    // count out edges from vertex i
    int sum = 0;
    for (int j = 1; j <= n; j++)
        if (a[i][j] != null) sum++;
    return sum;
}
```


The Class AdjacencyWDigraph (4)

```
/** create and return an iterator for vertex i
 * @throws IllegalArgumentException when i is an invalid vertex */
public Iterator iterator(int i) {
    if (i < 1 || i > n) throw new IllegalArgumentException("no vertex " + i);
    return new VertexIterator(i);
}
```

```
private class VertexIterator implements Iterator {
    // data members
    private int v;           // the vertex being iterated
    private int nextVertex;
    // constructor
    public VertexIterator(int i) {
        v = i; // find first adjacent vertex
        for (int j = 1; j <= n; j++)
            if (a[v][j] != null) {
                nextVertex = j;
                return; }
        // no edge out of vertex i
        nextVertex = n + 1;
    }
}
```

The Class AdjacencyWDigraph (5)

```
// iterator methods
public boolean hasNext() { return nextVertex <= n; } //true if there is next vertex
/** @return next adjacent vertex and edge weight */
public Object next() {
    if (nextVertex <= n) {
        int u = nextVertex; // find next adjacent vertex
        for (int j = u + 1; j <= n; j++)
            if (a[v][j] != null) {
                nextVertex = j;
                return new WeightedEdgeNode(u, a[v][u]); }
        // no next adjacent vertex for v
        nextVertex = n + 1;
        return new WeightedEdgeNode(u, a[v][u]);
    } else throw new NoSuchElementException("no next vertex");
} // end of next()

public void remove() { throw new UnsupportedOperationException(); } //unsupported
} // end of the class VertexIterator

} // end of the class AdjacencyWDigraph
```

The Class AdjacencyWGraph

(for undirected graph)

```
public class AdjacencyWGraph extends AdjacencyWDigraph {
    public void removeEdge(int i, int j) { /** remove the edge (i,j) */
        if (i >= 1 && j >= 1 && i <= n && j <= n && a[i][j] != null) {
            a[i][j] = null;
            a[j][i] = null;
            e--; }
        }
    /** put edge e into the graph; if already there, update its weight to e.weight
     * @throws IllegalArgumentException when theEdge cannot be an edge*/
    public void putEdge(Object theEdge) {
        WeightedEdge edge = (WeightedEdge) theEdge;
        int v1 = edge.vertex1;
        int v2 = edge.vertex2;
        if (v1 < 1 || v2 < 1 || v1 > n || v2 > n || v1 == v2) throw new
            IllegalArgumentException("(" + v1 + ", " + v2 + ") is not a permissible edge");
        if (a[v1][v2] == null) e++; // new edge
        a[v1][v2] = edge.weight;
        a[v2][v1] = edge.weight;
    }
}
```

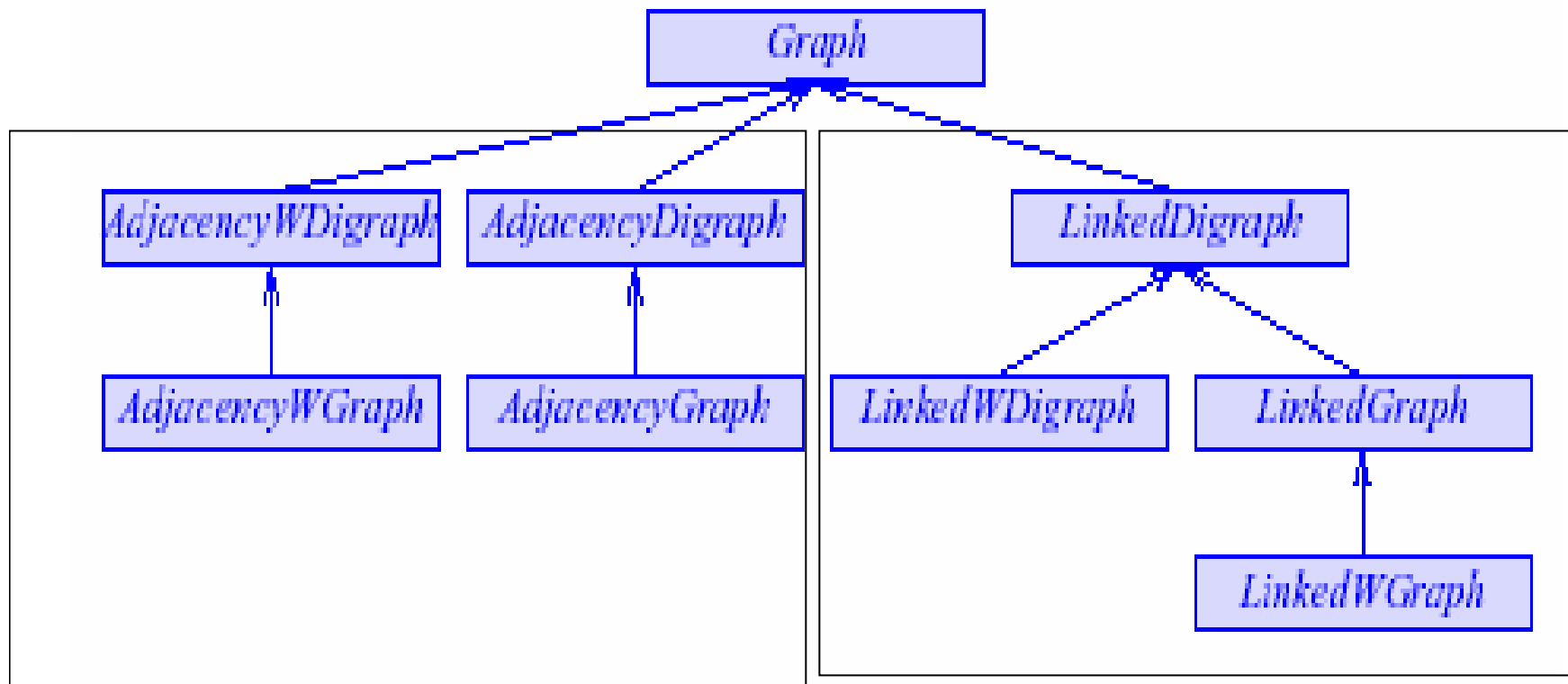


Linked-list classes for Graph

- Linked-list representation of a graph
 - each object is represented as an array element of chains
- In array-based graph → removeEdge()
- Here, removeElement(vertex)
 - first search the chain
 - If matching element is found → delete it from the chain
- Extension to the class **Chain** that includes the new methods is called the class **GraphChain**
- The class **LinkedDigraph** is a subclass of the class **Graph**

Class derivation hierarchy for Graph

* Left side: array-based vs Right-side: linked-based





Remember: The abstract class Graph

```
public abstract class Graph {  
    //ADT method  
    public abstract int vertices();  
    public abstract int edges();  
    public abstract boolean existEdge(int i, int j);  
    public abstract void putEdge(Object theEdge);  
    public abstract void removeEdge(int i, int j);  
    public abstract int degree(int i);  
    public abstract int inDegree(int i);  
    public abstract int outDegree(int i);  
  
    //create an iterator for vertex i  
    public abstract iterator iterator(int i);  
}
```



The class LinkedDigraph (1)

```
public class LinkedDigraph extends Graph {
    // data members
    int n;           // number of vertices
    int e;           // number of edges
    GraphChain [] aList; // adjacency lists

    // constructors
    public LinkedDigraph(int theVertices) {
        // validate theVertices
        if (theVertices < 0)
            throw new IllegalArgumentException ("number of vertices must be >= 0");
        n = theVertices;
        aList = new GraphChain [n + 1];
        for (int i = 1; i <= n; i++)    aList[i] = new GraphChain();
        // default value of e is 0
    }

    // default is a 0-vertex graph
    public LinkedDigraph() { this(0); }
}
```



The class LinkedDigraph (2)

```
// Graph methods
public int vertices() { return n; }    /** @return number of vertices */
public int edges()    { return e; }    /** @return number of edges */
public boolean existsEdge(int i, int j) { /** @return true iff (i,j) is an edge */
    if (i < 1 || j < 1 || i > n || j > n
        || aList[i].indexOf(new EdgeNode(j)) == -1) return false;
    else return true;
}

// put theEdge into the digraph & throws IllegalArgumentException when theEdge is invalid
public void putEdge (Object theEdge) {
    Edge edge = (Edge) theEdge;
    int v1 = edge.vertex1;
    int v2 = edge.vertex2;
    if (v1 < 1 || v2 < 1 || v1 > n || v2 > n || v1 == v2) throw new
        IllegalArgumentException ("(" + v1 + "," + v2 + ") is not a permissible edge");
    if (aList[v1].indexOf(new EdgeNode(v2)) == -1) { // new edge
        aList[v1].add(0, new EdgeNode(v2)); // put v2 at front of chain aList[v1]
        e++; }
}
```




The class LinkedDigraph (3)

```
/** remove the edge (i,j) */
public void removeEdge(int i, int j) {
    if (i >= 1 && j >= 1 && i <= n && j <= n) {
        Object v = aList[i].removeElement(j);
        if (v != null)    e--; // edge (i,j) did exist
    }
}

/** @return in-degree of vertex i
 * @throws IllegalArgumentException when i is an invalid vertex */
public int inDegree(int i) {
    if (i < 1 || i > n) throw new IllegalArgumentException("no vertex " + i);
    // count in edges at vertex i
    int sum = 0;
    for (int j = 1; j <= n; j++)
        if (aList[j].indexOf(new EdgeNode(i)) != -1)    sum++;
    return sum;
}

} // end of the class LinkedDigraph
```



Complexity of LinkedDGraph

- First Constructor: $O(n)$
- Second Constructor: $\Theta(1)$
- ExistsEdge(i, j): $O(d_i^{\text{out}})$
- Put(): $O(d_{v_1}^{\text{out}})$
- removeEdge(): $O(d_i^{\text{out}})$
- outDegree(): $\Theta(1)$
- inDegree(): $O(n+e)$



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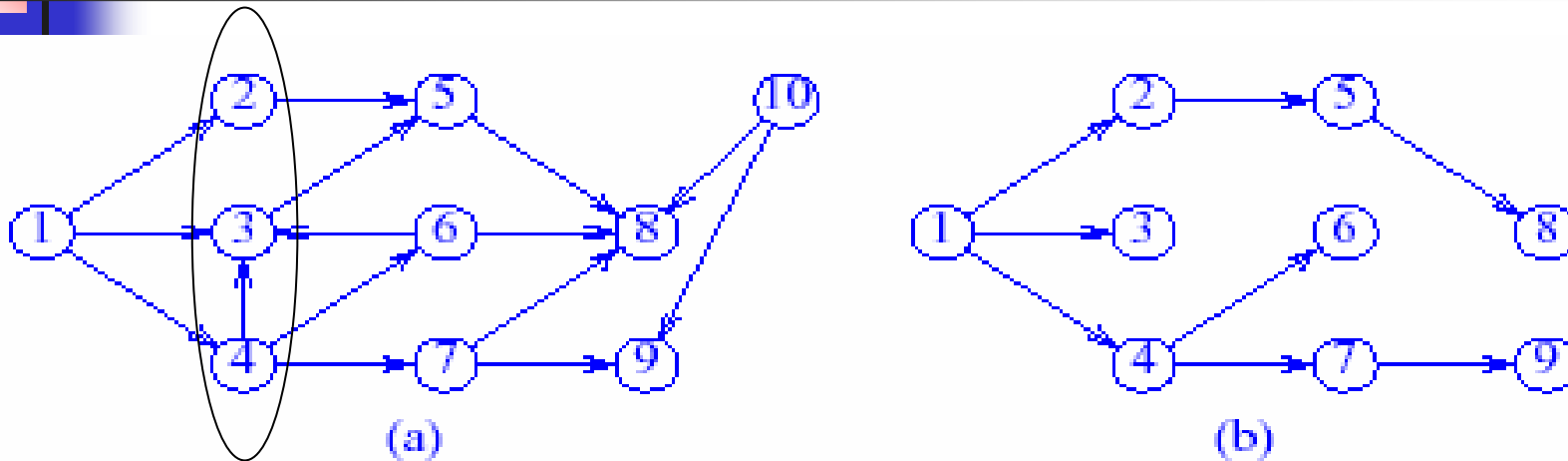
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Graph Search Methods

- Two standard ways
 - Breadth-first search (BFS)
 - Depth-first search (DFS)
- The DFS method is used more frequently to obtain efficient graph algorithms than the BFS method
- Here BFS & DFS examples are on directed graphs, but graph types do no matter
- Search a node → Visit a node → Put a label into a node

Breadth-First Search (1)



- To determine all the vertices **reachable** from vertex 1
 - $\{1\}$ first determine
 - $\{2,3,4\}$ is set of vertices adjacent from 1
 - $\{5,6,7\}$ is set of vertices adjacent from $\{2,3,4\}$
 - $\{8,9\}$ is set of vertices adjacent from $\{5,6,7\}$
 - $\{10\}$ is set of vertices adjacent from $\{8,9\}$
 - $\{1,2,3,4,5,6,7,8,9\}$ is the set of vertices reachable from vertex 1
- We need **QUEUE!**



Breadth-First Search (2)

- For finding reachable vertices from a given vertex V
 - BFS can be implemented using a queue
 - BFS $\hat{=}$ Level-order traversal of a binary tree
- The pseudo-code labels all vertices that are reachable from v

```
breadthFirstSearch(v) {  
    Label vertex v as reached  
    Initialize Q to be a queue with only v in it  
    while (Q is not empty) {  
        Delete a vertex w from the queue;  
        Let u be a vertex (if any) adjacent from w;  
        while (u) {  
            if (u has not been labeled) {  
                Add u to the queue;  
                Label u as reached; }  
            u = next vertex that is adjacent from w  
        }  
    }  
}
```



Implementations of BFS

- BFS can be performed
 - independently of **graph types**
 - undirected graph, digraph, weighted undirected graph, or weighted digraph
 - independently of **the particular representation**
- BFS codes
 - `Graph.java`, `AdjacencyDigraph.java`, `LinkedDigraph.java`
- Next program assumes
 - $\text{reach}[i]=0$ initially for all vertices i
 - $\text{label} \neq 0$



BFS code in Graph.java

```
/* reach[i] is set to label for all vertices reachable from vertex v ;  
   bfs(1, reach, 1): set "1" to all nodes in reach[] reachable from vertex 1 */  
public void bfs(int v, int [] reach, int label) {  
    ArrayQueue q = new ArrayQueue(10);  
    reach[v] = label;  
    q.put(new Integer(v));  
    while (!q.isEmpty()) { // remove a labeled vertex from the queue  
        int w = ((Integer) q.remove()).intValue();  
        // mark all unreached vertices adjacent from w  
        Iterator iw = iterator(w);  
        while (iw.hasNext()) { // visit an adjacent vertex of w  
            int u = ((EdgeNode) iw.next()).vertex;  
            if (reach[u] == 0) { // u is an unreached vertex  
                q.put(new Integer(u));  
                reach[u] = label; // mark reached }  
            }  
        }  
    }  
} // end of bfs
```


BFS code in AdjacencyDigraph.java

* Array-based implementation

```
public void bfs (int v, int [] reach, int label) {
    ArrayQueue q = new ArrayQueue(10);
    reach[v] = label;
    q.put(new Integer(v));
    while (!q.isEmpty()) {
        int w = ((Integer) q.remove()).intValue();
        for (int u = 1; u <= n; u++) {
            if (a[w][u] && reach[u] == 0){ // u is an unreached vertex
                q.put(new Integer(u));
                reach[u] = label; }
        }
    }
} // end of bfs
```



BFS code in LinkedDigraph.java

* Link-based implementation

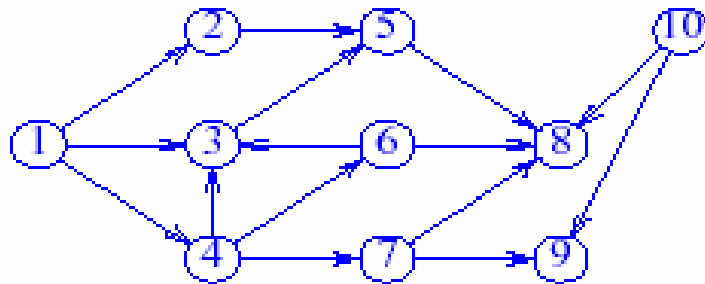
```
public void bfs (int v, int [] reach, int label) {
    ArrayQueue q = new ArrayQueue(10);
    reach[v] = label;
    q.put(new Integer(v));
    while (!q.isEmpty()) {
        int w = ((Integer) q.remove()).intValue();
        for (ChainNode p = aList[w].firstNode; p != null; p = p.next) {
            int u = ((EdgeNode) p.element).vertex;
            if (reach[u] == 0) { // u is an unreachable vertex
                q.put(new Integer(u));
                reach[u] = label; }
        }
    } // end of while
} // end of bfs
```



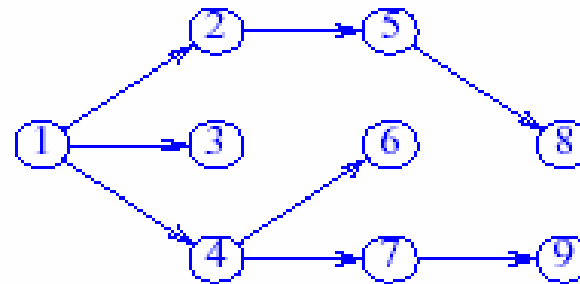
Complexity Analysis of BFS

- BFS steps
 - Add the adjacent vertices to the queue exactly once
 - Delete the vertices from queue exactly once
 - Traverse the adjacent vertices exactly once
- Time for these operations
 - If s vertices are labeled and there are n vertices in a graph
 - $O(s*n)$: if array-based adjacency matrix is used
 - $O(\sum_i d_i^{out})$: if linked adjacency list is used

Depth-First Search (1)



(a)



(b)

- To determine all the vertices **reachable** from vertex 1
 - v=1, candidate of u : 2, 3, 4 // 2 is selected
 - v=2, candidate of u : 5 // 5 is selected
 - v=5, candidate of u : 8 // 8 is selected
 - v=8, no unreached adjacent node // back up vertex 5.
 - v=5, no unreached adjacent node // back up vertex 2
 - v=2, no unreached adjacent noide // back up vertex 1
 - v=1, candidate of u : 3, 4 //3 is selected
 - Keep going.....

■ We need **STACK!**
Data Structures



Depth-First Search (2)

```
depthFirstSearch(v) {  
    Label vertex v as reached.  
    for(each unreached vertex u adjacent from v)  
        depthFirstSearch(u);  
}
```

- DFS can be implemented using a stack
- Theorem 17.2: Let G be an arbitrary graph and let v be any vertex of G . The pseudo-code `depthFirstSearch` labels all vertices that are reachable from v (including vertex v)



DFS in Graph.java

```
/* reach[i] is set to label for all vertices reachable from vertex v
   dfs(1, reach, 1): set "1" to all nodes in reach[] reachable from vertex 1 */
public void dfs (int v, int [] reach, int label) {
    Graph.reach = reach;
    Graph.label = label;
    rDfs(v);
}
/** recursive dfs method */
private void rDfs(int v) {
    reach[v] = label;
    Iterator iv = iterator(v);
    while (iv.hasNext()) { // visit an adjacent vertex of v
        int u = ((EdgeNode) iv.next()).vertex;
        if (reach[u] == 0)    rDfs(u); // u is an unreached vertex
    }
}
```



Other DFS codes

- DFS in AdjacencyDigraph.java
- DFS in LinkedDigraph.java

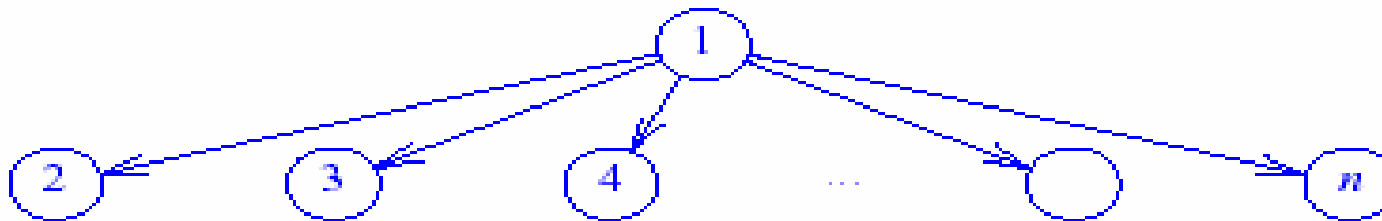
- Yes, it is your job!

Complexity Comparison of DFS vs BFS

- We can prove DFS & BFS have the same time & space complexities
- DFS → stack space for the recursion
- BFS → queue space



(a) Worst case for dfs (1) ; best case for bfs (1)



(b) Best case for dfs (1) ; worst case for bfs (1)

Figure 17.19 Worst-case and best-case space-complexity graphs



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Finding a Path in a Digraph

- To actually construct **the path in a directed graph**, we need to remember the edges used to move from one vertex to the next
- `findpath()`
 - Return null if no path
 - Return an array `p[length]` from `s` to `d` if find a path where `p[0] = s` and `p[p.length - 1] = d`
- `findPath()` calls `rFindPath()` which is **a modified DFS**



Code for findPath()

```
/** find a path from s to d
 * @return the path in an array using positions 0 on up
 * @return null if there is no path */
public int [] findPath(int s, int d) { // initialize for recursive path finder
    int n = vertices();
    path = new int [n];
    path[0] = s;           // first vertex is always s
    length = 0;           // current path length
    destination = d;
    reach = new int [n + 1]; // by default reach[i] = 0 initially
    // search for path
    if (s == d || rFindPath(s)) { // a path was found, trim array to path size
        int [] newPath = new int [length + 1];
        System.arraycopy(path, 0, newPath, 0, length + 1); // copy from old space to new space
        return newPath; }
    else return null;
} // end of findPath
```

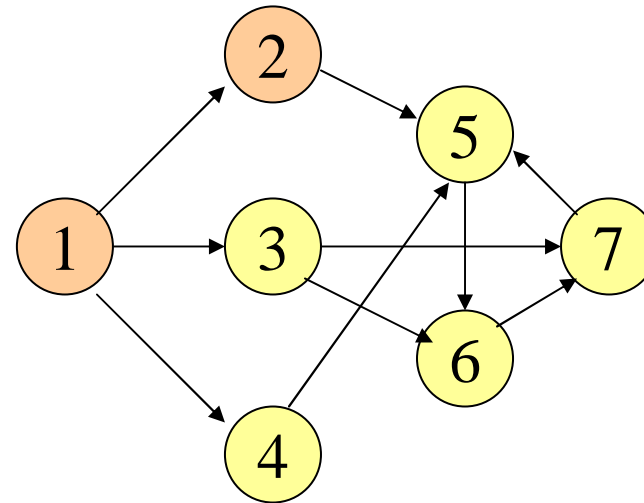
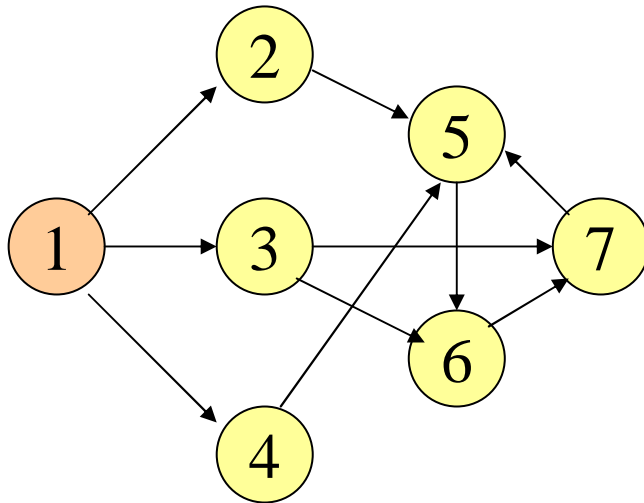


Code for rFindPath()

```
private boolean rFindPath(int s); {
    reach[s] = 1;
    Iterator is = iterator(s);
    while (is.hasNext()) { // visit an adjacent vertex of s
        int u = ((EdgeNode) is.next()).vertex;
        if (reach[u] == 0) { /* u is an unreached vertex & move to vertex u
            length++;
            path[length] = u; // add u to path
            if (u == destination) return true;
            if (rFindPath(u)) return true;
            // no path from u to destination
            length--; } // remove u from path
        }
    }
    return false
} // end of rFindPath
```

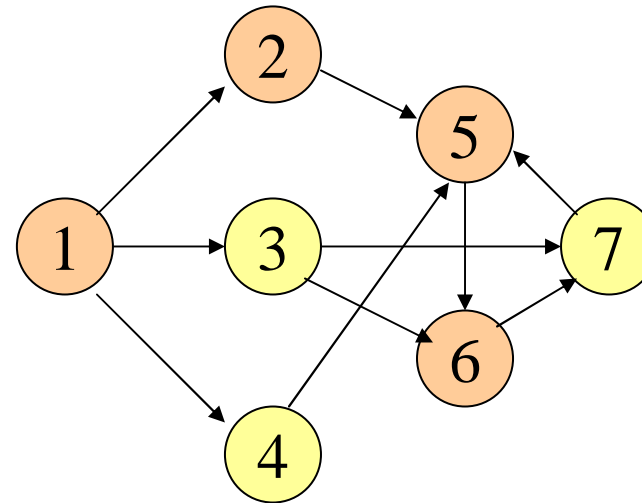
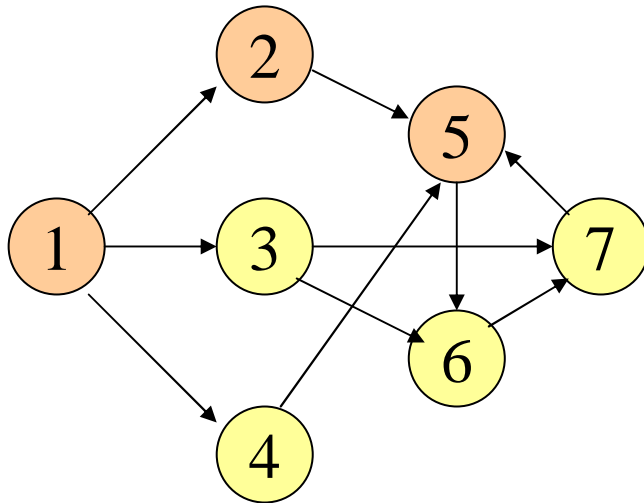
An Example: findPath() (1)

- Source = 1, Destination = 7: length=1, path={1,2}



An Example: findPath() (2)

- Source = 1, Destination = 7: length=3, path={1,2,5,6}



An Example: findPath() (3)

- Source = 1, Destination = 7: length = 4, path={1,2,5,6,7}

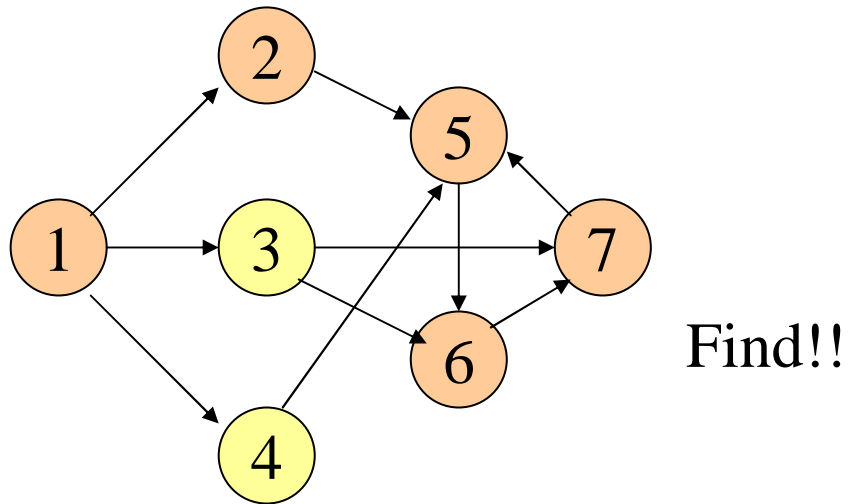




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Connected Graph

- Determine whether an undirected graph G is connected by performing DFS or BFS
- Here `connected()` is based on DFS
- `connected()` return
 - `true` : if the graph is connected
 - `false` : if the graph is not connected
- Connected component
 - Vertices that are reachable from a vertex i , together with the edges that connect pair of vertices in a graph



Code for connected()

```
/** @return true iff graph is connected */
public boolean connected() {
    // make sure this is an undirected graph
    verifyUndirected("connected");

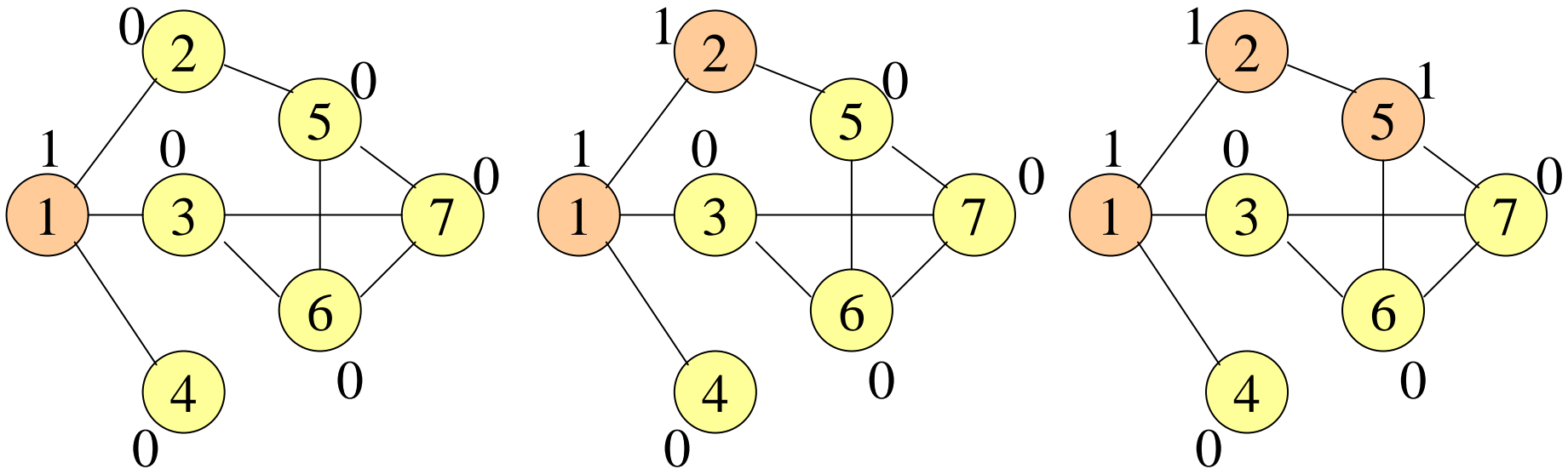
    int n = vertices();
    reach = new int [n + 1]; // by default reach[i] = 0

    dfs(1, reach, 1); // mark vertices reachable from vertex 1

    for (int i = 1; i <= n; i++) // check if all vertices marked
        if (reach[i] == 0) return false;
    return true;
}
```

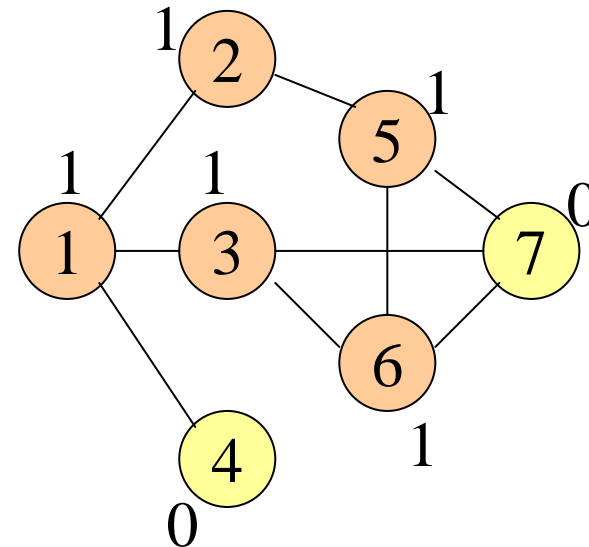
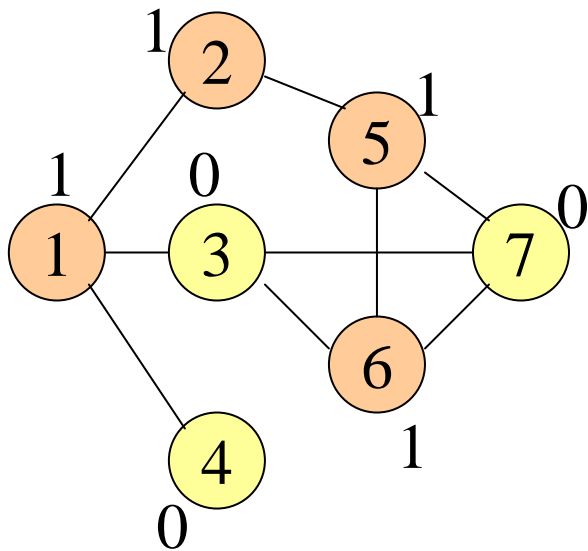
An Example: connected() (1)

- Mark vertices reachable from vertex 1
- DFS & visit the node with the smallest key first



An Example: connected() (2)

- From node 5: visit node 6
- From node 6: visit node 3



An Example: connected() (3)

- From node 3: visit node 7, then finish up **the first DFS**
- Go back to node 1, and visit the remaining node 4. → Done!

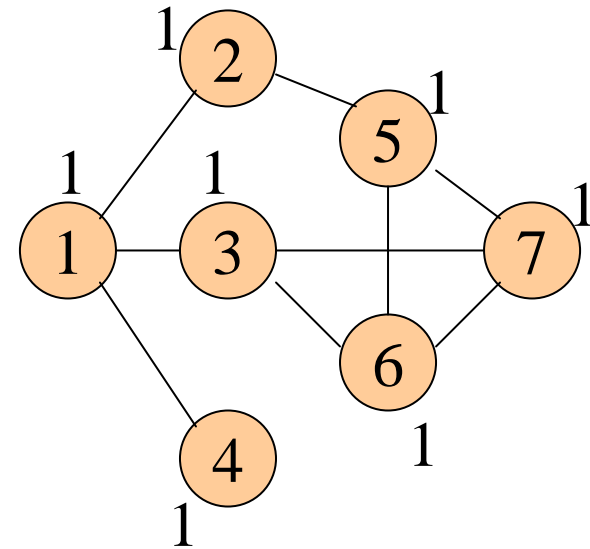
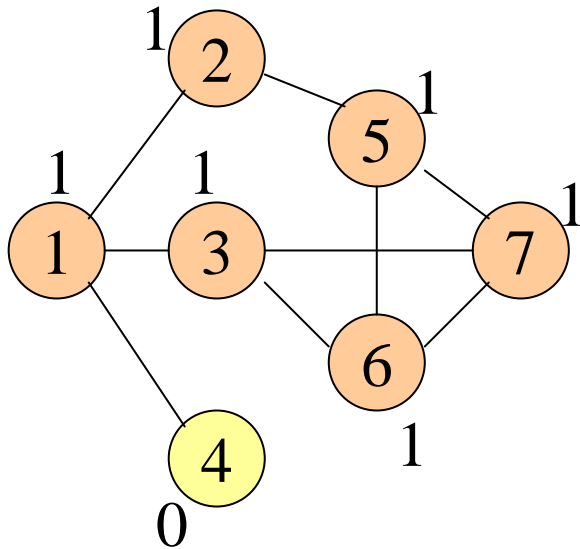




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Component Labeling Problem in a Graph

- Component-labeling problem
 - we are to label the vertices of **an undirected graph** so that two vertices are assigned the same label iff they belong to the same component
 - `verifyUndirected()` is needed
- Label components
 - making repeated invocations of either **a DFS or BFS**
- `Graph.labelComponent()`
 - Different components have different labels
 - Here, solve the component-labeling problem using **BFS**
 - $O(n^2)$: if adjacency matrix is used for n nodes
 - $O(n + e)$: if linked-adjacency-list representation is used for n nodes & e edges



Code for verifyUndirected()

```
/** verify that the graph is an undirected graph
 * @exception UndefinedMethodException if graph is directed */
public void verifyUndirected(String theMethodName) {
    Class c = getClass(); // class of this
    if (c == AdjacencyGraph.class ||
        c == AdjacencyWGraph.class ||
        c == LinkedGraph.class ||
        c == LinkedWGraph.class)
        return;

    // if not an undirected graph
    throw new UndefinedMethodException
        ("Graph." + theMethodName + " is for undirected graphs only");
}
```

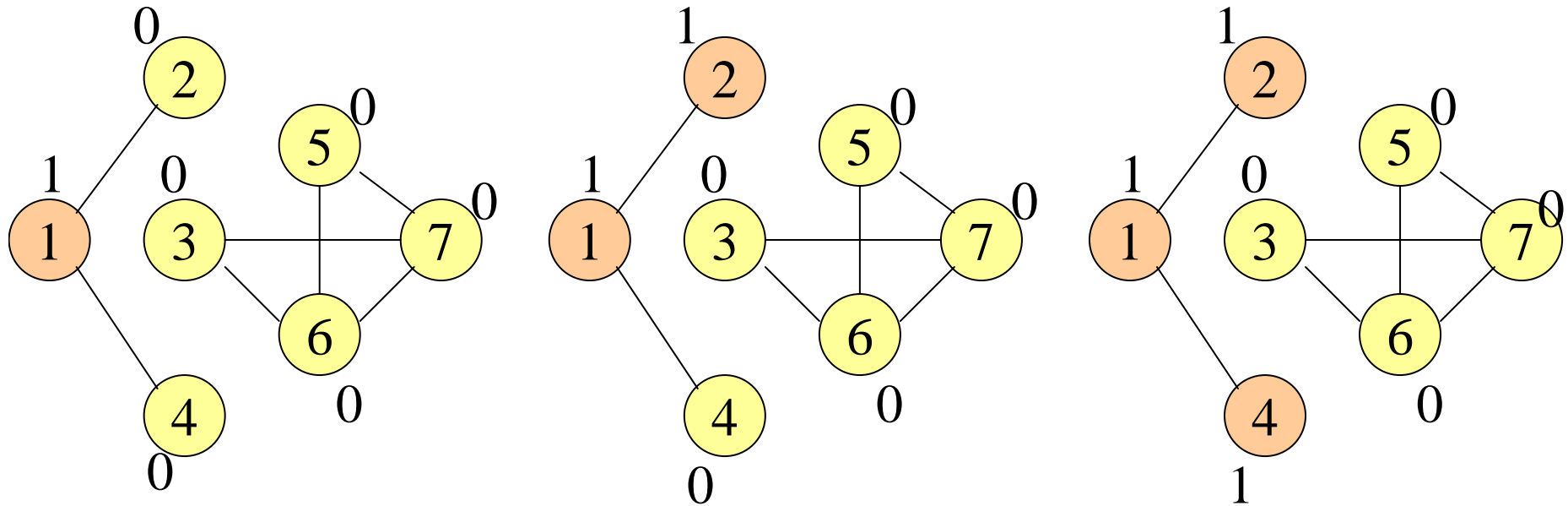



Code for labelComponents()

```
/** label the components of an undirected graph
 * @return the number of components
 * set c[i] to be the component number of vertex i */
public int labelComponents(int [] c) { // make sure this is an undirected graph
    verifyUndirected("labelComponents");
    int n = vertices();
    // assign all vertices to no component
    for (int i = 1; i <= n; i++) c[i] = 0;
    label = 0; // ID of last component
    // identify components
    for (int i = 1; i <= n; i++)
        if (c[i] == 0) { // vertex i is unreached // vertex i is in a new component
            label++; // new label for new component
            bfs(i, c, label); // mark new component
        }
    return label;
}
```

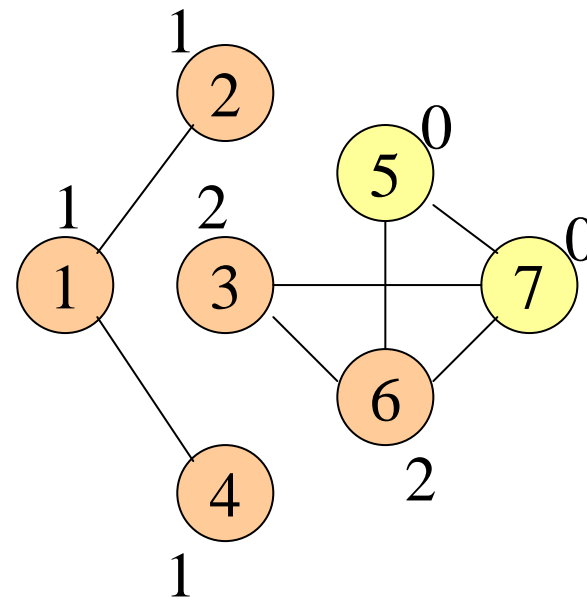
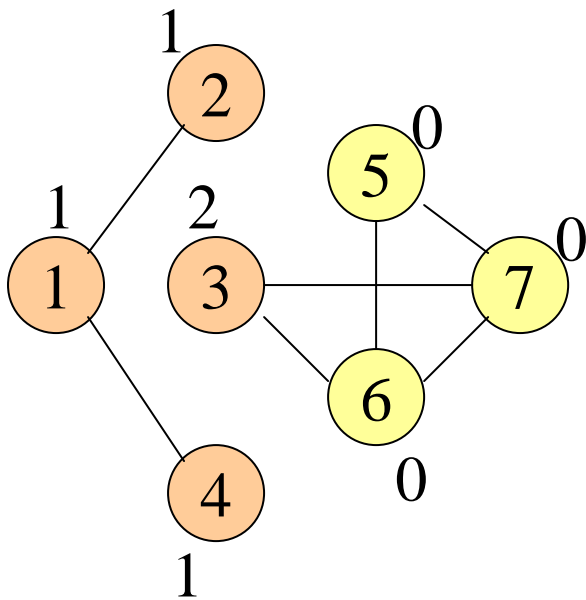
Example: labelComponents() (1)

* `label = 1`, execute `bfs(1, c, label)` from node 1



Example: labelComponents() (2)

* Now $label = 2$, execute $bfs(3, c, label)$ from node 3



Example: labelComponents() (3)

- `label = 2`, `bfs(3, c, label)`
- From node 3, visit node 6 & 7
- From node 6, visit node 5

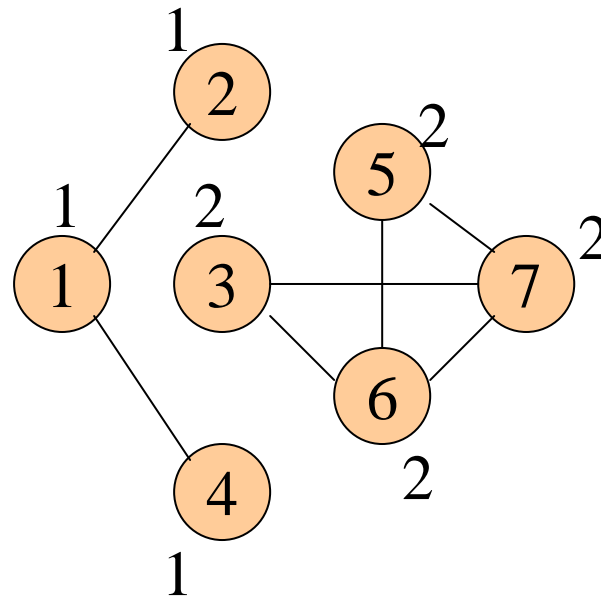
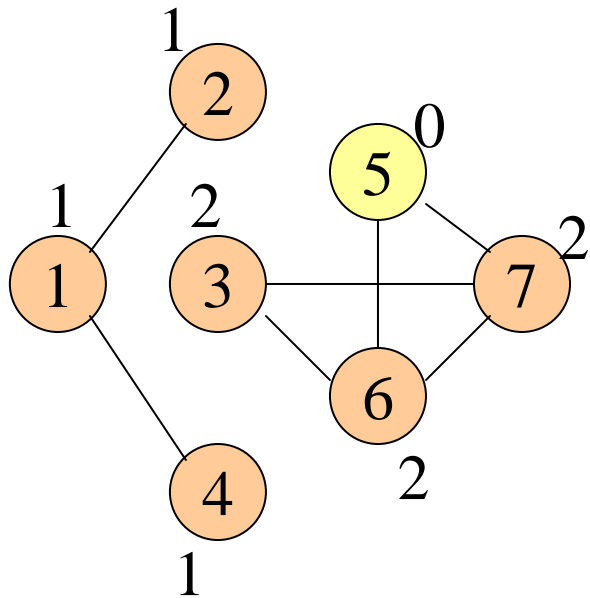




Table of Contents

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Spanning Trees

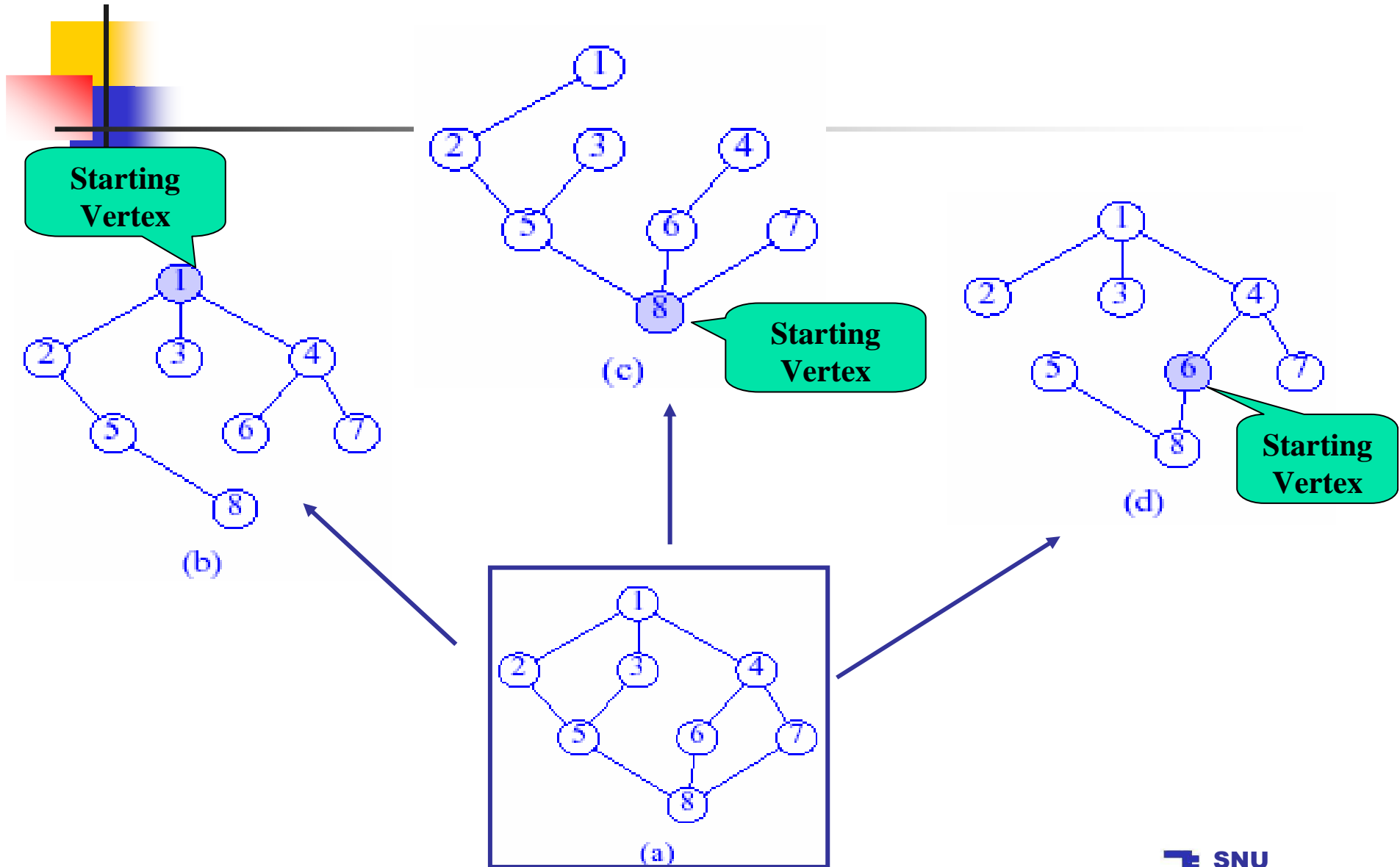
- Spanning Tree
 - A set of edges contains a path from v to every other vertex in the graph
 - It defines a connected subgraph
 - Normally applied to **connected undirected graphs**
- Bread-first spanning tree (BF spanning tree)
 - Spanning tree obtained in the manner from BFS
- Depth-first spanning tree (DF Spanning tree)
 - Spanning tree obtained in the manner from DFS



Code for BF Spanning Tree

```
/** SpanningTree with BFS
 * reach[i] is set to label for all vertices reachable from vertex v
 * sTreebfs(v, reach, 1): set "1" to the nodes in reach[] from the node v */
public void sTreebfs(int v, int [] reach, int label) {
    ArrayQueue q = new ArrayQueue(10);
    reach[v] = label;
    q.put(new Integer(v));
    while (!q.isEmpty()) {
        int w = ((Integer) q.remove()).intValue(); // remove a labeled vertex from the queue
        iterator iw = iterator(w); // mark all unreached vertices adjacent from w
        while (iw.hasNext()) { // visit an adjacent vertex of w
            int u = ((EdgeNode) iw.next()).vertex;
            if (reach[u] == 0) { // u is an unreached vertex
                q.put(new Integer(u));
                reach[u] = label; // mark reached
                for (i=1; i <=q.length(); i++) { // remove edge!!
                    int t = ((Integer) q.remove()).intValue();
                    if (existsEdge(u,t)) { removeEdge(u, t) }
                    q.put(new Integer(t)); }
            } // end of if
        } // end fo while
    } // end of sTreebfs
}
```

Example of BF Spanning Trees

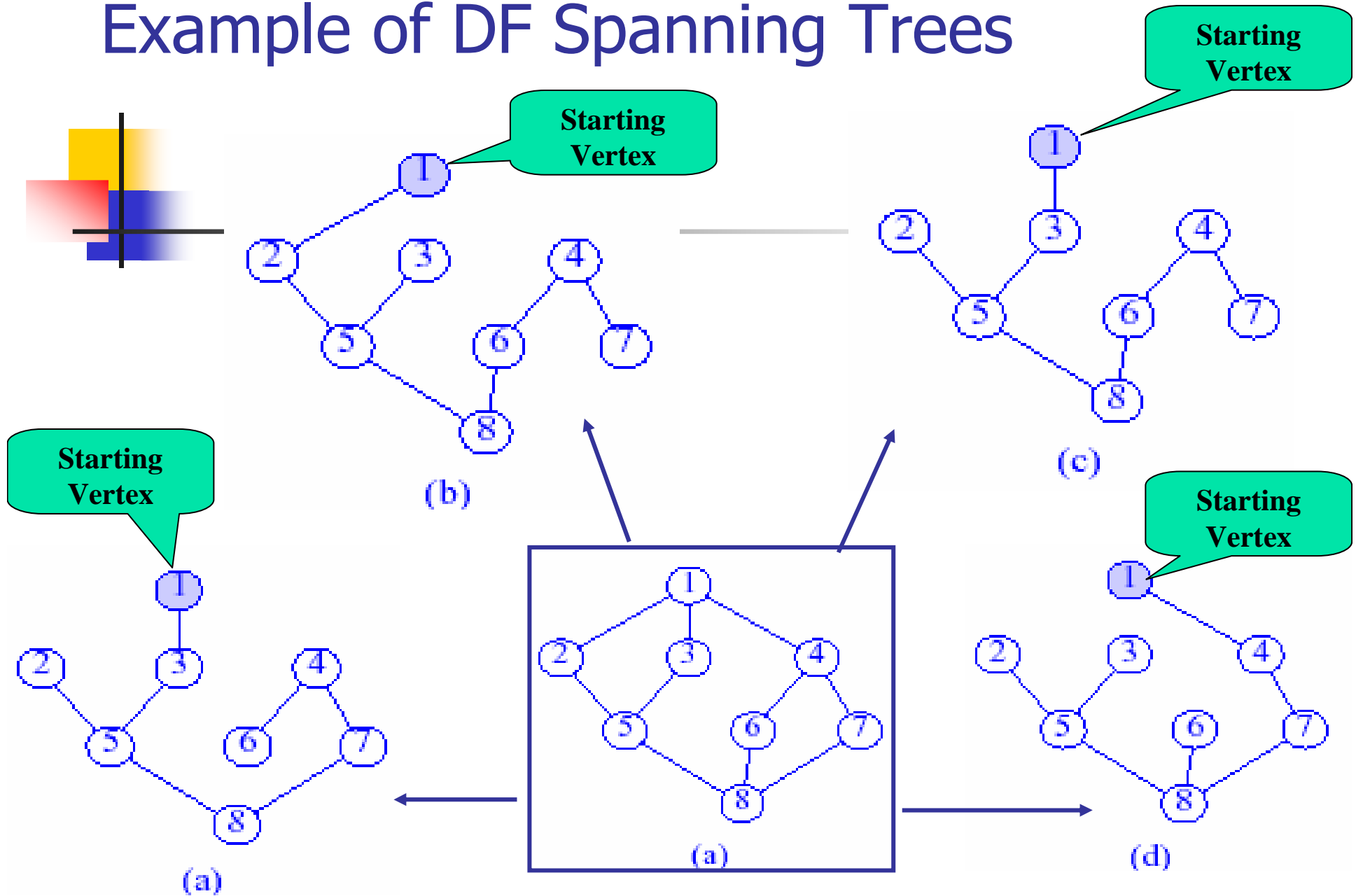




Code for DF SpanningTree

```
/* SpanningTree with DFS
   reach[i] is set to label for all vertices reachable from vertex v*/
public void sTreedfs(int v, int [] reach, int label) {
    reach[v] = label;
    Iterator iv = iterator(v);
    // visit an adjacent vertex of v
    int u1 = ((EdgeNode) iv.next()).vertex;
    if (reach[u] == 0) // u is an unreached vertex
        while (iv.hasNext()) {
            // remove edge
            int u2 = ((EdgeNode) iv.next()).vertex;
            if (existsEdge(v,u2)) { removeEdge(v,u2) }
        }
    sTreedfs(u1);
}
```

Example of DF Spanning Trees





Summary

- Graphs

- Used to model many real-world problems

- In this chapter

- Graph terminology
- Different types of graphs
- Common graph representations
- Standard graph search methods
- Algorithms to find a path in a graph
- Specifying an abstract data type as an abstract class

Sahni class:

dataStructures.LinkedDigraph (p.672)

```
public class LinkedDigraph extends Graph{
```

constructors

LinkedDigraph(): Constructs an empty directed graph

methods

int inDegree(int i): Returns the in-degree of vertex *i*

int outDegree(int i): Returns the out-degree of vertex *i*

int putEdge(theEdge): Puts *theEdge* into the digraph

int removeEdge(int i, int j): Removes the edge (*i, j*) from the digraph

int existsEdge(int i, int j): Returns *true* iff the graph contains (*i, j*)

```
}
```

Sahni class:

dataStructures.LinkedGraph (p.672)

```
public class LinkedGraph extends LinkedDigraph{
```

constructors

LinkedGraph(): Constructs an empty undirected graph

methods

int degree(int i): Returns the degree of vertex *i*

int putEdge(Object theEdge): Puts *theEdge* into the graph

int removeEdge(int i, int j): Removes the edge (*i, j*) from the graph

int existsEdge(int i, int j): Returns *true* iff the graph contains (*i, j*)

```
}
```



Data Structures

- Chapter 2-4: Complexity of algorithms
- Chapter 5-8: Linear List
- Chapter 9-11: Stack & Queue
- Chapter 12-16: Tree
- Chapter 17: Graph