1. Essential Concepts

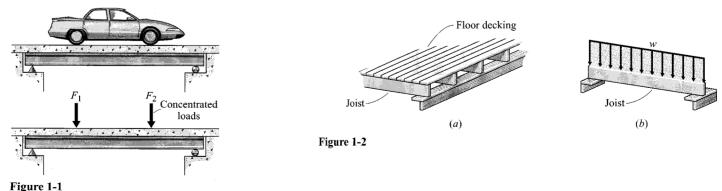
1.1 Introduction

• Mechanics

- Classical -, Quantum -, Relativistic –, etc.
- Statics: concerned with analysis of loads on physical systems in static equilibrium.
- Dynamics: kinematics (운동학-시간과 속도, 가속도) and kinetics (운동역학 힘과 운동). Normally dealing with particles and rigid bodies.
- Mechanics of materials: concerned with the behavior of solid materials such as bars, beams and columns on axial, torsional, and/or flexural loading.
- Primary objects of this course
 - Understanding relations between the load and deformation, load and stress, and stress and strain of a body
 - Familiar with fundamental concepts and skills for structural and machine design

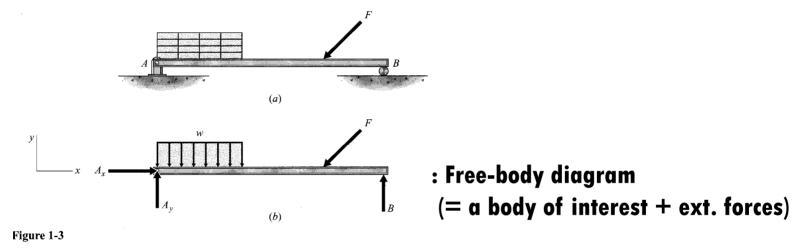
1.2 Classification of forces

- Newton's three laws of Motion
 - The law of inertia: every object tends to remain in a state of motion without an external force on it.
 - F = ma: force equals mass times acceleration.
 - The law of action-reaction: To every action there is an equal and opposite reaction.
- Classification of forces
 - Contact force vs. body force: person standing on a sidewalk, electromagnetic, gravitation...
 - Concentrated force (load) vs. distributed force



1.2 Classification of forces

- Applied force vs. reaction force



- External force vs. internal force: force on an object exerted by external sources force at a section of an object

- Equilibrium conditions (equations) of a rigid body
 - $\sum F = 0$ ($\equiv \sum F_x = 0$, $\sum F_y = 0$, and $\sum F_z = 0$) - $\sum M_0 = 0$ ($\equiv \sum M_x = 0$, $\sum M_y = 0$, and $\sum M_z = 0$)
 - For 2D cases: $\sum F_x = 0$, $\sum F_y = 0$, and $\sum M_z = 0$

- For coplanar and concurrent cases: $\sum F_x = 0$, $\sum F_y = 0$

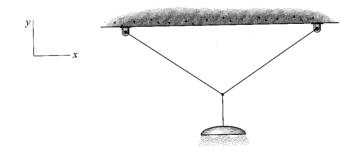


Figure 1-4

- Example problem 1-1
- Force at A and B

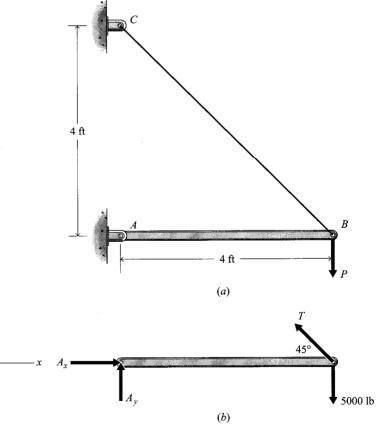


Figure 1-5

 $|\mathcal{Y}|$

- Example problem 1-2
- Force at A and B neglecting the beam mass
- Force at A and B at the beam mass of 8.5kg/m

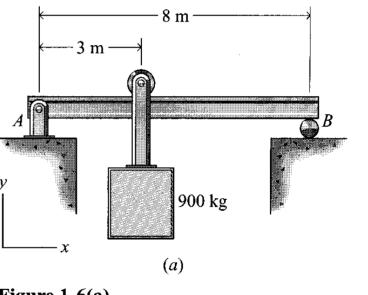


Figure 1-6(a)

- Example problem 1-4
- Forces on member BH

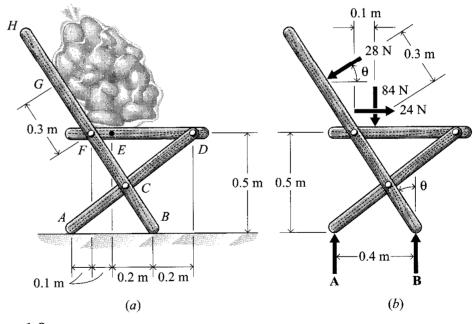
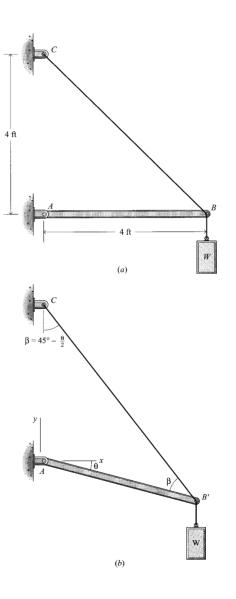


Figure 1-8

1.4 Equilibrium of a deformable body

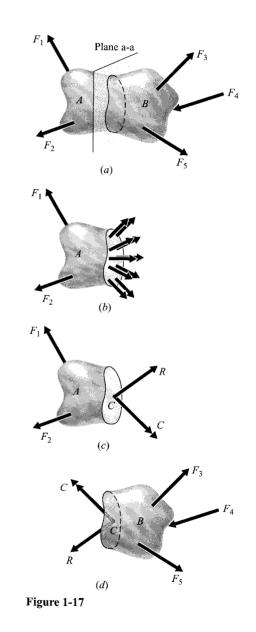
- Considerations
- Equation of equilibrium
- Force-deformation relationship
- Deformation
- Example problem 1-8
- Tension in the deformable wire at k = 5000 lb/in, 2500 lb/in, and 1000 lb/in (W=5000 lb)

→ Tension (force) depends on the force-deformation relationship of the deformable body



- Equilibrium of parts of a body
- If a whole body is in equilibrium any part of the body is also in equilibrium.
- Forces distributed on a section can be represented by a resultant force.

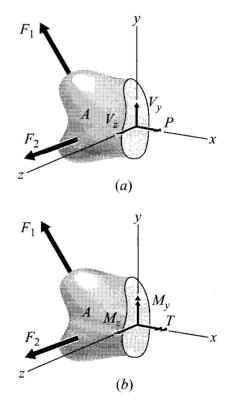
$$\sum F = 0: \quad F_1 + F_2 + R = 0$$
$$\sum M_C = 0: M_1 + M_2 + C = 0$$



- Internal forces in a section
- Select an *xyz*-coordinate system in which *x* is perpendicular to the section and *y* and *z* lie in the section.

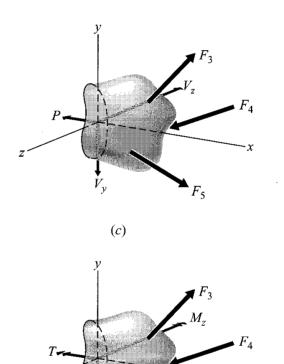
The components of *R* and *C* perpendicular to the section are called **normal force** (P) and **twisting couple** (T; twisting moment or torque).

- The components of *R* and *C* lying in the section are called **shear forces** (V_y, V_z) and **bending couples** $(M_y, M_z;$ bending moments).



-A section is called a positive (negative) section when its outward normal points in a positive coordinate direction.

- The component of *R* or *C* is defined as positive if both the section direction and the component direction are positive or negative.

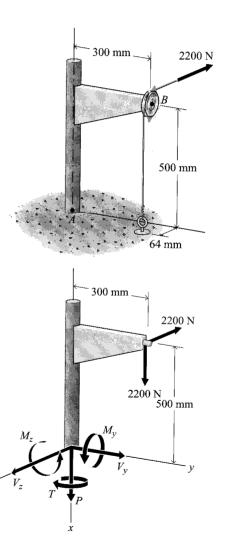


(d)

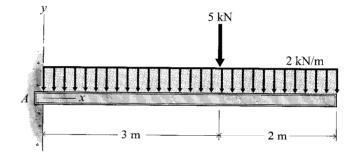
• Example problem 1-9

- Internal force components on a section A

- Internal moment components on a section A



- Example problem 1-10
- Support reaction force and moment at A
- Internal force and moment on a section 4 m to the right of the support A



- Example problem 1-11
- Internal force and moment on a mid-point section between D and F

