Topics in Fusion and Plasma Studies 2 (459.667, 3 Credits)

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Textbook

- J. Freidberg,

"Ideal Magnetohydrodynamics (Modern Perspectives in Energy)", Springer, 1st edition (1987)

T. Takeda and S. Tokuda,
 "Computation of MHD Equilibrium of Tokamak Plasma",
 Journal of Computational Physics,
 Vol. 93, p1~107 (1991)

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Week 1-2. The MHD Model, General Properties of Ideal MHD Week 3. Equilibrium: General Considerations Week 4. Equilibrium: One-, Two-Dimensional Configurations Week 5. Equilibrium: Two-Dimensional Configurations Week 6-7. Numerical Solution of the GS Equation Week 9. Stability: General Considerations Week 10-11. Stability: One-Dimensional Configurations Week 12. Stability: Multidimensional Configurations Week 14-15. Project Presentation

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- Basic physics areas in magnetic fusion
- Equilibrium and stability: plasma beta
- Heating and current drive: Lawson criterion
- Transport: Lawson criterion











Single particle motion of the plasma





Strong magnetic field: $r_L << a$

• Magnetic field lines trace out "magnetic surfaces", to particles stay on these surfaces.

Plasmas as fluids

- The single particle approach gets to be complicated.
- A more statistical approach can be used because we cannot follow each particle separately.
- Now introduce the concept of an **electrically charged current-carrying fluid.**
 - → Magnetohydrodynamic (magnetic fluid dynamic: MHD) equations

• Ideal MHD

- Single-fluid model
- how magnetic, inertial, and pressure forces interact within an ideal perfectly conducting plasma in an arbitrary magnetic geometry
- Any fusion reactor must satisfy the equilibrium and stability set by ideal MHD.

Nonideal effects (e.g. electrical resistivity)

- allow the development of slower, weaker instabilities

• Ideal MHD: $\eta = 0$

• Resistive MHD: $\eta \neq 0$





• Ideal MHD: $\eta = 0$

• Resistive MHD: $\eta \neq 0$



The MHD Model

Questions

- 1. The plasma is assumed to be collision dominated.
 - Is it true in fusion plasmas?
 - The ideal MHD provides a very accurate description of most macroscopic plasma behaviour.
 cf) collisionless MHD
- 2. Ideal MHD must be viewed as an asymptotic model in that specific length and time scales must be assumed for the derivation to be valid.
- Even when the collision-dominated assumption is not involved, there are many situations where MHD is used to described phenomena on time scales far beyond its strict range of applicability.

The MHD Model sighting the derivation of MHD Eliminated in the derivation of MHD physics wave propagation Important processes in fusion mas Not adequately described by - Radiation - RF heating - Resonant alous transport - Resistive instabilities - alpha-particle behaviour

The MHD Model

How does a given magnetic geometry provide forces to hold a plasma in equilibrium?

Why are certain magnetic geometries much more stable against macroscopic disturbances than others?

Why do fusion configurations have such technologically undesirable shapes as a torus, a helix, or a baseball seam?

Ideal MHD model

 $\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$ Mass continuity equation

$$\rho \frac{d\vec{v}}{dt} = \vec{J} \times \vec{B} - \nabla p$$

Single-fluid equation of motion

$$\frac{d}{dt}\left(\frac{p}{\rho^{\gamma}}\right) = 0$$

Energy equation (equation of state): adiabatic evolution

 $\vec{E} + \vec{v} \times \vec{B} = 0$

Ohm's law: perfect conductor \rightarrow "ideal" MHD

 $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ $\nabla \times \vec{B} = \mu_0 \vec{J}$ $\nabla \cdot \vec{B} = 0$

Maxwell equations

Validity of the ideal MHD model

- Characteristic length: a
- Characteristic speed: $V_{Ti} = (2T_i/m_i)^{1/2}$
- Characteristic time: $\tau_M = a/V_{Ti} \sim \mu s$

Starting Equations

Homework

С

$$\begin{aligned} \frac{\partial f_{\alpha}}{\partial t} + \vec{u} \cdot \nabla f_{\alpha} + \frac{q_{\alpha}}{m_{\alpha}} (\vec{E} + \vec{u} \times \vec{B}) \cdot \nabla_{u} f_{\alpha} &= \left(\frac{\partial f_{\alpha}}{\partial t}\right) \\ \nabla \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ \nabla \cdot \vec{B} &= 0 \\ \nabla \times \vec{B} &= \mu_{0} \vec{J} + \frac{1}{c^{2}} \frac{\partial \vec{E}}{\partial t} \\ \nabla \cdot \vec{E} &= \frac{\sigma}{\varepsilon_{0}} \\ \vec{J} &= \sum_{\alpha} q_{\alpha} \int \vec{u} f_{\alpha} d\vec{u} \quad \text{current density} \\ \sigma &\equiv \sum_{\alpha} q_{\alpha} \int f_{\alpha} d\vec{u} \quad \text{charge density} \end{aligned}$$

Collision operator for elastic collisions

$$\left(\frac{\partial f_{\alpha}}{\partial t}\right)_{c} = \sum_{\beta} C_{\alpha\beta}$$

1. Conservation of particles between like and unlike particle collisions

$$\int C_{ee} d\vec{u} = \int C_{ii} d\vec{u} = \int C_{ei} d\vec{u} = \int C_{ie} d\vec{u} = 0$$

2. Conservation of momentum and energy btw. like particle collisions

$$\int m_e \vec{u} C_{ee} d\vec{u} = \int m_i \vec{u} C_{ii} d\vec{u} = 0$$
 $\int \frac{1}{2} m_e u^2 C_{ee} d\vec{u} = \int \frac{1}{2} m_i u^2 C_{ii} d\vec{u} = 0$

3. Conservation of total momentum and energy btw. unlike particle collisions

$$\int (m_e \vec{u} C_{ei} + m_i \vec{u} C_{ie}) d\vec{u} = 0 \qquad \int \frac{1}{2} (m_e u^2 C_{ei} + m_i u^2 C_{ie}) d\vec{u} = 0$$

Two-Fluid Equations

$$\int Q_{i} \left[\frac{df_{\alpha}}{dt} - \left(\frac{\partial f_{\alpha}}{\partial t} \right)_{c} \right] d\vec{u} = 0 \qquad \begin{array}{c} Q_{1} = 1 & \text{mass} \\ Q_{2} = m_{\alpha}\vec{u} & \text{momentum} \\ Q_{3} = m_{\alpha}u^{2}/2 & \text{energy} \end{array}$$

$$\frac{\partial n_{\alpha}}{\partial t} + \nabla \cdot n_{\alpha} \vec{v}_{\alpha} = 0$$

$$\frac{\partial}{\partial t} (m_{\alpha} n_{\alpha} \vec{v}_{\alpha}) + \nabla \cdot (m_{\alpha} n_{\alpha} \langle \vec{u} \vec{u} \rangle) - q_{\alpha} n_{\alpha} (\vec{E} + \vec{v}_{\alpha} \times \vec{B}) = \int m_{\alpha} \vec{u} C_{\alpha\beta} d\vec{u}$$

$$\frac{\partial}{\partial t} \left(\frac{1}{2} m_{\alpha} n_{\alpha} \left\langle u^{2} \right\rangle \right) + \nabla \cdot \left(\frac{1}{2} m_{\alpha} n_{\alpha} \left\langle u^{2} \vec{u} \right\rangle \right) - q_{\alpha} n_{\alpha} \vec{v}_{\alpha} \cdot \vec{E} = \int \frac{1}{2} m_{\alpha} u^{2} C_{\alpha\beta} d\vec{u}$$

$$n_{\alpha}(\vec{r},t) \equiv \int f_{\alpha} d\vec{u} \qquad \vec{v}_{\alpha}(\vec{r},t) \equiv \frac{1}{n_{\alpha}} \int \vec{u} f_{\alpha} d\vec{u} \qquad \left\langle Q \right\rangle \equiv \frac{1}{n_{\alpha}} \int Q f_{\alpha} d\vec{u}$$

Considering the random thermal motion of particles

$$\vec{w} = \vec{u} - \vec{v}_{\alpha}(\vec{r},t), \left\langle \vec{w} \right\rangle = 0$$

 $p_{\alpha} = \frac{1}{3} n_{\alpha} m_{\alpha} \left\langle w^2 \right\rangle$

Scalar pressure

 $\vec{P}_{\alpha} \equiv n_{\alpha} m_{\alpha} \left\langle w^{2} \right\rangle$ $\vec{\Pi}_{\alpha} \equiv \vec{P}_{\alpha} - p_{\alpha} \vec{I}$

 $T_{\alpha} \equiv p_{\alpha} / n_{\alpha}$

Total pressure tensor

Anisotropic part of the pressure tensor

Temperature

 $h_{\alpha} \equiv \frac{1}{2} n_{\alpha} m_{\alpha} \left\langle w^{2} \vec{w} \right\rangle$ $\vec{R}_{\alpha} \equiv \int m_{\alpha} \vec{w} C_{\alpha\beta} d\vec{w}$ $Q_{\alpha} \equiv \int \frac{1}{2} m_{\alpha} w_{\alpha}^{2} C_{\alpha\beta} d\vec{w}$

Heat flux due to random motion

Mean momentum transfer btw. unlike particles due to the friction of collisions

Heat generated due to collisions btw. unlike particles.

$$\left(\frac{dn_{\alpha}}{dt}\right)_{\alpha} + n_{\alpha}\nabla\cdot\vec{v}_{\alpha} = 0$$

$$m_{\alpha}n_{\alpha}\left(\frac{d\vec{v}_{\alpha}}{dt}\right)_{\alpha} - q_{\alpha}n_{\alpha}(\vec{E} + \vec{v}_{\alpha} \times \vec{B}) + \nabla \cdot \vec{P}_{\alpha} = \vec{R}_{\alpha}$$

$$n_{\alpha} \left[\frac{d}{dt} \left(\frac{m_{\alpha} v_{\alpha}^2}{2} + \frac{3}{2} T_{\alpha} \right) \right]_{\alpha} + \nabla \cdot \left(\vec{v}_{\alpha} \cdot \vec{P} + \vec{h}_{\alpha} \right) - q_{\alpha} n_{\alpha} \vec{v}_{\alpha} \cdot \vec{E} = Q_{\alpha} + \vec{v}_{\alpha} \cdot \vec{R}_{\alpha}$$

$$\longleftarrow \qquad \left(\frac{d}{dt}\right)_{\alpha} \equiv \frac{\partial}{\partial t} + \vec{v}_{\alpha} \cdot \nabla$$

convective derivative

• Final set of two-fluid equations

$$\left(\frac{dn_{\alpha}}{dt}\right)_{\alpha} + n_{\alpha}\nabla\cdot\vec{v}_{\alpha} = 0$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$$

- 1. Certain asymptotic orderings are introduced which eliminate the very high-frequency, short-wavelength information in the model.
 - 2. The equations are rewritten as a set of single-fluid equations by the introduction of appropriate single-fluid variables.

3. The plasma is assumed to be collision dominated.

$$\nabla \cdot \vec{E} = \frac{1}{\varepsilon_0} (n_i - n_e) \qquad \qquad \nabla \cdot \vec{B} = 0$$
$$\nabla \cdot \vec{B} = 0$$

Low-Frequency, Long-Wavelength, Asymptotic Expansions

• First asymptotic assumption: $c \rightarrow \infty$ (Full \rightarrow low-frequency Maxwell's equations)

$$\begin{split} \varepsilon_{0} &\to 0: \quad \varepsilon_{0} \partial \vec{E} / \partial t = 0 \\ \varepsilon_{0} \nabla \cdot \vec{E} = 0 \end{split} \\ \begin{aligned} &\nabla \times \vec{B} = \mu_{0} e \big(n_{i} \vec{v}_{i} - n_{e} \vec{v}_{e} \big) + \frac{1}{c^{2}} \frac{\partial \vec{E}}{\partial t} \approx \mu_{0} \vec{J} \\ &n_{i} - n_{e} = \frac{\varepsilon_{0}}{e} \nabla \cdot \vec{E} \approx 0 \qquad n_{i} = n_{e} \equiv n \quad \text{quasineutrality} \end{split}$$

Conditions for validity:

$$\begin{split} \omega / k << c & \text{diana } \\ V_{T_e}, V_{T_i} << c, V_{T_e} \equiv (2T_\alpha / m_\alpha)^{1/2} & \text{ne} \\ \omega << \omega_{pe}, \ \omega_{pe} = (n_0 e^2 / m_e \varepsilon_0)^{1/2} \\ a >> \lambda_d, \ \lambda_d = V_{T_e} / \omega_{pe} \end{split}$$

displacement current neglected

net charge neglected

• Second asymptotic assumption: $m_e \rightarrow 0$ (electron inertia neglected: electrons have an infinitely fast response time because of their small mass)

$$0 \approx -en_e(\vec{E} + \vec{v}_e \times \vec{B}) - \nabla \cdot \vec{P}_e + \vec{R}_e$$

Conditions for validity:

$$\omega << \omega_{pe}, \ \lambda_d << a$$
$$\omega << \omega_{ce}, \ r_{Le} << a, \ r_{Le} = V_{T_e} / \omega_{ce}$$

- Subtle effect:
- Neglect of electron inertia along **B** can be tricky.
- For long wavelengths, electrons can still require a finite response time even though m_e is small. This is region of the drift wave.
- We shall see that MHD consistently treats || motion poorly, but for MHD behavior, remarkably this does not matter!!
- To treat such behavior more sophisticated models are required. The resulting instabilities are much weaker, (and still important) than for MHD.

The Single-Fluid Equations

Introduce single fluid variables

$$\begin{split} \rho &= m_i n & \text{mass density} \quad m_e \to 0, \ n_i = n_e \equiv n \\ \vec{v} &= \vec{v}_i & \text{fluid velocity} \\ \vec{J} &= en(\vec{v}_i - \vec{v}_e) & \text{current density} \\ \vec{v}_e &= \vec{v} - \vec{J} / en & \\ p &= nT = p_e + p_i & \text{total pressure} \\ T &= T_e + T_i & \text{total temperature} \end{split}$$

The Single-Fluid Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$$
 $\nabla \cdot \vec{J} = 0$ charge conservation

$$\rho \frac{d\vec{v}}{dt} - \vec{J} \times \vec{B} + \nabla p = -\nabla \cdot (\vec{\Pi}_i + \vec{\Pi}_e)$$

$$\rho[\frac{\partial u}{\partial t} + (u \cdot \nabla)u] = nq(E + u \times B) - \nabla \cdot P$$
$$\rho[\frac{\partial u}{\partial t} + (u \cdot \nabla)u] = -\nabla p + \rho v \nabla^2 u \quad \text{Navier-Stokes equation}$$

This momentum density conservation equation for species resembles in parts the one of conventional hydrodynamics, the Navier-Stokes equation. Yet, in a plasma for each species the Lorentz force appears in addition, coupling the plasma motion (via current and charge densities) to Maxwell's equation and also the various components (electrons and ions) among themselves.

The Single-Fluid Equations

 $\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0 \qquad \nabla \cdot \vec{J} = 0 \qquad \text{charge conservation}$

$$\rho \frac{d\vec{v}}{dt} - \vec{J} \times \vec{B} + \nabla p = -\nabla \cdot (\vec{\Pi}_i + \vec{\Pi}_e)$$

$$\vec{E} + \vec{v} \times \vec{B} = \frac{1}{en} (\vec{J} \times \vec{B} - \nabla p_e - \nabla \cdot \vec{\Pi}_e + \vec{R}_e) \qquad \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$
Ohm's law
$$\nabla \times \vec{B} = \mu_0 \vec{J}$$

$$\begin{aligned} \frac{d}{dt} \left(\frac{p_i}{\rho^{\gamma}}\right) &= \frac{2}{3\rho^{\gamma}} \left(Q_i - \nabla \cdot \vec{h}_i - \vec{\Pi}_i : \nabla \vec{v}\right) \\ \frac{d}{dt} \left(\frac{p_e}{\rho^{\gamma}}\right) &= \frac{2}{3\rho^{\gamma}} \left[Q_e - \nabla \cdot \vec{h}_e - \vec{\Pi}_e : \nabla \left(\vec{v} - \frac{\vec{J}}{en}\right)\right] + \frac{1}{en} \vec{J} \cdot \nabla \left(\frac{p_e}{\rho^{\gamma}}\right) \end{aligned}$$

The Ideal MHD Limit

- Assumptions leading to ideal MHD
- 1. Philosophy: Ideal MHD is concerned with phenomena occurring on certain length and time scales.
- 2. Ordering: Using this, we can order all the terms in the one fluid equations. After ignoring small terms, we obtain ideal MHD.
- 3. Status: At this point only the assumptions $c \rightarrow \infty$, $m_e \rightarrow 0$ have been used in the equation.
 - Characteristic length and time scales for ideal MHD

$$\frac{\partial}{\partial t} \sim \omega \sim \frac{V_{T_i}}{a}$$
$$\frac{\partial}{\partial x} \sim k \sim \nabla \sim \frac{1}{a}$$

macroscopic MHD phenomena

$$v \sim \frac{\omega}{k} \sim V_{T_i}$$

Collision dominated limit

- Isotropic pressure is expected to arise in systems where many collisions take place on a time scale short compared to those of interest. \rightarrow Maxwellian

- Evolution of full pressure tensor plays only a minor role in equilibrium and stability problems.

ons
$$\omega \tau_{ii} \sim V_{T_i} \tau_{ii} / a \ll 1$$

electrons $\omega \tau_{ee} \sim (m_e / m_i)^{1/2} V_{T_i} \tau_{ii} / a \ll 1$ $\tau_{ee} \sim (m_e / m_i)^{1/2} \tau_{ii} (T_e \sim T_i)$

 $\lambda_{\alpha} \sim V_{T_{\alpha}} \tau_{\alpha \alpha} << a$ mean free path

 $V_{T_i}\tau_{ii} / a \sim V_{T_e}\tau_{ee} / a \ll 1$

- MHD Limit
- 1. Use the collision dominated assumption to obtain ideal MHD.
- 2. Several additional assumptions will also be required.
- 3. Various moments in the equations are approximated by classical transport theory of Braginskii.
- 4. Transport coefficients can also be derived in the homework problems.
- Reduction of single fluid equation
- 1. Maxwell equations OK
- 2. Mass conservation OK
- 3. Momentum equation

$$\begin{split} \rho \frac{d\vec{v}}{dt} &- \vec{J} \times \vec{B} + \nabla p = -\nabla \cdot (\vec{\Pi}_i + \vec{\Pi}_e) \\ \vec{\Pi}_{jj} &\sim \mu \left(2\nabla_{||} \cdot \vec{v}_{||} - \frac{2}{3} \nabla \cdot \vec{v} \right) \sim \mu V_{T_i} / a \qquad \mu \sim n T_i \tau_{ii} \\ \left| \nabla \cdot \vec{\Pi}_i / \nabla p \right| \sim V_{T_i} \tau_{ii} / a <<1 \end{split}$$

Problems 2.2

- Reduction of single fluid equation
- 1. Maxwell equations OK
- 2. Mass conservation OK
- 3. Momentum equation OK
- 4. Ohm's law

$$\vec{E} + \vec{v} \times \vec{B} = \frac{1}{en} (\vec{J} \times \vec{B} - \nabla p_e - \nabla \vec{\Pi}_e + \vec{R}_e)$$

$$\frac{\left|\nabla p_{e} / en\right|}{\left|\vec{v} \times \vec{B}\right|} \sim \frac{r_{Li}}{a} <<1, \quad r_{Li} = V_{T_{i}} / \omega_{ci} \quad \omega / \omega_{ci} \sim r_{Li} / a <<1$$

$$\frac{\left|\vec{R}_{e} / en\right|}{\left|\vec{v} \times \vec{B}\right|} \sim \frac{\left|\eta \vec{J}\right|}{\left|\vec{v} \times \vec{B}\right|} \sim \frac{\left(m_{e} / m_{i}\right)^{1/2}}{\omega \tau_{ii}} \left(\frac{r_{Li}}{a}\right)^{2} <<1$$

resistivity momentum transfer due to collisions

$$\longleftarrow \frac{1}{en}\vec{R}_e \sim \eta \vec{J}, \quad \eta \sim \frac{m_e}{ne^2\tau_{ei}} \qquad \left|\vec{J}\right| \sim |\nabla p|/|\vec{E}$$

The plasma must be larger enough so that resistive diffusion does not play an important role.

- Reduction of single fluid equation
- 1. Maxwell equations OK
- 2. Mass conservation OK
- 3. Momentum equation OK
- 4. Ohm's law OK
- 5. Energy equation

$$\begin{aligned} \frac{d}{dt} \left(\frac{p_i}{\rho^{\gamma}} \right) &= \frac{2}{3\rho^{\gamma}} \left(Q_i - \nabla \cdot \vec{h}_i - \vec{\Pi}_i : \nabla \vec{v} \right) \\ \frac{d}{dt} \left(\frac{p_e}{\rho^{\gamma}} \right) &= \frac{2}{3\rho^{\gamma}} \left[Q_e - \nabla \cdot \vec{h}_e - \vec{\Pi}_e : \nabla \left(\vec{v} - \frac{\vec{J}}{en} \right) \right] + \frac{1}{en} \vec{J} \cdot \nabla \left(\frac{p_e}{\rho^{\gamma}} \right) \\ \frac{(\vec{J} \cdot \nabla p_e)/en}{\partial p_e/\partial t} &\sim \frac{r_{Li}}{a} << 1 \quad \frac{\vec{\Pi}_e : \nabla (\vec{J}/en)}{\partial p_e/\partial t} \sim \left(\frac{m_e}{m_i} \right)^{1/2} \left(\frac{r_{Li}}{a} \right)^2 \left(\frac{V_{T_i} \tau_{ii}}{a} \right) << 1 \\ \frac{\vec{\Pi}_e : \nabla \vec{v}}{\partial p_e/\partial t} \sim \left(\frac{m_e}{m_i} \right)^{1/2} \left(\frac{V_{T_i} \tau_{ii}}{a} \right) << 1 \quad \frac{\vec{\Pi}_i : \nabla \vec{v}}{\partial p_i/\partial t} \sim \left(\frac{V_{T_i} \tau_{ii}}{a} \right) << 1 \end{aligned}$$

$$\frac{d}{dt}\left(\frac{p_i}{\rho^{\gamma}}\right) = \frac{2}{3\rho^{\gamma}} \left[\nabla_{||} \cdot (\kappa_{|i} \nabla T_i) + \frac{n(T_e - T_i)}{\tau_{eq}}\right]$$

$$\frac{d}{dt}\left(\frac{p_e}{\rho^{\gamma}}\right) = \frac{2}{3\rho^{\gamma}} \left[\nabla_{||} \cdot (\kappa_{||e} \nabla T_e) - \frac{n(T_e - T_i)}{\tau_{eq}}\right]$$

To derive a single fluid model assuming small equilibration time

$$\omega \tau_{eq} \sim \omega \left(\frac{m_i}{m_e}\right)^{1/2} \tau_{ii} = \left(\frac{m_i}{m_e}\right)^{1/2} \frac{V_{T_i} \tau_{ii}}{a} << 1$$

If this is true, then

$$T_i \approx T_e = T/2, \quad p_i \approx p_e = p/2$$

$$\frac{d}{dt}\left(\frac{p}{\rho^{\gamma}}\right) = \frac{1}{3\rho^{\gamma}} \nabla_{||} \cdot \left[(\kappa_{||e} + \kappa_{||i}) \nabla_{||} T \right]$$

$$\vec{h}_{\alpha} \approx -\kappa_{\mid\mid \alpha} \nabla_{\mid\mid} T_{\alpha} \qquad \kappa_{\mid\mid} >> \kappa_{\perp}$$

Dominated by parallel thermal conduction

$$Q_i = -\frac{n(T_i - T_e)}{\tau_{eq}}$$
$$Q_e = -\frac{n(T_e - T_i)}{\tau_{eq}} + \frac{\vec{J} \cdot \vec{R}_e}{en}$$

Equilibration and Ohmic heating

$$\kappa_{||e} \sim nT_e \tau_{ee} / m_e \approx (m_i / m_e)^{1/2} \kappa_{||i|}$$

$$\frac{\nabla_{||} \cdot (\kappa_{||e} \nabla_{||} T)}{\partial p / \partial t} \sim \left(\frac{m_i}{m_e}\right)^{1/2} \frac{V_{T_i} \tau_{ii}}{a} \ll 1$$

Ideal MHD model

Mass continuity equation

$$\rho \frac{d\vec{v}}{dt} = \vec{J} \times \vec{B} - \nabla p$$

 $\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$

Single-fluid equation of motion

$$\frac{d}{dt}\left(\frac{p}{\rho^{\gamma}}\right) = 0$$

Energy equation (equation of state): adiabatic evolution

 $\vec{E} + \vec{v} \times \vec{B} = 0$

Ohm's law: perfect conductor \rightarrow "ideal" MHD

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$
$$\nabla \times \vec{B} = \mu_0 \vec{J}$$
$$\nabla \cdot \vec{B} = 0$$

Maxwell equations

Derivation of the Ideal MHD Model Summary of assumptions 1. Asymptotic: $n_e \rightarrow 0, c \rightarrow \infty$ $\pi \rightarrow p$ isotropic 2. Collision dominates: $\left(\frac{m_i}{m_e}\right)^{1/2} \frac{V_{T_i}\tau_{ii}}{a} \ll 1 - \frac{1}{\sqrt{1-1}} equilibration T_e = T_i$ $\kappa \rightarrow$ thermal conduction small if all term small electron diamagnetism small 3. Small gyro radius: $r_{ii}/a \ll 1$ small terms in energy equation ηJ in ohms law small 4. Small resistivity: $\left(\frac{m_e}{m_i}\right)^{1/2} \frac{a}{v_{\tau_i}\tau_{ii}} \left(\frac{r_{ii}}{a}\right)^2 \ll 1$ Ohmic heating small

Overall Criteria

- 1. High collisionality: $x \ll 1$ \longrightarrow $x = 3.0 \times 10^3 (T^2 / an) \ll 1$
- 2. Small gyro radius: $y << 1 \longrightarrow y = 2.3 \times 10^{-2} (\beta / na^2)^{1/2} << 1$





3. Small resistivity: $y^2/x << 1 \implies y^2/x = 1.8 \times 10^{-7} \beta/aT^2 << 1$



 β fixed(=0.05), *a*=1m, D, Λ =15



- Ideal MHD model is not valid for plasmas of fusion interest.
- Reason: collision dominated assumption breaks down
- But, large empirical evidence that MHD works very well in describing macroscopic plasma behavior.
- Question: is this the result of some subtle and perhaps unexpected physics?

- Where specifically does ideal MHD breakdown?
- 1. Momentum equation
- a. $\Pi << p$ because of collision dominated assumption
- b. $\Pi_{\perp} << p$ from collisionless theory
- c. $\Pi_{\parallel} \sim p$ parallel to the field, the motion of ions is kinetic.
- d. $\mathrel{\ddots} \mathrel{\perp}$ momentum equation OK
 - || momentum equation not accurate
- 2. Energy Equation a. collision dominated assumption $\frac{\nabla_{||} \cdot (\kappa_{||e} \nabla_{||} T)}{\partial p / \partial t} \sim \left(\frac{m_i}{m_e}\right)^{1/2} \frac{V_{T_i} \tau_{ii}}{a} << 1$
- b. $\kappa_{\parallel} \rightarrow \infty$ rather than zero in collisionless plasma
- c. More accurate equation of state \rightarrow B·VT=0
- d. \therefore energy equation not accurate

• MHD errors in the momentum and energy equation do not matter, why?

<u>_</u>

1. Momentum equation

Valid for collisionless and collisional theory

 $d\rho/dt=0$

Ohm's law and Faraday's law
$$\frac{\partial B}{\partial t} = \nabla \times \vec{v}_{\perp} \times \vec{B}$$

Note that v_{\parallel} does not appear.

- 2. Errors appear in || momentum equation and energy equation.
- 3. However, it turns out that for MHD equilibrium and most MHD instabilities, the parallel motion plays a small or negligible role. This is not obvious *a priori*.
- 4. Assuming this to be true, an incorrect treatment of parallel motion is unimportant, since no parallel motions are exerted: What is the motions are incompressible. imcompressibilty?
 - a. $B \cdot \nabla \rho = 0$ no density compression along B

b. B· ∇ T=0. $\kappa_{\parallel} \rightarrow \infty$

5. The condition $B \cdot \nabla \rho = 0$, Faraday's law and Ohm's law can be shown to imply dp/dt=0. Conservation of mass then implies $\nabla \cdot v = 0$

- Conclusion
- Once incompressibility is accepted as the dominant motion of unstable MHD modes, then errors in ideal MHD do not enter the calculation.
- Ideal MHD gives the "same" answer as "collisionless MHD".