

Week 13, 24 & 26 March

Mechanics in Energy Resources Engineering

- Chapter 9. Deflections of Beams

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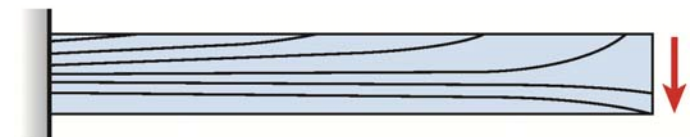
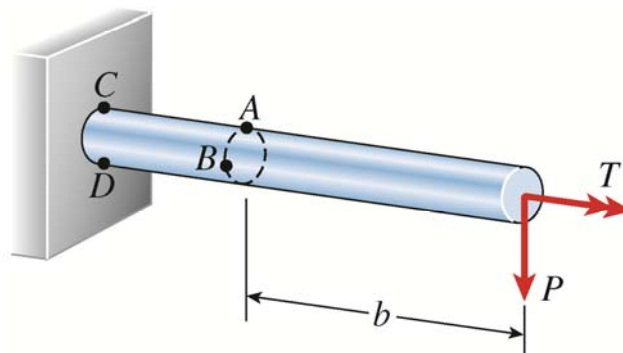
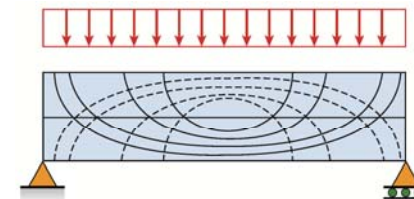
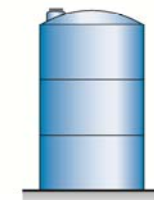
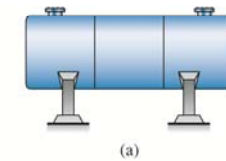
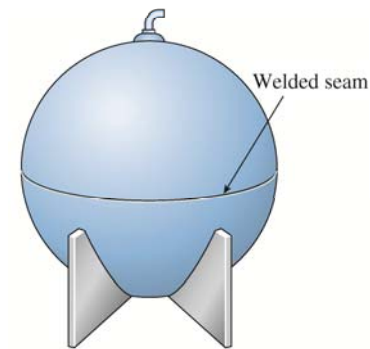
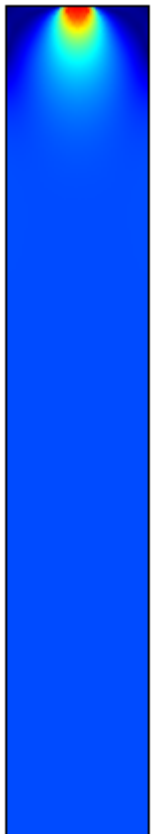
summary



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- Chapter 8: Practical Examples of plane stress or strain

- Introduction
- Spherical Pressure Vessels
- Cylindrical Pressure Vessels
- Maximum Stresses in Beams
- Combined Loadings



Useful Web Courses



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-
- <http://ocw.mit.edu/OcwWeb/web/home/home/index.htm>
 - <http://nptel.iitm.ac.in/>
 - <http://nptel.iitm.ac.in/video.php?courseId=1053>:
strength of materials

Deflections of Beams



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-
- Introduction
 - Differential Equations of the Deflection Curve (처짐곡선의 미분방정식)
 - Deflections by Integration of the Bending-Moment Equation (굽힘모멘트 방정식의 적분에 의한 처짐)
 - Deflections by Integration of the Shear-Force and Load Equations (전단력과 하중방정식의 적분에 의한 처짐)
 - Method of Superposition (중첩법)
 - Moment-Area Method (모멘트-면적법)
 - Nonprismatic Beams (불균일단면 보)

Introduction



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- A beam loaded by lateral forces \rightarrow axis is deformed into a curve \rightarrow deflection
- Chapter 5 Stresses in beams: curvature \rightarrow normal stresses and strains. Not the deflection curve itself.
- Finding deflections
 - Serviceability requirement
 - Useful for analysis of statically indeterminate structure
 - Important for dynamic analyses

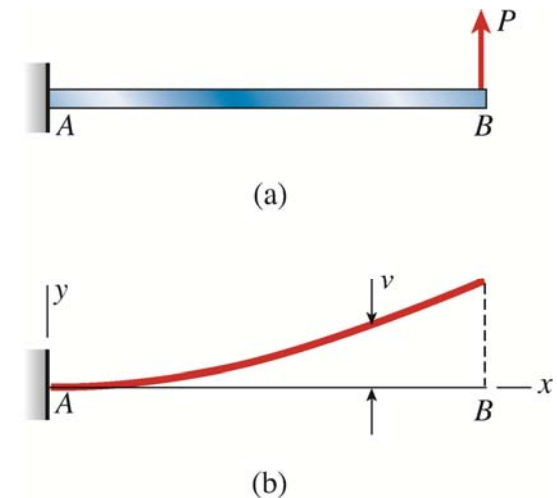


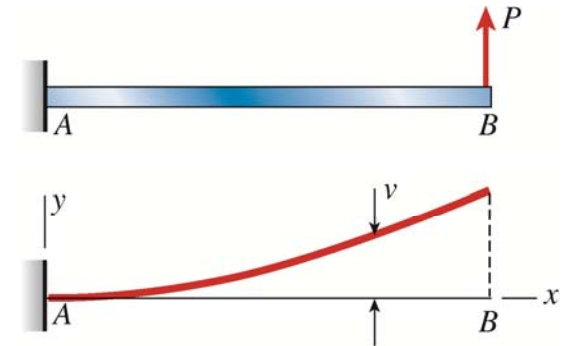
FIG. 9-1 Deflection curve of a cantilever beam

Differential Equations of the deflection curve

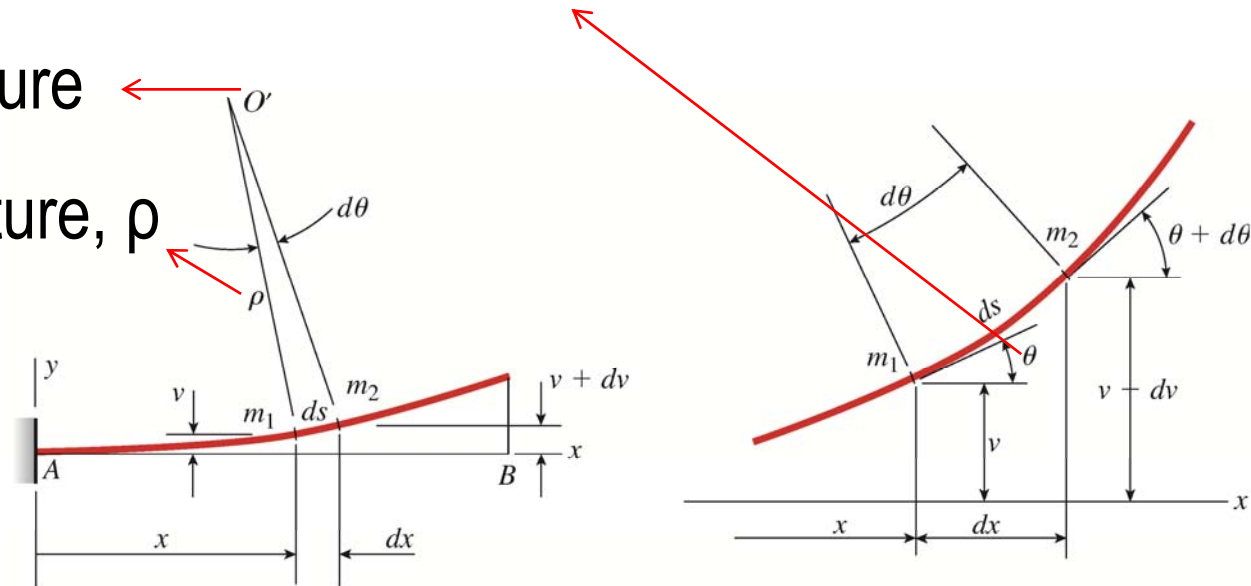


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- Deflection (처짐) v
 - displacement in y -direction. (+) \uparrow
- Angle of rotation (회전각), θ
 - angle between x -axis and the tangent to the deflection curve.



- Center of Curvature
- Radius of Curvature, ρ





Curvature of a Beam

- From the geometry of triangle $O'm_1m_2$,

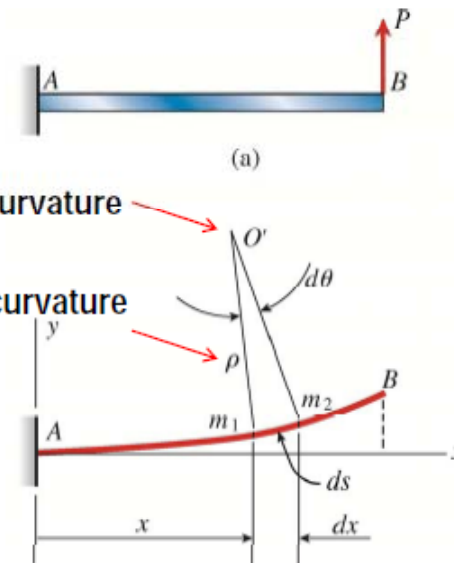
$$\rho d\theta = ds$$

- By rearranging,

$$\kappa = \frac{1}{\rho} = \frac{d\theta}{ds}$$

- Under the assumption of small deflections \rightarrow deflection curve is nearly flat

$$\kappa = \frac{1}{\rho} = \frac{d\theta}{dx}$$



– From chapter 5 Stresses in beams

Differential Equations of the deflection curve



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- Expression for Curvature κ & Angle of rotation

$$\kappa = \frac{1}{\rho} = \frac{d\theta}{ds}$$

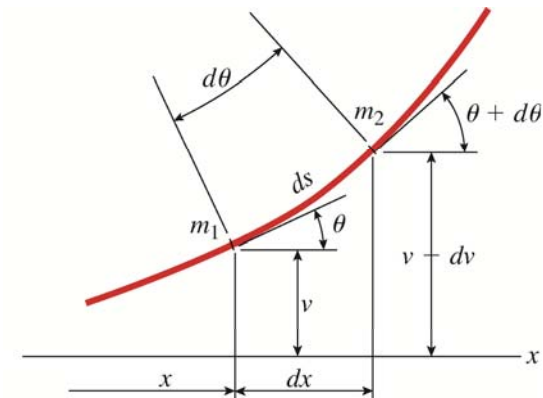
$$\frac{dv}{dx} = \tan \theta$$

- With small θ , v & $\kappa \rightarrow ds \approx dx, \theta \approx \tan \theta$

$$\kappa = \frac{1}{\rho} = \frac{d\theta}{dx}$$

$$\theta = \frac{dv}{dx} \longrightarrow$$

$$\kappa = \frac{1}{\rho} = \frac{d^2v}{dx^2}$$



- If a material is linearly elastic and follows Hooke's law

$$\kappa = \frac{1}{\rho} = \frac{M}{EI}$$

Moment-curvature relationship

- Differential equation of the deflection curve of a beam

$$\frac{d^2v}{dx^2} = \frac{M}{EI}$$

or

$$EI \frac{d^2v}{dx^2} = M$$

or

$$EIv'' = M$$

Differential Equations of the deflection curve



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- Differential equation of the deflection curve of a beam
 - Deflection v can be found with known bending moment M and flexural rigidity EI as functions of x .

$$\frac{d^2v}{dx^2} = \frac{M}{EI}$$

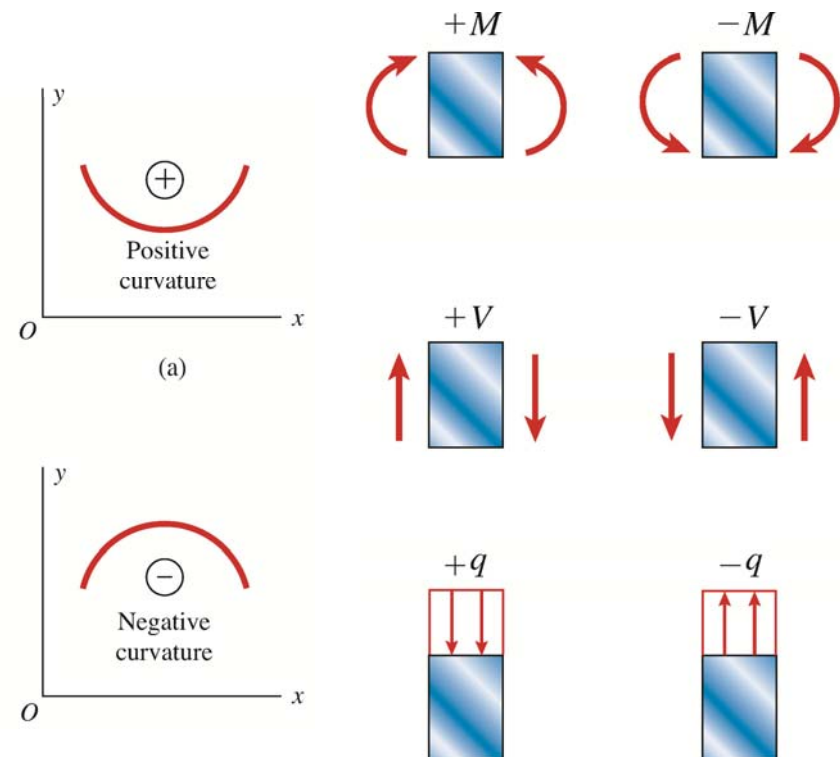
- Sign conventions:

$\propto v \uparrow (+)$

$\propto \theta$ counterclockwise (+)

$\propto \kappa$ concave upward (+)

$\propto M$ compression upper part (+)



Additional equations for M, V and q



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- Relations between bending moment M, shear force V, and intensity q of distributed load

$$\frac{dV}{dx} = -q \qquad \frac{dM}{dx} = V$$

- Through rearrangement

$$\begin{array}{l} \frac{d}{dx} \left(EI_x \frac{d^2 v}{dx^2} \right) = \frac{dM}{dx} = V \\ \frac{d^2}{dx^2} \left(EI_x \frac{d^2 v}{dx^2} \right) = \frac{dV}{dx} = -q \end{array} \xrightarrow[\text{Constant EI}]{\text{Prismatic beam}} \begin{array}{l} EI \frac{d^3 v}{dx^3} = V \\ EI \frac{d^4 v}{dx^4} = -q \end{array}$$

Differential equations of the deflection curve

Exact Expression for Curvature



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- With large slopes of deflection curve

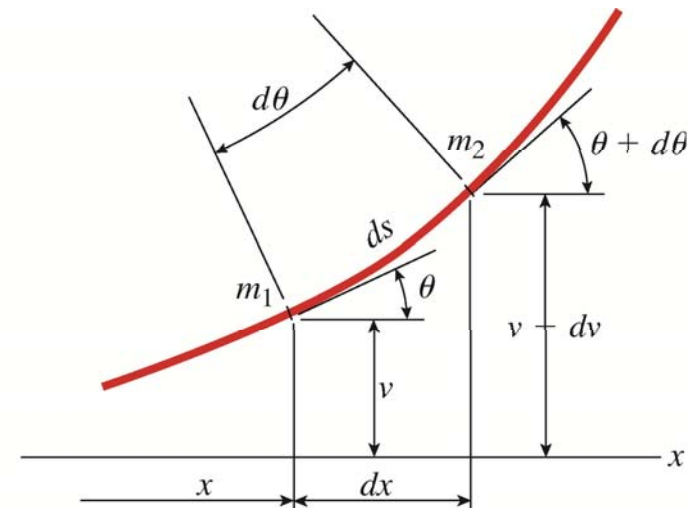
$$\kappa = \frac{1}{\rho} = \frac{d\theta}{ds} = \frac{d(\arctan v')}{dx} \frac{dx}{ds}$$

$$ds^2 = dx^2 + dv^2$$

$$\frac{ds}{dx} = \left[1 + \left(\frac{dv}{dx} \right)^2 \right]^{1/2} = \left[1 + (v')^2 \right]^{1/2}$$

$$\frac{d(\arctan v')}{dx} = \frac{v''}{1 + (v')^2}$$

$$\kappa = \frac{1}{\rho} = \frac{v''}{\left[1 + (v')^2 \right]^{3/2}}$$



With small θ

$$\kappa = \frac{1}{\rho} = v''$$

Deflections by integration of the differential equation



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$$EI \frac{d^2 v}{dx^2} = EI v'' = M$$

Bending-moment equation

$$EI \frac{d^3 v}{dx^3} = EI v''' = V$$

Shear-force equation

$$EI \frac{d^4 v}{dx^4} = EI v'''' = -q$$

Load equation

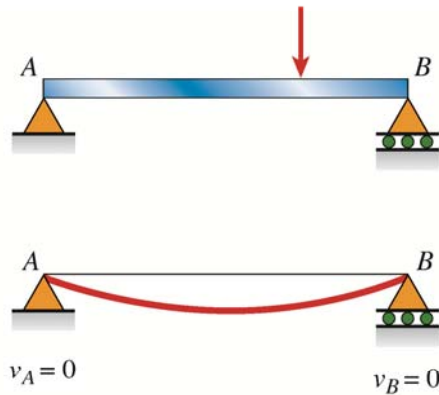
- Start from any equation that you want
- Deflections can be obtained by integrating above equations
 - ↻ Boundary condition
 - ↻ Continuity condition
 - ↻ Symmetry condition

Deflections by integration of the Bending-Moment Equation

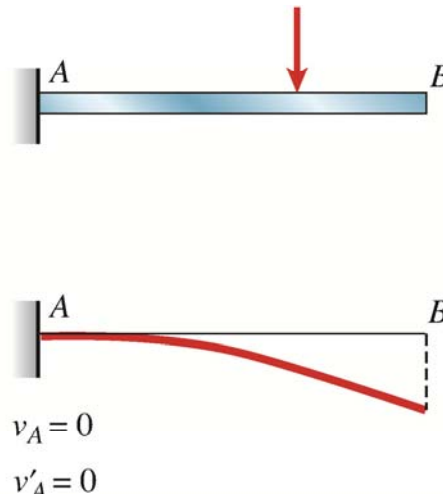


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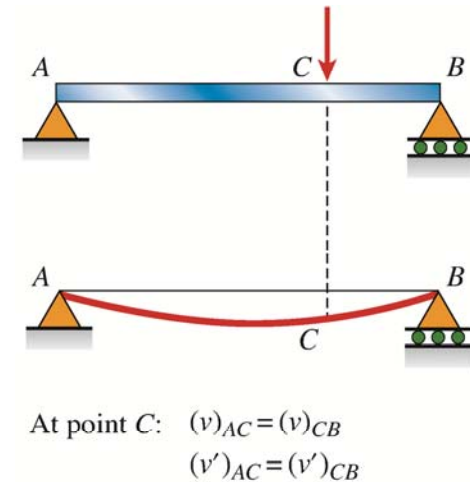
- Boundary, Continuity & Symmetry conditions



Boundary condition at a simple support



Boundary condition at a fixed support



Continuity conditions at point C

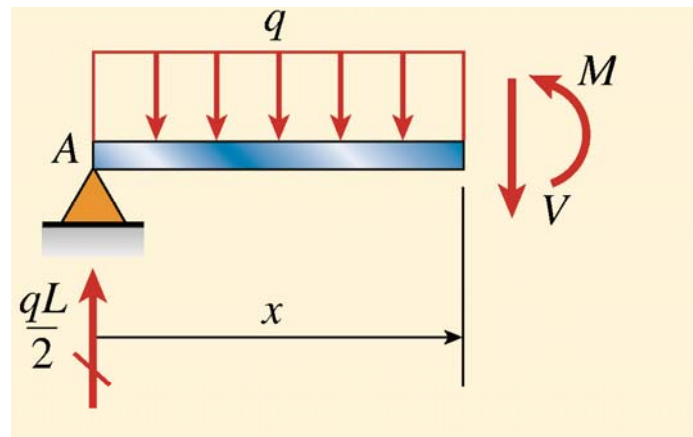
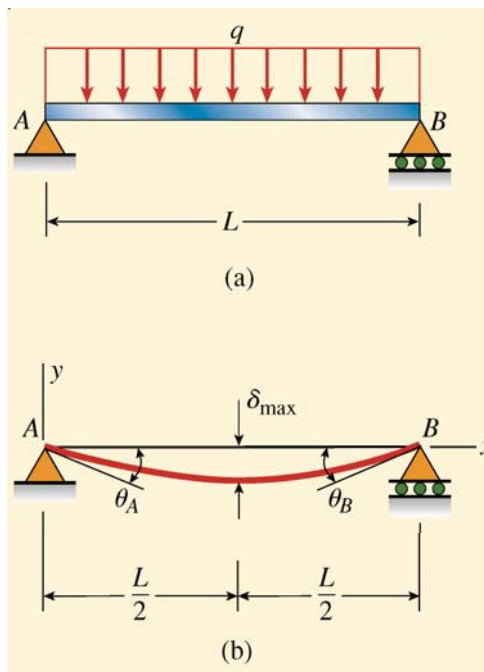
- **Symmetry Conditions:** additional equation by inspection
 e.g.) simple beam under uniform load throughout its length



Example 9-1

Deflection curve for a simple beam under a uniform load

- Equation of deflection curve?
- Maximum deflection at the midpoint?
- Angles of rotation at the supports?





Example 9-2

Deflection curve for a cantilever beam under a uniform load

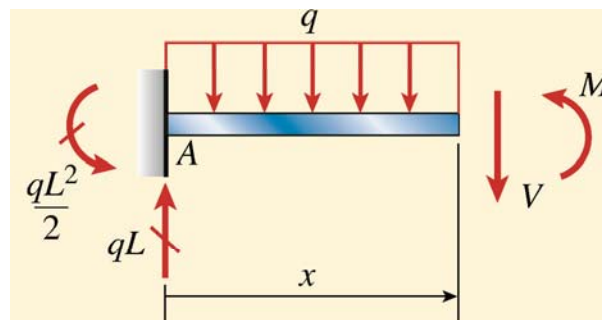
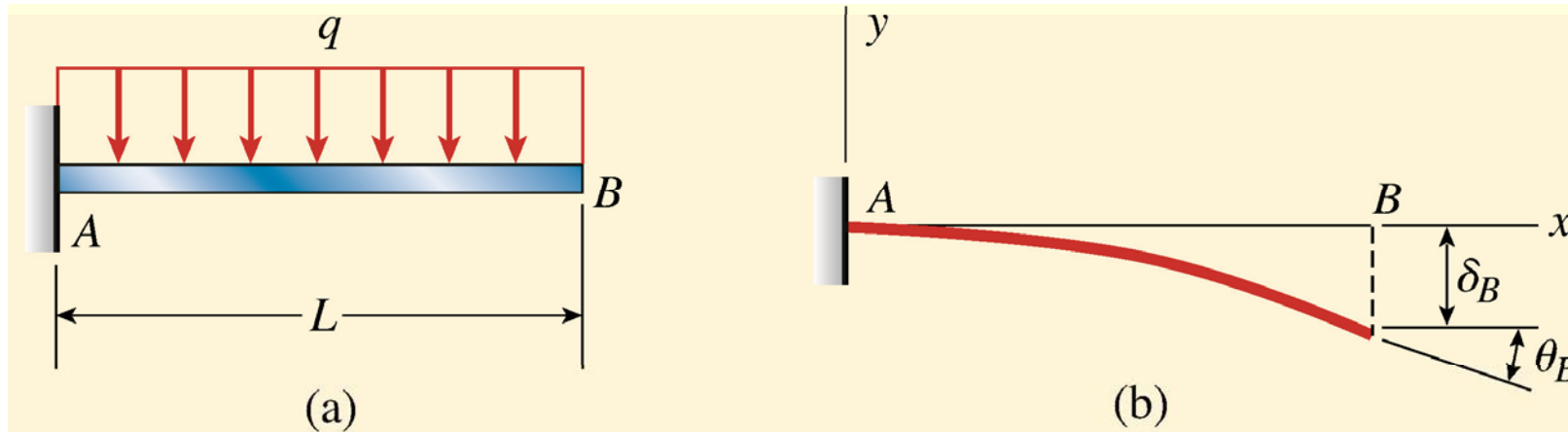
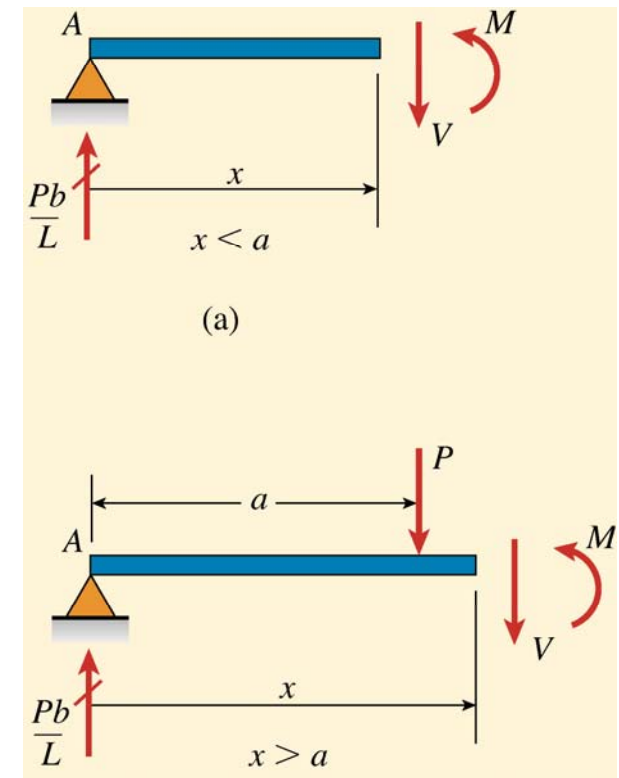
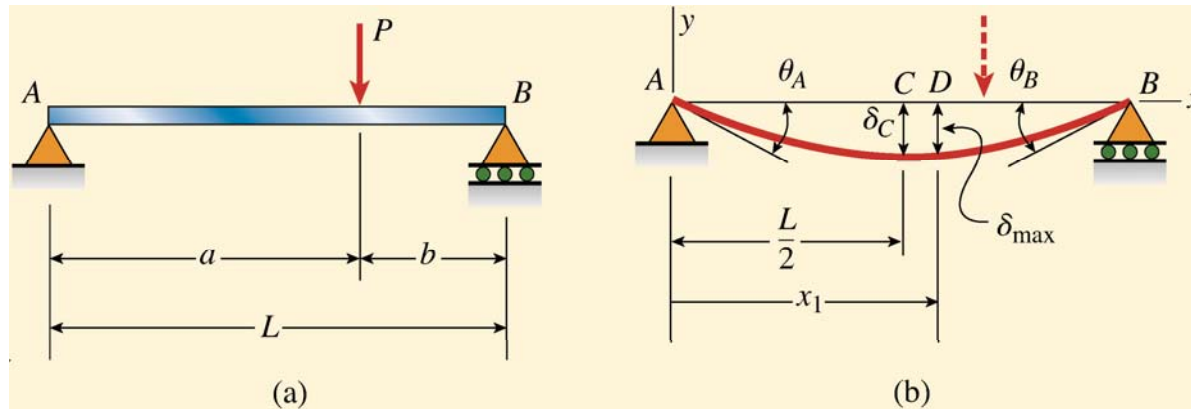


FIG. 9-11 Free-body diagram used in determining the bending moment M (Example 9-2)

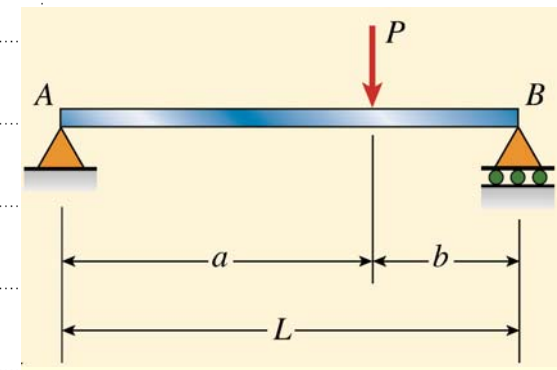
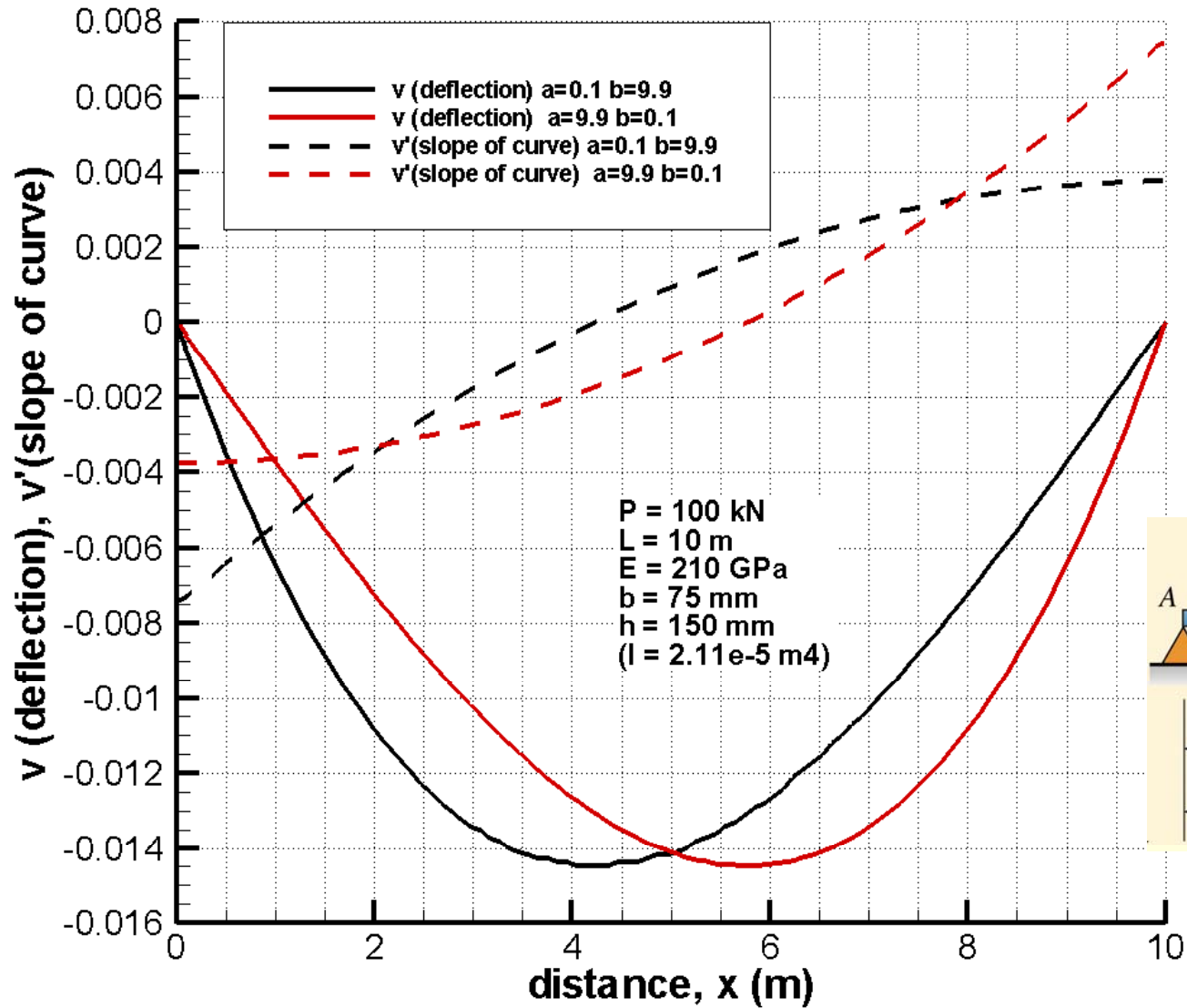


Example 9-3

Deflection curve for a simple beam under a concentrated load



Example 9-3



On Monday

Deflections by integration of the differential equation



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$$EI \frac{d^2 v}{dx^2} = EI v'' = M$$

Bending-moment equation

$$EI \frac{d^3 v}{dx^3} = EI v''' = V$$

Shear-force equation

$$EI \frac{d^4 v}{dx^4} = EI v'''' = -q$$

Load equation

- Start from any equation that you want
- Deflections can be obtained by integrating above equations
 - ↻ Boundary condition
 - ↻ Continuity condition
 - ↻ Symmetry condition

Deflections by integration of the shear-force & Load equations



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- We may start from shear force V or load q
 - This may be more convenient to some of you.

$$EI \frac{d^3 v}{dx^3} = EIv''' = V$$

Shear-force equation

$$EI \frac{d^4 v}{dx^4} = EIv'''' = -q$$

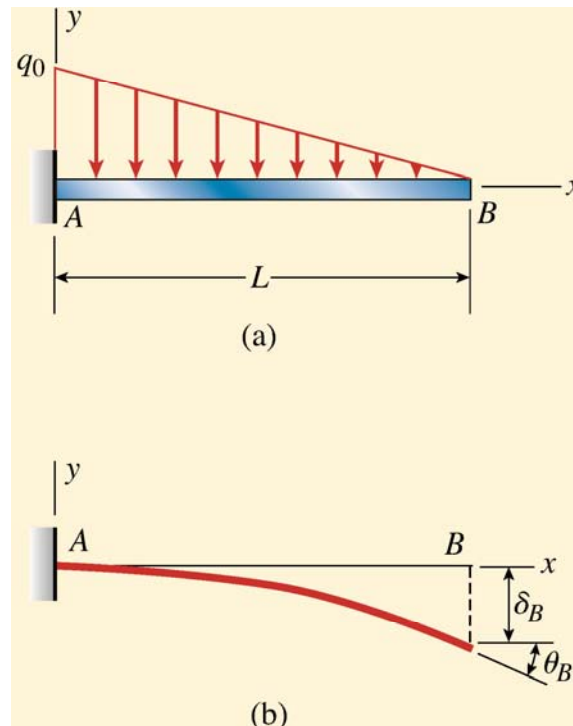
Load equation



Deflections by integration of the shear-force & Load equations

Example 9-4

- Equations of the Deflection curve?
- Deflection and angle of rotation at the free end?

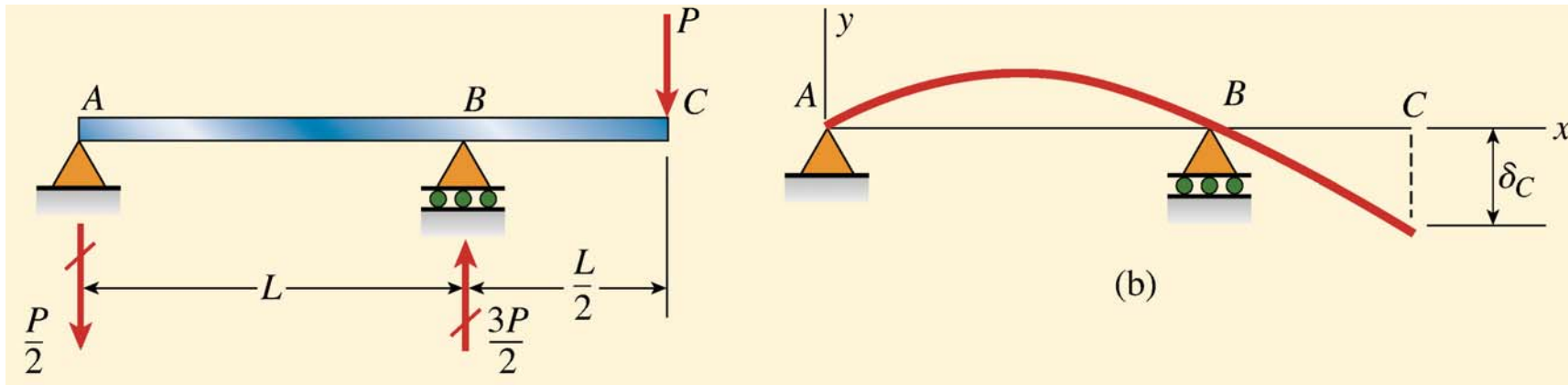




Deflections by integration of the shear-force & Load equations

Example 9-5

- Equations of the Deflection curve?
- Deflection and angle of rotation at the free end?



Method of Superposition



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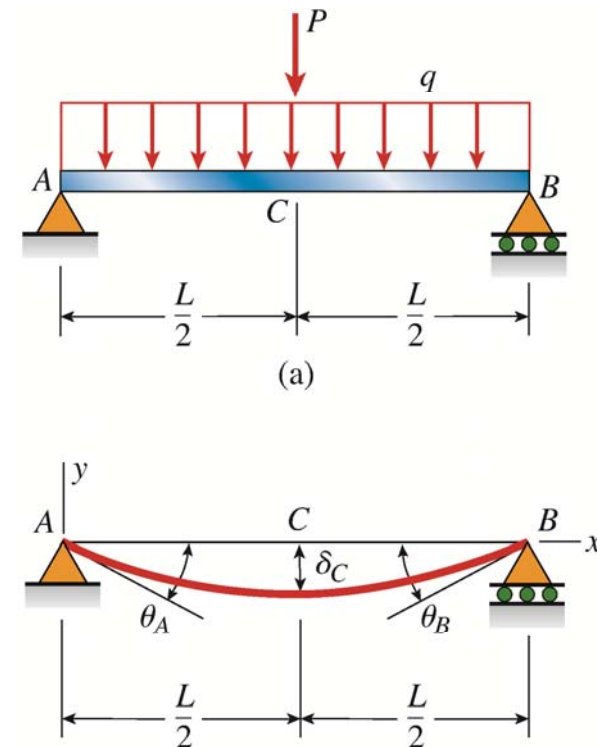
- Method of Superposition:
 - Deflections by different load can be found by superposition.
 - E.g.) v_1 due to q_1 , v_2 due to q_2
 $q_1 + q_2 \rightarrow v_1 + v_2$
 - Condition: *linear* differential equation

$$\delta_c = (\delta_c)_1 + (\delta_c)_2$$

Contribution from concentrated loading

$$\theta_A = (\theta_A)_1 + (\theta_A)_2$$

Contribution from distributed loading



Method of Superposition



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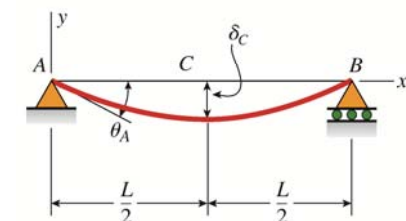
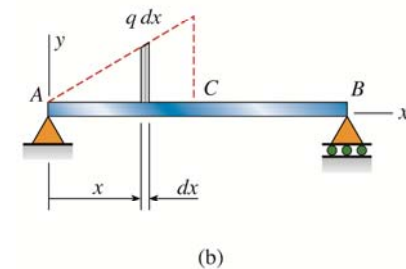
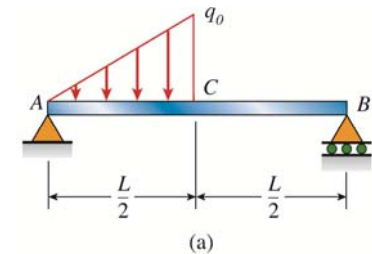
- Table is useful for calculation of deflection & rotation angles
- Superposition may be used for a type that is not available in the table

- qdx may be seen as a concentrated load
- Deflection of concentrated load

$$\delta_C = \frac{Pa(3L^2 - 4a^2)}{48EI}$$

$$qdx \leftarrow P \quad a \leftarrow x \quad q = \frac{2q_0x}{L}$$

$$d\delta_C = \frac{q_0x^2}{24LEI} (3L^2 - 4x^2) dx$$



Appendix G. Table G-2



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4

$$v = -\frac{Px}{48EI}(3L^2 - 4x^2) \quad v' = -\frac{P}{16EI}(L^2 - 4x^2) \quad \left(0 \leq x \leq \frac{L}{2}\right)$$

$$\delta_C = \delta_{\max} = \frac{PL^3}{48EI} \quad \theta_A = \theta_B = \frac{PL^2}{16EI}$$

5

$$v = -\frac{Pbx}{6LEI}(L^2 - b^2 - x^2) \quad v' = -\frac{Pb}{6LEI}(L^2 - b^2 - 3x^2) \quad (0 \leq x \leq a)$$

$$\theta_A = \frac{Pab(L+b)}{6LEI} \quad \theta_B = \frac{Pab(L+a)}{6LEI}$$

If $a \geq b$, $\delta_C = \frac{Pb(3L^2 - 4b^2)}{48EI}$ If $a \leq b$, $\delta_C = \frac{Pa(3L^2 - 4a^2)}{48EI}$

If $a \geq b$, $x_1 = \sqrt{\frac{L^2 - b^2}{3}}$ and $\delta_{\max} = \frac{Pb(L^2 - b^2)^{3/2}}{9\sqrt{3}LEI}$

6

$$v = -\frac{Px}{6EI}(3aL - 3a^2 - x^2) \quad v' = -\frac{P}{2EI}(aL - a^2 - x^2) \quad (0 \leq x \leq a)$$

$$\theta_A = \frac{Pab(L+b)}{6LEI}$$

If $a \leq b$, $\delta_C = \frac{Pa(3L^2 - 4a^2)}{48EI}$

$$\delta_C = \frac{M_0L^2}{16EI} \quad \theta_A = \frac{M_0L}{3EI} \quad \theta_B = \frac{M_0L}{6EI}$$

$$x_1 = L\left(1 - \frac{\sqrt{3}}{3}\right) \quad \text{and} \quad \delta_{\max} = \frac{M_0L^2}{9\sqrt{3}EI}$$

8

$$v = -\frac{M_0x}{24LEI}(L^2 - 4x^2) \quad v' = -\frac{M_0}{24LEI}(L^2 - 12x^2) \quad \left(0 \leq x \leq \frac{L}{2}\right)$$

$$\delta_C = 0 \quad \theta_A = \frac{M_0L}{24EI} \quad \theta_B = -\frac{M_0L}{24EI}$$

$$\theta_A = \frac{Pab(L+b)}{6LEI}$$

If $a \leq b$, $\delta_C = \frac{Pa(3L^2 - 4a^2)}{48EI}$

Method of Superposition



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- Total deflection can be obtained by superposing all the contribution of concentrated load

$$\delta_C = \int d\delta_C = \int_0^{L/2} \frac{q_0 x^2}{24LEI} (3L^2 - 4x^2) dx = \frac{q_0}{24LEI} \int_0^{L/2} (3L^2 - 4x^2) x^2 dx = \frac{q_0 L^4}{240LEI}$$

- Similarly rotation of angle can be obtained.

$$\theta_A = \frac{Pab(L + b)}{6LEI}$$

$$qdx \leftarrow P$$

$$a \leftarrow x$$

$$q = \frac{2q_0 x}{L}$$

$$b \leftarrow (L - x)$$

$$\theta_A = \int_0^{L/2} \frac{q_0}{3L^2 EI} (L - x)(2L - x)x^2 dx = \frac{41q_0 L^3}{2880EI}$$

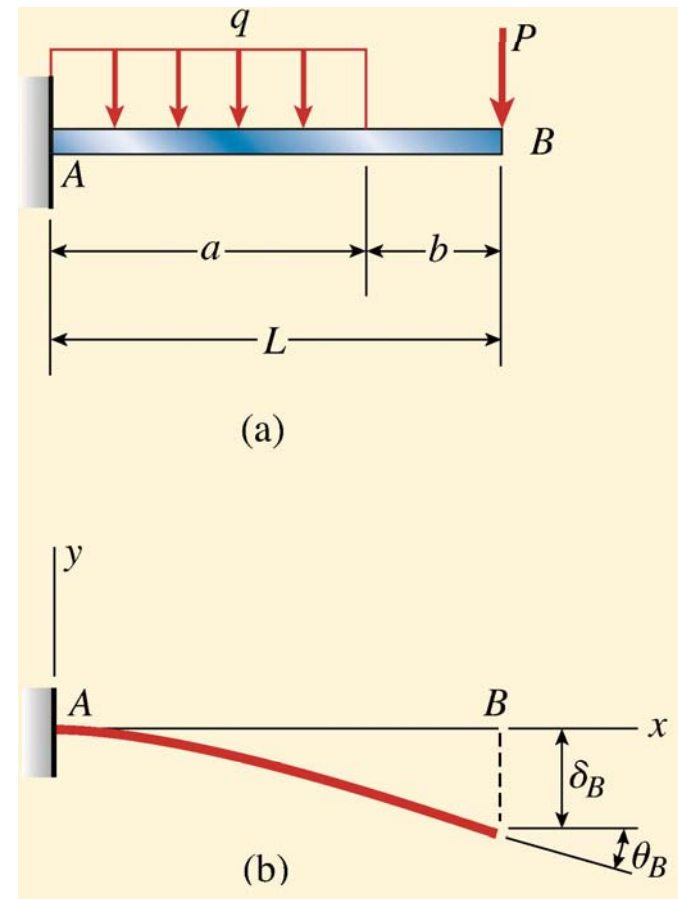
Method of Superposition

Example 9-6



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- θ_B & δ_B ?
- Refer to Appendix G. Table G-2



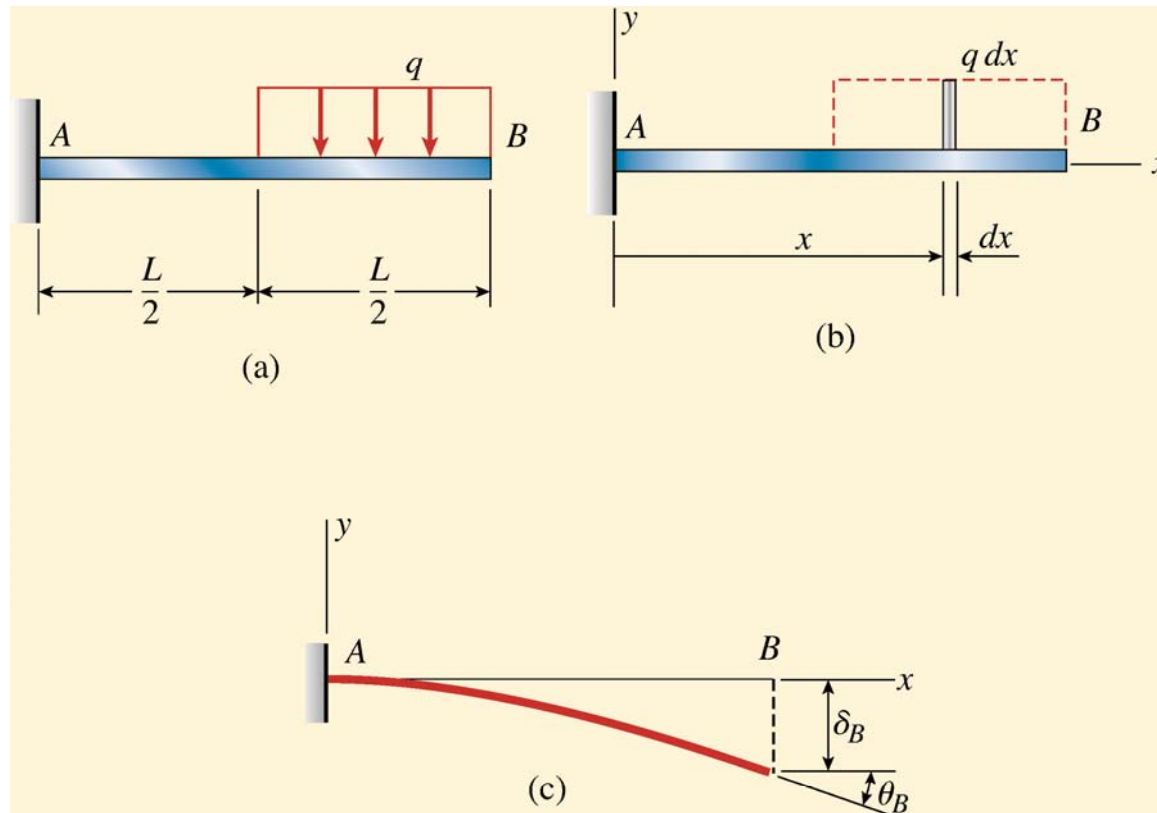
Method of Superposition

Example 9-7



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- θ_B & δ_B ?



Moment-Area method

First Moment-Area Theorem



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- From geometry (assuming a small angle of rotation)

$$\kappa = \frac{1}{\rho} = \frac{d\theta}{dx}$$

$$\kappa = \frac{1}{\rho} = \frac{M}{EI}$$

- Two points m_1 & m_2 small distance apart

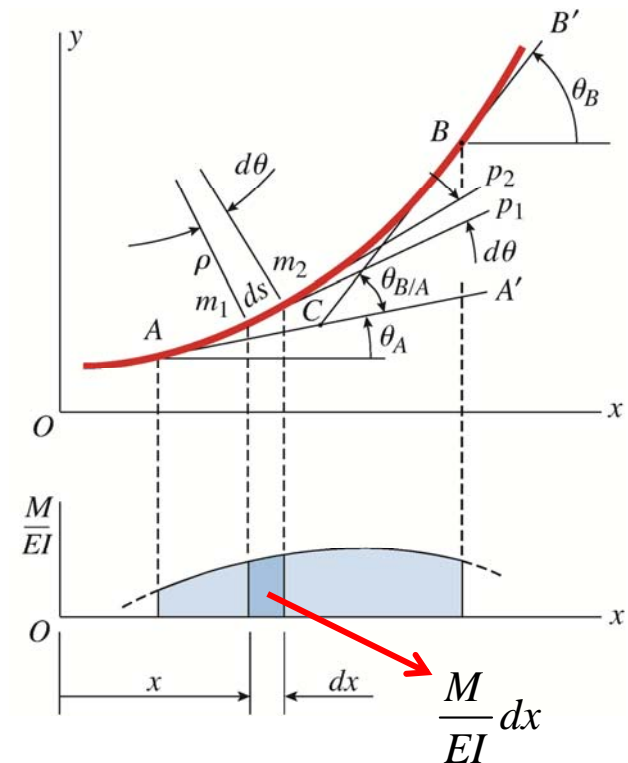
$$d\theta = \frac{M}{EI} dx$$

Area of the M/EI diagram
between points A and B

$$\int_A^B d\theta = \theta_B - \theta_A = \theta_{B/A} = \int_A^B \frac{M}{EI} dx$$

First Moment-Area Theorem:

The angle $\theta_{B/A}$ = the area of the M/EI Diagram



Moment-Area method

Second Moment-Area Theorem



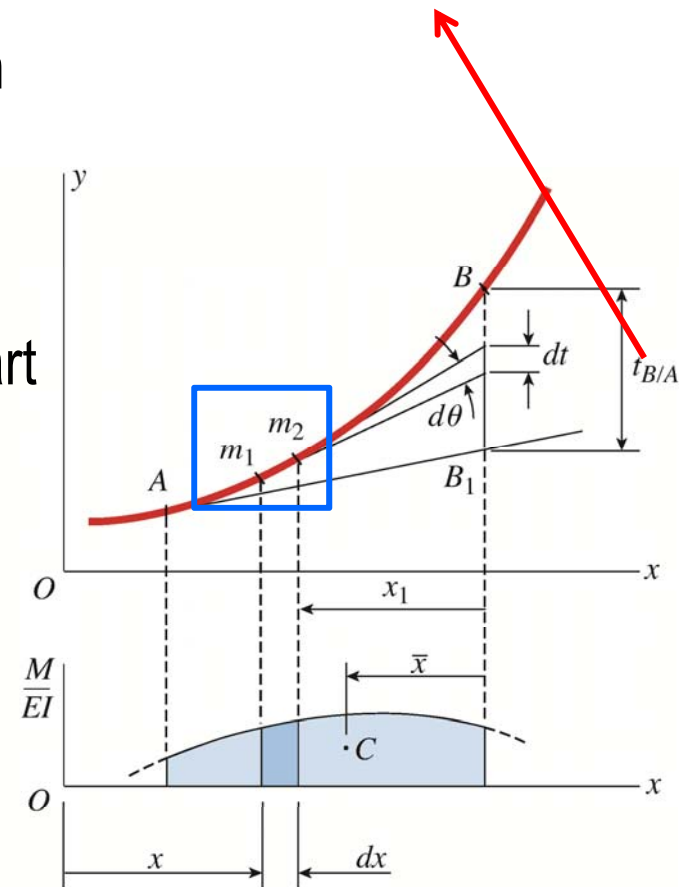
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- Tangential deviation
 - Vertical deviation of B on the deflection curve from the tangent at A
 - (+) when B is above
 - Two points m_1 & m_2 small distance apart

$$dt = x_1 d\theta = x_1 \frac{M}{EI} dx$$

Deviation due to bending of element $m_1 m_2$
 = first moment of the area of the shaded strip

Tangential deviation of B with respect to A



Moment-Area method

Second Moment-Area Theorem



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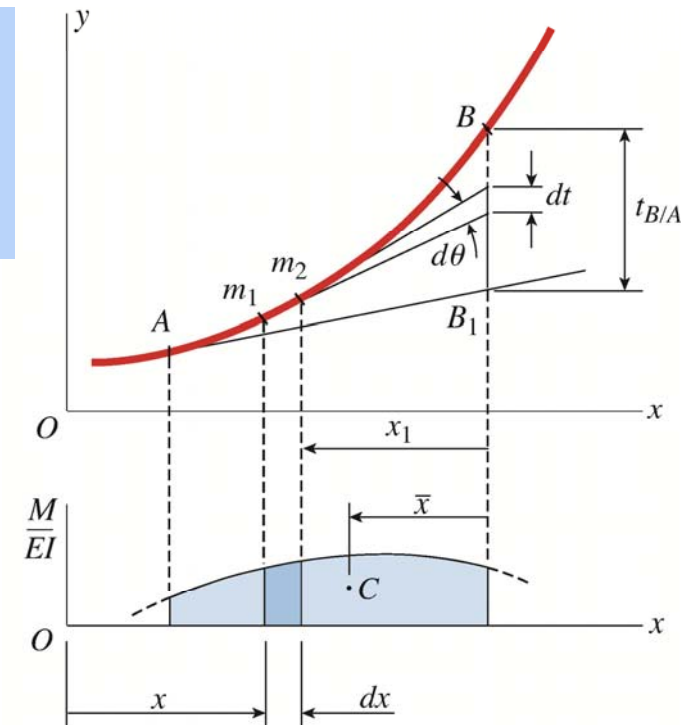
- By integrating

$$\int_A^B dt = t_{B/A} = \int_A^B x_1 \frac{M}{EI} dx$$

Second Moment-Area Theorem:

Tangential deviation $t_{B/A}$ = first moment of the area of M/EI diagram between A and B

- (+) $M \rightarrow$ B is above A
- (-) $M \rightarrow$ B is below A
- First moment of the area of the M/EI diagram: area x centroid C



Moment-Area method

Example 9-10



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- θ_B & δ_B ?

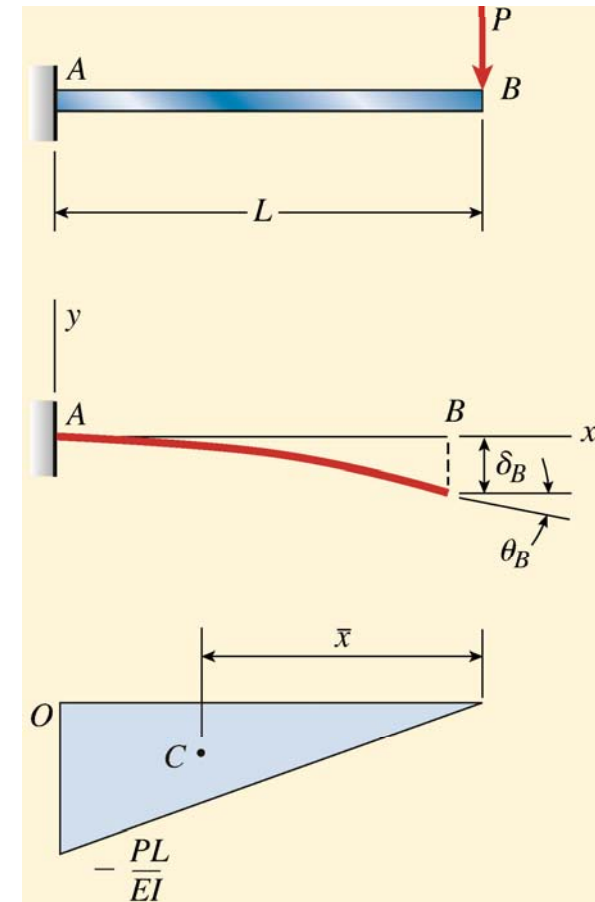


FIG. 9-24 Example 9-10. Cantilever beam with a concentrated load

Moment-Area method

Example 9-11



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- θ_B & δ_B ?

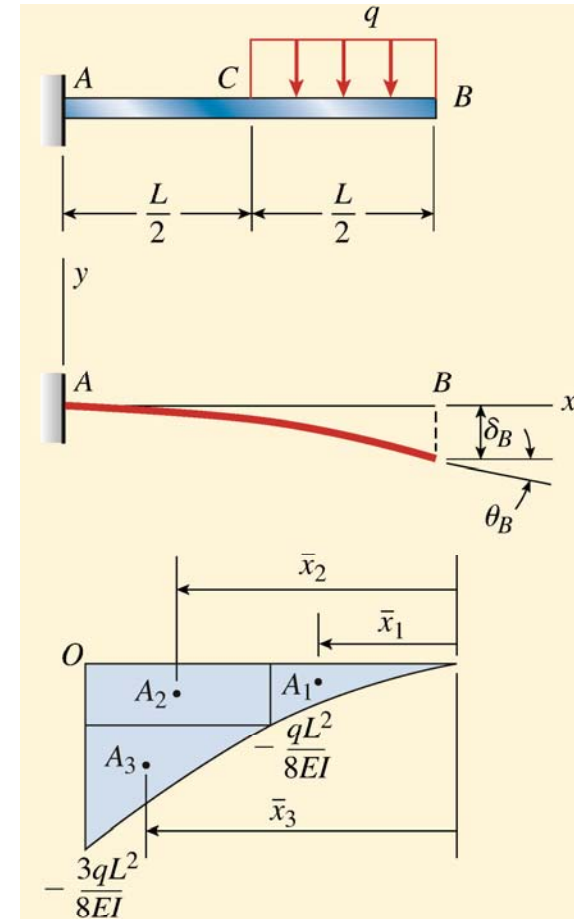


FIG. 9-25 Example 9-11. Cantilever beam supporting a uniform load on the right-hand half of the beam

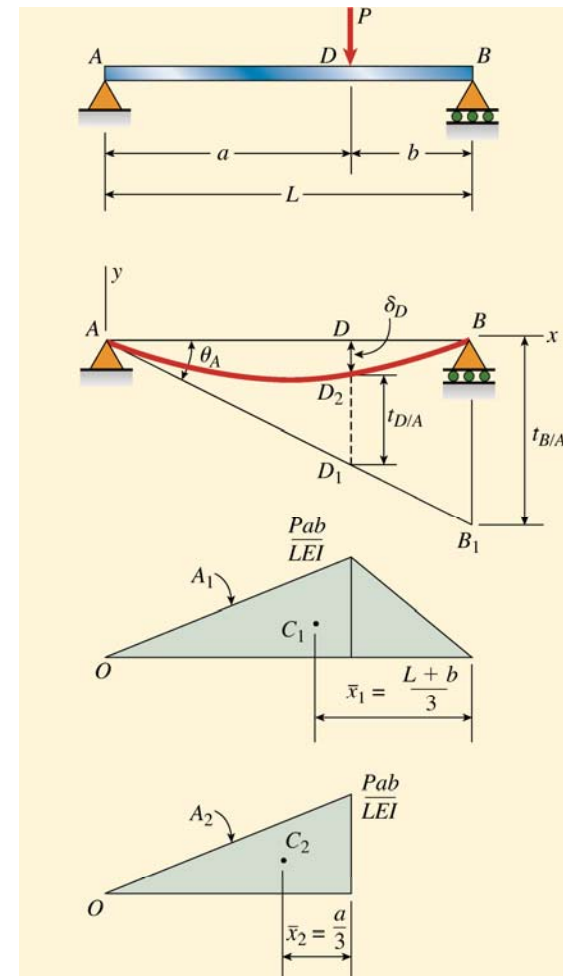
Moment-Area method

Example 9-12



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- θ_A & δ_D ?

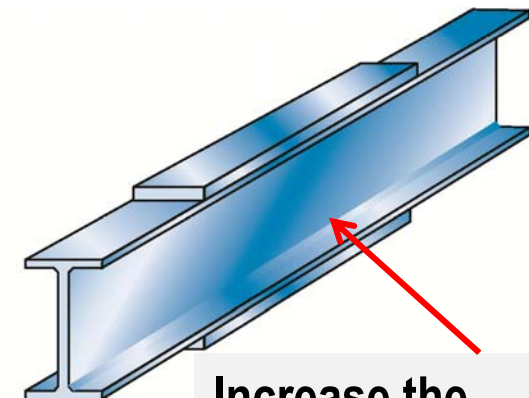


Nonprismatic beams



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- Beams having varying moments of inertia
 - No new concept is needed
 - Not always work by analytical method
 - Analysis could be more complex

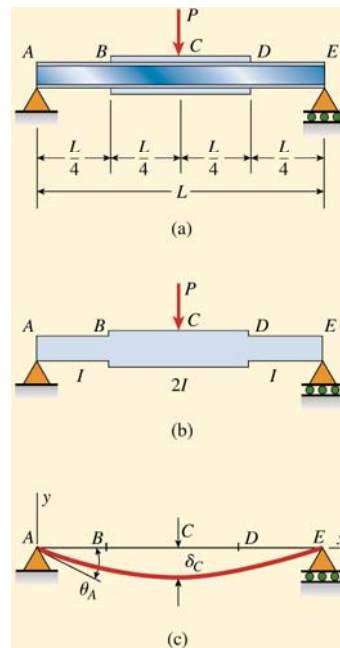


**Increase the
moment of inertia
← M is largest**

Nonprismatic beams



- Example 9-13
 - Cover plate doubles the moment of inertia
 - θ_A & δ_C ?



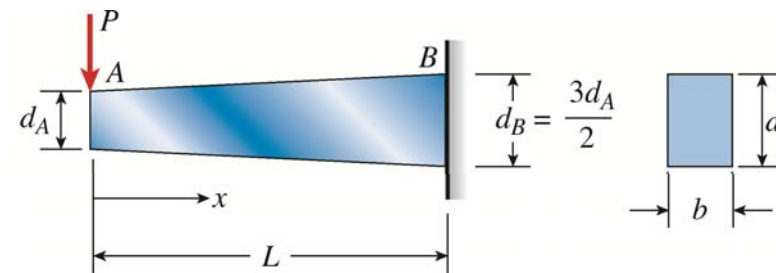
- Prob 9.7-9

$$d = \frac{d_A}{2L}(2L + x)$$

$$I = \frac{bd^3}{12} = \frac{bd_A^3}{96L^3}(2L + x)^3 = \frac{I_A}{8L^3}(2L + x)^3$$

- θ_A & δ_C ?

$$M = -Px$$



PROB. 9.7-9

Deflections of Beams



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- Introduction
 - Differential Equations of the Deflection Curve (처짐곡선의 미분방정식)
 - Deflections by Integration of the Bending-Moment Equation (굽힘모멘트 방정식의 적분에 의한 처짐)
 - Deflections by Integration of the Shear-Force and Load Equations (전단력과 하중방정식의 적분에 의한 처짐)
 - Method of Superposition (중첩법)
 - Moment-Area Method (모멘트-면적법)
 - Nonprismatic Beams (불균일단면 보)