

Lecture Note 1

I. Solution of One-Dimensional, One-Group Neutron Diffusion Equation

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1D 1G Neutron Diffusion Equation

- Neutron Diffusion Equation

$$\frac{dJ(x)}{dx} + \Sigma_a(x)\phi(x) = \lambda \cdot v\Sigma_f(x)\phi(x), \quad \lambda = \frac{1}{k_{eff}}$$

Fick's Law: $J(x) = -D(x) \frac{d\phi(x)}{dx} \rightarrow -\frac{d}{dx} \left(D(x) \frac{d\phi(x)}{dx} \right) + \Sigma_a(x)\phi(x) = \lambda v\Sigma_f(x)\phi(x)$

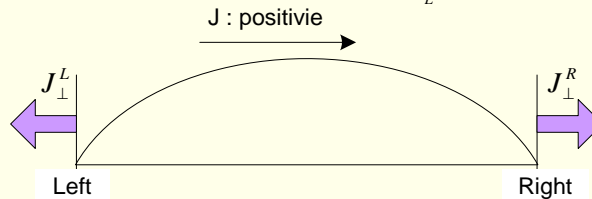
- Boundary condition with Albedo

– Right ($x = x_R$)

1) $\alpha_R = \frac{J_{\perp}^R}{\phi}$ 2) $J_{\perp}^R = J|_{x=x_R} = -D \frac{d\phi}{dx} \Big|_{x=x_R} \rightarrow D \frac{d\phi}{dx} + \alpha_R \phi = 0$ (Robin condition)

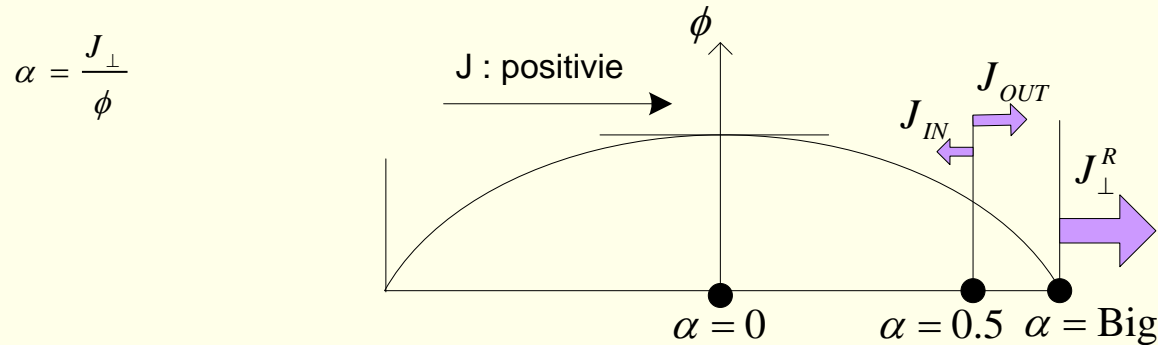
– Left ($x = x_L$)

1) $\alpha_L = \frac{J_{\perp}^L}{\phi}$ 2) $J_{\perp}^L = -J|_{x=x_L} = -\left(-D \frac{d\phi}{dx}\right) = D \frac{d\phi}{dx} \Big|_{x=x_L} \rightarrow -D \frac{d\phi}{dx} + \alpha_L \phi = 0$



- Homogeneous D.E. with Homogeneous B.C \rightarrow Homogeneous problem, Eigenvalue problem

Albedos for Various Boundary Conditions



a) $\alpha = 0 \quad \rightarrow \quad J = -D \frac{d\phi}{dx} = 0 \quad : \text{ Reflective BC}$

b) $\alpha = \infty \quad \rightarrow \quad \phi = 0 \quad : \text{ Zero-flux BC}$

c) $\alpha = 0.5 \quad \rightarrow \quad J_{IN} = 0 \quad : \text{ Zero-incoming current BC}$

$$\varphi(\mu) = \frac{1}{2}\phi + \frac{3}{2}J\mu \quad \Rightarrow \quad \begin{cases} J_{IN} = \int_0^{-1} \varphi(\mu)\mu \, d\mu = \frac{1}{4}\phi - \frac{1}{2}J \\ J_{OUT} = \int_0^1 \varphi(\mu)\mu \, d\mu = \frac{1}{4}\phi + \frac{1}{2}J \end{cases} \quad (\mu = \cos\theta)$$

$$J_{IN} = 0 \quad \Leftrightarrow \quad \frac{1}{4}\phi - \frac{1}{2}J = 0 \quad \Leftrightarrow \quad \alpha = \frac{J}{\phi} = 0.5$$

Positiveness of Eigenvalue

- Neutron Diffusion Equation

$$-\frac{d}{dx} \left(D \frac{d\phi}{dx} \right) + \Sigma_a \phi = \lambda \cdot \nu \Sigma_f \phi$$

– Multiply $\phi(x)$

$$-\frac{d}{dx} \left(D \frac{d\phi}{dx} \right) \cdot \phi + \Sigma_a \phi \cdot \phi = \lambda \cdot \nu \Sigma_f \phi \cdot \phi$$

– Integrate above eqn. over $[x_L, x_R]$

$$A = \int_{x_L}^{x_R} \left[-\frac{d}{dx} \left(D \frac{d\phi}{dx} \right) \cdot \phi \right] dx = -D \frac{d\phi}{dx} \cdot \phi \Big|_{x_L}^{x_R} + \int_{x_L}^{x_R} D \frac{d\phi}{dx} \cdot \frac{d\phi}{dx} dx = \alpha_R \phi_R^2 + \alpha_L \phi_L^2 + \int_{x_L}^{x_R} D \left(\frac{d\phi}{dx} \right)^2 dx > 0$$

$$B = \int_{x_L}^{x_R} [\Sigma_a \phi \cdot \phi] dx > 0$$

$$C = \int_{x_L}^{x_R} [\nu \Sigma_f \phi \cdot \phi] dx > 0$$

$$\lambda = \frac{A + B}{C} > 0 \quad (\text{Always})$$

physically λ is an adjustment factor for nontrivial solution

1D Problem in Other Coordinates

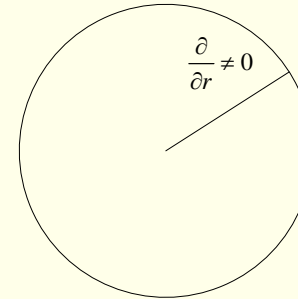
- Extension of 1-D to other coordinates

$$\nabla \cdot J = -\nabla \cdot D \nabla \phi = -D \nabla^2 \phi \text{ if } D = \text{const.}$$

– Polar

$$-\frac{1}{r} \frac{d}{dr} \left(r D \frac{d\phi}{dr} \right) = -\frac{d}{dr} \left(D \frac{d\phi}{dr} \right) - \frac{1}{r} D \frac{d\phi}{dr} = \frac{dJ}{dr} + \frac{J}{r}$$

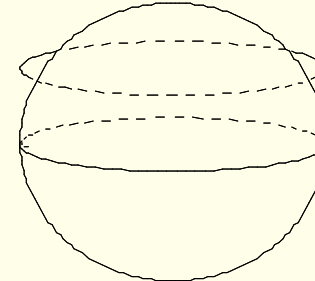
$$\nabla_r^2 = \frac{1}{r} \frac{d}{dr} \left(r \frac{d}{dr} \right)$$



- Spherical

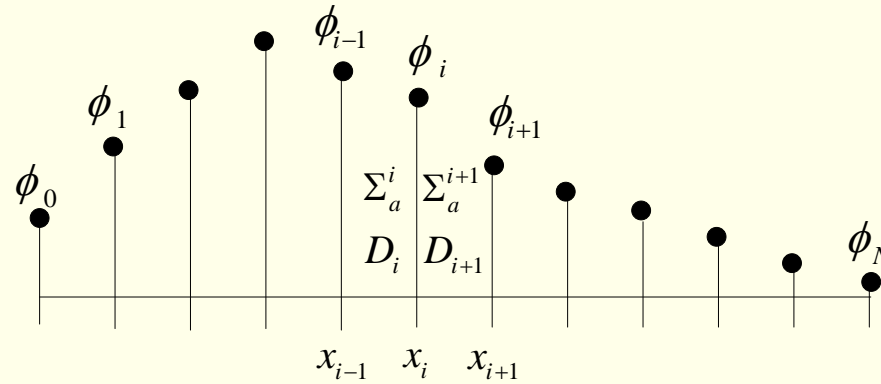
$$-\frac{1}{r^2} \frac{d}{dr} \left(r^2 D \frac{d\phi}{dr} \right) = -\frac{d}{dr} \left(D \frac{d\phi}{dr} \right) - \frac{2}{r} D \frac{d\phi}{dr} = \frac{dJ}{dr} + 2 \frac{J}{r}$$

$$\nabla_r^2 = \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d}{dr} \right)$$

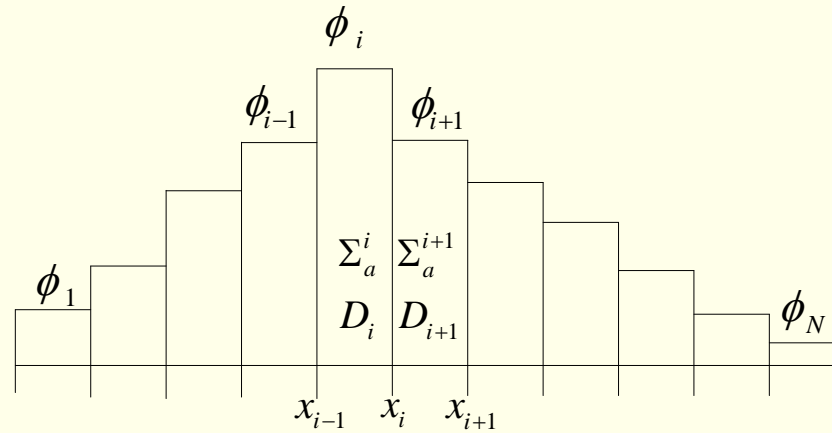


Discretization

- Point scheme



- Box scheme scheme

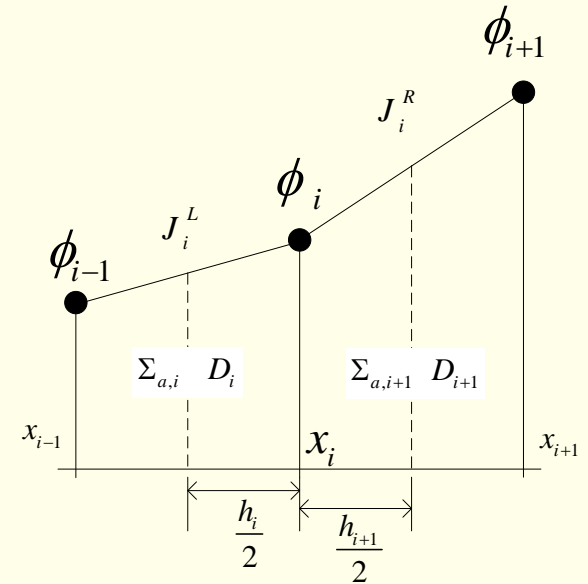


Discretization with Point Scheme

$$-\frac{d}{dx} \left(D(x) \frac{d\phi(x)}{dx} \right) + \Sigma_a(x) \phi(x) = \lambda \cdot \nu \Sigma_f(x) \phi(x)$$

$$\frac{dJ}{dx} + \Sigma_a \phi = \lambda \cdot \nu \Sigma_f \phi$$

$$\frac{dJ}{dx} \cong \frac{J_i^R - J_i^L}{\Delta x_i} = \frac{J_i^R - J_i^L}{\frac{1}{2}h_i + \frac{1}{2}h_{i+1}}$$



$$\begin{cases} J_i^L = -D_i \frac{\phi_i - \phi_{i-1}}{h_i} \\ J_i^R = -D_{i+1} \frac{\phi_{i+1} - \phi_i}{h_{i+1}} \end{cases}$$

$$a) \frac{dJ}{dx} = \frac{-D_{i+1} \frac{\phi_{i+1} - \phi_i}{h_{i+1}} - \left(-D_i \frac{\phi_i - \phi_{i-1}}{h_i} \right)}{\frac{1}{2}h_i + \frac{1}{2}h_{i+1}} = \frac{2}{h_i + h_{i+1}} \left\{ -D_{i+1} \frac{\phi_{i+1} - \phi_i}{h_{i+1}} + D_i \frac{\phi_i - \phi_{i-1}}{h_i} \right\}$$

$$b) \bar{\Sigma}_{a,i} = \frac{h_i \Sigma_{a,i} + h_{i+1} \Sigma_{a,i+1}}{h_i + h_{i+1}}$$

$$c) \bar{\nu \Sigma}_{f,i} = \frac{h_i \nu \Sigma_{f,i} + h_{i+1} \nu \Sigma_{f,i+1}}{h_i + h_{i+1}}$$

Discretization with Point Scheme

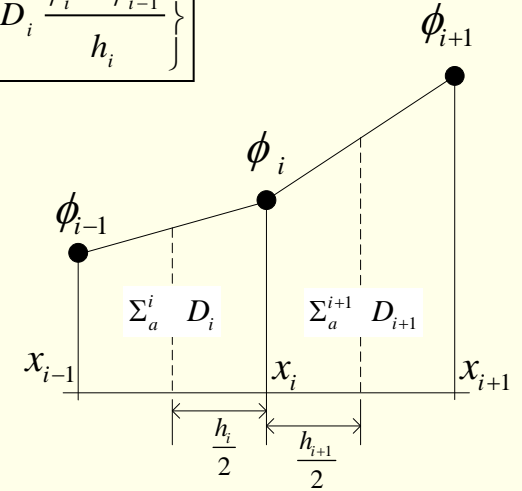
– if $h_i = h_{i+1} = h$

$$\frac{dJ}{dx} = \frac{2}{h_i + h_{i+1}} \left\{ -D_{i+1} \frac{\phi_{i+1} - \phi_i}{h_{i+1}} + D_i \frac{\phi_i - \phi_{i-1}}{h_i} \right\}$$

$$\begin{aligned} a) \quad \frac{dJ}{dx} &= \frac{1}{h} \left(-D_{i+1} \frac{\phi_{i+1} - \phi_i}{h} + D_i \frac{\phi_i - \phi_{i-1}}{h} \right) \\ &= -\frac{D_{i+1}}{h^2} (\phi_{i+1} - \phi_i) + \frac{D_i}{h^2} (\phi_i - \phi_{i-1}) \\ &= -\Sigma_{i+1}^D (\phi_{i+1} - \phi_i) + \Sigma_i^D (\phi_i - \phi_{i-1}) \\ &= -\Sigma_{i-1}^D \phi_{i-1} + (\Sigma_{i+1}^D + \Sigma_i^D) \phi_i - \Sigma_{i+1}^D \phi_{i+1} \end{aligned}$$

$$\otimes \frac{D \text{ [cm]}}{h^2 \text{ [cm}^2\text{]}} = \Sigma^D \text{ [cm}^{-1}\text{]}$$

Diffusion Xsec!



$$b) \quad \bar{\Sigma}_{a,i} = \frac{\Sigma_{a,i} + \Sigma_{a,i+1}}{2}$$

$$c) \quad \bar{\nu\Sigma}_{f,i} = \frac{\nu\Sigma_{f,i} + \nu\Sigma_{f,i+1}}{2}$$

– At $x = x_i$

$$\frac{dJ}{dx} + \Sigma_a \phi = \lambda \cdot \nu\Sigma_f \phi \rightarrow -\Sigma_{i-1}^D \phi_{i-1} + (\Sigma_{i+1}^D + \Sigma_i^D) \phi_i - \Sigma_{i+1}^D \phi_{i+1} + \bar{\Sigma}_{a,i} \phi_i = \lambda \cdot \bar{\nu\Sigma}_{f,i} \phi_i$$

$$-\Sigma_{i-1}^D \phi_{i-1} + (\Sigma_{i+1}^D + \Sigma_i^D + \bar{\Sigma}_{a,i}) \phi_i - \Sigma_{i+1}^D \phi_{i+1} = \lambda \cdot \bar{\nu\Sigma}_{f,i} \phi_i$$

Boundary Condition with Point Scheme

-At left boundary ($x = 0$)

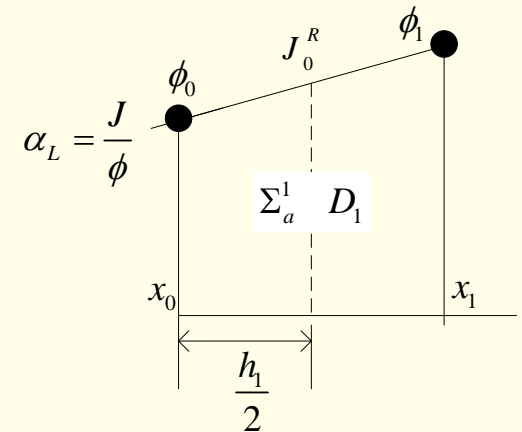
$$J_0 = -\alpha_L \phi_0 \quad J_0^R = -D_1 \frac{\phi_1 - \phi_0}{h_1}$$

$$\frac{dJ}{dx} = \frac{J_0^R - J_0}{\frac{h_1}{2}} = \frac{-D_1 \frac{\phi_1 - \phi_0}{h_1} - (-\alpha_L \phi_0)}{\frac{h_1}{2}} = \left(\frac{2D_1}{h_1^2} + \frac{2\alpha_L}{h_1} \right) \phi_0 - \frac{2D_1}{h_1^2} \phi_1$$

$$= \left(2\Sigma_1^D + \frac{2\alpha_L}{h_1} \right) \phi_0 - 2\Sigma_1^D \phi_1$$

$$\frac{dJ}{dx} + \Sigma_a \phi = \lambda \cdot \nu \Sigma_f \phi \rightarrow \left(2\Sigma_1^D + \frac{2\alpha_L}{h_1} \right) \phi_0 - 2\Sigma_1^D \phi_1 + \Sigma_{a,1} \phi_0 = \lambda \cdot \nu \Sigma_{f,1} \phi_0$$

$$\left(\Sigma_1^D + \frac{\alpha_L}{h_1} + \frac{1}{2} \Sigma_{a,1} \right) \phi_0 - \Sigma_1^D \phi_1 = \lambda \cdot \frac{1}{2} \nu \Sigma_{f,1} \phi_0$$



Boundary Condition with Point Scheme

– At right boundary ($x = H$)

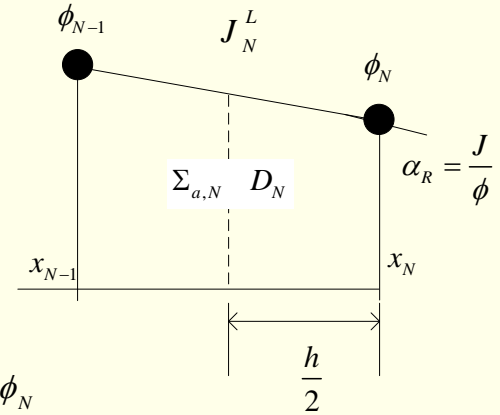
$$J_N = \alpha_R \phi_N \quad J_N^L = -D_N \frac{\phi_N - \phi_{N-1}}{h_N}$$

$$\frac{dJ}{dx} = \frac{J_N - J_N^L}{\frac{h_N}{2}} = \frac{\alpha_R \phi_N - \left(-D_N \frac{\phi_N - \phi_{N-1}}{h_N} \right)}{\frac{h_N}{2}} = -\frac{2D_N}{h_N^2} \phi_{N-1} + \left(\frac{2D_N}{h_N^2} + \frac{2\alpha_R}{h_N} \right) \phi_N$$

$$= -2\Sigma_D^N \phi_{N-1} + \left(2\Sigma_D^N + \frac{2\alpha_R}{h_N} \right) \phi_N \quad cf : \left(2\Sigma_1^D + \frac{2\alpha_L}{h_1} \right) \phi_0 - 2\Sigma_1^D \phi_1 \rightarrow \text{same as left}$$

$$\frac{dJ}{dx} + \Sigma_a \phi = \lambda \cdot \nu \Sigma_f \phi \rightarrow -2\Sigma_D^N \phi_{N-1} + \left(2\Sigma_D^N + \frac{2\alpha_R}{h_N} \right) \phi_N + \Sigma_{a,N} \phi_N = \lambda \cdot \nu \Sigma_{f,N} \phi_N$$

$$-\Sigma_D^N \phi_{N-1} + \left(\Sigma_D^N + \frac{\alpha_R}{h_N} + \frac{1}{2} \Sigma_{a,N} \right) \phi_N = \lambda \cdot \frac{1}{2} \nu \Sigma_{f,N} \phi_N$$



Linear System for Point Scheme

- Point scheme – Result

$$\begin{aligned}
 \left(\Sigma_1^D + \frac{\alpha_L}{h_1} + \frac{1}{2} \Sigma_{a,1} \right) \phi_0 - \Sigma_1^D \phi_1 &= \lambda \cdot \frac{1}{2} \nu \Sigma_{f,1} \phi_0 \quad (x = 0) \\
 - \Sigma_{i-1}^D \phi_{i-1} + \left(\Sigma_{i+1}^D + \Sigma_i^D + \bar{\Sigma}_{a,i} \right) \phi_i - \Sigma_{i+1}^D \phi_{i+1} &= \lambda \cdot \nu \bar{\Sigma}_{f,i} \phi_i \quad (x_1 \sim x_{N-1}) \\
 - \Sigma_D^N \phi_{N-1} + \left(\Sigma_D^N + \frac{\alpha_R}{h_N} + \frac{1}{2} \Sigma_{a,N} \right) \phi_N &= \lambda \cdot \frac{1}{2} \nu \Sigma_{f,N} \phi_N \quad (x = H)
 \end{aligned}$$

Matrix Form of Tridiagonal Linear System

$$\begin{bmatrix}
 \Sigma_1^D + \frac{\alpha_L}{h_1} + \frac{1}{2}\Sigma_{a,1} & -\Sigma_1^D & 0 & & & & 0 \\
 -\Sigma_1^D & \Sigma_1^D + \Sigma_2^D + \bar{\Sigma}_{a,1} & -\Sigma_2^D & 0 & & & 0 \\
 0 & \ddots & \ddots & \ddots & 0 & & \\
 & 0 & \ddots & \ddots & \ddots & & 0 \\
 & & 0 & \ddots & \ddots & & \\
 & & & 0 & -\Sigma_{N-1}^D & \Sigma_{N-1}^D + \Sigma_N^D + \bar{\Sigma}_{a,N-1} & -\Sigma_N^D \\
 0 & & & & 0 & -\Sigma_N^D & \Sigma_N^D + \frac{\alpha_R}{h_N} + \frac{1}{2}\Sigma_{a,N}
 \end{bmatrix}
 \begin{bmatrix}
 \phi_0 \\
 \phi_1 \\
 \vdots \\
 \vdots \\
 \vdots \\
 \phi_{N-1} \\
 \phi_N
 \end{bmatrix}$$

$$= \lambda \begin{bmatrix}
 \frac{1}{2}v\Sigma_{f,1} & & & & & & \\
 & \bar{v}\Sigma_{f,1} & & & & & \\
 & & \ddots & & & & \\
 & & & \ddots & & & \\
 & & & & \bar{v}\Sigma_{f,N-1} & & \\
 & & & & & \frac{1}{2}v\Sigma_{f,N} & \\
 & & & & & &
 \end{bmatrix}
 \begin{bmatrix}
 \phi_0 \\
 \phi_1 \\
 \vdots \\
 \vdots \\
 \vdots \\
 \phi_{N-1} \\
 \phi_N
 \end{bmatrix}$$

Box Scheme

- To derive conservation form

$$\frac{dJ}{dx} + \Sigma_a \phi = \lambda \cdot v \Sigma_f \phi \quad \dots \quad (1)$$

–Integrate (1) over $[x_{i-1}, x_i]$

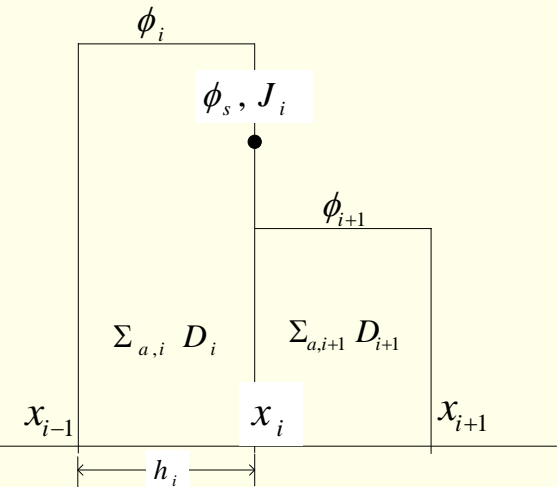
$$A = \int_{x_{i-1}}^{x_i} \frac{dJ}{dx} dx = J_i - J_{i-1}$$

$$B = \int_{x_{i-1}}^{x_i} \Sigma_{a,i} \phi(x) dx = \Sigma_{a,i} \cdot \bar{\phi}_i \cdot h_i \quad \leftarrow \bar{\phi}_i \equiv \frac{1}{h_i} \int_{x_{i-1}}^{x_i} \phi(x) dx : \text{average flux}$$

$$C = \int_{x_{i-1}}^{x_i} \lambda \cdot v \Sigma_{f,i} \phi(x) dx = \lambda \cdot v \Sigma_{f,i} \cdot \bar{\phi}_i \cdot h_i$$

$$J_i - J_{i-1} + \Sigma_{a,i} \cdot \bar{\phi}_i \cdot h_i = \lambda \cdot v \Sigma_{f,i} \cdot \bar{\phi}_i \cdot h_i \quad \leftarrow \text{Mesh Balance Equation}$$

$$\bar{\phi} = \phi \quad (\text{drop the overbar from now on})$$



Current in Box Scheme

– Current in terms of surface flux

$$J_i^R = -D_i \frac{\phi_s - \phi_i}{\frac{h_i}{2}} \quad J_{i+1}^L = -D_{i+1} \frac{\phi_{i+1} - \phi_s}{\frac{h_{i+1}}{2}}$$

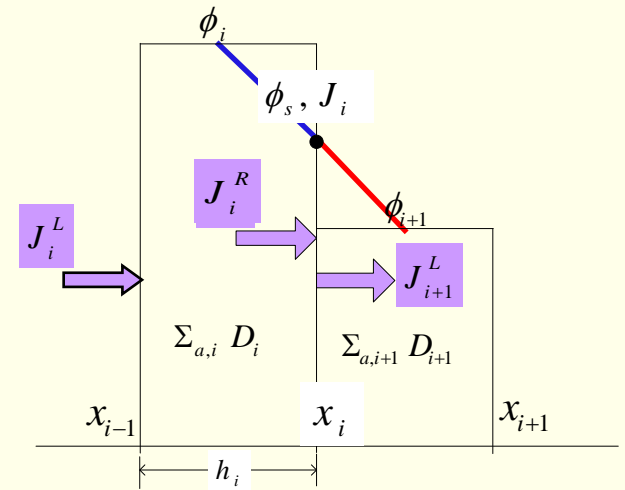
$$J_i^R = J_{i+1}^L$$

$$-D_i \frac{\phi_s - \phi_i}{\frac{h_i}{2}} = -D_{i+1} \frac{\phi_{i+1} - \phi_s}{\frac{h_{i+1}}{2}}$$

$$\phi_s = \frac{\frac{D_i}{h_i} \phi_i + \frac{D_{i+1}}{h_{i+1}} \phi_{i+1}}{\frac{D_i}{h_i} + \frac{D_{i+1}}{h_{i+1}}} = \omega_i \phi_i + (1 - \omega_i) \phi_{i+1}$$

$$J_{i+1}^L = J_i^R = -D_i \frac{\omega_i \phi_i + (1 - \omega_i) \phi_{i+1} - \phi_i}{h_i / 2} = -2\beta_i (1 - \omega_i) (\phi_{i+1} - \phi_i)$$

$$= -\frac{2\beta_i \beta_{i+1}}{\beta_i + \beta_{i+1}} (\phi_{i+1} - \phi_i) = -\tilde{D}_i (\phi_{i+1} - \phi_i)$$



$$\beta_i \leftarrow \text{Diffusivity}$$

$$\leftarrow \omega_i = \frac{\frac{D_i}{h_i}}{\frac{D_i}{h_i} + \frac{D_{i+1}}{h_{i+1}}} = \frac{\beta_i}{\beta_i + \beta_{i+1}}$$

Coupling Coefficient

$$\tilde{D}_i = \frac{2\beta_i \beta_{i+1}}{\beta_i + \beta_{i+1}}$$

(Surface Quantity)

Mesh Balance Equation

-In the i-th node, $x_{i-1} \leq x \leq x_i$

$$J_i = -\tilde{D}_i(\phi_{i+1} - \phi_i) \quad \left(\tilde{D}_i = \frac{2\beta_i\beta_{i+1}}{\beta_i + \beta_{i+1}} \right)$$

$$J_{i-1} = -\tilde{D}_{i-1}(\phi_i - \phi_{i-1}) \quad \left(\tilde{D}_{i-1} = \frac{2\beta_{i-1}\beta_i}{\beta_{i-1} + \beta_i} \right)$$

$$J_i - J_{i-1} + \Sigma_{a,i} \cdot \phi_i \cdot h_i = \lambda \cdot v \Sigma_{f,i} \cdot \phi_i \cdot h_i$$

$$-\tilde{D}_i(\phi_{i+1} - \phi_i) + \tilde{D}_{i-1}(\phi_i - \phi_{i-1}) + \Sigma_a \cdot \phi_i \cdot h_i = \lambda \cdot v \Sigma_f \cdot \phi_i \cdot h_i$$

$$-\tilde{D}_{i-1}\phi_{i-1} + (\tilde{D}_{i-1} + \tilde{D}_i + \Sigma_a \cdot h_i)\phi_i - \tilde{D}_i\phi_{i+1} = \lambda \cdot v \Sigma_f \cdot h_i \cdot \phi_i$$

Boundary Condition with Box Scheme

–At left boundary

$$J_0 = -\alpha_L \phi_s = -D_1 \frac{\phi_1 - \phi_s}{\frac{h_1}{2}} \quad \rightarrow \quad \phi_s = \frac{\frac{D_1}{h_1}}{\frac{D_1}{h_1} + \frac{\alpha_L}{2}} \phi_1 = \frac{\beta_1}{\beta_1 + \frac{\alpha_L}{2}} \phi_1 = \frac{\beta_1}{\beta_0 + \beta_1} \phi_1$$

$$J_0 = -\alpha_L \frac{\beta_1}{\beta_0 + \beta_1} \phi_1 = -\frac{2 \frac{\alpha_L}{2} \beta_1}{\beta_0 + \beta_1} \phi_1 = -\tilde{D}_0 \phi_1 \quad \tilde{D}_0 = \frac{2 \beta_0 \beta_1}{\beta_0 + \beta_1} \text{ with } \beta_0 = \frac{\alpha_L}{2}$$

$$J_1 - J_0 + \Sigma_a \cdot \phi_1 \cdot h_1 = \lambda \cdot \nu \Sigma_f \cdot \phi_1 \cdot h_1$$

$$-\tilde{D}_1(\phi_2 - \phi_1) + \tilde{D}_0 \phi_1 + \Sigma_{a,1} \cdot \phi_1 \cdot h_1 = \lambda \cdot \nu \Sigma_{f,1} \cdot h_1 \cdot \phi_1$$

$$(\tilde{D}_0 + \tilde{D}_1 + \Sigma_{a,1} \cdot h_1) \phi_1 - \tilde{D}_1 \phi_2 = \lambda \cdot \nu \Sigma_{f,1} \cdot h_1 \cdot \phi_1$$

–At Left Boundary ($x = 0$)

$$-\tilde{D}_{N-1} \phi_{N-1} + (\tilde{D}_{N-1} + \tilde{D}_N + \Sigma_{a,N} \cdot h_N) \phi_N = \lambda \cdot \nu \Sigma_{f,N} \cdot h_N \cdot \phi_N$$

–At Right Boundary ($x = H$)

Tridiagonal Linear System for Box Scheme

- Box scheme – Result

$$\begin{aligned}
 (\tilde{D}_0 + \tilde{D}_1 + \Sigma_{a,1} \cdot h_1) \phi_1 - \tilde{D}_1 \phi_2 &= \lambda \cdot \nu \Sigma_{f,1} \cdot h_1 \cdot \phi_1 \quad (x_0) \\
 -\tilde{D}_{i-1} \phi_{i-1} + (\tilde{D}_{i-1} + \tilde{D}_i + \Sigma_a \cdot h_i) \phi_i - \tilde{D}_i \phi_{i+1} &= \lambda \cdot \nu \Sigma_f \cdot h_i \cdot \phi_i \quad (x_1 \sim x_{N-1}) \\
 -\tilde{D}_{N-1} \phi_{N-1} + (\tilde{D}_{N-1} + \tilde{D}_N + \Sigma_{a,N} \cdot h_N) \phi_N &= \lambda \cdot \nu \Sigma_{f,N} \cdot h_N \cdot \phi_N \quad (x_N)
 \end{aligned}$$

$$\begin{bmatrix} d_1 & u_1 & 0 & & & & 0 \\ l_2 & d_2 & u_2 & 0 & & & 0 \\ 0 & \ddots & \ddots & \ddots & 0 & & \\ & & l_i & d_i & u_i & 0 & \\ & & 0 & l_{i+1} & \ddots & \ddots & 0 \\ & 0 & 0 & l_{N-1} & d_{N-1} & u_{N-1} & \phi_{N-1} \\ 0 & & & 0 & l_N & d_N & \phi_N \end{bmatrix} \begin{bmatrix} \phi_0 \\ \phi_1 \\ \vdots \\ \vdots \\ \vdots \\ \phi_{N-1} \\ \phi_N \end{bmatrix} = \lambda \begin{bmatrix} \nu \Sigma_{f,1} & 0 & & & & & 0 \\ 0 & \nu \Sigma_{f,2} & 0 & & & & 0 \\ & 0 & \ddots & 0 & & & \\ & & 0 & \ddots & 0 & & \\ & & & 0 & \ddots & 0 & \\ & & & & 0 & \ddots & 0 \\ 0 & & & & 0 & \nu \Sigma_{f,N-1} & 0 \\ 0 & & & & & 0 & \nu \Sigma_{f,N} \end{bmatrix} \begin{bmatrix} \phi_0 \\ \phi_1 \\ \vdots \\ \vdots \\ \vdots \\ \phi_{N-1} \\ \phi_N \end{bmatrix}$$

$$M \Phi = \lambda F \Phi$$

$$d_i = \tilde{D}_{i-1} + \tilde{D}_i + \Sigma_{a,i} \cdot h_i$$

$$u_i = -\tilde{D}_i$$

$$l_i = -\tilde{D}_{i-1}$$

$$l_{i+1} = u_i = -\tilde{D}_{i-1} \Rightarrow \text{Symmetric } (M = M^T)$$

1. Generalized Form

– Same form every where

2. Conservation Form

– Nodal balance assured because of starting from integration

Analytic Solution for Matrix Eigenvalue Problem

- For a single region

$$-D \frac{d^2 \phi}{dx^2} + \Sigma_a \phi = \lambda \cdot v \Sigma_f \phi$$

- Point scheme with $\phi_0 = 0, \phi_N = 0$

$$-\Sigma_{i-1}^D \phi_{i-1} + (\Sigma_{i+1}^D + \Sigma_i^D + \bar{\Sigma}_{a,i}) \phi_i - \Sigma_{i+1}^D \phi_{i+1} = \lambda \cdot \bar{v} \Sigma_{f,i} \phi_i$$

$$L = \sqrt{\frac{D}{\Sigma_a}} : \text{Diffusion Length}$$

–if $\Sigma_i^D = \Sigma_{i+1}^D = \frac{D}{h^2}, \quad \Sigma_{a,i} = \Sigma_{a,i+1} = \Sigma_a, \quad v \Sigma_{f,i} = v \Sigma_{f,i+1} = v \Sigma_f$

$$-\frac{D}{h^2}(\phi_{k-1} - 2\phi_k + \phi_{k+1}) + \Sigma_a \phi_k = \lambda \cdot v \Sigma_f \phi_k$$

$$1) -\frac{h^2}{D}(\Sigma_a - \lambda \cdot v \Sigma_f) \quad 2) k_{eff} = \frac{k_\infty}{1 + L^2 B^2}$$

$$\phi_{k-1} - 2\phi_k + \phi_{k+1} - \frac{h^2}{D}(\Sigma_a - \lambda \cdot v \Sigma_f) \phi_k = 0$$

$$= -h^2 \frac{\Sigma_a}{D} \left(1 - \lambda \cdot \frac{v \Sigma_f}{\Sigma_a} \right) \quad B^2 = \frac{1}{L^2} \left(\frac{k_\infty}{k_{eff}} - 1 \right) > 0 \because k_\infty > k_{eff}$$

$$\phi_{k-1} - 2\phi_k + \phi_{k+1} + \tilde{B}^2 \phi_k = 0$$

$$= -h^2 \frac{1}{L^2} \left(1 - \frac{1}{k_{eff}} \cdot k_\infty \right)$$

or

$$= \frac{\lambda \cdot v \Sigma_f - \Sigma_a}{D}$$

$$= h^2 B^2$$

$$= \tilde{B}^2$$

Analytic Solution for Matrix Eigenvalue Problem

$$\phi_{k-1} - 2\phi_k + \phi_{k+1} + \tilde{B}^2 \phi_k = 0$$

-Let $\phi_k = e^{mk}$

$$e^{m(k-1)} - 2e^{mk} + e^{m(k+1)} + \tilde{B}^2 e^{mk} = 0$$

$$e^{-m} - 2 + e^m + \tilde{B}^2 = 0$$

$$\frac{e^m + e^{-m}}{2} = 1 - \frac{\tilde{B}^2}{2}$$

$$\text{Cosh } m (\geq 1) = 1 - \frac{\tilde{B}^2}{2} (< 1) \quad \text{Not possible}$$

-Let $\phi_k = e^{imk}$

$$\frac{e^{im} + e^{-im}}{2} = 1 - \frac{\tilde{B}^2}{2}$$

$$\cos m = 1 - \frac{\tilde{B}^2}{2}$$

$\phi_k = e^{-imk}$ as well

$$\phi_k = C_1 e^{imk} + C_2 e^{-imk} = \tilde{C}_1 \cos mk + \tilde{C}_2 \sin mk$$

Buckling Eigenvalue

$$\phi_k = \tilde{C}_1 \cos mk + \tilde{C}_2 \sin mk$$

$$\text{B.C.} \begin{cases} \phi_0 = \tilde{C}_1 = 0 \\ \phi_N = \tilde{C}_2 \sin mN = 0, \quad mN = l\pi \quad (l = 1, \dots, n-1) \end{cases} \rightarrow m = \frac{l\pi}{N}$$

$$\text{Fundamental Model Only } (l = 1); \quad \cos\left(\frac{\pi}{N}\right) = 1 - \frac{\tilde{B}^2}{2}$$

$$\leftarrow \cos m = 1 - \frac{\tilde{B}^2}{2}$$

$$\tilde{B}^2 = 2 \left[1 - \cos\left(\frac{\pi}{N}\right) \right] = 2 \left[1 - \left\{ 1 - \frac{1}{2} \left(\frac{\pi}{N}\right)^2 + \frac{1}{4!} \left(\frac{\pi}{N}\right)^4 \right\} + \dots \right]$$

$$= \left(\frac{\pi}{N}\right)^2 \left(1 - \frac{1}{12} \left(\frac{\pi}{N}\right)^2 \right) + O\left(\frac{\pi}{N}\right)^6$$

$$N = \frac{H}{h}, \quad \tilde{B} = hB$$

$$= \left(\frac{\pi}{H}\right)^2 h^2 \left(1 - \frac{1}{12} \left(\frac{\pi}{H} h\right)^2 \right) + O(h^6)$$

$$\rightarrow B^2 = \left(\frac{\pi}{H}\right)^2 \left(1 - \frac{1}{12} \left(\frac{\pi}{H} h\right)^2 \right) + O(h^4)$$

Eigenvalue

$$B^2 = \frac{\lambda \cdot v \Sigma_f - \Sigma_a}{D} = \left(\frac{\pi}{H} \right)^2 \left(1 - \frac{1}{12} \left(\frac{\pi}{H} h \right)^2 \right) + O(h^4)$$

$$\rightarrow \lambda = \frac{1}{v \Sigma_f} \left[\Sigma_a + D \left\{ \left(\frac{\pi}{H} \right)^2 \left(1 - \frac{1}{12} \left(\frac{\pi}{H} h \right)^2 \right) + O(h^4) \right\} \right]$$

– Analytic Solution for differential eqn.

$$B^2 = \left(\frac{\pi}{H} \right)^2 v s \left(\frac{\pi}{H} \right)^2 - \frac{1}{12} \left(\frac{\pi}{H} \right)^4 h^2$$

$$\lambda^* = \frac{1}{v \Sigma_f} \left(\Sigma_a + D \left(\frac{\pi}{H} \right)^2 \right)$$

$$\text{Error } \Delta \lambda = \frac{1}{v \Sigma_f} \cdot \frac{D}{12} \left(\frac{\pi}{H} \right)^4 h^2 \propto h^2$$