

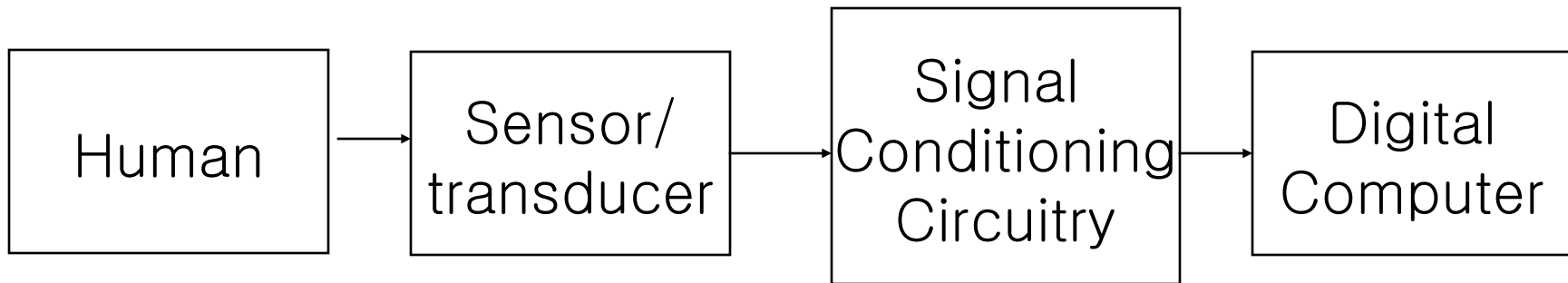
# Amplifiers

Operational Amplifier  
Instrumentation Amplifier  
Analog Computation  
Active Filter  
Grounding  
Isolation

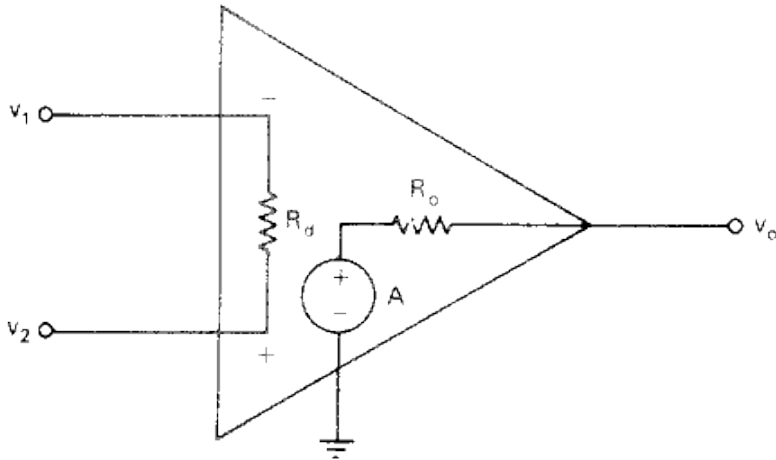


# Function of Amplifiers

- Amplifiers provides
  - GAIN
  - Filtering, Signal processing, Correction for Nonlinearities



# Ideal Amps



- Assumptions

- Open loop Gain = Infinity

- Input Impedance  $R_d =$   
Infinity

- Output Impedance  $R_o = 0$

- Bandwidth = Infinity

- Infinite Frequency Response

- $v_o = 0$  when  $v_1 = v_2$

- No Offset Voltage

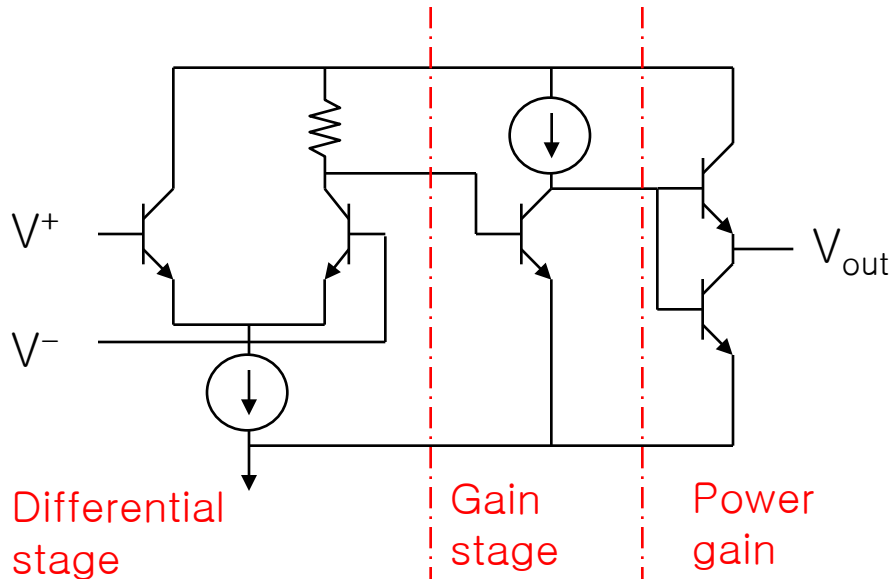
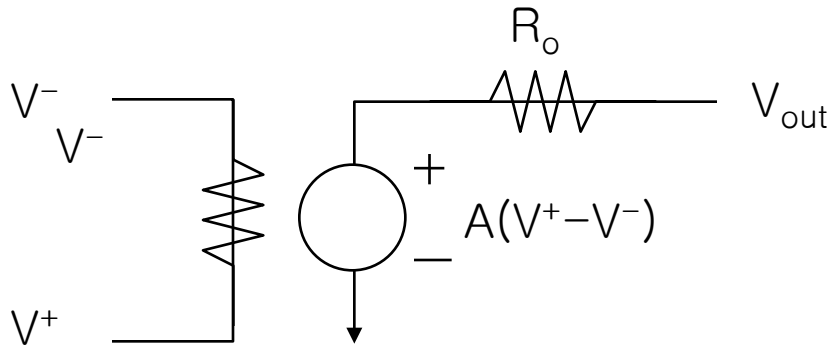
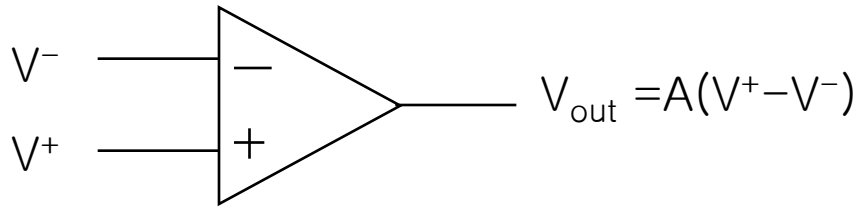


# OP Amplifier Properties

Ideal Op. Amp.	ideally	means
gain(open-loop)	$\infty$	$\geq 10^4$
open-loop BW	$\infty$	Dominant Pole at 10Hz
CMRR	$\infty$	$\geq 70\text{dB}$
$R_i$	$\infty$	$\geq 10\text{M}\Omega$
$R_o$	0	$< 500\Omega$
$I_B$	0	$< 0.5\mu\text{A}$
$V_{os}$	0	$< 10\text{mV}$
$I_{os}$	0	$< 0.2\mu\text{A}$



# How do we achieve these properties?



741인 경우

(Stage 1)  $R=1.6M\Omega$   
Gain=1200

(Stage 2)  $V_{tg}$  gain=220

(Stage 3)  $R_o=60\Omega$   
 $V_{tg}$  gain=1

Overall Gain=108dB



# Two rules of Ideal OP Amps

- Note
  - $v_0 = A(v_2 - v_1)$ 
    - For finite  $v_0$  and  $A = \infty$  (Typically 100,000)
      - $v_2 - v_1$  should be 0  $\Rightarrow v_2 = v_1$
    - Since  $v_2 = v_1$  and input impedance is  $\infty$ ,
      - There should be no currents flowing into the input terminals
- Rule 1
  - When the OP Amp is in linear range the two inputs are at the same voltage (Virtual Ground)
- Rule 2
  - No Current flows into either terminal of the OP Amp

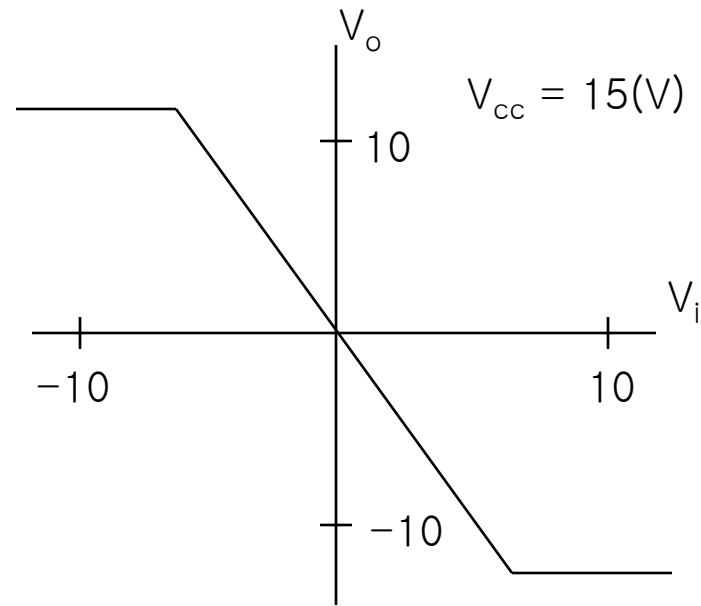
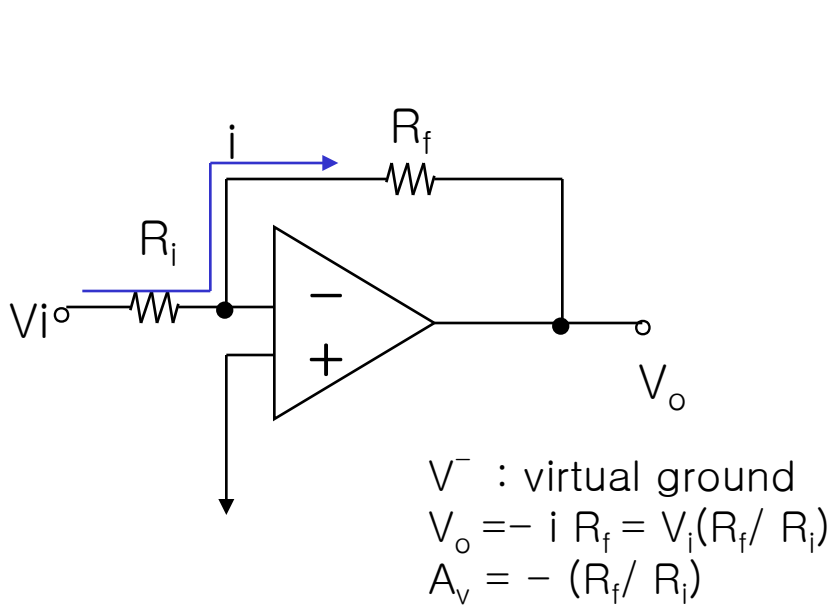


# Basic OP Amp Circuit Blocks

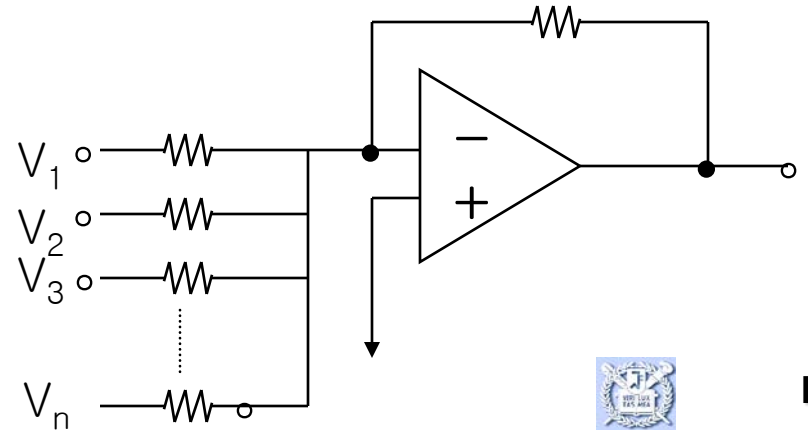
- Inverting Amplifier
- Noninverting Amplifier
- Unity-Gain Amplifier
- Differential Amplifier
- Instrumental Amplifier
- The ECG(Electrocardiogram) Amplifier



# Inverting Amp.



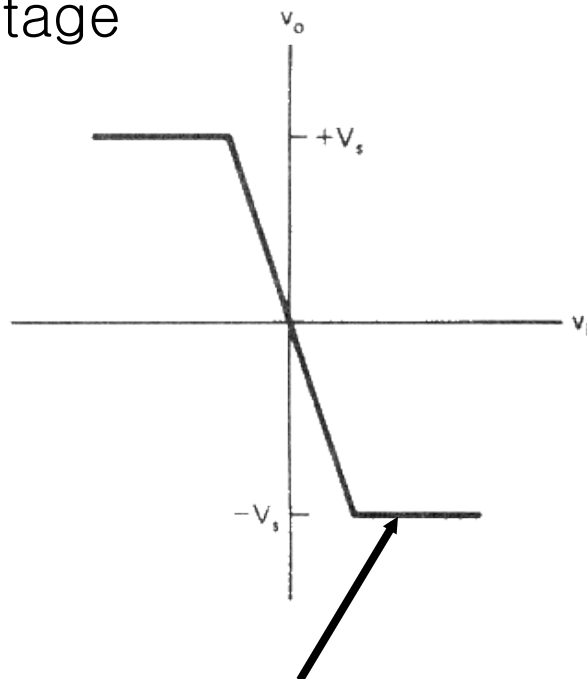
## ■ Summing





# Inverting Amplifier (Cont.)

- Linear Range
  - By Power Supply Voltage



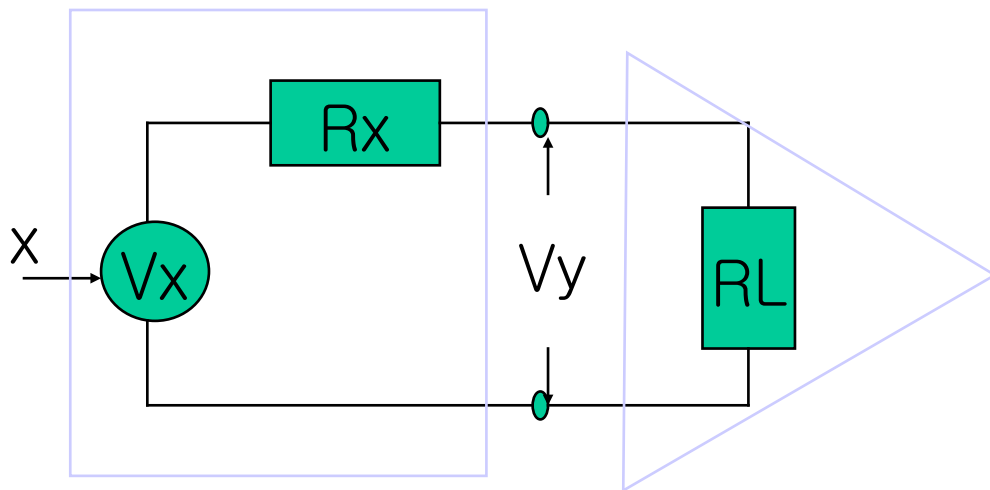
Saturation

- Input Impedance
  - Low ( $R_i$ )
  - Increasing  $R_i \rightarrow$  Decreasing Gain
    - Increasing Gain by increasing  $R_f$ 
      - But there is practical limit



# Why High Input Impedance ?

- Concept of Loading
  - To avoid the effect of output value
  - Only depends on the amplitude of sensor output, not on the frequency or digital output

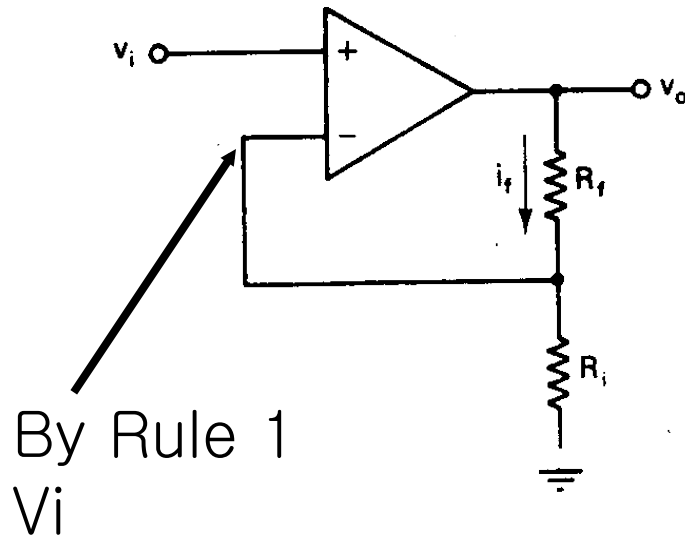


- Open Loop Output
  - $V_x$
- Voltage Drop by Load
  - $V_y = V_x - V_x \times R_x / (R_L + R_x)$
- Let  $R_L \gg R_x$ 
  - $V_y = V_x$
  - We can eliminate the effect of amplifier or detector.



# Noninverting Amplifiers

- Noninverting Amp
  - Gain =  $(R_f + R_i) / R_f$

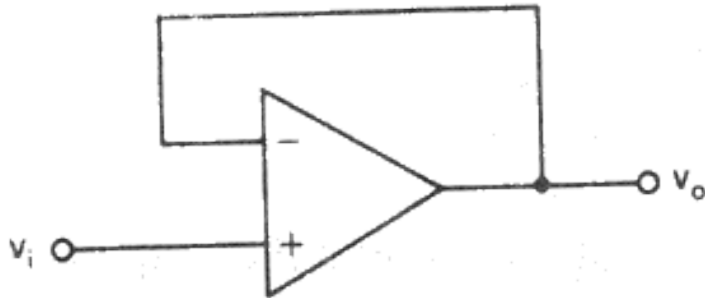


- By Rule 2
  - $V_o = I_f \times (R_f + R_i)$
  - $V_i = I_f \times R_i$
  - $V_o = V_i \times (R_f + R_i) / R_i$
- Gain:  $V_o / V_i = 1 + R_f / R_i$
- Gain  $\geq 1$ , Always
- Input Impedance
  - Very Large (Infinite)



# Unity-Gain Amplifier

- Homework #2-1
  - Verify that the Gain of Unity-Gain Amp is 1

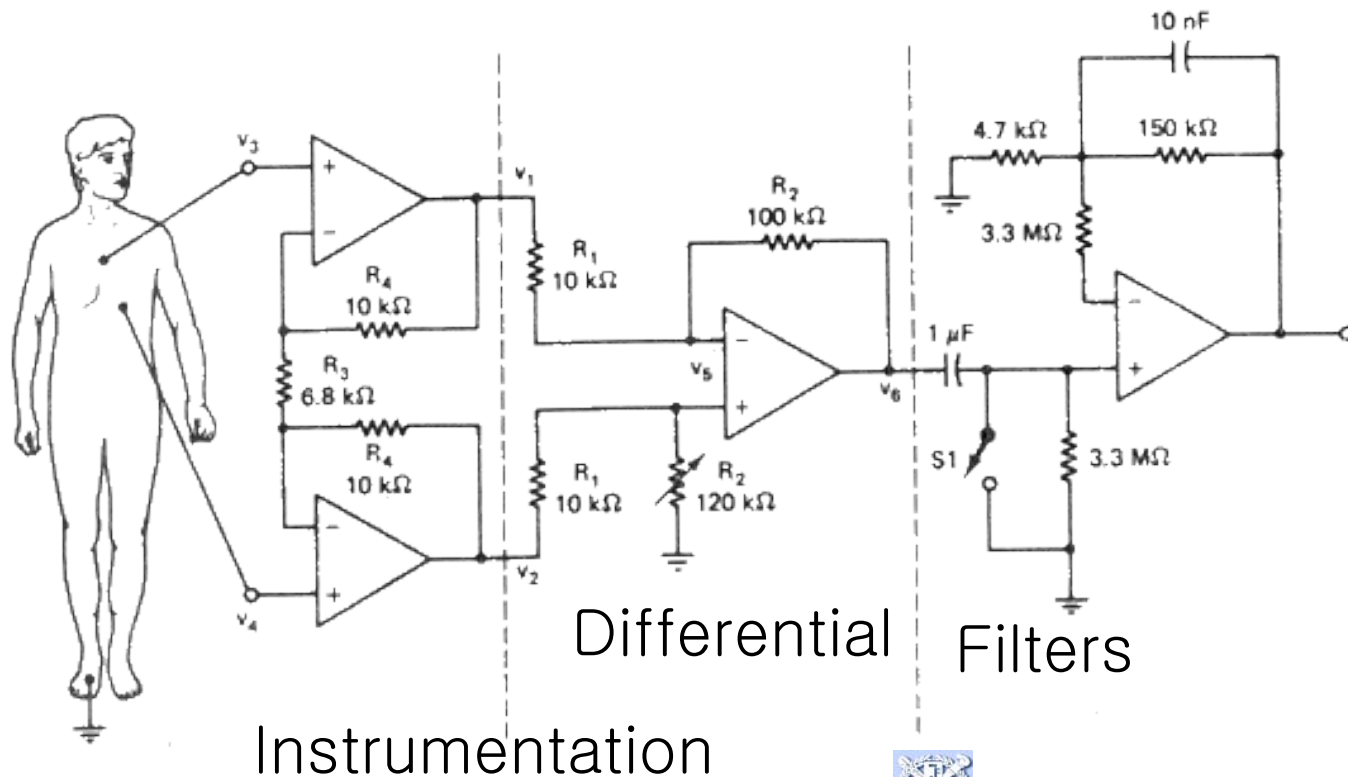


- $V_o = V_i$
- Applications
  - Buffer amplifier
    - Isolate one circuit from the loading effects of a following stage
  - Impedance converter
    - Data conversion System (ADC or DAC) where constant impedance or high impedance is required



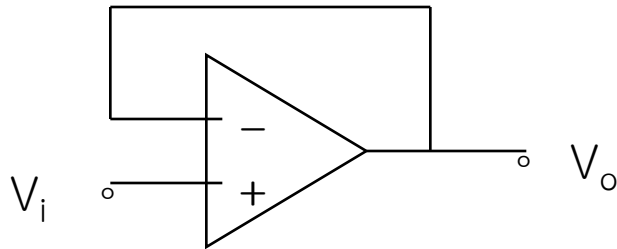
# Differential Amplifiers

- Can reject 60Hz interference
- Example Use of Diff. Amp. In ECG amplifier



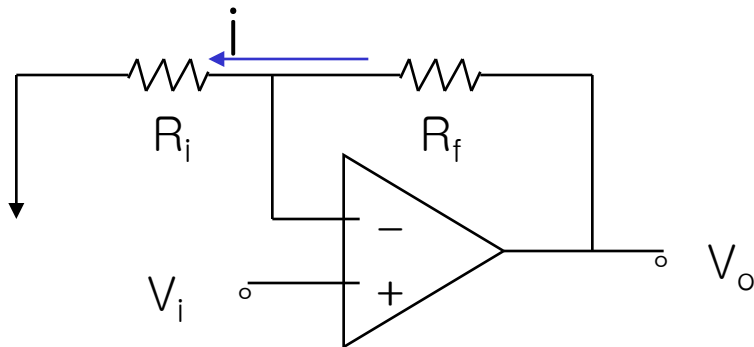
# Non Inverting Amp.

- Follower



Buffer, Impedance Converter

- Non-inverting Amp.



$$V_o = i \cdot (R_i + R_f)$$
$$V_i = i \cdot R_i$$

$$\Rightarrow A_v = \frac{R_i + R_f}{R_i}$$

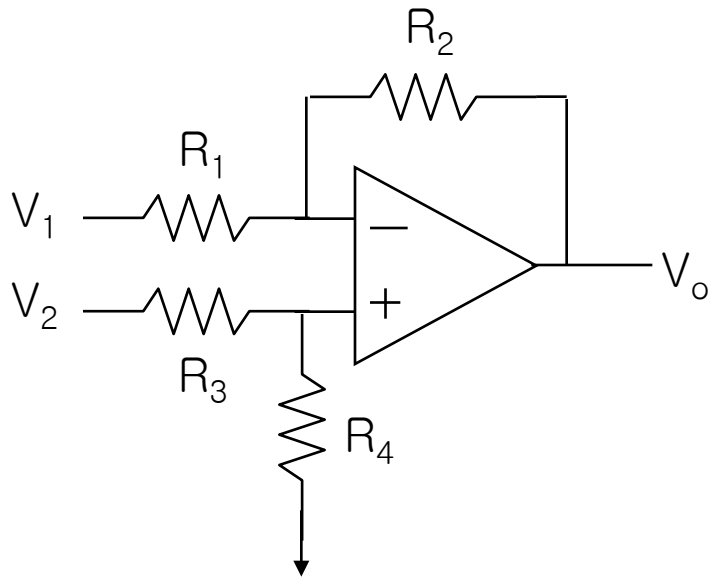


# Instrumentation Amp- Differential Amp.

- High gain DC coupled differential amp with single ended output.

High  $Z_{in}$ , CMRR

Used to Amplify small differential signals from transducer where there may be a large common signal.



$$V^+ = V_2 \cdot \frac{R_4}{R_3 + R_4}, \quad V^- = (V_o - V_1) \frac{R_1}{R_1 + R_2} + V_1$$

From  $V^+ = V^-$

$$V_o = \frac{R_4}{R_3 + R_4} \left( 1 + \frac{R_2}{R_1} \right) V_2 - \frac{R_2}{R_1} V_1$$

$$\text{if } \frac{R_3}{R_4} = \frac{R_1}{R_2} \rightarrow V_o = \frac{R_2}{R_1} (V_2 - V_1), \quad G_d = \frac{R_2}{R_1}$$

Common mode  $V_1 = V_2 \rightarrow V_o = 0 \rightarrow G_c = 0$

CMRR =  $G_d / G_c$



# Differential Amplifiers (Cont.)

- CMRR (Common Mode Rejection Ratio)
  - Measure of the ability to reject CMV
  - $CMRR = DG / CMG$ 
    - The Higher CMRR, the better quality
    - Typically, 100 ~ 10,000
    - 60Hz noise common to V1 and V2 can be rejected



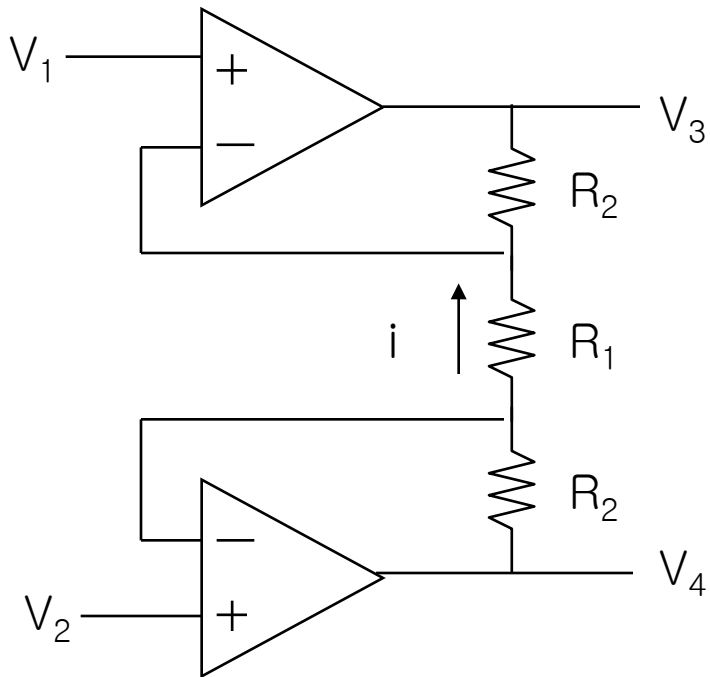


# Instrumentation Amplifiers

- The One OP Amp Differential Amplifier is not desirable.
  - Input Impedance is not so High
    - Good for Low impedance source
      - Strain gage Bridge
    - Bad for High impedance source
- Thus An Instrumentation Amplifier consists of
  - Differential Amp with High Input Impedance and Low Output Impedance
  - Two Noninverting Amp + One Differential Amp



# For High Input Impedance



If  $V_1 = V_2$  (CMG)

$$\rightarrow i = 0$$

$$\rightarrow V_1 = V_2 = V_3 = V_4$$

$$\rightarrow G_c \text{ (CMG)} = 0$$

If  $V_1 \neq V_2$  (DMG)

$$\rightarrow i = (V_2 - V_1) / R_1$$

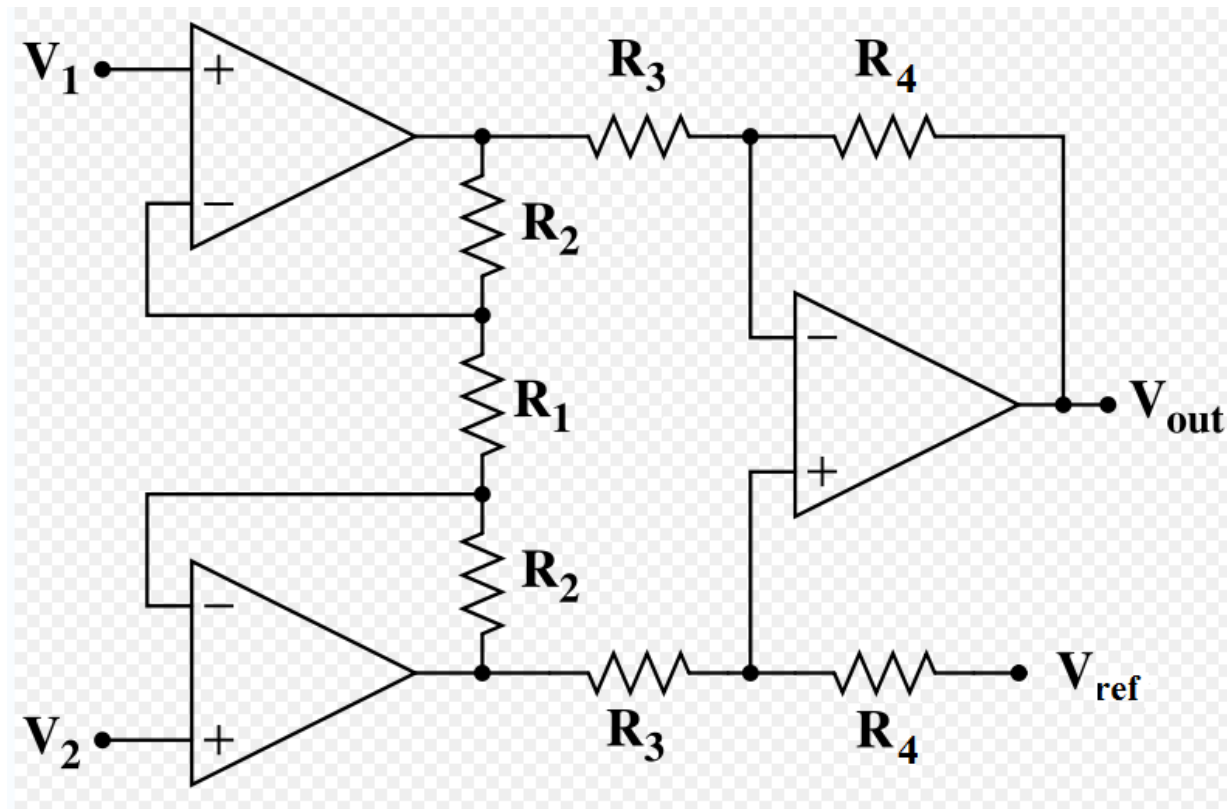
$$\frac{V_4 - V_3}{V_2 - V_1} = \frac{R_1 + 2R_2}{R_1} = 1 + 2 \cdot \frac{R_2}{R_1}$$



# Complete Design of Instrumentation Amp.

$$V_{out} - V_{ref} = G(v_2 - v_1)$$

$$G = \frac{R_4}{R_3} \left( 1 + 2 \frac{R_2}{R_1} \right)$$





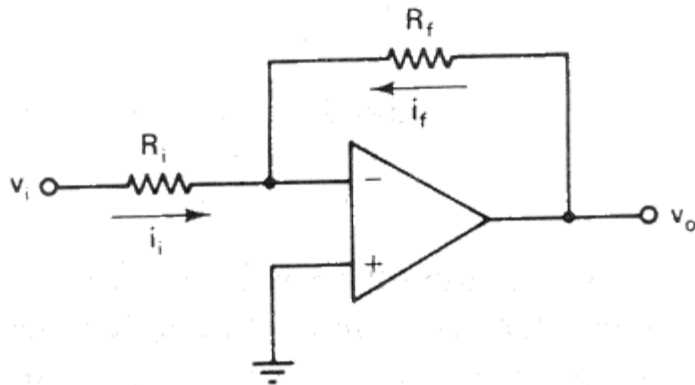
# Analog Computation

- Digital Signal Processing is preferred
  - Flexibility
  - Easy to Change
  - Elimination of hardware
- Analog Signal Processing
  - Is preferred when DSP consumes too much time



# Inverter and Scale Changer

- Inverting Amp with  
Gain =  $- R_f / R_i$

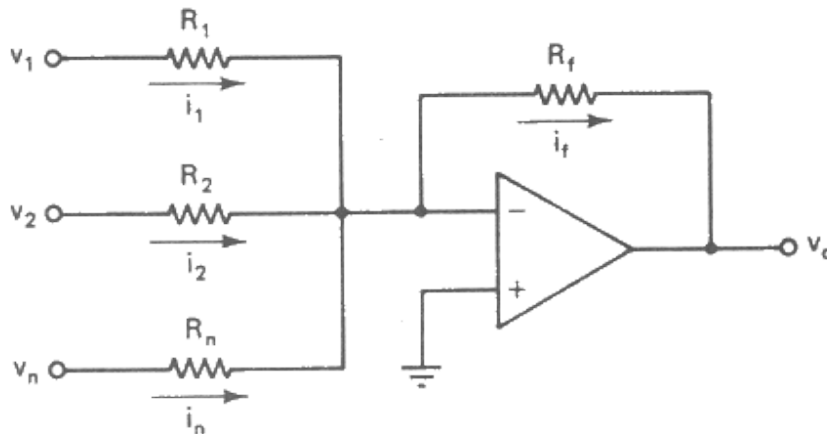


- Inverter
  - $R_f / R_i = 1$
- Inverter and Scale Changer
  - Proper choice of  $R_f / R_i$
- Application
  - Use of inverter to scale the output of DAC



# Adders (Summing Amplifiers)

- Adder
  - Inverter with Several inputs



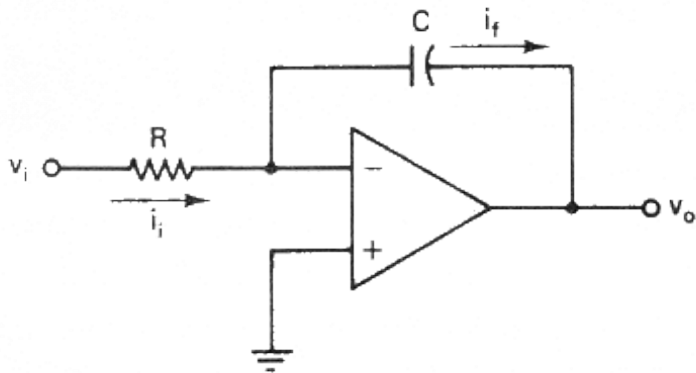
- $V_o = -R_f(V_1/R_1 + V_2/R_2 + \dots + V_n/R_n)$ 
  - $I_f = I_1 + I_2 + I_n$
  - $I_1 = V_1/R_1, \dots$
  - $V_o = -I_f * R_f$
- $R_f$  determines overall Gain
- $R_i$  determines weighting factor and input impedance



# Integrator

- Self homework
  - Show that

$$v_o = \frac{-1}{RC} \int_0^{t_1} v_i dt + v_{ic}$$



- Drawbacks
  - $V_o$  will reach saturation voltage, if  $V_i$  is left connected indefinitely
  - Integrator operates as an open-loop amplifier for DC inputs

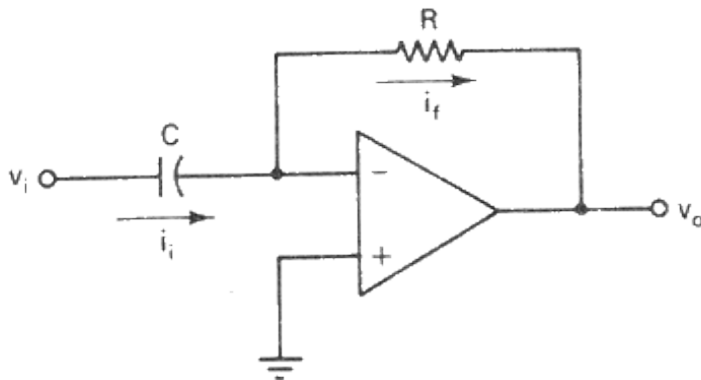




# Differentiators

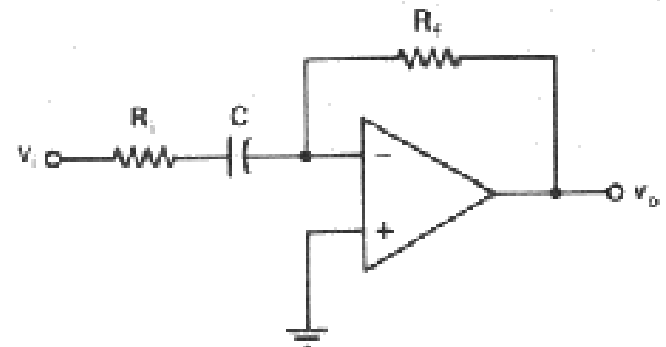
- Self Homework
- Show that

$$v_o = -RC \frac{dv_i}{dt}$$



- Drawbacks
  - Instability at High frequencies
- Practical Differentiator
  - To Stable

$$R_i = \sqrt{\frac{R}{A_0 \omega_0 C}}$$



# Comparators

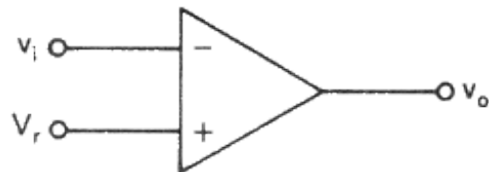
- Compare Two Inputs

- $V_i > V_r$

- $V_o = -V_s$

- $V_i < V_r$

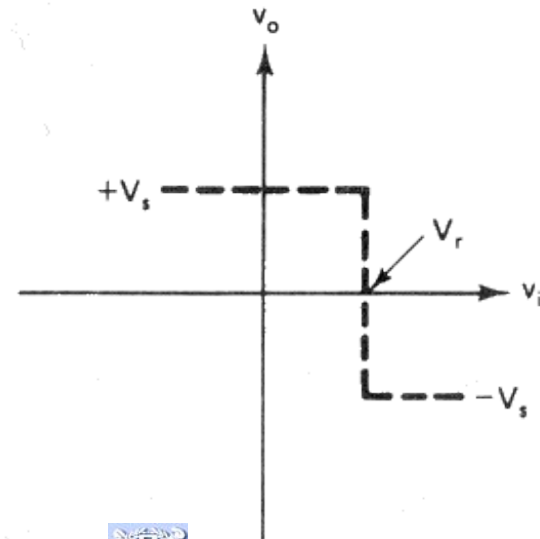
- $V_o = V_s$



- Drawbacks

- If  $V_i = V_r + \text{small noise}$

- Rapid fluctuation between  $\pm V_s$



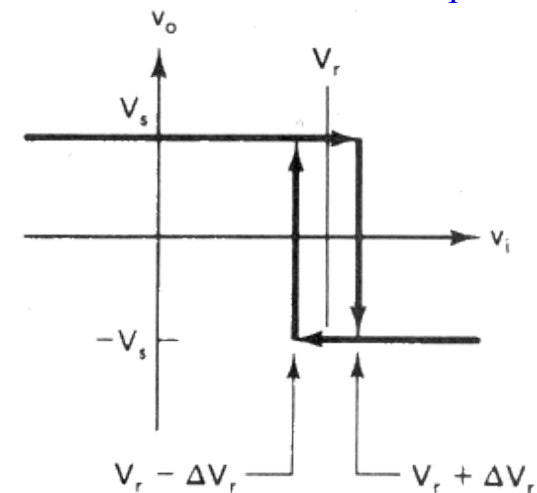
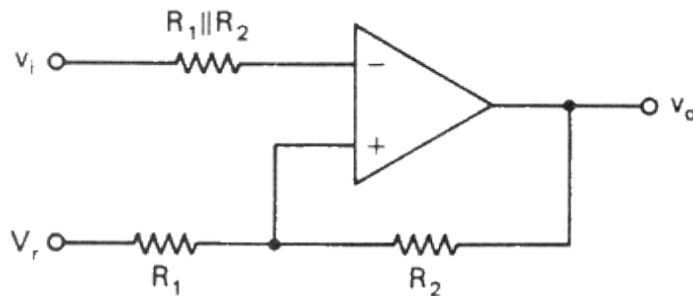
# Comparators with Hysteresis

- Positive Feedback
  - Hysteresis loop
  - Can remove the effect of Small Noise
    - Reduce Fluctuation

- Homework
  - Show that

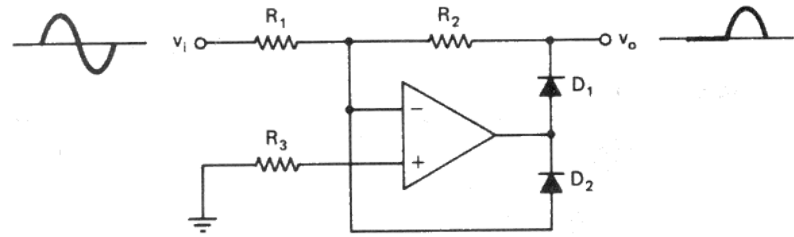
$$V_r + \Delta V_r = V_r + \frac{(V_S - V_r)R_1}{R_1 + R_2}$$

$$V_r - \Delta V_r = V_r + \frac{(-V_S - V_r)R_1}{R_1 + R_2}$$

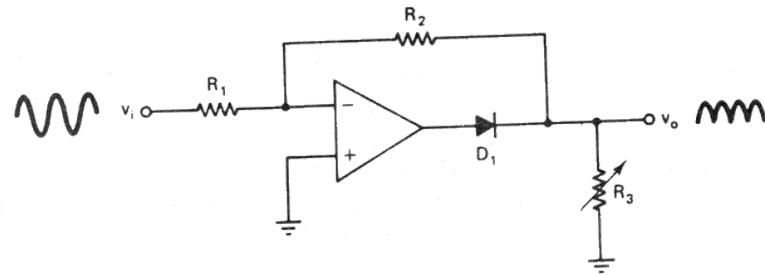


# Rectifiers

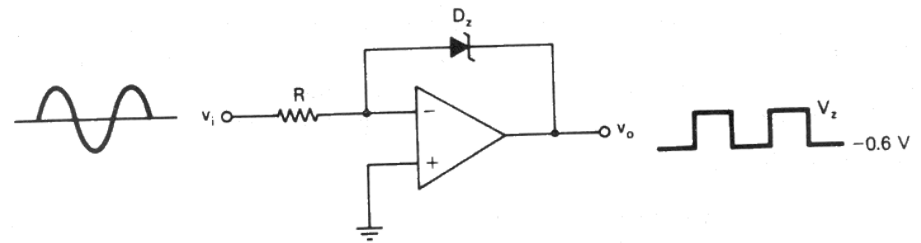
- Precision Half Wave Rectifier



- Precision Full Wave Rectifier



- Limiters



# Practical OP Amp Considerations

- Effects of Nonlinear characteristics
  - Compensation
    - Undesirable Oscillation at High frequency
      - Add external Capacitance according to Spec sheet
  - GBW (Gain Bandwidth Product)
    - $\text{Gain} \times \text{Bandwidth} = \text{Constant}$  (Typically 1MHz)
      - For Noninverting Amp:  $\text{Bandwidth} = \text{GBW} / \text{Gain}$
  - Input Offset Voltage
    - Practical OP Amp
      - Zero input Does NOT give Zero output
    - Input Offset Voltage
      - Applied input voltage to obtain Zero output
    - Nulling the offset Voltage
      - Adding External Resistor according to Spec sheet



# OP Amp Considerations (Cont.)

- Input Bias Current
  - Practical OP amp
    - Current flowing into the terminal is NOT Zero
    - To keep the input Tr of OP amp turned on
    - Causes errors proportional to feedback network R
  - To minimize errors
    - feedback R should be low ( $<10\text{K}\Omega$ )
- Slew Rate
  - Maximal rate of change of amplifier output voltage
    - Ex: Slew rate of 741 =  $0.5\text{ V} / \mu\text{s}$ 
      - » Time to output change from  $-5\text{V}$  to  $5\text{V}$  =  $20\ \mu\text{s}$
  - To Minimize slew rate problem
    - Use OP amp with smaller external compensating C



# OP Amp Considerations (Cont.)

- Power Supply
  - Usually  $\pm 15V$ 
    - Linear Range  $\pm 13V$
  - Reducing power supply voltage
    - Results reduced linear range
    - Device does not work  $< 4V$
- Different OP Amps
  - Bipolar Op Amps
    - Good input offset stability
    - Moderate input bias current and Input resistances
  - FET
    - Very Low input bias current and Very High Input resistances
    - Poor Input offset voltage stability



# OP Amps on the market

- Common OP amps, Typical Specifications

Figure 1.18 shows characteristics of commonly used op amps.

Type	Feature	Input bias current	Offset voltage	GBW	Price
741	Low cost	80 nA	2 mV	1 MHz	\$0.35
308	Low bias current	3 nA	2 mV	1 MHz	0.69
ICL8007	FET input	50 pA	50 mV	1 MHz	5.00
CA3130	FET input	6 pA	20 mV	4 MHz	0.89
OP-07	Low offset	1 nA	30 $\mu$ V	800 kHz	1.99
LH0052	Low offset	0.5 pA	0.1 $\mu$ V	1 MHz	5.00
LF351	High GBW	50 pA	5 mV	4 MHz	0.62
LM312	Low bias current	3 nA	0.7 mV	1 MHz	2.49
UC4250	Programmable	7.5 nA	4 mV	800 kHz	1.84





# Filters

- Passive Circuits
  - Contains only passive elements
    - Resistors, Capacitors and Inductors
  - Examples
    - Bridge Circuit
    - Voltage Divider
    - Filters
- Filters
  - Eliminate unwanted signal from the loop
  - Low Pass, High Pass, Band Pass, Notch, ...



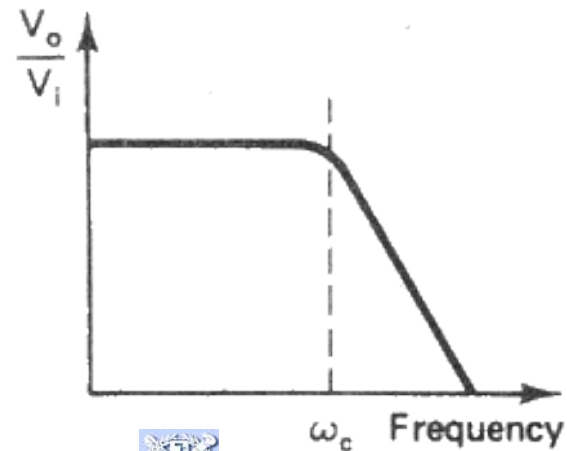
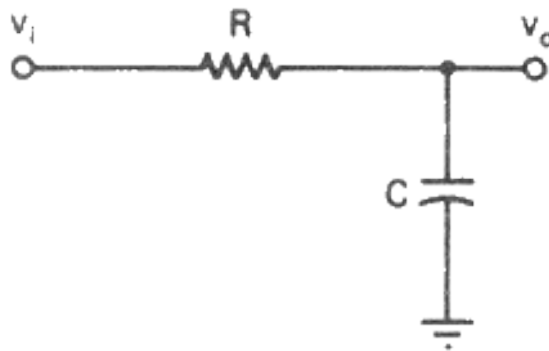
# Passive first-order Low pass Filter

- Pass desired Audio signal and reject undesired RF
- Order of Filter
  - Number of C and L

- Show that

$$\frac{V_o}{V_i} = \frac{1}{1 + j\omega\tau}, \quad \tau = RC$$

- Plot Magnitude and Phase plot (Bode plot)
- Meaning of  $\omega_c$



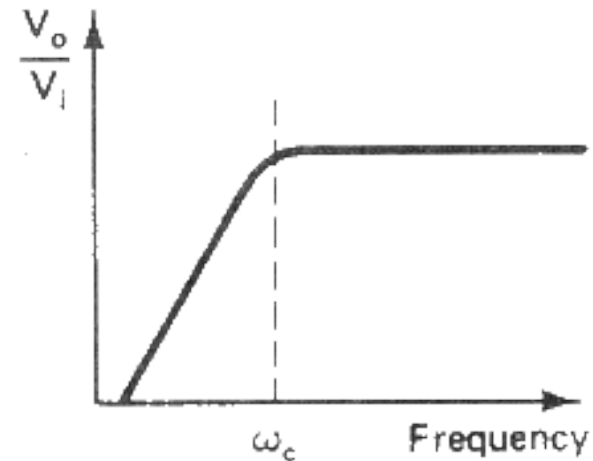
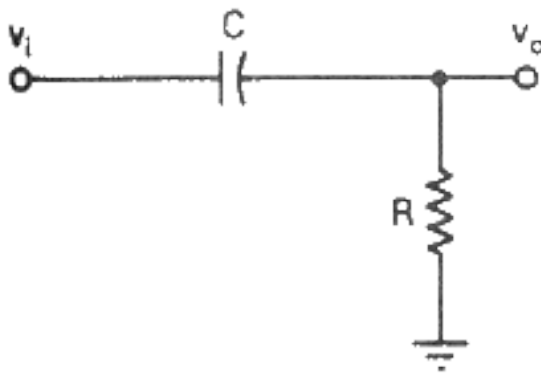
# Passive first-order High pass Filter

- Pass desired High frequency signal and reject undesired low frequency signal

- ◆ Show that

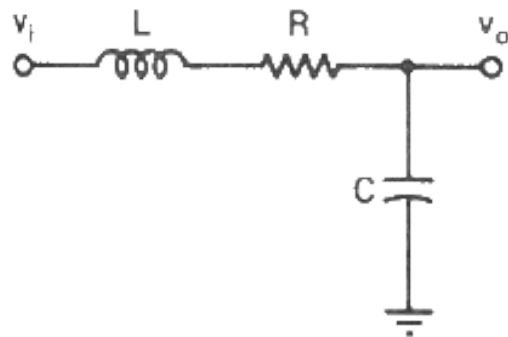
$$\frac{V_o}{V_i} = \frac{j\omega\tau}{1 + j\omega\tau}, \quad \tau = RC$$

- ◆ Plot Magnitude and Phase plot (Bode plot)
- ◆ Meaning of  $\omega_c$



# Passive second-order Low pass Filter

- To increase the attenuation of transfer function
- Order of Filter
  - ◆ Number of C and L



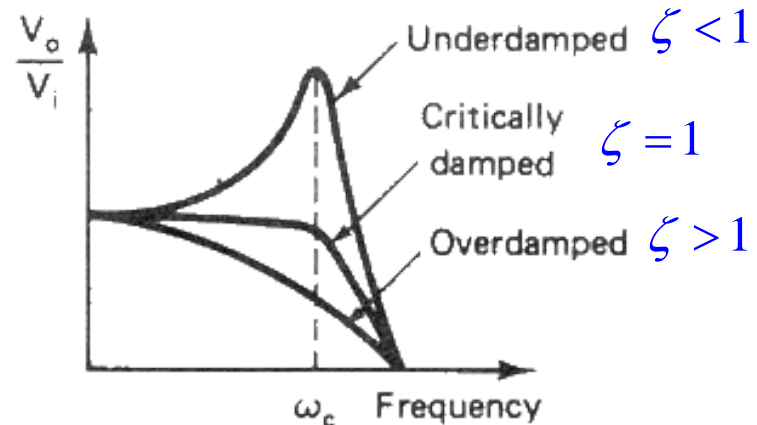
- ◆ Show that

$$\frac{V_o}{V_i} = \frac{1}{(j\omega/\omega_c)^2 + (2\zeta j\omega/\omega_c) + 1}$$

$$\omega_c = \sqrt{\frac{1}{LC}}, \zeta = \frac{R}{2} \sqrt{\frac{C}{L}}$$

- ◆ Meaning of Quality factor

$$Q = \frac{1}{2\zeta} = \frac{\omega_c}{\Delta\omega}, \Delta\omega = 3dB BW$$



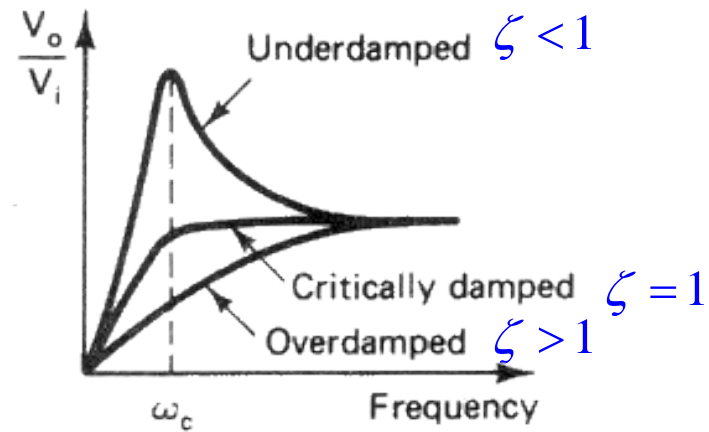
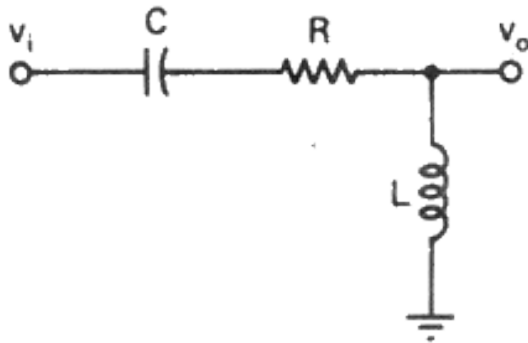
# Passive second-order High pass Filter

- To increase the attenuation of transfer function
- Order of Filter
  - ◆ Number of C and L

◆ Show that

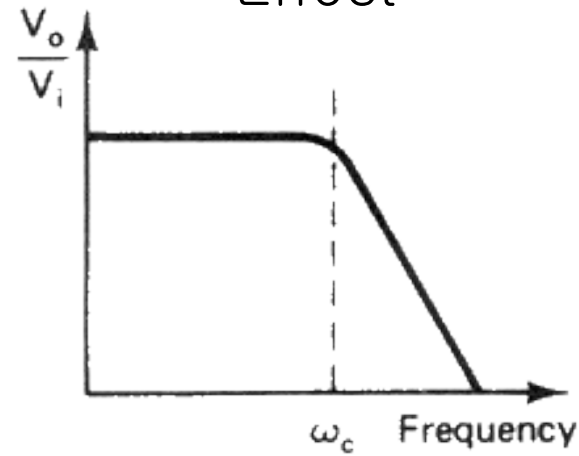
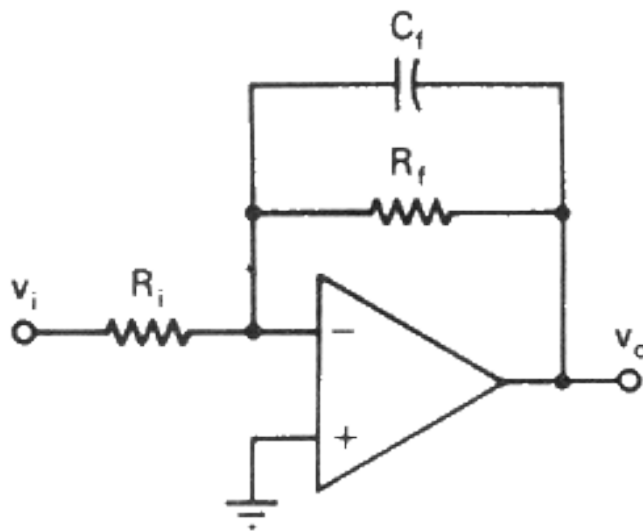
$$\frac{V_o}{V_i} = \frac{\omega^2}{(j\omega/\omega_c)^2 + (2\zeta j\omega/\omega_c) + 1}$$

$$\omega_c = \sqrt{\frac{1}{LC}}, \zeta = \frac{R}{2} \sqrt{\frac{C}{L}}$$



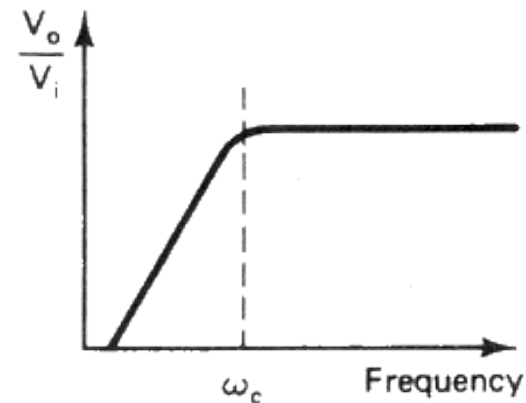
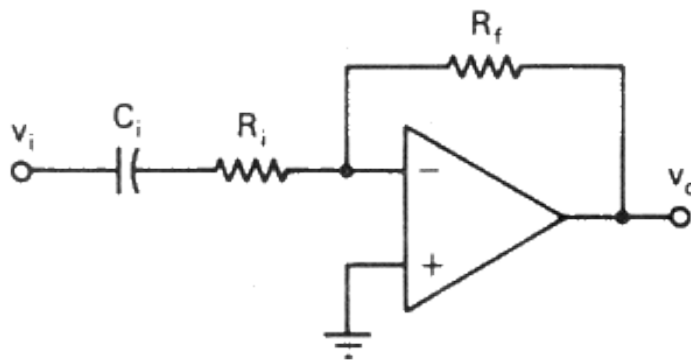
# Active First-order Low Pass Filter

- Inverting Amp + Feedback Capacitor
- Identical frequency response with Passive filter
- Very Low Output impedance
  - Negligible Loading Effect



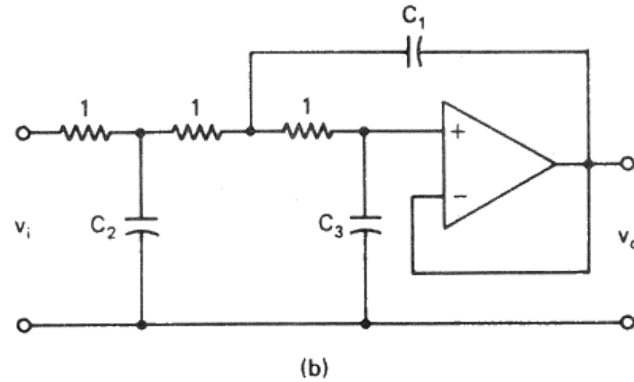
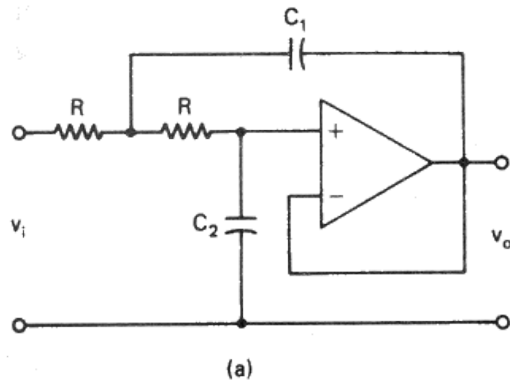
# Active First-order High Pass Filter

- Inverting Amp + Input Capacitor
- Identical frequency response with Passive filter
- Very Low Output impedance
  - ◆ Negligible Loading Effect

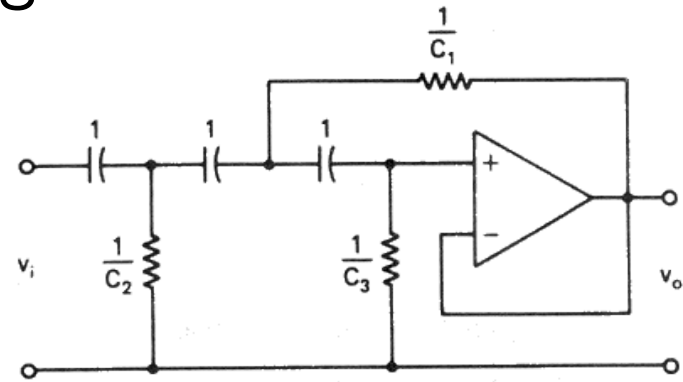
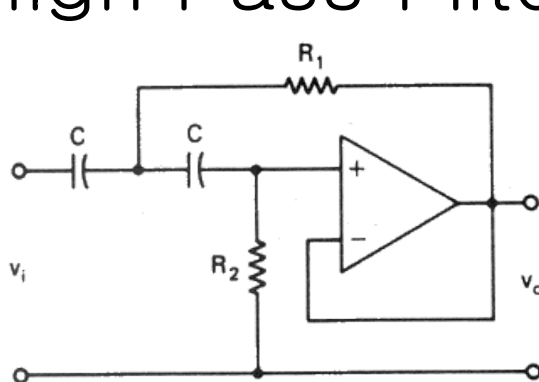


# Active High-order Filters

- Low Pass Filters



- High Pass Filters





# Bandpass and Band-reject Filters

- Butterworth Filters
  - Maximally Flat Magnitude response in pass band
  - High Attenuation Rate
- Chebyshev Filters
  - Maximum Attenuation Rate
  - Ripple in pass band
- Bessel Filters
  - Maximally flat time delay in response to step input
  - Attenuation Rate is very gradual



# Filter Design Table

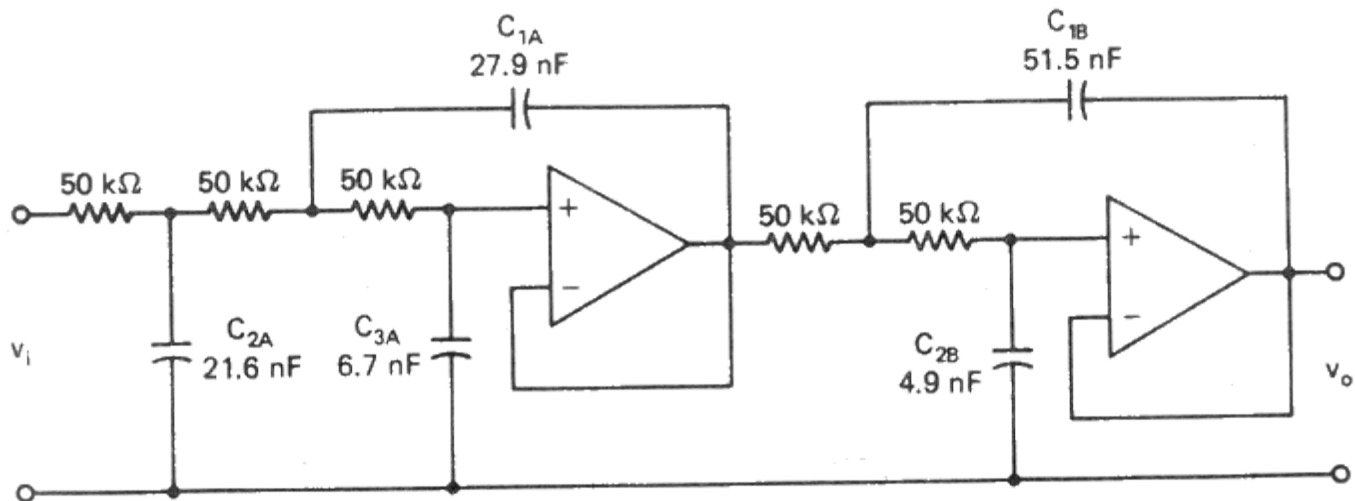
- C when  $\omega_0 = R_0 = 1$

Poles	$C_1$	$C_2$	$C_3$	$C_1$	$C_2$	$C_3$
	Bessel			Butterworth		
2	9.066 -1	6.799 -1		1.414 +0	7.071 -1	
3	1.423 +0	9.880 -1	2.538 -1	3.546 +0	1.392 +0	2.024 -1
4	7.351 -1	6.746 -1		1.082 +0	9.241 -1	
	1.012 +0	3.900 -1		2.613 +0	3.825 -1	
5	1.009 +0	8.712 -1	3.095 -1	1.753 +0	1.354 +0	4.214 -1
	1.041 +0	3.098 -1		3.235 +0	3.089 -1	
6	6.352 -1	6.098 -1		1.035 +0	9.660 -1	
	7.225 -1	4.835 -1		1.414 +0	7.071 -1	
	1.073 +0	2.561 -1		3.863 +0	2.588 -1	
	2-dB Chebyshev			0.25-dB Chebyshev		
2	2.672 +0	5.246 -1		1.778 +0	6.789 -1	
3	2.782 +1	3.113 +0	3.892 -2	8.551 +0	2.018 +0	1.109 -1
4	4.021 +0	1.163 +0		2.221 +0	1.285 +0	
	9.707 +0	1.150 -1		5.363 +0	2.084 -1	
5	1.240 +1	4.953 +0	1.963 -1	5.543 +0	2.898 +0	3.425 -1
	1.499 +1	7.169 -2		8.061 +0	1.341 -1	
6	5.750 +0	1.769 +0		3.044 +0	1.875 +0	
	7.853 +0	2.426 -1		4.159 +0	4.296 -1	
	2.146 +1	4.902 -2		1.136 +1	9.323 -2	

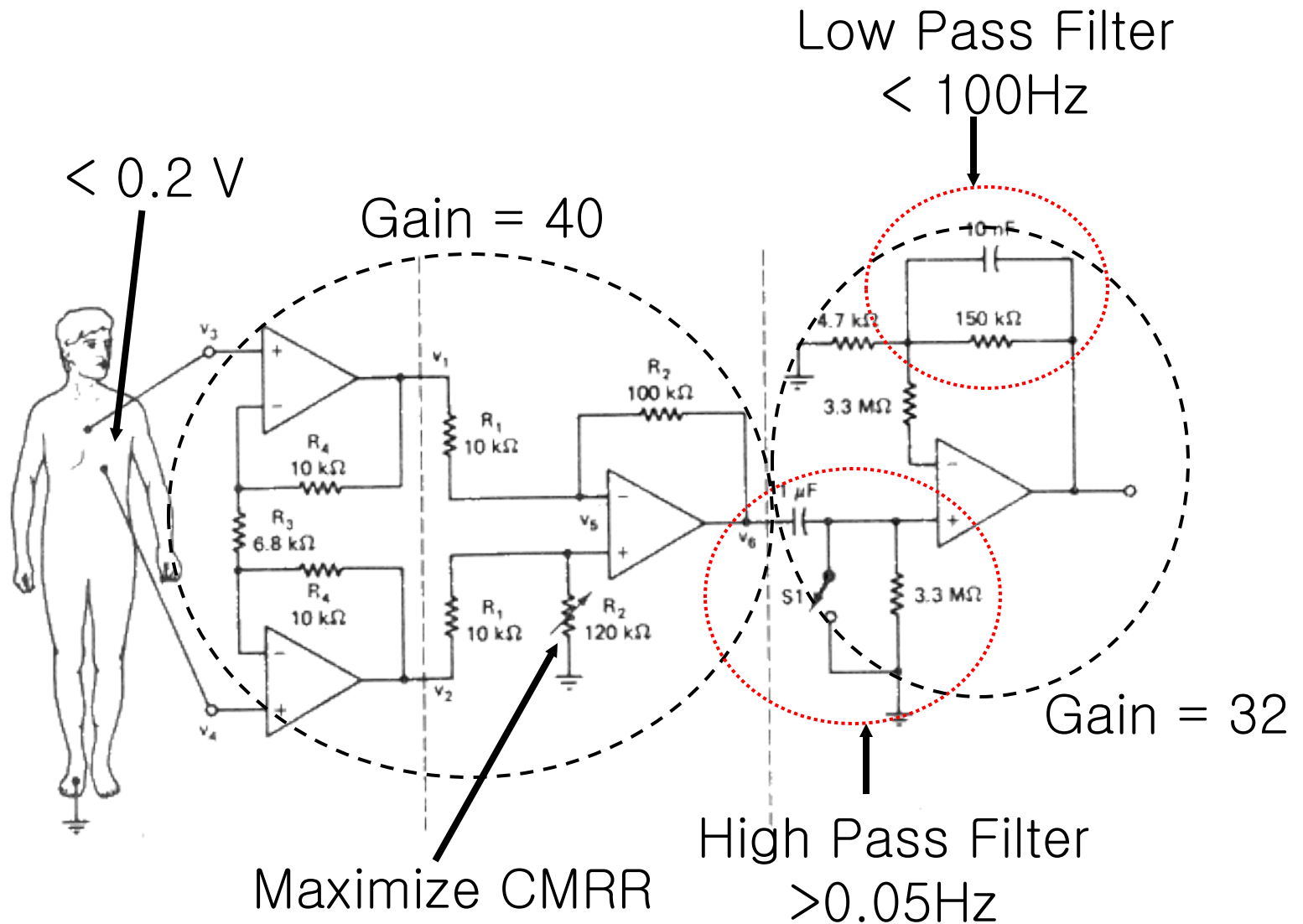


# Filter Design Example

- Low pass five-pole Butterworth filter with a corner frequency of 200Hz and input resistance of 50K $\Omega$ 
  - Economic Solution = 3<sup>rd</sup> order + 2<sup>nd</sup> order
  - Desired R and C ?
    - $C_{1A} = (\omega_0 R_0 C_0) / (\omega R)$   
 $= 1 \times 1 \times 1.753 / 2\pi \times 200 \times 50K = 27.9 \text{ nF}$
    - $C_{2A} = 21.6 \text{ nF}$ ,  $C_{3A} = 6.7 \text{ nF}$ ,  $C_{1B} = 51.5 \text{ nF}$ ,  $C_{2B} = 4.9 \text{ nF}$



# The Electrocardiogram Amplifier



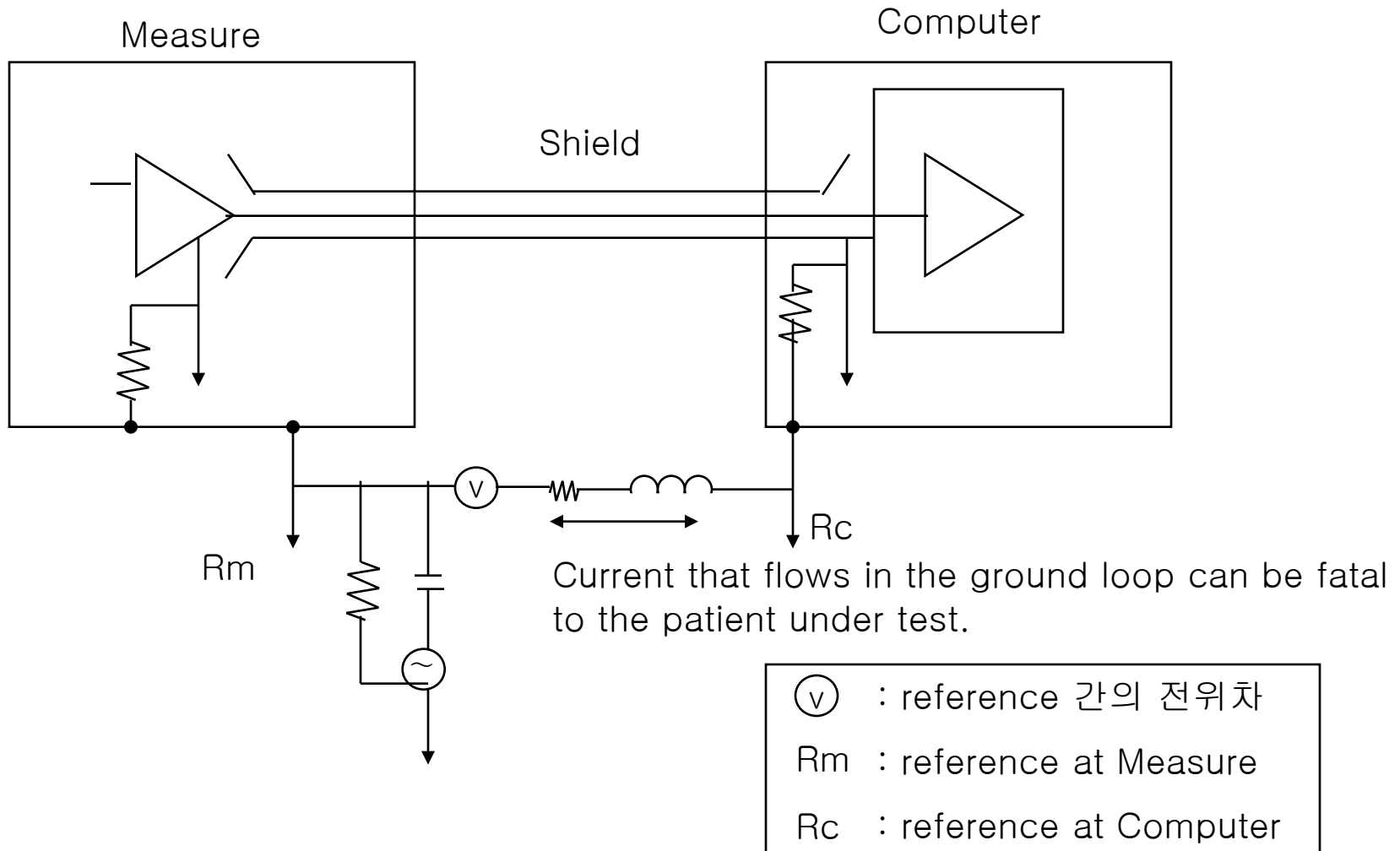
# Interference

- Noise : random
- Interference : not random, comes from a known source
- Dominant interference : 60Hz
  - Thru.      ① AC capacitive coupling  
                 ② AC inductive coupling  
                 ③ Ground loops
  - Solutions
    - (1) Elimination at the source
      - Use of Instrumentation Amps and Isolation Amps.
      - Star Ground (one true ground)
    - (2) (Adaptive) Filtering



# Grounding & Instrumentation Amp.

- Ground Loop is a problem.



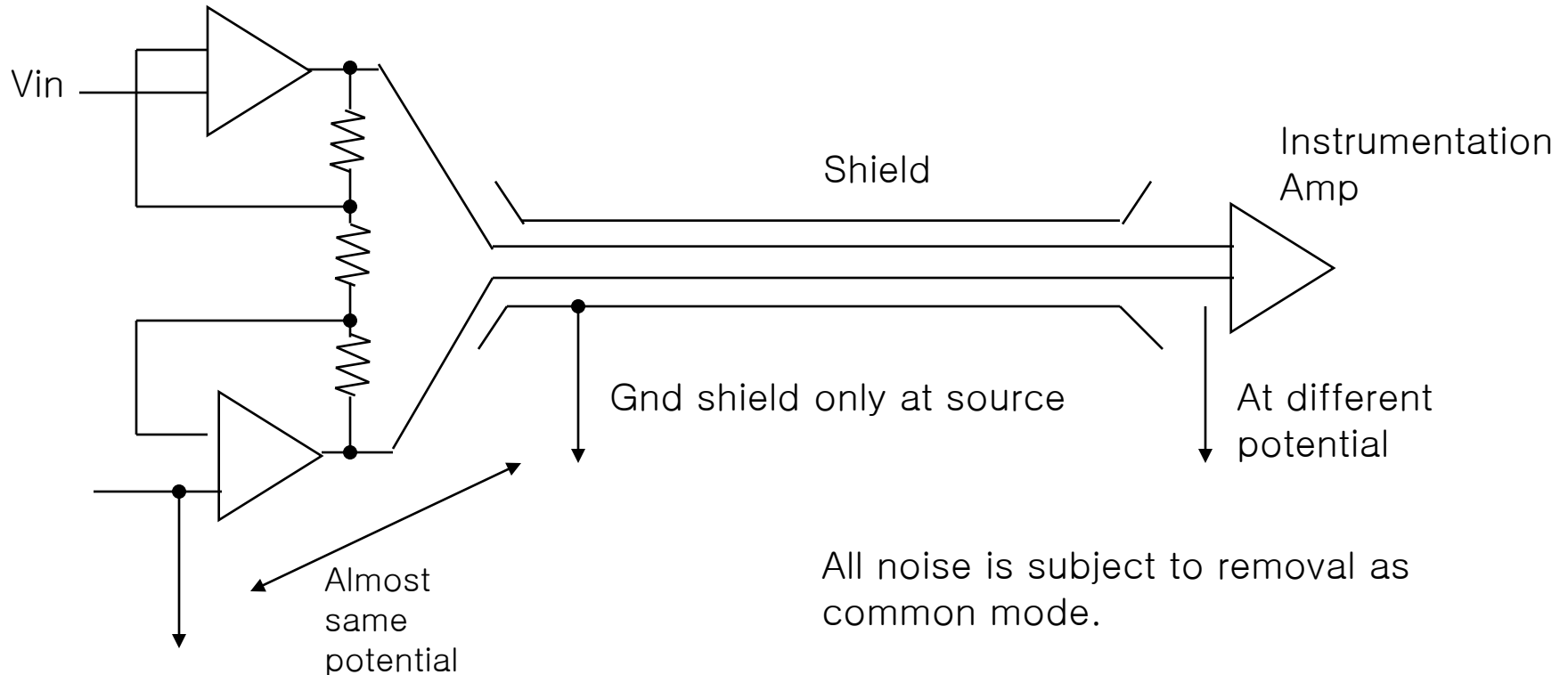
# Grounding & Instrumentation Amp.

- **Ground Loop => safety**  
During ExG (x=E,M,C etc.) measurements, a ground loop current can threaten the safety of the patient under measurement.
- **Bias current => safety**  
Devices with particularly small  $I_B$  is favored.  
Ex) AD55L max  $I_B = 75\text{fA}$   
AD00L max  $I_B = 10\text{fA}$



# Grounding & Instrumentation Amp.

- Solution : (I) Differential Transmission :
- Grounding only at source to prevent the group loop.

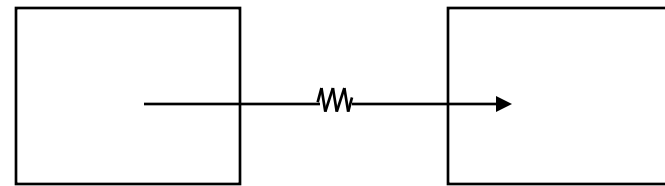
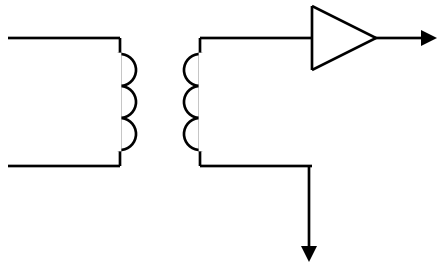




# Grounding & Instrumentation Amp.

- Solution(II) : Isolation between Measure and Computer stations.

- By transformer



Optics, RF ....

- Optical coupling : optical isolator : (LED/LD)–PD combination
- Radio link
  - Signal – Modulator – Transmitter ...– Receiver – Demodulator



# Datasheet



## Low Cost, Miniature Isolation Amplifiers

### AD202/AD204

#### FEATURES

- Small Size: 4 Channels/Inch
- Low Power: 35 mW (AD204)
- High Accuracy:  $\pm 0.025\%$  max Nonlinearity (K Grade)
- High CMR: 130 dB (Gain = 100 V/V)
- Wide Bandwidth: 5 kHz Full-Power (AD204)
- High CMV Isolation:  $\pm 2000$  V pk Continuous (K Grade)  
(Signal and Power)
- Isolated Power Outputs
- Uncommitted Input Amplifier

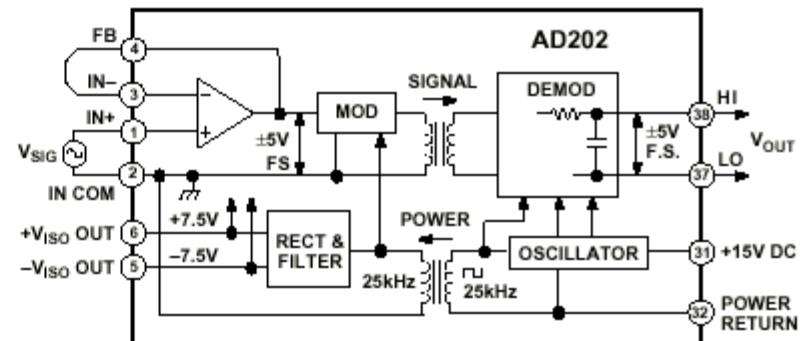
#### APPLICATIONS

- Multichannel Data Acquisition
- Current Shunt Measurements
- Motor Controls
- Process Signal Isolation
- High Voltage Instrumentation Amplifier

#### GENERAL DESCRIPTION

The AD202 and AD204 are general purpose, two-port, transformer-coupled isolation amplifiers that may be used in a broad range of applications where input signals must be measured, these industry standard isolation amplifiers offer a complete isolation function, with both signal and power isolation provided

#### FUNCTIONAL BLOCK DIAGRAM



Isolation mode rejection ratio(IMRR):105dB@60Hz

ing. For applications requiring a low profile, the DIP package provides a height of just 0.350".

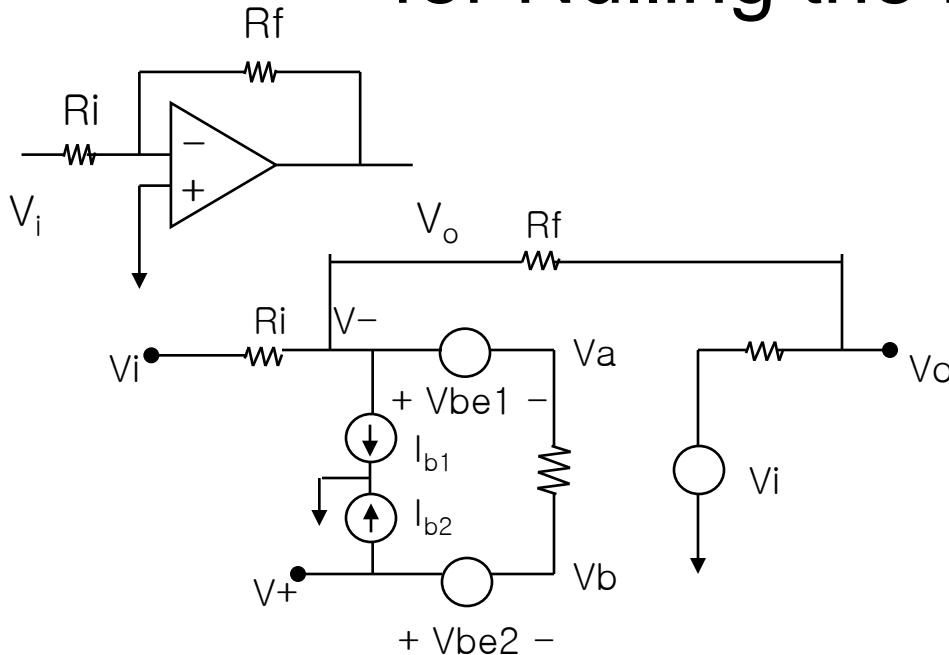
**High Accuracy:** With a maximum nonlinearity of  $\pm 0.025\%$  for the AD202K/AD204K ( $\pm 0.05\%$  for the AD202J/AD204J) and low drift over temperature, the AD202 and AD204 provide high isolation without loss of signal integrity.

**Low Power:** Power consumption of 35 mW (AD204) and 75 mW (AD202) over the full signal range makes these isolators power budgets.



Intro. BME

# Choice of resistors (R3 and R4) for Nulling the bias current



Assume

$$V^+ = V^-$$

$$I_{b1} = I_{b2} = I_b$$

$$\frac{V_o - V^-}{R_f} + \frac{V_i - V^-}{R_i} = I_b \quad (\text{eq 1})$$

Ideally we want,  $V_o/R_f = -V_i/R_i$  (eq 2)

Comparing eq 1 and 2,

$$I_b + V^+ / (R_f // R_i) = 0$$

This condition can be satisfied by the next circuit.

