

## **Chapter 2 Fluid Statics**

**2.1 Pressure-Density-Height Relationship**

**2.2 Absolute and Gage Pressure**

**2.3 Manometry**

**2.4 Forces on Submerged Plane Surfaces**

**2.5 Forces on Submerged Curved Surfaces**

**2.6 Buoyancy and Floatation**

**2.7 Fluid Masses Subjected to Acceleration**

**Objectives**

구름위로 비를 만드는 커다란 나무  
한 그루 있어 그 잎사귀를 흔들어  
비를 내리고 높은 탑 위로 올라가 나는 멀리  
돌들을 나르는 강물을 본다. 그리고 그 너머 더 먼 곳에도  
강이 있어 더욱 많은 돌들을 나르고 그 돌들이  
밀려가 내 눈이 가닿지 않는 그 어디에서  
한 도시를 이루고 한 나라를 이룬다 해도



류 시화의 “구월의 이틀”  
중에서

## 2.1 Pressure-Density-Height Relationship

Fluid statics

~ study of fluid problems in which there is no relative motion between fluid elements

- no velocity gradients
- no shear stress
- only normal pressure forces are present

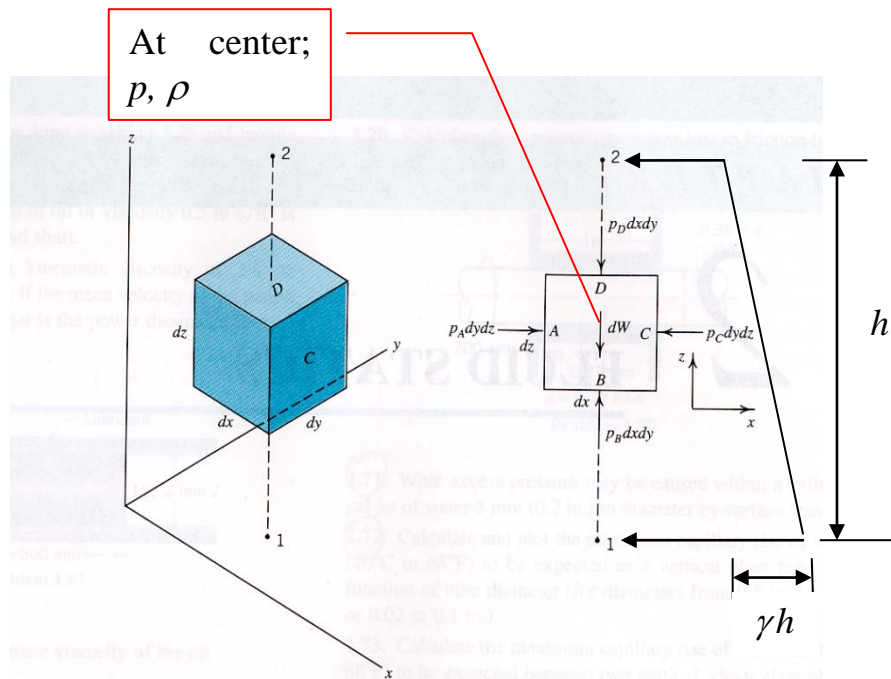


Fig. 2.1

- Static equilibrium of a typical differential element of fluid
  - vertical axis =  $z$  - axis = direction parallel to the gravitational force field
  - Newton's first law

$$\sum F = 0$$

$F$  = external force:  
pressure, shear, gravity

$$\Sigma F_x = 0: \quad \Sigma F_x = p_A dz - p_c dz = 0 \quad (2.1)$$

Assume unit thickness  
in y direction;  $dy=1$

$$\Sigma F_z = 0: \quad \Sigma p_B dx - p_D dx - dW = 0 \quad (2.2)$$

in which  $p = f(x, z)$

$$p_A = p - \frac{\partial p}{\partial x} \frac{dx}{2} \quad p_c = p + \frac{\partial p}{\partial x} \frac{dx}{2} \quad (1)$$

$\frac{\partial p}{\partial x}$  = variation of pressure  
with  $x$  direction

$$p_B = p - \frac{\partial p}{\partial z} \frac{dz}{2} \quad p_D = p + \frac{\partial p}{\partial z} \frac{dz}{2} \quad (2)$$

$$dW = \rho g dx dz = \gamma dx dz \quad (3)$$

Substituting (1) and (3) into (2.1) yields

$$dF_x = \left( p - \frac{\partial p}{\partial x} \frac{dx}{2} \right) dz - \left( p + \frac{\partial p}{\partial x} \frac{dx}{2} \right) dz = -\frac{\partial p}{\partial x} dx dz = 0$$

$$\rightarrow \frac{\partial p}{\partial x} = 0 \quad (A)$$

Substituting (2) and (3) into (2.2) yields

$$dF_z = \left( p - \frac{\partial p}{\partial z} \frac{dz}{2} \right) dx - \left( p + \frac{\partial p}{\partial z} \frac{dz}{2} \right) dx - \gamma dx dz = -\frac{\partial p}{\partial z} dz dx - \gamma dx dz = 0$$

$$\rightarrow \frac{\partial p}{\partial z} = \frac{dp}{dz} = -\gamma = -\rho g \quad (\text{partial derivative} \rightarrow \text{total derivative because of (A)})$$

$$\frac{\partial p}{\partial x} = 0 \quad (\because p = fn(z \text{ only}))$$

(1)  $\frac{\partial p}{\partial x} = 0$

~ no variation of pressure with horizontal distance

~ pressure is constant in a horizontal plane in a static fluid

$p_1 = p_2 = p_3$

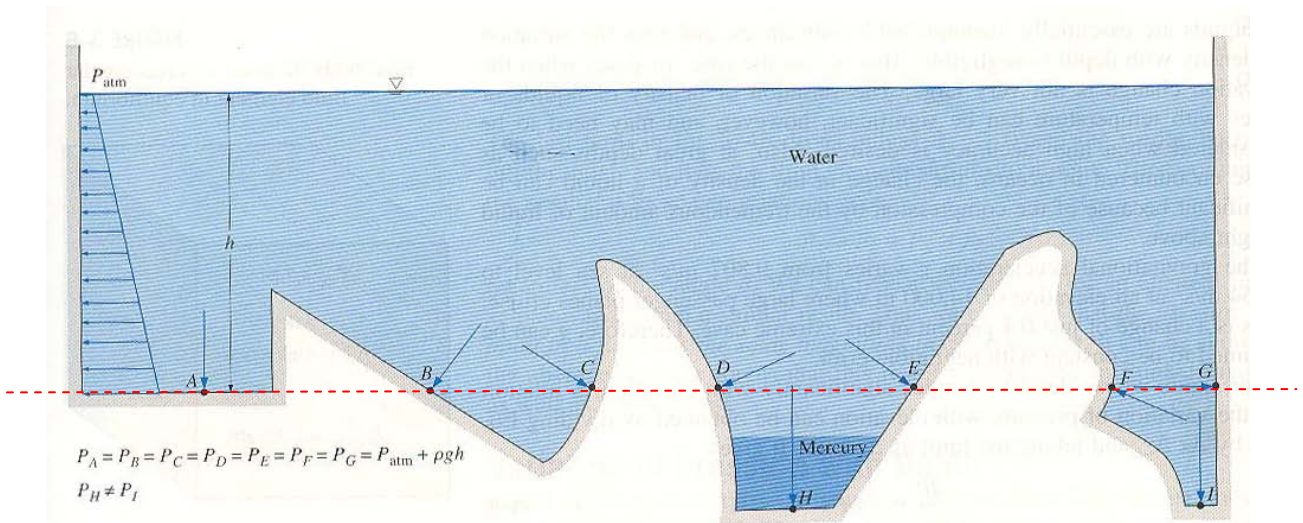
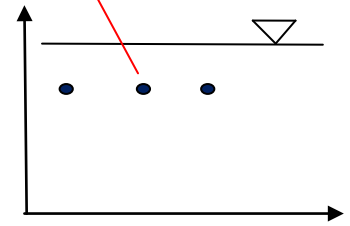
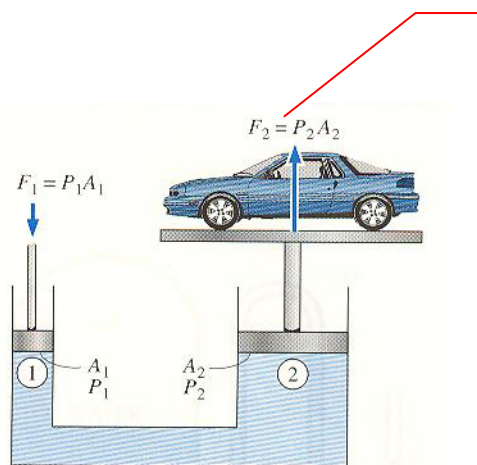


FIGURE 3-9

The pressure is the same at all points on a horizontal plane in a given fluid regardless of geometry, provided that the points are interconnected by the same fluid.



$p_1 = p_2$   
 $\frac{F_1}{A_1} = \frac{F_2}{A_2}$   
 $F_2 = \frac{A_2}{A_1} F_1$   
 $\frac{A_2}{A_1} = \text{mechanical advantage}$   
*of hydraulic lift*

FIGURE 3-10

Lifting of a large weight by a small force by the application of Pascal's law.

(2)  $\frac{dp}{dz} = -\gamma$  (minus sign indicates that as  $z$  gets larger, the pressure gets smaller)

$$\rightarrow -dz = \frac{dp}{\gamma}$$

$$\int_{z_1}^{z_2} -dz = \int_{p_1}^{p_2} \frac{dp}{\gamma}$$

Integrate over depth

$$(z_2 - z_1) = -\int_{p_1}^{p_2} \frac{dp}{\gamma} = \int_{p_2}^{p_1} \frac{dp}{\gamma} \tag{2.4}$$

For fluid of constant density (incompressible fluid;  $\gamma = \text{const.}$ )

$$z_2 - z_1 = h = \frac{p_1 - p_2}{\gamma}$$

$$\therefore p_1 - p_2 = \gamma(z_2 - z_1) = \gamma h$$

$$\therefore p_1 = p_2 + \gamma h \tag{2.5}$$

~ increase of pressure with depth in a fluid of constant density  $\rightarrow$  linear increase

~ expressed as a head  $h$  of fluid of specific weight  $\gamma$

~ heads in millimeters of mercury, meters of water;  $\frac{\Delta p}{\gamma} = h$  (m)

[Cf] For compressible fluid,  $\gamma = fn(z \text{ or } p)$

[Re] External forces

no contact

1) body force - forces acting on the fluid element

- gravity force, centrifugal force, Coriolis's force (due to Earth's rotation)

2) surface force - forces transmitted from the surrounding fluid and acting at right angles

against sides of the fluid element

- pressure, shear force

• Manometer or Piezometer

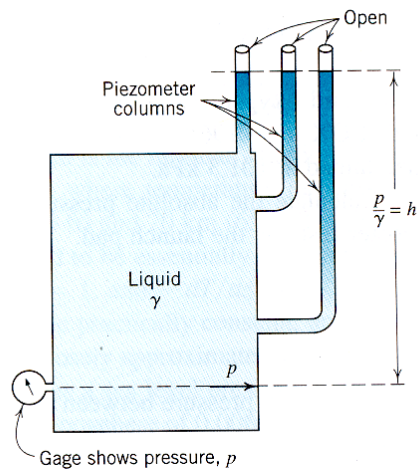


Fig. 2.2

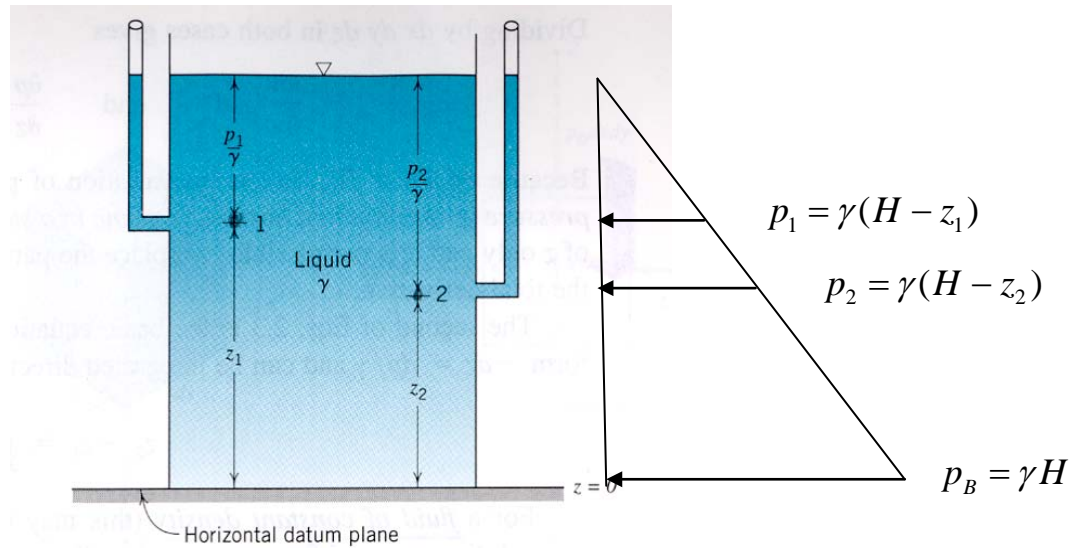
$h$  = height of a column of any fluid

$$h \text{ (m of H}_2\text{O)} = \frac{p \text{ (kN/m}^2\text{)}}{9.81 \text{ kN/m}^3} = 0.102 \times p \text{ (kN/m}^2\text{)}$$

$\gamma_w$

• For a static fluid

$$\frac{p_1}{\gamma} + z_1 = \frac{p_2}{\gamma} + z_2 = \text{const.} \tag{2.6}$$



- For a fluid of variable density (compressible fluid)

~ need to know a relationship between  $p$  and  $\gamma$

~ oceanography, meteorology

[IP 2.1] The liquid oxygen (LOX) tank of space shuttle booster is filled to a depth of 10 m with LOX at  $-196^\circ\text{C}$ . The absolute pressure in the vapor above the liquid surface is 101.3 kPa.

Calculate absolute pressure at the inlet valve.

[Sol]

From App. 2 (Table A2.1)

$$\rho \text{ of LOX at } -196^\circ\text{C} = 1,206 \text{ kg/m}^3$$

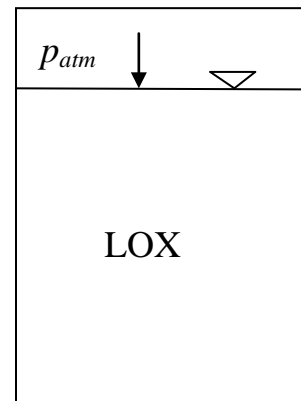
$$p_2 = p_{atm} + \gamma_{LOX} h$$

$$p_2 = 101.3 \text{ kPa} + (1,206 \text{ kg/m}^3) (9.81 \text{ m/s}^2) (10 \text{ m})$$

$$= 101.3 \text{ kPa} + 118,308 \text{ kg}\cdot\text{m/s}^2/\text{m}^2$$

$$= 101.3 \text{ kPa} + 118,308 \text{ kPa}$$

$$= 219.6 \text{ kPa absolute}$$





2.2 Absolute and Gage Pressure

1) absolute pressure =  $\begin{cases} \text{atmospheric pressure} + \text{gage pressure for } p > p_{atm} \\ \text{atmospheric pressure} - \text{vacuum for } p < p_{atm} \end{cases}$

2) relative (gage) pressure  $\rightarrow p_{atm} = 0$

- ┌ Bourdon pressure gage ~ measure gage pressure  $\Rightarrow$  open U-tube manometer
- └ Aneroid pressure gage ~ measure absolute pressure  $\Rightarrow$  mercury barometer

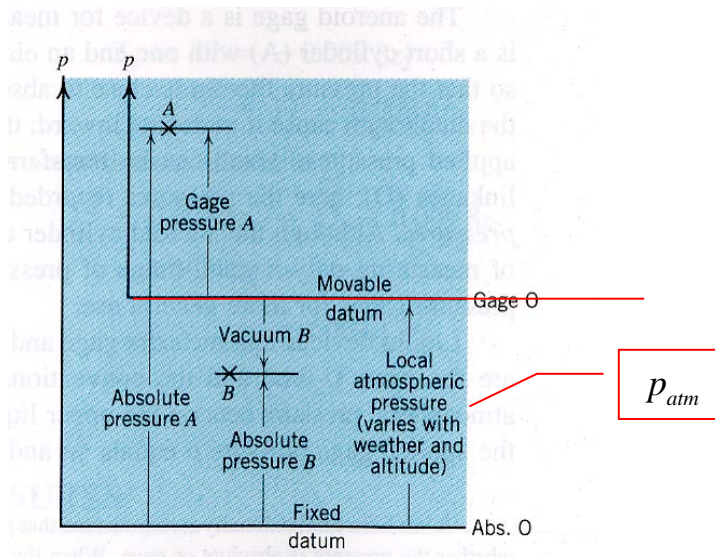


Fig. 2.6

- gage pressure is normally substituted by "pressure"

• Mercury barometer (Fig. 2.5)

~ invented by Torricelli (1643)  $\rightarrow$  measure absolute pressure/local atmospheric pressure

~ filling tube with air-free mercury

~ inverting it with its open end beneath the mercury surface in the receptacle

[IP 2.4] A Bourdon gage registers a vacuum of 310 mm of mercury;

$$p_{atm} = 100 \text{ kPa, absolute.}$$

Gage  
pressure

Find absolute pressure.

[Sol] absolute pressure = 100 kPa – 310 mm Hg

$$= 100 \text{ kPa} - 310 \left( \frac{101.3 \text{ kPa}}{760} \right) = 58.7 \text{ kPa}$$

[Re] App. 1

$$760 \text{ mmHg} = 101.3 \text{ kPa} = 1,013 \text{ mb} \rightarrow 1 \text{ mmHg} = 101,300 / 760 = 133.3 \text{ Pa}$$

$$1 \text{ bar} = 100 \text{ kPa} = 10^3 \text{ mb}$$

$$760 \text{ mmHg} = 760 \times 10^{-3} \text{ m} \times 13.6 \times 9,800 \text{ N/m}^3 = 101.3 \text{ kN/m}^2$$

$$= 101,300 \text{ N/m}^2 / 9,800 \text{ N/m}^3 = 10.3 \text{ m of H}_2\text{O}$$

2.3 Manometry

~ more precise than Bourdon gage (mechanical gage)

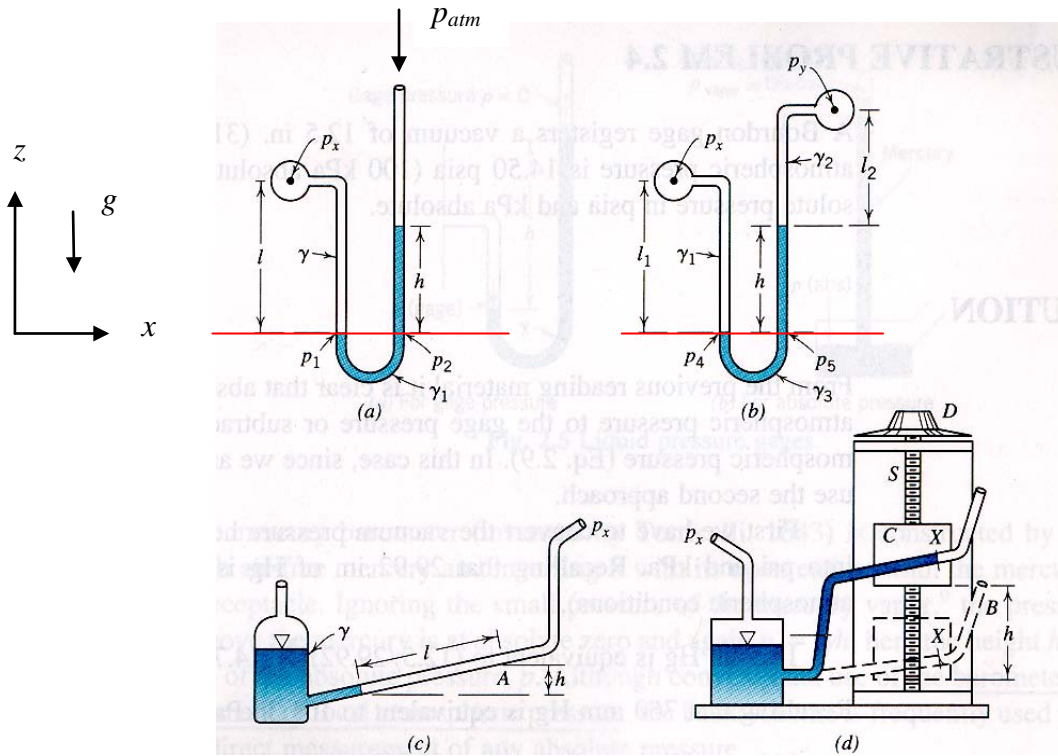


Fig. 2.7

(i) U-tube manometer

~ Over horizontal planes within continuous columns of the same fluid, pressures are equal.

$$\left( \because \frac{\partial p}{\partial x} = 0 \right)$$

$$\rightarrow p_1 = p_2$$

$$p_1 = p_x + \gamma l$$

$$p_2 = 0 + \gamma_1 h \quad \boxed{P_{atm} \rightarrow 0}$$

$$p_1 = p_2; p_x + \gamma l = 0 + \gamma_1 h$$

$$\therefore p_x = \gamma_1 h - \gamma l$$

(ii) Differential manometer

~ measure difference between two unknown pressures

$$p_4 = p_5$$

$$p_4 = p_x + \gamma_1 l_1 \quad p_5 = p_y + \gamma_2 l_2 + \gamma_3 h$$

$$p_x + \gamma_1 l_1 = p_y + \gamma_2 l_2 + \gamma_3 h$$

$$\therefore p_x - p_y = \gamma_2 l_2 + \gamma_3 h - \gamma_1 l_1$$

If  $\gamma_1 = \gamma_2 = \gamma_w$  and  $x$  and  $y$  are horizontal

$$p_x - p_y = \gamma_3 h + \gamma_w (l_2 - l_1) \quad \boxed{-h}$$

$$= \gamma_3 h + \gamma_w (-h) = (\gamma_3 - \gamma_w) h$$

$$\text{head: } \frac{p_x - p_y}{\gamma_w} = \left( \frac{\gamma_3}{\gamma_w} - 1 \right) h$$

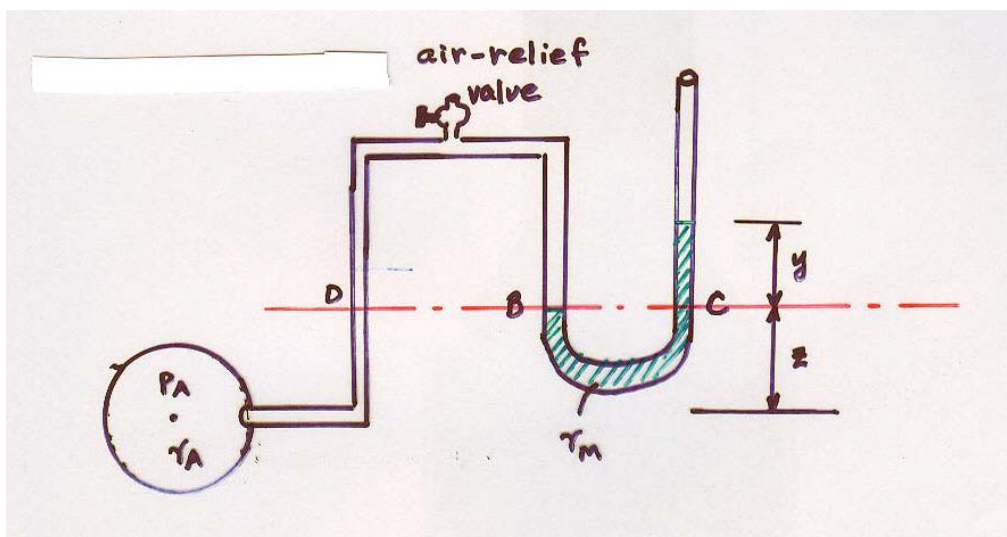
## (iii) Inclined gages

~ measure the comparatively small pressure in low-velocity gas flows

$$p_x = \gamma h = \gamma l \sin \theta$$

reading of  $l >$  reading of  $h \rightarrow$  accurate

## (iv) Open-end manometer



$$p_D = p_B = p_C$$

$$p_D = p_A - \gamma_A z$$

$$p_C = p_{atm} + \gamma_M y$$

$$p_A = p_{atm} + \gamma_M y + \gamma_A z$$

$$\text{head : } \frac{p_A}{\gamma_A} = \frac{p_{atm}}{\gamma_A} + \frac{\gamma_M}{\gamma_A} y + z$$

(v) Measure vacuum

$$p_1 = p_2$$

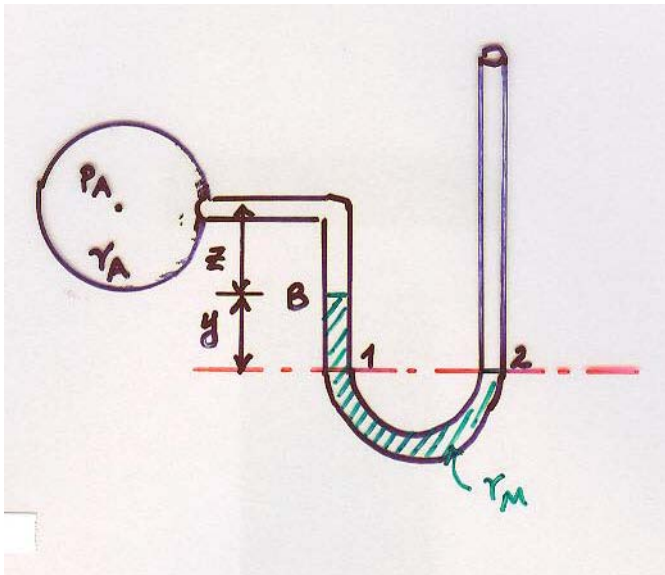
$$p_1 = p_A + \gamma_A z + \gamma_M y$$

$$p_2 = p_{atm}$$

$$p_A + \gamma_A z + \gamma_M y = p_{atm}$$

$$p_A = p_{atm} - \gamma_A z - \gamma_M y$$

$$p_A < p_{atm} \rightarrow \text{vacuum}$$



(vi) Differential manometer

$$p_1 = p_2$$

$$p_1 = p_A - \gamma z_A$$

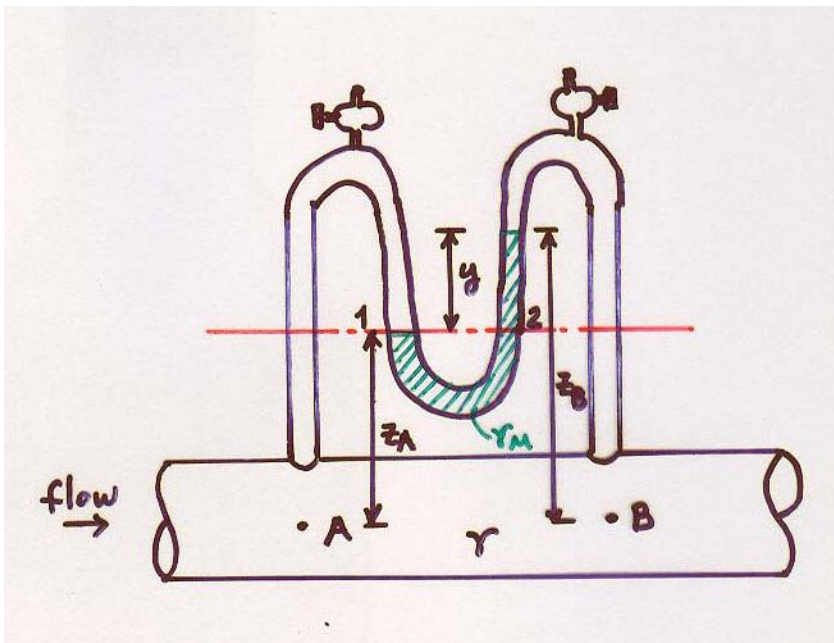
$$p_2 = p_B - \gamma z_B + \gamma_M y$$

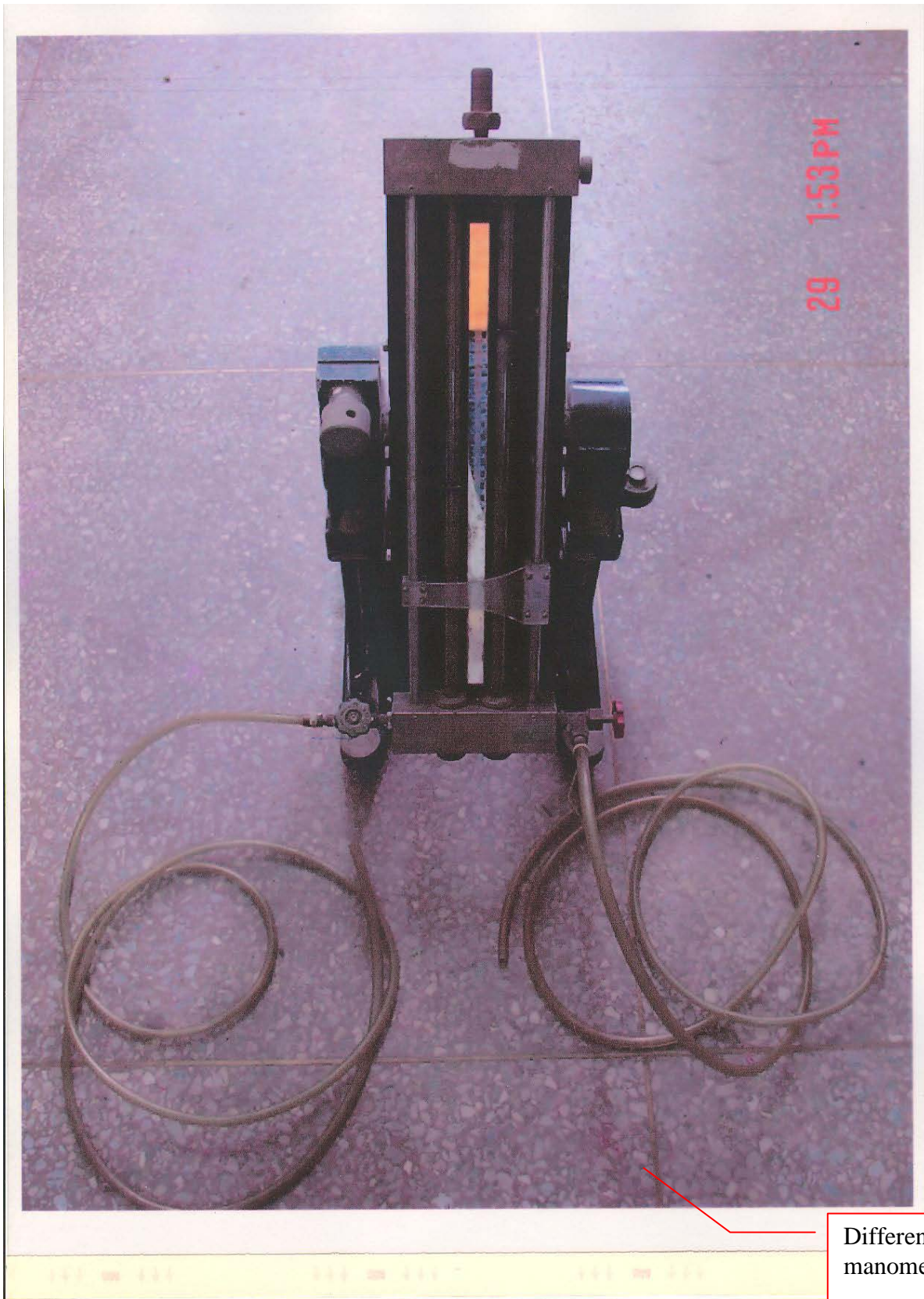
$$\therefore p_A - \gamma z_A = p_B - \gamma z_B + \gamma_M y$$

$$\begin{aligned}P_A - P_B &= \gamma(z_A - z_B) + \gamma_M y \\ &= -\gamma y + \gamma_M y = (\gamma_M - \gamma)y\end{aligned}$$

$$\frac{P_A - P_B}{\gamma} = \left( \frac{\gamma_M}{\gamma} - 1 \right) y$$

$$\text{If } \gamma = \gamma_w \rightarrow \frac{P_A - P_B}{\gamma_w} = (s.g.M - 1)y$$









For measuring large pressure difference,

→ use heavy measuring liquid, such as mercury  $s.g. = 13.55$  → makes  $y$  small

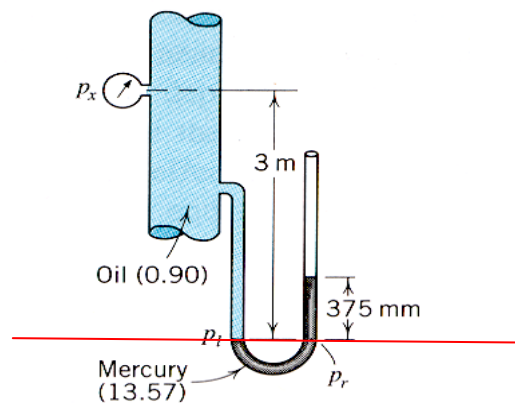
For a small pressure difference,

→ use a light fluid such as oil, or even air  $s.g. < 1$

• Practical considerations for manometry

- ① Temperature effects on densities of manometer liquids should be appreciated.
- ② Errors due to capillarity may frequently be canceled by selecting manometer tubes of uniform sizes.

[IP 2.5] The vertical pipeline shown contains oil of specific gravity 0.90. Find  $p_x$



[Sol]

$$p_l = p_r$$

$$\gamma_f = s.g. \times \gamma_w$$

$$p_l = p_x + (0.90 \times 9.8 \times 10^3) \times 3$$

$$p_{atm} = 0$$

$$p_r = (13.57 \times 9.8 \times 10^3) \times 0.375$$

$$\therefore p_x = 23.4 \text{ kPa (kN/m}^2\text{)}$$

## 2.4 Forces on Submerged Plane Surfaces

- Calculation of magnitude, direction, and location of the total forces on surfaces submerged in a liquid is essential.

→ design of dams, bulkheads, gates, tanks, ships

- Pressure variation for non-horizontal planes

$$\frac{\partial p}{\partial z} = -\gamma$$

$$\therefore p = \gamma h$$

→ The pressure varies linearly with depth.

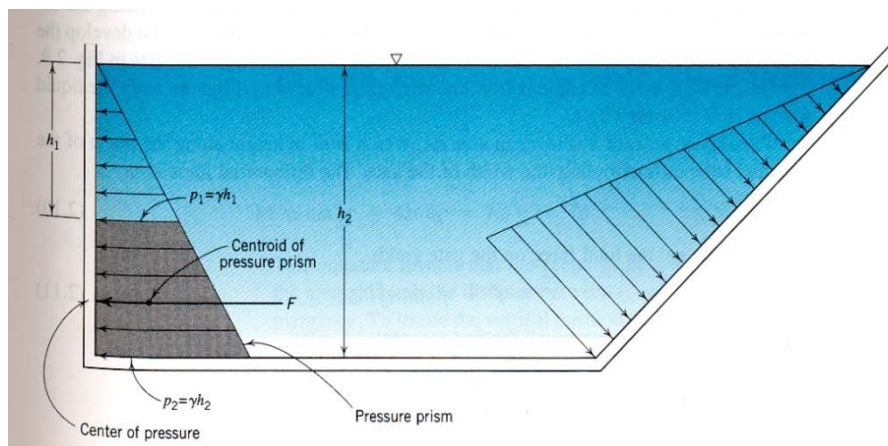


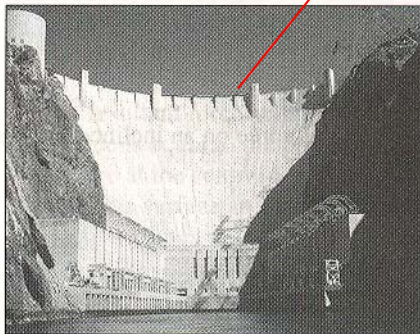
Fig. 2.8

Dams & gates

Spillway



Arch dam



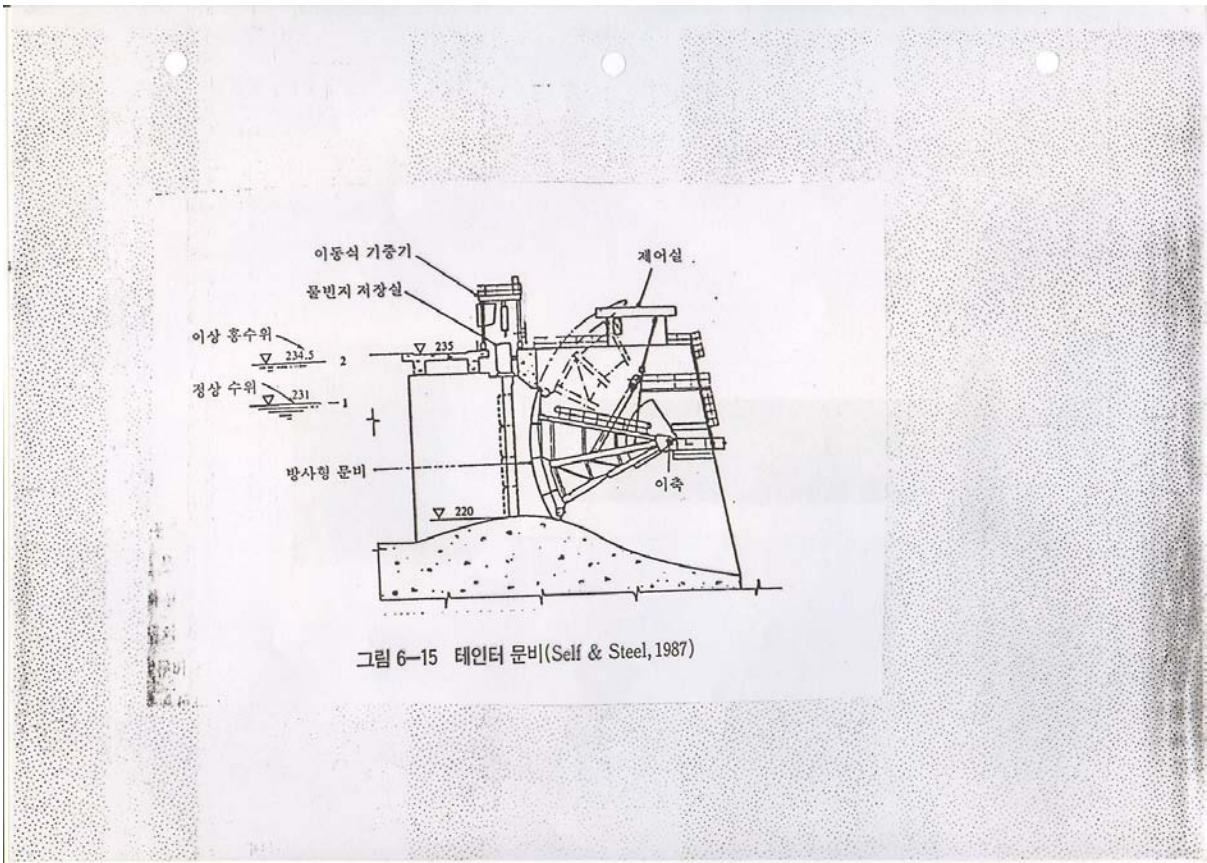
**FIGURE 3-23**  
Hoover Dam.

*Courtesy United States Department of the Interior,  
Bureau of Reclamation-Lower Colorado Region.*



소양강댐 여수로 (테인터게이트)





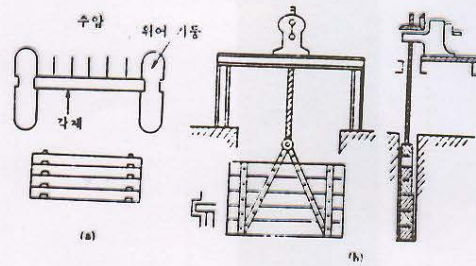


그림 4.58 물빈지

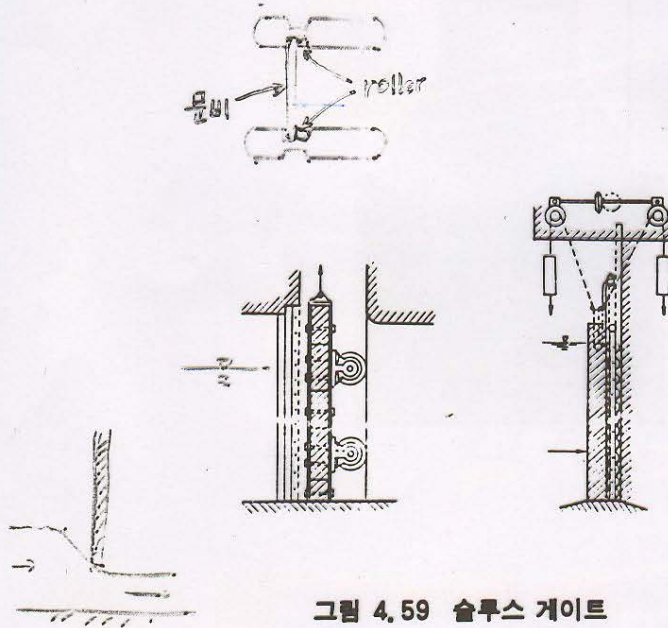
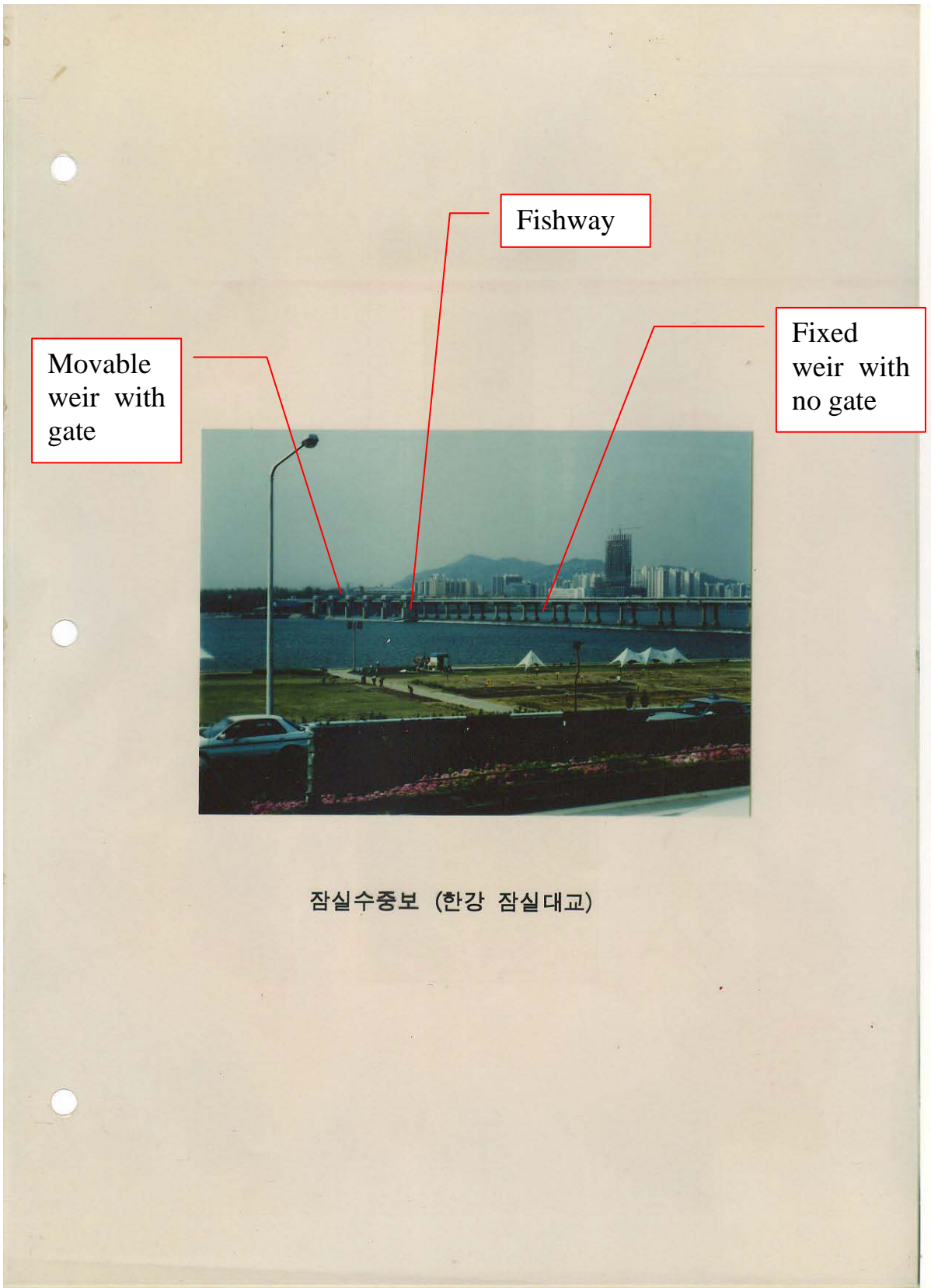


그림 4.59 슬루스 게이트





- Pressure on the inclined plane

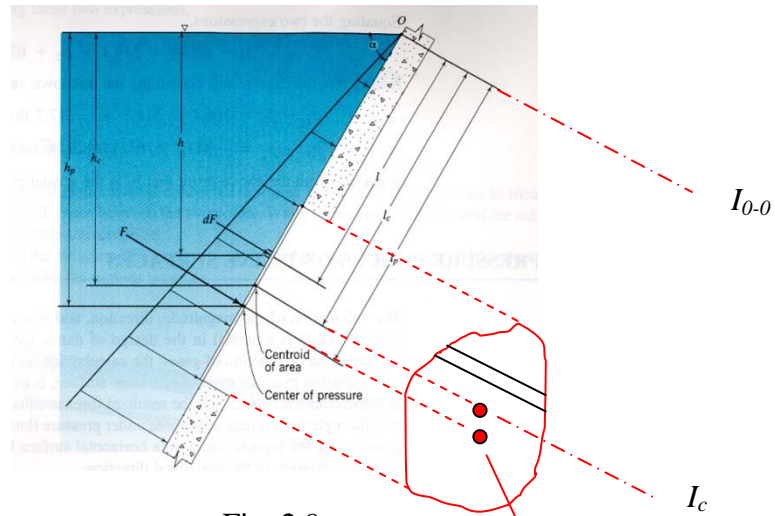


Fig. 2.9

- Centroid of area  $A$  ~ at a depth  $h_c$

~ at a distance  $l_c$  from the line of intersection 0-0

Center of resultant force

(i) Magnitude of total force

First, consider differential force  $dF$

$$dF = p dA = \gamma h dA$$

$$h = l \sin \alpha$$

$$\rightarrow dF = \gamma l \sin \alpha dA \tag{2.10}$$

Then, integrate  $dF$  over area  $A$

$$F = \int^A dF = \gamma \sin \alpha \int^A l dA \tag{2.11}$$

in which  $\int^A l dA = \underline{\text{1st moment of the area } A}$  about the line 0-0

$$= A \cdot l_c$$

in which  $l_c =$  perpendicular distance from 0-0 to the centroid of area

$$\therefore F = \gamma A l_c \sin \alpha$$

Substitute  $h_c = l_c \sin \alpha$

$$F = \gamma h_c A$$

(pressure at centroid)  $\times$  (area of plane)

(2.12)

(ii) Location of total force

$$dF = \gamma l \sin \alpha dA$$

Consider moment of force about the line 0-0

$$dM = dF \cdot l = \gamma l^2 d \sin \alpha$$

$$M = \int^A dM = \gamma \sin \alpha \int^A l^2 dA$$

where  $\int^A l^2 dA = \underline{\text{second moment of the area } A}$ , about the line 0-0  $= I_{0-0}$

$$\therefore M = \gamma \sin \alpha I_{0-0} \quad (\text{a})$$

By the way,

$$M = F \cdot l_p \quad (\text{total force} \times \text{moment arm}) \quad (\text{b})$$

$$l_p = \text{unknown}$$

Combine (a) and (b)

$$Fl_p = \gamma I_{0-0} \sin \alpha \quad (c)$$

Substitute  $F = \gamma l_c \sin \alpha A$  into (c)

$$\gamma l_c \sin \alpha A l_p = \gamma I_{0-0} \sin \alpha$$

$$\therefore l_p = \frac{I_{0-0}}{l_c A} = \frac{I_c + l_c^2 A}{l_c A} = l_c + \frac{I_c}{l_c A} \quad (2.14)$$

→ Center of pressure is always below the centroid by  $\frac{I_c}{l_c A}$

$$l_p - l_c = \frac{I_c}{l_c A}$$

→ as  $l_c$  (depth of centroid) increases  $l_p - l_c$  decreases

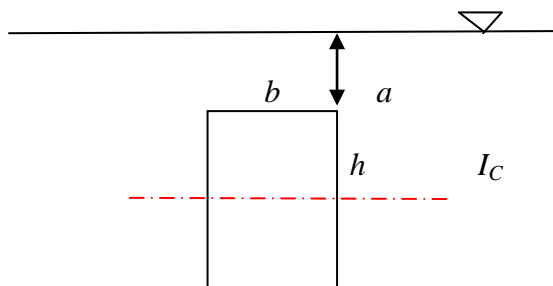
• Second moment transfer equation

$$I_{0-0} = I_c + l_c^2 A$$

$I_c$  = 2nd moment of the area  $A$  about a axis through the centroid, parallel to 0-0

→ Appendix 3

1) Rectangle



$$A = bh, \quad y_c = \frac{h}{2}, \quad I_c = \frac{bh^3}{12}$$

$$\therefore h_c = a + (h - y_c) = a + \frac{h}{2}$$

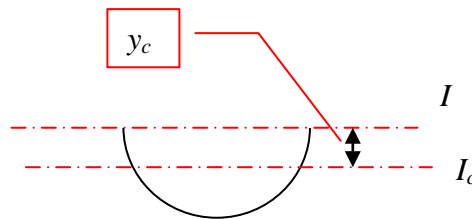
$$F = \gamma h_c A = \gamma \left( a + \frac{h}{2} \right) (bh)$$

$$h_p = h_c + \frac{I_c}{h_c A}$$

$$\text{If } a = 0; \quad h_c = \frac{h}{2}$$

$$h_p = \frac{h}{2} + \frac{\frac{bh^3}{12}}{\frac{h}{2}bh} = \frac{h}{2} + \frac{h}{6} = \frac{2}{3}h$$

2) Semicircle



$$I = \frac{\pi d^4}{128}, \quad y_c = \frac{4r}{3\pi}$$

$$I = I_c + y_c^2 A$$

$$\therefore I_c = I - y_c^2 A$$

$$= \frac{\pi d^4}{128} - \left( \frac{4r}{3\pi} \right)^2 \left( \frac{\pi d^2}{8} \right)$$

$$= \left( \frac{\pi}{128} - \frac{1}{18\pi} \right) d^4 = 0.10976r^4$$

3) Quadrant

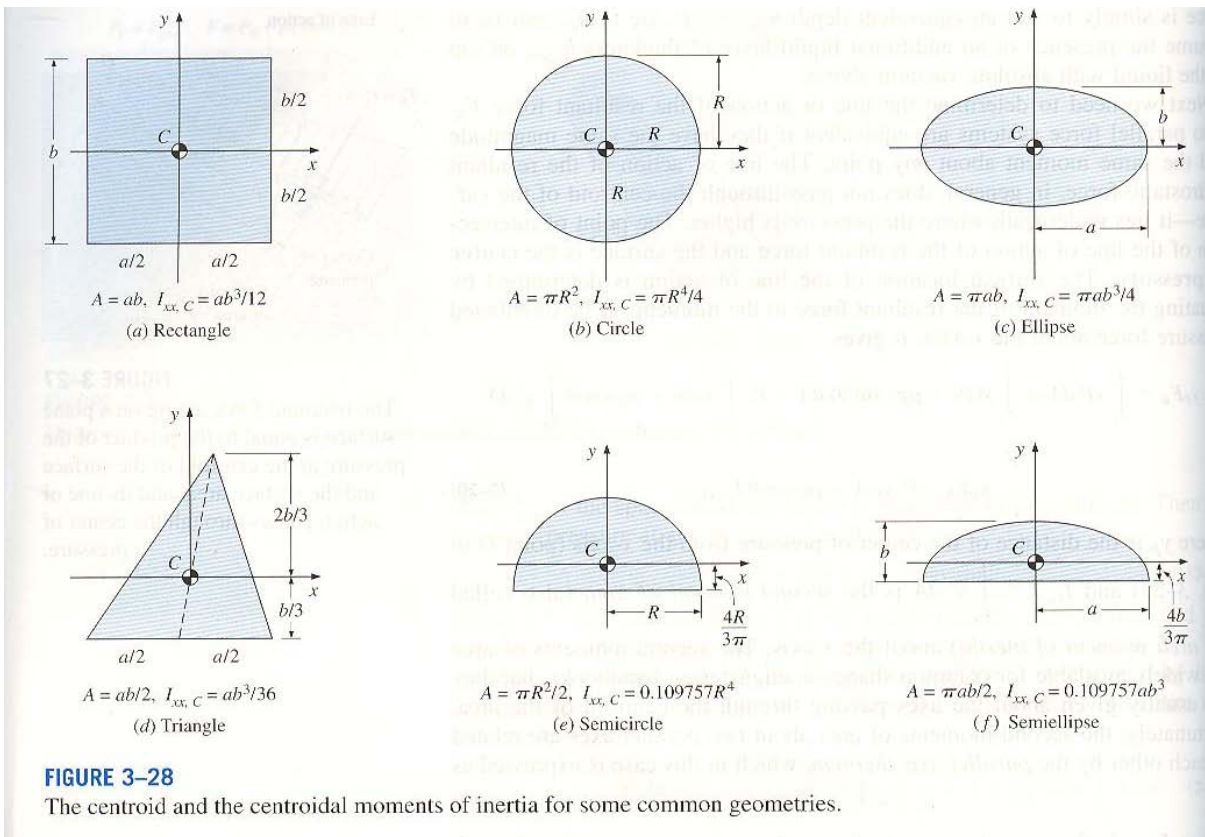
$$I = \frac{\pi d^4}{256}, y_c = \frac{4r}{3\pi}$$

$$I_c = I + y_c^2 A$$

$$= \frac{\pi d^4}{256} - \left(\frac{4r}{3\pi}\right)^2 \left(\frac{\pi d^2}{16}\right)$$

$$= \left(\frac{\pi}{256} - \frac{1}{36\pi}\right) d^4$$

$$= 0.054888r^4$$



(iii) Lateral location of the center of pressure for asymmetric submerged area

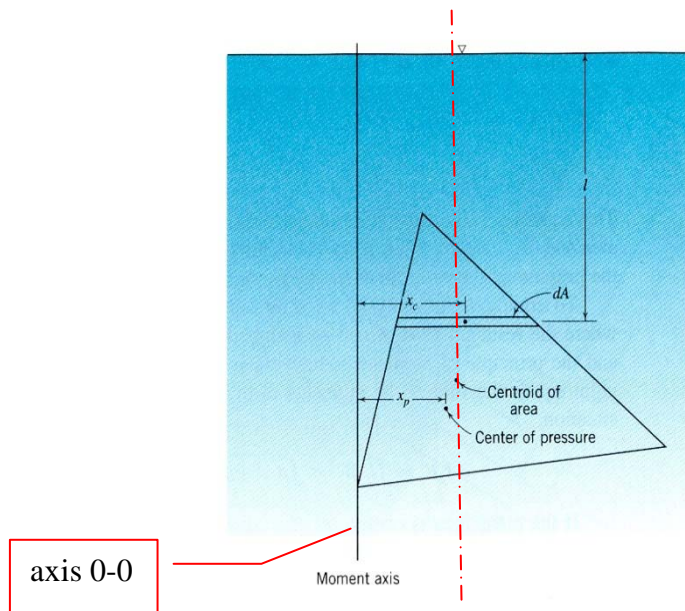


Fig. 2.10

a. For regular plane

(i) divide whole area into a series of elemental horizontal strips of area  $dA$

(ii) center of pressure for each strip would be at the midpoint of the strip (the strip is a rectangle in the limit)

(iii) apply moment theorem about a vertical axis 0-0

$$dF = \gamma h_c dA = \gamma l \sin \alpha dA \quad (a)$$

$$dM = x_c dF = x_c \gamma l \sin \alpha dA$$

Integrate (a)

$$M = \int_A dM = \int x_c \gamma l \sin \alpha dA \quad (b)$$

By the way,  $M = x_p F$  (c)

Equate (b) and (c)

$$x_p F = \int x_c \gamma l \sin \alpha dA$$

$$x_p = \frac{1}{F} \gamma \sin \alpha \int x_c l dA \quad (2.15)$$

b. For irregular forms

~ divide into simple areas

~ use methods of statics

[Re] Moment theorem

→ The moment of the resultant force is equal to the sum of the moments of the individual forces.



[IP 2.9] A vertical gate: quarter circle

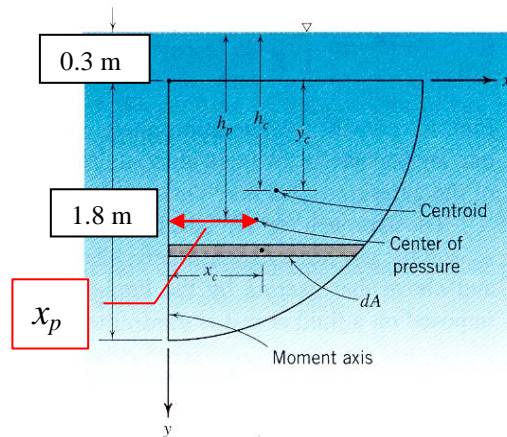


Fig. Problem 2.9

[Sol]

(i) Magnitude

$$y_c)_{\text{quadrant}} = \frac{4r}{3\pi} = \frac{4}{3\pi}(1.8) = 0.764;$$

$$h_c = 0.3 + 0.764 = 1.064$$

$$F_{\text{quad}} = \gamma h_c A = 9,800(1.064) \left( \frac{\pi}{4} (1.8)^2 \right) = 26.53 \text{ kN}$$

(ii) Vertical location of resultant force

$$\left( \frac{I_c}{l_c A} \right)_{\text{quad}} = \frac{0.05488(1.8)^4}{(1.064) \left( \frac{\pi}{4} (1.8)^2 \right)} = 0.213 \text{ m}$$

$$\rightarrow l_p = 1.064 + 0.213 = 1.277 \text{ m}$$

(iii) Lateral location of the center of pressure

Divide quadrant into horizontal strips

Take a moment of the force on  $dA$  about  $y$ -axis

$$dM = \gamma h dA \cdot (\text{moment arm}) = 9800(y + 0.3)(x dy) \left( \frac{x}{2} \right)$$

$$x^2 + y^2 = (1.8)^2$$

$$\frac{9800}{2}(y + 0.3)x^2 dy = \frac{9800}{2}(y + 0.3)(1.8^2 - y^2) dy$$

$$\therefore M = \int_0^{1.8} \frac{9800}{2}(y + 0.3)(1.8^2 - y^2) dy = 18575 \text{ N} \cdot \text{m}$$

By the way,  $M = F_{quad} x_p$

$$x_p = 18575 / 26.53 \times 10^3 = 0.7 \text{ m} \text{ right to the } y\text{-axis}$$

2.5 Forces on Submerged Curved Surfaces

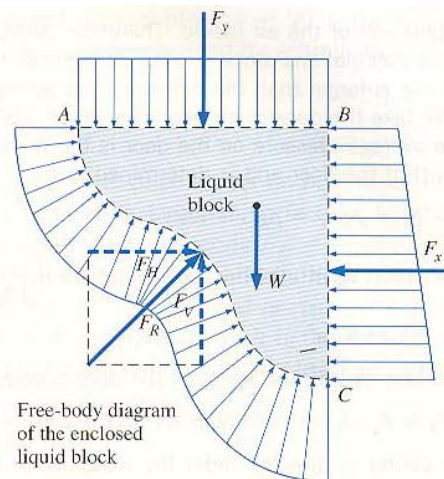
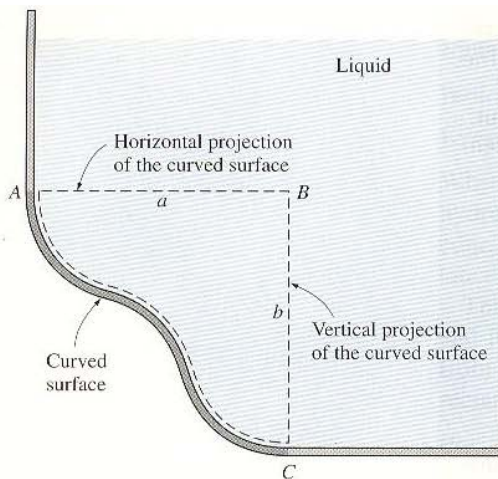
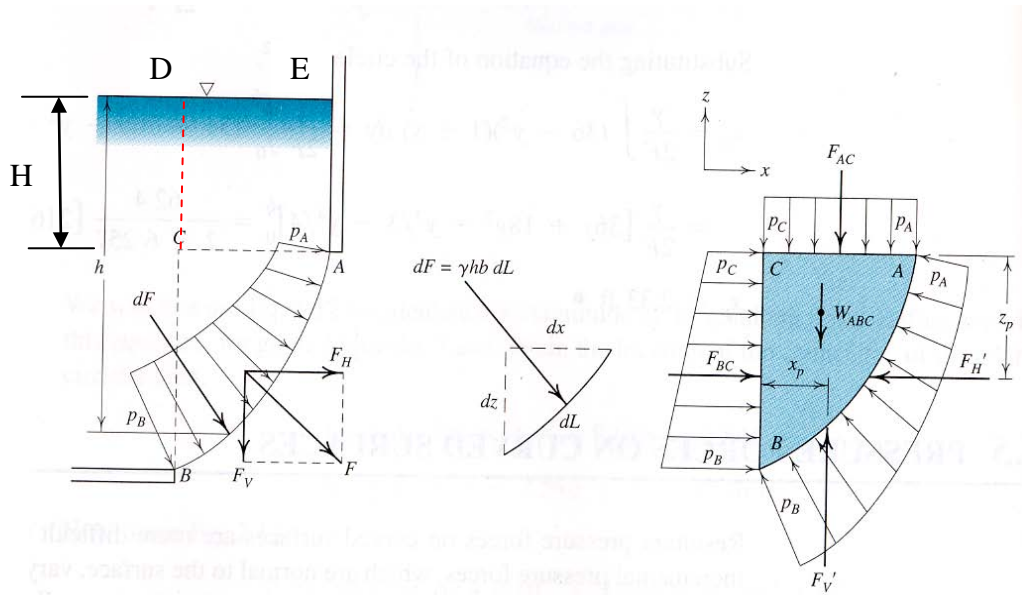


FIGURE 3-32

Determination of the hydrostatic force acting on a submerged curved surface.

- Resultant pressure forces on curved surfaces are more difficult to deal with because the incremental pressure forces vary continually in direction.

→ { Direct integration  
Method of basic mechanics

## 1) Direct integration

- Represent the curved shape functionally and integrate to find horizontal and vertical components of the resulting force

## i) Horizontal component

$$F_H = \int dF_H = \int \gamma h b dz$$

where  $b$  = the width of the surface;  $dz$  = the vertical projection of the surface element  $dL$

location of  $F_H$ : take moments of  $dF$  about convenient point, e.g., point C

$$z_p F_H = \int z dF_H = \int z \gamma h b dz$$

where  $z_p$  = the vertical distance from the moment center to  $F_H$

## ii) Vertical component

$$F_V = \int dF_V = \int \gamma h b dx$$

where  $dx$  = the horizontal projection of the surface element  $dL$

location of  $F_V$ : take moments of  $dF$  about convenient point, e.g., point C

$$x_p F_V = \int x dF_V = \int x \gamma h b dx$$

where  $x_p$  = the horizontal distance from the moment center to  $F_V$

## 2) Method of basic mechanics

- Use the basic mechanics concept of a free body and the equilibrium of a fluid mass
- Choose a convenient volume of fluid in a way that one of the fluid element boundaries coincide with the curved surface under consideration

- Isolate the fluid mass and show all the forces acting on the mass to keep it in equilibrium

- Static equilibrium of free body  $ABC$

$$\sum F_x = F_{BC} - F'_H = 0 \qquad \therefore F'_H = F_{BC} = \gamma h_c A_{BC}$$

$$\sum F_z = F'_V - W_{ABC} - F_{AC} = 0 \qquad \therefore F'_V = F_{AC} + W_{ABC}$$

$$F_{AC} = \gamma h_c A_{AC} = \gamma H A_{AC} = W_{ACDE}$$

$$W_{ABC} = \text{weight of free body } ABC$$

$$\therefore F'_V = \text{weight of } ABDE$$

- Location

From the inability of the free body of fluid to support shear stress,

→  $F'_H$  must be colinear with  $F_{BC}$

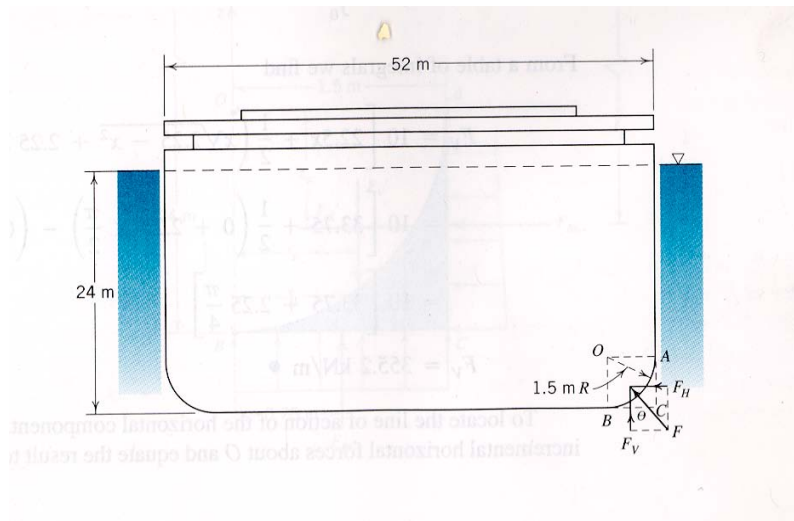
→  $F'_V$  must be colinear with the resultant of  $W_{ABC}$  and  $F_{AC}$ .

[IP 2.10] p. 59

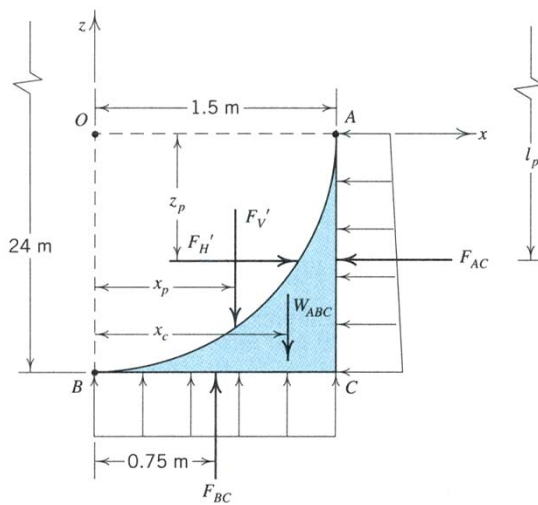
Oil tanker  $W = 330,000$  tone  $= 330,000 \times 10^3$  kg

Calculate magnitude, direction, and location of resultant force/meter exerted by seawater

( $\gamma = 10 \times 10^3$  N/m<sup>3</sup>) on the curved surface  $AB$  (quarter cylinder) at the corner.



[Sol] Consider a free body  $ABC$



(i) Horizontal Comp.

$$h_c = 22.5 + \frac{h}{2} = 22.5 + \frac{1.5}{2} = 23.25$$

$$F'_H = F_{AC} = \gamma h_c A = 10^4 \times \left( 22.5 + \frac{1.5}{2} \right) \times (1.5 \times 1) = 348.8 \text{ kN/m}$$

$$l_p = l_c + \frac{I_c}{l_c A} = 23.25 + \frac{1 \times (1.5)^3}{23.25 \times 1.5} = 23.25 + 0.0081 = 23.258 \text{ m}$$

$$\therefore z_p = 23.258 - 22.5 = 0.758 \text{ m below line OA}$$

$$= 24 - 23.258 = 0.742 \text{ m above line BC}$$

(ii) Vertical Comp.

$$\sum F_z = F_{BC} - F'_V - W_{ABC} = 0$$

$$\therefore F'_V = F_{BC} - W_{ABC} = \gamma h_c A - \gamma \text{Vol.}$$

$$= 10^4 \times 24 \times (1.5 \times 1) - 10^4 \left( 1.5 \times 1.5 - \frac{1}{4} \pi (1.5)^2 \right) \times 1 = 355.2 \text{ kN / m}$$

- To find the location of  $F'_V$ , we should first find center of gravity of  $ABC$  using statics

Take a moment of area about line  $OB$ 

$$\frac{4(1.5)}{3\pi} \times \frac{1}{4} \pi (1.5)^2 + x_c \times 0.483 = 2.25 \times \frac{1.5}{2}$$

$$x_c = 1.1646 \text{ m}$$

[Cf] From App. 3, for segment of square

$$x_c = \frac{2}{3} \frac{r}{4 - \pi} = \frac{2}{3} \frac{1.5}{4 - \pi} = 1.165 \text{ m}$$

Now, find location of force  $F'_V$

Take a moment of force about point  $O$

$$F'_V \times x_p = F_{BC} \times 0.75 - W_{ABC} \times 1.1646$$

$$355.2 \times x_p = 360 \times 0.75 - 4.83 \times 1.1646$$

$$\therefore x_p = 0.744 \text{ m right of } OB$$

[Summary]

i) Magnitude of Resultant force  $F$

$$F = \sqrt{(348.8)^2 + (355.2)^2} = 497.8 \text{ kN/m}$$

ii) Direction  $\theta$

$$\theta = \tan^{-1}\left(\frac{F_V}{F_H}\right) = \tan^{-1}\left(\frac{355.2}{348.8}\right) = 45.5^\circ$$

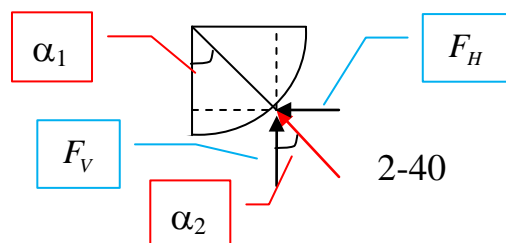
iii) Location

Force acting through a point 0.742 m above line  $BC$  and 0.744 m right of  $B$

$$\alpha_1 = \tan^{-1}\left(\frac{0.744}{0.758}\right) = 44.47^\circ$$

$$\alpha_2 = \tan^{-1}\left(\frac{348.8}{355.2}\right) = 44.47^\circ$$

$\alpha_1 = \alpha_2 \rightarrow F$  act through point  $O$ .





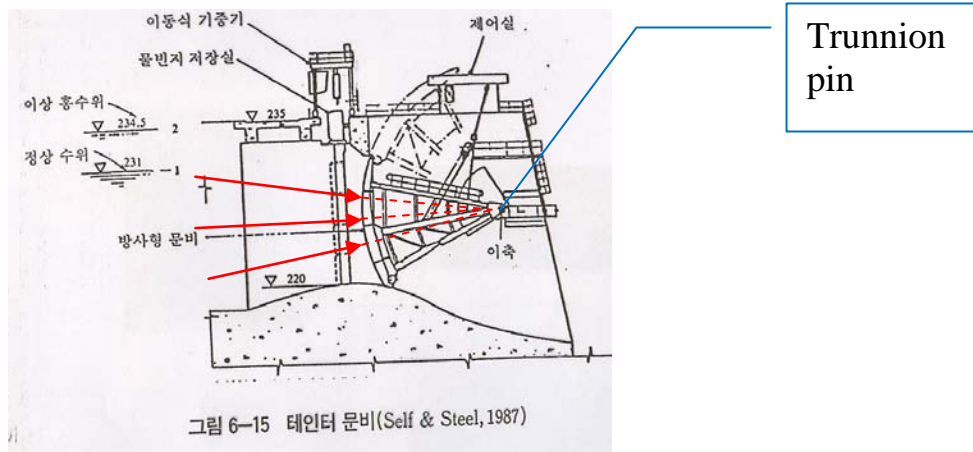
- Pressure acting on the cylindrical or spherical surface
  - The pressure forces are all normal to the surface.
  - For a circular arc, all the lines of action would pass through the center of the arc.
  - Hence, the resultant would also pass through the center.

- Tainter gate (Radial gate) for dam spillway

All hydrostatic pressures are radial, passing through the trunnion bearing.

→ only pin friction should be overcome to open the gate

pin friction (radial gate) < roller friction (lift gate)



**2.6 Buoyancy and Floatation**

• Archimedes' principle

I. A body immersed in a fluid is buoyed up by a force equal to the weight of fluid displaced.

II. A floating body displaces its own weight of the liquid in which it floats.

→ Calculation of draft of surface vessels, lift of airships and balloons

(i) Immersed body

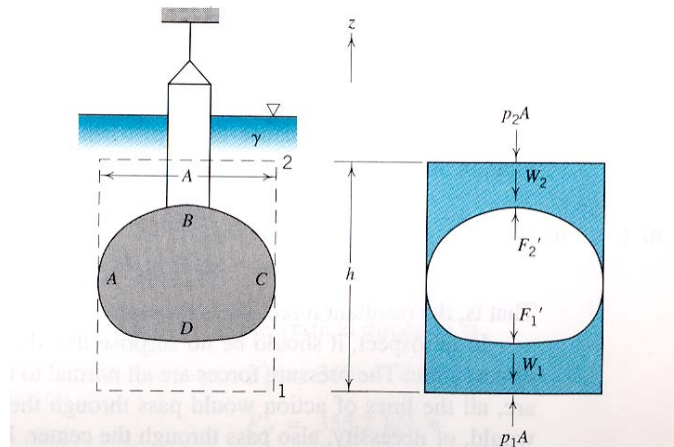


Fig. 2.12

Isolate a free body of fluid with vertical sides tangent to the body

→  $F_1'$  = vertical force exerted by the lower surface (ADC) on the surrounding fluid

$F_2'$  = vertical force exerted by the upper surface (ABC) on the surrounding fluid

$$F_1' - F_2' = F_B$$

$F_B$  = buoyancy of fluid; act vertically upward.

For upper portion of free body

$$\sum F_z = F_2' - W_2 - P_2A = 0 \tag{a}$$

For lower portion

$$\sum F_z = F_1' - W_1 + P_1 A = 0 \quad (b)$$

Combine (a) and (b)

$$\gamma h$$

$$F_B = F_1' - F_2' = (P_1 - P_2)A - (W_1 + W_2)$$

$$(P_1 - P_2)A = \gamma h A = \text{weight of free body}$$

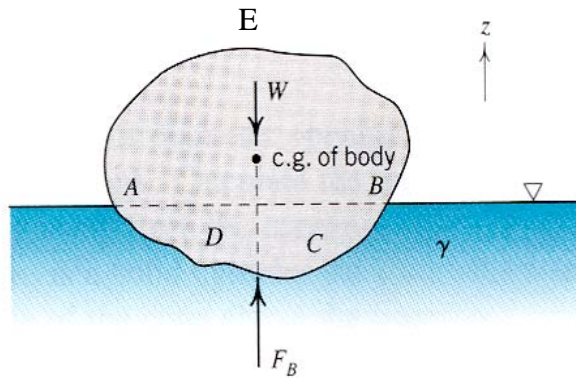
$$W_1 + W_2 = \text{weight of dashed portion of fluid}$$

$$\therefore (P_1 - P_2)A - (W_1 + W_2) = \text{weight of a volume of fluid equal to that of the body}$$

ABCD

$$\therefore F_B = \gamma_{fluid} (\text{volume of submerged object}) \quad (2.16)$$

(ii) Floating body



For floating object

$$F_B = \gamma_f (\text{volume displaced, } ABCD)$$

$$F_B = \gamma_f ABCD$$

$$W_{ABCDE} = \gamma_s V_{ABCDE}$$

$$W = \gamma_s ABCDE$$

where  $\gamma_s =$  specific weight of body

From static equilibrium:  $F_B = W_{ABCDE}$

$$\gamma_f V_{ABCD} = \gamma_s V_{ABCDE}$$

$$\therefore V_{ABCD} = \frac{\gamma_s}{\gamma_f} V_{ABCDE}$$

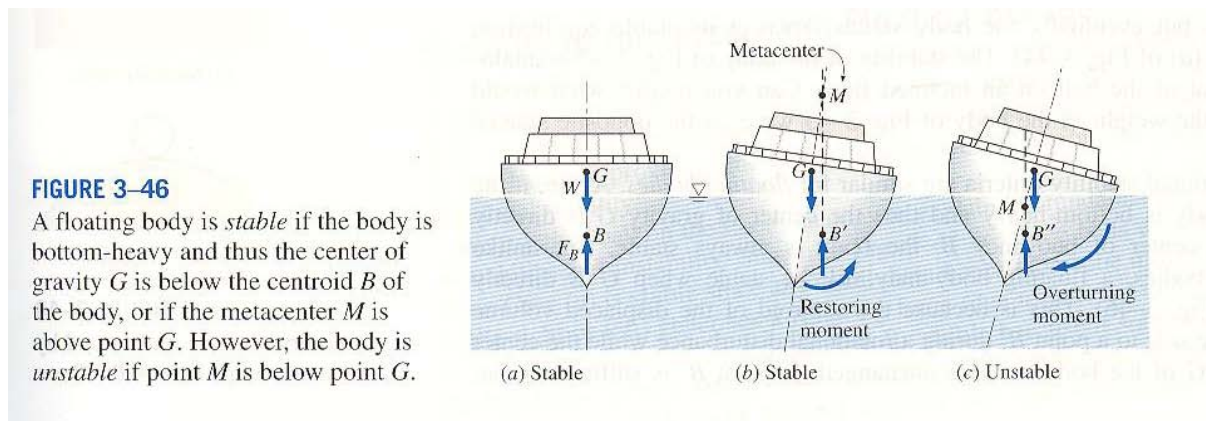
[Ex] Iceberg in the sea

Ice s.g.= 0.9

Sea water s.g.= 1.03

$$V_{sub} = \frac{0.9(9800)}{1.03(9800)} V_{total} = 0.97 V_{total}$$

- Stability of submerged or floating bodies



$G_1 < M \rightarrow$  stable, righting moment

$G_2 > M \rightarrow$  unstable, overturning moment

$G_1, G_2 =$  center of gravity

$M =$  metacenter

**2.7 Fluid Masses Subjected to Acceleration**

- Fluid masses can be subjected to various types of acceleration without the occurrence of relative motion between fluid particles or between fluid particles and boundaries.

→ laws of fluid statics modified to allow for the effects of acceleration

- A whole tank containing fluid system is accelerated.

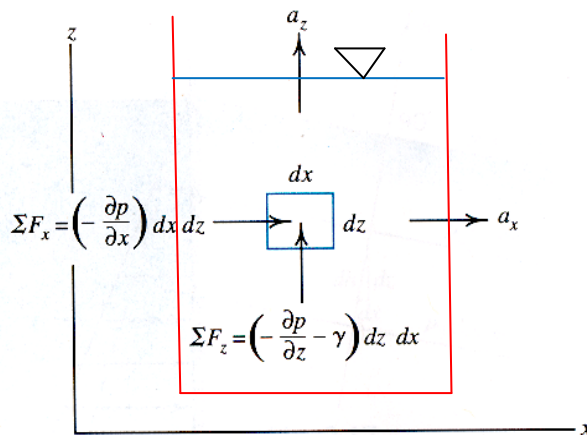


Fig. 2.15

- Newton's 2nd law of motion (Sec. 2.1)

$$\Sigma F = Ma$$

First, consider force

$$\Sigma F_x = \left( p - \frac{\partial p}{\partial x} \frac{dx}{2} \right) dz - \left( p + \frac{\partial p}{\partial x} \frac{dx}{2} \right) dz = \left( -\frac{\partial p}{\partial x} \right) dx dz \tag{2.18a}$$

$$\Sigma F_z = \left( -\frac{\partial p}{\partial z} - \gamma \right) dx dz \tag{2.18b}$$

Then, consider acceleration

$$x: \left( -\frac{\partial p}{\partial x} \right) dx dz = \left( \frac{\gamma}{g} dx dz \right) a_x$$

mass

$$z: \left( -\frac{\partial p}{\partial z} - \gamma \right) dx dz = \left( \frac{\gamma}{g} dx dz \right) a_z$$

where mass =  $\rho vol. = \frac{\gamma}{g} dx dz \times 1$

$$\frac{\partial p}{\partial x} = -\frac{\gamma}{g} a_x \tag{2.19}$$

$$\frac{\partial p}{\partial z} = -\frac{\gamma}{g} (g + a_z) \tag{2.20}$$

→ pressure variation through an accelerated mass of fluid

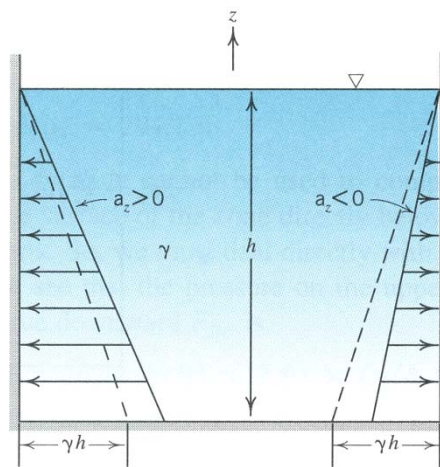


Fig. 2.16

[Cf] For fluid at rest,

$$\frac{\partial p}{\partial x} = 0$$

$$\frac{\partial p}{\partial z} = -\gamma$$

- Chain rule for the total differential for  $dp$  (App. 5)

$$dp = \frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial z} dz \quad (a)$$

Combine (2.19) , (2.20), and (a)

$$dp = -\frac{\gamma}{g} a_x dx - \frac{\gamma}{g} (g + a_z) dz \quad (2.21)$$

- Line of constant pressure  $dp = 0$

$$-\frac{\gamma}{g} a_x dx - \frac{\gamma}{g} (g + a_z) dz = 0$$

$$\therefore \frac{dz}{dx} = -\left( \frac{a_x}{g + a_z} \right) \quad (2.22)$$

→ slope of a line of constant pressure

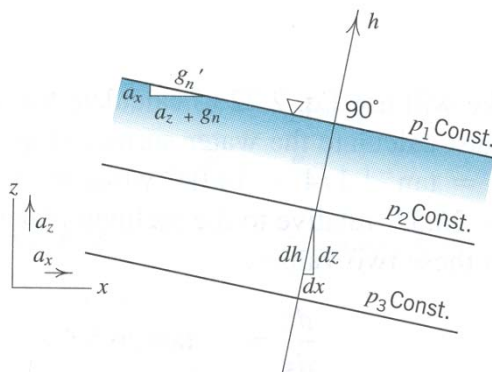


Fig. 2.17

1) No horizontal acceleration:  $a_x = 0$

$$\frac{\partial p}{\partial x} = 0$$

$$\therefore \frac{dp}{dz} = -\gamma \left( \frac{g + a_z}{g} \right)$$

• For free falling fluid,  $a_z = -g$

$$\frac{dp}{dz} = 0$$

2) Constant linear acceleration

Divide (2.21) by  $dh$

$$\frac{dp}{dh} = -\gamma \left( \frac{a_x}{g} \frac{dx}{dh} + \frac{g + a_z}{g} \frac{dz}{dh} \right) \quad (a)$$

Use similar triangles

$$\frac{dx}{dh} = \frac{a_x}{g'} \quad (b.1)$$

$$\frac{dz}{dh} = \frac{a_z + g}{g'} \quad (b.2)$$

$$g' = \left[ a_x^2 + (a_z + g)^2 \right]^{1/2}$$

Substitute (b) into (a)



$$\frac{dp}{dh} = -\gamma \frac{g'}{g}$$

→ pressure variation along  $h$  is linear.

[IP 2.13] p. 70

An open tank of water is accelerated vertically upward at  $4.5 \text{ m/s}^2$ . Calculate the pressure at a depth of 1.5 m.

[Sol]

$$\frac{dp}{dz} = -\gamma \left( \frac{g + a_z}{g} \right) = (-9,800 \text{ N/m}^3) \left( \frac{9.81 + 4.5}{9.81} \right) = -14,300 \text{ N/m}^3$$

$$dp = -14,300 dz$$

integrate

$$\int_0^p dp = \int_0^{-1.5} -14,300 dz$$

$$p = -14,300[z]_0^{-1.5} = 14,300(-1.5 - 0) = 21,450 \text{ N/m}^2 = 21.45 \text{ kPa}$$

[Cf] For  $a_z = 0$

$$p = \gamma h = 9800(1.5) = 14.7 \text{ kPa}$$

**Homework Assignment # 2**

Due: 1 week from today

Prob. 2.4

Prob. 2.6

Prob. 2.11

Prob. 2.26

Prob. 2.31

Prob. 2.39

Prob. 2.52

Prob. 2.59

Prob. 2.63

Prob. 2.76

Prob. 2.91

Prob. 2.98

Prob. 2.129