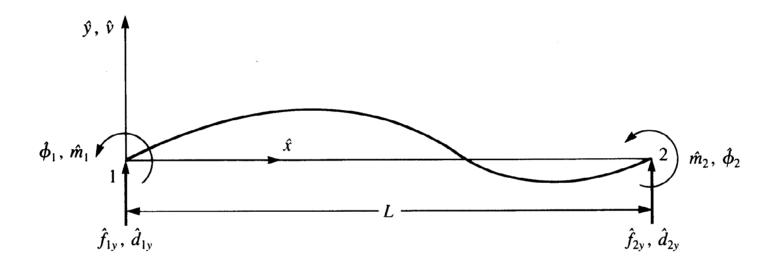
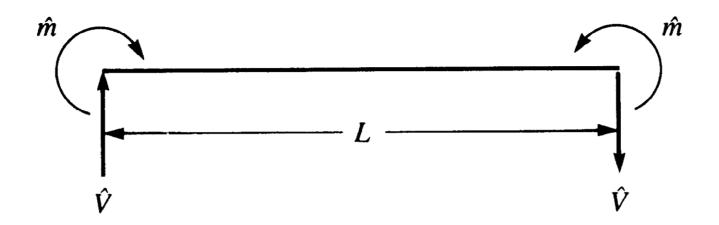
Beam Element

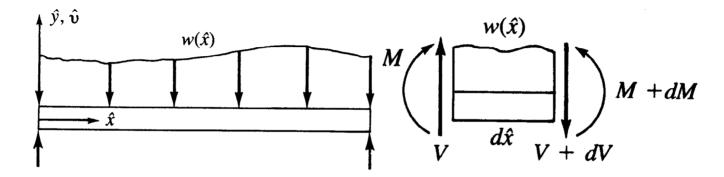


- ♦ Beam: A long thin structure that is subject to the vertical loads. A beam shows more evident bending deformation than the torsion and/or axial deformation.
- ♦ Bending strain is measured by the lateral deflection and the rotation → Lateral deflection and rotation determine the number of DoF (Degree of Freedom).



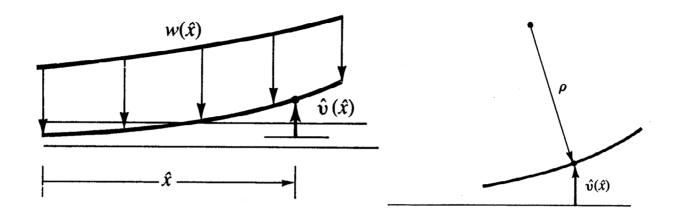
♦ Sign convention

- 1. Positive bending moment: Anti-clock wise rotation.
- 2. Positive load: \hat{y} -direction.
- 3. Positive displacement: \hat{y} -direction.



♦ The governing equation

$$-wd\hat{x} - dV = 0$$
 or $w = -\frac{dV}{d\hat{x}}$
 $Vd\hat{x} - dM = 0$ or $V = \frac{dM}{d\hat{x}}$



◆ Relation between beam curvature (k) and bending moment

$$k = \frac{1}{\rho} = \frac{M}{EI}$$
 or $\frac{d^2\hat{v}}{d\hat{x}^2} = \frac{M}{EI}$

$$\frac{d^2\hat{v}}{d\hat{x}^2} = \frac{M}{EI}$$

• Curvature for small slope $(\theta = d\hat{v}/d\hat{x})$: $k = \frac{d^2\hat{v}}{d\hat{x}^2}$

ho: Radius of the deflection curve, \hat{v} : Lateral displacement function along the \hat{y} -axis direction

E: Stiffness coefficient, I: Moment of inertia along the \hat{z} -axis

Solving the equation with ${\it M}$,

$$\frac{d^2}{d\hat{x}^2} \left(EI \frac{d^2 \hat{v}}{d\hat{x}^2} \right) = -w(\hat{x})$$

When EI is constant, and force and moment are only applied at nodes,

$$EI\frac{d^4\hat{v}}{d\hat{x}^4} = 0$$

Step 1: To select beam element type

Step 2: To select displacement function

Assumption of lateral displacement

$$\hat{v}(\hat{x}) = a_1 \hat{x}^3 + a_2 \hat{x}^2 + a_3 \hat{x} + a_4$$

- Complete 3-order displacement function is suitable, because it has four degree of freedom (one lateral displacement and one small rotation at each node)
- The function is proper, because it satisfies the fundamental differential equation of a beam.
- The function satisfies continuity of both displacement and slope at each node.

Representing \hat{v} with functions of \hat{d}_{1y} , \hat{d}_{2y} , $\hat{\phi}_1$, $\hat{\phi}_2$

$$\hat{v}(0) = \hat{d}_{1y} = a_4$$

$$\frac{d\hat{v}(0)}{d\hat{v}} = \hat{\phi}_1 = a_3$$

$$\hat{v}(L) = \hat{d}_{2y} = a_1 L^3 + a_2 L^2 + a_3 L + a_4$$

$$\frac{d\hat{v}(L)}{d\hat{r}} = \hat{\phi}_2 = 3a_1L^2 + 2a_2L + a_3$$

$$\begin{split} \text{Replacing $a_1 \sim a_4$ with \hat{d}_{1y}, \hat{d}_{2y}, $\hat{\phi}_1$, $\hat{\phi}_2$} \\ \hat{v} &= \left[\frac{2}{L^3} \Big(\hat{d}_{1y} - \hat{d}_{2y} \Big) + \frac{1}{L^2} \Big(\hat{\phi}_1 + \hat{\phi}_2 \Big) \right] \hat{x}^3 \\ &+ \left[-\frac{3}{L^2} \Big(\hat{d}_{1y} - \hat{d}_{2y} \Big) - \frac{1}{L} \Big(2 \hat{\phi}_1 + \hat{\phi}_2 \Big) \right] \hat{x}^2 + \hat{\phi}_1 \, \hat{x} + \hat{d}_{1y} \end{split}$$

Representing it in matrix form, $\hat{v} = [N] \{\hat{d}\}$

$$N_{1} = \frac{1}{L^{3}} (2\hat{x}^{3} - 3\hat{x}^{2}L + L^{3}) \qquad N_{2} = \frac{1}{L^{3}} (\hat{x}^{3}L - 2\hat{x}^{2}L^{2} + \hat{x}L^{3})$$

$$N_{3} = \frac{1}{L^{3}} (-2\hat{x}^{3} + 3\hat{x}^{2}L) \qquad N_{4} = \frac{1}{L^{3}} (\hat{x}^{3}L - \hat{x}^{2}L^{2})$$

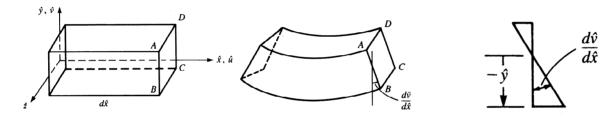
where N_{l} , N_{2} , N_{3} , N_{4} : shape functions of the beam element

Step 3: To define strain-displacement relation and stress-strain relation

Assume that the equation of strain-displacement relation is valid

$$\varepsilon_x(\hat{x},\hat{y}) = \frac{d\hat{u}}{d\hat{x}}$$
, $\hat{u} = -\hat{y}\frac{d\hat{v}}{d\hat{x}} \Rightarrow \varepsilon_x(\hat{x},\hat{y}) = -\hat{y}\frac{d^2\hat{v}}{d\hat{x}^2}$

Basic assumption: Cross-section of the beam sustains its shape after deformation by bending, and generally rotates by degree of $(d\hat{v}/d\hat{x})$.



Bending moment-lateral displacement relation and shear force-lateral displacement relation

$$\hat{m}(\hat{x}) = EI \frac{d^2 \hat{v}}{d\hat{x}^2} \qquad \hat{V} = EI \frac{d^3 \hat{v}}{d\hat{x}^3}$$

Step 4: To derive an element stiffness matrix and governing equations by direct stiffness method

• Element stiffness matrix and governing equations

$$\hat{f}_{1y} = \hat{V} = EI \frac{d^3 \hat{v}(0)}{d\hat{x}^3} = \frac{EI}{L^3} \Big(12\hat{d}_{1y} + 6L\hat{\phi}_1 - 12\hat{d}_{2y} + 6L\hat{\phi}_2 \Big)$$

$$\hat{m}_1 = -\hat{m} = -EI \frac{d^2 \hat{v}(0)}{d\hat{x}^2} = \frac{EI}{L^3} \Big(6L\hat{d}_{1y} + 4L^2\hat{\phi}_1 - 6\hat{d}_{2y} + 2L^2\hat{\phi}_2 \Big)$$

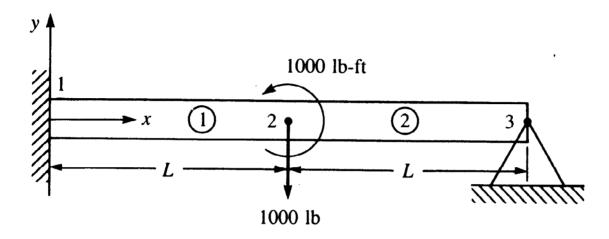
$$\hat{f}_{2y} = -\hat{V} = -EI \frac{d^3 \hat{v}(L)}{d\hat{x}^3} = \frac{EI}{L^3} \Big(-12\hat{d}_{1y} - 6L\hat{\phi}_1 + 12\hat{d}_{2y} - 6L\hat{\phi}_2 \Big)$$

$$\hat{m}_2 = \hat{m} = EI \frac{d^2 \hat{v}(L)}{d\hat{x}^2} = \frac{EI}{L^3} \Big(6L\hat{d}_{1y} + 2L^2\hat{\phi}_1 - 6L\hat{d}_{2y} + 4L^2\hat{\phi}_2 \Big)$$

- Matrix Form

$$\begin{cases}
\hat{f}_{1y} \\
\hat{m}_{1} \\
\hat{f}_{2y} \\
\hat{m}_{2}
\end{cases} = \frac{EI}{L^{3}} \begin{bmatrix}
12 & 6L & -12 & 6L \\
6L & 4L^{2} & -6L & 2L^{2} \\
-12 & -6L & 12 & -6L \\
6L & 2L^{2} & -6L & 4L^{2}
\end{bmatrix} \begin{bmatrix}
\hat{d}_{1y} \\
\hat{\phi}_{1} \\
\hat{d}_{2y} \\
\hat{\phi}_{2}
\end{bmatrix} \quad \underline{\hat{k}} = \frac{EI}{L^{3}} \begin{bmatrix}
12 & 6L & -12 & 6L \\
6L & 4L^{2} & -6L & 2L^{2} \\
-12 & -6L & 12 & -6L \\
6L & 2L^{2} & -6L & 4L^{2}
\end{bmatrix}$$

Step 5: To constitute a global stiffness matrix using boundary conditions



Assemble example

Assume EI of the beam element is constant.

 $1000 \; lb$ load and $1000 \; lb-ft$ moment are applied at the center of the beam.

Assume load and moment were only applied at nodes.

Left end of the beam is fixed and right end is pin-connected.

The beam is divided into two elements (nodes 1, 2, and 3 as shown above figure).

$$\underline{k}^{(1)} = \frac{EI}{L^{3}} \begin{bmatrix} 12 & 6L & -12 & 6L \\ 6L & 4L^{2} & -6L & 2L^{2} \\ -12 & -6L & 12 & -6L \\ 6L & 2L^{2} & -6L & 4L^{2} \end{bmatrix} \qquad \underline{k}^{(2)} = \frac{EI}{L^{3}} \begin{bmatrix} 12 & 6L & -12 & 6L \\ 6L & 4L^{2} & -6L & 2L^{2} \\ -12 & -6L & 12 & -6L \\ 6L & 2L^{2} & -6L & 4L^{2} \end{bmatrix}$$

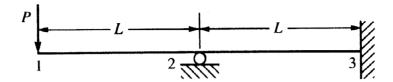
$$\underline{k}^{(2)} = \frac{EI}{L^3} \begin{bmatrix} d_{2y} & \phi_2 & d_{3y} & \phi_3 \\ 12 & 6L & -12 & 6L \\ 6L & 4L^2 & -6L & 2L^2 \\ -12 & -6L & 12 & -6L \\ 6L & 2L^2 & -6L & 4L^2 \end{bmatrix}$$

$$\begin{cases} F_{1y} \\ M_1 \\ F_{2y} \\ M_2 \\ F_{3y} \\ M_3 \end{cases} = \frac{EI}{L^3} \begin{bmatrix} 12 & 6L & -12 & 6L & 0 & 0 \\ 6L & 4L^2 & -6L & 2L^2 & 0 & 0 \\ -12 & -6L & 12 + 12 & -6L + 6L & -12 & 6L \\ 6L & 2L^2 & -6L + 6L & 4L^2 + 4L^2 & -6L & 2L^2 \\ 0 & 0 & -12 & -6L & 12 & -6L \\ 0 & 0 & 6L & 2L^2 & -6L & 4L^2 \end{bmatrix} \times \begin{cases} d_{1y} \\ \phi_1 \\ d_{2y} \\ \phi_2 \\ d_{3y} \\ \phi_3 \end{cases}$$

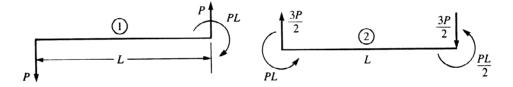
Boundary conditions and constrains at the node 1(fixed) and node 3(pin-connected) are

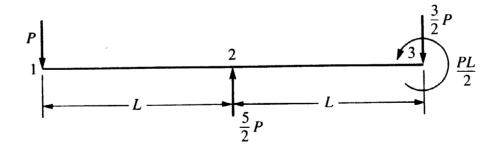
$$\phi_1 = 0$$
 $d_{1y} = 0$ $d_{3y} = 0$

Example: Beam analysis using direct stiffness method



Cantilever beam supported by roller at the center





Load P is applied at node 1.

Length: 2L , Stiffness: EI

Constrains: (1) Roller at node 2, (2) Fixed at node 3.

- Global stiffness matrix

$$\underline{K} = \frac{EI}{L^{3}}\begin{bmatrix} 12 & 6L & -12 & 6L & 0 & 0\\ & 4L^{2} & -6L & 2L^{2} & 0 & 0\\ & & & 12+12 & -6L+6L & -12 & 6L\\ & & & & 4L^{2}+4L^{2} & -6L & 2L^{2} \\ & & & & & 12 & -6L\\ & & & & & & 4L^{2} \end{bmatrix}$$

$$\begin{cases} F_{1y} \\ M_1 \\ F_{2y} \\ M_2 \\ F_{3y} \\ M_3 \end{cases} = \frac{EI}{L^3} \begin{bmatrix} 12 & 6L & -12 & 6L & 0 & 0 \\ 6L & 4L^2 & -6L & 2L^2 & 0 & 0 \\ -12 & -6L & 24 & 0 & -12 & 6L \\ 6L & 2L^2 & 0 & 8L^2 & -6L & 2L^2 \\ 0 & 0 & -12 & -6L & 12 & -6L \\ 0 & 0 & 6L & 2L^2 & -6L & 4L^2 \end{bmatrix} \begin{bmatrix} d_{1y} \\ \phi_1 \\ d_{2y} \\ \phi_2 \\ d_{3y} \\ \phi_3 \end{bmatrix}$$

Boundary conditions $d_{2y} = 0$ $d_{3y} = 0$ $\phi_3 = 0$

$$d_{2y} = 0$$

$$d_{3y}=0$$

$$\phi_3 = 0$$

$$\begin{cases} -P \\ 0 \\ 0 \end{cases} = \frac{EI}{L^3} \begin{bmatrix} 12 & 6L & 6L \\ 6L & 4L^2 & 2L^2 \\ 6L & 2L^2 & 4L^2 \end{bmatrix} \begin{bmatrix} d_{1y} \\ \phi_1 \\ \phi_2 \end{bmatrix}$$

$$d_{1y} = -\frac{7PL^3}{12EI}$$
 $\phi_1 = \frac{3PL^2}{4EI}$ $\phi_2 = \frac{PL^2}{4EI}$

$$\phi_1 = \frac{3PL^2}{4EI}$$

$$\phi_2 = \frac{PL^2}{4EI}$$

• Substituting the obtained values to the final equation,

$$\begin{cases} F_{1y} \\ M_1 \\ F_{2y} \\ M_2 \\ F_{3y} \\ M_3 \end{cases} = \underbrace{EI}_{L^3} \begin{bmatrix} 12 & 6L & -12 & 6L & 0 & 0 \\ 6L & 4L^2 & -6L & 2L^2 & 0 & 0 \\ -12 & -6L & 24 & 0 & -12 & 6L \\ 6L & 2L^2 & 0 & 8L^2 & -6L & 2L^2 \\ 0 & 0 & -12 & -6L & 12 & -6L \\ 0 & 0 & 6L & 2L^2 & -6L & 4L^2 \end{bmatrix} \begin{bmatrix} -\frac{7PL^3}{12EI} \\ \frac{3PL^2}{4EI} \\ 0 \\ \frac{PL^2}{4EI} \\ 0 \\ 0 \end{bmatrix}$$

$$F_{1y} = -P$$
 $M_1 = 0$ $F_{2y} = \frac{5}{2}P$ $M_2 = 0$ $F_{3y} = -\frac{3}{2}P$ $M_3 = \frac{1}{2}PL$

 $F_{1v} = -P$: Force at node 1

 F_{2y} , F_{3y} , M_3 : Reacting forces and moment at nodes

 M_1 , M_2 : Zero

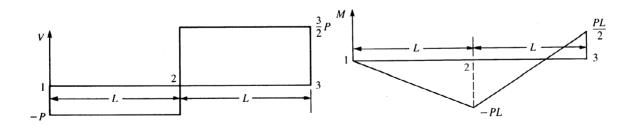
◆ Calculating local nodal loads

Force at the element 1.

When
$$\hat{f} = \hat{k}\hat{d}$$

$$\begin{cases}
\hat{f}_{1y} \\
\hat{m}_{1} \\
\hat{f}_{2y} \\
\hat{m}_{2}
\end{cases} = \frac{EI}{L^{3}} \begin{bmatrix}
12 & 6L & -12 & 6L \\
6L & 4L^{2} & -6L & 2L^{2} \\
-12 & -6L & 12 & -6L \\
6L & 2L^{2} & -6L & 4L^{2}
\end{bmatrix} \begin{bmatrix}
-\frac{7PL^{3}}{12EI} \\
\frac{3PL^{2}}{4EI} \\
0 \\
\frac{PL^{2}}{4EI}
\end{bmatrix}$$

$$\hat{f}_{1y} = -P$$
 $\hat{m}_1 = 0$ $\hat{f}_{2y} = P$ $\hat{m}_2 = -PL$



Shear moment curve

Homework: Distributed load

◆ Equivalent force

