

NS2

How to implement a new protocol?

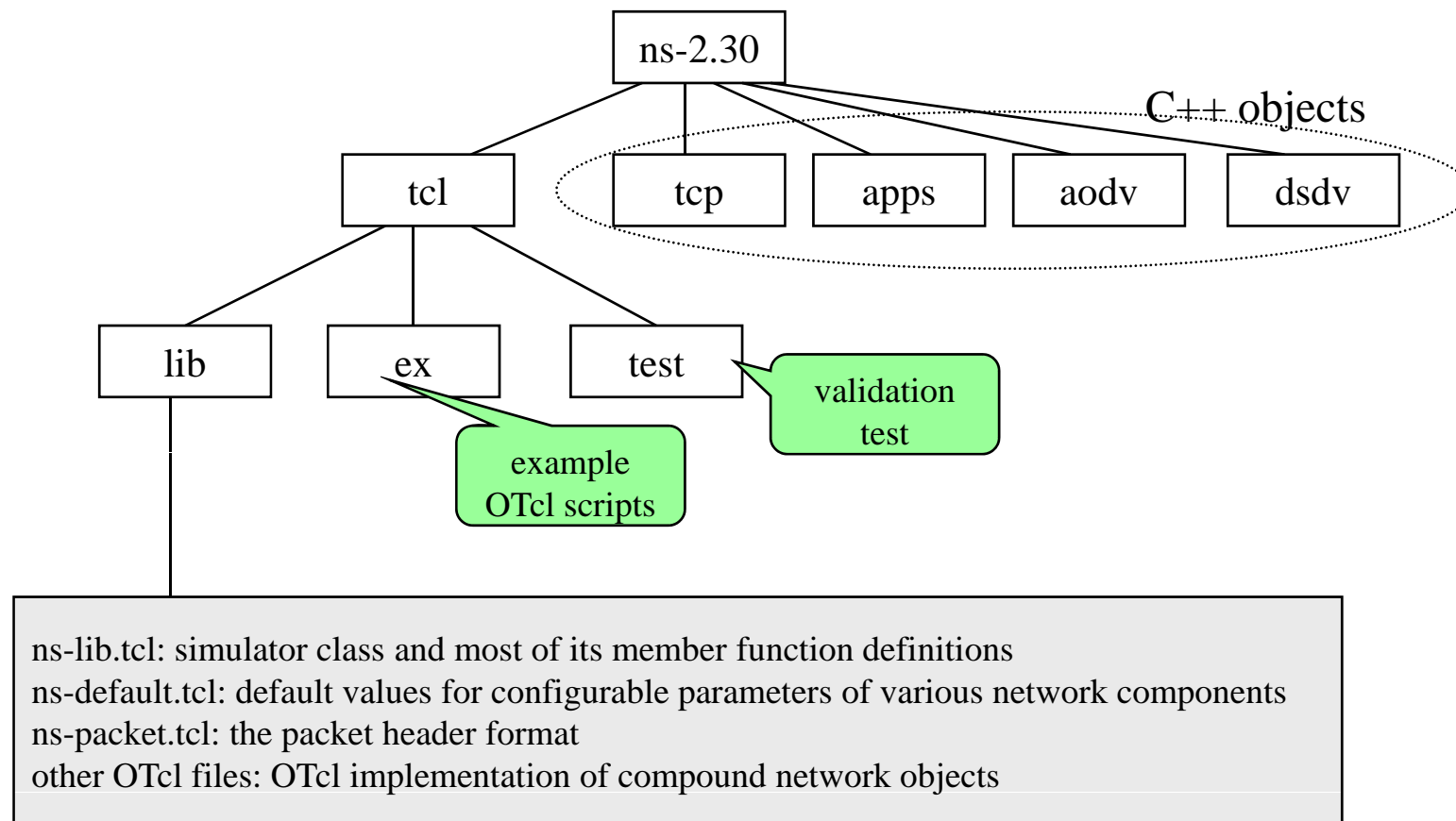
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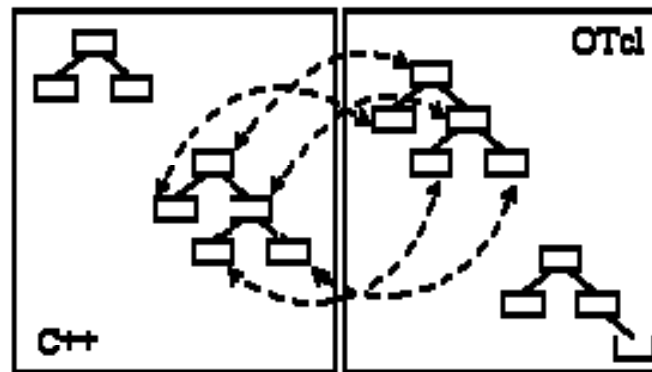
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NS directory structure



What to do to make a new object

- Define a new object in C++ source
- Define its corresponding OTcl linkage object in C++ source
 - Why?
 - To make it possible to create an instance of this object in OTcl
 - To make it possible for OTcl to access C++ object variables and member functions

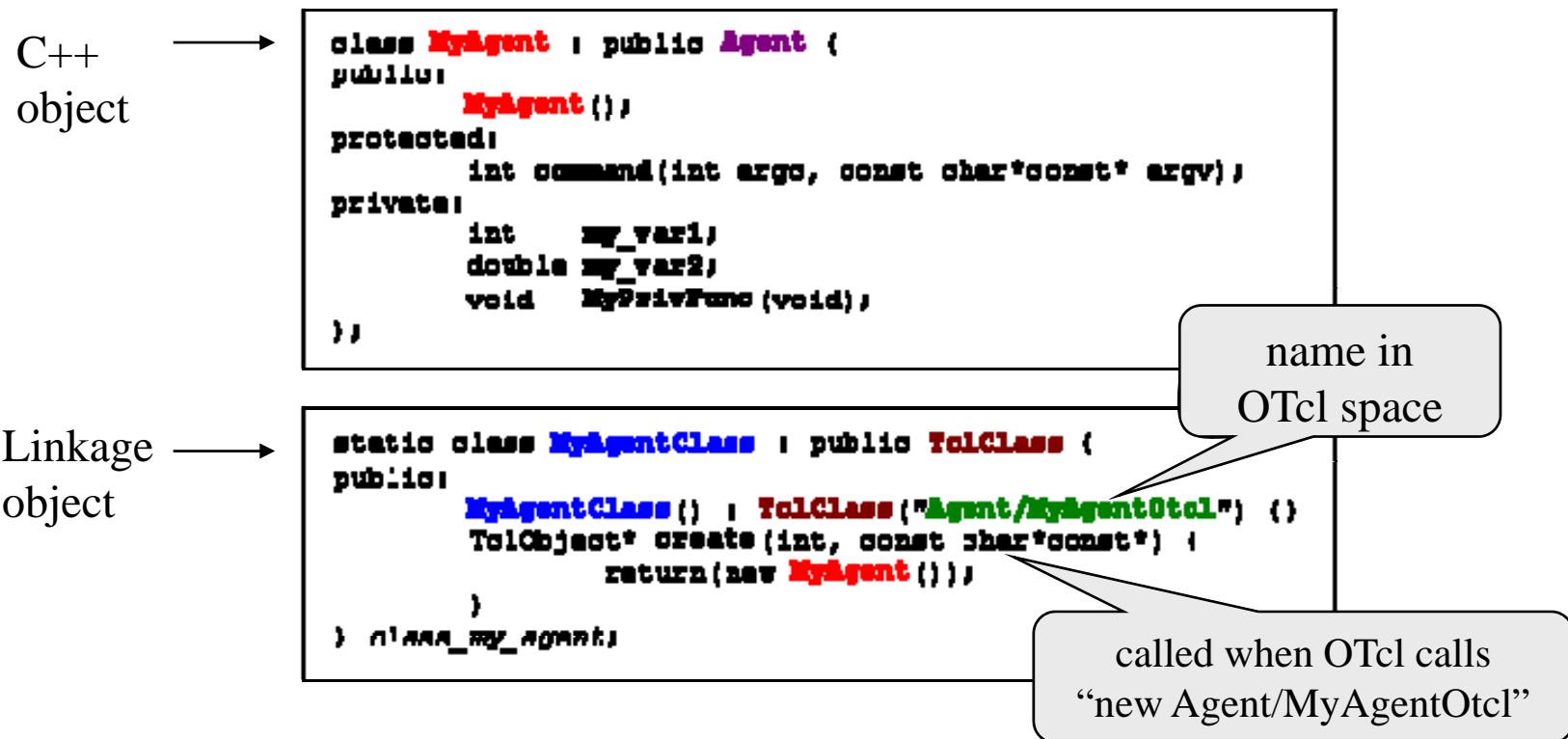


- Change Makefile so that it compiles the new C++ source
- Make
- Now you can create and use the new object in OTcl script

Let's make a simple dummy object

MyAgent

- Define a new object in C++ source
- Define its corresponding OTcl linkage object in C++ source



How to make OTcl access C++?

- Export C++ object member variables to OTcl
 - Use “bind” in Object constructor function
 - Set default values for the exported variables in “ns-2.30/tcl/lib/ns-lib.tcl” (ns-default.tcl???)

```
MyAgent::MyAgent() : Agent(PT_UDP) {  
    bind("my_var1_otcl", &my_var1);  
    bind("my_var2_otcl", &my_var2);  
}
```

name in OTcl space

Now, OTcl can
“\$myagent set my_var2_otcl 3.14”

- Export C++ object member functions to OTcl
 - Define a “command” member function of your C++ object (MyAgent) that maps OTcl commands to C++ member functions

```
int MyAgent::command(int argc, const char*const* argv) {  
    if(argc == 2) {  
        if(strcmp(argv[1], "call-my-priv-func") == 0) {  
            MyPrivFunc();  
            return(TCL_OK);  
        }  
    }  
    return(Agent::command(argc, argv));  
}
```

Now, OTcl can
“\$myagent call-my-priv-func”

How to execute an OTcl command from C++?

- get a reference to “Tcl::instance()”
- use “eval” (or something like that) to execute OTcl commands

OTcl script command

```
void MyAgent::MyPrivFunc(void) {  
    Tcl& tcl = Tcl::instance();  
    tcl.eval("puts \"Message From MyPrivFunc\"");  
    tcl.evalf("puts \"    my_var1 = %d\"", my_var1);  
    tcl.evalf("puts \"    my_var2 = %f\"", my_var2);  
}
```

Complete C++ code

```
#include <stdio.h>
#include <string.h>
#include "agent.h"

class MyAgent : public Agent {
public:
    MyAgent();
protected:
    int command(int argc, const char*const* argv);
private:
    int my_var1;
    double my_var2;
    void MyPrivFunc(void);
};

static class MyAgentClass : public TclClass {
public:
    MyAgentClass() : TclClass("Agent/MyAgentOttl")
    {}
    TclObject* create(int, const char*const*) {
        return(new MyAgent());
    }
} class_my_agent;
```

```
MyAgent::MyAgent() : Agent(PT_UDP) {
    bind("my_var1_otcl", &my_var1);
    bind("my_var2_otcl", &my_var2);
}

int MyAgent::command(int argc, const char*const*
argv) {
    if(argc == 2) {
        if(strcmp(argv[1], "call-my-priv-func") == 0) {
            MyPrivFunc();
            return(TCL_OK);
        }
    }
    return(Agent::command(argc, argv));
}

void MyAgent::MyPrivFunc(void) {
    Tcl& tcl = Tcl::instance();
    tcl.eval("puts \"Message From MyPrivFunc\"");
    tcl.evalf("puts \"    my_var1 = %d\"", my_var1);
    tcl.evalf("puts \"    my_var2 = %f\"", my_var2);
}
```

Rebuild NS

- Open “Makefile”, add “yourObject.o” at the end of object file list
- Recompile NS using the “make” command
 - make depend
 - make
 - cp ns /usr/local/bin

OTcl script using the new object

ex-linkage.tcl

```
# Create MyAgent (This will give two warning messages that  
# no default vaules exist for my_var1_otcl and my_var2_otcl)  
set myagent [new Agent/MyAgentOtcl]  
  
# Set configurable parameters of MyAgent  
$myagent set my_var1_otcl 2  
$myagent set my_var2_otcl 3.14  
  
# Give a command to MyAgent  
$myagent call-my-priv-func
```

Run “ns ex-linkage.tcl”

result

```
warning: no class variable Agent/MyAgentOtcl::my_var1_otcl  
      see tcl-object.tcl in tclcl for info about this warning.  
warning: no class variable Agent/MyAgentOtcl::my_var2_otcl  
  
Message From MyPrivFunc  
my_var1 = 2  
my_var2 = 3.140000
```

More Realistic Object (new protocol “MyPing”)

- An agent object that sends a ping packet, receives a reply from the peer, and calculate the round-trip delay.

Step 1: C++ programming

- Write myping.h and myping.cc files

```
struct hdr_myping {  
  char ret;  
  double send_time;  
  
  // packet header access function  
  static int offset_; // required by PacketHeaderManager  
  inline static int& offset() {return offset_;}  
  inline static hdr_myping* access(const Packet* p){  
    return (hdr_myping*) p->access(offset_);  
  }  
};  
  
class MyPingAgent : public Agent {  
public:  
  MyPingAgent();  
  int command(int argc, const char*const* argv);  
  void recv(Packet*, Handler*);  
};
```

new proto packet header structure

necessary for packet header access

protocol agent object in C++ space

```
int hdr_myping::offset_;  
static class MyPingHeaderClass : public PacketHeaderClass {  
public:  
  MyPingHeaderClass() :  
    PacketHeaderClass("PacketHeader/Ping",  
                      sizeof(hdr_myping)) {  
    bind_offset(&hdr_myping::offset_);  
  }  
} class_mypinghdr;  
  
static class MyPingClass : public TclClass {  
public:  
  MyPingClass() : TclClass("Agent/MyPing") {}  
  TclObject* create(int, const char*const*) {  
    return (new MyPingAgent());  
  }  
} class_myping;
```

instantiation of OTcl linkage object for packet header structure

instantiation of OTcl linkage object for the agent object

```

MyPingAgent::MyPingAgent() : Agent(PT_MyPing)
{
    bind("packetSize_", &size_);
}

int MyPingAgent::command(int argc, const char*const* argv)
{
    if (argc == 2) {
        if (strcmp(argv[1], "send") == 0) {
            // Create a new packet
            Packet* pkt = allocpkt();
            // Access the Ping header for the new packet:
            hdr_myping* hdr = hdr_myping::access(pkt);
            // Set the 'ret' field to 0, so the receiving node knows
            // that it has to generate an echo packet
            hdr->ret = 0;
            // Store the current time in the 'send_time' field
            hdr->send_time = Scheduler::instance().clock();
            // Send the packet
            send(pkt, 0);
            // return TCL_OK, so the calling function knows that the
            // command has been processed
            return (TCL_OK);
        }
    }
    // If the command hasn't been processed by
    PingAgent::command,
    // call the command() function for the base class
    return (Agent::command(argc, argv));
}

```

export C++ object variable to OTcl

export the C++ object control to OTcl

```

void MyPingAgent::recv(Packet* pkt, Handler*)
{
    // Access the IP header for the received packet:
    hdr_ip* hdrip = hdr_ip::access(pkt);
    // Access the Ping header for the received packet:
    hdr_myping* hdr = hdr_myping::access(pkt);
    // Is the 'ret' field = 0 (i.e. the receiving node is be
    if (hdr->ret == 0) {
        // Send an 'echo'. First save the old packet's send_time
        double stime = hdr->send_time;
        // Discard the packet
        Packet::free(pkt);
        // Create a new packet
        Packet* pktret = allocpkt();
        // Access the Ping header for the new packet:
        hdr_myping* hdrret = hdr_myping::access(pktret);
        // Set the 'ret' field to 1, so the receiver won't send another echo
        hdrret->ret = 1;
        // Set the send_time field to the correct value
        hdrret->send_time = stime;
        // Send the packet
        send(pktret, 0);
    } else {
        // A packet was received. Use tcl.eval to call the Tcl
        // interpreter with the results.
        // Note: In the Tcl code, a
        // has to be defined which allow
        // result.
        char out[100];
        // Prepare the output to the Tcl inter
        // trip time
        sprintf(out, "%s recv %d %3.1f", name(),
            hdrip->src_addr_ >> Address::instance().NodeShift_[1],
            (Scheduler::instance().clock() - hdr->send_time) * 1000);
        Tcl& tcl = Tcl::instance();
        tcl.eval(out);
        // Discard the packet
        Packet::free(pkt);
    }
}

```

“recv” member: packet handler

access packet header

receive message with ret=0: “reply”

receive message with ret=1: “calculate and print RoundTrip Time”

OTcl script command

Step 2: Register the new protocol

- Modify packet.h, ns-packet.tcl, ns-default.tcl files of NS

```
enum packet_t {  
    PT_TCP,                packet.h  
    PT_UDP,  
    ...  
    PT_MyPing,  
    PT_NTTYPE // this must be the last one  
};  
  
class p_info {  
public:  
    p_info(){  
        name_[PT_TCP] = "tcp";  
        name_[PT_UDP] = "udp";  
        ...  
        name_[PT_MyPing] = "MyPing";  
        name_[PT_NTTYPE] = "undefined";  
    }  
    ...  
};
```

```
foreach prot {  
    AODV                ns-packet.tcl  
    ...  
    MyPing  
} {  
    add-packet-header $prot  
}
```

```
...                ns-default.tcl  
...  
Agent/MyPing set packetSize_ 64  
...
```

set default values
of the protocol
parameters

Step 3: Rebuild NS

- **Modify Makefile**
 - add MyPing.o to the object file list
- **Renew dependency**
 - make depend
- **Re-Make NS**
 - make
- **Install NS**
 - cp ns /usr/local/bin

Step 4: Writing and running OTcl script

```
#Create three nodes
set n0 [$ns node]
set n1 [$ns node]
set n2 [$ns node]

#Connect the nodes with two links
$ns duplex-link $n0 $n1 1Mb 10ms DropTail
$ns duplex-link $n1 $n2 1Mb 10ms DropTail

#Define a 'recv' function for the class 'Agent/MyPing'
Agent/MyPing instproc recv {from rtt} {
    $self instvar node_
    puts "node [$node_ id] received ping answer"
}

from \
    $from with round-trip-time $rtt ms."
}

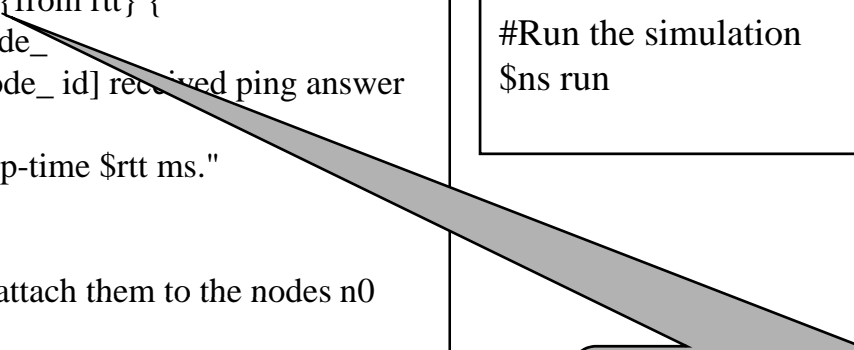
#Create two ping agents and attach them to the nodes n0
and n2
set p0 [new Agent/MyPing]
$ns attach-agent $n0 $p0

set p1 [new Agent/MyPing]
$ns attach-agent $n2 $p1
```

```
#Connect the two agents
$ns connect $p0 $p1

#Schedule events
$ns at 0.2 "$p0 send"
$ns at 0.4 "$p1 send"
$ns at 0.6 "$p0 send"
$ns at 0.6 "$p1 send"
$ns at 1.0 "finish"

#Run the simulation
$ns run
```



called by C++ when an echo is received

Homework 8

- Make a newPing
 - once started, it sends probing packets 5 times periodically at every 1 sec.
- Using the same network of Homework 7, measure the round-trip delays of each way between node 1 and 5
 - first newPing start at 1.0 sec
 - second newPing start at 11.0 sec