

8. Networks



- ⌘ Why networked embedded systems
- ⌘ General network architecture
 - ☑ ISO seven network layers
- ⌘ Networks
 - ☑ I²C, CAN, Ethernet
- ⌘ Internet-enabled embedded systems
- ⌘ Sensor networks

Distributed embedded systems

⌘ Distributed embedded systems

- ☒ Processing elements (PEs) are connected through a network

⌘ The application can be distributed over the PEs

- ☒ Clients and servers

⌘ Network

- ☒ Internet

- ☒ CAN

Network-based ES



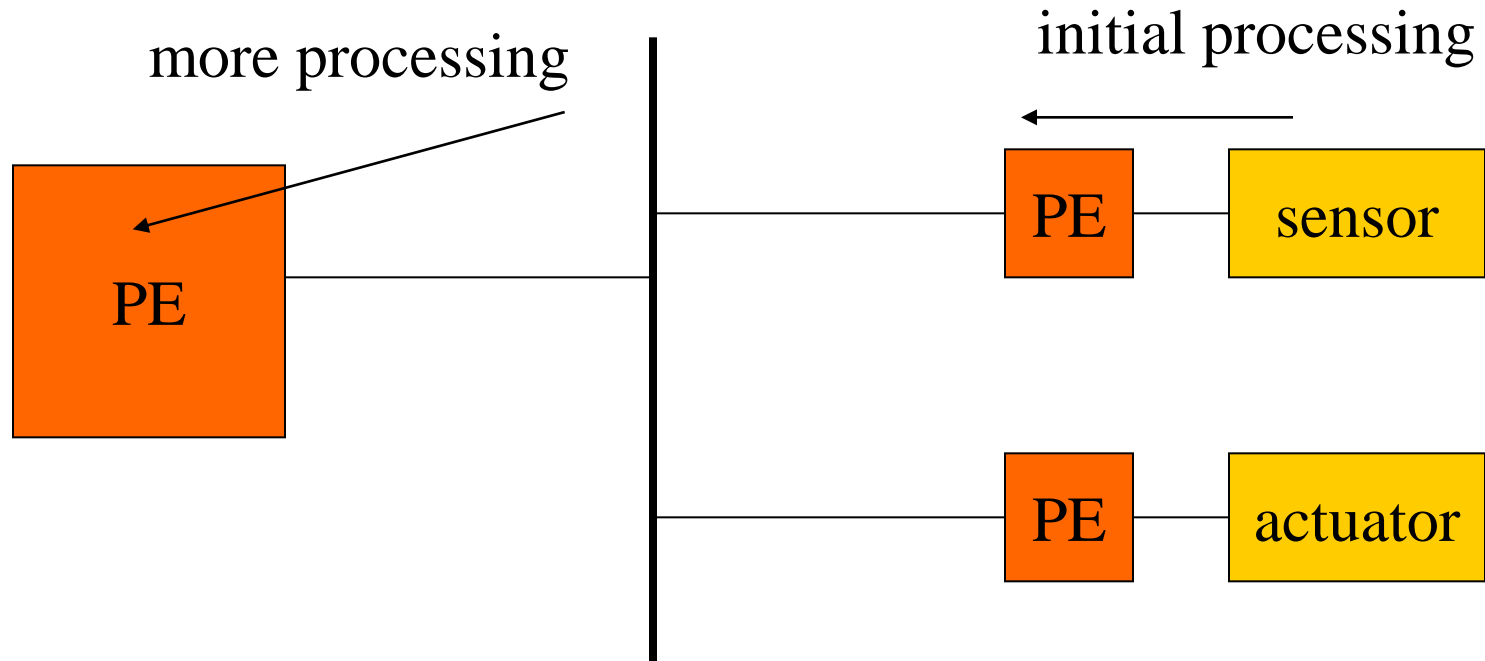
- ⌘ Physically distributed activities---time constants may not allow transmission to central site.
 - ☑ Engine control: short time delays required for the task
- ⌘ Data reduction is another important reason for distributed processing.
- ⌘ Modularity is another motivation for network-based design.
 - ☑ A large system is assembled out of existing components.

Network-based ES



- ⌘ Improved debugging---use one CPU in network to debug others.
- ⌘ In some cases, networks are used to build fault tolerance into systems.
- ⌘ Distributed embedded system design is a good example of hardware/software co-design since we must design the network topology as well as the software running on the network node.

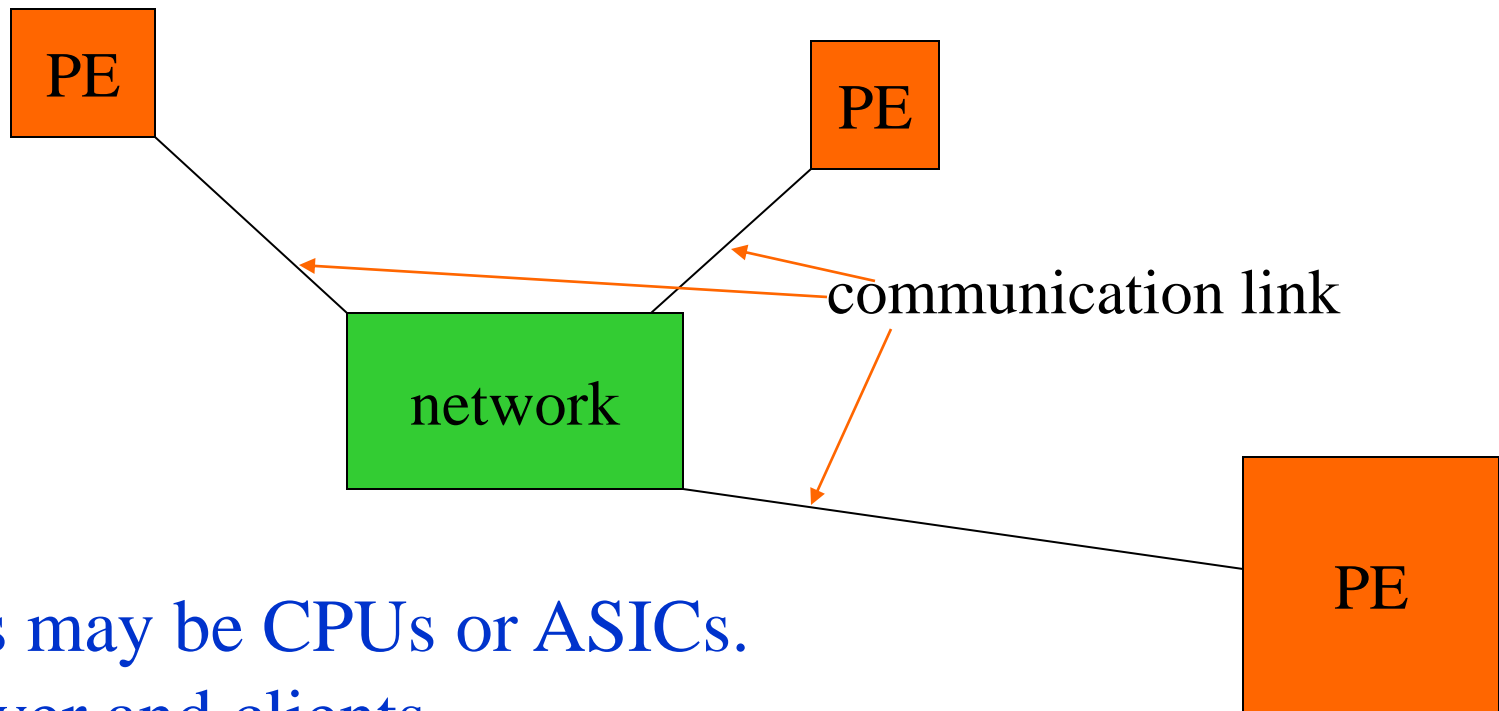
Sensor-actuator networks



It is necessary to put some PEs near where the events occur.

Network elements

distributed computing platform:



PEs may be CPUs or ASICs.
Server and clients

Distributed ES



- ⌘ Unlike the system bus, the distributed embedded system does not have memory on the network (or bus)
- ⌘ PEs do not fetch instruction over the network as they do on the microprocessor bus.
 - ☑ speed of PE and latency of network

Why distributed?

⌘ Network-based embedded system

☑ More complicated, then why?

⌘ Physically separated & deadline is short

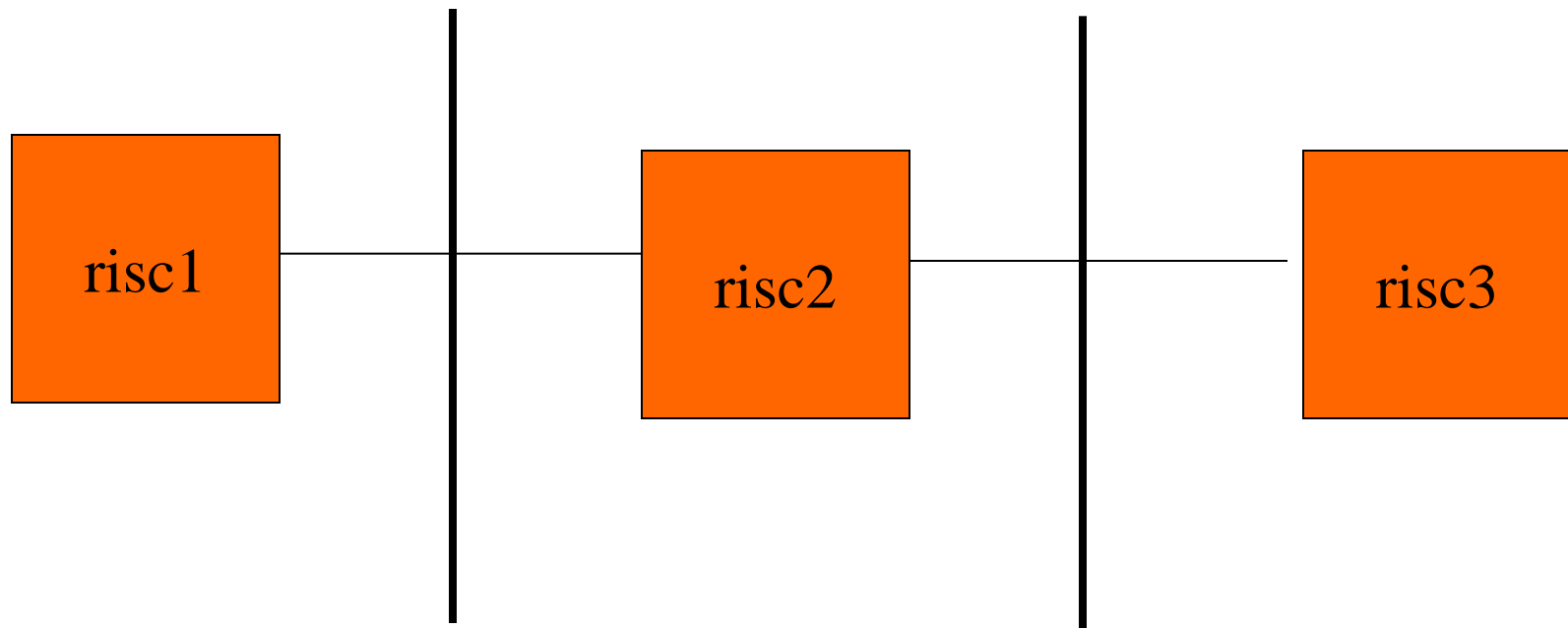
☑ Rather than building high-speed network to carry the data to a distant, fast PE.

☑ PE near to the location data collected

⌘ Advantage of a distributed system with several CPU

☑ A part of the system can be used to debug another part.

Debugging a multi-core system



To diagnose risc 2, we can use risc1 to generate inputs and risc3 to watch output.

Network abstractions



- ⌘ Networks are complex
- ⌘ Ideally, they provide high-level services while hiding details of data transmission
- ⌘ International Standards Organization (ISO) developed the **Open Systems Interconnection (OSI)** model to help us to understand networks:
 - ☑ 7-layer model.
- ⌘ Provides a standard way to classify network components and operations.

OSI reference model



7. application	end-use interface
6. presentation	data format
5. session	application dialog control
4. transport	connections
3. network	end-to-end service
2. data link	reliable data transport
1. physical	mechanical, electrical

OSI layers



- ⌘ **Physical**: connectors, bit formats, etc.
- ⌘ **Data link**: error detection and control across a single link (single hop).
- ⌘ **Network**: end-to-end multi-hop data communication.
- ⌘ **Transport**: provides connections; may optimize network resources.
- ⌘ **Session**: services for end-user applications: data grouping, checkpointing, etc.
- ⌘ **Presentation**: data formats, transformation services.
- ⌘ **Application**: interface between network and end-user programs.

LAN - Local Area Network

⌘ connects computers that are physically close together (< 1 mile).

☑ high speed

☑ multi-access

⌘ Technologies:

☑ Ethernet 10 Mbps, 100Mbps, 1Gbps

☑ Token Ring 16 Mbps

☑ FDDI 100 Mbps

WAN - Wide Area Network

⌘ connects computers that are physically far apart. “long-haul network”.

- ☑ typically slower than a LAN.

- ☑ typically less reliable than a LAN.

- ☑ point-to-point

⌘ Technologies:

- ☑ telephone lines

- ☑ Satellite communications

MAN - Metropolitan Area Network

⌘ Larger than a LAN and smaller than a WAN

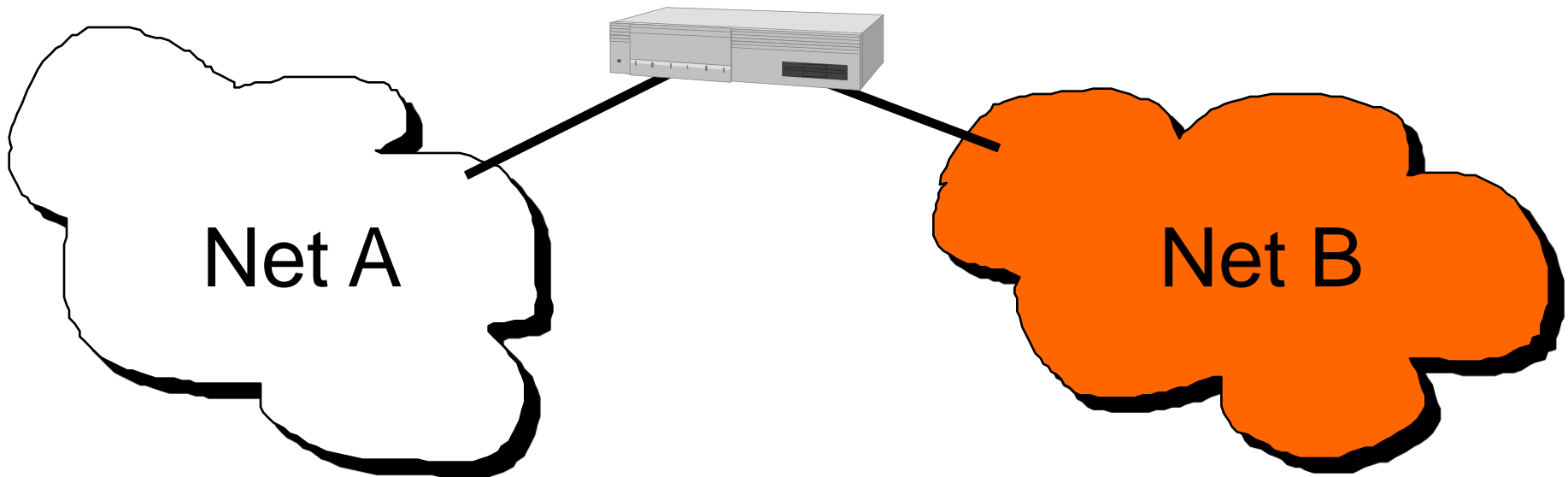
- example: campus-wide network
- multi-access network

⌘ Technologies:

- ☑ coaxial cable
- ☑ microwave

Internetwork

- ⌘ Connection of 2 or more distinct (possibly dissimilar) networks.
- ⌘ Requires some kind of network device to facilitate the connection.



1. Physical Layer

- ⌘ deals with physical characteristics of the transmission medium.
- ⌘ defines electrical, mechanical, procedural, and functional specifications for activating, maintaining, and deactivating the physical link
- ⌘ defines such characteristics as voltage levels, timing of voltage changes, physical data rates, maximum transmission distances, physical connectors, and other similar attributes
- ⌘ Examples : EIA/TIA-232, RJ45, NRZ.

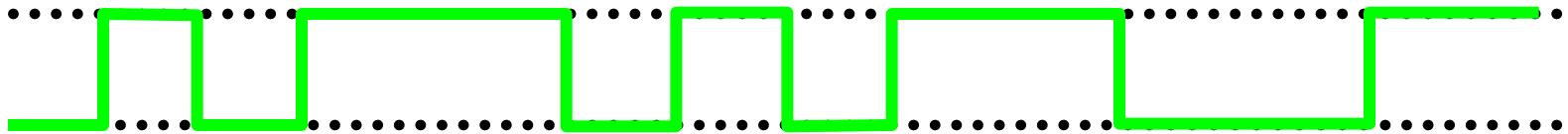
1. Physical Layer

⌘ Responsibility:

- ⊞ transmission of raw bits over a communication channel.

⌘ Issues:

- ⊞ mechanical and electrical interfaces
- ⊞ time per bit
- ⊞ distances



2. Data Link Layer

- ⌘ provides **access** to the media and physical transmission across the media, which enables the data to locate its intended destination
- ⌘ provides **reliable transit** of data across a physical link by using the MAC addresses, which define a hardware or data link address in order for multiple stations to share the same medium and still uniquely identify each other.
- ⌘ Concerned with network topology, network access, error notification, ordered delivery of frames, and flow control.
- ⌘ Examples: **Ethernet**, Frame Relay, FDDI.

2. Data Link Layer



⌘ Two sublayers

☒ Data link control, which provide an error-free communication link

☒ *framing* (dividing data into chunks)

- header & trailer bits

☒ addressing

☒ MAC, which is needed by multiaccess networks.

☒ MAC provides DLC with “virtual wires” on multiaccess networks.

3. Network Layer

⌘ defines

- ⊞ end-to-end delivery of packets.
- ⊞ logical addressing so that any endpoint can be identified.
- ⊞ how routing works and how routes are learned so that the packets can be delivered.
- ⊞ how to fragment a packet into smaller packets to accommodate different media.

⌘ Routers operate at Layer 3.

3. Network Layer

⌘ Examples: IP, IPX, AppleTalk.

⌘ Responsibilities:

- ☑ path selection between end-systems (routing).

- ☑ subnet flow control.

- ☑ fragmentation & reassembly

- ☑ translation between different network types.

⌘ Issues:

- ☑ *packet* headers

- ☑ virtual circuits

4. Transport Layer



- ⌘ regulates information flow to ensure end-to-end connectivity between host applications reliably and accurately.
- ⌘ segments data from the sender and reassembles the data into a data stream on the receiver.
- ⌘ the lower four layers are concerned with data transport issues.

4. Transport Layer

⌘ Layer 4 protocols include

☑ TCP (Transmission Control Protocol) and

☑ UDP (User Datagram Protocol).

⌘ Responsibilities:

☑ provides virtual end-to-end links between peer processes.

☑ end-to-end flow control

⌘ Issues:

☑ headers

☑ error detection

☑ reliable communication

5. Session Layer



- ⌘ defines how to start, control and end sessions between applications.
- ⌘ includes the control and management of multiple bi-directional messages using dialogue control.
- ⌘ synchronizes dialogue between two hosts' presentation layers and manages their data exchange.
- ⌘ The upper three layers (the application, presentation, and session layers) are concerned with application issues.

5. Session Layer

- ⌘ The session layer offers provisions for efficient data transfer.
- ⌘ Examples: SQL, ASP(AppleTalk Session Protocol).
- ⌘ Responsibilities:
 - ☑ establishes, manages, and terminates sessions between applications.
 - ☑ service location lookup
- ⌘ Many protocol suites do not include a session layer.

6. Presentation Layer



- ⌘ The information that the application layer of one system sends out is ensured to be read by the application layer of another system.
- ⌘ If necessary, translates between multiple data formats by using a common format.
- ⌘ provides encryption and compression of data.

6. Presentation Layer

⌘ Examples: JPEG, MPEG, ASCII, EBCDIC, HTML.

⌘ Responsibilities:

- ☑ data encryption

- ☑ data compression

- ☑ data conversion

⌘ Many protocol suites do not include a Presentation Layer.

7. Application Layer

- ⌘ provides network services to the user's applications.
- ⌘ does not provide services to any other OSI layer, but rather, only to applications outside the OSI model.
- ⌘ Examples of such applications: spreadsheet programs, word processing programs, and bank terminal programs.

7. Application Layer

- ⌘ establishes the availability of intended communication partners, synchronizes and establishes agreement on procedures for error recovery and control of data integrity.
- ⌘ Responsibilities:
 - ☑ anything not provided by any of the other layers
- ⌘ Issues:
 - ☑ application level protocols
 - ☑ appropriate selection of “type of service”

TCP/IP protocols

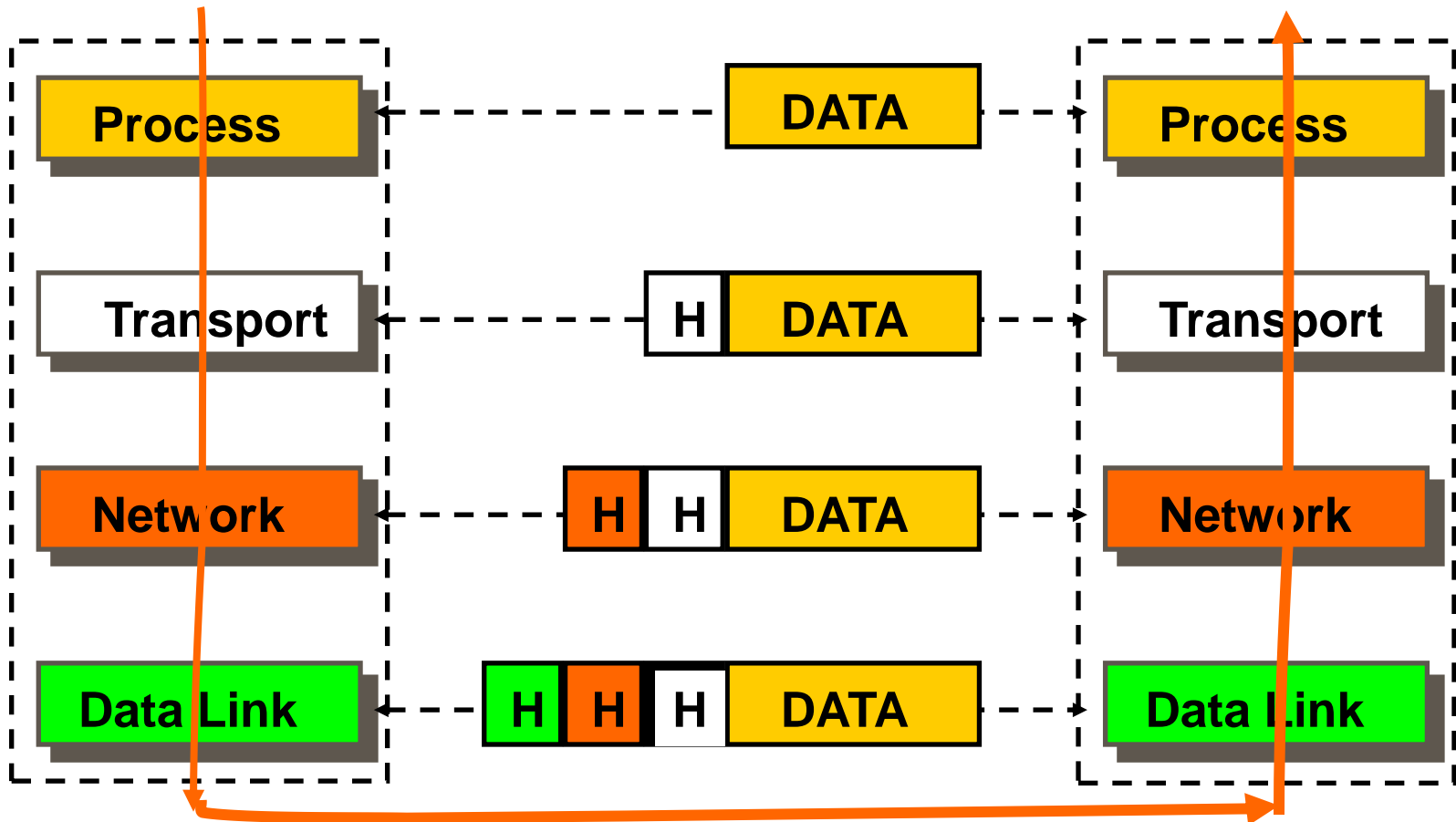
- ⌘ Application layer (telnet, ssh, http, ftp, etc)
 - ☑ Main functionality: run application protocols
- ⌘ Transport layer (TCP, UDP)
 - ☑ Main functionality: reliability
- ⌘ Network layer (IPv4, IPv6)
 - ☑ Main functionality:
routing/fragmentation/internetworking
- ⌘ Host to data link layer (Ethernet)
 - ☑ Main functionality: medium access, encoding

Layering & Headers



- ⌘ Each layer needs to add some control information to the data in order to do its job.
- ⌘ This information is typically appended to the data before being given to the lower layer.
- ⌘ Once the lower layers deliver the the data and control information - the peer layer uses the control information.

Headers



Important Summary



- ⌘ **Data-Link**: communication between machines on the same network.
- ⌘ **Network**: communication between machines on possibly different networks.
- ⌘ **Transport**: communication between processes (running on machines on possibly different networks).

Connecting Networks



- ⌘ Repeater: physical layer
- ⌘ Bridge: data link layer
- ⌘ Router: network layer
- ⌘ Gateway: network layer and above.

Repeater in the physical layer

- ⌘ Copies bits from one network to another
- ⌘ Does not look at any bits
- ⌘ Allows the extension of a network beyond physical length limitations



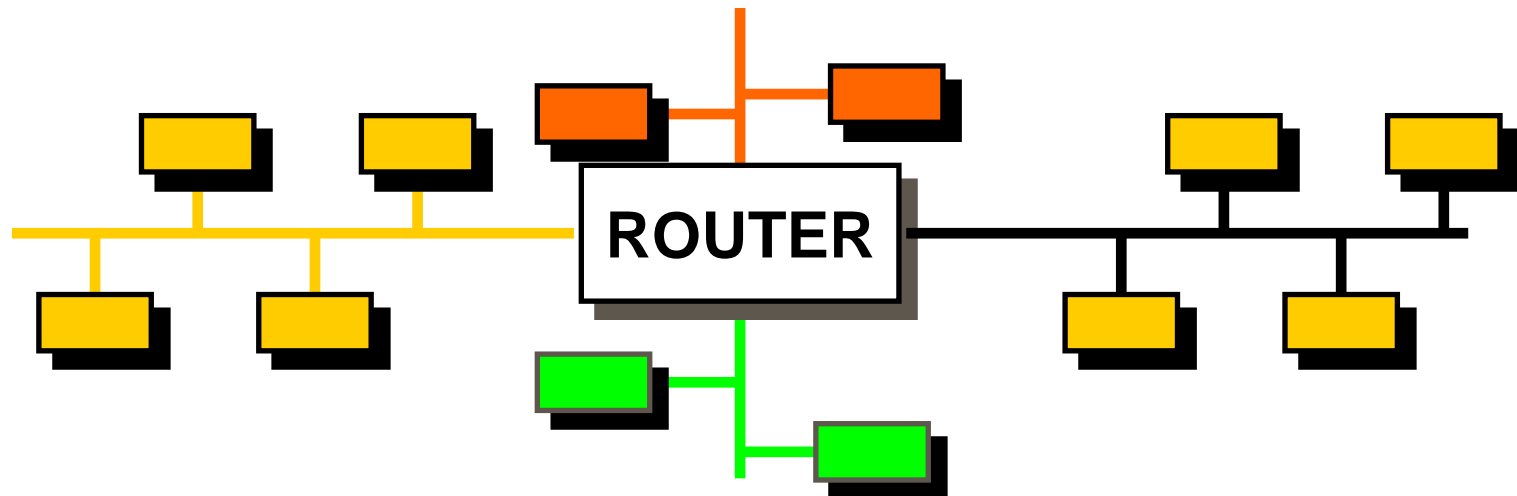
Bridge in the data link layer

- ⌘ Copies frames from one network to another
- ⌘ Can operate selectively - does not copy all frames (must look at data-link headers).
- ⌘ Extends the network beyond physical length limitations.



Router in the network layer

- ⌘ Copies packets from one network to another.
- ⌘ Makes decisions about what *route* a packet should take (looks at network headers).

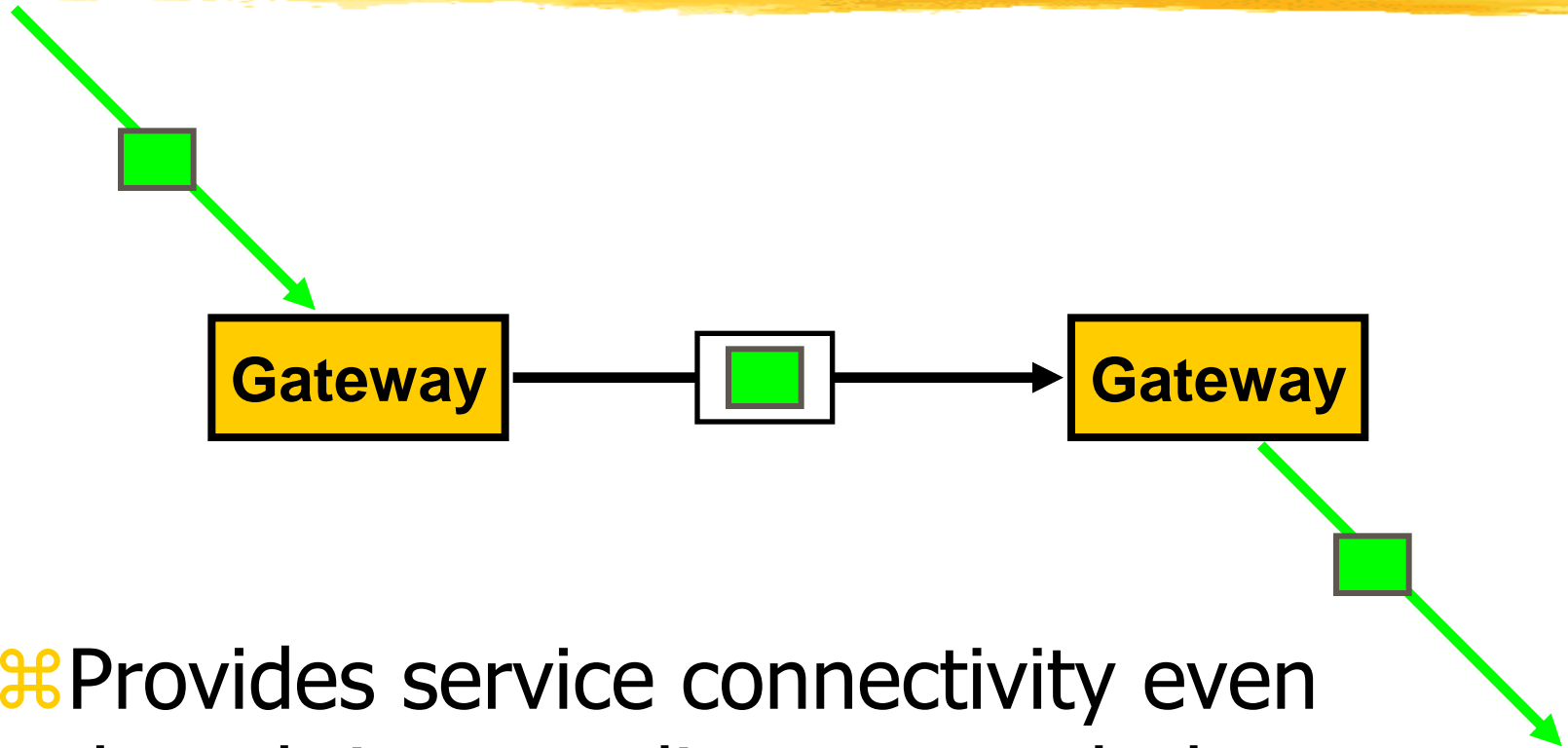


Gateway



- ⌘ Operates as a router
- ⌘ Data conversions above the network layer.
- ⌘ Conversions:
 - encapsulation - use an intermediate network
 - translation - connect different application protocols
 - encryption - could be done by a gateway

Encapsulation



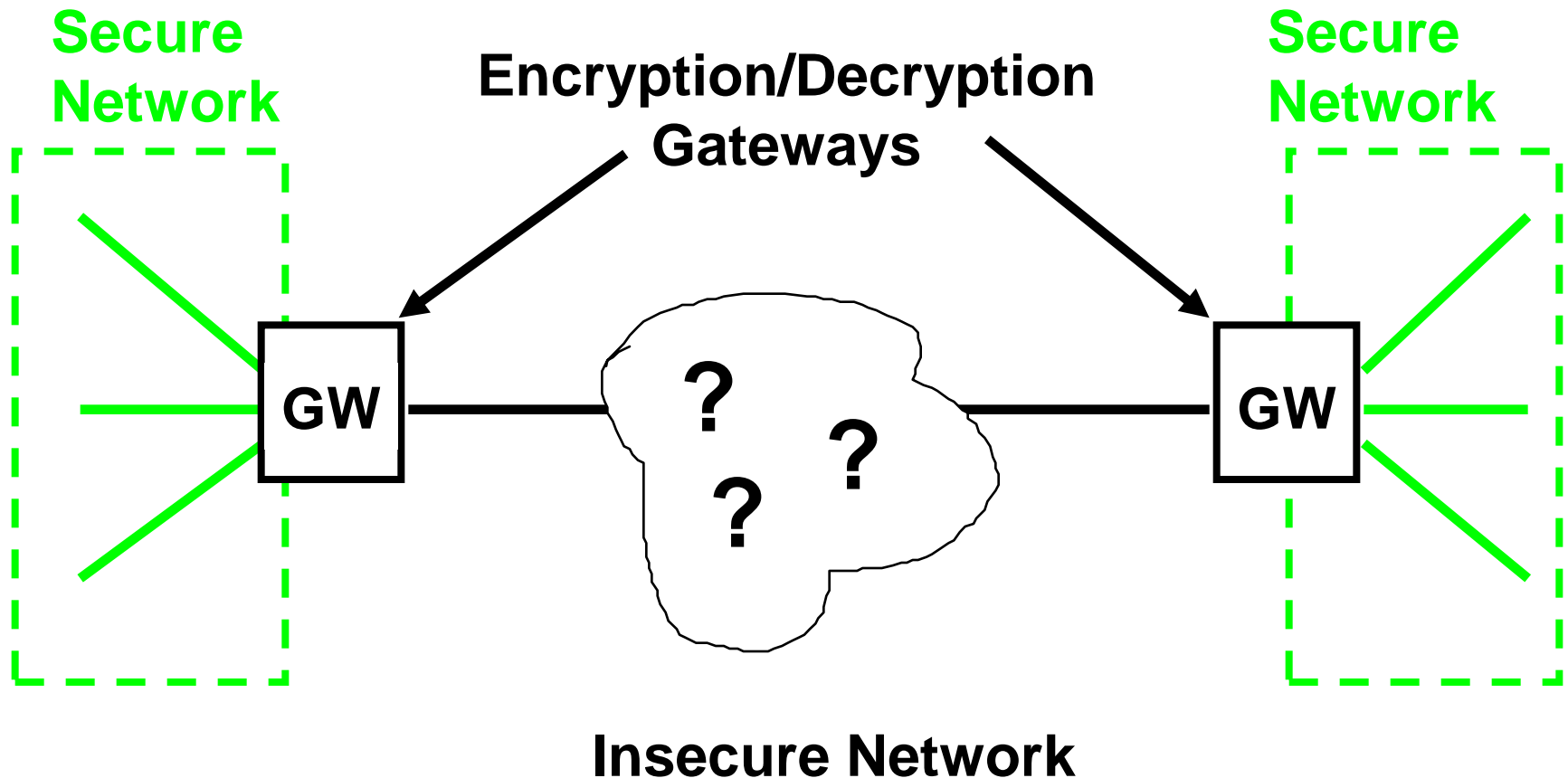
- ⌘ Provides service connectivity even though intermediate network does not support protocols.

Translation



⌘ Translate from green protocol to brown protocol

Encryption gateway



Hardware vs. Software



- ⌘ Repeaters are typically hardware devices.
- ⌘ Bridges can be implemented in hardware or software.
- ⌘ Routers & Gateways are typically implemented in software so that they can be extended to handle new protocols.
- ⌘ Many workstations can operate as routers or gateways.

Hardware architectures



⌘ Many different types of networks:

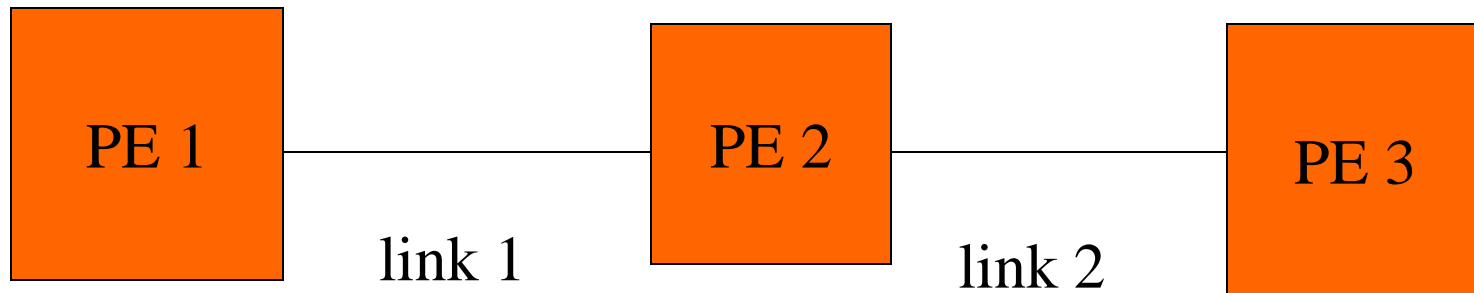
- ☑ topology;

- ☑ scheduling of communication;

- ☑ routing.

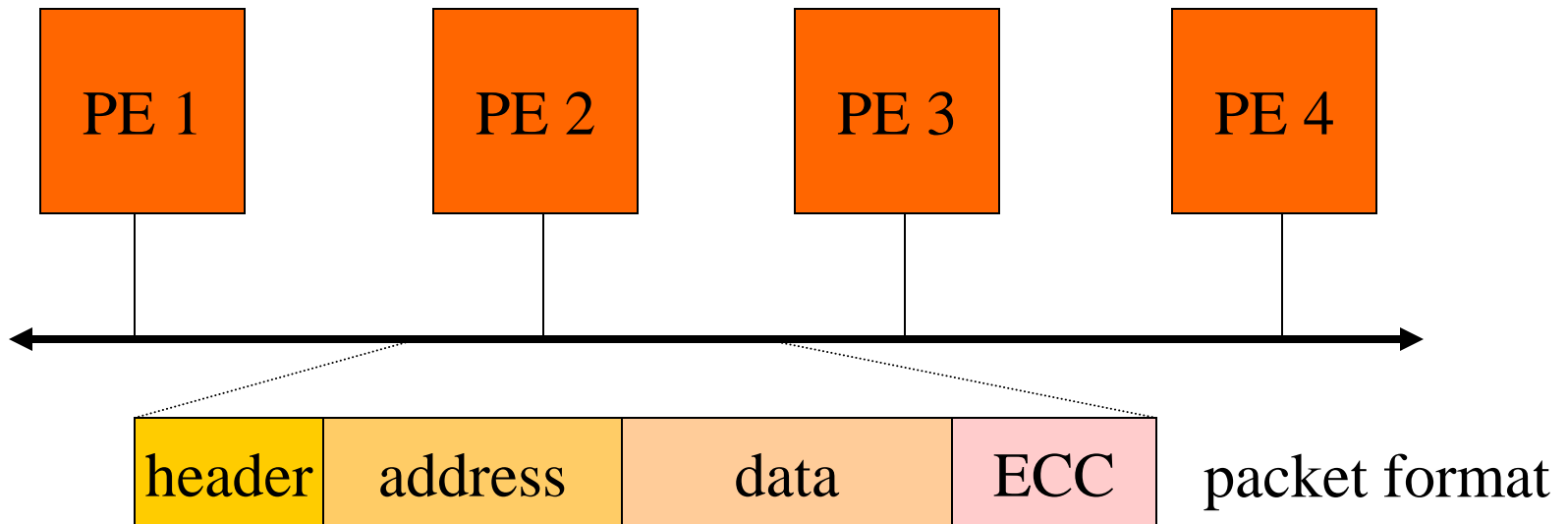
Point-to-point networks

⌘ One source, one or more destinations, no data switching (serial port):



Bus networks

⌘ Common physical connection:

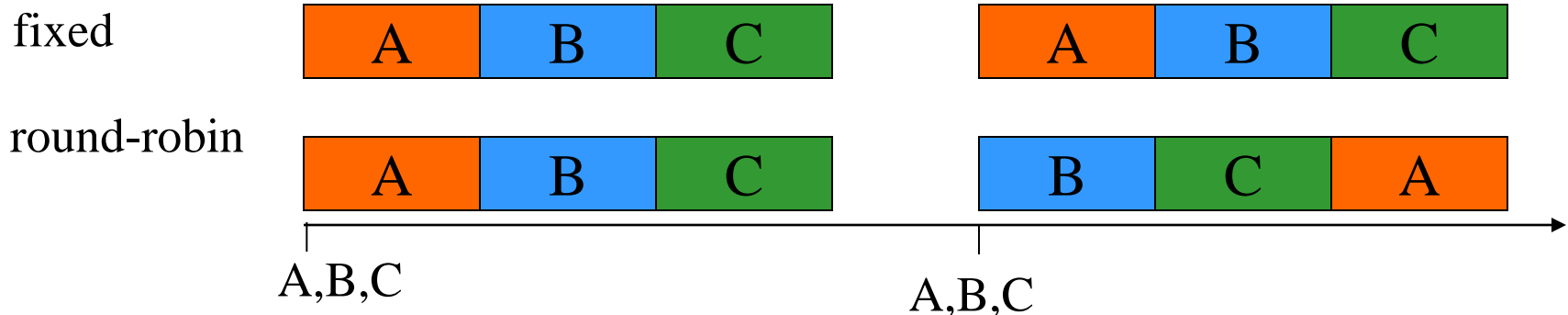


Bus arbitration

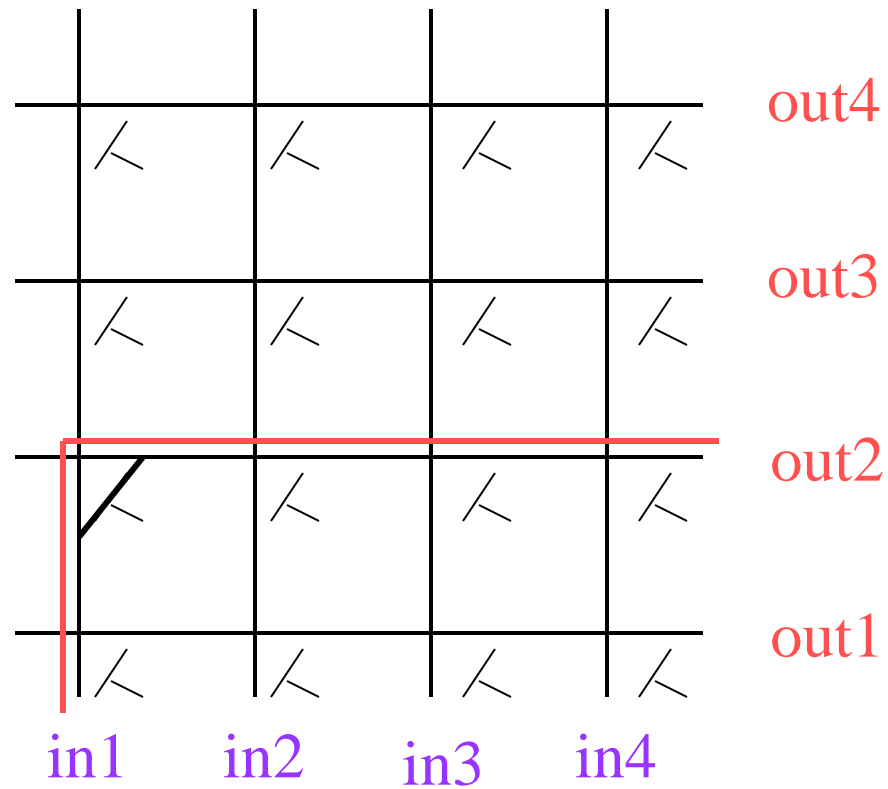
⌘ **Fixed**: Same order of resolution every time.

⌘ **Fair**: every PE has same access over long periods.

⏏ **round-robin**: rotate top priority among PEs.



Crossbar



Crossbar characteristics

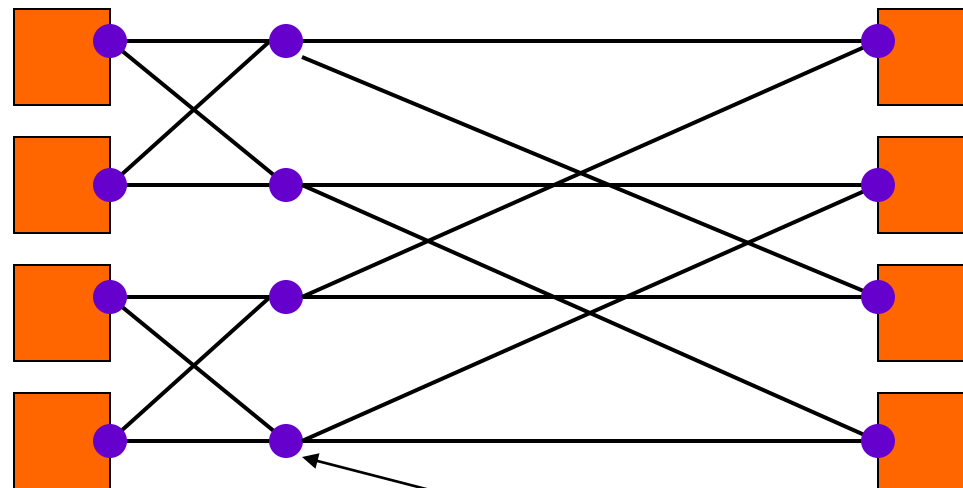


- ⌘ **Non-blocking** (for 1-to-1 mapping)
- ⌘ Can handle multiple multi-cast combinations.
- ⌘ Size proportional to n^2 .

Blocking: if some combinations of sources and destinations
For which messages cannot be delivered simultaneously.

Multi-stage networks

- ⌘ Use several stages of switching elements.
- ⌘ Often blocking.
- ⌘ Often smaller than crossbar.



Message-based programming

⌘ Transport layer provides message-based programming interface:

```
send_msg(adrs, data1);
```

⌘ Data must be broken into packets at source, reassembled at destination.

Blocking vs non-blocking



⌘ Message passing: blocking

- ☑ Simplest implementation

- ☑ The routine is not returning until its data has received or transmitted

⌘ Nonblocking network interface requires a queue of data to be sent

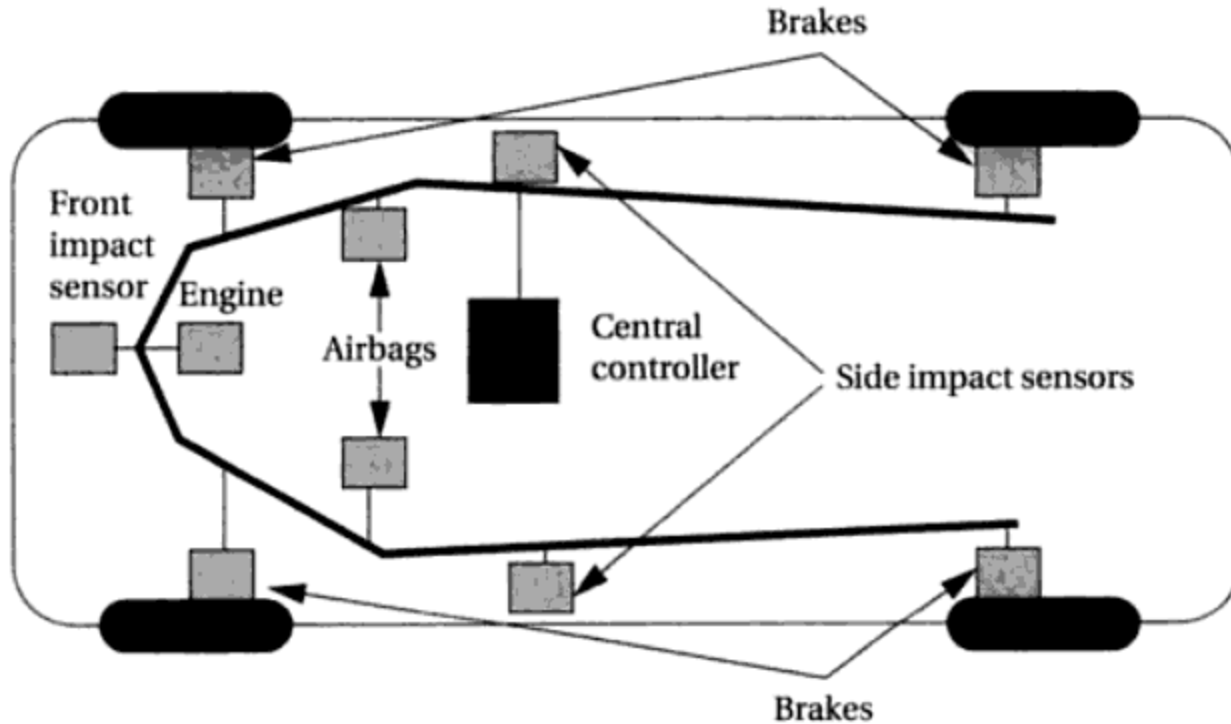
Data-push programming

⌘ **Data-push programming**: make things happen in network based on data transfers.

☑ Nodes send data out without any request from their intended users.

⌘ Data-push programming makes sense for periodic data, which reduces data traffic on the network by automatically sending it when it is needed.

Data-push network



The sensors generally need to be sampled periodically. In such a system, it makes sense for sensors to transmit their **data** automatically rather than waiting for the controller to request it.

System buses



- ⌘ Multibus [Intel] & VME [Motorola]: multi-card computer system
- ⌘ ISA bus: I/O cards for PC-based systems
- ⌘ PCI bus: high-speed interfaces for PC-based applications; replace ISA

Interconnection networks



- ⌘ For embedded systems
- ⌘ I²C bus: microcontroller-based systems
- ⌘ CAN bus: for automotive electronics
- ⌘ Echelon LON network: for home and industrial automation

I²C (inter-integrated circuit) bus

- ⌘ Designed for low-cost, medium data rate applications.
- ⌘ Command interface in a MPEG2 video chip
- ⌘ Characteristics:
 - ☑ serial;
 - ☑ multiple-master;
 - ☑ fixed-priority arbitration.
- ⌘ Several microcontrollers come with built-in I²C controllers.

I²C bus



⌘ ~ up to 100 kbps (standard) ~up to 400 bps (extended)

⌘ Two lines

☑ SDL: serial data line

☑ SCL: serial clock line

Terminology



- ⌘ Transmitter – The device sending data to the bus
- ⌘ Receiver – Device receiving data from the bus
- ⌘ Master – device initiating a transfer, generates to clock and terminates a transfer
- ⌘ Slave – Device addressed by the master
- ⌘ Multi-master – more than one master can attempt to control the bus
- ⌘ Arbitration – procedure to insure that only one master has control of ther bus at any instant
- ⌘ Synchronization – procedure to sync then clocks of two or more devices

Inter-Integrated Circuit

⌘ Multi-master, two wire bus , up to 100 kbits/sec

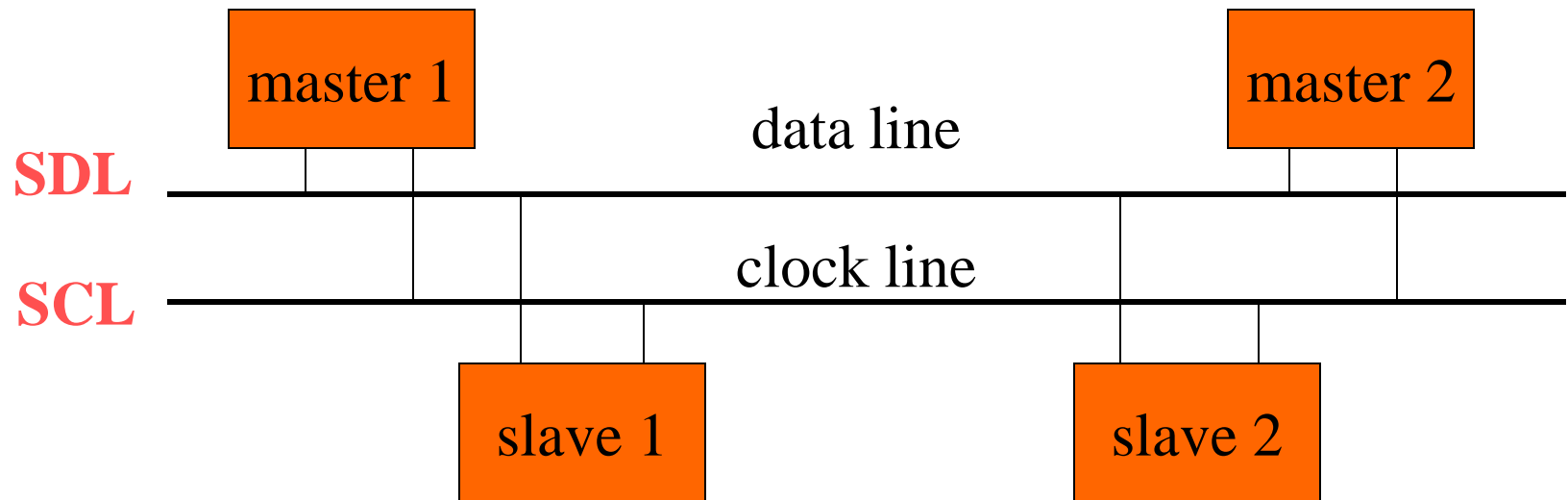
- ☒ One data line (SDA)

- ☒ One clock line (SCL)

- ☒ Master controls clock for slaves

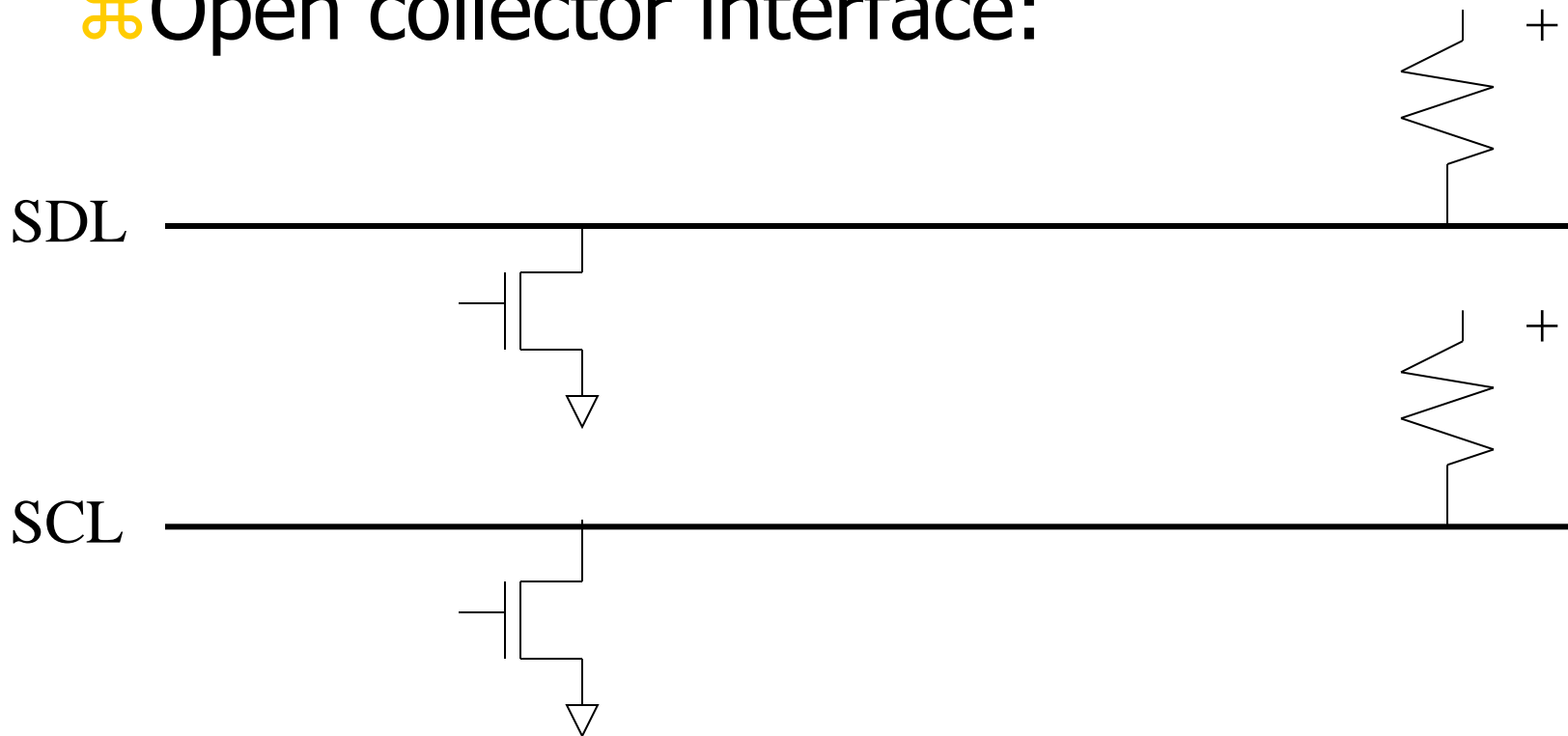
- ☒ Each connected slave has a unique 7-bit address

I²C physical layer



I²C electrical interface

⌘ Open collector interface:



I²C signaling



- ⌘ Sender pulls down bus for 0.
- ⌘ Sender listens to bus---if it tried to send a 1 and heard a 0, someone else is simultaneously transmitting.
- ⌘ Transmissions occur in 8-bit bytes.

Protocol



- ⌘ Transfers are byte oriented, msb first
- ⌘ Start: SDA goes low while SCL is high
- ⌘ Master sends address of slave (7-bits) on next 7 clocks
- ⌘ **Master** sends read/write request bit
 - ⊞ 0-write to slave
 - ⊞ 1-read from slave
- ⌘ **Slave** ACKs by pulling SDA low on next clock
- ⌘ Data transfers now commence

Complete I2C Transfer

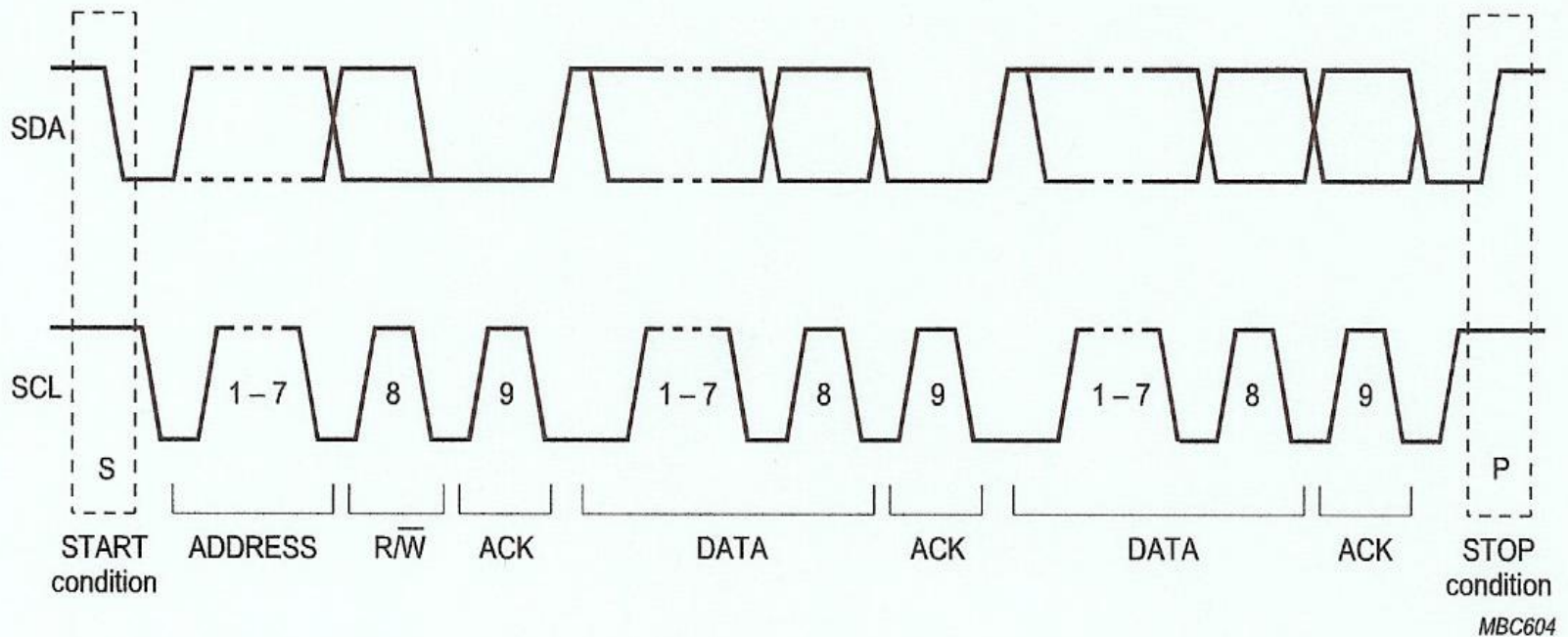


Fig.10 A complete data transfer.

Master-to-Slave Data Transfer



- ⌘ Clock is controlled by master
- ⌘ Data is written to slave on next 8 clock pulses
- ⌘ Data receipt is ACKed by slave on 9th pulse by pulling SDA low
- ⌘ When slave releases SDA, master can send next byte
- ⌘ Master will eventually set a Stop condition by making a low to high transition on SDA with SCL is high

Master Writes to Slave

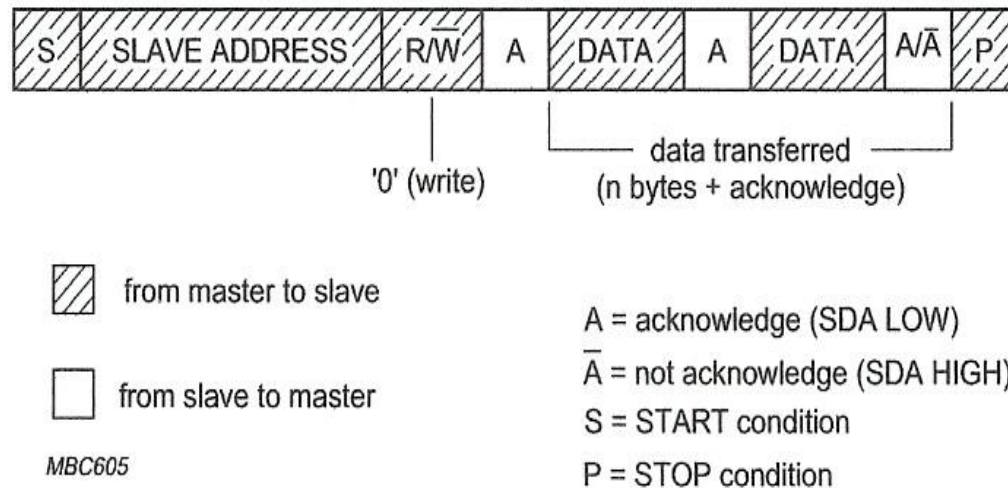


Fig.11 A master-transmitter addressing a slave receiver with a 7-bit address. The transfer direction is not changed.

Master Reads from Slave

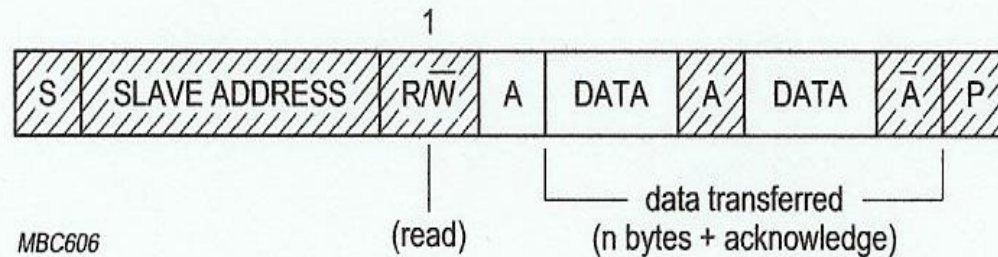


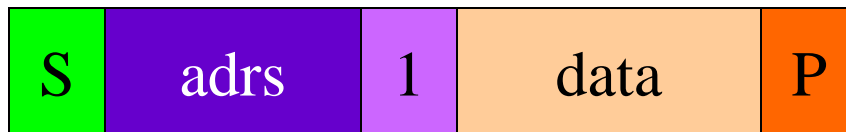
Fig.12 A master reads a slave immediately after the first byte.

I²C transmissions

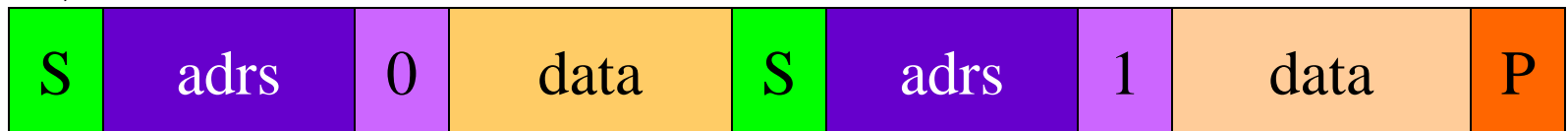
multi-byte write



read from slave



write, then read



I2C Extensions



- ⌘ 10 bit addressing (up to 1024 addresses)
- ⌘ Fast mode – up to 400 kbits/sec
- ⌘ High-Speed – up to 3.4 Mbits/sec

I²C bus arbitration



- ⌘ Sender listens while sending address.
- ⌘ When sender hears a conflict, if its address is higher, it stops signaling.
- ⌘ Low-priority senders relinquish control early enough in clock cycle to allow bit to be transmitted reliably.