



# **Chapter 2. Non-linear Stability and Hyperbolic PDE**

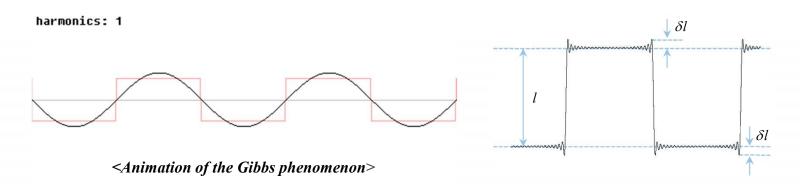


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### Gibbs-Wilbraham Phenomenon

- Approximation of a profile including discontinuity by Fourier Series (or interpolating techniques using basis functions)
  - Oscillations occurs across discontinuity with  $O(1) \rightarrow$  It never dies out even if the number of basis function is increasing.
  - Henry Wilbraham (1848), J. Willard Gibbs (1899)



- **Magnitude of overshoot/undershoot:**  $(\delta l / l) \sim \pm 14\%$
- Locally converge (or L<sub>1</sub>, L<sub>2</sub> convergence) but not uniformly (L<sub>∞</sub> convergence)
   → warning to naïve capturing discontinuities by simply increasing the number of interpolating function or mesh point

- First-Order Scheme and Numerical Diffusion
  - For  $u_t + au_x = 0$  with Upwind or L-F scheme

$$F_{j+1/2,up} = \frac{a}{2} \left( u_{j}^{n} + u_{j+1}^{n} \right) - \frac{|a|}{2} \Delta u_{j+1/2}^{n}$$
with  $u_{j}^{n+1} = u_{j}^{n} - \frac{\Delta t}{\Delta x} \left( F_{j+1/2} - F_{j-1/2} \right)$ 

$$F_{j+1/2,L-F} = \frac{a}{2} \left( u_{j}^{n} + u_{j+1}^{n} \right) - \frac{\Delta x}{2\Delta t} \Delta u_{j+1/2}^{n}$$

Modified equations

$$u_t + au_x = \begin{cases} \frac{a\Delta x}{2} (1 - \sigma^2) u_{xx} + \dots & \text{for upwind} \\ \frac{\Delta x^2}{2\Delta t} (1 - \sigma^2) u_{xx} + \dots & \text{for L-F} \end{cases} \rightarrow u_t + au_x = c_1 u_{xx} \dots$$

- Leading error term is numerical dissipative → smooth transition across discontinuity without oscillations
  - Excessive numerical dissipation of  $O(\Delta x)$ 
    - Unacceptable loss of accuracy  $\rightarrow$  Too many grid points
    - Viscous computation and resolution of boundary layer requires at least 2<sup>nd</sup>-order accuracy.
- Second-Order Scheme and Numerical Dispersion
  - With L-W or B-W scheme

• 
$$F_{j+1/2,L-W} = \frac{a}{2} \left( u_j^n + u_{j+1}^n \right) - \frac{a^2 \Delta t}{2\Delta x} \Delta u_{j+1/2}^n$$
 •  $F_{j+1/2,B-W} = a u_j^n + \frac{a(1-\sigma)}{2} \Delta u_{j-1/2}^n$  with  $a > 0$ 

1.2

0.6

0.2

Exact

○ L-F ★ Upwind

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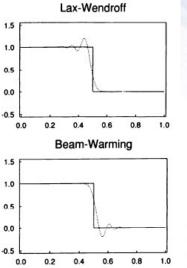
0.8 0.85

- Second-Order Scheme and Numerical Dispersion (cont'd)
  - Modified equations

$$u_t + au_x = \begin{cases} -\frac{a\Delta x^2}{6} (1 - \sigma^2) u_{xxx} \dots & \text{for L-W} \\ \frac{a\Delta x^2}{6} (2 - 3\sigma + \sigma^2) u_{xxx} \dots & \text{for B-W} \end{cases}$$

$$u_{t} + au_{x} = c_{1}u_{xxx} \xrightarrow{discrete FT}{u(x,t) \sim \hat{u}(\omega,t)e^{i\omega x}} \hat{u}(\omega,t)_{t} + i(a\omega + c_{1}\omega^{3})\hat{u}(\omega,t) = 0$$
  

$$\rightarrow \hat{u}(\omega,t) \sim e^{-i(a\omega + c_{1}\omega^{3})t} \quad \text{vs.} \quad \hat{u}_{ex}(\omega,t) \sim e^{-ia\omega t}$$



Numerical dispersion relation :  $a(\omega) = a\omega + c_1\omega^3$  vs.  $a_{ex}(\omega) = a\omega$ For each Fourier component with  $\omega$ , group velocity  $a_g(\omega) \equiv da(\omega)/d\omega$ 

•  $a_g(\omega) = a + 3c_1\omega^2 \approx a$  for small wave number (long wave length)

 $\neq a$  for large wave number (short wave length)

For 
$$a > 0$$
,  $c_1 < 0$  for  $L - W \rightarrow$  lagging error

 $c_1 > 0$  for  $B - W \rightarrow$  leading error

## • Observation

• Numerical oscillations across discontinuity occurs regardless of differencing type (central or upwind) once the order of accuracy is greater than one.

- Godunov's Barrier Theorem on Monotonicity
  - General form of one-step numerical schemes for  $u_t + au_x = 0$  $\sum_{i=1}^{n} \beta_{q} u_{j+q}^{n+1} = \sum_{i=1}^{n} \alpha_{q} u_{j+q}^{n} \text{ with } \beta_{q} \text{ st. } u_{j}^{n+1} \text{ can be uniquely obtained (or } \mathbf{B}_{im} \mathbf{u}^{n+1} = A_{ex} \mathbf{u}^{n})$  $\xrightarrow{\text{Linear mapping}} u_j^{n+1} = \sum c_{jq} u_{j+q}^n, \ c_{jq} = c_{jq} \left( \Delta x, \Delta t, a \right)$ • Upwind:  $u_j^{n+1} = \frac{1}{2}(\sigma + |\sigma|)u_{j-1}^n + (1 - |\sigma|)u_j^n + \frac{1}{2}(|\sigma| - \sigma)u_{j+1}^n$ • L-W:  $u_j^{n+1} = \frac{\sigma}{2}(\sigma+1)u_{j-1}^n + (1-\sigma^2)u_j^n + \frac{\sigma}{2}(\sigma-1)u_{j+1}^n$ **Conditions for consistency and accuracy** • For  $u_j^{n+1} = \sum c_q u_{j+q}^n$  $u_{j} + u_{t}\Delta t + u_{tt}\frac{\Delta t^{2}}{2} + \dots = u_{j} - au_{x}\Delta t + a^{2}u_{xx}\frac{\Delta t^{2}}{2} + \dots = \sum_{q} c_{q} \left[ u_{j} + q\Delta xu_{x} + \frac{(q\Delta x)^{2}}{2}u_{xx} + \dots \right]$ • Consistency :  $\sum c_q = 1$ Eq. (\*1) First-order accuracy :  $\Delta x \sum qc_q = -a\Delta t \rightarrow \sum qc_q = -\sigma$ • Eq. (\*2) Second-order accuracy :  $\Delta x^2 \sum_{q} q^2 c_q = a^2 \Delta t^2 \rightarrow \sum_{q} q^2 c_q = \sigma^2$ Eq. (\*3)

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(Godunov's barrier theorem) For the fully discretized *linear* scheme of  $u_j^{n+1} = Ru_j^n \equiv \sum c_q u_{j+q}^n$ ,

it can not be better than first-order accurate if the scheme is not oscillatory.

• (Positivity condition) If R is stable in maximum-norm,  $c_q$  should be non-negative. (pf) Suppose it is not true, then there exists some negative  $c_q$ .

Choose  $u_{j+q}^n$  st.  $u_{j+q}^n = \begin{cases} 1 & \text{if } c_q > 0 \\ -1 & \text{if } c_q < 0 \end{cases}$ Then,  $\|u^n\|_{\infty} = 1$  and  $u_j^{n+1} = Ru_j^n = \sum_q c_q u_{j+q}^n = \sum_q |c_q|$ Since the scheme is consistent,  $\sum c_q = 1$  and

$$1 = \left|\sum_{q} c_{q}\right| \leq \sum_{q} \left|c_{q}\right| \quad \rightarrow \quad \left\|u^{n}\right\|_{\infty} \leq \sum_{q} \left|c_{q}\right| = u_{j}^{n+1} \leq \left\|u^{n+1}\right\|_{\infty}$$

Thus,  $c_q$  should be non-negative.

The scheme cannot be better than first-order accurate. (pf) Since  $c_q > 0$ , define positive  $\alpha_q$  with  $c_q = \alpha_q^2$ , and

$$\alpha_q = \sqrt{c_q}, \quad \beta_q = q\sqrt{c_q}$$

For second-order accuracy, we have

$$\sum_{q} \alpha_{q}^{2} = 1 \text{ (consistency)}, \quad \sum_{q} \alpha_{q} \beta_{q} = -\sigma \text{ (1st-order)}, \quad \sum_{q} \beta_{q}^{2} = \sigma^{2} \text{ (2nd-order)}$$

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By Cauchy-Schwartz inequality,

$$\left(\sum_{q} \alpha_{q} \beta_{q}\right)^{2} \leq \left(\sum_{q} \alpha_{q}^{2}\right) \left(\sum_{q} \beta_{q}^{2}\right)$$

But equality holds only if  $\beta_q = k\alpha_q$  for some 'constant' k.

This is possible only if  $\alpha_q$  has only one non-zero value.

From Eq. (\*1),  $c_{\tilde{q}} = 1$  for the specific  $\tilde{q}$ , and, from Eq. (\*2),  $\sigma = -\tilde{q} = -k$ .

But this cannot be satisfied for arbitrary value of a,  $\Delta x$ ,  $\Delta t$  (or equivalently,  $\sigma$ ).

#### Constructive implication of Godunov's barrier theorem

- To obtain more than 2<sup>nd</sup>-order scheme without oscillations, the scheme should be 'non-linear' even for linear equation. → Aside from the linear stability for the linear difference schemes, such as Von Neumann stability, the need to develop non-linear stability theory becomes apparent.
  - Maximum-norm boundedness means that a computed result is non-oscillatory.
- Oscillation check of first- or second-order linear schemes from the view point of positivity condition

• Upwind: 
$$u_j^{n+1} = \frac{1}{2}(\sigma + |\sigma|)u_{j-1}^n + (1 - |\sigma|)u_j^n + \frac{1}{2}(|\sigma| - \sigma)u_{j+1}^n$$

• 
$$L-F: u_j^{n+1} = \frac{1+\sigma}{2}u_j^n + \frac{1-\sigma}{2}u_{j+1}^n$$
  
•  $L-W: u_j^{n+1} = \frac{\sigma(1+\sigma)}{2}u_{j-1}^n + (1-\sigma^2)u_j^n - \frac{\sigma(1-\sigma)}{2}u_{j+1}^n$