

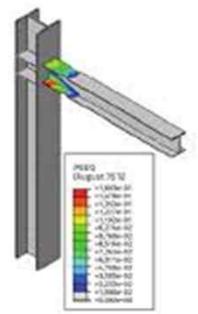
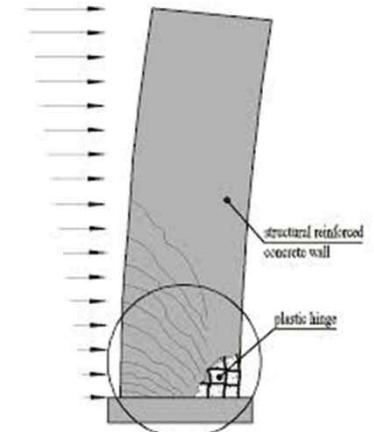
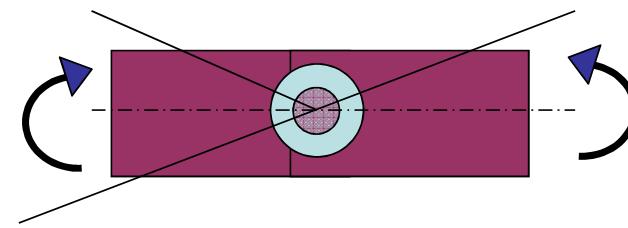
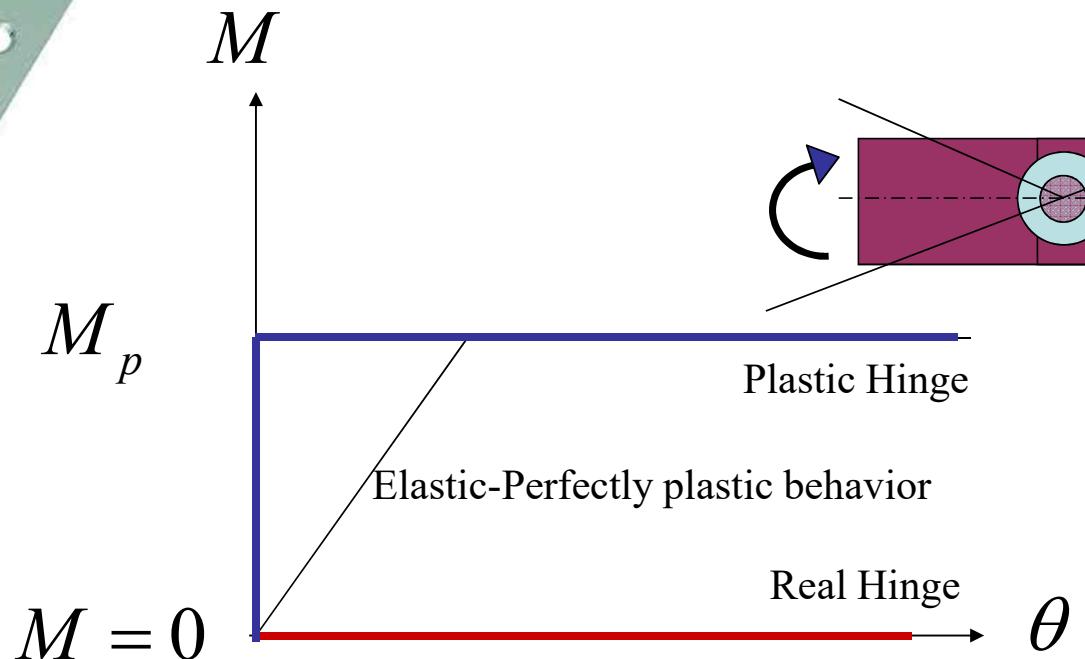
Chap. 2 Plastic Hinge

1. Introduction
2. Moment-curvature relationship and Plastic Hinge Length
3. Full Plastic Moment
4. Design of a cross Section
5. Effect of Axial Load
6. Effect of Shear Force
7. Effect of Combined Axial and Shear Force
8. Compactness
9. Connections

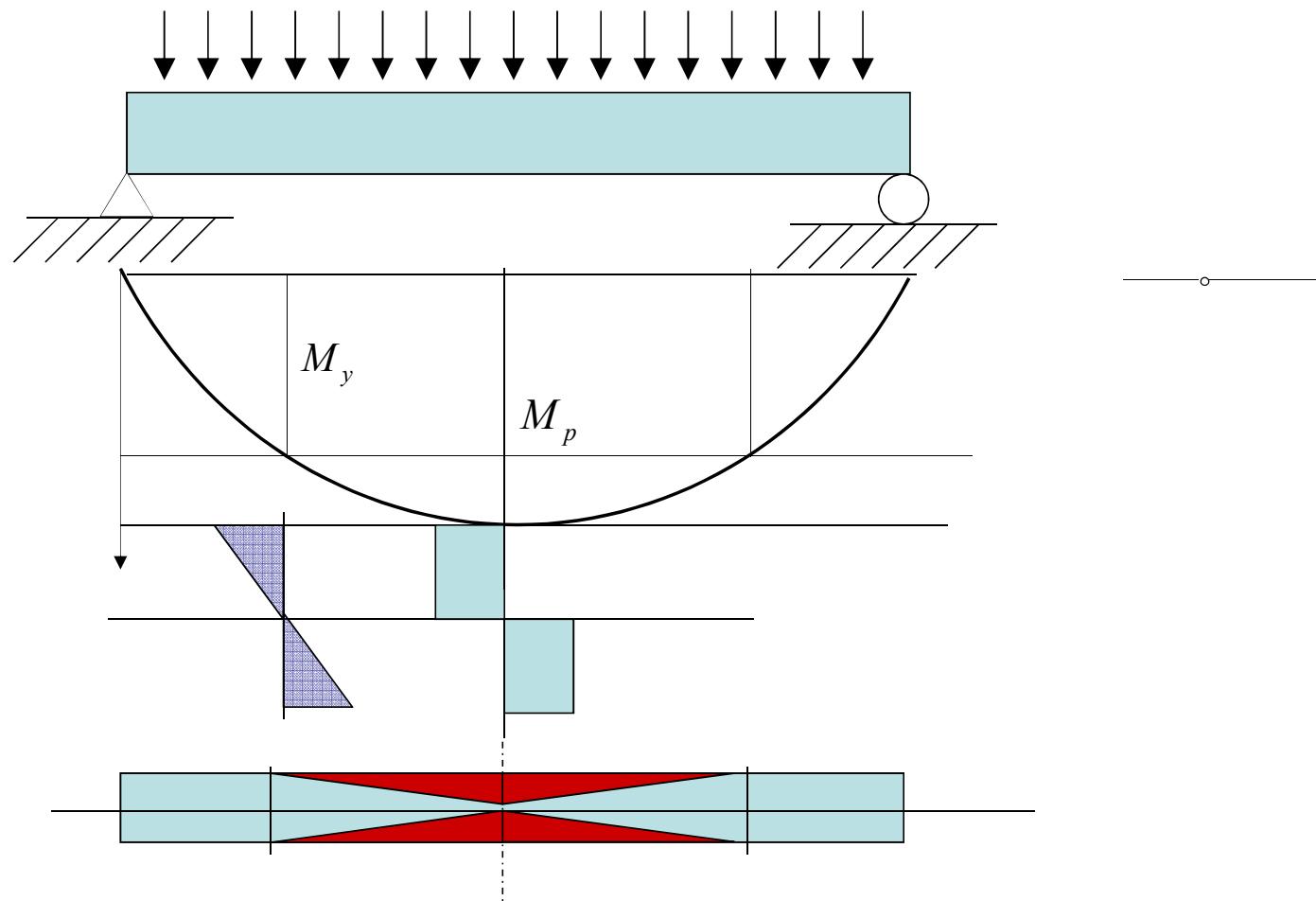
2.1 Introduction

- To elaborate the concept of the plastic hinge and plastic moment
we extend
 - Effect of axial force and shear
 - Compactness (local buckling in plastic hinge zone)

Concept of Plastic Hinge



Plastic Hinge Length (Zone)



Moment-Curvature Relationship and Plastic Hinge Length

2.2.1 M– ϕ relationship of

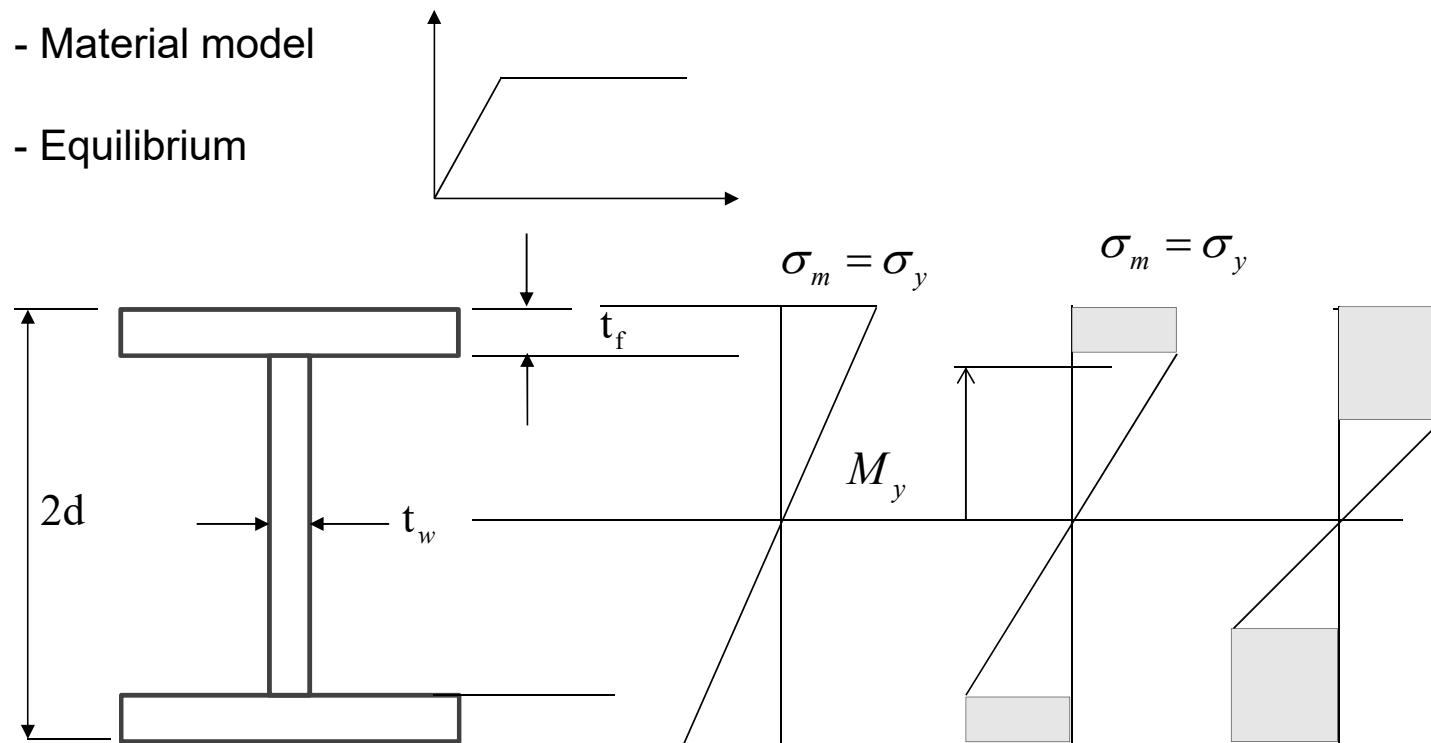


Assumptions

- Plane sections remain plane after bending

- Material model

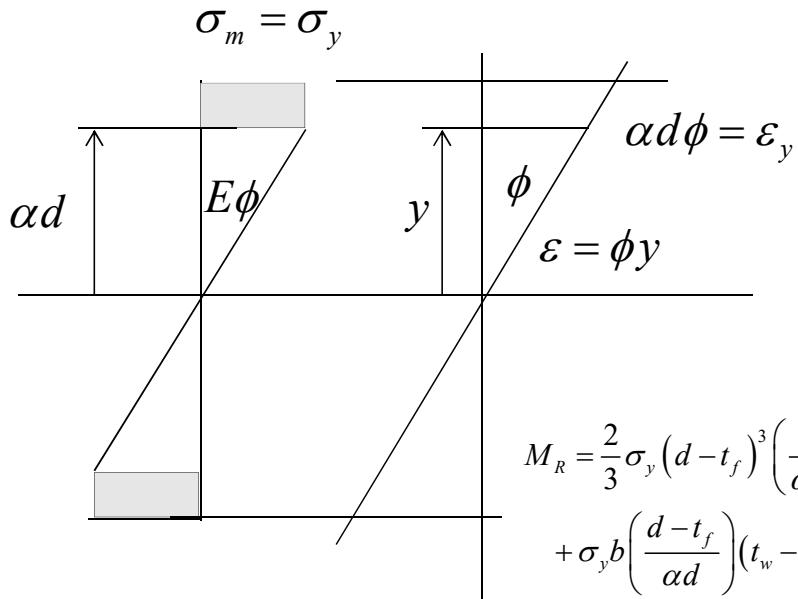
- Equilibrium



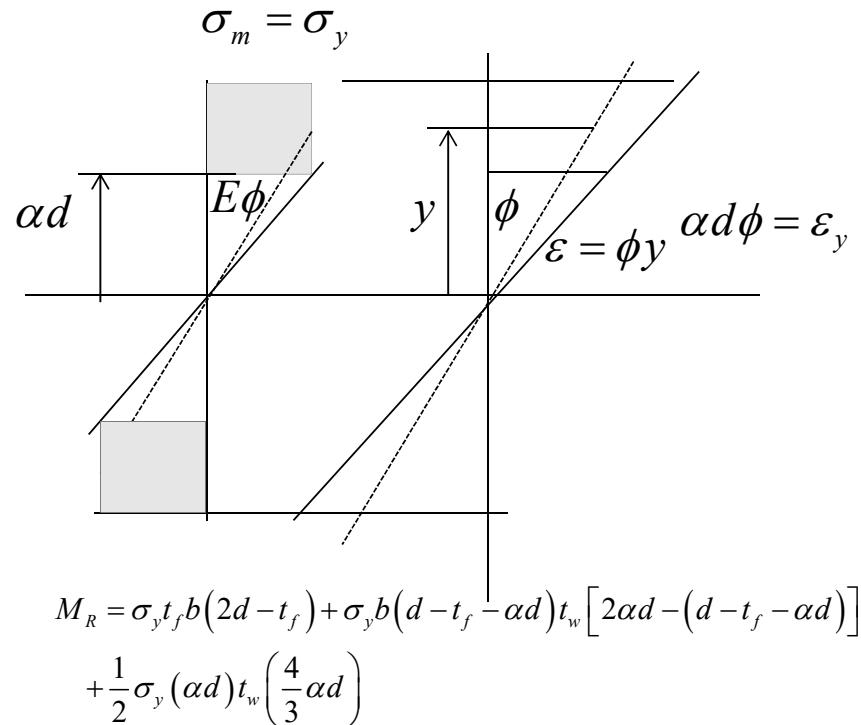
1. Elastic regime

$$\phi_y = \frac{\varepsilon_y}{d} = \frac{\sigma_y}{E} \frac{1}{d}$$

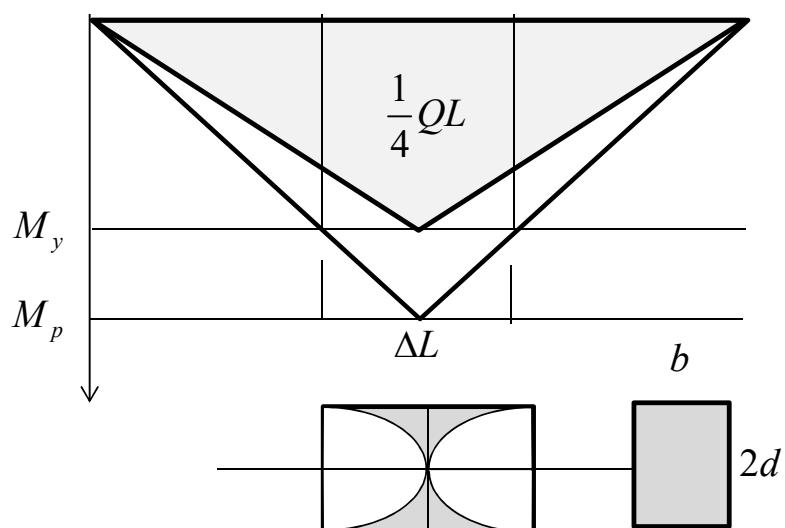
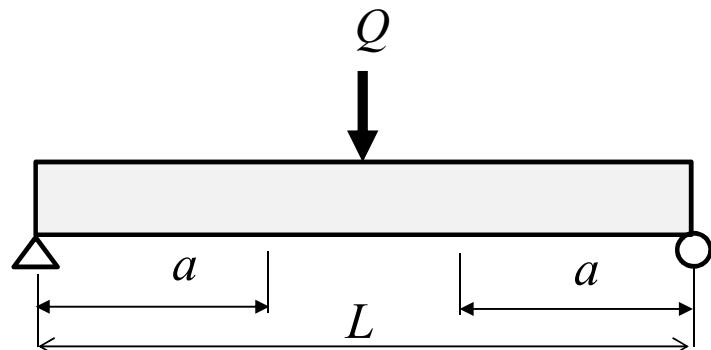
2. Regime II: flange is partially yielded



3. Regime III: Web is partially yielded



2.2.2 Plastic Hinge Length



At the yield $\frac{1}{4}Q_y L = M_y$

At the ultimate $\frac{1}{4}Q_p L = M_p \quad Q_p = \frac{4M_p}{L}$

$$M_c = \frac{Q_p}{2}a = M_y \quad a = \frac{2M_y}{Q_p}$$

$$a = \frac{L}{2\frac{M_p}{M_y}} = \frac{L}{2f}$$

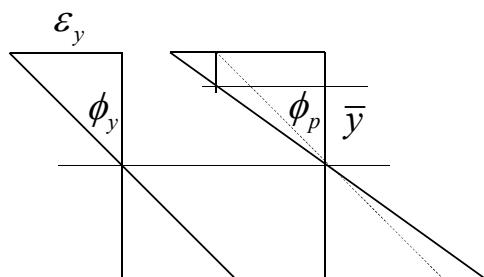
The plastic hinge length

$$\Delta L = L - 2a = L(1 - 1/f)$$

The length of the plastic hinge length depends on the
The boundary and loading patterns

The distribution of the yield zone for 

$$M = \frac{3}{2} M_y \left[1 - \frac{1}{3} \left(\frac{\phi_y}{\phi} \right)^2 \right]$$



$$\phi = \frac{\varepsilon_y}{\bar{y}} \quad \phi_y = \frac{\varepsilon_y}{d}$$

Section

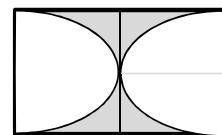
$$M(\bar{y}) = M_p \left[1 - \frac{1}{3} \left(\frac{\bar{y}}{d} \right)^2 \right] \Rightarrow A$$

Member length

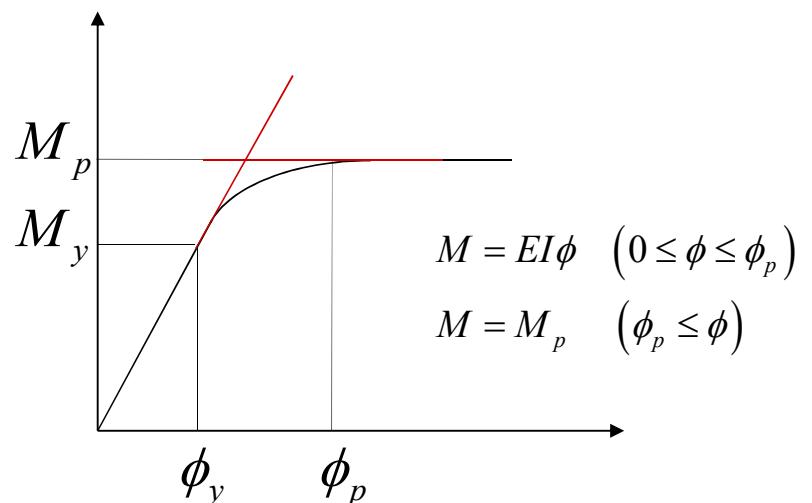
$$M(x) = M_p \frac{L - 2x}{L} \Rightarrow B$$

A=B

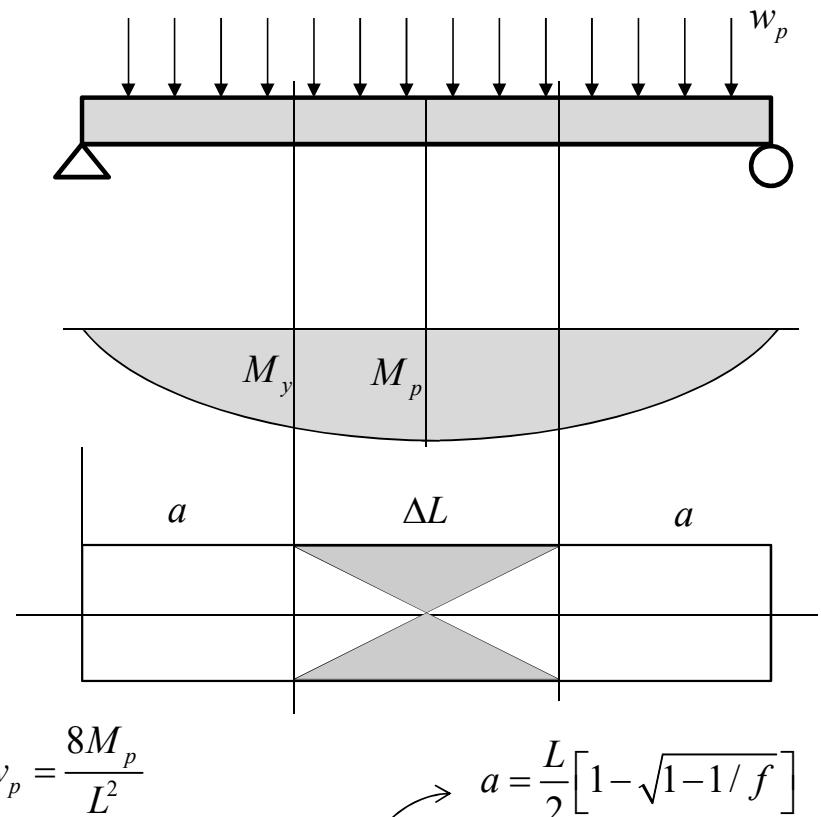
$$\bar{y} = d \sqrt{\frac{6x}{L}}$$



2.2.3 Plastic Hinge Idealization

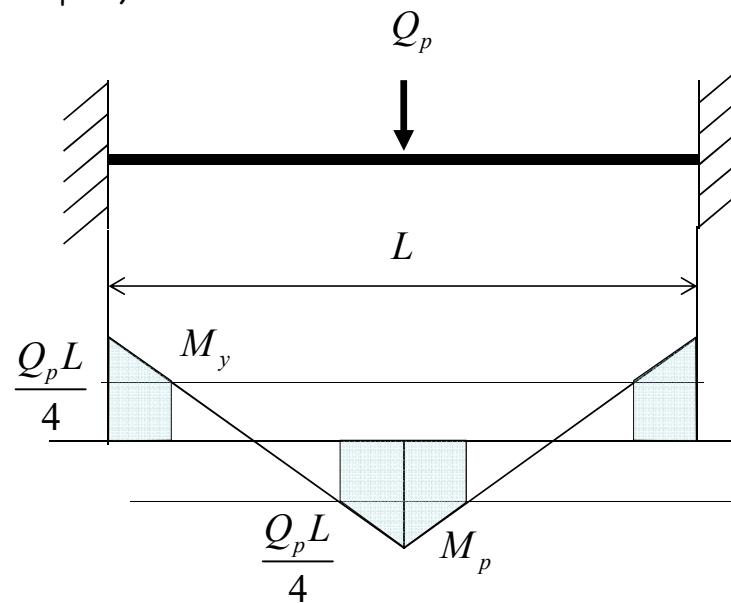


2.2.4 Another example of Plastic Hinge Length



$$\frac{w_p L}{2} a - w_p \frac{a^2}{2} = M_y \quad \Delta L = L - 2a = a = L\sqrt{1 - 1/f}$$

Example)



$$Q_p = \frac{8M_p}{L}$$

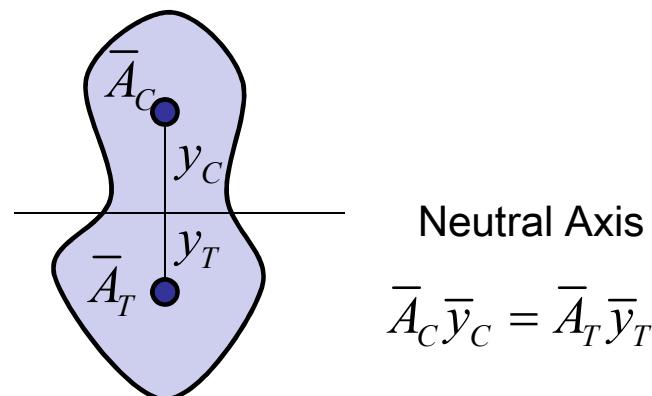
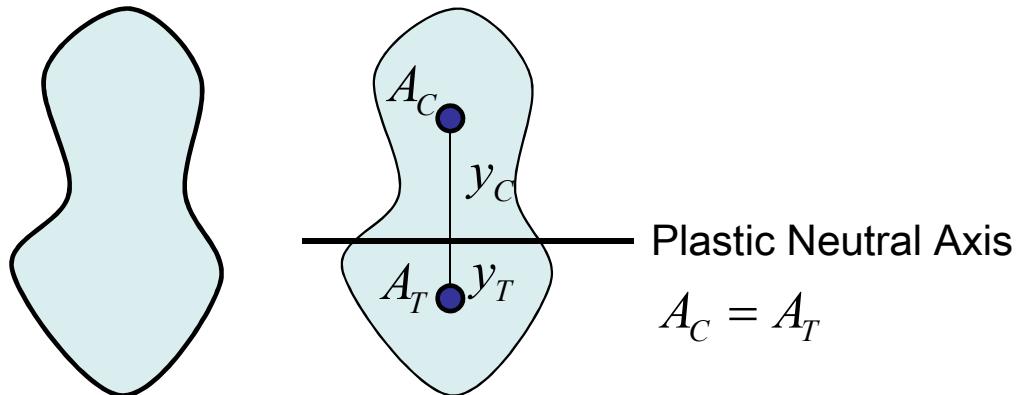
$$M_x = \frac{Q_p}{2}x - M_p$$

$$-M_y = \frac{Q_p}{2}\Delta L_1 - M_p$$

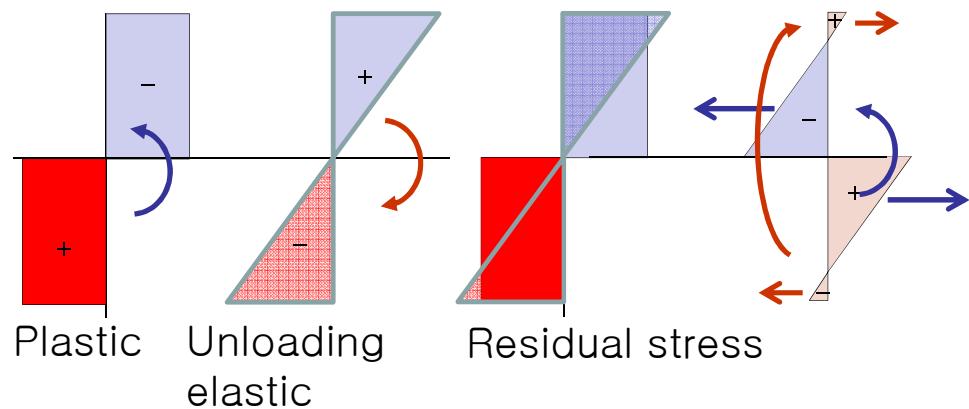
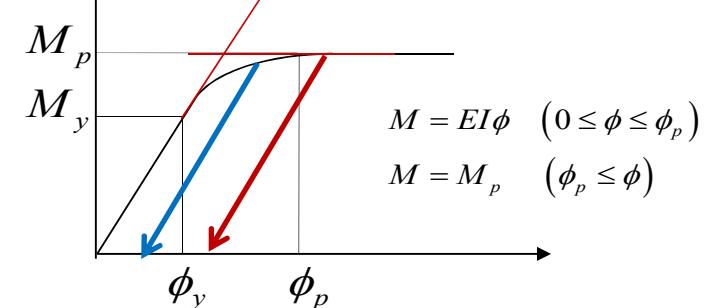
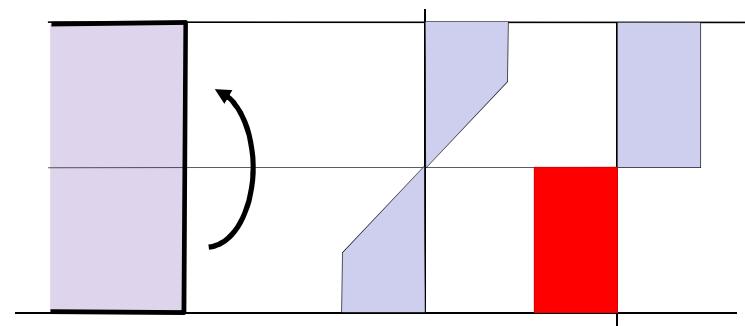
$$\Delta L_1 = \frac{L}{4}(1 - 1/f)$$

$$\Delta L_2 = 2 \frac{L}{4}(1 - 1/f)$$

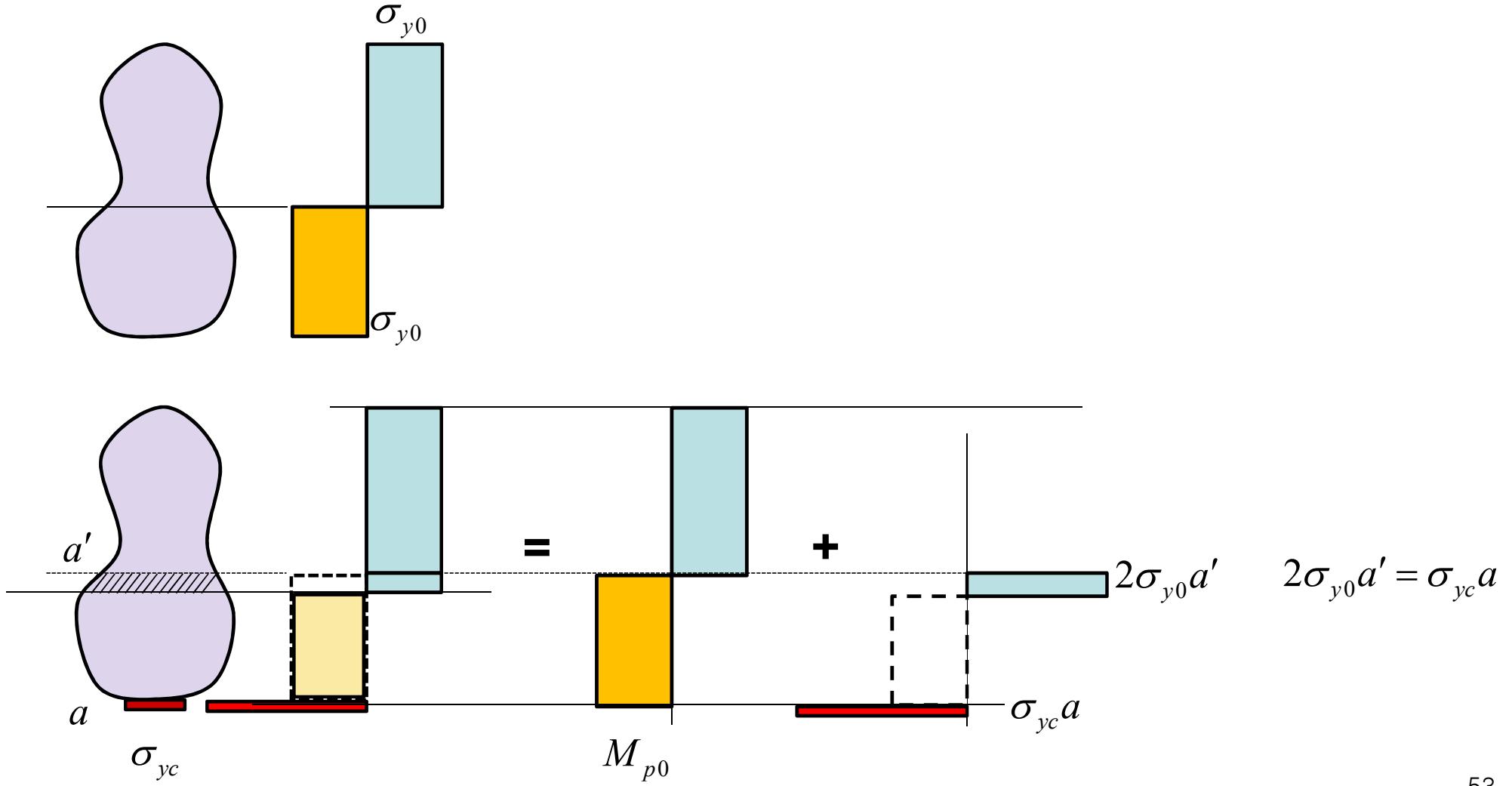
2.3 Full Plastic Moment



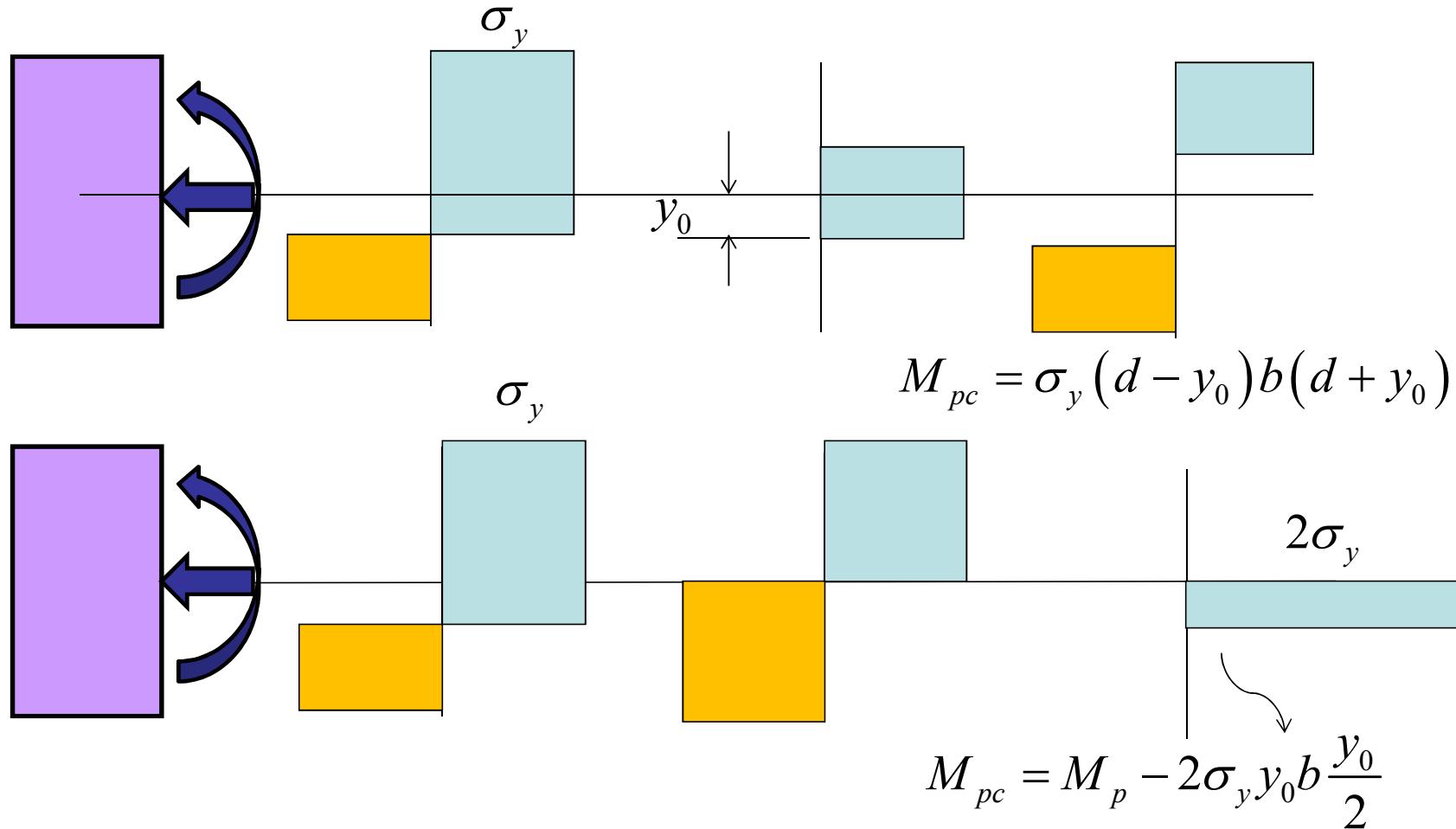
Unloading after Full Plastic Moment



2.4 Design of Cross Section

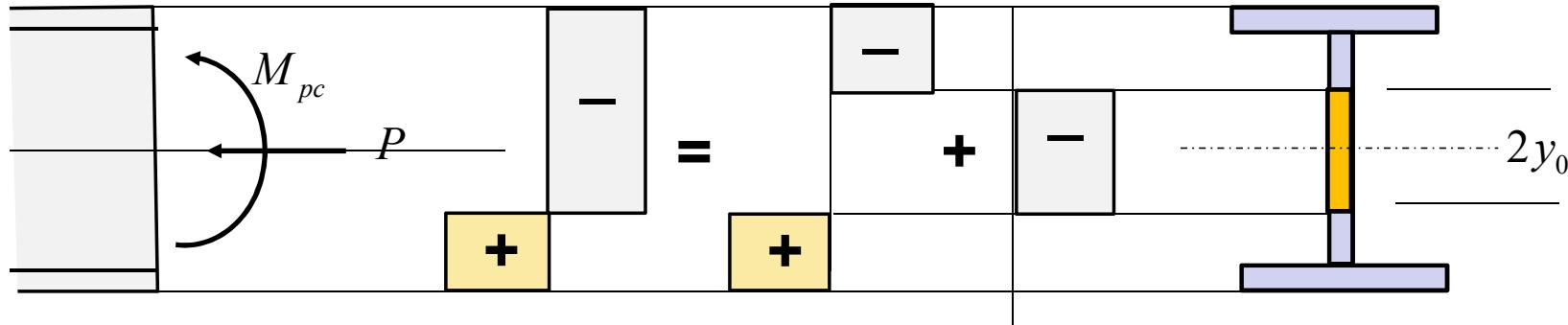


Axial Force Effect: two approaches



2.5.3 WF bending about strong axis

PNA in web

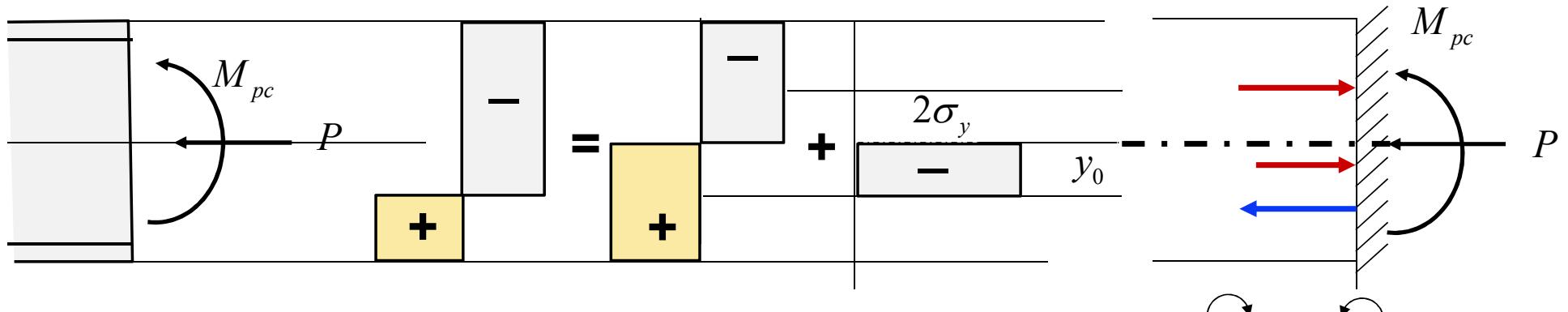


$$P = \sigma_y \times t_w \times 2y_0 \quad (P_y = \sigma_y (2bt_f + t_w d_w))$$

$$\frac{P}{\sigma_y t_w} \leq d_w$$

$$\frac{P}{P_y} \leq \frac{d_w t_w}{(2bt_f + t_w d_w)} = \frac{1}{1 + \frac{2bt_f}{t_w d_w}}$$

PNA in web



$$M_{pc} = M_p - 2\sigma_y t_w y_0 \frac{y_0}{2}$$

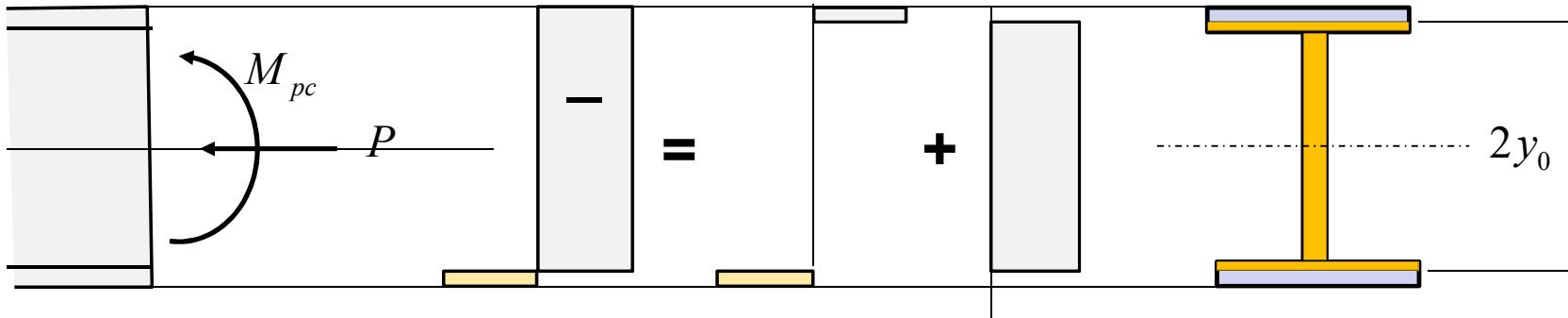
$$= \sigma_y Z - \sigma_y t_w y_0^2$$

since $y_0 = \frac{P}{2\sigma_y t_w}$

$$M_{pc} = \sigma_y \left[Z - \frac{P^2}{4\sigma_y^2 t_w} \right]$$

$$\frac{M_{pc}}{M_p} = 1 - \frac{A^2}{4t_w Z} \left(\frac{P}{P_y} \right)^2$$

PNA in flange



$$P = \sigma_y [A - b(d - 2y_0)]$$

$$M_{pc} = \sigma_y b \frac{d - 2y_0}{2} \frac{d + 2y_0}{2}$$

$$y_0 = \frac{P}{2b\sigma_y} - \frac{A}{2b} + \frac{d}{2}$$

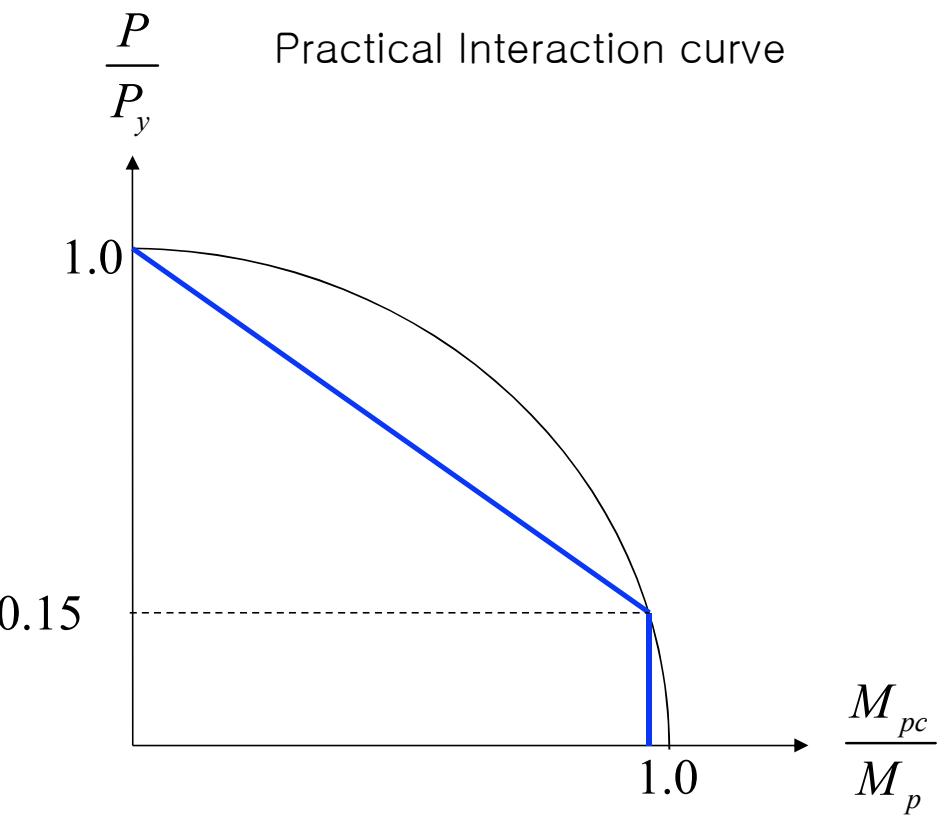
$$M_{pc} = \sigma_y b \left[\frac{1}{2} \frac{PA}{b^2 \sigma_y} + \frac{Ad}{2b} - \frac{P^2}{4b^2 \sigma_y^2} - \frac{A^2}{4b^2} - \frac{Pd}{2b\sigma_y} \right]$$

$$M_{pc} = \frac{\sigma_y}{2} \left[d \left(A - \frac{P}{\sigma_y} \right) - \frac{1}{2b} \left(A - \frac{P}{\sigma_y} \right)^2 \right]$$

Since $P_y = \sigma_y A$

$$M_p = \sigma_y Z$$

$$\frac{M_{pc}}{M_p} = \frac{Ad}{2Z} \left[\left(1 - \frac{P}{P_y} \right) - \frac{A}{2bd} \left(1 - \frac{P}{P_y} \right)^2 \right]$$

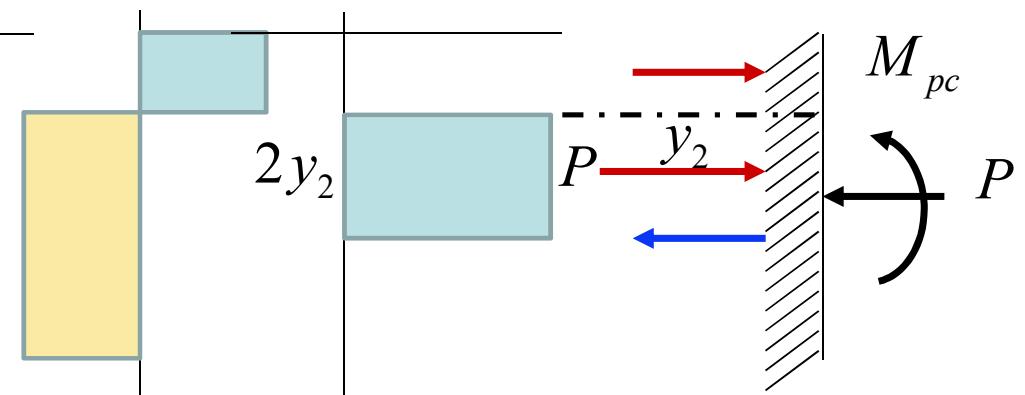
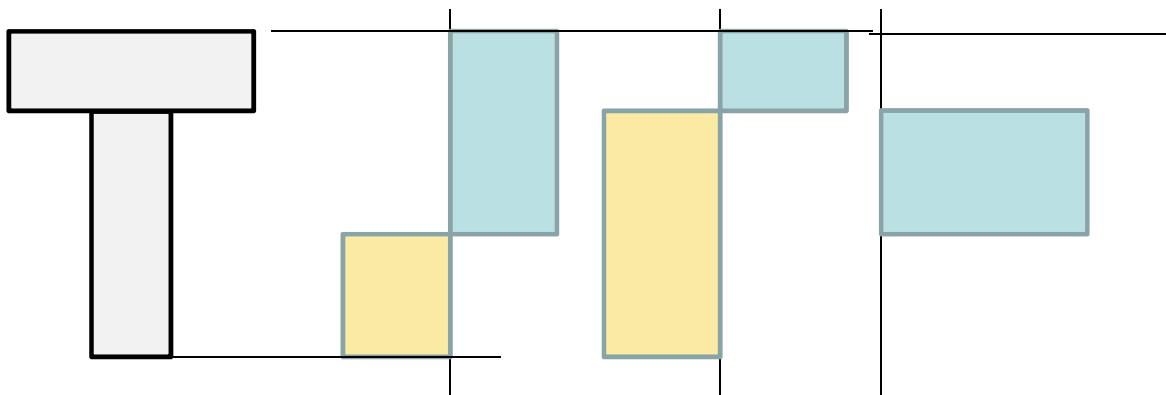
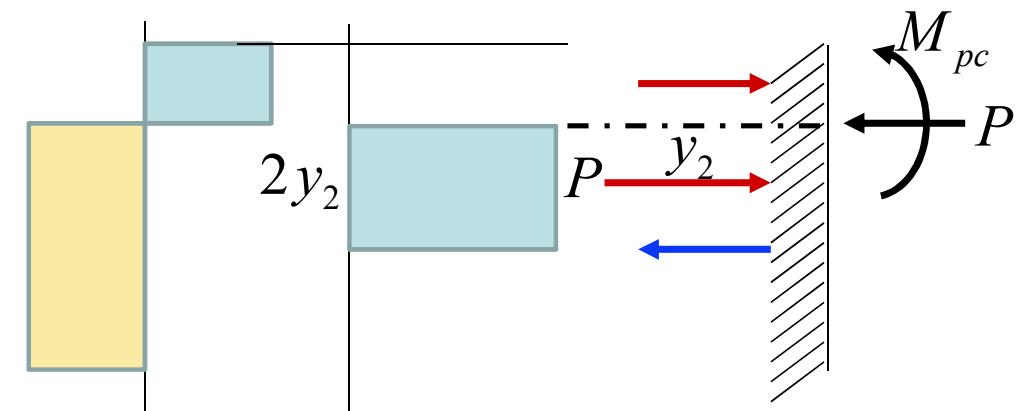
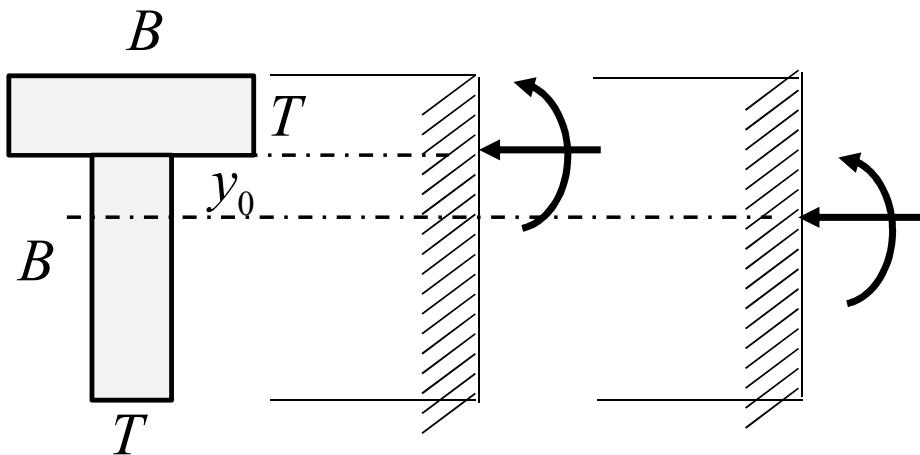


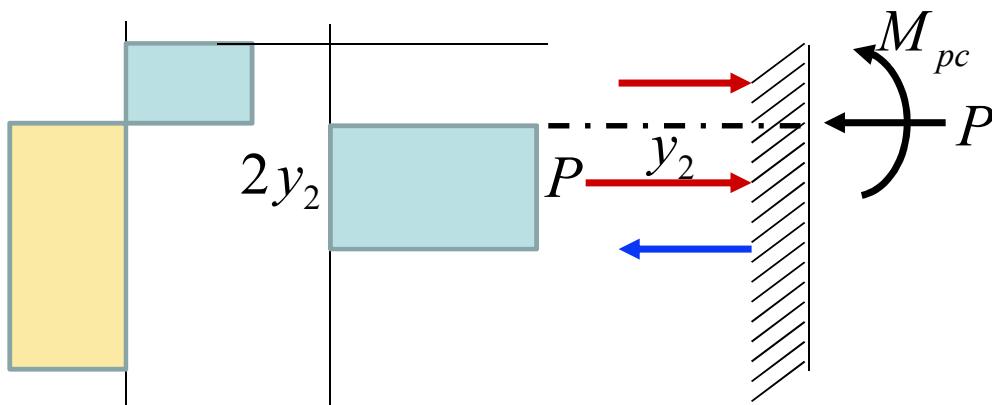
$$M_{pc} = M_p \quad \text{for } 0 \leq P \leq 0.15P_y$$

$$M_{pc} = 1.18 \left(1 - \frac{P}{P_y} \right) M_p \quad \text{for } 0.15P_y \leq P \leq P_y$$

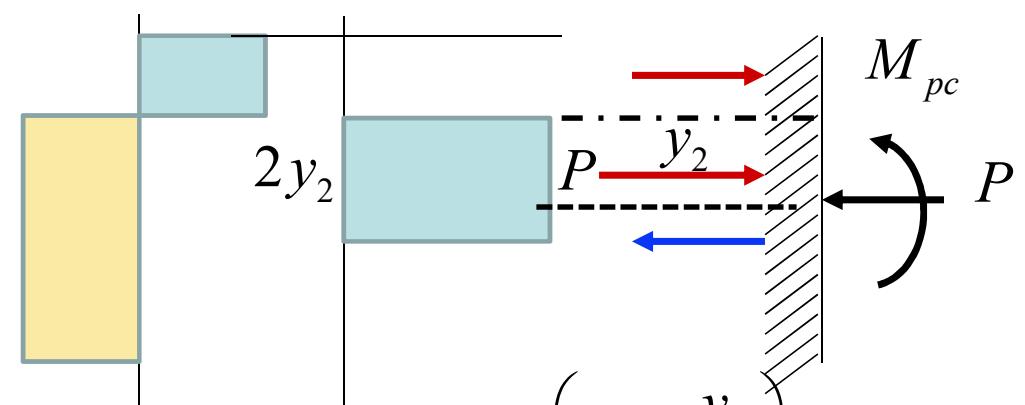
2.5.5 T-section

- 1) P thru PNA
- 2) P thru centroid





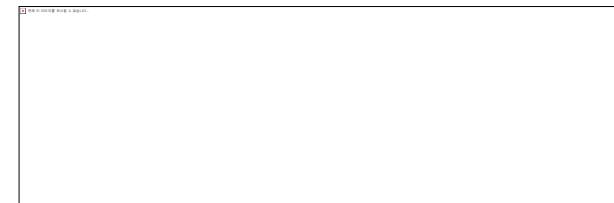
$$\begin{aligned}
 M_{pc} &= M_p - P \frac{y_2}{2} \\
 &= M_p - P \frac{P}{4\sigma_y T} \\
 &= M_p - \frac{M_p}{P_y^2} \frac{P_y^2}{M_p} \frac{P^2}{4\sigma_y T} \\
 &= M_p \left[1 - \left(\frac{P}{P_y} \right)^2 \frac{2B}{B+T} \right]
 \end{aligned}$$



$$M_{pc} = M_p + P \left(y_0 - \frac{y_2}{2} \right)$$

$$\begin{aligned}
 &= M_p - P \frac{y_2}{2} + Py_0 \\
 \text{for } & \frac{B-T}{4} \geq \frac{P}{4\sigma_y T}
 \end{aligned}$$

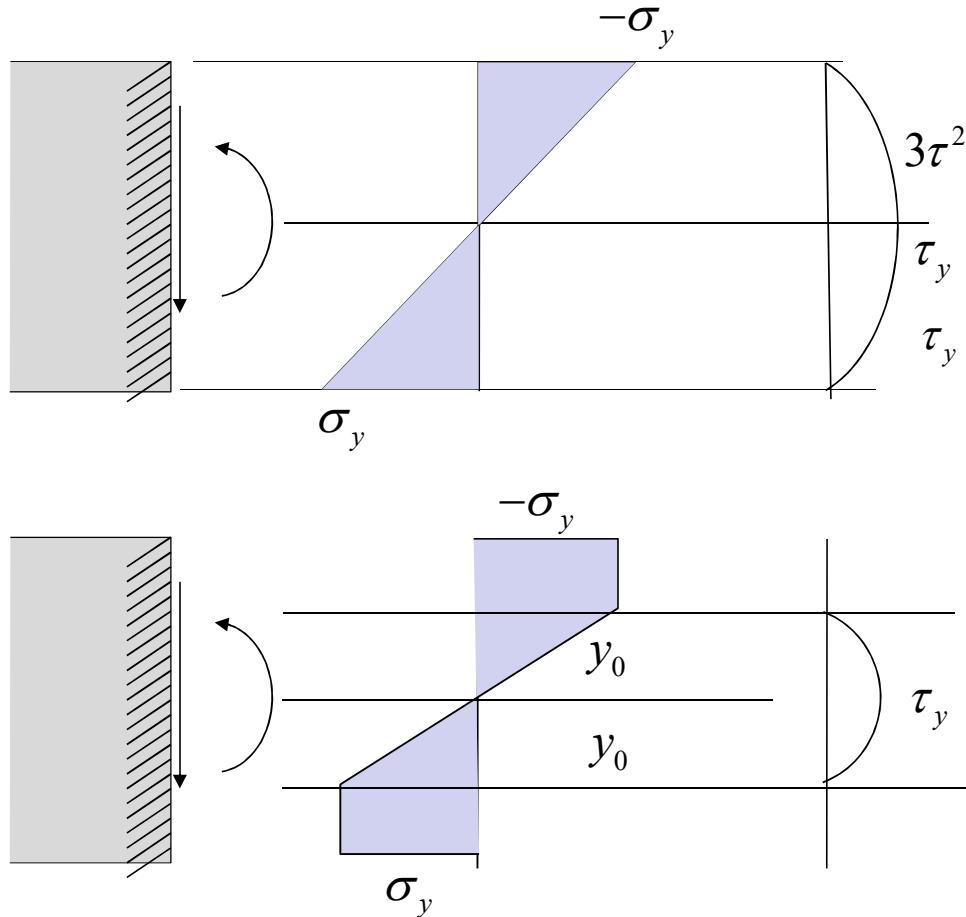
$$T(B-T)\sigma_y \geq P$$



Shear Force Effect

- Rectangular Section
- Wide Flange Section
- Effects of Combined Axial Force and Shear Force

Rectangular Sections



Von Mises yield criteria

$$\sigma^2 + 3\tau^2 \leq \sigma_y^2$$

Lower bound 1

$$\sigma = \sigma_y \frac{y}{d/2}$$

$$\tau = \frac{\sigma_y}{\sqrt{3}} \left[1 - \left(\frac{y}{d/2} \right)^2 \right]^{1/2}$$

$$M_{ps} = \int \sigma y dA = \frac{1}{6} \sigma_y b d^2 = \frac{2}{3} M_p$$

$$V = \int \tau dA = \frac{2}{3} \frac{\sigma_y}{\sqrt{3}} b d$$

Lower bound 2

$$M_{ps} = M_p \left[1 - \frac{1}{3} \left(\frac{2y_0}{d} \right)^2 \right]$$

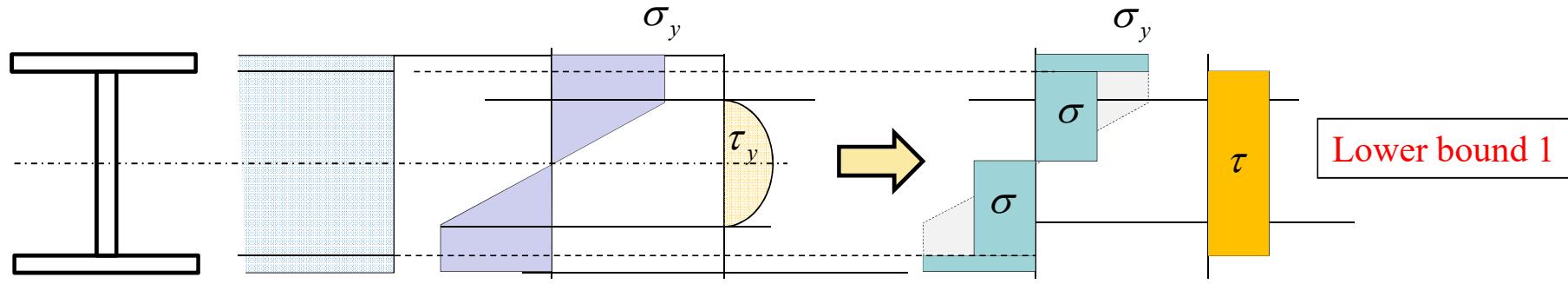
$$V = \frac{4}{3} \tau_y b y_0$$

$$\frac{M_{ps}}{M_p} = 1 - \frac{3}{4} \left(\frac{V}{V_p} \right)^2$$

where

$$V_p = \frac{\sigma_y}{\sqrt{3}} b d$$

2.6.2 Wide-flange section



$$M_{ps} = M_p - \frac{1}{3} \sigma_y y_0^2 t_w$$

$$V = \frac{4}{3} \frac{\sigma_y}{\sqrt{3}} t_w y_0$$

$$\frac{M_{ps}}{M_p} = 1 - \frac{\frac{3}{4} \left(\frac{V}{V_p} \right)}{1 + \frac{4bt_f d_f}{t_w d_w^2}}$$

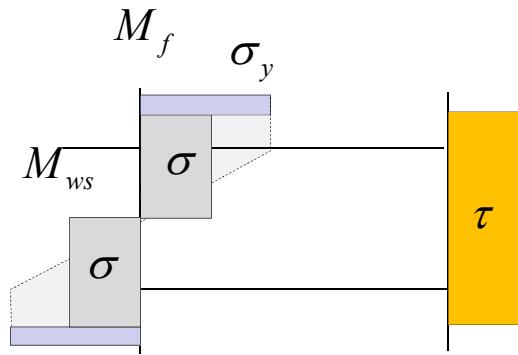
$$M_{ps} = \sigma_y b t_f + \frac{1}{4} \sigma t_w d_w^2$$

$$\tau = \frac{V}{t_w d_w}$$

$$\sigma^2 + 3\tau^2 = \sigma_y^2 \Rightarrow \frac{\sigma}{\sigma_y} = \sqrt{1 - \left(\frac{3\tau}{\sigma_y} \right)^2} = \sqrt{1 - \left(\frac{V}{V_p} \right)^2}$$

Lower bound 2

$$\frac{M_{ps}}{M_p} = \frac{1 + \frac{t_w d_w^2}{4t_f d_f^2} \sqrt{1 - \left(\frac{V}{V_p} \right)^2}}{1 + \frac{t_w d_w^2}{4t_f d_f^2}}$$



Ex 2.6.1)

$$M_{ps} = M_f + M_{ws}$$

$$M_{ws} = M_w \frac{\sigma}{\sigma_y}$$

$$M_{ps} = M_f + M_{ws} - M_{ws} + M_{ws}$$

$$= M_p - M_w \left(1 - \frac{\sigma}{\sigma_y} \right)$$

$$Z_{ps} = Z_p - Z_w \left(1 - \frac{\sigma}{\sigma_y} \right)$$

For W14×82

$$V_u = 100 \text{ kips}$$

$$Z = 139 \text{ in}^3$$

$$d_w = d - 2t_f = 12.6 \text{ in}$$

$$t_w = 0.51 \text{ in}$$

$$Z_w = t_w \frac{d_w^2}{4}$$

to find σ

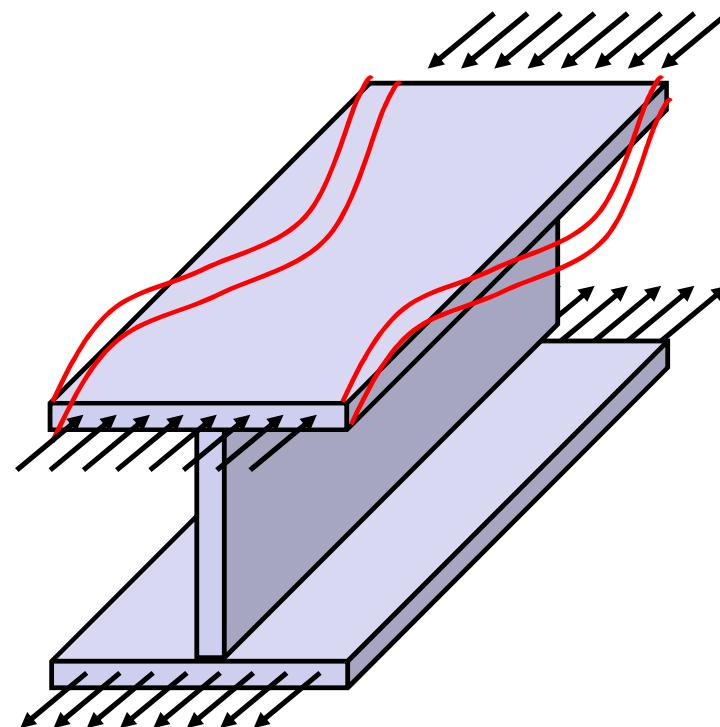
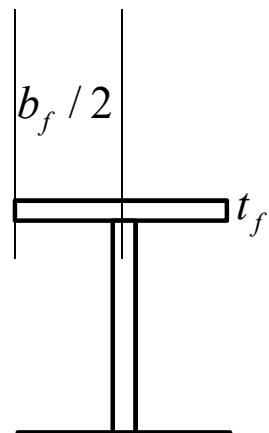
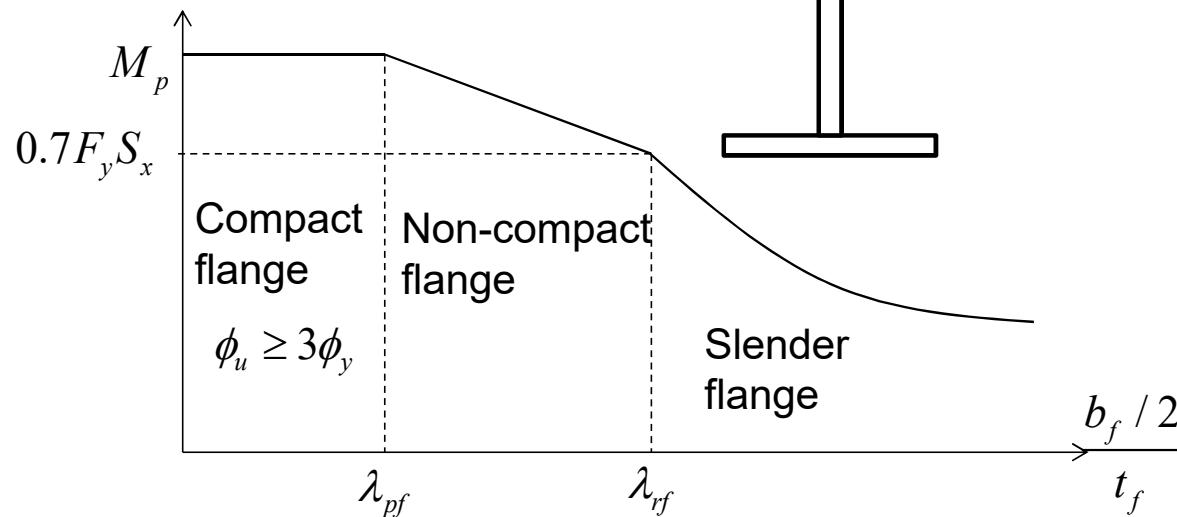
$$\tau = \frac{V}{d_w t_w} = \frac{100}{12.6 \times 0.51} = 15.56 \text{ ksi}$$

$$\sigma = \sqrt{\sigma_y^2 - 3\tau^2} = 23.81 \text{ ksi}$$

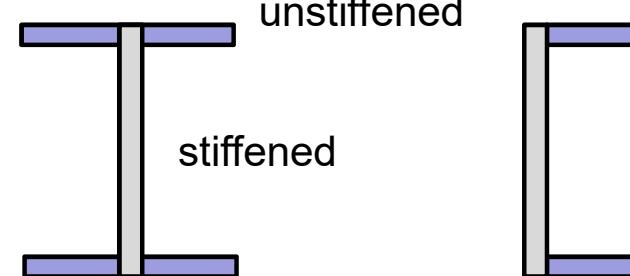
$$Z_{ps} = 139 - 20.24 \left(1 - \frac{23.87}{36} \right) = 132.18 \text{ in}^2$$

2.8 Compactness

2.8.1 LRFD

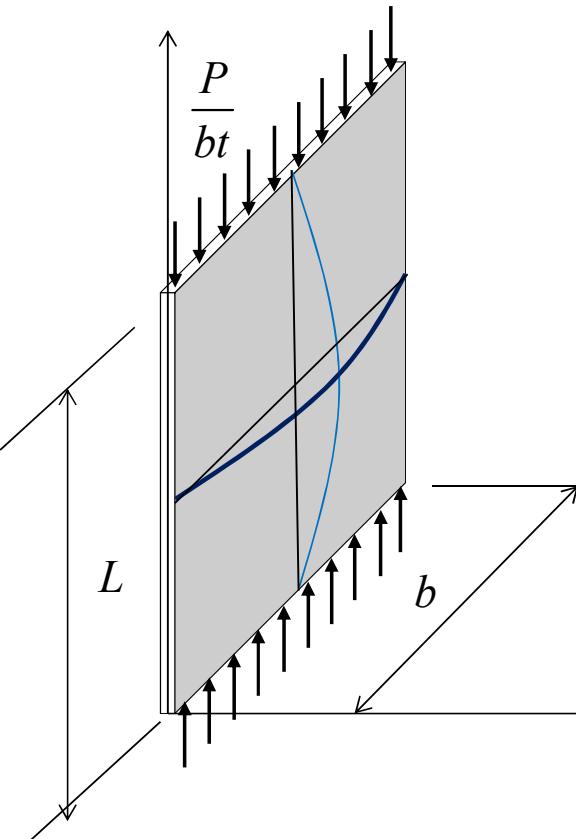


$$0.38 \sqrt{\frac{E}{F_y}} = \frac{65}{\sqrt{F_y \text{ ksi}}} \quad 1.0 \sqrt{\frac{E}{F_y}} = \frac{170}{\sqrt{F_y \text{ ksi}}}$$



$$\frac{b}{t} \leq \alpha \sqrt{\frac{k}{F_y}}$$

2.8.1 Plate Buckling



$$D \left(\frac{\partial^4 u}{\partial z^4} + 2 \frac{\partial^4 u}{\partial^2 z \partial^2 y^2} + \frac{\partial^4 u}{\partial y^4} \right) = -\frac{P}{b} \frac{\partial^2 u}{\partial z^2}$$

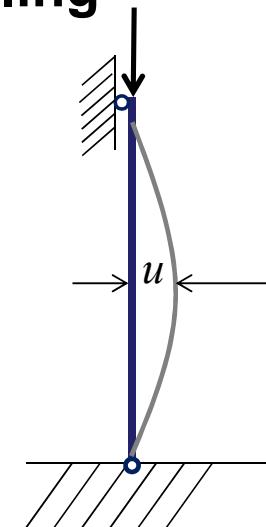
$$D = \frac{Et^3}{12(1-\nu^2)}$$

$$u = \delta \sin \frac{m\pi y}{b} \sin \frac{n\pi z}{L}$$

$$F_{01} = \frac{P_{01}}{bt}$$

$$\rightarrow F_{01} = \frac{\pi^2 E}{12(1-\nu^2)} \frac{k}{(b/t)^2}$$

Column Buckling



$$u = \delta \sin \frac{\pi z}{L}$$

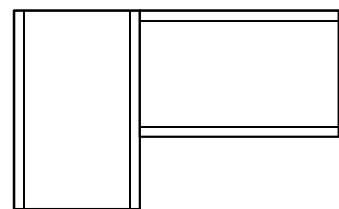
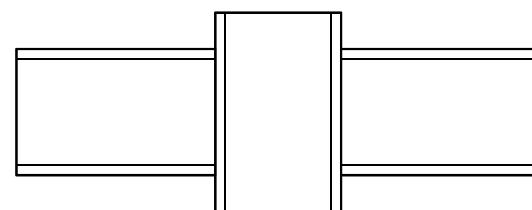
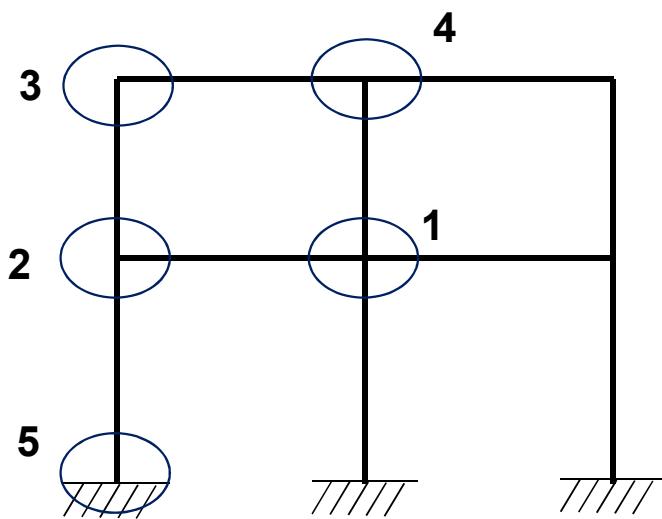
$$P_{cr} = \frac{\pi^2 EI}{L^2}$$

$$P_{cr} = \frac{\pi^2 EA}{(L/r)^2} \quad r = \sqrt{\frac{I}{A}}$$

Plate Buckling

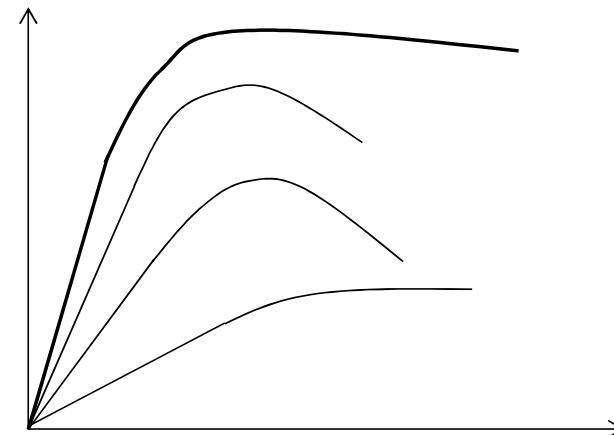
$$F_{cr} = \frac{\pi^2 E}{12(1-\nu^2)} \frac{k}{(b/t)^2}$$

2.9 Connections



Requirement for connections

1. Strength
2. Rotation capacity
3. Adequate stiffness
4. Constructability



2.9.2 Corner Connections

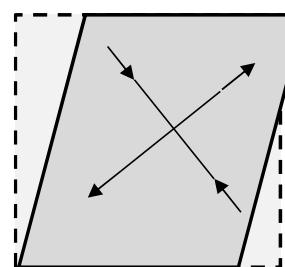
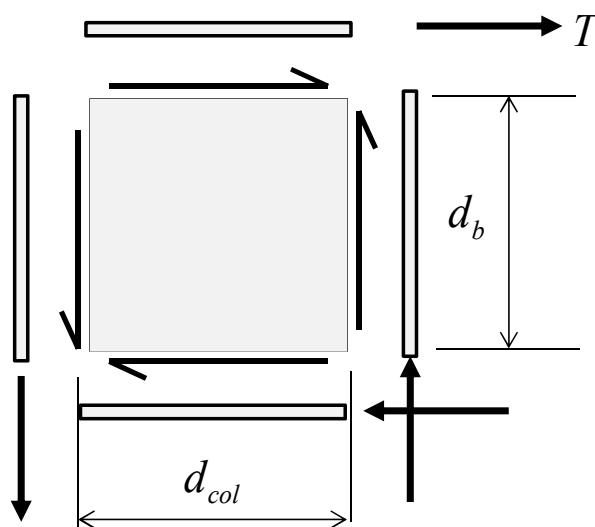
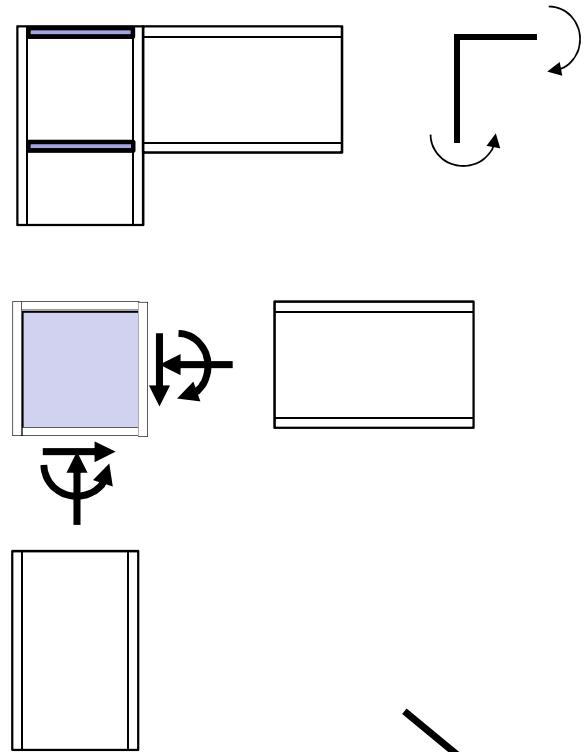
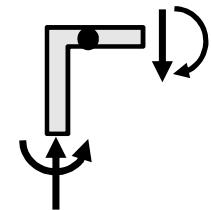
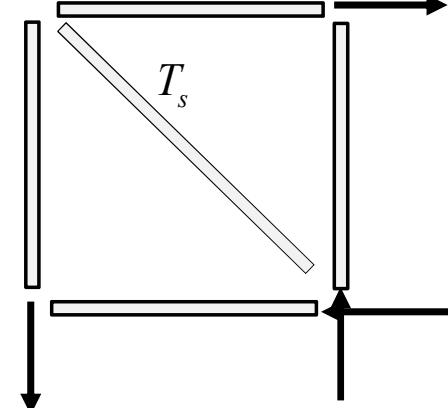
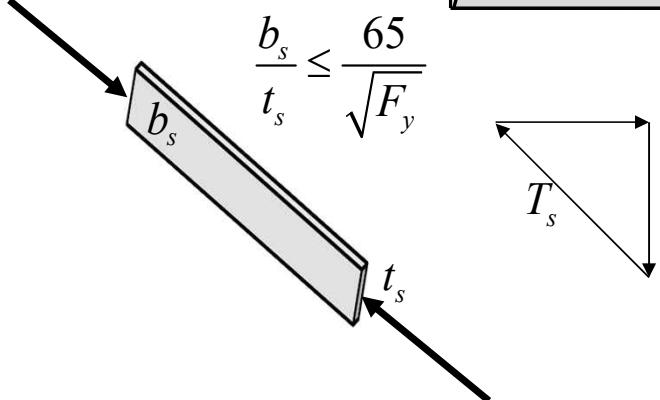


Plate buckling
by shear

$$T = \frac{M_p}{d_b}$$



Strong column and weak beam

$$T = \frac{M_p}{d_b} = \tau_{yb} t_w d_{col}$$

$$\tau_{yb} = \frac{\sigma_{yb}}{\sqrt{3}} \Rightarrow 0.6\sigma_y$$

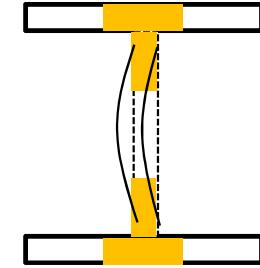
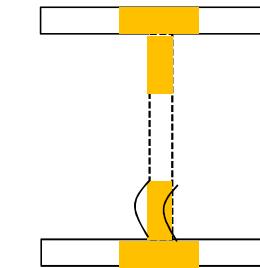
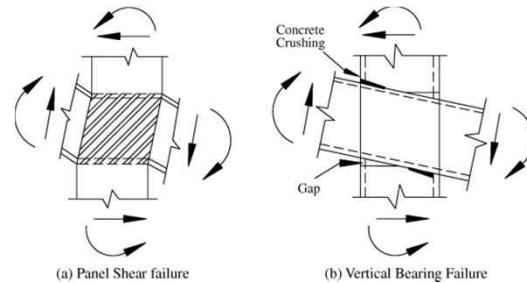
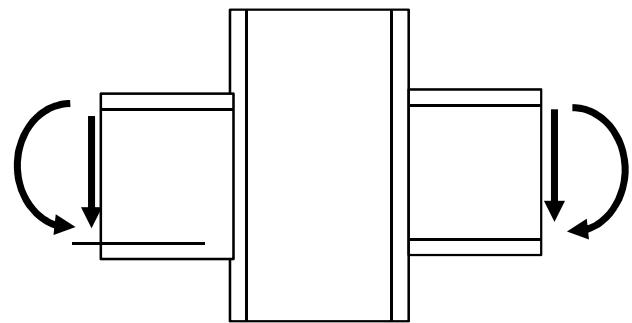
$$t_w = \frac{M_p}{\phi_v \tau_{yb} d_b d_{col}}$$

$$T_{req} \leq T_{PL} + T_s$$

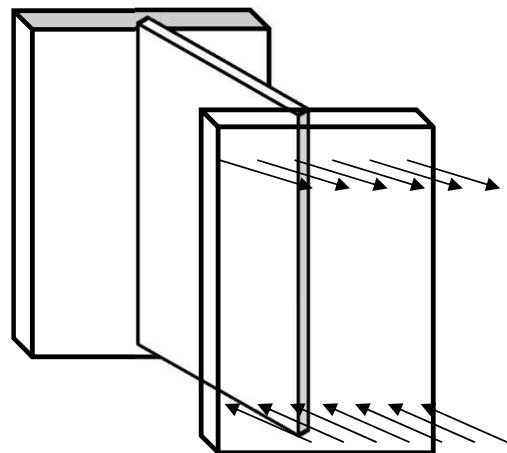
$$\frac{M_p}{d_b} \leq \phi_v \tau_{yp} t_w d_{col} + T_s \cos \theta$$

$$T_s \geq \frac{1}{\cos \theta} \left[\frac{M_p}{d_b} - \frac{\phi_v \sigma_{yp} t_w d_{col}}{\sqrt{3}} \right]$$

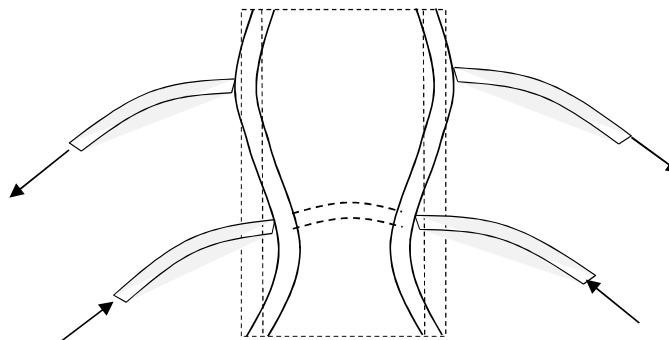
2.9.3 interior Connections



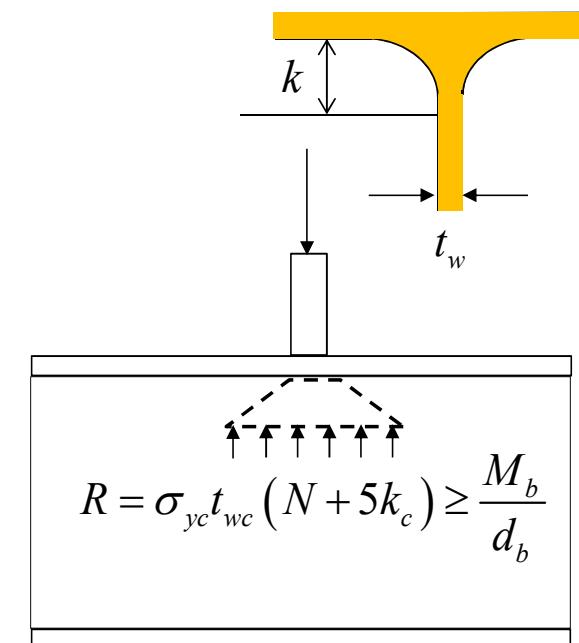
Column web yielding Column web buckling



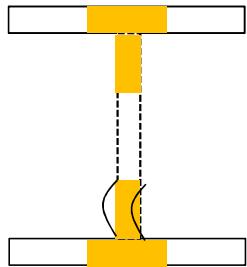
Column flange bending in tension



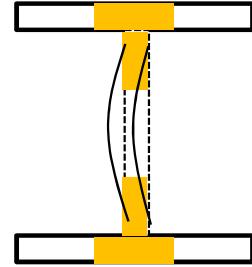
Column web yielding
Column web buckling



2.9.3 Unbalanced interior Connections

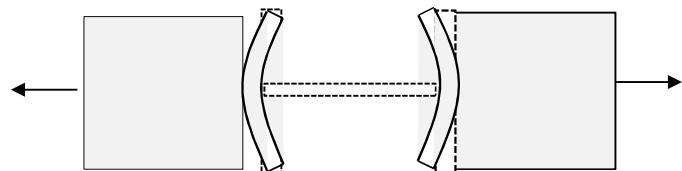


Column web yielding



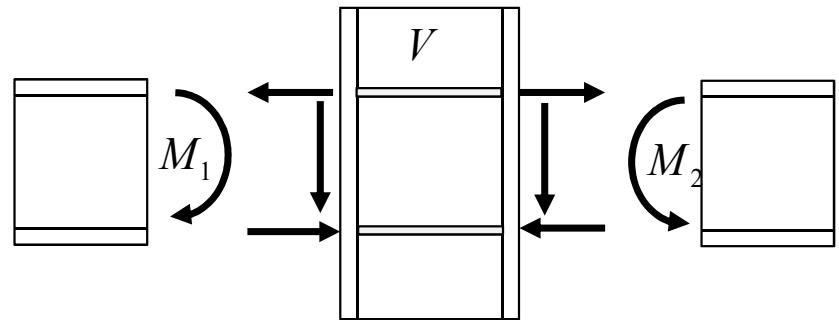
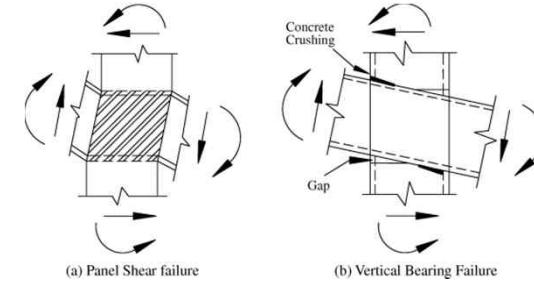
Column web buckling

$$R = \frac{4100\phi t_w^3 \sqrt{\sigma_{yc}}}{d_c}$$



Column flange bending

$$\phi R = \phi 6.25 t_{fc}^3 \sigma_{yc}$$



$$T_1 = \frac{M_1}{d_b} \quad T_2 = \frac{M_2}{d_b}$$

$$\phi_v \tau t_{wc} d_{col} = \frac{M_2}{d_{b2}} - \frac{M_1}{d_{b1}} - V$$

$$t_{wc} = \frac{1}{\phi_v \tau d_{col}} \left[\frac{M_2}{d_{b2}} - \frac{M_1}{d_{b1}} - V \right]$$