

Chapter 18. Calculus of Variation and Dynamic Programming

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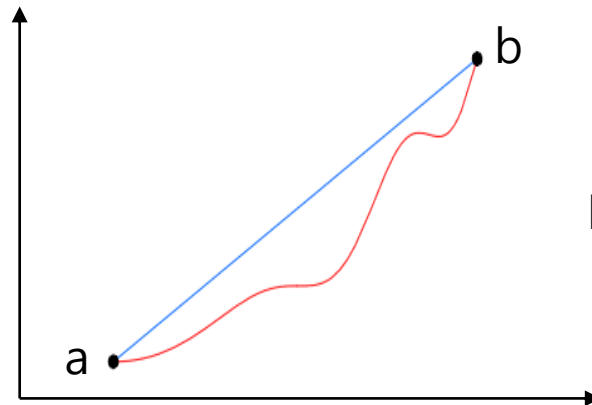


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Chapter 18. Calculus of variation and dynamic programming

18.1 The relationship between calculus of variations and dynamic programming

- Dynamic programming method applies to problems seeking an **optimal function**, rather than an optimal point.
- Calculus of variation (COV) and dynamic programming (DP) are companion methods since both are techniques to determine the optimal function $y(x)$.
- A difference between COV and DP is that DP breaks the function into discrete stages, while COV treats it as a continuous function.



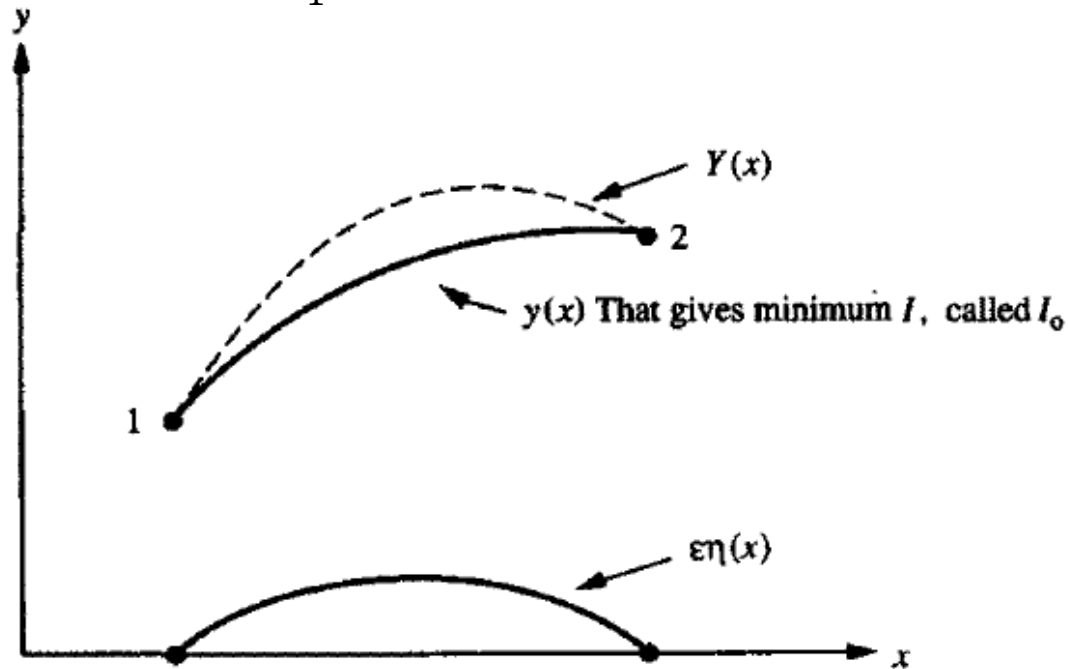
For minimum $\int_a^b F(x)dx$

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18.2 The Euler-Lagrange equation

- The Euler-Lagrange (E-L) equation is a basic tool in the calculus of variation (COV)

$$I = \int_{x_1}^{x_2} F(x, y, y') dx \quad y = y(x)$$



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18.2 The Euler-Lagrange equation

Suppose

1. $y(x)$ is a solution

2. $\eta(x)$ is a test function with $\eta(x_1) = \eta(x_2) = 0$, ε is a numerical value

$$Y(x) = y(x) + \varepsilon\eta(x)$$

3. $\eta(x)$ is a test function, ε is a numerical value

$$I(\varepsilon) = \int_{x_1}^{x_2} F(x, y + \varepsilon\eta, y' + \varepsilon\eta') dx = \int_{x_1}^{x_2} F(x, Y, Y') dx$$

4. $I(\varepsilon)$ can be expressed as a Taylor series expansion of ε

$$I(\varepsilon) = I_o + \left[\frac{\partial I(\varepsilon)}{\partial \varepsilon} \right]_{\varepsilon=0} \varepsilon + \frac{1}{2} \left[\frac{\partial^2 I(\varepsilon)}{\partial \varepsilon^2} \right]_{\varepsilon=0} \varepsilon^2 + \dots \quad I_o: \text{optimal of } I$$

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18.2 The Euler-Lagrange equation

5. Verify the existence of an optimal point,

$$\left. \frac{\partial I(\varepsilon)}{\partial \varepsilon} \right|_{\varepsilon=0} = \left[\frac{\partial}{\partial \varepsilon} \int_{x_1}^{x_2} F(x, Y, Y') dx \right]_{\varepsilon=0} = 0$$

6. Applied the chain rule, $\frac{\partial x}{\partial \varepsilon} = 0$, $\frac{\partial Y}{\partial \varepsilon} = \eta$, $\frac{\partial Y'}{\partial \varepsilon} = \eta'$

$$\begin{aligned} & \left[\int_{x_1}^{x_2} \left(\frac{\partial F}{\partial x} \frac{\partial x}{\partial \varepsilon} + \frac{\partial F}{\partial Y} \frac{\partial Y}{\partial \varepsilon} + \frac{\partial F}{\partial Y'} \frac{\partial Y'}{\partial \varepsilon} \right) dx \right]_{\varepsilon=0} = \left[\int_{x_1}^{x_2} \left(\frac{\partial F}{\partial Y} \eta + \frac{\partial F}{\partial Y'} \eta' \right) dx \right]_{\varepsilon=0} \\ & = \int_{x_1}^{x_2} \frac{\partial F}{\partial y} \eta dx + \int_{x_1}^{x_2} \frac{\partial F}{\partial y'} \eta' dx = 0 \\ & \quad \swarrow \quad \quad \quad \searrow \quad \quad \quad \begin{aligned} \int_{x_1}^{x_2} \frac{\partial F}{\partial y'} \eta' dx &= \frac{\partial F}{\partial y} [\cancel{\eta(x_2)} - \cancel{\eta(x_1)}] - \int_{x_1}^{x_2} \frac{d(\partial F / \partial y')}{dx} \eta(x) dx \\ & \quad \quad \quad \begin{matrix} 0 & 0 \end{matrix} \end{aligned} \\ & = \int_{x_1}^{x_2} \left[\frac{\partial F}{\partial y} - \frac{d(\partial F / \partial y')}{dx} \right] \eta(x) dx = 0 \end{aligned}$$

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18.2 The Euler-Lagrange equation

7. $\eta(x)$ can be arbitrary, so the integral is always zero

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0 \quad \boxed{\text{Euler-Lagrange equation}}$$

8. The E-L equation general form,

$$\frac{\partial F}{\partial y} - \frac{\partial(\partial F / \partial y')}{\partial x} \frac{dx}{dx} - \frac{\partial(\partial F / \partial y')}{\partial y'} \frac{dy'}{dx} - \frac{\partial(\partial F / \partial y')}{\partial y} \frac{dy}{dx} = 0$$

$$F_y - F_{xy} - F_{y'y'} y'' - F_{yy'} y' = 0$$

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Example 18.1

- Determine the equation for m' as a function of time t such that **minimum pumping energy** is required during the process

(Given)

- time, $t : 0 \rightarrow 120$ s, vessel pressure $p : 100 \rightarrow 190$ kPa, liquid mass $m : 0 \rightarrow 180$ kg
- Laminar flow, $p_1 - p_2 = 15m'$, vessel pressure $p_2 = 100 + 0.5m$
- Pumping power $m'_p(p_1 - 100)$, back leakage $m' = m'_p - 0.2(p_1 - 100)$

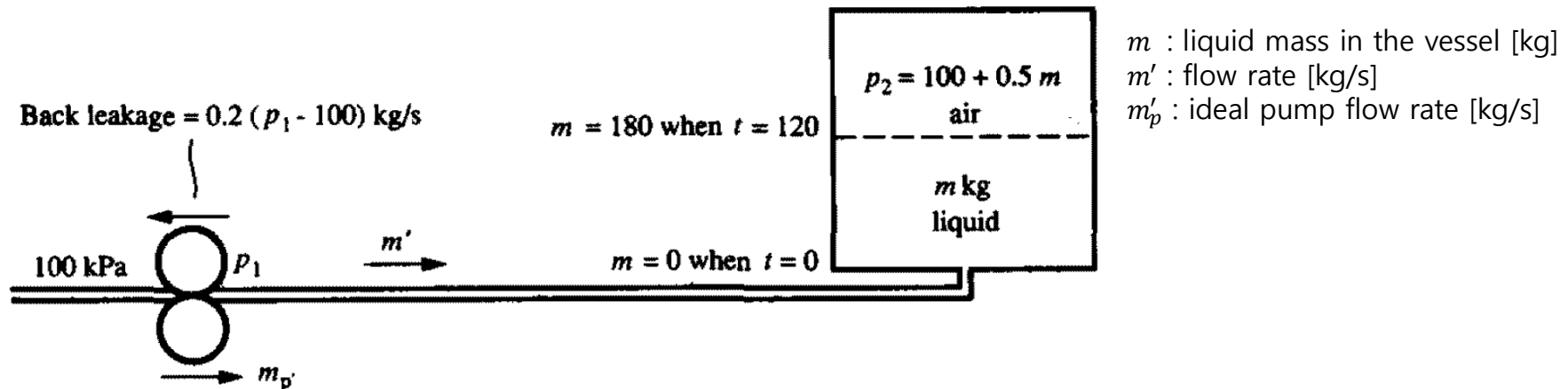


Fig. Pump delivering hydraulic fluid through a long pipe to build up pressure in a vessel.

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Example 18.1

(Solution)

- The integral to minimize

$$\begin{aligned}
 I &= \int_0^{120} m'_p(p_1 - 100)dt = \int_0^{120} [m' + 0.2(p_1 - 100)](p_1 - 100)dt \\
 &\quad \swarrow \quad \quad \quad \nwarrow \\
 &\quad \quad \quad p_1 - 100 = 15m' + p_2 - 100 = 15m' + 0.5m \\
 &= \int_0^{120} [3.5mm' + 60(m')^2 + 0.05m^2]dt
 \end{aligned}$$

- Subjecting F to the E-L equation of the form in Eq. (18.14)

$$m'' - 0.0008333m = 0$$

$$F_y - F_{xy} - F_{y'y'}y'' - F_{yy'}y' = 0$$

$$m = C_1 \sinh \sqrt{0.0008333} t + C_2 \cosh 0.02887t$$

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Example 18.1

(Solution)

- The boundary condition, $m(0) = 0$ required that $C_2 = 0$, so,

$$m = C_1 \sinh \sqrt{0.02887} t$$

- The second boundary condition, $m(120) = 180 \rightarrow C_1 = 180 / \sinh 3.464 = 11.28$

$$m = 11.28 \sinh(0.02887t)$$

$$m' = 0.3257 \cosh(0.02887t)$$

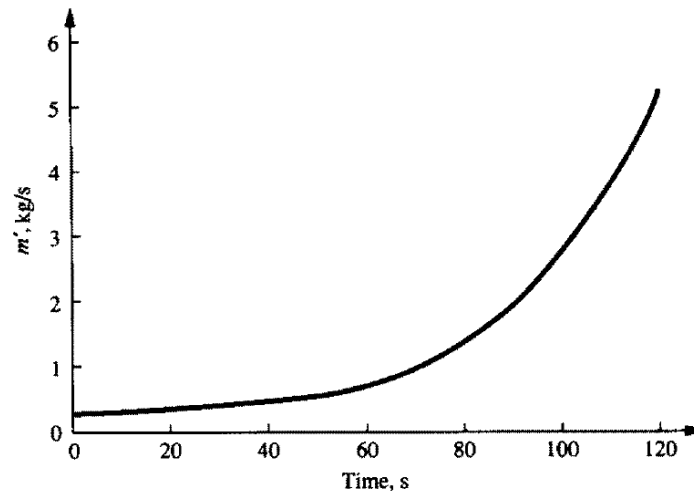


Fig. Optimal plan for flow rate to build up pressure

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18.3 The Euler-Lagrange equation to optimize a constrained function

- The constrained problem is find y that minimizes I and J

$$I = \int_{x_1}^{x_2} F(x, y, y') dx, \quad J = \int_{x_1}^{x_2} G(x, y, y') dx \quad (J \text{ is a constant})$$

- The E-L equation for the constrained case will be shown to be

$$\frac{\partial(F - \lambda G)}{\partial x} - \frac{d}{dx} \left[\frac{\partial(F - \lambda G)}{\partial y'} \right] = 0$$

- Test function $y(x)$ as the one that minimizes I and J

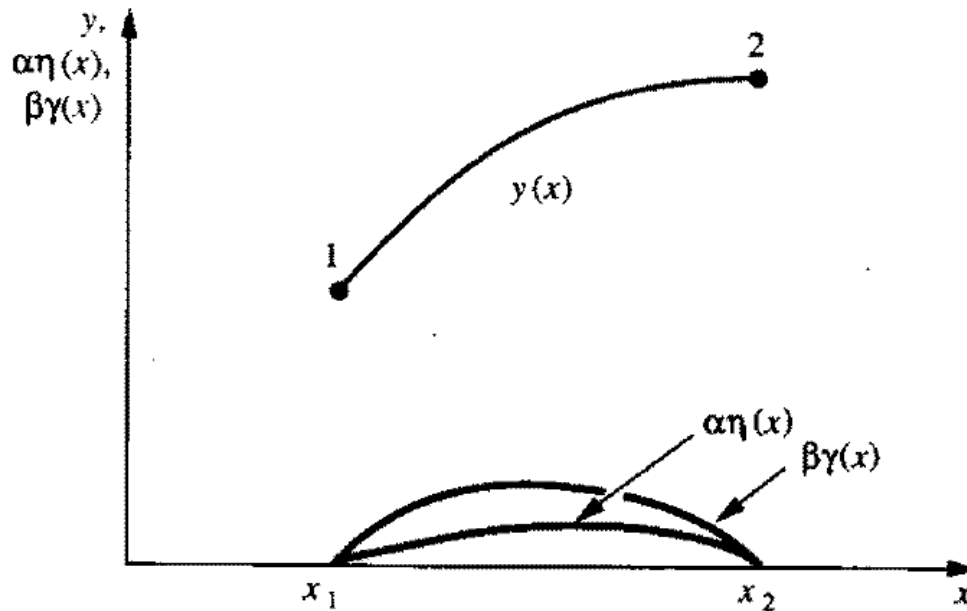
$$Y(x) = y(x) + \alpha \eta(x) + \beta \gamma(x) \quad (\alpha, \beta \text{ are constants})$$

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18.3 The Euler-Lagrange equation to optimize a constrained function

- Replace y and y' to the revised function Y and Y'

$$I = \int_{x_1}^{x_2} F(x, Y, Y') dx, \quad K = \int_{x_1}^{x_2} G(x, Y, Y') dx$$



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18.3 The Euler-Lagrange equation to optimize a constrained function

- Express I and K in Talyor series of α and β

$$I(\alpha, \beta) = I(0,0) + \alpha \left. \frac{\partial I}{\partial \alpha} \right|_{\alpha, \beta=0} + \beta \left. \frac{\partial I}{\partial \beta} \right|_{\alpha, \beta=0} + \dots$$

$$K(\alpha, \beta) = K(0,0) + \alpha \left. \frac{\partial K}{\partial \alpha} \right|_{\alpha, \beta=0} + \beta \left. \frac{\partial K}{\partial \beta} \right|_{\alpha, \beta=0} + \dots$$

- $I(0,0) = \int_{x_1}^{x_2} y(x)dx$, $K(0,0) = J$

- In order for $I(\alpha, \beta)$ and $K(\alpha, \beta)$ to be a minimum the first-degree terms

$$\left. \frac{\partial I}{\partial \alpha} \right|_{\alpha, \beta=0} \alpha + \left. \frac{\partial I}{\partial \beta} \right|_{\alpha, \beta=0} \beta = 0 \qquad \left. \frac{\partial K}{\partial \alpha} \right|_{\alpha, \beta=0} \alpha + \left. \frac{\partial K}{\partial \beta} \right|_{\alpha, \beta=0} \beta = 0$$

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18.3 The Euler-Lagrange equation to optimize a constrained function

- Combining the equations

$$\left. \begin{array}{l} \frac{\partial I}{\partial \alpha} \Big|_{\alpha, \beta=0} \alpha + \frac{\partial I}{\partial \beta} \Big|_{\alpha, \beta=0} \beta = 0 \\ \frac{\partial K}{\partial \alpha} \Big|_{\alpha, \beta=0} \alpha + \frac{\partial K}{\partial \beta} \Big|_{\alpha, \beta=0} \beta = 0 \end{array} \right\} -\frac{\beta}{\alpha} = \frac{\partial I / \partial \alpha}{\partial I / \partial \beta} = \frac{\partial K / \partial \alpha}{\partial K / \partial \beta} \rightarrow \frac{\partial I / \partial \alpha}{\partial K / \partial \alpha} = \lambda = \frac{\partial I / \partial \beta}{\partial K / \partial \beta}$$

- Rewritten the equations

$$\frac{\partial}{\partial \alpha} [I - \lambda K] = \frac{\partial}{\partial \alpha} \left[\int_{x_1}^{x_2} F(x, Y, Y') dx - \lambda \int_{x_1}^{x_2} G(x, Y, Y') dx \right] = 0$$

$$\frac{\partial}{\partial \beta} [I - \lambda K] = \frac{\partial}{\partial \beta} \left[\int_{x_1}^{x_2} F(x, Y, Y') dx - \lambda \int_{x_1}^{x_2} G(x, Y, Y') dx \right] = 0$$

- The E-L equation for a constrained function

$$\frac{\partial(F - \lambda G)}{\partial x} - \frac{d}{dx} \left[\frac{\partial(F - \lambda G)}{\partial y'} \right] = 0$$

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Example 18.2

- Calculate the pump power by solving the constrained problem

(Given)

- 40 m³ tank is to be completely pumped in 1200 second
- The pressure difference : $\Delta p = (360 + 6t)V'$
- The mean pressure difference : $\frac{1}{1200} \int_0^{1200} \Delta p dt = 210 \text{ [kPa]}$

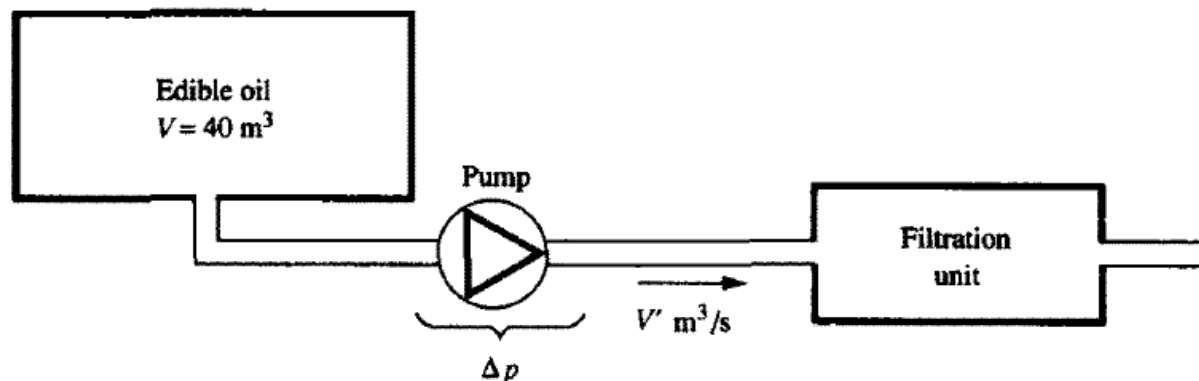


Fig. Pumping edible oil from a tank through a filter

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Example 18.2

(Solution)

- Pump power $\Delta p V'$ [kW] is to be minimized

$$\int_0^{1200} (3600 + 6t)(V')^2 dt = 252,000 \quad \left\{ \begin{array}{l} F = (3600 + 6t)(V')^2 \\ G = (3600 + 6t)V' \end{array} \right.$$

- Solve for the minimum energy function **without** the constraint

$$\left\{ \begin{array}{ll} V = 36.41 \ln(3600 + 6t) - 298.15 [\text{m}^3] \\ V' = 218.46 / (3600 + 6t) & [\text{m}^3/\text{s}] \\ \Delta p = 218.46 & [\text{kPa}] \end{array} \right.$$

$$\therefore \Delta p V' = 8738 \quad [\text{kJ}]$$

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Example 18.2

(Solution)

- Solve for the minimum energy function **with** the constraint

$$F - \lambda G = (3600 + 6t)[(V')^2 - \lambda V'] , \quad \frac{\partial(F - \lambda G)}{\partial V'} = (3600 + 6t)[2V' - \lambda] = \text{constant}$$

$$\frac{dV}{dt} = \frac{C_1}{3600 + 6t} + \frac{\lambda}{2} \quad \xrightarrow{\text{integrating}} \quad V - C_2 \ln(3600 + 6t) + \frac{\lambda}{2}t + C_3 = 0$$

- Boundary condition; $(V, t)_{\text{initial}} = (0, 0), (V, t)_{\text{final}} = (40, 120)$

$$\therefore \begin{cases} C_2 = 36.41 - 546.1\lambda \\ C_3 = 4472\lambda - 298.2 \\ \lambda = -0.02616 \end{cases} \quad \begin{cases} V = 50.7 \ln(3600 + 6t) - 0.01308t - 415.2 \\ V' = 304.2 \ln(3600 + 6t) - 0.01308 \\ \Delta p = 257.1 - 0.07848t \end{cases}$$

$$\therefore \Delta p V' = 8872 \quad [\text{kJ}]$$

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Example 18.2

(Solution)

- Value of λ represents the sensitivity coefficient

$$\lambda = \frac{(p_{ave} - 218.46)}{323.4}$$

$$\lambda_{p_{ave}=210} = -0.02616$$

$$\lambda_{p_{ave}=214.23} = -0.01308$$

$$\lambda_{p_{ave}=218.46} = 0$$

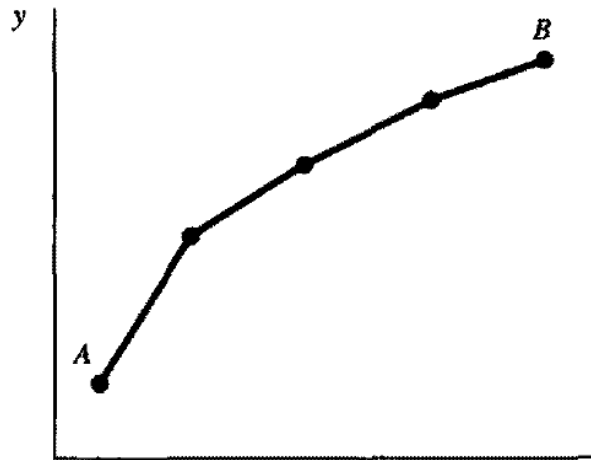
- The mean value of λ by the difference in p_{ave} ,

$$(\lambda_{p_{ave}=214.23}) \times (218.46 - 210) = 133$$

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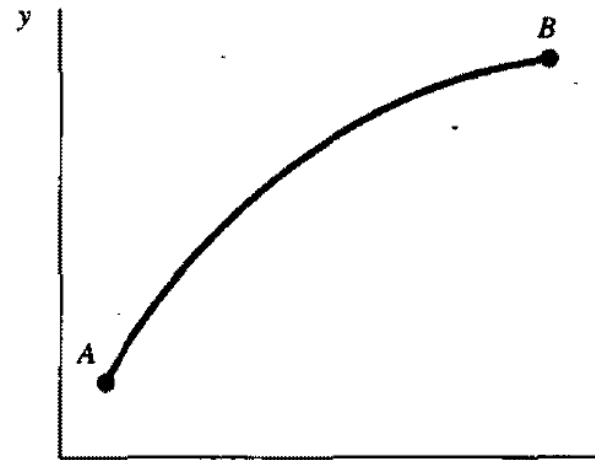
18.4 Dynamic programming and calculus of variations

- Calculus of variation(COV) develops an equation for the function that is continuous with continuous derivatives. COV is more representative of the physical problem.
- If the physical situation is one of discrete stages, dynamic programming(DP) is more accurate and COV is an approximation.



$$\text{Optimize } \sum_{i=1}^4 F_i(y, y', x)$$

Fig. (a) Dynamic programming



$$\text{Optimize } \int_A^B F_i(y, y', x) dx$$

(b) calculus of variation

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18.5 Stage operation with recycle

- The objective is to maximize the summation

$$\sum_{n=1}^N r_n$$

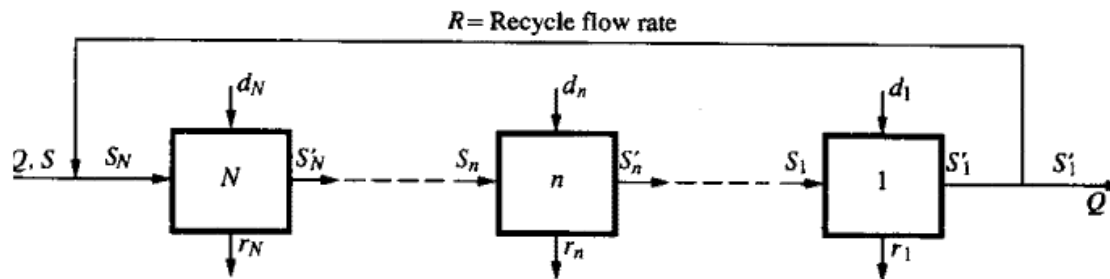


Fig. Recycle stream in a staged process

Known values;
 S : concentration
 Q : entering flow rate
 R : recycle rate

Assume values;
 S_n and S'_1

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18.6 Dynamic programming for constrained optimizations

- The value of λ represents the sensitivity coefficient
- The DP process will be conducted with internal choices made to hold a constant value of λ through the successive tables.

Example 18.3 : Solve example 18.2 by treating it as a 4-stage DP

(Given)

- Each stage consisting of 300 s of pumping operation

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Example 18.3

Table Pumping energy is a stage

Volume at start	Volume at end															
	15.8	16.2	16.6	17.0	17.4	26.4	26.8	27.2	27.6	28.0	33.8	34.2	34.6	35.0	35.4	40.0
0.0	3694.1	3883.5	4077.7	4276.6	4480.2											
15.8						2343.4	2523.6	2710.5	2904.0	3104.3						
16.2						2169.9	2343.4	2523.6	2710.5	2904.0						
16.6						2003.0	2169.9	2343.4	2523.6	2710.5						
17.0						1842.9	2003.0	2169.9	2343.4	2523.6						
17.4						1689.4	1842.9	2003.0	2169.9	2343.4						
26.4											1472.4	1635.9	1808.0	1988.7	2178.0	
26.8											1317.5	1472.4	1635.9	1808.0	1988.7	
27.2											1171.3	1317.5	1472.4	1635.9	1808.0	
27.6											1033.6	1171.3	1317.5	1472.4	1635.9	
28.0											904.5	1033.6	1171.3	1317.5	1472.4	
33.8																1265.0
34.2																1107.0
34.6																959.6
35.0																822.7
35.4																696.3

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Example 18.3

Table Δp contribution in a stage

Volume at start	Volume at end															
	15.8	16.2	16.6	17.0	17.4	26.4	26.8	27.2	27.6	28.0	33.8	34.2	34.6	35.0	35.4	40.0
0.0	70142	71917	73693	75469	77245											
15.8						66323	68826	71329	73831	76334						
16.2						63821	66323	68826	71329	73831						
16.6						61318	63821	66323	68826	71329						
17.0						58815	61318	63821	66323	68826						
17.4						56312	58815	61318	63821	66323						
26.4											59693	62919	66146	69372	72599	
26.8											56466	59693	62919	66146	69372	
27.2											53239	56466	59693	62919	66146	
27.6											50013	53239	56466	59693	62919	
28.0											46786	50013	53239	56466	59693	
33.8																61211
34.2																57261
34.6																53312
35.0																49363
35.4																45414

Example 18.3 **Table** Cumulative energy and Δp from 600 to 1200 s

V at 600s	V at 900s	Cumulative energy					Cumulative Δp					λ
26.4	33.8	1265.0	+	1472.4	=	2737.4	61211	+	59693	=	120,904	] -0.008
	34.2	1107.0	+	1635.9	=	2742.9	57261	+	62919	=	120,180	
	34.6	959.6	+	1808.0	=	2767.6	53312	+	66146	=	119,458	] -0.034
	35.0	822.7	+	1988.7	=	2811.4	49363	+	69372	=	118,735	] -0.061
	35.4	696.3	+	2178.0	=	2874.3	45414	+	72599	=	118,013	] -0.087
26.8	33.8	1265.0	+	1317.5	=	2582.5	61211	+	56466	=	117,677	] 0.0043
	34.2	1107.0	+	1472.4	=	2579.4	57261	+	59693	=	116,954	
	34.6	959.6	+	1635.9	=	2595.5	53312	+	62919	=	116,231	] -0.022
	35.0	822.7	+	1808	=	2630.7	49363	+	66146	=	115,509	] -0.049
	35.4	696.3	+	1988.7	=	2685.0	45414	+	69372	=	114,786	] -0.075
27.2	33.8	1265.0	+	1171.3	=	2436.3	61211	+	53239	=	114,450	] 0.0163
	34.2	1107.0	+	1317.5	=	2424.5	57261	+	56466	=	113,727	
	34.6	959.6	+	1472.4	=	2432.0	53312	+	59693	=	113,005	] -0.01
	35.0	822.7	+	1635.9	=	2458.6	49363	+	62919	=	112,282	] -0.037
	35.4	696.3	+	1808	=	2504.3	45414	+	66146	=	111,560	] -0.063
27.6	33.8	1265.0	+	1033.6	=	2298.6	61211	+	50013	=	111,224	] 0.0281
	34.2	1107.0	+	1171.3	=	2278.3	57261	+	53239	=	110,500	
	34.6	959.6	+	1317.5	=	2277.1	53312	+	56466	=	109,778	] 0.0017
	35.0	822.7	+	1472.4	=	2295.1	49363	+	59693	=	109,056	] -0.025
	35.4	696.3	+	1635.9	=	2332.2	45414	+	62919	=	108,333	] -0.051
28.0	33.8	1265.0	+	904.5	=	2169.5	61211	+	46786	=	107,997	] 0.04
	34.2	1107.0	+	1033.6	=	2140.6	57261	+	50013	=	107,274	
	34.6	959.6	+	1171.3	=	2130.9	53312	+	53239	=	106,551	] 0.0134
	35.0	822.7	+	1317.5	=	2140.2	49363	+	56466	=	105,829	] -0.013
	35.4	696.3	+	1472.4	=	2168.7	45414	+	59693	=	105,107	] -0.039

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Example 18.3

Table Optimal pumping plan

Time stage, s	Volumes in/leaving	Contribution to energy, kJ	Contribution to Δp
0 to 300	0/17.0	4,276.6	75,469
300 to 600	17.0/27.2	2,169.9	63,820
600 to 900	27.2/34.6	1,472.4	59,692
900 to 1200	34.6/40.0	959.6	53,312
Total:		8,878.5	252,293