

457.646 Topics in Structural Reliability
In-Class Material: Class 20

“ ” (cf.)

V. Structural Reliability under Model & Stastical Uncertainties

(Ref.: “Analysis of Structural Reliability under Model and Statistical Uncertainties: A Bayesian Approach” ~ eTL)

◎ Formulation of Reliability Problems under Epistemic Uncertainties

- ① Reliability Problem with Aleatoric uncertainties (only)

$$P_f = \int f_x(\mathbf{x})d\mathbf{x} \quad \mathbf{x}: \text{r.v.'s representing aleatoric uncertainties in the problem}$$

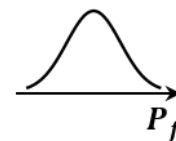
→ Use component and/or system reliability method

- ② Reliability Problem under Aleatoric & Epistemic certainties

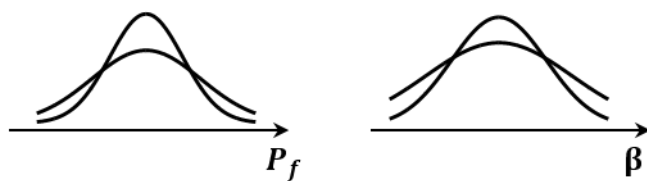
$$P_f(\boldsymbol{\theta}) = \int_{\cup \cap g(\mathbf{x}; \boldsymbol{\theta}) \leq 0} f_x(\mathbf{x}; \boldsymbol{\theta})d\mathbf{x} \Rightarrow \beta(\boldsymbol{\theta}) = \Phi^{-1}[\quad]$$

$$\boldsymbol{\theta} = [\boldsymbol{\theta}_f \quad \boldsymbol{\theta}_g]$$

uncertain parameters



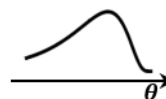
⇒ P_f & β become _____ due to uncertainty in $\boldsymbol{\theta}_f$ and/or $\boldsymbol{\theta}_g$



cf. $\beta(\boldsymbol{\theta}), P_f(\boldsymbol{\theta}) \Rightarrow$ _____ reliability index given value of uncertain parameters

◎ Three approaches for estimating reliability under epistemic uncertainties

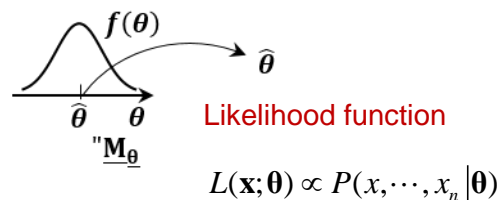
Suppose $f_{|\theta|}(\boldsymbol{\theta})$ is available,



- ① Point estimate of Reliability: $P_f(\boldsymbol{\theta})$ at $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}$

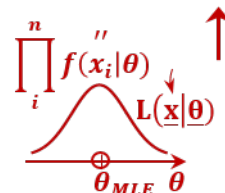
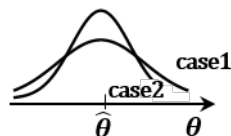
$\hat{\boldsymbol{\theta}}$: point estimate (representative) of $\boldsymbol{\theta}$

e.g.
$$\begin{cases} \hat{\theta} = \mathbf{M}_\theta = \int \theta f_\theta(\theta) d\theta & \text{Bayesian} \\ \hat{\theta} = \theta_{MLE} = \arg \max_{\theta} L(\mathbf{x}; \theta) & \text{Non-Bayesian} \end{cases}$$



$\Rightarrow P_f(\hat{\theta}), \beta(\hat{\theta})$: Perform reliability analysis with $\theta =$ fixed

Note i) $P_f(\mathbf{M}_\theta) = \mathbf{M}_{P_f(\theta)}^{FO}$



ii) Variability in θ not considered

② **Predictive** Reliability

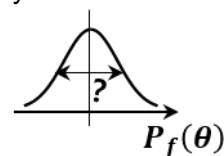
$$\begin{aligned} \tilde{P}_f &= E_\theta [P_f(\theta)] \\ &= \int P_f(\theta) \cdot f_\theta(\theta) d\theta \end{aligned}$$

$$\tilde{\beta} = \Phi^{-1} [\quad]$$

\rightarrow incorporates variability in θ

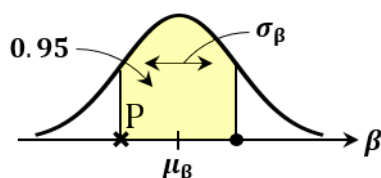
\rightarrow but still point estimate, i.e. does not measure variability in $P_f(\theta)$ caused by

that in θ



③ **Bounds** on Reliability (Confidence Intervals)

$100 \times p(\%)$ confident that β is b/w x and o



First, find mean and variance of $\beta(\theta)$

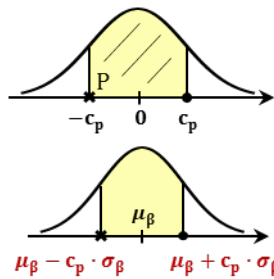
reliability analysis

$$\begin{cases} \mu_\beta \cong \mu_\beta^{FO} = \beta(\mathbf{M}_\theta) \\ \sigma_\beta^2 \cong (\sigma_\beta^2)^{FO} = \nabla_\theta \beta(\mathbf{M}_\theta) \Sigma_{\theta\theta} \nabla_\theta \beta(\mathbf{M}_\theta)^T \end{cases}$$

Parameter sensitivity (e.g. FORM)

Second, assume $\beta \sim N(\mu_\beta, \sigma_\beta)$

Std. normal



$$u_\beta = \frac{\beta - \mu_\beta}{\sigma_\beta}$$

P	c _p
0.70	1.04
0.80	1.28
0.90	1.64
0.95	1.96
0.99	2.58

$$\langle \beta \rangle_{100 \times p(\%)} = \mu_\beta \pm c_p \sigma_\beta$$

(if $\tilde{\beta}$ available, $\tilde{\beta} \pm c_p \sigma_\beta$)

$$\langle P_f \rangle_{100 \times p(\%)} = \Phi \left[-(\tilde{\beta} \pm c_p \sigma_\beta) \right]$$

$$P_f = \Phi(-\beta)$$

Then, $f_{\theta_f}(\theta_f)$, $f_{\theta_g}(\theta_g)$??

(Review) Rel. Analysis under Epistemic Uncertainties (Model or Statistical)

① Point Estimate $P_f(\hat{\theta}), \beta(\hat{\theta})$

② Predictive Reliability $\tilde{P}_f = E_\theta [P_f(\theta)]$

③ Bounds $\langle \beta \rangle_{100 \times p(\%)} = \mu_\beta \pm c_p \sigma_\beta$

$f_{\theta_f}(\theta_f)$? $f_{\theta_g}(\theta_g)$?

◎ Bayesian Parameter Estimation

cf. Bayes rule

$$f(\theta) = c \cdot L(\theta) \cdot p(\theta)$$

$$P(A|B) = \frac{1}{P(B)} \cdot P(B|A) \cdot P(A)$$

f
c
L
p

① $P(\theta)$: () distribution

- represents state of our knowledge () making observations (objective information)

- may incorporate () info. such as “engineering judgment”

② $L(\boldsymbol{\theta})$: () function

- represents () information gained from the observation
- function () to conditional prob. of the observation given $\boldsymbol{\theta}$

$$L(\boldsymbol{\theta}) \propto P(E_{obs} | \boldsymbol{\theta})$$

③ c : () factor

- makes $c \cdot L(\boldsymbol{\theta}) \cdot p(\boldsymbol{\theta})$ a valid PDF

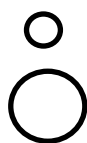
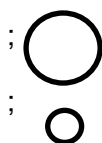
$$\text{i.e. } \int_{\boldsymbol{\theta}} f(\boldsymbol{\theta}) = \int_{\boldsymbol{\theta}} c \cdot L(\boldsymbol{\theta}) \cdot P(\boldsymbol{\theta}) d\boldsymbol{\theta} =$$

$$\therefore c =$$

④ $f(\boldsymbol{\theta})$: () distribution

- represents updated knowledge about $\boldsymbol{\theta}$
- subjective + objective

-



rare observation available

as more observations are made

⊙ Computation of c and posterior statistics

$$\left. \begin{aligned} c &= \left[\int L(\boldsymbol{\theta}) \cdot p(\boldsymbol{\theta}) \cdot d\boldsymbol{\theta} \right]^{-1} \\ \mathbf{M}(\boldsymbol{\theta}) &= \int \boldsymbol{\theta} \cdot f(\boldsymbol{\theta}) d\boldsymbol{\theta} = \int \boldsymbol{\theta} \cdot c \cdot L(\boldsymbol{\theta}) \cdot p(\boldsymbol{\theta}) \cdot d\boldsymbol{\theta} \\ \boldsymbol{\Sigma}_{\boldsymbol{\theta}\boldsymbol{\theta}} &= \int \boldsymbol{\theta}\boldsymbol{\theta}^T f(\boldsymbol{\theta}) d\boldsymbol{\theta} - \mathbf{M}(\boldsymbol{\theta})\mathbf{M}(\boldsymbol{\theta})^T \end{aligned} \right\} \text{multi-fold integrals}$$

How?

- Convenient forms for special distribution (directly update statistics “conjugate”)
- Special numerical algorithms (Geyskens et al. 1993)
- Sampling methods (MCS, importance sampling, ...)