



# Data Structure

## Lecture#25: Graphs 3 (Chapter 11)

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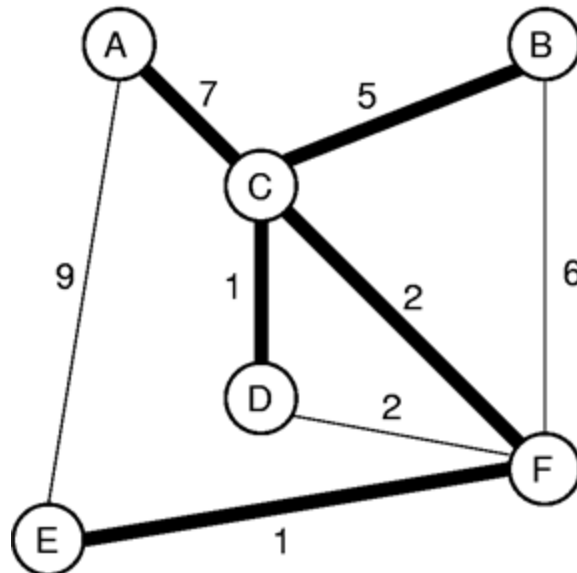
# In This Lecture

- MST (Minimum Spanning Tree) problem
- Main idea and cost of Prim's algorithm for MST
- Main idea and cost of Kruskal's algorithm for MST



# Minimum Cost Spanning Trees (1)

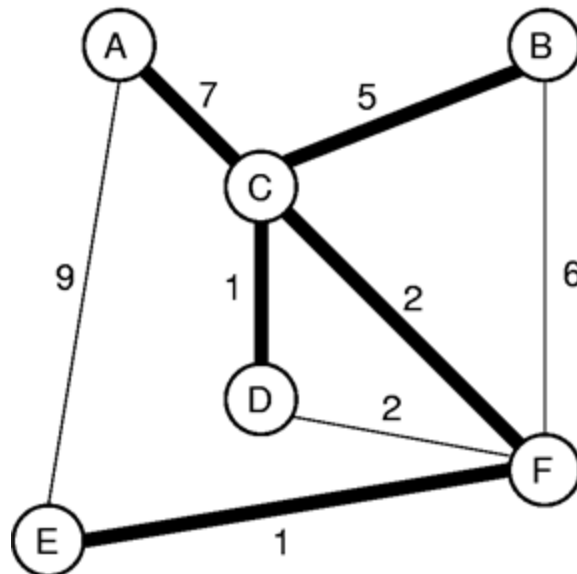
- Minimum Cost Spanning Tree (MST) Problem:
  - Input: An undirected, connected graph  $G$ .
  - Output: The subgraph of  $G$  that
    - 1) has minimum total cost as measured by summing the values of all the edges in the subset, and
    - 2) keeps the vertices connected.





# Minimum Cost Spanning Trees (2)

- Minimum Cost Spanning Tree (MST) Problem:
  - A tree means a graph without cycle
  - Property 1) of the output ensures MST has no cycle (why?)
    - Property 1) G has minimum total cost as measured by summing the values of all the edges in the subset





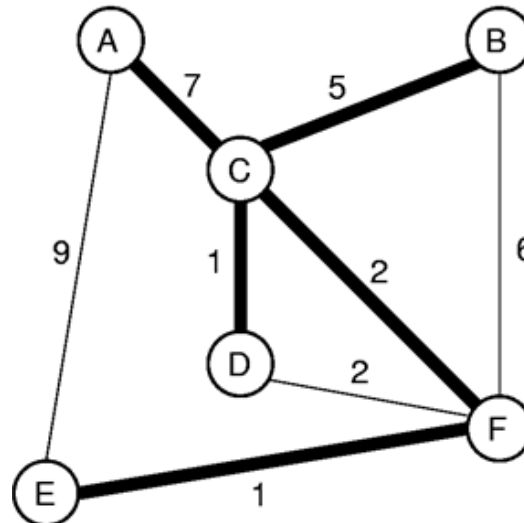
# Minimum Cost Spanning Trees (3)

- Minimum Cost Spanning Tree (MST) Problem:
  - Solution may not be unique
    - E.g., (C,F) can be replaced with (D,F) in the previous slide
  - But, the minimum costs are the same for all the solutions
  
- MST algorithms
  - Prim's algorithm
  - Kruskal's algorithm



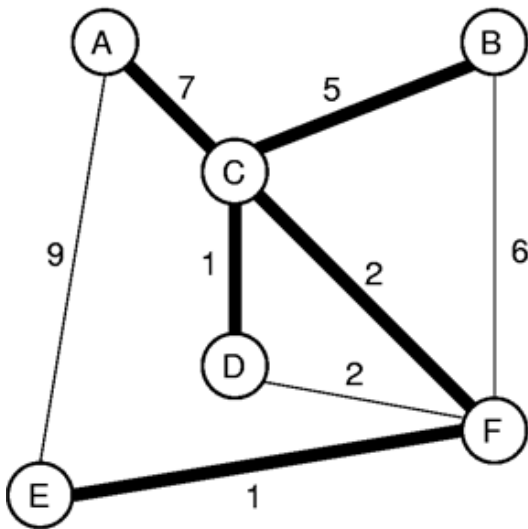
# Prim's MST Algorithm (1)

- Start with any vertex  $N$  in the graph. Add  $N$  to MST.
- Pick the least-cost edge  $(N,M)$  connected to  $N$ .
- Add vertex  $M$  and edge  $(N,M)$  to the MST.
- Pick the least-cost edge connected to  $(N$  or  $M)$ . Let the vertex  $X$  be connected to the edge.
  - $X$  should not belong to the current MST.
- Add vertex  $X$  and the edge to the MST.
- (continue, until all vertices are added to MST)...





# Prim's MST Algorithm (2)



	A	B	C	D	E	F
Initial	$\infty$	$\infty$	0	$\infty$	$\infty$	$\infty$
Process C	7	5	0	1	$\infty$	2
Process D	7	5	0	1	$\infty$	2
Process F	7	5	0	1	1	2
Process E	7	5	0	1	1	2
Process B	7	5	0	1	1	2
Process A	7	5	0	1	1	2



# Prim's MST Algorithm (3)

```
// Compute a minimal-cost spanning tree
void Prim(Graph G, int s, int[] D, int[] V) {
    int v, w;
    for (int i=0; i<G.n(); i++) // Initialize
        D[i] = Integer.MAX_VALUE;
    D[s] = 0;
    for (int i=0; i<G.n(); i++) {
        v = minVertex(G, D);
        G.setMark(v, VISITED);
        if (v != s) AddEdgeToMST(V[v], v);
        if (D[v] == Integer.MAX_VALUE) return;
        for (w=G.first(v); w<G.n(); w=G.next(v, w))
            if (D[w] > G.weight(v, w)) {
                D[w] = G.weight(v, w);
                V[w] = v;
            }
    }
}
```





# Running Time of Prim's MST

- Prim's MST is very similar to Dijkstra's algorithm
  - MST:  $D[w] = G.\text{weight}(v, w);$
  - Shortest Path:  $D[w] = D[v] + G.\text{weight}(v, w);$
- So does the running time of Prim's MST
  - Scan through the distance table:  $\Theta(|V|^2 + |E|) = \Theta(|V|^2)$
  - Min-heap:  $\Theta((|V| + |E|)\log|V|)$

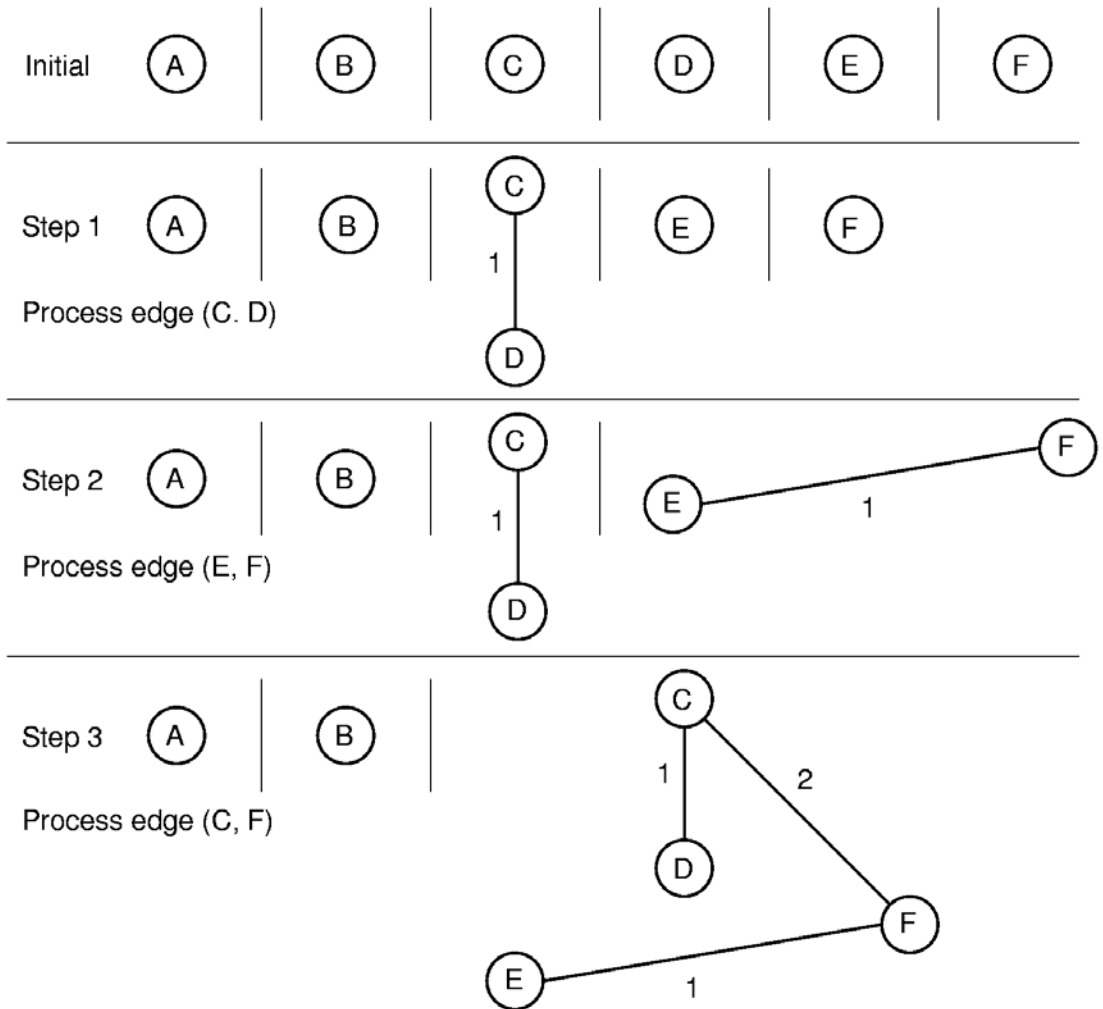
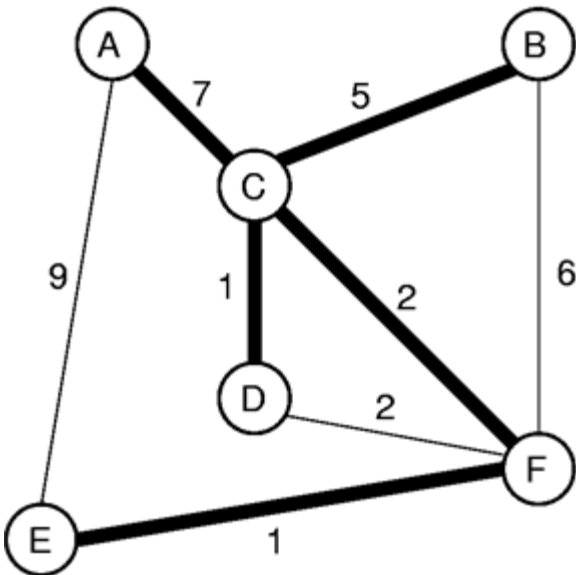


# Kruskal's MST Algorithm (1)

- Initially, each vertex is in its own MST.
- Merge two MST's that have the shortest edge between them.
  - Use a priority queue to order the unprocessed edges. Grab next one at each step.
  - Make sure the edge does not connect two vertices in a same MST
- How to tell if an edge connects two vertices already in the same MST?
  - Use the UNION/FIND algorithm with parent-pointer representation.



# Kruskal's MST Algorithm (2)





# Kruskal's MST Algorithm (3)

- Cost is dominated by the time to remove edges from the heap.
  - Can stop processing edges once all vertices are in the same MST
- Total cost:  $\Theta(|E| \log |E|)$ 
  - Can remove edges  $|E|$  times



# Summary

- MST (Minimum Spanning Tree) problem
- Main idea and cost of Prim's algorithm for MST
  - Cost the same as that of Dijkstra's
- Main idea and cost of Kruskal's algorithm for MST



# Questions?