

### **Introduction to Data Mining**

#### Lecture #13: Frequent Itemsets-2

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### Outline

#### ➡ □ A-Priori Algorithm

- □ PCY Algorithm
- ☐ Frequent Itemsets in ≤ 2 Passes

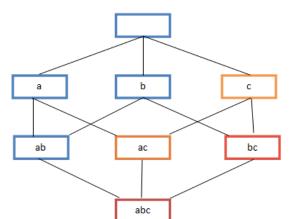


# A-Priori Algorithm – (1)

 A two-pass approach called A-Priori limits the need for main memory

#### Key idea: monotonicity

 If a set of items *I* appears at least *s* times, so does every subset *J* of *I*



- □ E.g., if {A,C} is frequent, then {A} is frequent (so does {C})
- Contrapositive for pairs:
  If item *i* does not appear in *s* baskets, then no pair including *i* can appear in *s* baskets
  Equif (A) is not frequent, then (A, C) is not frequent.
  - □ E.g., if {A} is not frequent, then {A,C} is not frequent

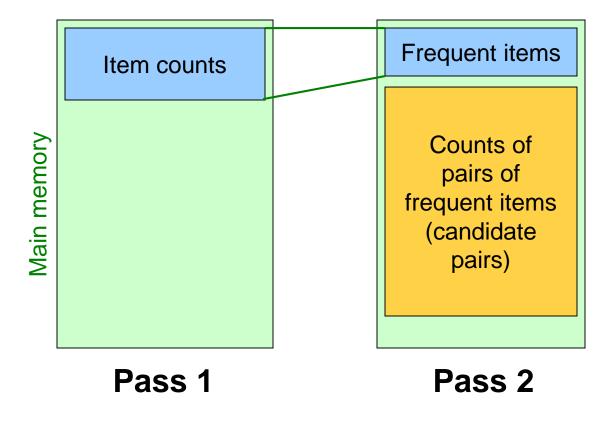
#### So, how does A-Priori find freq. pairs?



# A-Priori Algorithm – (2)

- Pass 1: Read baskets and count in main memory the occurrences of each individual item
  - Requires only memory proportional to #items
- Items that appear  $\geq s$  times are the <u>frequent items</u>
- Pass 2: Read baskets again and count in main memory only those pairs where both elements are frequent (from Pass 1)
  - Requires memory proportional to square of frequent items only (for counts)
  - Plus a list of the frequent items (so you know what must be counted)

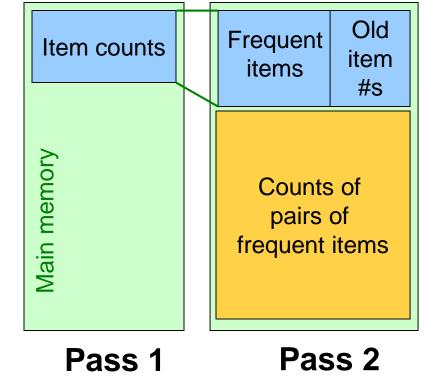
# Main-Memory: Picture of A-Priori





# **Detail for A-Priori**

- You can use the triangular matrix method with n = number of frequent items
  - Why?
  - => May save space compared with storing triples
- Trick: re-number frequent items 1,2,... and keep a table relating new numbers to original item numbers

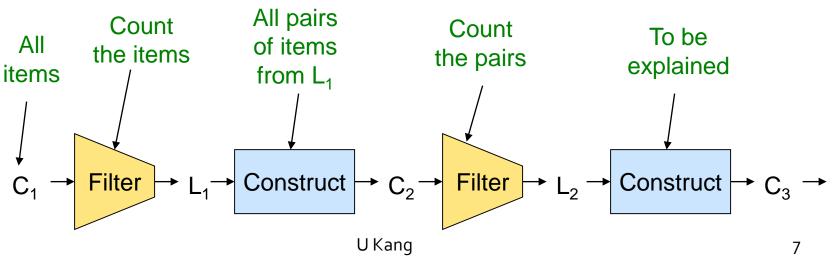




# Frequent Triples, Etc.

- For each k, we construct two sets of k-tuples (sets of size k):
  - C<sub>k</sub> = candidate k-tuples = those that might be frequent sets (support > s) based on information from the pass for k-1

•  $L_k$  = the set of truly frequent *k*-tuples





## Example

#### Hypothetical steps of the A-Priori algorithm

- **C**<sub>1</sub> = { {b} {c} {j} {m} {n} {p} }
- Count the support of itemsets in C<sub>1</sub>
- Prune non-frequent:  $L_1 = \{ b, c, j, m \}$
- Generate C<sub>2</sub> = { {b,c} {b,j} {b,m} {c,j} {c,m} {j,m} }
- Count the support of itemsets in C<sub>2</sub>
- Prune non-frequent:  $L_2 = \{ \{b,c\} \{b,m\} \{c,j\} \{c,m\} \}$
- Generate C<sub>3</sub> = { {b,c,m} {b,c,j} {b,m,j} {c,m,j} }
- Count the support of itemsets in  $C_3$
- Prune non-frequent: L<sub>3</sub> = { {b,c,m} }

\*\* Note here we generate new candidates by generating  $C_k$  from  $L_{k-1}$ .

\*\*

But one can be more careful with candidate generation. For example, in  $C_3$  we know {b,m,j}

UKang cannot be frequent since {m,j} is not frequent



# **Generating C<sub>3</sub> From L<sub>2</sub>**

- Assume {x1, x2, x3} is frequent.
- Then, {x1,x2}, {x1, x3}, {x2, x3} are frequent, too.
- = > if any of {x1,x2}, {x1, x3}, {x2, x3} is NOT frequent, then {x1, x2, x3} is NOT frequent!

- So, to generate C<sub>3</sub> from L<sub>2</sub>,
  - □ Find two frequent pairs in the form of {a, b}, and {a, c}
    - This can be done efficiently if we sort L<sub>2</sub>
  - Check whether {b,c} is also frequent
  - □ If yes, include {a,b,c} to C<sub>3</sub>

# A-Priori for All Frequent Itemsets

- One pass for each k (itemset size)
- Needs room in main memory to count each candidate *k*-tuple
- For typical market-basket data and reasonable minimum support (e.g., 1%), k = 2 requires the most memory

#### Many possible extensions:

- Association rules with intervals:
  - For example: Men over 60 have 2 cars
- Association rules when items are in a taxonomy
  - Bread, Butter → FruitJam
  - BakedGoods, MilkProduct → PreservedGoods
- Lower the min. support *s* as itemset gets bigger



### Outline

- Markov A-Priori Algorithm
- ➡ □ PCY Algorithm
  - □ Frequent Itemsets in < 2 Passes



# PCY (Park-Chen-Yu) Algorithm

#### Observation:

- In pass 1 of A-Priori, most memory is idle
- We store only individual item counts
- Can we use the idle memory to reduce memory required in pass 2?
- Pass 1 of PCY: In addition to item counts, maintain a hash table with as many buckets as fit in memory
  - Keep a count for each bucket into which pairs of items are hashed
    - For each bucket just keep the count, not the actual pairs that hash to the bucket!



# PCY Algorithm – First Pass

F	'OR	(ead	ch bas	sket)	•				
		FOR	(each	ı ite	m in	the ba	asket	<b>こ):</b>	
			add	1 to	iter	n's cou	unt;		
New in	ſ	FOR	(eacł	ı pai	r of	items	) :		
	4	hash the pair to a bucket;							
PCY	l		add	1 to	the	count	for	that	bucket;

#### Few things to note:

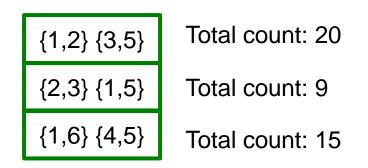
- Pairs of items need to be generated from the input file; they are not present in the file
- We are not just interested in the presence of a pair, but we need to see whether it is present at least *s* (support) times



### Example

#### Assume min. support = 10

- □ Sup(1,2) = 10
- □ Sup(3,5) = 10
- □ Sup(2,3) = 5
- □ Sup(1,5) = 4
- □ Sup(1,6) = 7
- □ Sup(4,5) = 8



Note that {2,3}, and {1,5} cannot be frequent itemsets. (Why?)



### **Observations about Buckets**

- Observation: If a bucket contains a frequent pair, then the bucket is surely frequent
- However, even without any frequent pair, a bucket can still be frequent ☺
  - So, we cannot use the hash to eliminate any member (pair) of a "frequent" bucket
- But, for a bucket with total count less than s, none of its pairs can be frequent <sup>(C)</sup>
  - Pairs that hash to this bucket can be eliminated as candidates (even if the pair consists of 2 frequent items)
    - E.g., even though {A}, {B} are frequent, count of the bucket containing {A,B} might be < s</li>

#### Pass 2:

Only count pairs that hash to frequent buckets



- Replace the buckets by a bit-vector:
  - 1 means the bucket count exceeded the support s
    (call it a frequent bucket); 0 means it did not
- 4-byte integer counts are replaced by bits, so the bit-vector requires 1/32 of memory
- Also, decide which items are frequent and list them for the second pass

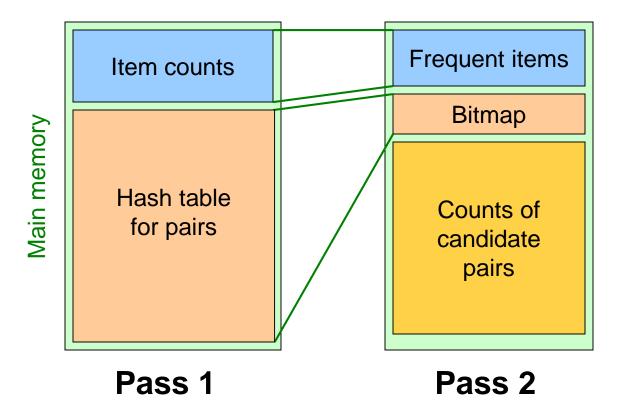


# PCY Algorithm – Pass 2

- Count all pairs {i, j} that meet the conditions for being a candidate pair:
  - 1. Both *i* and *j* are frequent items
  - The pair *{i, j}* hashes to a bucket whose bit in the bit vector is 1 (i.e., a frequent bucket)
- Both conditions are necessary for the pair to have a chance of being frequent



### Main-Memory: Picture of PCY





## **Main-Memory Details**

- Buckets require a few bytes each:
  - Note: we do not have to count past s
    - If s < 256, then we need at most 1 byte for a bucket</p>
  - #buckets is O(main-memory size)
    - Large number of buckets helps. (How?)
    - => decreases false positive

# **Refinement: Multistage Algorithm**

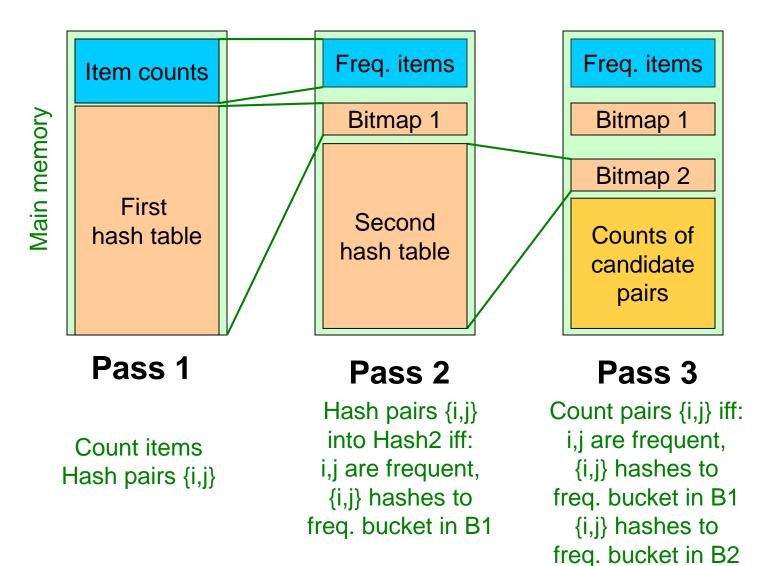
#### Limit the number of candidates to be counted

- Remember: Memory is the bottleneck
- We only want to count/keep track of the ones that are frequent
- Key idea: After Pass 1 of PCY, rehash only those pairs that qualify for Pass 2 of PCY
  - □ *i* and *j* are frequent, and
  - [] {i, j} hashes to a frequent bucket from Pass 1
- On middle pass, fewer pairs contribute to buckets, so fewer *false positives*

#### Requires 3 passes over the data



# Main-Memory: Multistage





# Multistage – Pass 3

- Count only those pairs  $\{i, j\}$  that satisfy these candidate pair conditions:
  - 1. Both *i* and *j* are frequent items
  - Using the first hash function, the pair hashes to a bucket whose bit in the first bit-vector is 1
  - 3. Using the second hash function, the pair hashes to a bucket whose bit in the second bit-vector is 1



### **Important Points**

- 1. The two hash functions have to be independent
- 2. We need to check both hashes on the third pass
  - If not, we may end up counting pairs of items that hashed first to an infrequent bucket but happened to hash second to a frequent bucket

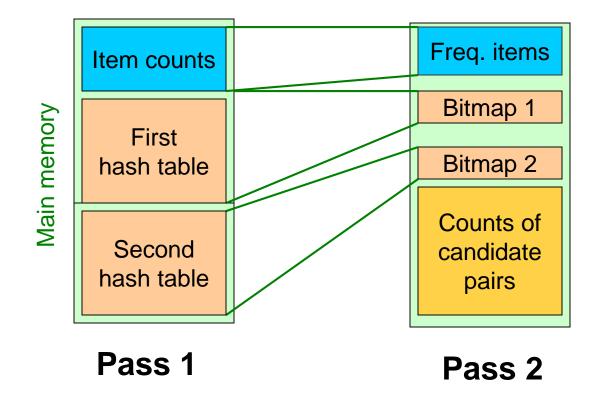


### **Refinement: Multihash**

- Key idea: Use several independent hash tables on the first pass
- Risk: Halving the number of buckets doubles the average count
  - We have to be sure most buckets will still not reach count s
- If so, we can get a benefit like multistage, but in only 2 passes



### Main-Memory: Multihash





### **PCY: Extensions**

- Either multistage or multihash can use more than two hash functions
- In multistage, there is a point of diminishing returns, since the bit-vectors eventually consume all of main memory
  - If we spend too much space for bit-vectors, then we run out of space for candidate pairs
- For multihash, the bit-vectors occupy exactly what one PCY bitmap does, but too many hash functions make all counts <u>></u> s



### Outline

- Martin Algorithm
- PCY Algorithm
- ➡ ☐ Frequent Itemsets in < 2 Passes</p>



### Frequent Itemsets in < 2 Passes

- A-Priori, PCY, etc., take k passes to find frequent itemsets of size k
- Can we use fewer passes?
- Method that uses 2 or fewer passes for all sizes:
  - Random sampling
  - SON (Savasere, Omiecinski, and Navathe)
  - Toivonen (see textbook)



# Random Sampling (1)

- Take a random sample of the market baskets
- Run a-priori or one of its improvements in main memory
  - So we don't pay for disk I/O each time we increase the size of itemsets
  - Reduce min. support proportionally to match the sample size

nemory	Copy of sample baskets
	Space for counts



# Random Sampling (2)

- Optionally, verify that the candidate pairs are truly frequent in the entire data set by a second pass (avoid false positives)
- But you don't catch sets frequent in the whole but not in the sample (cannot avoid false negatives)
  - Smaller min. support, e.g., s/125, helps catch more truly frequent itemsets
    - But requires more space



# SON Algorithm – (1)

- Repeatedly read small subsets of the baskets into main memory and run an in-memory algorithm to find all frequent itemsets
  - We are not sampling, but processing the entire file in memory-sized chunks
  - Min. support decreases to (s/k) for k chunks
- An itemset becomes a candidate if it is found to be frequent in *any* one or more subsets of the baskets.



# SON Algorithm – (2)

- On a second pass, count all the candidate itemsets and determine which are frequent in the entire set
- Key "monotonicity" idea: an itemset cannot be frequent in the entire set of baskets unless it is frequent in at least one subset.
  - Task: find frequent (>= s) itemsets among n baskets
  - n baskets divided into k subsets
  - Load (n/k) baskets in memory, look for frequent (>= s/k) pairs



### **SON – Distributed Version**

- SON lends itself to distributed data mining
- Baskets distributed among many nodes
  - Compute frequent itemsets at each node
  - Distribute candidates to all nodes
  - Accumulate the counts of all candidates



# SON: Map/Reduce

#### Phase 1: Find candidate itemsets

- Map? each machine finds frequent itemsets for the subset of baskets assigned to it
- Reduce? Collect and output candidate frequent itemsets (remove duplicates)

#### Phase 2: Find true frequent itemsets

- Map? Output (candidate\_itemset, count) for the subset of baskets assigned to it
- Reduce? Sum up the count, and output truly frequent (>= s) itemsets



### Summary

- Frequent Itemsets
  - One of the most 'classical' and important data mining task
- Association Rules: {A} -> {B}
  - Confidence, Support, Interestingness
- Algorithms for Finding Frequent Itemsets
  - A-Priori
  - PCY
  - <= 2-Pass algorithm: Random Sampling, SON</p>



# **Questions?**