

재료의 기계적 거동 (Mechanical Behavior of Materials)

Lecture 12 – Plastic Deformation

Heung Nam Han

Professor

Department of Materials Science & Engineering

College of Engineering

Seoul National University

Seoul 151-744, Korea

Tel : +82-2-880-9240

Fax : +82-2-885-9647

email : hnhan@snu.ac.kr

Office hours : Tuesday, Thursday 16:45~17:30

Homepage : <http://mmmpdl.snu.ac.kr>



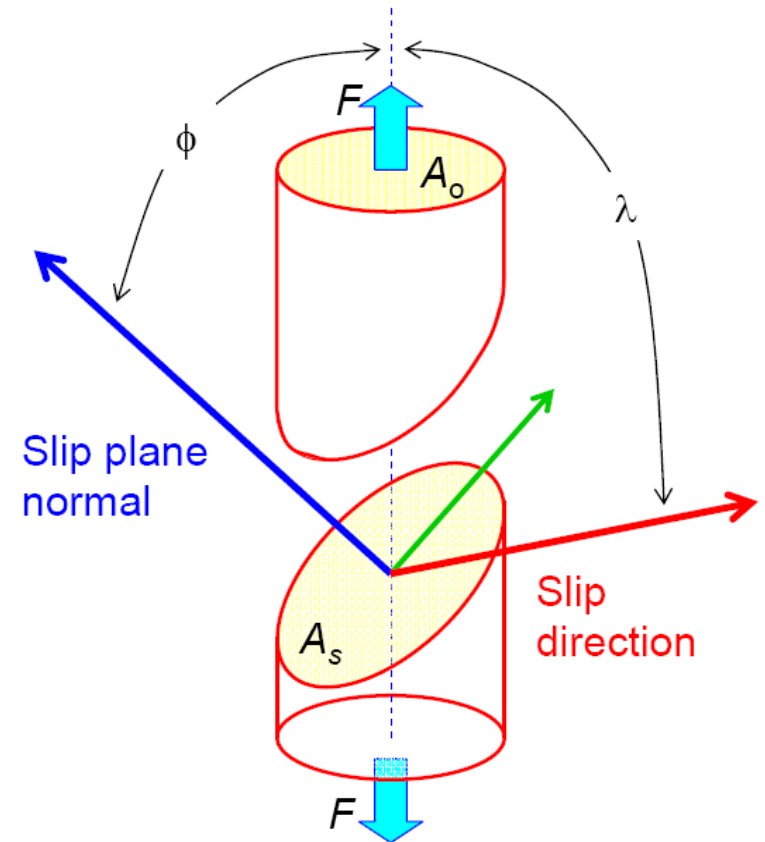
Critical Resolved Shear Stress

- Plastic deformation is initiated at a **critical stress** the critical resolved shear stress (**CRSS**).
- The CRSS is the stress at which dislocations begin to move.

Resolved Shear Stress

$$\tau_{RSS} = \frac{F}{A_o} \underbrace{\cos \phi \cos \lambda}_{\text{Schmid Factor}} = \sigma / m$$

Talyor factor



Plastic flow is initiated when τ_{RSS} reaches a critical value, characteristic of the material, called *critical RSS*, when $m \tau_{CRSS} = \sigma_{ys}$ (*Schmid law*).

Critical Resolved Shear Stress

Example problem I

Calculate the tensile yield stress that is applied along the $[1\bar{2}0]$ axis of a gold crystal to cause slip on the $(1\bar{1}\bar{1})[0\bar{1}1]$ slip system. The critical resolved shear stress is 10 MPa.

Example II: FCC Cu with Loading axis [112]

- What is most likely initial slip system?
- If CRSS is 50 MPa, what is the tensile yield stress at which Cu will start to deform plastically?

Slip Plane n	Slip direction s	n^*l $\cos\phi$	s^*l $\cos\lambda$	Schmid factor $\cos\phi\cos\lambda$	σ (MPa)
(111)	$\bar{1}10$	$2\sqrt{2}/3$	0	0	Not def.
	$\bar{1}01$		$\sqrt{3}/6$	$\sqrt{6}/9$	184
	$0\bar{1}1$		$\sqrt{3}/6$	$\sqrt{6}/9$	184
$(\bar{1}11)$	110	$\sqrt{2}/3$	$\sqrt{3}/3$	$\sqrt{6}/9$	184
	101		$-\sqrt{3}/2$	$-\sqrt{6}/6$	- 122
	$0\bar{1}1$		$\sqrt{3}/6$	$\sqrt{6}/18$	367
$(1\bar{1}1)$	110	$\sqrt{2}/3$	$\sqrt{3}/3$	$\sqrt{6}/9$	184
	$\bar{1}01$		$-\sqrt{3}/6$	$-\sqrt{6}/18$	- 367
	011		$\sqrt{3}/2$	$\sqrt{6}/6$	122
$(11\bar{1})$ $=(\bar{1}\bar{1}1)$	$\bar{1}10$	0	0	0	Not def.
	101		$\sqrt{3}/2$	0	Not def.
	011		$\sqrt{3}/2$	0	Not def.

Smallest
stress to
cause slip
(yielding)

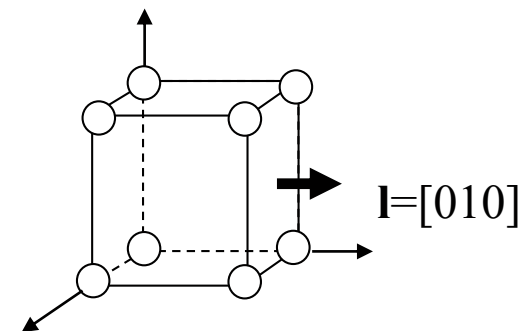
Initial Slip Systems (plane, direction) are then $(\bar{1}11)[101], (1\bar{1}1)[011]$

Example III:

Crystal with simple cubic structure :
slip planes $\{100\}$ and slip directions $\langle 010 \rangle$

Load is applied along $[010]$.
Determine Schmid factor and what slip occurs.

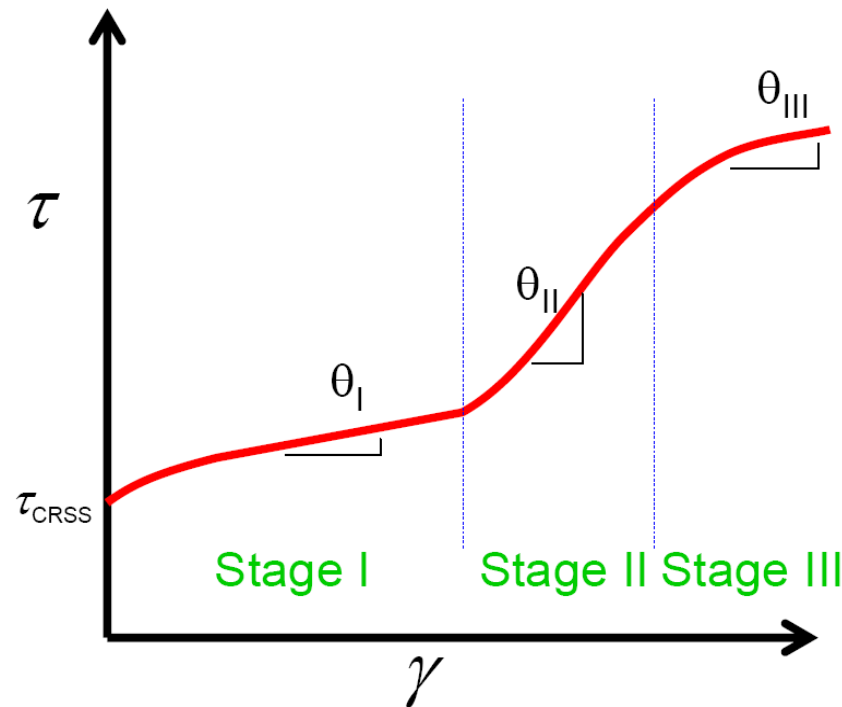
slip plane \mathbf{n}	$\phi, \cos\phi$ $\mathbf{n} \cdot \mathbf{l}$	slip dir. \mathbf{s}	$\lambda, \cos\lambda$ $\mathbf{s} \cdot \mathbf{l}$	$1/m$ $\cos\phi \cos\lambda$
(100)	$90^\circ, 0$	$[010]$	$0^\circ, 1$	0
		$[001]$	$90^\circ, 0$	
(010)	$0^\circ, 1$	$[100]$	$90^\circ, 0$	0
		$[001]$	$90^\circ, 0$	
(001)	$90^\circ, 0$	$[100]$	$90^\circ, 0$	0
		$[010]$	$0^\circ, 1$	



Is there any slip? Why?

If no slip, what must happen finally to material as load is increased?

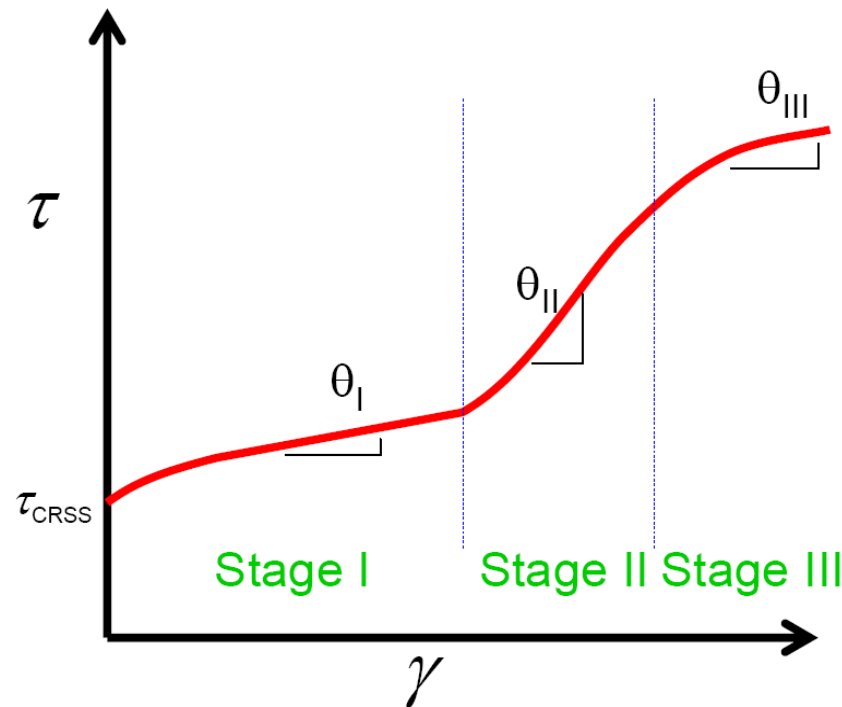
Deformation of single crystals



Stage I:

- After yielding, the shear stress for plastic deformation is essentially constant. There is **little or no work hardening**.
- This is typical when there is a **single slip system** operative. **Dislocations do not interact** much with each other. **“Easy glide”**
- Active slip system is one with maximum Schmid factor.

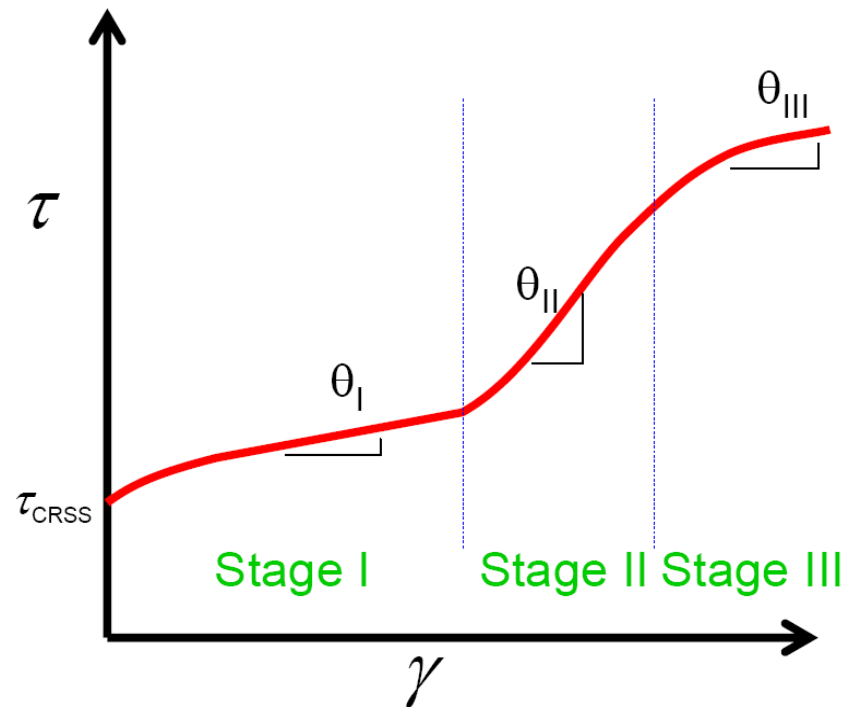
Deformation of single crystals



Stage II:

- The shear stress needed to continue plastic deformation begins to increase in an almost **linear fashion**. There is **extensive work hardening** ($\theta \cong G/300$).
- This stage begins when slip is initiated on **multiple slip systems**.
- Work hardening is due to interactions between dislocations moving on intersecting slip planes.

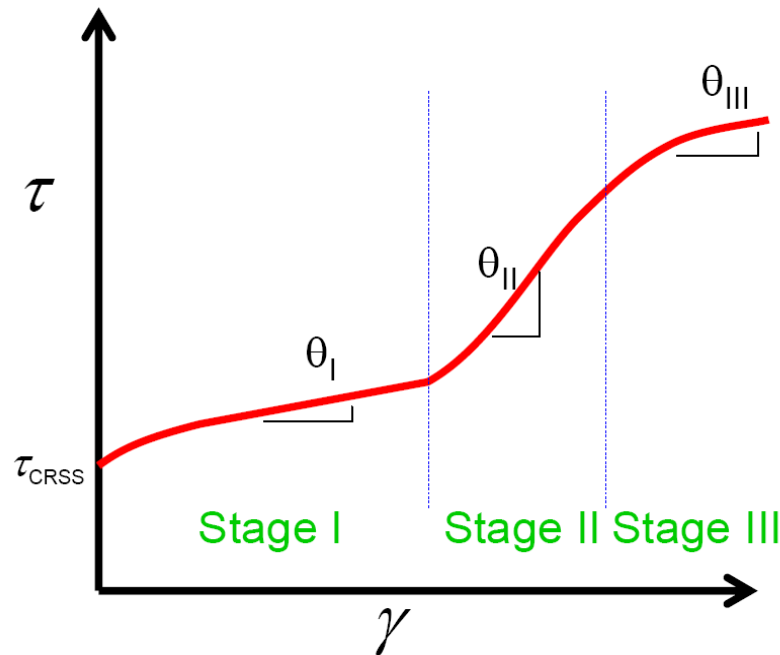
Deformation of single crystals



Stage III:

- There is a decreasing rate of work hardening.
- This decrease is due to an increase in the degree of **cross slip** resulting in a parabolic shape to the curve.

Deformation of single crystals



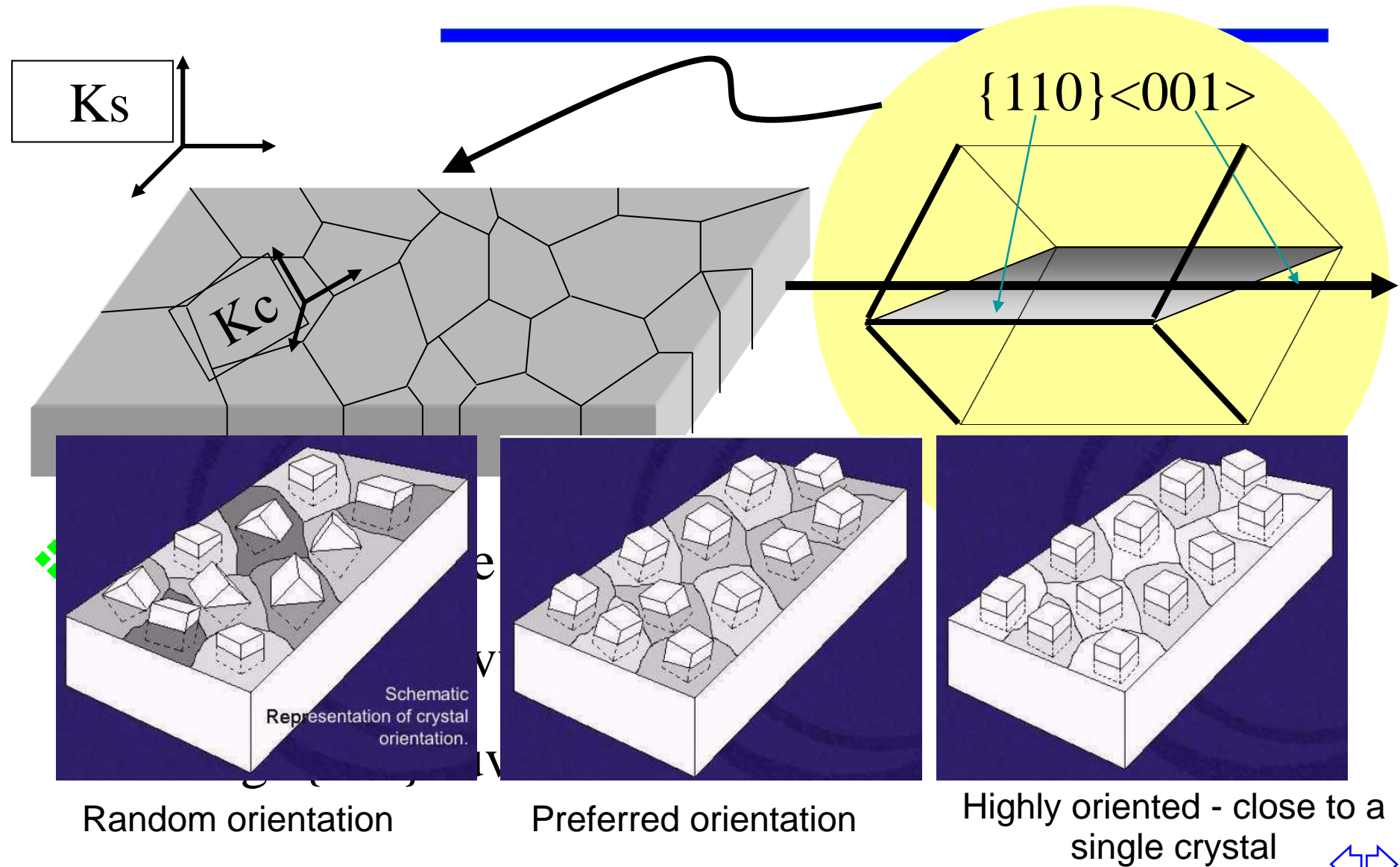
Effect of Temperature:

- Increasing T results in a decrease in the extent of Stage I and Stage II.
- Stage I:—Initiation of secondary slip systems is easier.
- Stage II:—Cross slip is easier.

Stacking Fault Energy (SFE) in FCC metals:

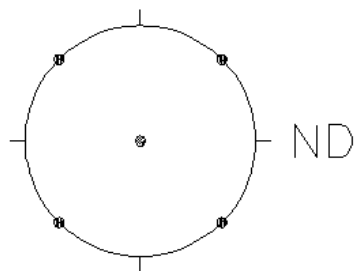
- Decrease SFE, decrease cross slip
- This increases the stress level needed to have a transition from Stage II to Stage III.

Crystal orientation: Miller Indices



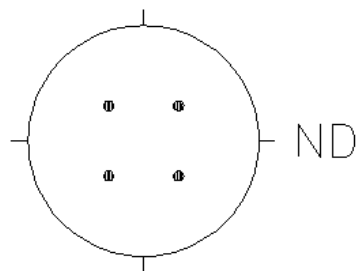
■ (100)

RD



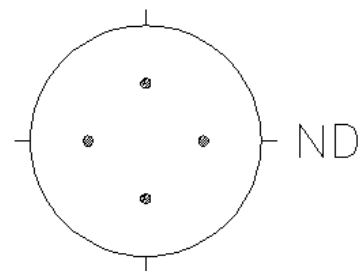
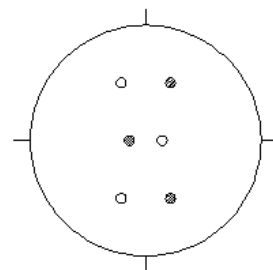
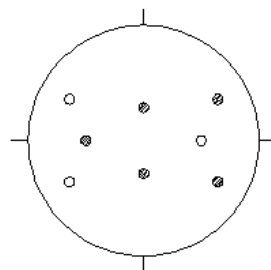
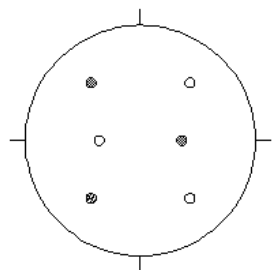
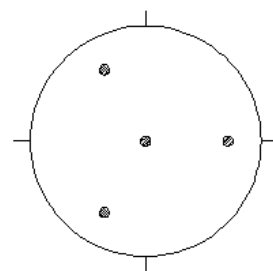
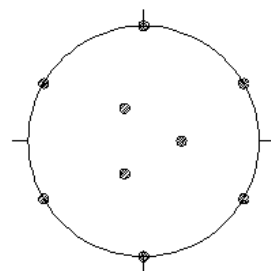
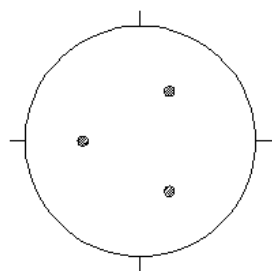
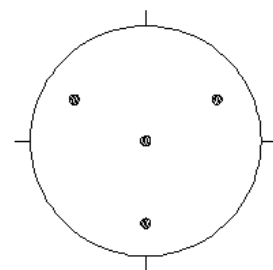
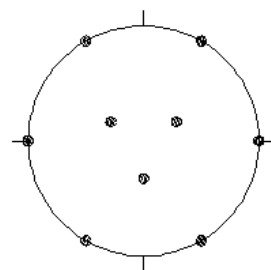
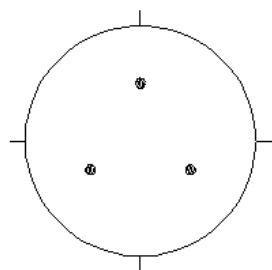
(110)

RD

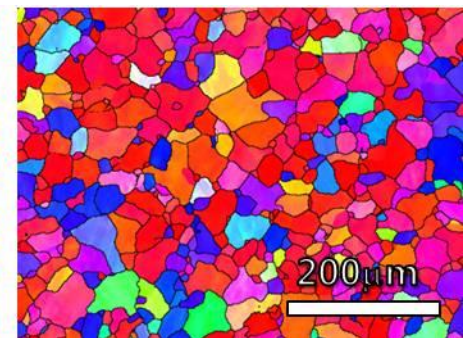
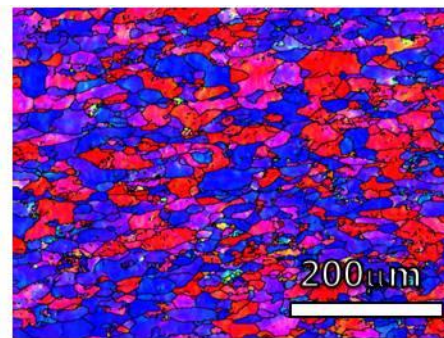
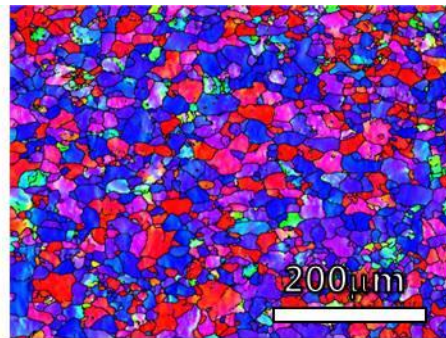
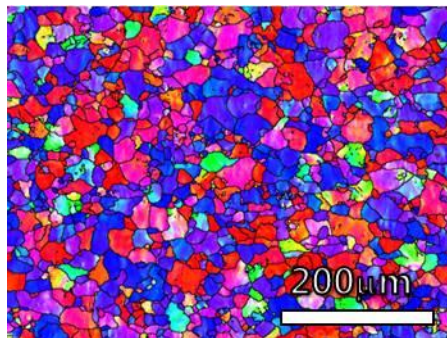
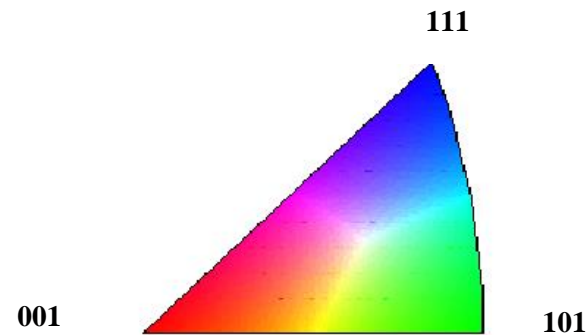


(111)

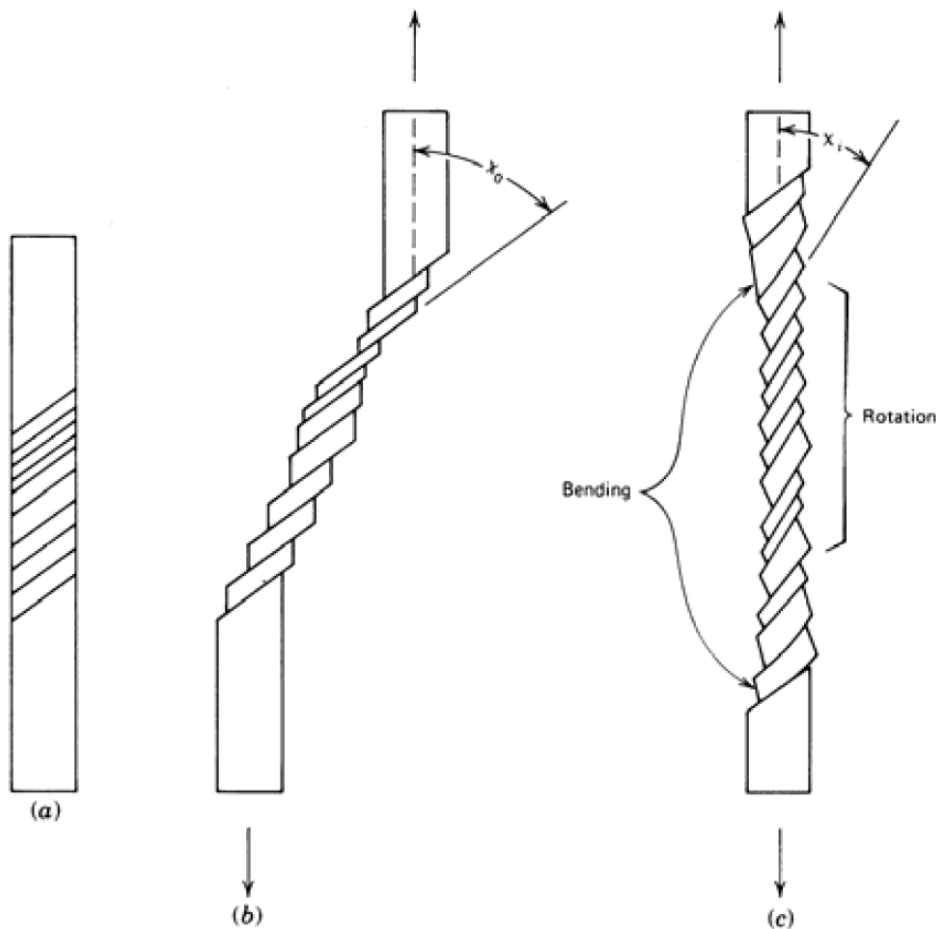
RD

 $(100)[011]$  $(211)[0\bar{1}1]$  $(111)[01\bar{1}]$  $(111)[\bar{1}\bar{1}2]$ 

Orientation (ND) maps



What happens to a single crystal when it starts to yield?

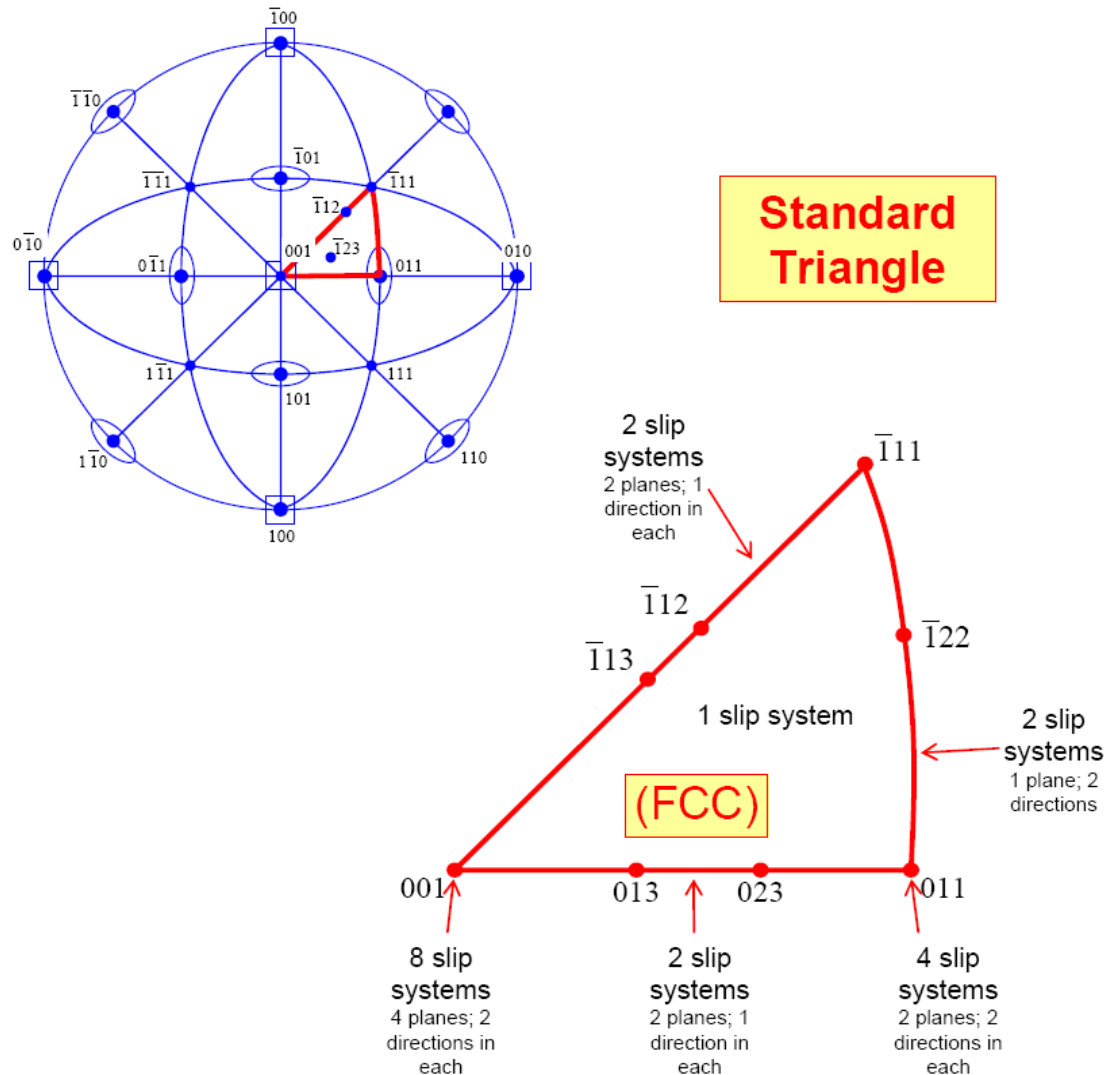


- Consider a single crystal oriented for slip on planes oriented χ degrees from the tensile axis.

- Ideally, crystal planes will “glide” over one another without changing their relative orientation to the load axis.

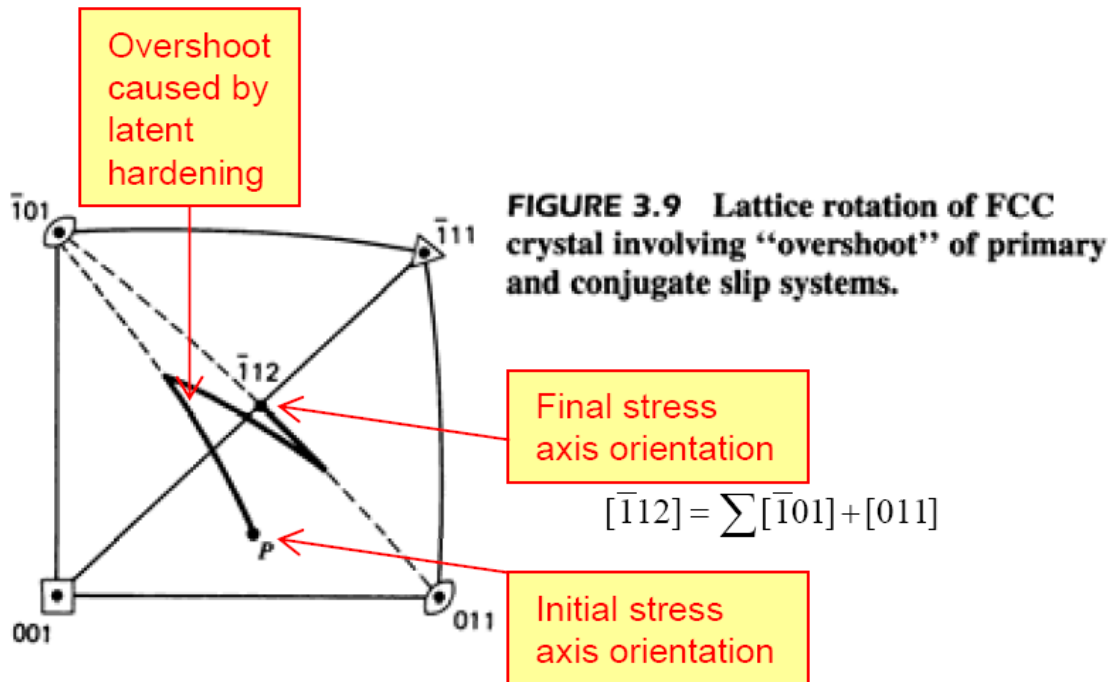
- However, **during tensile testing, the ends of the tensile bar are constrained. Thus, the crystal planes cannot glide freely. They are forced to rotate** towards the tensile axis ($\chi_i < \chi_0$).

[001] stereographic projection of cubic crystal



What happens to a single crystal when it starts to yield?

- When (as is usual) testing constrains the upper and lower ends keeping them aligned, the crystal will rotate such that the **angle between the stress axis and the slip direction decreases**.
- Thus, the Schmid factor changes! This can lead to the initiation of slip on a different system.

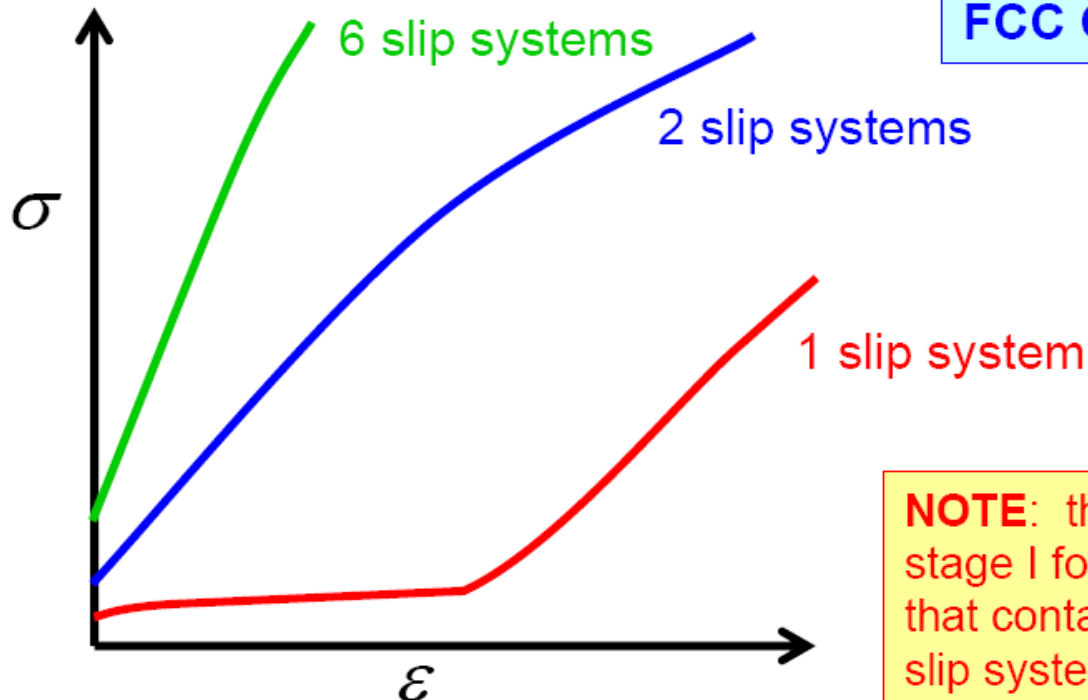


- The crystal will continue to rotate with deformation occurring on alternating slip systems.
- This will continue until the load axis reaches $[-112]$ where the crystal will neck down until failure without changing orientation.

Influence of stress axis orientation

The stress axis orientation plays a **major role** in the stress-strain behavior of a single crystal

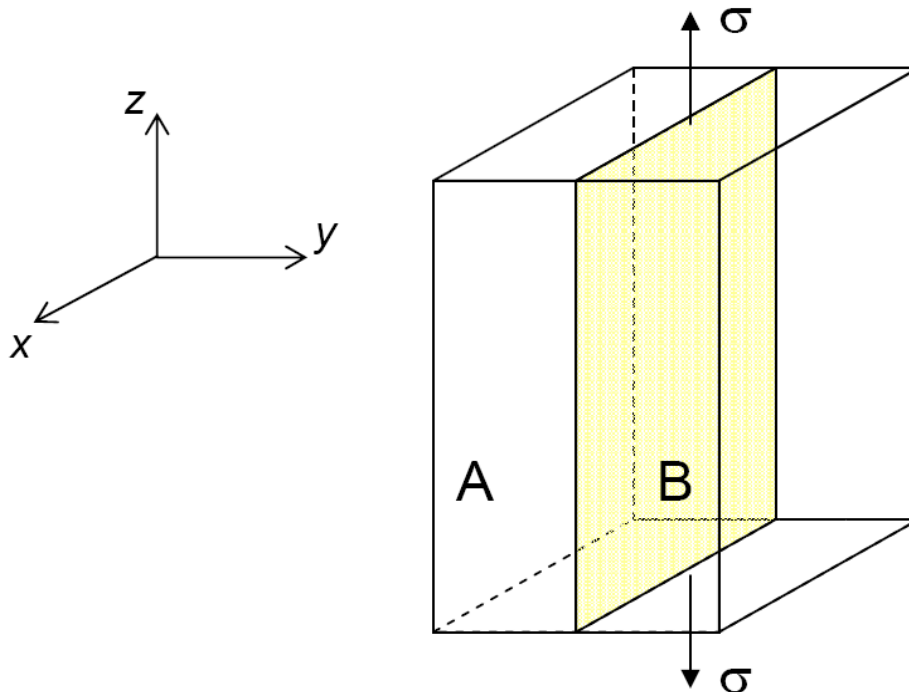
More slip systems means a “harder” material.



NOTE: there is no stage I for crystals that contain multiple slip systems? WHY?

Implications for polycrystalline materials

- Plastic deformation within an individual grain is constrained by the neighboring grains.
- Since plastic deformation of a single grain is restrained by its neighboring grain, a polycrystalline material will have an intrinsically greater resistance to plastic flow than would a single crystal.

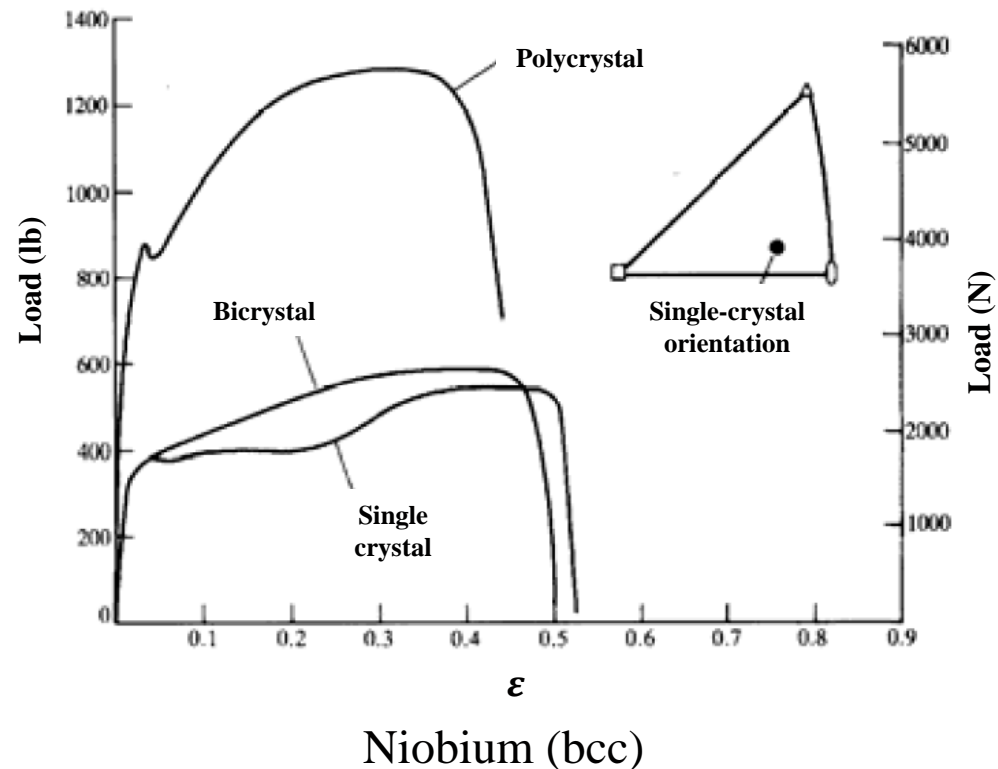
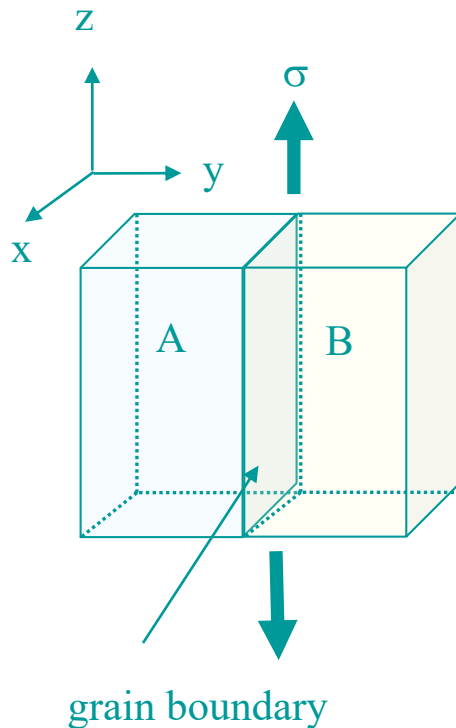


$$\begin{aligned}\epsilon_x^A &= \epsilon_x^B \\ \epsilon_z^A &= \epsilon_z^B \\ \gamma_{xz}^A &= \gamma_{xz}^B\end{aligned}$$

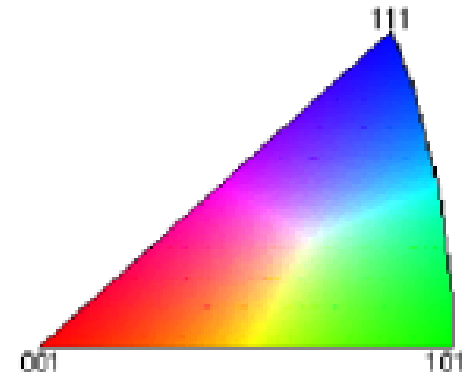
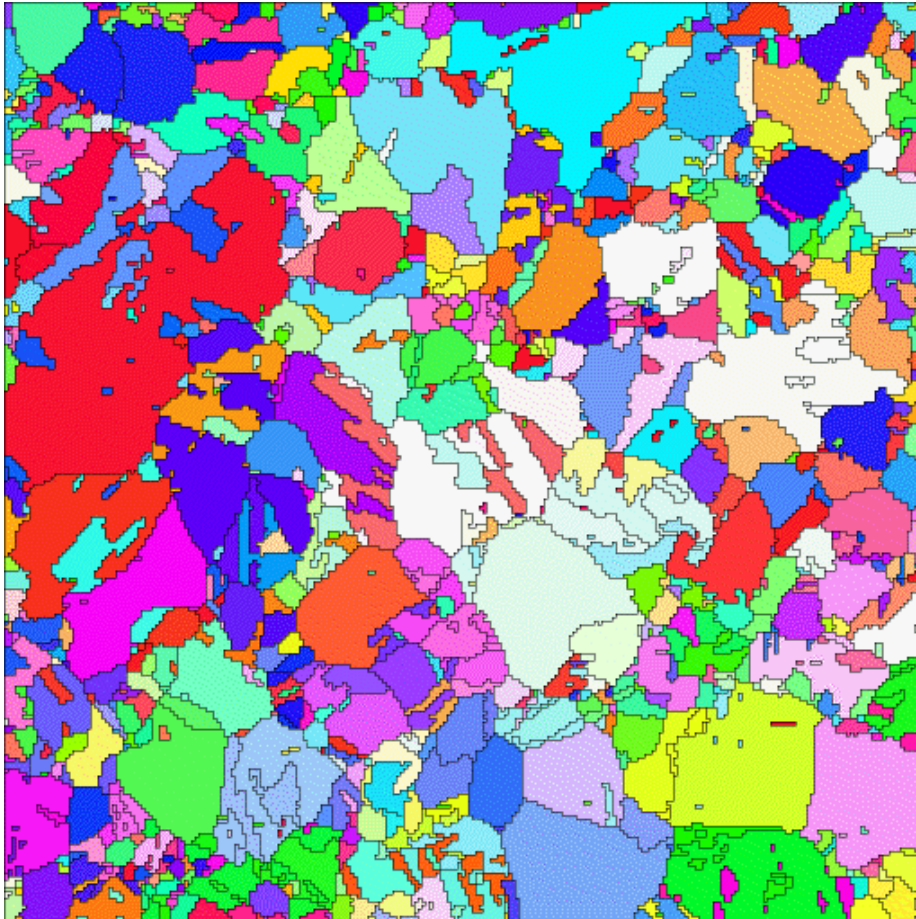
Required to maintain continuity of the grain boundary

Implications for polycrystalline materials

Because *one grain* has a **larger value of $\cos \phi \cos \lambda$** [smaller Taylor factor ($1/m$)], the above constraints restrict the deformation of this more favorably oriented grain and result in a **higher Yield Strength** (greater work-hardening response of the bicrystal).

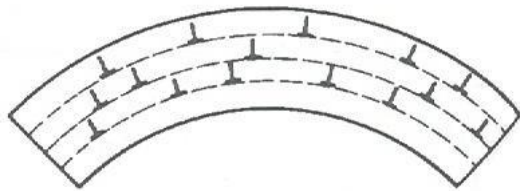
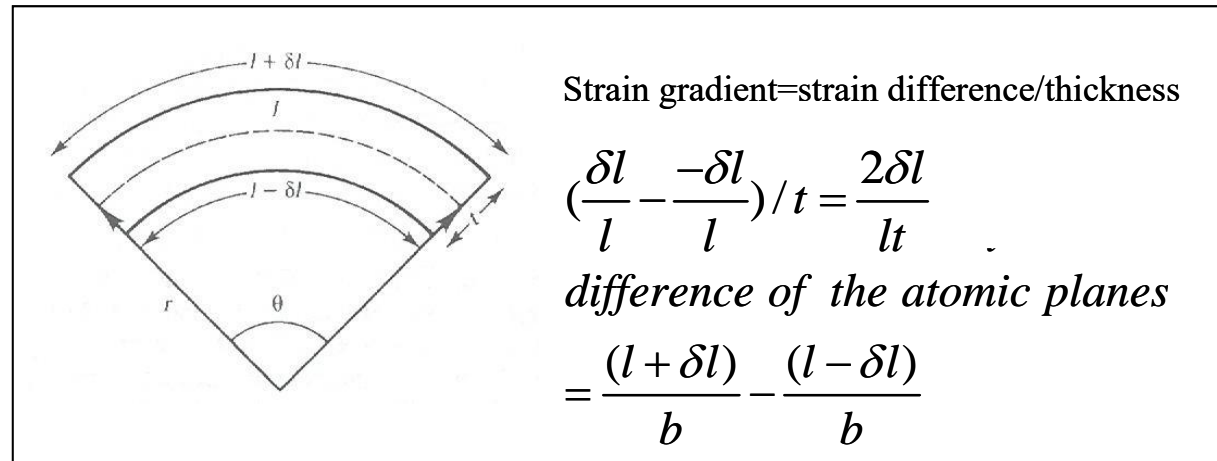
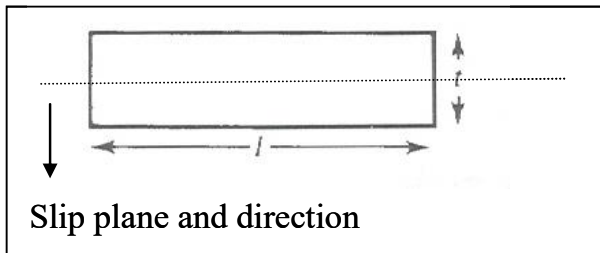


Implications for polycrystalline materials



Geometrically necessary dislocation (GND), Statistically stored dislocation (SSD)

Plastic bending of a crystal



density of geometrical dislocation

$$\rho_s = \frac{\text{the number of dislocation}}{\text{surface area}} = 2 \frac{\delta l}{b l t} = \frac{\text{strain gradient}}{b}$$

Generally,

$$\rho_s = \alpha \frac{\text{strain gradient}}{b}$$

Geometrically necessary dislocation (GND)

15.2 16.8 $\text{Log}_{10}[\text{m}^{-2}]$

