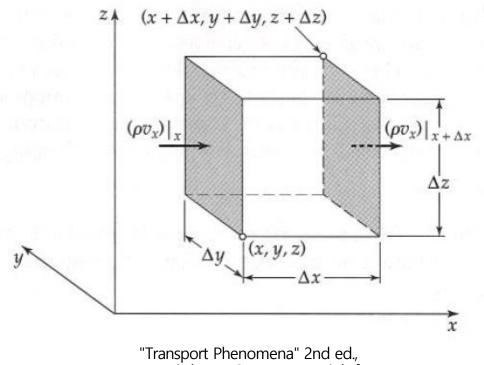
Chapter 3. The Equation of Change for Isothermal System

- The equation of continuity, of motion
- The equation of mechanical energy
- The equation of angular momentum
- The equations of change in terms of the substantial derivative
- Dimensional analysis of the equations of change

Chapter 3. The Equation of Change for Isothermal System

Equation of continuity



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3.1. Equation of continuity

• Transient !

$$\begin{bmatrix} \text{rate of} \\ \text{increase} \\ \text{of mass} \end{bmatrix} = \begin{bmatrix} \text{rate of} \\ \text{mass in} \end{bmatrix} - \begin{bmatrix} \text{rate of} \\ \text{mass out} \end{bmatrix}$$

$$\begin{aligned} \Delta x \Delta y \Delta z \frac{\partial \rho}{\partial t} &= \Delta y \Delta z \cdot \left[\left(\rho v_x \right)_x - \left(\rho v_x \right)_{x+\Delta x} \right] \\ &+ \Delta z \Delta x \cdot \left[\left(\rho v_y \right)_y - \left(\rho v_y \right)_{y+\Delta y} \right] \\ &+ \Delta x \Delta y \cdot \left[\left(\rho v_z \right)_z - \left(\rho v_z \right)_{z+\Delta z} \right] \end{aligned}$$

Equation of continuity

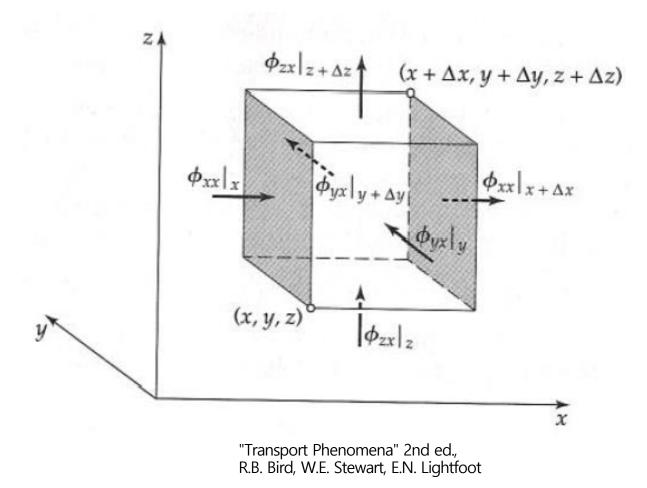
$$\frac{\partial \rho}{\partial t} = -\left(\frac{\partial}{\partial x}\rho v_x + \frac{\partial}{\partial y}\rho v_y + \frac{\partial}{\partial z}\rho v_z\right)$$

$$/\frac{\partial\rho}{\partial t} = -(\nabla \cdot \rho \underline{v})$$

Rate of increase of mass per unit volume

Net rate of mass addition per unit volume by convection

3.2 The Equation of Motion





$$\begin{bmatrix} \text{rate of} \\ \text{increase of} \\ \text{momentum} \end{bmatrix} = \begin{bmatrix} \text{rate of} \\ \text{momentum} \\ \text{in} \end{bmatrix} - \begin{bmatrix} \text{rate of} \\ \text{momentum} \\ \text{out} \end{bmatrix} + \begin{bmatrix} \text{external} \\ \text{forces on} \\ \text{the fluid} \end{bmatrix}$$

• Momentum by convective and molecular transport: net rate of addition of x-component

$$\Delta y \Delta z \left(\phi_{xx} \Big|_{x} - \phi_{xx} \Big|_{x + \Delta x} \right) + \Delta z \Delta x \left(\phi_{yx} \Big|_{y} - \phi_{yx} \Big|_{y + \Delta y} \right) + \Delta x \Delta y \left(\phi_{zx} \Big|_{z} - \phi_{zx} \Big|_{z + \Delta z} \right)$$

Equation of motion

$$\frac{\partial}{\partial t}\rho v_x = -\left(\frac{\partial}{\partial x}\phi_x + \frac{\partial}{\partial y}\phi_y + \frac{\partial}{\partial z}\phi_z\right) + \rho g_x$$

• Vector notation $\frac{\partial}{\partial t}\rho \underline{v} = -\left(\nabla \cdot \underline{\phi}\right) + \rho \underline{g}$

where

 $\underline{\phi} = \underline{\pi} + \rho \underline{vv} = p\underline{\delta} + \underline{\tau} + \rho \underline{vv}$ $\underline{\phi} : \text{combined momentum flux tensor}$ $\rho \underline{vv} : \text{convective momentum flux tensor}$ $\underline{\pi} : \text{Molecular momentum flux tensor}$

Equation of motion

$$\frac{\partial}{\partial t}\rho \underline{v} = -\left(\nabla \cdot \rho \underline{v} \underline{v}\right) - \nabla \cdot \underline{p} - \left(\nabla \cdot \underline{\tau}\right) + \rho \underline{g}$$

- $\frac{\partial}{\partial t} \rho \underline{v}$: rate of increase of momentum per unit volume
- $-(\nabla \cdot \rho \underline{vv})$: rate of momentum addition by convection
- $-\nabla \cdot \underline{p} (\nabla \cdot \underline{\tau})$: rate of momentum addition by molecular transport
- $\rho \underline{g}$: external force on fluid

3.3. The equation of mechanical energy

• Dot product between velocity and equation of motion:

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{2} \rho v^2 \right) &= -\left(\nabla \cdot \frac{1}{2} \rho v^2 \underline{v} \right) - \left(\nabla \cdot p \underline{v} \right) - p(-\nabla \cdot \underline{v}) \\ &- \left(\nabla \cdot \left(\underline{\tau} \cdot \underline{v} \right) \right) - \left(-\underline{\tau} : \nabla \underline{v} \right) + \rho \left(\underline{v} \cdot \underline{g} \right) \end{aligned}$$

The equation of mechanical energy

- Terms: rate of..... per unit volume
 - increase of kinetic energy
 - addition of kinetic energy by convection
 - work done by pressure of surroundings on the fluid
 - reversible conversion of kinetic energy into internal energy
 - work done by viscous forces on the fluid
 - irreversible conversion from kinetic energy to internal energy
 - work by external force on the fluid

3.4. The equation of angular momentum

• Cross product between position and equation of motion:

$$\frac{\partial}{\partial t}\rho(\underline{r}\times\underline{v}) = -\left(\nabla\cdot\rho\underline{v}(\underline{r}\times\underline{v})\right) - \left(\nabla\cdot(\underline{r}\times\underline{v}\underline{\delta})^{\dagger}\right)$$

$$-\left(\nabla \cdot \left(\underline{r} \times \underline{\tau}^{\dagger}\right)^{\dagger}\right) + \left(\underline{r} \times \rho \underline{g}\right) - \left(\underline{\varepsilon} : \underline{\tau}\right)$$

3.5. The equations of change in terms of the substantial derivative

- The partial time derivative $\frac{\partial c}{\partial t}$
- The total time derivative

$$\frac{dc}{dt} = \left(\frac{\partial c}{\partial t}\right)_{x,y,z} + \frac{dx}{dt} \left(\frac{\partial c}{\partial x}\right)_{y,z,t} + \frac{dy}{dt} \left(\frac{\partial c}{\partial y}\right)_{z,x,t} + \frac{dz}{dt} \left(\frac{\partial c}{\partial z}\right)_{x,y,t}$$

• The substantial time derivative

$$\frac{Dc}{Dt} = \frac{\partial c}{\partial t} + v_x \frac{\partial c}{\partial x} + v_y \frac{\partial c}{\partial y} + v_z \frac{\partial c}{\partial z} = \frac{\partial c}{\partial t} + \left(\underline{v} \cdot \nabla c\right)$$

• For constant density and viscosity. Navier-Stokes equation

$$\rho \frac{D}{Dt} \vec{v} = -\nabla p + \mu \nabla^2 \vec{v} + \rho \vec{g} \quad \text{or}$$

$$\rho \frac{\mathrm{D}}{\mathrm{D}\,t} \,\vec{\mathrm{v}} = -\nabla \mathrm{P} + \mu \nabla^2 \vec{\mathrm{v}}$$

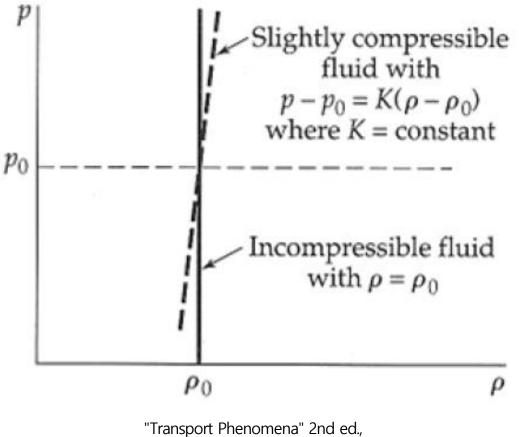
 Negligible acceleration terms: Stokes flow equation

$$0 = -\nabla p + \mu \nabla^2 \vec{v} + \rho \vec{g}$$

 Negligible viscous forces: Euler equation

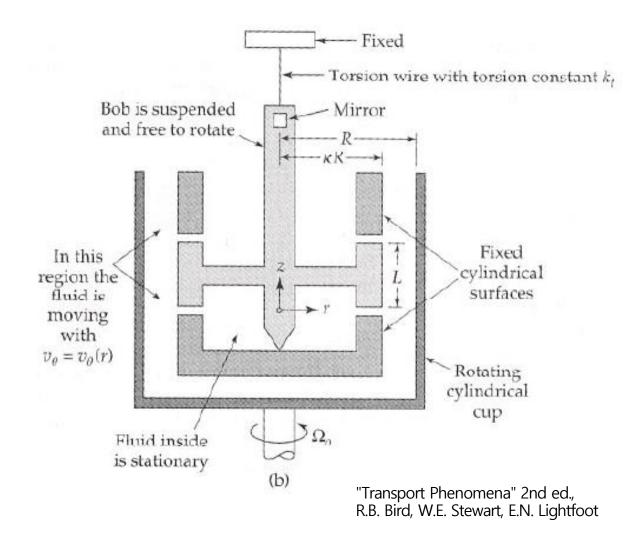
$$\rho \frac{D}{Dt} \vec{v} = -\nabla p + \rho \vec{g}$$

The equation of state

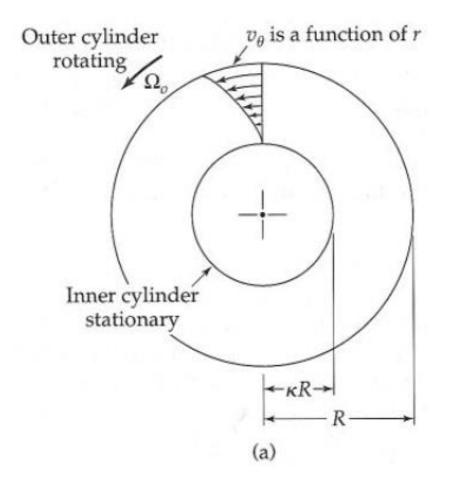


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3.6 Use of the Equations of Change







• Constant ρ and μ

$$v_{\theta} = v_{\theta}(r)$$

$$v_r = v_z = 0$$

$$p = p(r, z)$$

"Transport Phenomena" 2nd ed., R.B. Bird, W.E. Stewart, E.N. Lightfoot

Equations

- r-component $-\rho \frac{v_o^2}{r} = -\frac{\partial p}{\partial r}$
- θ-component

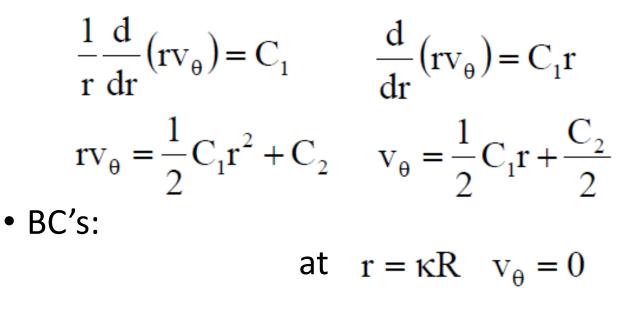
$$0 = \frac{d}{dr} \left(\frac{1}{r} \frac{d}{dr} (rv_{\theta}) \right)$$

• z-component

$$0 = -\frac{\partial p}{\partial z} - \rho g$$

Solving equations

Integrating

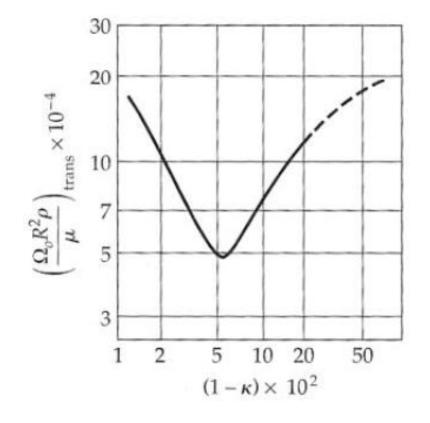


at r = R $v_{\theta} = \Omega_{o}R$

Results

- Then $v_{\theta} = \Omega_{o}R \frac{\left(\frac{r}{\kappa R} - \frac{\kappa R}{r}\right)}{\left(\frac{1}{\kappa} - \kappa\right)}$
- Torque

$$T_{z} = (-\tau_{r\theta})|_{r=\kappa R} \cdot 2\pi\kappa RL \cdot \kappa R$$
$$= 4\pi\mu\Omega_{o}R^{2}L\left(\frac{\kappa^{2}}{1-\kappa^{2}}\right)$$



"Transport Phenomena" 2nd ed., R.B. Bird, W.E. Stewart, E.N. Lightfoot

- Critical Reynolds numbers for the tangential flow in an annulus (above which the system becomes turbulent)
- Outer cylinder rotating
- Inner cylinder stationary

3.7. Dimensional analysis of the equations of change

• For simplicity, constant density and viscosity

$$\left(\nabla \cdot \underline{v} \right) = 0 \qquad \qquad \rho \frac{D}{Dt} \underline{v} = -\nabla \underline{P} + \mu \nabla^2 \underline{v}$$

• Defining dimensionless variables

$$\tilde{x} = \frac{x}{l_o} \qquad \tilde{y} = \frac{y}{l_o} \qquad \tilde{z} = \frac{z}{l_o} \qquad \tilde{t} = \frac{v_o t}{l_o}$$
$$\tilde{v} = \frac{v}{v_o} \qquad \tilde{P} = \frac{P - P_o}{\rho v_o}$$

3.7. Dimensional analysis of the equations of change

• Equation of continuity

$$\left(\widetilde{\nabla} \cdot \underline{\widetilde{v}} \right) = 0$$

• Equation of motion

$$\frac{D}{D\tilde{t}}\frac{\tilde{\nu}}{\tilde{v}} = -\tilde{\nabla}\frac{\tilde{P}}{\tilde{P}} + \frac{\mu}{l_o v_o \rho}\tilde{\nabla}^2\underline{\tilde{\nu}}$$

3.7. Dimensional analysis of the equations of change

• Reynolds number

$$\operatorname{Re} = \begin{bmatrix} \underline{1_{o}v_{o}\rho} \\ \mu \end{bmatrix} = \begin{bmatrix} \text{inertial forces} \\ \text{viscous forces} \end{bmatrix}$$

• Other numbers are Froude and Weber numbers

$$Fr = \left[\frac{v_o^2}{l_o g}\right] \qquad We = \left[\frac{\sigma}{l_o v_o^2 \rho}\right]$$