SEOUL NATIONAL UNIVERSITY SCHOOL OF MECHANICAL AND AEROSPACE ENGINEERING

SYSTEM CONTROL

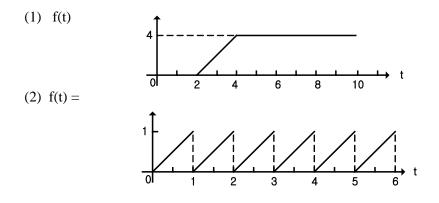
| SYSTEM CONTROL | Fall 2014 |
|------------------------|------------------------------|
| HW#1 Laplace Transform | Out: September 11, 2014 (Th) |
| | Due: September 18, 2014 (Th) |

[1] Compute Laplace Transform

- (1) unit step 1(t)
- (2) $\sin \omega t$

(3)
$$\frac{1}{a}(1-e^{-at})$$

- (4) $e^{-at}\cos\omega t$
- [2] Find the Laplace transforms of



[3] Obtain the inverse Laplace transform of followings:

(1)
$$\frac{1}{s+a}$$
 (2) $\frac{1}{(s+a)^2}$ (3) $\frac{1}{s^2-\omega^2}$ (4) $F(S) = \frac{1}{(S+2)^2(S+3)}$.

- [4] Show that $L\left\{\frac{d}{dt}f(t)\right\} = sF(s) - f(0)$ where $F(s) = L\{f(t)\}$
- [5] Show that:

 $\lim_{t\to 0} f(t) = \lim_{s\to\infty} sF(s)$

[6] Solve following differential equation by Laplace transformation. $\ddot{y} + 2\dot{y} + 4y = 1$ $y(0) = 0, \dot{y}(0) = 2$