

$$1. \quad \dot{x} = Ax + Bu$$

$$J(x_0) := \min_{u \in \mathcal{U}_2} \int_0^{\infty} [x^T Q x + u^T u] dt$$

$$\text{subject to } \begin{aligned} x(0) &= x_0 \\ \dot{x} &= Ax + Bu. \end{aligned}$$

sol) Let P be any symmetric matrix.

$$\begin{aligned} \frac{d}{dt} (x^T P x) &= \dot{x}^T P x + x^T \dot{P} x + x^T P \dot{x} \\ &= (Ax + Bu)^T P x + x^T \dot{P} x + x^T P (Ax + Bu) \\ &= x^T (A^T P + \dot{P} + PA) x + 2u^T B^T P x \end{aligned}$$

$$\begin{aligned} x^T P x \Big|_0^{\infty} &= \int_0^{\infty} \{ x^T (A^T P + \dot{P} + PA) x + 2u^T B^T P x \} dt \\ &= \cancel{x^T(\infty)P(\infty)x(\infty)} - \underline{x^T(0)P(0)x(0)} \end{aligned}$$

$$\begin{aligned} J &= \int_0^{\infty} (x^T Q x + u^T u) dt + x^T P x \Big|_0^{\infty} - x^T P x \Big|_0^{\infty} \\ &= x^T(0)P(0)x(0) + \int_0^{\infty} \{ x^T (\dot{P} + A^T P + PA + Q) x + 2x^T P B u + u^T u \} dt \\ &= x^T(0)P(0)x(0) + J_1 \end{aligned}$$

$$\text{where } J_1 = \int_0^{\infty} \{ x^T (\dot{P} + A^T P + PA + Q) x + \underbrace{2x^T P B u + u^T u}_{\text{or } 2u^T B^T P x} \} dt$$

by "Completion of squares" approach

$$J_1 = \int_0^{\infty} \left\{ x^T (\dot{P} + A^T P + P A + Q) x + \underbrace{2x^T P B u + u^T u}_{= x^T P B u + u^T B^T P x} \right\} dt$$
$$= \int_0^{\infty} \left\{ (B^T P x + u)^T (B^T P x + u) - x^T P B B^T P x + x^T (\dot{P} + A^T P + P A + Q) x \right\} dt$$

$$= \int_0^{\infty} \left\{ x^T (\dot{P} + A^T P + P A + Q - P B B^T P) x + (B^T P x + u)^T (B^T P x + u) \right\} dt$$

if $\dot{P} + A^T P + P A + Q - P B B^T P = 0$ 이고, -①

$u = -B^T P x$ -② 이면,

$J_1 = 0$ 이되고, 따라서

$$J(x) = \min_{u \in L_2} \int_0^{\infty} [x^T Q x + u^T u] dt$$

$$= x^T(0) P(0) x(0) \quad \text{when } J_1 = 0$$

한편 $P(t)$ 는 0 근처에서 일정하고,

$\therefore \dot{P} = 0$, near 0.

$\therefore \left\{ \begin{array}{l} J(x_0) = P x_0^2 \quad : \text{value of function } J \end{array} \right.$

$\left\{ \begin{array}{l} u = -B^T P x \quad : \text{input } u \text{ which achieves the optimum} \end{array} \right.$

when P is solution of

$$A^T P + P A + Q - P B B^T P = 0$$

which called ARE (algebraic Riccati equation)



Prob 2

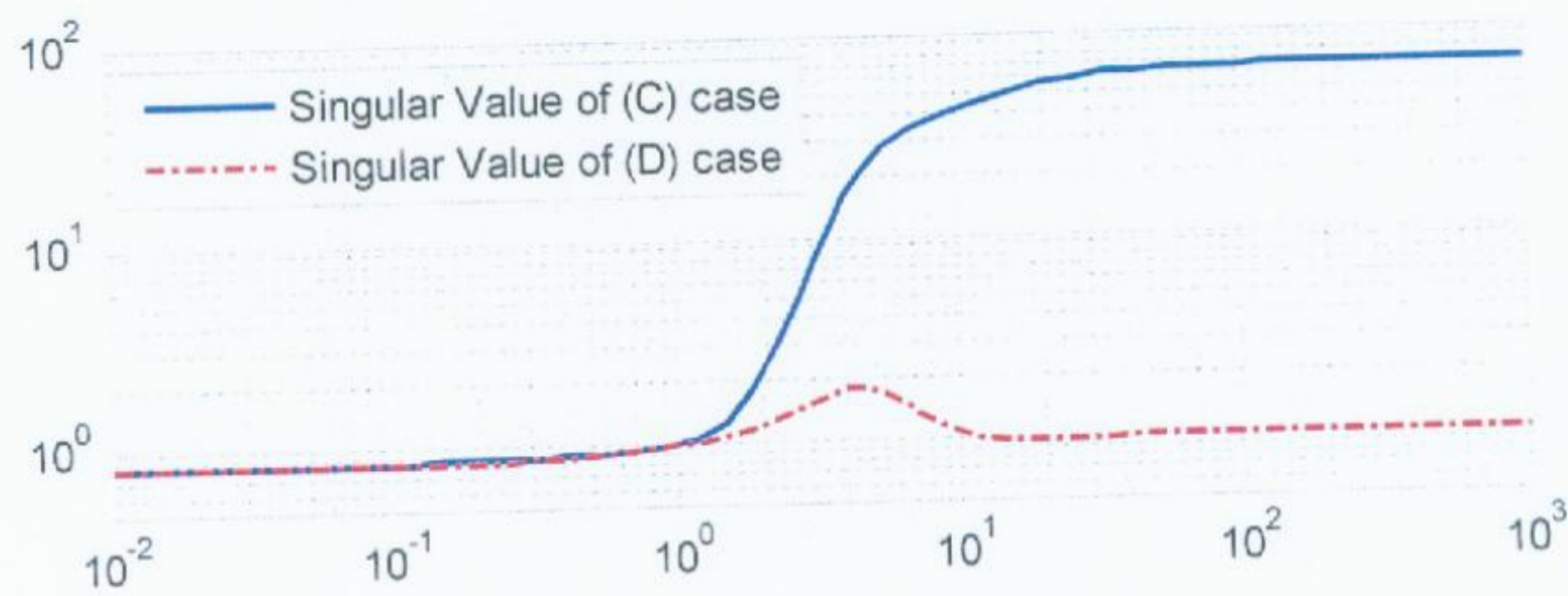
Why do (c) & (d) differ by a very wide margin?

- The test $\sqrt{\ln(C)}$ is based on full uncertainties rather than the structured uncertainties given in the problem.

- The test also allows dynamical uncertainties rather than the real uncertainties implied by the problem setting.

- (d) is less conservative by allowing $\alpha_1, \alpha_2, \beta_1, \beta_2$ to be freq-dependent and choosing them to minimize $\bar{\sigma}(\omega)$ for each freq ω .

(d) Compare the (b) case result with (d) case result



[Fig3. Maximum singular value]

Prob. 3. structured sing. val. of a dyadic matrix

$$M = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \end{pmatrix} [b_1 b_2 \dots] \quad a_i, b_j \in \mathbb{C}$$

with $\Delta = \text{diag}[\Delta_1, \Delta_2, \dots] \quad \Delta_i \in \mathbb{C}.$

is $\mu_\Delta(M) = \sum_i |a_i b_i|.$

Pf

$$\det(I - M\Delta) = \det(I - \overset{\text{col.}}{\downarrow} a \overset{\text{row}}{\leftarrow} b \Delta) = \det(I - b \Delta a)$$

$$\textcircled{1} = 1 - \sum_i a_i b_i \Delta_i$$

$$\geq 1 - \sum_i |a_i b_i| \max_i |\Delta_i| = 1 - \sum_i |a_i b_i| \bar{\sigma}(\Delta) \quad \textcircled{2}$$

To make $\textcircled{1} = 0$, we need at least $\textcircled{2} \leq 0$.

thus, $\bar{\sigma}(\Delta) \geq \frac{1}{\sum_i |a_i b_i|}$

Choose

$$\Delta = \frac{1}{\sum_i |a_i b_i|} \begin{bmatrix} \text{sgn}(a_1 b_1) & 0 & & \\ 0 & \text{sgn}(a_2 b_2) & & \\ & & \ddots & \\ & & & \ddots \end{bmatrix}$$

then

$$\bar{\sigma}(\Delta) = \frac{1}{\sum_i |a_i b_i|} \quad \text{and}$$

$$\textcircled{1} = 1 - \sum_j a_j b_j \Delta_j = 1 - \sum_j a_j b_j \frac{\text{sgn}(a_j b_j)}{\sum_i |a_i b_i|} = 0$$

\therefore The smallest Δ has $\bar{\sigma}(\Delta) = \frac{1}{\sum_i |a_i b_i|}$,

thus, $\mu_\Delta(M) = \sum_i |a_i b_i|.$

In prob 2,

$$H(j\omega) = \frac{\frac{1}{1+j\omega\theta_0}}{1+L_0(j\omega)} \begin{bmatrix} \beta_1 C(j\omega) \\ -\beta_2 \end{bmatrix} \begin{bmatrix} +\frac{\alpha_1}{\omega^2} & \alpha_2 j\omega \end{bmatrix}$$

↖ dyadic structure ↗

$$\Delta = \text{diag}[\Delta_s \quad \Delta_0]$$

$$\therefore M_\Delta(H) = \left| \frac{\frac{1}{1+j\omega\theta_0}}{1+L_0(j\omega)} \right| \left(\frac{\alpha_1 \beta_1}{\omega^2} |C(j\omega)| + \alpha_2 \beta_2 \omega \right)$$

= same as 2(d).