

Prob 4

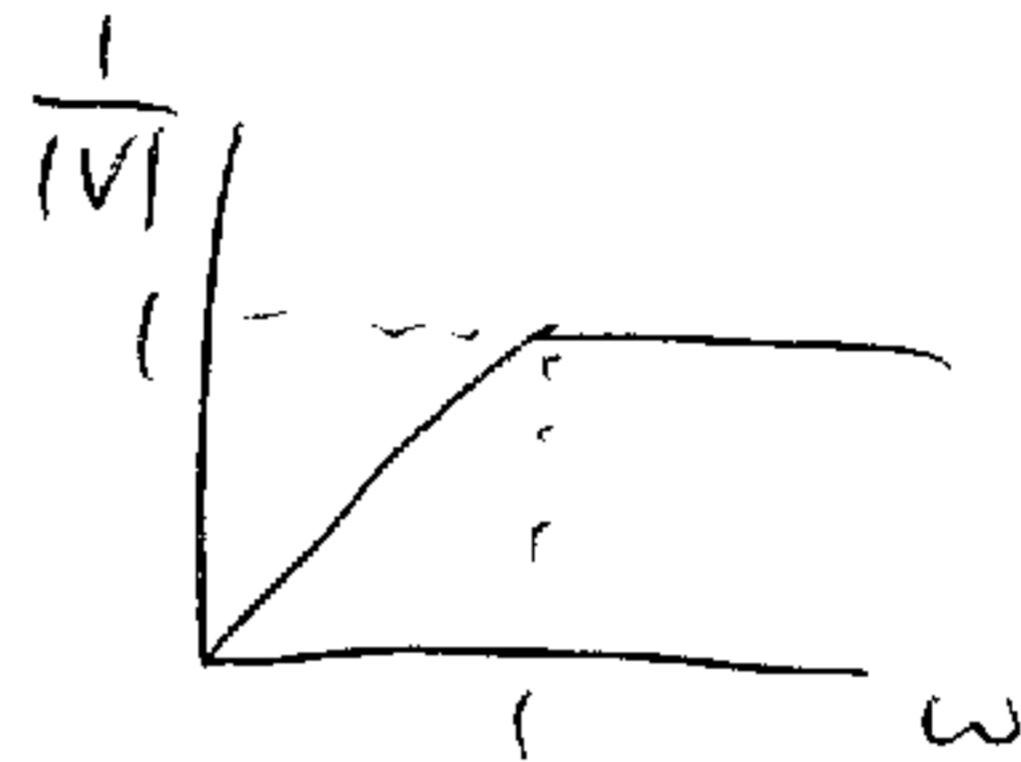
(b) If $|W_1 S V(j\omega)|^2 + |W_2 U V(j\omega)|^2 \approx \gamma^2$,

then $\underbrace{\text{dominates at low freq}}_{|W_1 S V(j\omega)|^2} + \underbrace{\text{dominates at high freq}}_{|W_2 U V(j\omega)|^2} \approx \gamma^2$
 $|S(j\omega)| \approx \frac{\gamma}{|W_1 V(j\omega)|}$ for ω small

$|U(j\omega)| \approx \frac{\gamma}{|W_2 V(j\omega)|}$ for ω large

In this example,

$|S(j\omega)| \approx \frac{\gamma}{|V(j\omega)|}$



↳ very good low freq behavior.

If $r=0$, then $W_2 = C$. $|U(j\omega)| \approx \frac{\gamma}{C |V(j\omega)|}$

↳ Controller $K \approx \text{const.}$ at high freq.

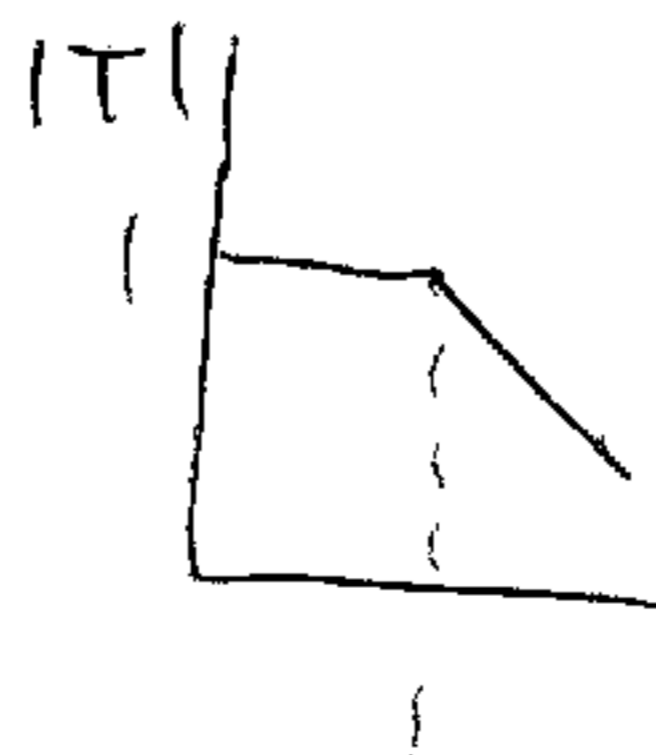
$|T| = |PK(I+PK)^{-1}| \approx \frac{\gamma}{C} \cdot \frac{1}{\omega^2}$ at high freq.

↳ rolls off at 40dB/decade.

If $r \neq 0$, then $W_2 \approx C\omega$ at high freq.

$|T| \approx \frac{\gamma}{C\omega} \cdot \frac{1}{\omega^2}$ at high freq

↳ rolls off at 60dB/decade.



CC)

Matlab Code

```

c = 0.1;
A = [ 0 0 ; 1 0 ];
B1 = [ 1 ; sqrt(2) ];
B2 = [ 1 ; 0 ];
C1 = [ 0 1 ; 0 0 ];
C2 = [ 0 -1 ];
D11 = [ 1 ; 0 ];
D12 = [ 0 ; c ];
D21 = -1;
D22 = zeros(1,1);

P = ss(A, [ B1 B2 ], [ C1 ; C2 ], [ D11 D12 ; D21 D22 ]);
sys = pck(A, [ B1 B2 ], [ C1 ; C2 ], [ D11 D12 ; D21 D22 ]);

[K,CL,GAM] = hinfsyn(P,1,1,0,2,0.01);

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다음은 위의 코드를 실행한 결과로, bisection algorithm 이 적용된 흔적이 볼수있다.

Resetting value of Gamma min based on D_11, D_12, D_21 terms

Test bounds: 1.0000 < gamma <= 2.0000

gamma	hamx_eig	xinf_eig	hamy_eig	yinf_eig	nrho_xy	p/f
2.000	2.4e+000	2.5e-001	7.1e-001	0.0e+000	0.0000	P
1.500	2.6e+000	2.8e-001	7.1e-001	-3.7e-017	0.0000	P
1.250	2.9e+000	<u>-8.4e+001#</u>	7.1e-001	0.0e+000	0.0000	(f)
1.375	2.7e+000	2.9e-001	7.1e-001	0.0e+000	0.0000	P
1.313	2.8e+000	3.0e-001	7.1e-001	0.0e+000	0.0000	P
1.281	2.8e+000	<u>-6.5e+002#</u>	7.1e-001	0.0e+000	0.0000	(f)
1.297	2.8e+000	3.0e-001	7.1e-001	0.0e+000	0.0000	P
1.289	2.8e+000	3.1e-001	7.1e-001	0.0e+000	0.0000	P

Gamma value achieved:

1.2891