

$$v_0 = \underline{v_0} \text{ m/s.}$$

$$v_A = 2.6 \hat{i} \text{ m/s.} \quad v_C = 4.5 \hat{i} \text{ m/s.}$$

$$a = 260 \text{ mm} \quad d = 150 \text{ mm.}$$

(a) conservation of linear momentum

$$m(\overline{v}_{A/G} + \overline{v}_0) + m(\overline{v}_{B/G} + \overline{v}_0) + m(\overline{v}_{C/G} + \overline{v}_0) = m\overline{v}_A + m\overline{v}_B + m\overline{v}_C$$

$$\underline{m(\overline{v}_{A/G} + \overline{v}_{B/G} + \overline{v}_{C/G} + 3\overline{v}_0)} = m\underline{v_A} + m\underline{v_B} + m\underline{v_C}$$

||
0 (same center rotation)
(same angle (120°))

$$3 \underline{v_0} = \underline{v_A} - \underline{v_B} + \underline{v_C}$$

$$= (\underline{v_A} - \underline{v_B}) \hat{j} + \underline{v_C} \hat{i}$$

$$v_A - v_B = 0 \quad v_B = v_A = \underline{2.6}$$

$$v_C = 3v_0 \quad v_0 = \frac{1}{3}v_C = \underline{\underline{1.5}},$$

$$\underline{\underline{v_0 = 1.5 \hat{i} \text{ m/s}}},$$

(b) conservation of angular momentum

$$3ml^2\omega \hat{k} = ma v_B \hat{k} + md v_C \hat{b} = m(0.26 \cdot 2.6 + (0.15) \cdot (4.5))$$

$$\underline{\underline{l^2\omega = 0.45033 \text{ m}^2/\text{s}}}$$

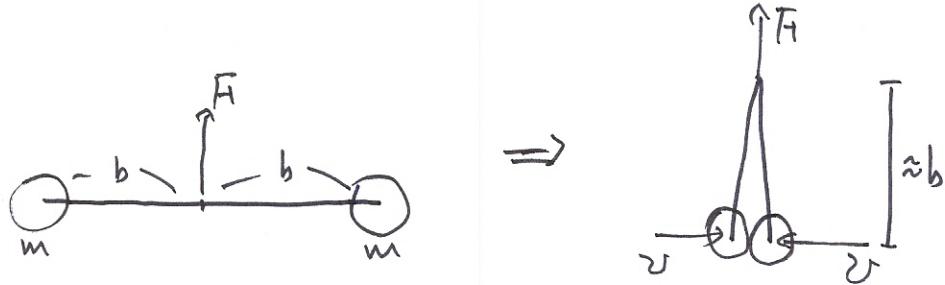
$$\left(\begin{array}{l} V_{A/G} = V_A - V_0 = 2.6j - 1.5i \\ V_{B/G} = V_B - V_0 = -2.6j - 1.5i \\ V_{C/G} = V_C - V_0 = 4.5i - 1.5j \end{array} \right)$$

$$|V_{A/G}| = \ell\omega = |2.6j - 1.5i| = 3 \text{ V/s.}$$

$$\therefore \ell = \frac{\ell \omega}{\ell \omega} = \frac{0.45033}{3} = \underline{\underline{0.1501 \text{ m.}}}$$

$$(c) \quad \omega = \frac{\ell \omega}{\ell} = \frac{3}{0.1501} = \underline{\underline{19.99 \text{ rad/s}}},$$

2.



- Energy conserve. ($\text{input} = \text{output}$)

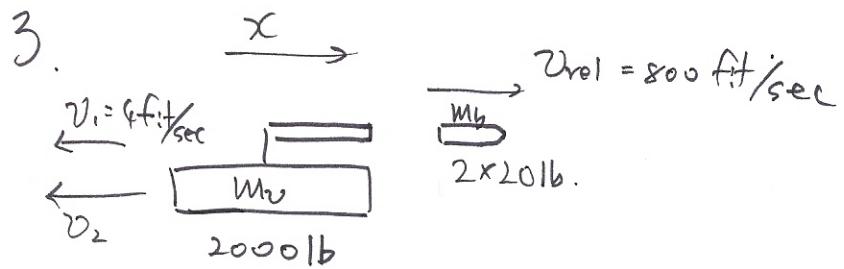
$$\begin{aligned} & \text{Initial State: } \theta = 0^\circ, v_0, F \text{ acts vertically upwards.} \\ & \Delta U = \Delta T \\ & Fb \sin \theta = \frac{1}{2}(2m)v^2 \end{aligned}$$

$$v = \sqrt{\frac{Fb}{m} \sin \theta}$$

$$v_{\theta=90^\circ} = \sqrt{\frac{Fb}{m}}$$

- $T_{\max} < 2mg$ (\because ball do not lose contact)

$$\begin{aligned} & \text{Final State: } \theta = 90^\circ, v = 0, F \text{ acts vertically upwards.} \\ & mg + mg = 0 \quad \therefore F - 2mg = 0 \\ & F = 2mg \end{aligned}$$



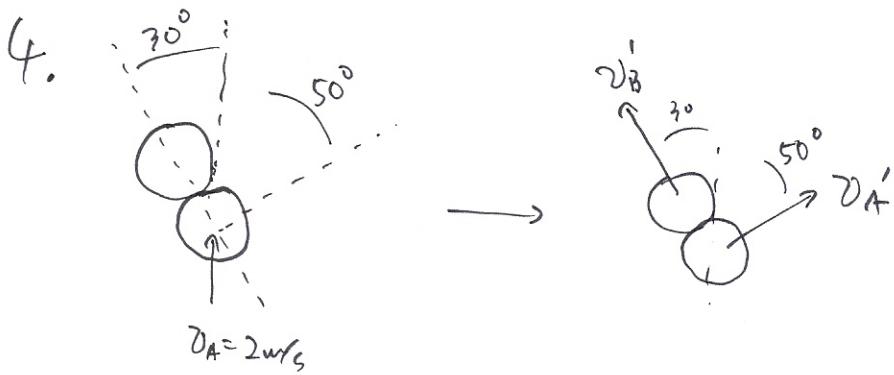
Linear momentum conserve (x -directn.)

$$(M_A + M_B) v_1 = M_A v_2 + M_B (v_{\text{rel}} + v_2)$$

$$\frac{1}{g} (2000 + 40)(-4) = \frac{1}{g} (2000(-v_2) + 40(800 - v_2))$$

$$2040v_2 = 32000 + 8160$$

$$\underline{\underline{v_2 = 19.69 \text{ ft/sec}}} \quad \uparrow$$



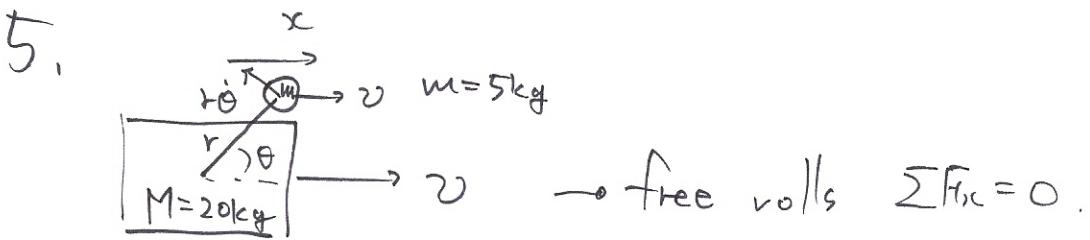
$$\sum F_{\text{nc}} = \sum F_y = 0$$

linear momentum conserve.

$$\rightarrow x \quad 0 = -M v_B' \sin 30 + M v_A \sin 50 \quad \dots \quad (1)$$

$$\uparrow y \quad M \cdot 2 = M v_B \cos 30 + M v_A \cos 50 \quad \dots \quad (2)$$

$$(1), (2) \rightarrow v_A = 1.015 \text{ m/s} \quad v_B = 1.556 \text{ m/s}$$



$$\dot{\Theta} = 4 \text{ rad/s}, \quad r = 0.4 \text{ m}.$$

linear momentum conserve (x-direction)

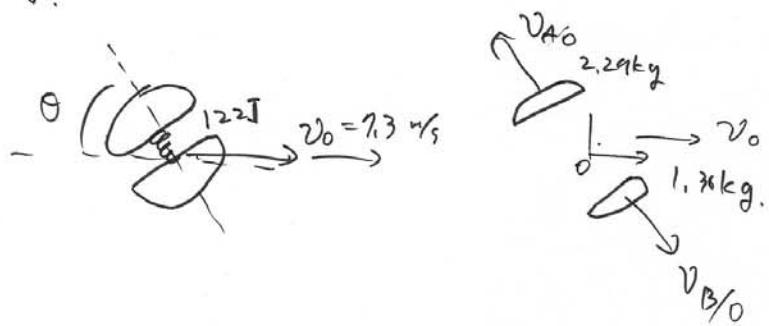
$$\Theta = 0 \quad \Theta = 60$$

$$(M+m)v_1 = Mv_2 + m(v - (r\dot{\Theta})\sin 60)$$

$$(25)(0.6) = 20 \cdot v_2 + 5(0.6 - 1.6 \sin 60)$$

$$v_2 = 0.877 \text{ m/s}$$

6.



momentum conserve.

$$(m_A + m_B) v_0 = m_A (v_{A0} \cos \theta + v_0) + m_B (v_{B0} \cos \theta + v_0)$$

$$\begin{aligned} v_{B0} &= -\frac{m_A}{m_B} v_{A0} \\ &= -\frac{2.29}{1.36} v_{A0}. \quad \dots \textcircled{1} \end{aligned}$$

energy conserve.

in moving frame. ($\uparrow \rightarrow v_0 = 7.3$)

$$122 = \frac{1}{2} m_A v_{A0}^2 + \frac{1}{2} m_B v_{B0}^2 \quad \dots \textcircled{2}$$

$$\textcircled{1}, \textcircled{2} \quad \left(\frac{2.29}{2} + \frac{1.36}{2} \left(\frac{2.29}{1.36} \right)^2 \right) v_{A0}^2 = 122$$

$$v_{A0} = 6.346 \text{ m/s}$$

$$|v_A| = \left((v_{A0} \cos \theta + v_0)^2 + (v_{A0} \sin \theta)^2 \right)^{1/2}$$

$$|v_B| = \left((v_{B0} \cos \theta + v_0)^2 + (-v_{B0} \sin \theta)^2 \right)^{1/2}$$

Source code

```
theta=(30/180)*pi:0.01:(120/180)*pi;
ang=theta*180/pi;

va = (122/(2.27/2 + 2.27^2/(2*1.36)))^(1/2);
vb = (va*2.27)/1.36;

Va = ((-va.*cos(theta)+7.3).^2 + (va.*sin(theta)).^2).^(1/2);
Vb = ((vb.*cos(theta)+7.3).^2 + (-vb.*sin(theta)).^2).^(1/2);
V(:,1) =Va;
V(:,2) =Vb;

plot(ang,V);
```

