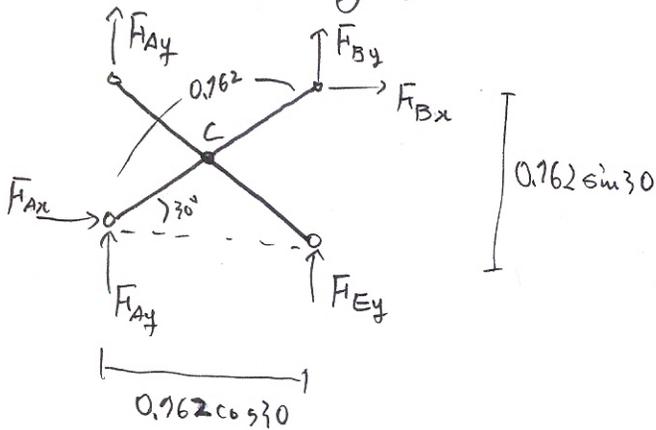


# Hw #7 solution

## 1. FBD (linkage)



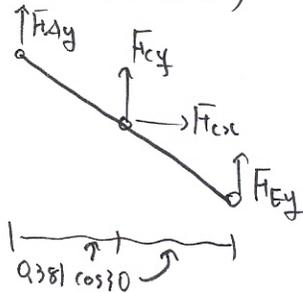
$$\sum M_D = 0$$

$$(F_{By} + F_{Ey})(0.162 \cos 30)$$

$$- F_{Bx}(0.162 \sin 30) = 0$$

$$(F_{By} + F_{Ey}) \cos 30 - F_{Bx} \sin 30 = 0 \dots \textcircled{1}$$

## FBD (ACE)



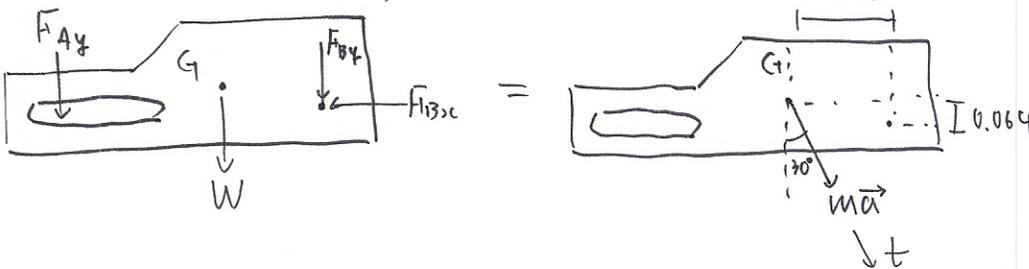
$$\sum M_c = 0$$

$$-F_{Ay}(0.381 \cos 30) + F_{Ey}(0.381 \cos 30) = 0$$

$$F_{Ay} = F_{Ey} \dots \textcircled{2}$$

$$\textcircled{1}, \textcircled{2} \rightarrow (F_{By} + F_{Ay}) \cos 30 - F_{Bx} \sin 30 = 0 \dots \textcircled{3}$$

## FBD (AB part)



$$(a) \sum F_t - \sum F_{eff}:$$

$$(F_{By} + F_{Ay}) \cos 30 - F_{By} \sin 30 + W \cos 30 = ma$$

$$\textcircled{3} = 0$$

$$\therefore a = \frac{W}{m} \cos 30 = g \cos 30 = 8.5 \text{ m/s}^2 \quad \text{A}$$

$$(b) \quad \sum \uparrow M_B = \sum (M_B)_{\text{eff}}$$

$$W(0.191) + F_{Ay}(0.762)\cos 30 = (m\bar{a}\sin 60)(0.191) - ma(\cos 60)(0.064)$$

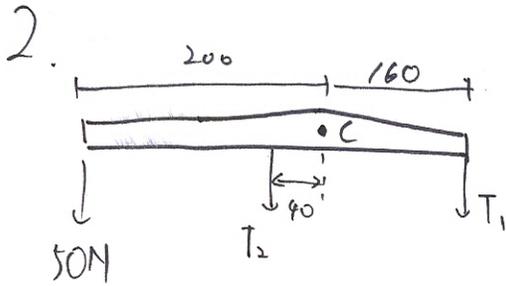
$$ma = W\cos 30 \quad \dots (a)$$

$$0.191W + 0.762F_{Ay}\cos 30 = W\cos 30(0.191)\sin 60 - 0.064\cos 60$$

$$F_{Ay} = \frac{-0.191}{0.762\cos 30}W + \frac{W}{0.762}(0.191\sin 60 - 0.064\cos 60)$$

$$= -10.1\text{ N} \quad (W = 88.3\text{ N})$$

$$\therefore \underline{\underline{F_{Ay} = 10.1\text{ N} \uparrow}}$$



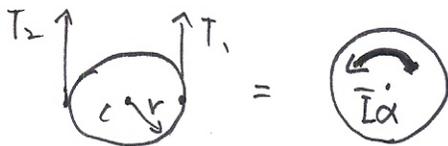
moment equilibrium

$$\sum M_c = 0$$

$$50(0.2) + T_2(0.04) - T_1(0.16) = 0$$

$$4T_1 - T_2 = 250 \quad \dots \textcircled{1}$$

FBD (wheel)



E<sub>a</sub> of motion

$$\begin{aligned} \bar{I} &= m k^2 = 300 (0.6)^2 \\ &= 108 \text{ kg} \cdot \text{m}^2 \end{aligned}$$

$$\sum M_c = T_1 r - T_2 r = \bar{I} \alpha$$

$$T_1 - T_2 = \frac{108 \alpha}{0.1}$$

$$\alpha = 925.9 \times 10^{-6} (T_1 - T_2) \quad \dots \textcircled{2}$$

o Belt friction

$$\frac{T_2}{T_1} = e^{\mu \theta} \quad T_2 = T_1 e^{\mu \theta}$$

$$\mu_k = 0.3 \quad \theta = \pi$$

$$T_2 = 2.663 T_1 \quad \dots \textcircled{3}$$

$$\textcircled{1}, \textcircled{3} \quad 4T_1 - T_2 = 250$$

$$4T_1 - 2,566T_1 = 250$$

$$T_1 = 174,38 \quad T_2 = 447,51 \text{ N}$$

$$\textcircled{2} \rightarrow \alpha = 925,9 \times 10^{-6} (174,38 - 447,51) \\ = -0,2529 \text{ rad/s}^2$$

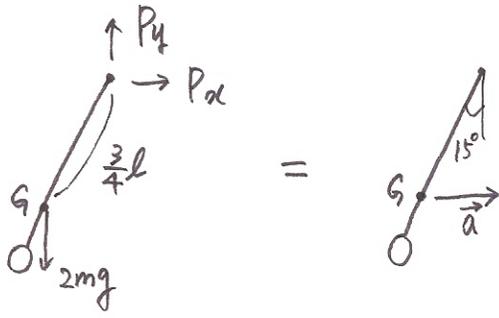
$$\omega_0 = 180 \text{ rpm} = 18,850 \text{ rad/s} \curvearrowright$$

$$\alpha = 0,2529 \text{ rad/s}^2 \curvearrowleft$$

$$\omega = \omega_0 + \alpha t \Rightarrow 0 = 18,850 - 0,2529 t$$

$$t = \underline{\underline{14,5 \text{ s}}}$$

3.

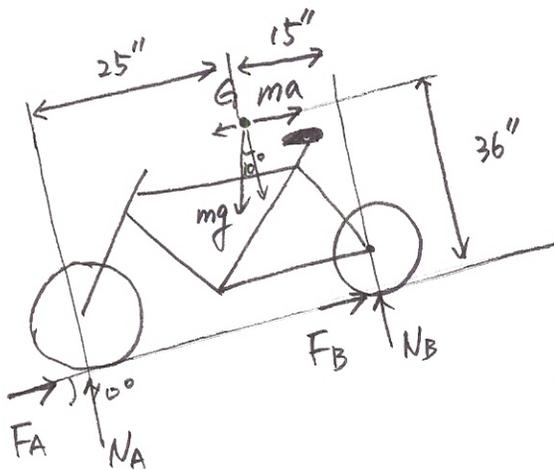


$$\curvearrowright \sum M_p = 2mg \sin 15^\circ \times \frac{3}{4}l = 2ma \cos 15^\circ \times \frac{3}{4}l$$

$$a = g \tan 15^\circ$$

$$= 0.268 g.$$

4.



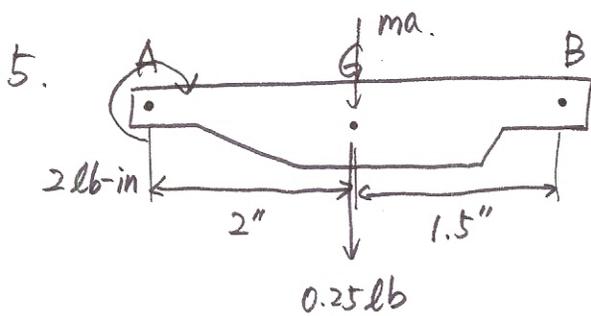
Tipping at front wheel:  $N_B$  &  $F_B \rightarrow 0$ .

$$\curvearrowright \sum M_A = mad.$$

$$mg (25 \cos 15^\circ - 36 \sin 10^\circ) = ma \times 36$$

$$a = 0.51 g$$

$$= 16.43 \text{ ft/sec}^2 \quad (\because g = 32.2 \text{ ft/sec}^2)$$



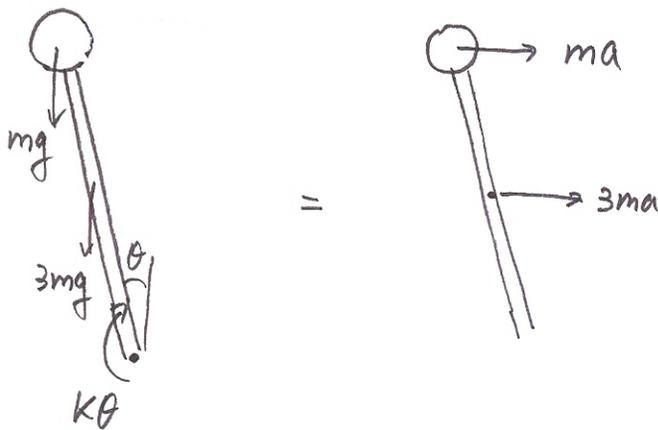
$$\Sigma M_A = ma d.$$

$$2 + 0.25 \times 2 = \frac{0.25}{32.2 \times 12} \times 2 \times a \quad (\because 1 \text{ ft} = 12 \text{ inch})$$

$$a = 1932 \text{ inch/sec}^2$$

$$= 161 \text{ ft/sec}^2$$

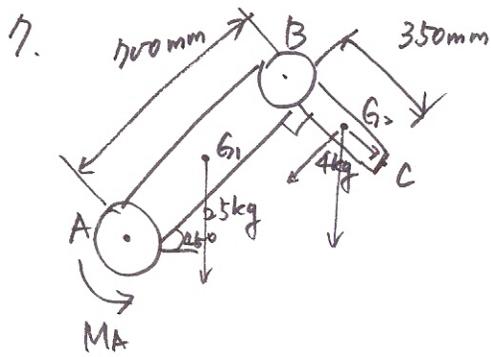
6.  $a = 2g$      $m = 0.5 \text{ kg}$      $l = 0.6 \text{ m}$      $\theta = 20^\circ$



$$\textcircled{+} \Sigma M_o \quad K\theta - 3mg \sin\theta \frac{l}{2} - mg \sin\theta l = 3ma \cos\theta \frac{l}{2} + ma \cos\theta l$$

$$K\theta - \frac{5}{2} mgl \sin\theta = \frac{5}{2} mal \cos\theta$$

$$\therefore K = 46.8 \text{ N}\cdot\text{m/rad}.$$



$$\begin{aligned}
 I_B &= \frac{1}{12} m_{BC} L_{BC}^2 + m_{BC} d^2 \quad (d = \frac{1}{2} L_{BC}) \\
 &= \frac{1}{3} m_{BC} L_{BC}^2 \\
 &= \frac{1}{3} \times 4 \times 0.35^2 \\
 &= 0.1633 \text{ kg} \cdot \text{m}^2
 \end{aligned}$$

$$\begin{aligned}
 I_A &= \frac{1}{3} m_{AB} L_{AB}^2 + \frac{1}{12} m_{BC} L_{BC}^2 + m_{BC} \left\{ L_{AB}^2 + \left( \frac{L_{BC}}{2} \right)^2 \right\} \\
 &= \frac{1}{3} \times 2.5 \times 0.7^2 + \frac{1}{12} \times 4 \times 0.35^2 + 4 (0.7^2 + 0.175^2) \\
 &= 6.21 \text{ kg} \cdot \text{m}^2
 \end{aligned}$$

$$\sum M_A = I_A \alpha$$

$$\begin{aligned}
 M_A - m_{AB} g \times \cos 45^\circ \times \frac{L_{AB}}{2} - m_{BC} g \cos 45^\circ \left( L_{AB} + \frac{L_{BC}}{2} \right) \\
 = I_A \alpha
 \end{aligned}$$

$$\begin{aligned}
 M_A - 2.5 \times 9.81 \times \cos 45^\circ \times 0.35 - 4 \times 9.81 \times \cos 45^\circ (0.7 + 0.175) \\
 = 6.21 \times \alpha
 \end{aligned}$$

$$\therefore M_A = 109.8 \text{ N} \cdot \text{m}$$



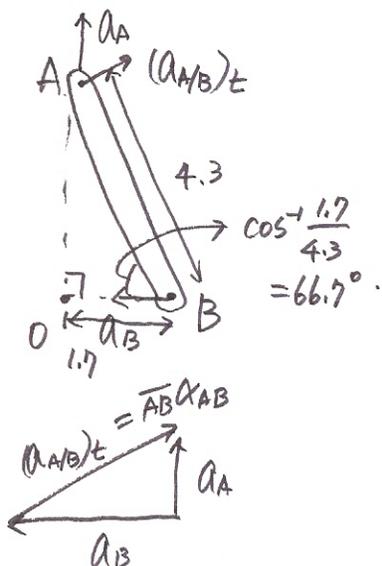
$$\sum M_B = I_B \alpha$$

$$M_B - 4 \times 9.81 \times 0.175 \times \cos 45^\circ = 0.1633 \times \alpha$$

$$\therefore M_B = 5.51 \text{ N} \cdot \text{m}$$

8. engine weight 1.2 lb.

radius of gyration about G 1.12 in.



$$a_A = a_B + (a_{A/B})_t$$

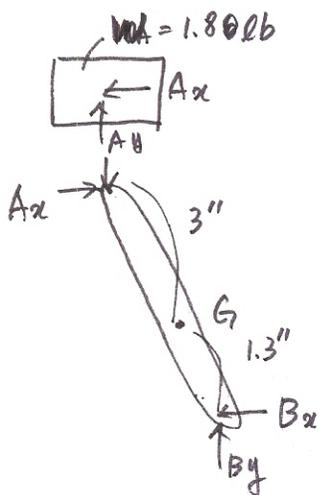
$$(a_{A/B})_n = \bar{AB} \omega_{AB}^2 = 0$$

$$\begin{aligned} a_B &= r \omega^2 \\ &= \frac{1.7}{12} (100\pi)^2 \\ &= 13.98 \times 10^3 \text{ ft/sec}^2 \end{aligned}$$

$$\begin{aligned} (a_{A/B})_t &= \frac{a_B}{\sin 66.7^\circ} \\ &= 15.22 \times 10^3 \text{ ft/sec}^2 \end{aligned}$$

$$\therefore \alpha_{AB} = \frac{15.22 \times 10^3}{4.3/12} = 42.5 \times 10^3 \text{ rad/sec}^2 \curvearrowright$$

$$\begin{aligned} a_A &= 13.98 \times 10^3 / \tan 66.7^\circ \\ &= 6.02 \times 10^3 \text{ ft/sec}^2 \end{aligned}$$



$$\sum F_y = m a_y \quad A_y = \frac{1.80}{32.2} \times 6.02 \times 10^3 = 336 \text{ lb.}$$

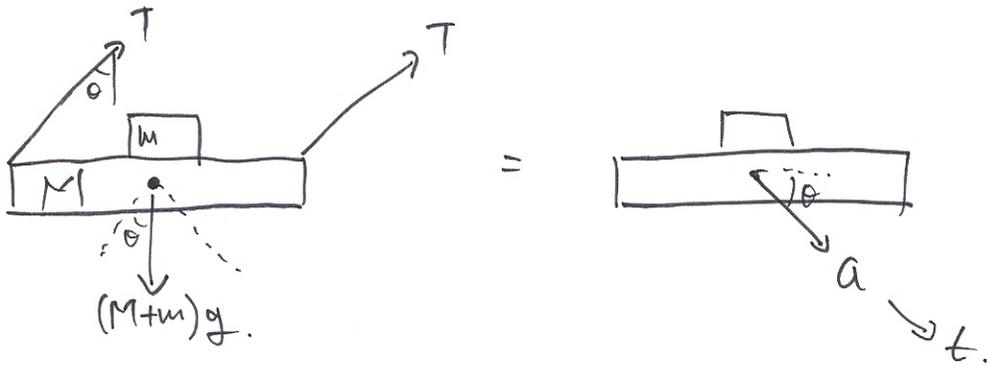
$$\sum M_B = I_B \alpha + \vec{r} \times m \vec{a}_B$$

$$336 \times 1.7 - A_x \times 3.95 = \frac{1.20}{32.2 \times 12} [1.12^2 + 1.3^2] (-42.5) \times 10^3$$

$$+ 1.3 \times \frac{1.20}{32.2 \times 12} (13.98) \times 10^3 \times 12 \times \sin 66.7^\circ$$

$$\therefore A_x = 85.6 \text{ lb} \quad A = 347 \text{ lb.}$$

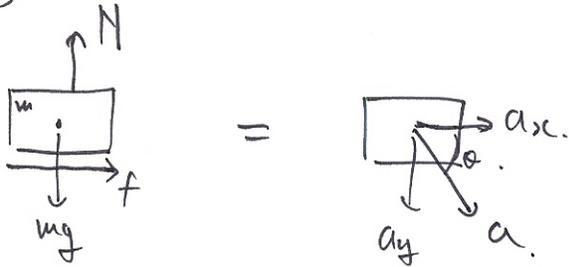
9.



$$\Sigma F_t : (M+m)g \sin \theta = (M+m)a$$

$$a = g \sin \theta \quad a_y = g \sin^2 \theta \quad a_x = g \sin \theta \cos \theta$$

no slip



$$\Sigma F_y : N - mg = -ma_y$$

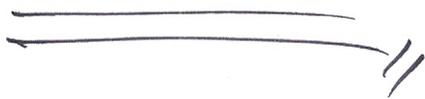
$$N = m(g - a_y) = mg(1 - \sin^2 \theta) = mg \cos^2 \theta$$

$$\Sigma F_x : f = ma_x$$

$$\mu N = ma_x$$

$$\mu mg \cos^2 \theta = mg \sin \theta \cos \theta$$

$$\mu = \frac{\sin \theta}{\cos \theta}$$



```
ang=0:0.01:40*pi/180;  
mu = sin(ang)./cos(ang);  
deg=ang*180/pi;  
plot(deg,mu);  
xlabel('ang'); ylabel('friction coef.');
```

