System Analysis in Mechanical & Aerospace Engineering 2009

HW #6. Due 5/07 PM 8:00

1. For the pneumatic system shown in Figure 1, assume that the steady-state values of the air pressure and the displacement of the bellows are \overline{P} and \overline{X} , respectively. Assume also that the input pressure is changed from \overline{P} to $\overline{P} + p_i$, where p_i is small. This change will cause the displacement of the bellows to change a small amount x. Assuming that the capacitance of the bellows is C and the resistance of the valve is R, obtain the transfer function relation x and p_i



2. Consider the conical water tank system shown in Figure 2. The flow through the valve is turbulent and is related to the head H by

$$Q = 0.0005\sqrt{H}$$

Where Q is the flow rate measured in m^3/s and H is in meters. Suppose that the head is 2 m at t = 0. What will be the head at t = 60s?



Fig. 2

3. Figure 3. Shows a liquid-level system with a pump input and a drain whose linear resistance is R₂. The inlet from the pump to the tank has a linear resistance R₁. Obtain a linearized model of the liquid height h



(a) Develop a model of the two liquid heights in the system shown in Figure 4. The inflow rate q_{mi}(t) is a mass flow rate. (b) Using the values R₁=R, R₂=3R, A₁=A, A₂=4A, find the transfer function H₂(s)/Q_{mi}(s)



5. An electric motor is sometimes used to move the spool valve of a hydraulic motor. In Figure 5. The force f is due to and electric motor acting through a rack-and-pinion gear. Develop a model of the system with the load displacement y as the output and the force f as the input. Consider two cases: (a)m₁ = 0 and (b)m₁ ≠ 0

