

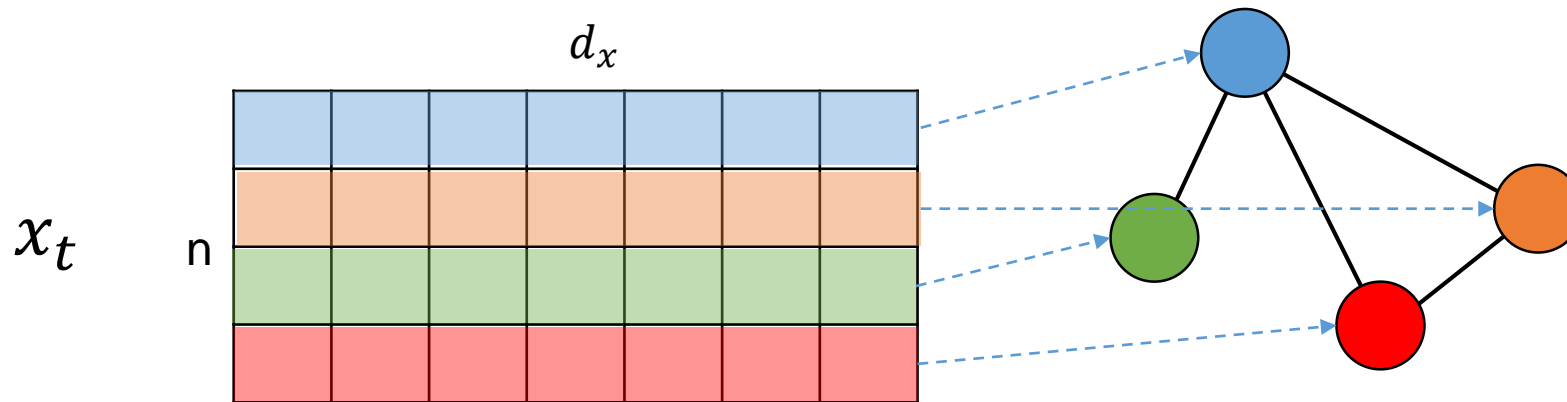
Structured Sequence Modeling With Graph Convolutional Recurrent Networks

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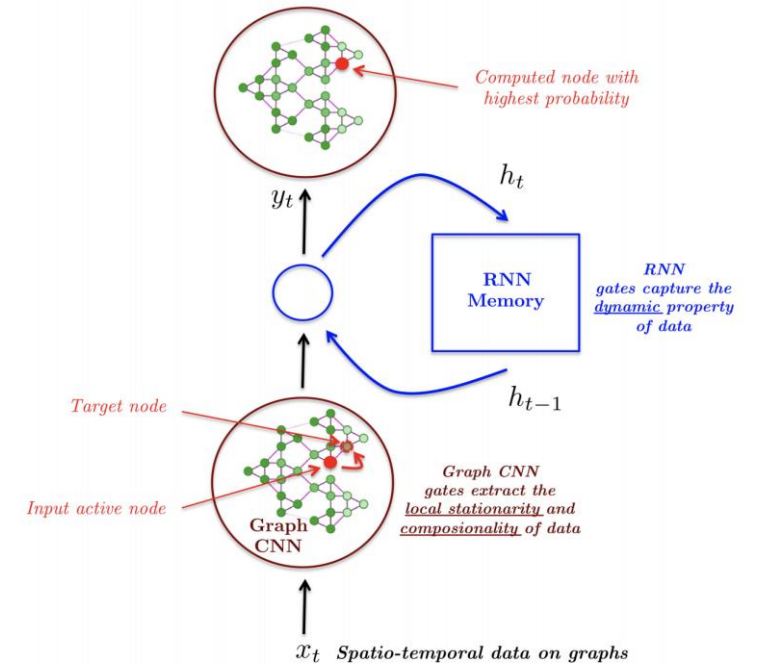
Objective of Research

- How to deal with **structured sequence** data?
- Spatio-temporal sequences
 - $\hat{x}_{t+1}, \dots, \hat{x}_{t+K} = \operatorname{argmax}_{x_{t+1}, \dots, x_{t+K}} P(x_{t+1}, \dots, x_{t+K} | x_{t-J+1}, \dots, x_t)$
 - Consider data x_t as a graph signal : features are linked by pairwise relationship



Proposed Models : GCRN

- Graph Convolutional Recurrent Network (GCRN)
- Main idea
 - Use Graph CNN **and** RNN
 - Graph CNN : Identify spatial structures
 - RNN : Find dynamic patterns
- Model 1 : Stack a graph CNN on an LSTM



Graph CNN

$$x_t^{\text{CNN}} = \text{CNN}_{\mathcal{G}}(x_t)$$

LSTM

$$\begin{aligned} i &= \sigma(W_{xi}x_t^{\text{CNN}} + W_{hi}h_{t-1} + w_{ci} \odot c_{t-1} + b_i), \\ f &= \sigma(W_{xf}x_t^{\text{CNN}} + W_{hf}h_{t-1} + w_{cf} \odot c_{t-1} + b_f), \\ c_t &= f_t \odot c_{t-1} + i_t \odot \tanh(W_{xc}x_t^{\text{CNN}} + W_{hc}h_{t-1} + b_c), \\ o &= \sigma(W_{xo}x_t^{\text{CNN}} + W_{ho}h_{t-1} + w_{co} \odot c_t + b_o), \\ h_t &= o \odot \tanh(c_t). \end{aligned}$$

Graph filtering operation

$$y = g_{\theta} *_{\mathcal{G}} x = g_{\theta}(L)x = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{L})x,$$

θ : Chebyshev coefficients

$T_k(\tilde{L})$: Chebyshev polynomial of order k

Proposed Models : GCRN

- Model 2 : Generalize the convLSTM model to graphs

$$\begin{aligned} i &= \sigma(W_{xi} *_{\mathcal{G}} x_t + W_{hi} *_{\mathcal{G}} h_{t-1} + w_{ci} \odot c_{t-1} + b_i), \\ f &= \sigma(W_{xf} *_{\mathcal{G}} x_t + W_{hf} *_{\mathcal{G}} h_{t-1} + w_{cf} \odot c_{t-1} + b_f), \\ c_t &= f_t \odot c_{t-1} + i_t \odot \tanh(W_{xc} *_{\mathcal{G}} x_t + W_{hc} *_{\mathcal{G}} h_{t-1} + b_c), \\ o &= \sigma(W_{xo} *_{\mathcal{G}} x_t + W_{ho} *_{\mathcal{G}} h_{t-1} + w_{co} \odot c_t + b_o), \\ h_t &= o \odot \tanh(c_t). \end{aligned}$$

$$W_{xi}x_t$$



$$W_{xi} * x_t$$



$$W_{xi} *_{\mathcal{G}} x_t$$

Classic LSTM : matrix multiplication by dense matrix W

convLSTM : Replace multiplication by 2D convolution($*$) by a set of kernels (Shi et al.(2015))

GCRN : Replace 2D convolution by the graph convolution($*_{\mathcal{G}}$)