

Spatial-aware Graph Relation Network for Large-scale Object Detection

CVPR 2019

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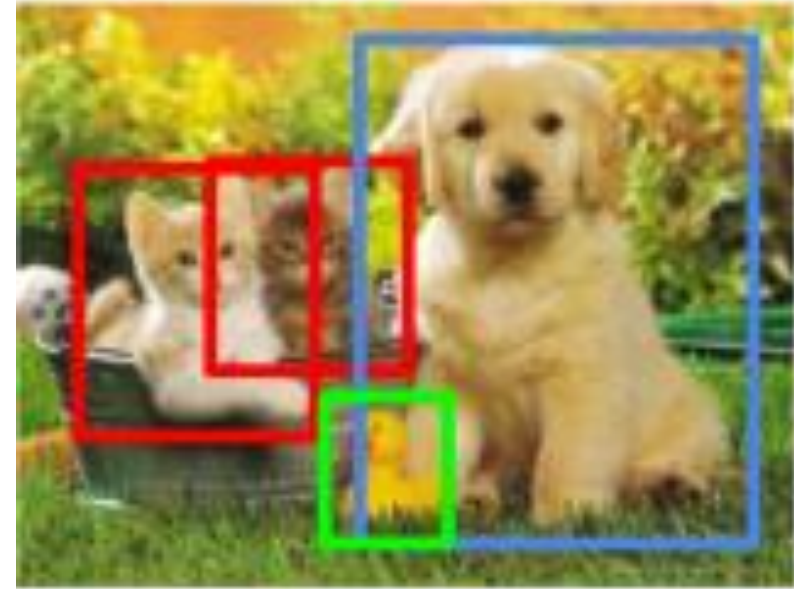
Problem

- Object Detection

- A computer technology related to computer vision and image processing that deals with detecting instances of semantic objects of a certain class
- Dataset : MS COCO (80 classes), VOC (20 classes)

- Large Scale Object Detection

- Recognize **thousands of objects** entangled with complex spatial and semantic relationships
- Dataset : VisualGenome (**3000** classes), ADE (**455** classes)



CAT, DOG, DUCK

Key Idea

- Using graph to discover and incorporate key semantic and spatial relationships over each object.
- Inject module into existing detection pipelines to boost the performance.



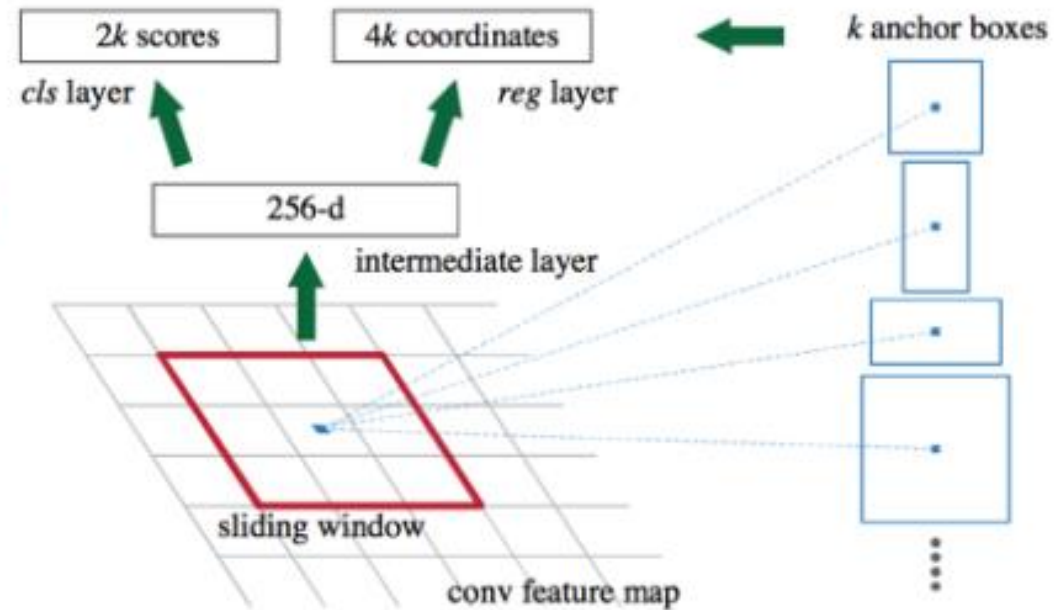
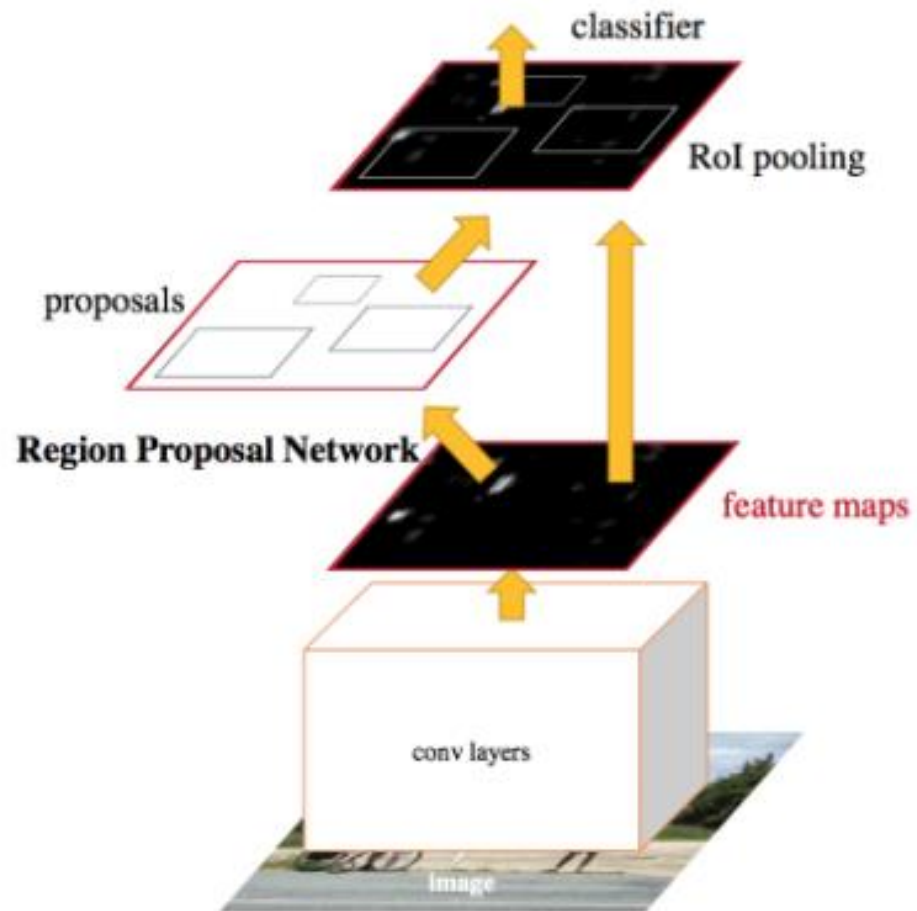
Input Image



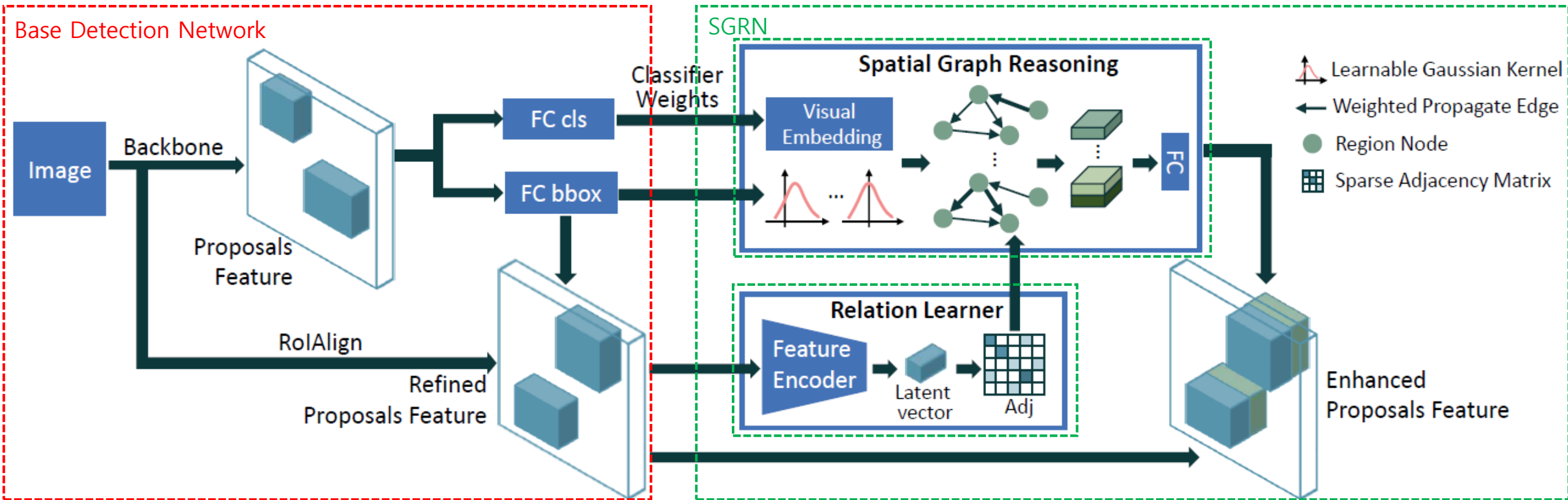
Spatial-aware Sparse Graph

Two Stage Object Detection

- Region Proposal Network + Classifier, Box Regression
- Faster R-CNN



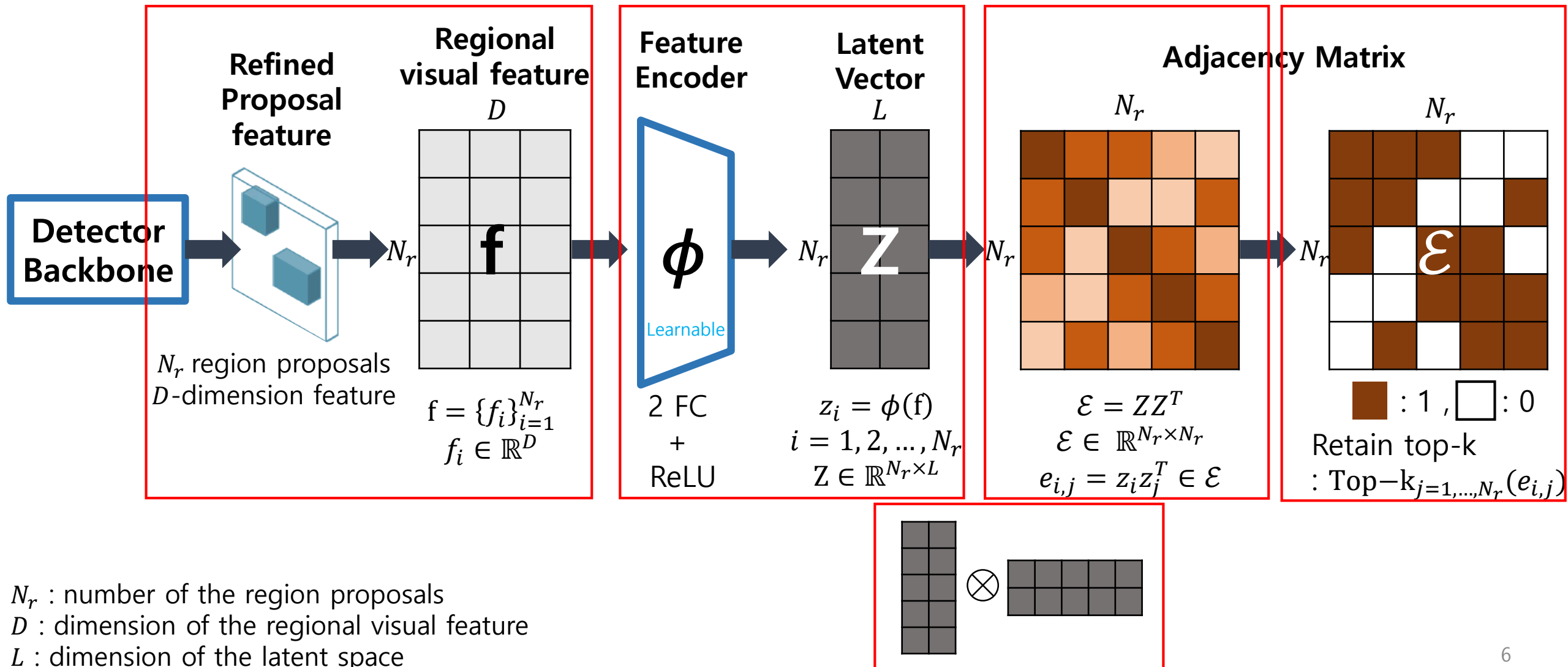
Spatial-aware Graph Relation Network



- Relation Learner
 - Learn a interpretable sparse graph structure
- Spatial Graph Reasoning
 - Graph inference with spatial awareness

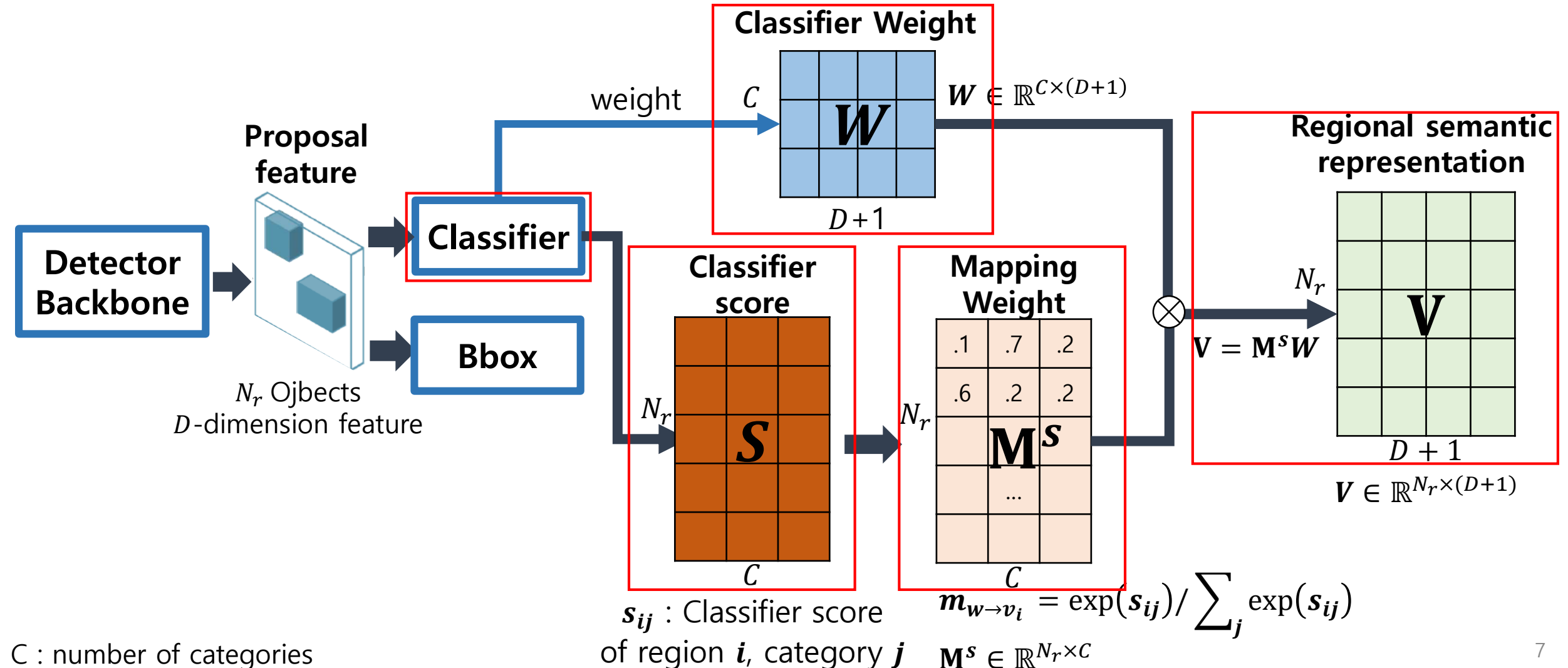
Relation Learner Module

- Learn graph structure from regional visual feature



Node Feature Embedding of the Regions

- Convert classifier weight to regional semantic representation



Spatial-aware Graph Reasoning Module

- Node Feature Propagation with Spatial Gaussian
 - Relative position of node j from node i : $u(i, j) = (d, \theta)$

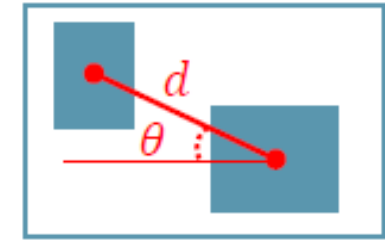
- k-th Gaussian kernel

$$w_k(u(i, j)) = \exp\left(-\frac{1}{2}(u(i, j) - \mu_k)^T \Sigma_k^{-1}(u(i, j) - \mu_k)\right)$$

μ_k : 2×1 mean vector, Σ_k : 2×2 covariance matrix

- Weighted sum feature data from connected nodes

$$f'_k(i) = \sum_{j \in \text{Neighbour}(i)} w_k(u(i, j)) v_j e_{ij}$$



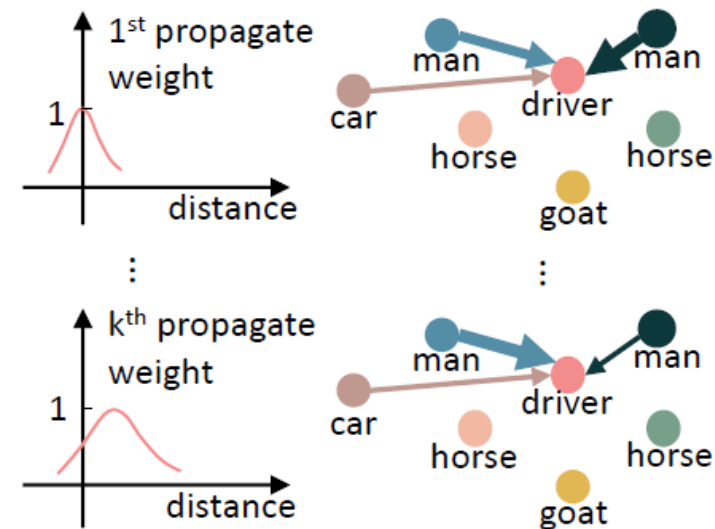
$$d = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$$

$$\theta = \arctan\left(\frac{y_j - y_i}{x_j - x_i}\right)$$

Pseudo-coordinate function



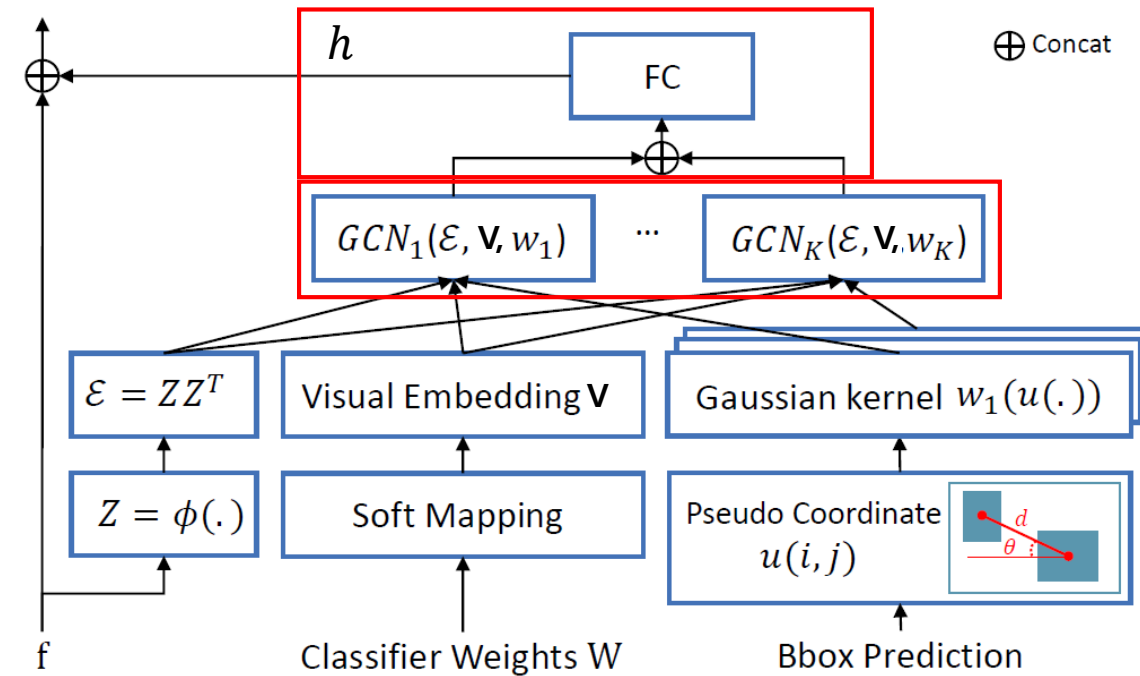
Spatial-aware Sparse Graph



Propagation with Gaussian Kernels

Spatial-aware Graph Reasoning Module

- GCN : $GCN_k(\varepsilon, V, w_k)$
 - ε : Adjacency Matrix from Region Proposal Feature
 - V : Node Representation from Classifier
 - w_k : k-th Gaussian kernel using relative spatial information
- Enhanced Feature : $h_i = L[f'(i)]$
 - Fully Connected Layer : $L \in \mathbb{R}^{E \times (D+1)}$
 E : dimension of the output enhanced feature
 - h_i is concatenated to f_i
 (Improve classification and localization)



Flowchart of the Spatial-aware Graph Reasoning Module

Experiments

%	Method	AP	AP ₅₀	AP ₇₅	AP _S	AP _M	AP _L	AR ₁	AR ₁₀	AR ₁₀₀	AR _S	AR _M	AR _L
VG ₁₀₀₀	Light-head RCNN[28]	6.2	10.9	6.2	2.8	6.5	9.8	14.6	18.0	18.7	7.2	17.1	25.3
	Cascade RCNN[4]	6.5	12.1	6.1	2.4	6.9	11.2	15.3	19.4	19.5	6.1	19.2	27.5
	HKRM[23]	7.8	13.4	8.1	4.1	8.1	12.7	18.1	22.7	22.7	9.6	20.8	31.4
	Faster-RCNN[45]	5.7	9.9	5.8	2.7	6.9	8.9	13.8	17.0	17.0	6.6	15.8	23.5
	Faster-RCNN w SGRN	6.8 ^{+1.1}	11.1 ^{+1.2}	7.1 ^{+1.3}	3.3 ^{+0.6}	7.0 ^{+0.1}	10.8 ^{+1.9}	15.3 ^{+1.5}	19.5 ^{+2.5}	19.6 ^{+2.6}	8.3 ^{+1.7}	17.8 ^{+2.0}	26.7 ^{+3.2}
	FPN[30]	7.1	12.9	7.3	4.2	7.9	10.7	14.9	19.8	20.0	11.1	19.3	23.6
	FPN w SGRN	8.1 ^{+0.9}	13.6 ^{+0.7}	8.4 ^{+1.1}	4.4 ^{+0.2}	8.2 ^{+0.3}	12.8 ^{+2.1}	19.5 ^{+4.6}	26.0 ^{+6.2}	26.2 ^{+6.2}	12.4 ^{+1.3}	23.9 ^{+4.6}	34.0 ^{+10.4}
VG ₃₀₀₀	Light-head RCNN[28]	3.0	5.1	3.2	1.7	4.0	5.8	7.3	9.0	9.0	4.3	10.3	15.4
	Cascade RCNN[4]	3.8	6.5	3.4	1.9	4.8	4.9	7.1	8.5	8.6	4.2	9.9	13.7
	HKRM[23]	4.3	7.2	4.4	2.6	5.5	8.4	10.1	12.2	12.2	5.9	13.0	20.5
	Faster-RCNN[45]	2.6	4.4	2.7	1.7	3.6	4.8	6.2	7.6	7.6	4.3	9.1	12.9
	Faster-RCNN w SGRN	3.2 ^{+0.6}	5.0 ^{+0.6}	3.4 ^{+1.3}	2.0 ^{+0.3}	4.2 ^{+0.6}	6.5 ^{+1.7}	7.3 ^{+0.9}	9.2 ^{+1.6}	9.2 ^{+1.6}	4.9 ^{+0.6}	11.4 ^{+1.7}	16.2 ^{+3.3}
	FPN[30]	3.4	6.1	3.4	2.6	4.8	6.3	6.9	9.1	9.1	6.7	11.5	13.4
	FPN w SGRN	4.5 ^{+1.1}	7.4 ^{+1.3}	4.3 ^{+1.0}	2.9 ^{+0.3}	6.0 ^{+1.2}	8.6 ^{+2.3}	10.8 ^{+3.9}	13.7 ^{+4.6}	13.8 ^{+4.7}	8.1 ^{+1.4}	15.1 ^{+3.6}	21.8 ^{+8.4}
ADE	Light-head RCNN[28]	7.0	11.7	7.3	2.4	5.1	11.2	9.6	13.3	13.4	4.3	10.4	20.4
	Cascade RCNN[4]	9.1	16.8	8.9	3.5	7.1	15.3	12.1	16.4	16.6	6.4	13.8	25.8
	HKRM[23]	10.3	18.0	10.4	4.1	7.8	16.8	13.6	18.3	18.5	7.1	15.5	28.4
	Faster-RCNN[45]	6.9	12.8	6.8	3.1	6.4	12.3	9.3	13.3	13.6	7.9	13.4	20.5
	Faster-RCNN w SGRN	9.5 ^{+2.6}	15.3 ^{+2.5}	10.1 ^{+3.3}	4.9 ^{+1.8}	8.4 ^{+2.0}	16.0 ^{+3.7}	12.5 ^{+3.2}	17.6 ^{+4.3}	17.7 ^{+4.1}	8.4 ^{+0.5}	16.0 ^{+2.6}	27.3 ^{+6.8}
	FPN[30]	10.9	21.0	12.0	7.3	12.1	18.4	13.5	20.3	20.9	13.3	21.9	29.0
	FPN w SGRN	14.0 ^{+3.1}	23.1 ^{+2.1}	14.8 ^{+2.8}	8.1 ^{+0.8}	13.7 ^{+1.6}	21.4 ^{+3.0}	16.5 ^{+3.0}	25.5 ^{+5.2}	26.2 ^{+5.3}	17.7 ^{+4.4}	27.5 ^{+5.6}	35.3 ^{+6.3}

Table 1. Main results of test datasets on VG₁₀₀₀(Visual Genome), VG₃₀₀₀ and ADE₄₄₅. “w SGRN” is the baseline model Faster-RCNN [45] and FPN [30] adding the proposed SGRN method. Note that comparison of HKRM [23] is not fair since their method here used the relation and attribute annotations of Visual Genome.

Conclusion

- Spatial-aware graph relation network (SGRN) for encoding object relation in the detection system
- Modular Design plugged into existing detection pipeline
- GCN Design
 - Graph Structure from feature map
 - Node representation from classifier
 - Propagation weight from spatial relation

Reproducing 실험

- 구현 내용

- https://github.com/dohoseok/SGRN_torch
- 공개된 논문 구현 코드가 없어서 [Pytorch Faster RCNN](#) 기반으로 SGRN 구현
- Faster RCNN, Visual Genome 3000 dataset 에 대해서 실험

- 실험 환경

- Intel i7-9700KF CPU@ 3.60GHz, 32G RAM, NVIDIA GeForce RTX 2080Ti
- Windows 10, CUDA 10.1, Python 3.6, PyTorch 1.4.0

- 실험 방법

- Faster RCNN 120만 iteration 학습 (약 12epoch)
- 위 weight를 pre-weight로 하여 SGRN 모듈 120만회 학습 (약 12epoch)

Reproducing 실험

- 실험 결과

	Faster RCNN	Faster RCNN w SGRN
Average Precision	11.2	11.5

- SGRN 적용하여 성능 향상 확인 (+0.3)

- 기존 Detector가 충분히 학습된 상태에서 SGRN을 통한 추가 성능 향상 가능.
- Visual Genome Dataset을 Train과 Test로 나눈 기준과 클래스 선택 등이 달라서 Average Precision 값 자체는 논문과 차이가 있음.
- 논문에 설명 부족한 부분 존재
 - Kernel 개수인 K 값을 얼마로 하였는지
 - SGRN 학습 시 기존 baseline detector의 weight는 fix하였는지