

HyperGCN:

A New Method of Training Graph Convolutional Networks on Hypergraphs

N Yadati, et al
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Contents

Introduction

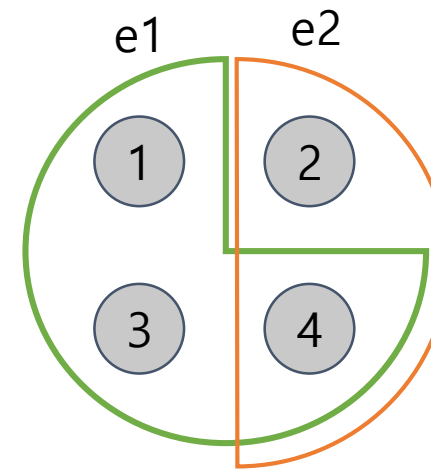
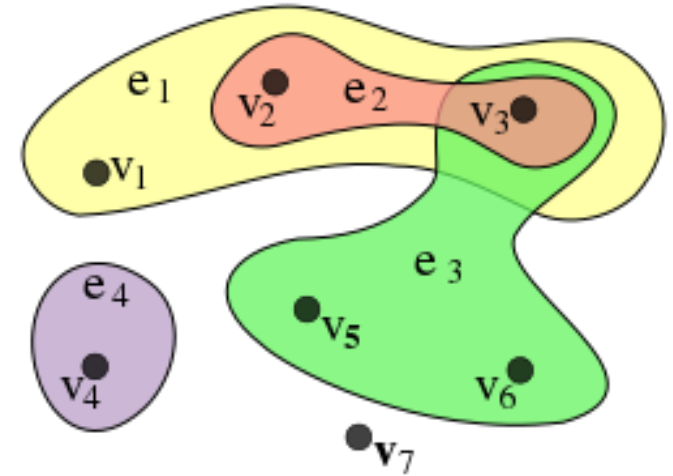
Backgrounds

HyperGCN

Experiments

Introduction - Hypergraph

- Generalization of a graph
 - Hyperedge can join any number of nodes
- Examples
 - Co-citation
 - Co-authorship
 - Chemical reaction
 - 3D point cloud
- Tasks (like graphs)
 - SSL
 - Combinatorial optimization



$$H = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$$

Backgrounds - Remind

- GCN

- $\mathcal{G} = (V, E)$, $|V| = n$, $|E| = m$, $V_L \subset V$
- $\bar{A} = \tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}}$, $\tilde{A} = A + I$, $\tilde{D}_{ii} = \sum_j \tilde{A}_{ij}$
- GCN: $\sigma(\bar{A}X\Theta)$, $X \in \mathbb{R}^{n \times p}$, $\Theta \in \mathbb{R}^{p \times r}$

$$Z = f_{GCN}(X, A) = \text{softmax} \left(\bar{A} \text{ReLU} \left(\bar{A}X\Theta^{(1)} \right) \Theta^{(2)} \right)$$

- SSL

- Cross-entropy $\mathcal{L} = - \sum_{i \in V_L} \sum_{j=1}^q Y_{ij} \ln Z_{ij}$

Backgrounds - Hypergraph

- Definition

- $\mathcal{H} = (V, E)$, $|V| = n$, $|E| = m$, $V_L \subset V$
- $x_v \in \mathbb{R}^p, X \in \mathbb{R}^{n \times p}, H = 1^{n \times m}$

- Normalized Hypergraph Cut

$$\operatorname{argmin}_{\emptyset \neq S \subset V} c(S) := \operatorname{vol} \partial S \left(\frac{1}{\operatorname{vol} S} + \frac{1}{\operatorname{vol} S^c} \right)$$

- Relaxation with constraints

$$\begin{aligned} \operatorname{argmin}_{f \in \mathbb{R}^{|V|}} \frac{1}{2} \sum_{e \in E} \sum_{\{u,v\} \subseteq e} \frac{w(e)}{\delta(e)} \left(\frac{f(u)}{\sqrt{d(u)}} - \frac{f(v)}{\sqrt{d(v)}} \right)^2 &= f^T \Delta f. \\ \text{subject to } \sum_{v \in V} f^2(v) = 1, \sum_{v \in V} f(v) \sqrt{d(v)} = 0. &\Theta = D_v^{-1/2} H W D_e^{-1} H^T D_v^{-1/2} \text{ and } \Delta = I - \Theta \end{aligned}$$

Backgrounds - Hypergraph

- Hypergraph convolution(HGNN)

- $\Delta = I - D_v^{-\frac{1}{2}} H W D_e^{-1} H^T D_v^{-\frac{1}{2}}$

$$\mathbf{g} \star \mathbf{x} = \Phi((\Phi^T \mathbf{g}) \odot (\Phi^T \mathbf{x})) = \Phi g(\Lambda) \Phi^T \mathbf{x} \approx \sum_{k=0}^K \theta_k T_k(\tilde{\Delta}) \mathbf{x},$$

$$\approx \theta_0 \mathbf{x} - \theta_1 \mathbf{D}^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{x},$$

$$\approx \frac{1}{2} \theta \mathbf{D}_v^{-1/2} \mathbf{H} (\mathbf{W} + \mathbf{I}) \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{x}$$

$$\approx \theta \mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{x},$$

$$\mathbf{Y} = \mathbf{D}_v^{-1/2} \mathbf{H} \mathbf{W} \mathbf{D}_e^{-1} \mathbf{H}^T \mathbf{D}_v^{-1/2} \mathbf{X} \Theta,$$

Backgrounds - Hypergraph

- Hypergraph approximation

- Hypergraph to graph

- Clique expansion

- Hyperedge to Clique

- $O(s^2)$ edges

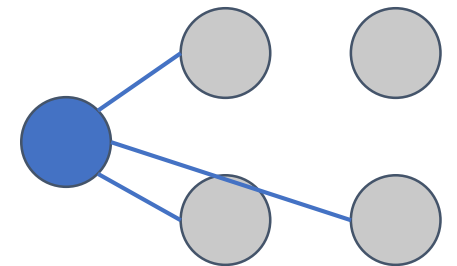
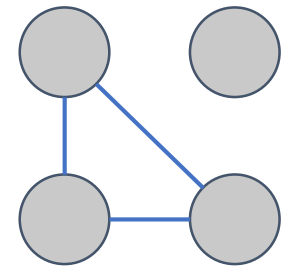
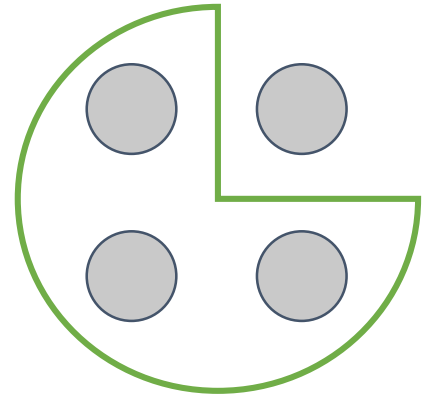
- Star expansion

- Hyperedge to

- a new vertex

- edges connecting the new vertex to each vertex in the hyperedge

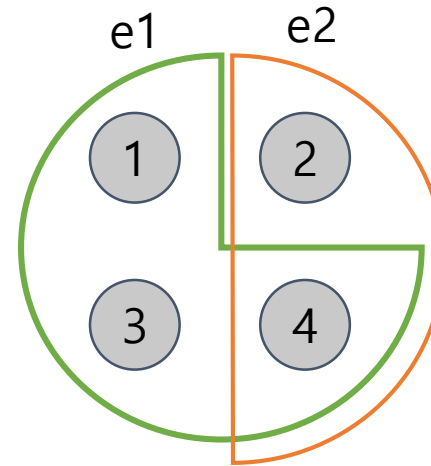
- $O(s)$ edges



Backgrounds - Hypergraph

■ Hypergraph approximation

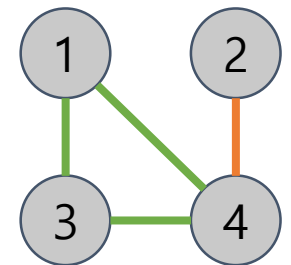
- $\Delta = I - D_v^{-\frac{1}{2}} \boxed{H W D_e^{-1} H^T} D_v^{-\frac{1}{2}}$
- $L = I - D^{-\frac{1}{2}} A D^{-\frac{1}{2}}$



$$H = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$$

$$H H^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \boxed{1} & 0 & \boxed{1} & \boxed{1} \\ 0 & 1 & 0 & 1 \\ \boxed{1} & 0 & \boxed{1} & \boxed{1} \\ \boxed{1} & 1 & \boxed{1} & \boxed{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & \boxed{1} & 0 & \boxed{1} \\ 1 & 0 & 1 & 1 \\ 1 & \boxed{1} & 1 & \boxed{2} \end{bmatrix}$$

- Hypergraph Laplacian implies clique expansion
 - Inefficient when hyperedges are large



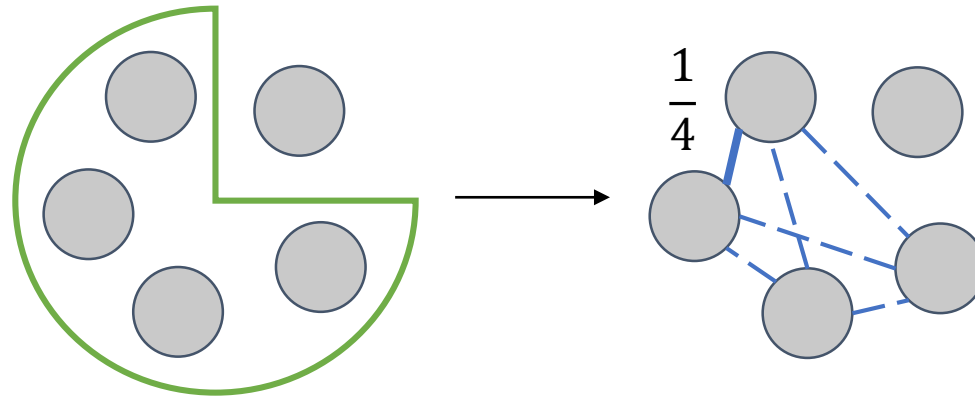
HyperGCN

- Let's reduce order of edges added for each hyperedge
 - **Explicit** hyperedge expansion
 - Select all edge = Clique
 - Select some edges?
 - Select 1 edge?
- What do we learn?
 - SSL node classification setting: nodes in hyperedge should be similar
 - Smoothness regularizer: $\sum_{e \in E} \max_{i, j \in e} |h_i - h_j|^2$
 - Let's select with $\arg\max_{i, j \in e} |h_i - h_j|^2$
 - Edges with large difference should be “learned” more

HyperGCN

▪ 1-HyperGCN (select 1 edge)

- $G_S = \{V, E_S\}, E_S = \left\{ \underset{i,j \in e}{\operatorname{argmax}} |h_i - h_j|^2 : e \in E \right\} + \text{self edges}$
- $w(\{i_e, j_e\}) = \frac{1}{|e|}, A_S = \text{weighted adjacency matrix}$
- GCN step: $\sigma(\overline{A_S} X \Theta)$



HyperGCN

■ 1-HyperGCN

Algorithm 3 Algorithm for 1-HyperGCN

Input: An attributed hypergraph $\mathcal{H} = (V, E, X)$, with attributes X , a set of labelled vertices \mathcal{V}_L

Output All hypernodes in $V - \mathcal{V}_L$ labelled

for each epoch τ of training **do**

for layer $l = 1, 2$ of the network **do**

 set $A_{vv}^{(l)} = 1$ for all hypernodes $v \in V$

 let $\Theta = \Theta^\tau$ be the parameters for the current epoch

for $e \in E$ **do**

$H \leftarrow$ hidden representation matrix of layer $l - 1$

$i_e, j_e := \operatorname{argmax}_{i, j \in e} \|H_i(\Theta^{(l)}) - H_j(\Theta^{(l)})\|_2$

$A_{i_e, j_e}^{(l)} = A_{j_e, i_e}^{(l)} = \frac{1}{|e|}$

end for

end for

$$Z = \operatorname{softmax} \left(\bar{A}^{(2)} \operatorname{ReLU} \left(\bar{A}^{(1)} X \Theta^{(1)} \right) \Theta^{(2)} \right)$$

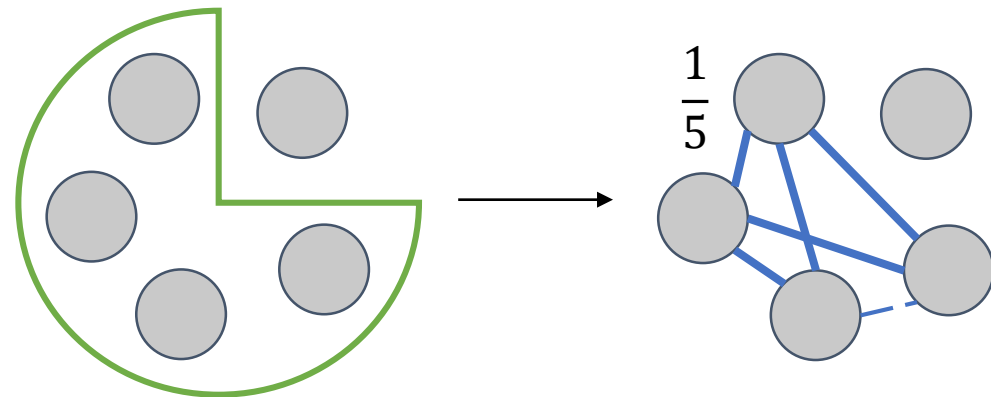
 update parameters Θ^τ to minimise cross entropy loss on the set of labelled hypernodes \mathcal{V}_L

end for

 label the hypernodes in $V - \mathcal{V}_L$ using Z

HyperGCN

- One is not enough: ignores nodes in $K_e = \{k \in e : k \neq i_e, k \neq j_e\}$
- Enhance by using them as mediators
- **HyperGCN** (Select more)
 - $G_S = \{V, E_S\}, E_S = \left\{ \underset{i,j \in e}{\operatorname{argmax}} |h_i - h_j|^2 : e \in E \right\}$
 - $+ \{(k, l) : l \in \{i_e, j_e\}, k \in K_e, e \in E\} + \text{self edges}$
 - $w(\{i_e, j_e\}) = \frac{1}{2|e|-3}, A_S = \text{weighted adjacency matrix}$
 - GCN step: $\sigma(\overline{A_S} X \Theta)$



Algorithm 1 Algorithm for HyperGCN

Input: An attributed hypergraph $\mathcal{H} = (V, E, X)$, with attributes X , a set of labelled vertices \mathcal{V}_L

Output All hypernodes in $V - \mathcal{V}_L$ labelled

- 1: **for** each epoch τ of training **do**
- 2: **for** layer $l = 1, 2$ of the network **do**
- 3: set $A_{vv}^{(l)} = 1$ For all hypernodes $v \in V$
- 4: let $\Theta = \Theta^\tau$ be the parameters For the current epoch
- 5: **for** $e \in E$ **do**
- 6: $H \leftarrow$ hidden representation matrix of layer $l - 1$
- 7: $i_e, j_e := \operatorname{argmax}_{i, j \in e} \|H_i(\Theta^{(l)}) - H_j(\Theta^{(l)})\|_2$
- 8: $A_{i_e, j_e}^{(l)} = A_{j_e, i_e}^{(l)} = \frac{1}{2|e| - 3}$
- 9: $K_e := \{k \in e : k \neq i_e, k \neq j_e\}$
- 10: **for** $k \in K_e$ **do**
- 11: $A_{i_e, k}^{(l)} = A_{k, i_e}^{(l)} = \frac{1}{2|e| - 3}$
- 12: $A_{j_e, k}^{(l)} = A_{k, j_e}^{(l)} = \frac{1}{2|e| - 3}$
- 13: **end for**
- 14: **end for**
- 15: **end for**
- 16: $Z = \operatorname{softmax} \left(\bar{A}^{(2)} \operatorname{ReLU} \left(\bar{A}^{(1)} X \Theta^{(1)} \right) \Theta^{(2)} \right)$
- 17: update parameters Θ^τ to minimise cross entropy loss on the set of labelled hypernodes \mathcal{V}_L
- 18: **end for**
- 19: label the hypernodes in $V - \mathcal{V}_L$ using Z

HyperGCN

- G_S is recomputed every epoch
 - To learn different structures as parameter changes
- **FastHyperGCN**
 - Use initial features X to construct fixed Laplacian

Algorithm 2 Algorithm for FastHyperGCN

Input: An attributed hypergraph $\mathcal{H} = (V, E, X)$, with attributes X , a set of labelled vertices \mathcal{V}_L

Output All hypernodes in $V - \mathcal{V}_L$ labelled

set $A_{vv} = 1$ for all hypernodes $v \in V$

$i_e, j_e := \operatorname{argmax}_{i, j \in e} \|X_i - X_j\|_2$

for $e \in E$ **do**

$$A_{i_e, j_e} = A_{j_e, i_e} = \frac{1}{2|e| - 3}$$

$$K_e := \{k \in e : k \neq i_e, k \neq j_e\}$$

for $k \in K_e$ **do**

$$A_{i_e, k} = A_{k, i_e} = \frac{1}{2|e| - 3}$$

$$A_{j_e, k} = A_{k, j_e} = \frac{1}{2|e| - 3}$$

end for

end for

for each epoch τ of training **do**

let $\Theta = \Theta^\tau$ be the parameters for the current epoch

$$Z = \operatorname{softmax} \left(\bar{A} \operatorname{ReLU} \left(\bar{A} X \Theta^{(1)} \right) \Theta^{(2)} \right)$$

update parameters Θ^τ to minimise cross entropy loss on the set of labelled hypernodes \mathcal{V}_L

end for

label the hypernodes in $V - \mathcal{V}_L$ using Z

Experiments

- Dataset: Co-citation/authorship hypergraph

	DBLP (co-authorship)	Pubmed (co-citation)	Cora (co-authorship)	Cora (co-citation)	Citeseer (co-citation)
# hypernodes, $ V $	43413	19717	2708	2708	3312
# hyperedges, $ E $	22535	7963	1072	1579	1079
avg.hyperedge size	4.7 ± 6.1	4.3 ± 5.7	4.2 ± 4.1	3.0 ± 1.1	3.2 ± 2.0
# features, d	1425	500	1433	1433	3703
# classes, q	6	3	7	7	6
label rate, $ V_L / V $	0.040	0.008	0.052	0.052	0.042

- SSL: Hypernode classification task
- Combinatorial Optimization: K-subhypergraph problem
 - Find subset $W \subseteq V$ of k hypernodes s.t. maximize # of hyperedges in W (NPhard)

Experiments

- SSL: Hypernode classification task

Data	Method	DBLP co-authorship	Pubmed co-citation	Cora co-authorship	Cora co-citation	Citeseer co-citation
\mathcal{H}	CI	54.81 ± 0.9	52.96 ± 0.8	55.45 ± 0.6	64.40 ± 0.8	70.37 ± 0.3
\mathcal{X}	MLP	37.77 ± 2.0	30.70 ± 1.6	41.25 ± 1.9	42.14 ± 1.8	41.12 ± 1.7
\mathcal{H}, \mathcal{X}	MLP + HLR	30.42 ± 2.1	30.18 ± 1.5	34.87 ± 1.8	36.98 ± 1.8	37.75 ± 1.6
\mathcal{H}, \mathcal{X}	HGNN	25.65 ± 2.1	29.41 ± 1.5	31.90 ± 1.9	32.41 ± 1.8	37.40 ± 1.6
\mathcal{H}, \mathcal{X}	1-HyperGCN	33.87 ± 2.4	30.08 ± 1.5	36.22 ± 2.2	34.45 ± 2.1	38.87 ± 1.9
\mathcal{H}, \mathcal{X}	FastHyperGCN	27.34 ± 2.1	29.48 ± 1.6	32.54 ± 1.8	32.43 ± 1.8	37.42 ± 1.7
\mathcal{H}, \mathcal{X}	HyperGCN	24.09 ± 2.0	25.56 ± 1.6	30.08 ± 1.8	32.37 ± 1.7	37.35 ± 1.6

- Clique expansion = expansion with mediators when $|e| = 2, 3$

Experiments

- SSL: Hypernode classification task
 - Robust to noisiness (*low η = noisy*)

Method	$\eta = 0.75$	$\eta = 0.70$	$\eta = 0.65$	$\eta = 0.60$	$\eta = 0.55$	$\eta = 0.50$	sDBLP
HGNN	15.92 \pm 2.4	24.89 \pm 2.2	31.32 \pm 1.9	39.13 \pm 1.78	42.23 \pm 1.9	44.25 \pm 1.8	45.27 \pm 2.4
FastHyperGCN	28.86 \pm 2.6	31.56 \pm 2.7	33.78 \pm 2.1	33.89 \pm 2.0	34.56 \pm 2.2	35.65 \pm 2.1	41.79 \pm 2.8
HyperGCN	<u>22.44 \pm 2.0</u>	<u>29.33 \pm 2.2</u>	<u>33.41 \pm 1.9</u>	33.67 \pm 1.9	<u>35.05 \pm 2.0</u>	<u>37.89 \pm 1.9</u>	41.64 \pm 2.6

- Training time

Model↓ Metric →	Training time	Density	DBLP	Pubmed
HGNN	170s	337	0.115s	0.019s
FastHyperGCN	143s	352	0.035s	0.016s

Table 1: average training time of an epoch (lower is better)

Experiments

- Combinatorial Optimization: K-subhypergraph problem
 - Maxmizing “density”
 - Greedy heuristic
 - MaxDegree: select k nodes with largest degree
 - RemoveMinDegree: remove all hyperedge including smallest degree node (repeat n-k times)

Dataset→ Approach↓	Synthetic test set	DBLP co-authorship	Pubmed co-citation	Cora co-authorship	Cora co-citation	Citeseer co-citation
MaxDegree	174 ± 50	4840	1306	194	544	507
RemoveMinDegree	147 ± 48	7714	7963	450	1369	843
MLP	174 ± 56	5580	1206	238	550	534
MLP + HLR	231 ± 46	5821	3462	297	952	764
HGNN	337 ± 49	6274	7865	437	1408	969
1-HyperGCN	207 ± 52	5624	1761	251	563	509
FastHyperGCN	352 ± 45	7342	7893	452	1419	969
HyperGCN	359 ± 49	7720	7928	504	1431	971
# hyperedges, E	500	22535	7963	1072	1579	1079

Thank you

Experiments - reproducing

- Settings

- SSL Node classification

- Dataset: DBLP co-authorship
CORA co-citation

- Parameters

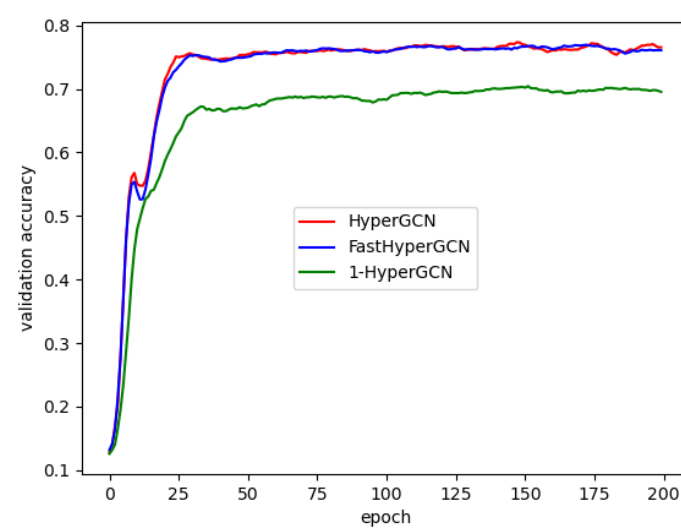
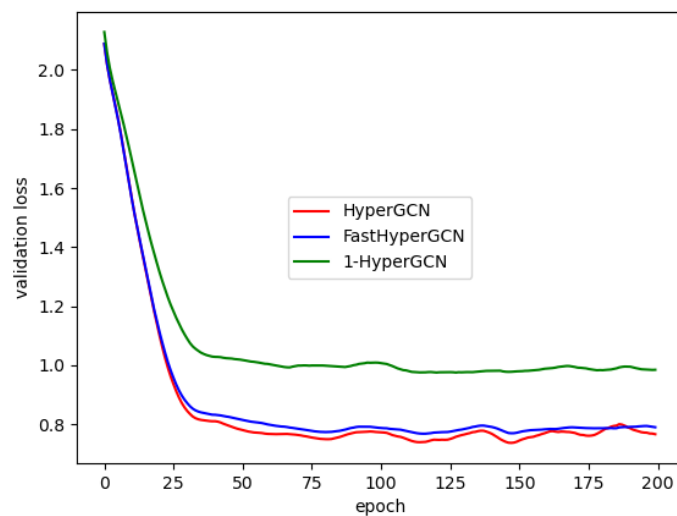
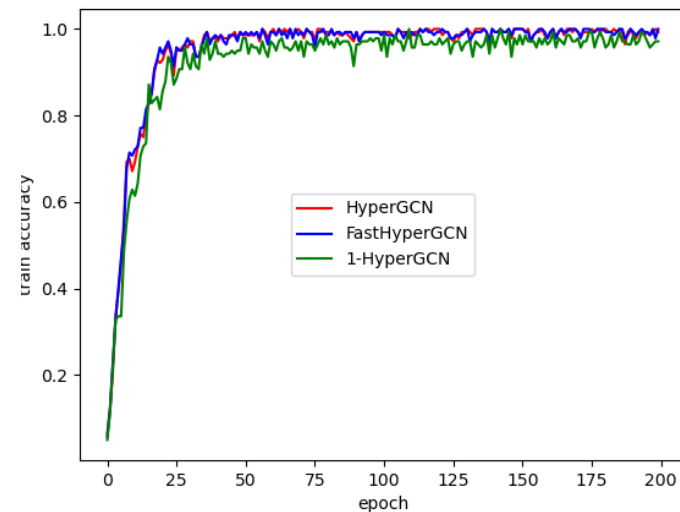
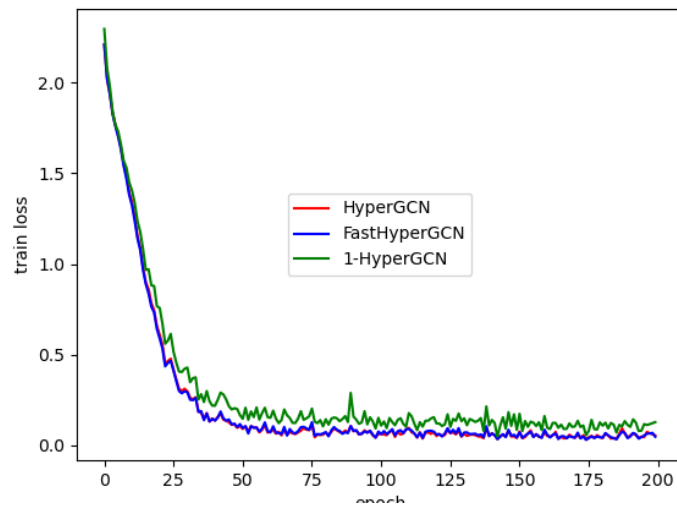
- lr=0.01, weight_decay=5e-4, epochs=200
 - hidden=16, dropout=0.5

```
[DBLP] # of nodes: 41302
[DBLP] Dim of feature: 1425
[DBLP] # of hyperedges: 22363
[DBLP] # of classes: 41302
[DBLP] Labels: [0 1 2 3 4 5]
[DBLP] # of train: 1740
[DBLP] # of val: 39562
[MODEL] in, hid, out: [1425, 16, 6]
[OPTIM] lr, decay: 0.01, 0.0005
```

```
[CORA] # of nodes: 2708
[CORA] Dim of feature: 1433
[CORA] # of hyperedges: 1564
[CORA] # of classes: 7
[CORA] Labels: [0 1 2 3 4 5 6]
[CORA] # of train: 140
[CORA] # of val: 500
[CORA] # of test: 2068
[MODEL] in, hid, out: [1433, 16, 7]
[OPTIM] lr, decay: 0.01, 0.0005
```

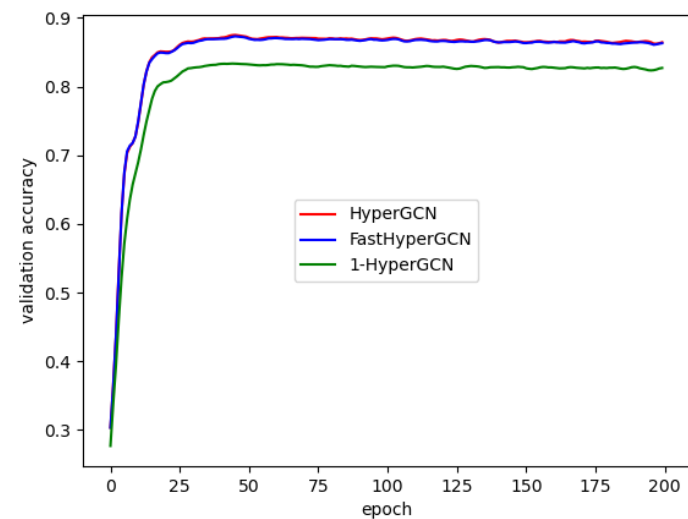
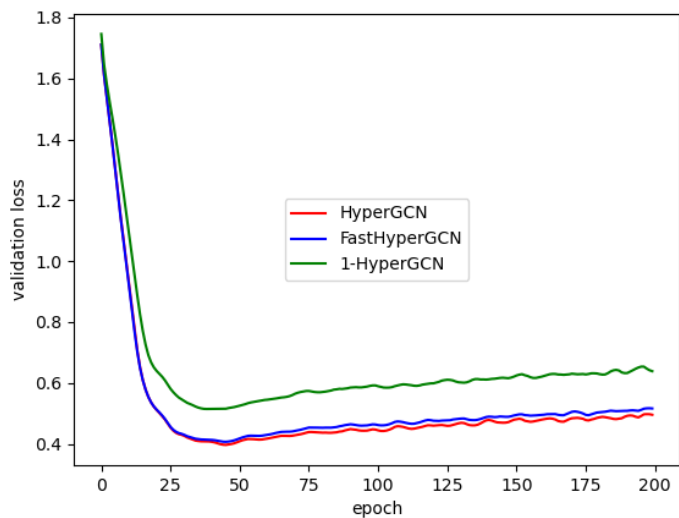
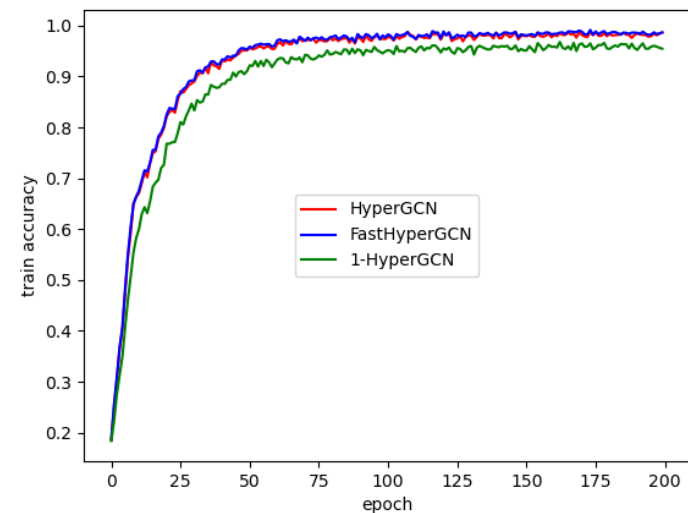
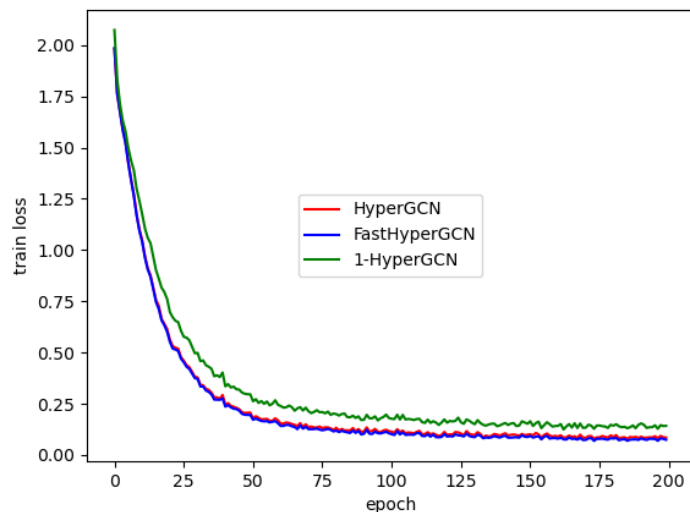
Experiments - reproducing

- Cora results



Experiments - reproducing

- DBLP results



Experiments - reproducing

- Results in the paper is not reliable
 - Train-test split experiments
 - While Train-val-test should be done
 - Numbers in the table: 1 – accuracy
 - Too high error, experiment settings are not clear
- It reached certain performance
 - Near 77.3%(cora), 87.5%(dblp)
 - But worse than reported performances from other works
 - GCN(81.5%, cora), HGNN(81.6%, cora)
 - There might be bugs in my code
 - but also couldn't reach the performance from official public code

Data	Method	DBLP co-authorship	Cora co-authorship
\mathcal{H}, \mathbf{X}	1-HyperGCN	33.87 ± 2.4	36.22 ± 2.2
\mathcal{H}, \mathbf{X}	FastHyperGCN	27.34 ± 2.1	32.54 ± 1.8
\mathcal{H}, \mathbf{X}	HyperGCN	24.09 ± 2.0	30.08 ± 1.8

Repository

- Link: <https://github.com/nikriz/HyperGCN>

- How to run (README.md)

conda env create -f env.yaml

conda activate hypergcn

python train.py	--dataset	<"cora" or "dblp">	to choose the dataset
	--split_id	<1~10>	to choose the split, for dblp
	--one/fast		to choose the 1-HyperGCN/FastHyperGCN
	--epochs	<value>	to choose training epochs
	--lr	<value>	to choose learning rate
	--weight_decay	<value>	to choose weight decay
	--hidden	<value>	to choose hidden layer size
	--dropout	<value>	to choose dropout rate

Implementation

- Code structure

- Model.py: basic GCN model

ref) <https://github.com/tkipf/pygcn/blob/master/pygcn/models.py>

- Train.py: training code

- Util.py: graph utility functions and graph update

ref) <https://github.com/malllabiisc/HyperGCN/blob/master/model/utils.py>

- Data/: dataset and load scripts

Implementation

- Model.py
 - Graph Convolution
 - Same as reference
 - reset_parameters
 - Gaussian initialization
 - forward
 - $(\text{output}) = A(\text{input})\Theta + b$

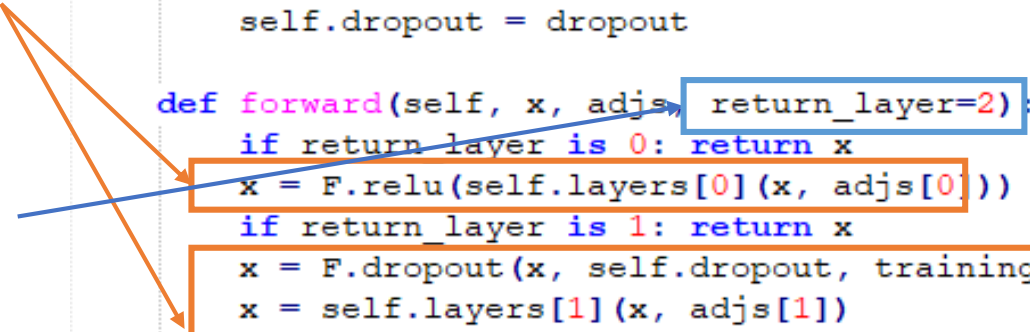
```
class GraphConvolution(Module):  
    """  
    Simple GCN layer, similar to https://arxiv.org/abs/1609.02907  
    """  
    def __init__(self, in_features, out_features, bias=True):  
        super(GraphConvolution, self).__init__()  
        self.in_features = in_features  
        self.out_features = out_features  
        self.weight = Parameter(torch.FloatTensor(in_features,  
                                                    out_features))  
        if bias:  
            self.bias = Parameter(torch.FloatTensor(out_features))  
        else:  
            self.register_parameter('bias', None)  
        self.reset_parameters()  
  
    def reset_parameters(self):  
        stdv = 1. / math.sqrt(self.weight.size(1))  
        self.weight.data.uniform_(-stdv, stdv)  
        if self.bias is not None:  
            self.bias.data.uniform_(-stdv, stdv)  
  
    def forward(self, input, adj):  
        support = torch.mm(input, self.weight)  
        output = torch.spmm(adj, support)  
        if self.bias is not None:  
            return output + self.bias  
        else:  
            return output  
  
    def __repr__(self):  
        return self.__class__.__name__ + ' (' \  
            + str(self.in_features) + ' -> ' \  
            + str(self.out_features) + ')
```

Implementation

- Model.py
 - 2-layer GCN module
 - Same as reference
 - `Softmax(gc2(Dropout(Relu(gc1))))`
 - Little modifications
 - To use intermediate features in graph structure update, return layers argument is added to retrieve features from wanted layer.

```
class GCN(nn.Module):
    def __init__(self, nfeat, nhid, nclass, dropout):
        super(GCN, self).__init__()
        print("[MODEL] in, hid, out:", [nfeat, nhid, nclass])
        self.gc1 = GraphConvolution(nfeat, nhid)
        self.gc2 = GraphConvolution(nhid, nclass)
        self.layers = nn.ModuleList([self.gc1, self.gc2])
        self.dropout = dropout

    def forward(self, x, adj, return_layer=2):
        if return_layer is 0: return x
        x = F.relu(self.layers[0](x, adj[0]))
        if return_layer is 1: return x
        x = F.dropout(x, self.dropout, training=self.training)
        x = self.layers[1](x, adj[1])
        return F.log_softmax(x, dim=1)
```



Implementation

- Util.py

- Utility functions

- Same as reference

- Symnormalize: $D^{-\frac{1}{2}}MD^{-\frac{1}{2}}$

- Referenced, but not copied

- Format modifiers

```
# Symnormalize matrix
def symnormalise(M):
    d = np.array(M.sum(1))
    dhi = np.power(d, -1/2).flatten()
    dhi[np.isinf(dhi)] = 0.
    DHI = sp.diags(dhi)
    return (DHI.dot(M)).dot(DHI)

# Dictionary of edges to normalized adjacency matrix
def dictionary_to_sparse_mx(dictionary, n):
    edges = [list(k) for k in dictionary.keys()]
    weights = [dictionary[k] for k in dictionary.keys()]
    edges = np.array(edges)
    weights = np.array(weights)
    adj = sp.coo_matrix((weights, (edges[:, 0], edges[:, 1])), shape=(n, n), dtype=np.float32)
    adj = adj + sp.eye(n)
    adj = symnormalise(sp.csr_matrix(adj, dtype=np.float32))
    return adj

# Sparse matrix to sparse tensor
def sparse_mx_to_torch_sparse_tensor(sparse_mx):
    sparse_mx = sparse_mx.tocoo().astype(np.float32)
    indices = torch.from_numpy(
        np.vstack((sparse_mx.row, sparse_mx.col)).astype(np.int64))
    values = torch.from_numpy(sparse_mx.data)
    shape = torch.Size(sparse_mx.shape)
    return torch.sparse.FloatTensor(indices, values, shape)
```

Implementation

- Util.py

- Utility functions

- Same as reference
 - Evaluation function



```
# Get accuracy of result
def accuracy(output, labels):
    preds = output.max(1)[1].type_as(labels)
    correct = preds.eq(labels).double()
    correct = correct.sum()
    return correct / len(labels)
```

- Not from reference
 - Sparse Identity generator



```
# Get identity matrix
def eye(n, to_tensor=False):
    m = {}
    for i in range(n):
        m[(i, i)] = 0
    if to_tensor:
        m = dictionary_to_sparse_mx(m, n)
        m = sparse_mx_to_torch_sparse_tensor(m)
    return m
```

Implementation

- Util.py
 - Graph Updater
 - Refactored reference
 - Sparse dictionary edge adder
 - Graph updating function

```
# Link node i and j with weight w
def link(adj, i, j, w):
    if (i, j) not in adj:
        adj[(i, j)] = 0
    adj[(i, j)] += w
    if (j, i) not in adj:
        adj[(j, i)] = 0
    adj[(j, i)] += w

# Update graph structure for hypergcn
def update_graph(hypergraph, features, one=False):
    print("[UPDATE]")
    n = features.shape[0]
    adj = eye(n)
    cnt = 0
    for author in hypergraph:
        hyperedge = np.array(hypergraph[author])

        # Get max feature diff
        with torch.no_grad():
            f = np.array(features[hyperedge])
            dist = cdist(f, f)
            idx = np.unravel_index(np.argmax(dist, axis=None), dist.shape)

        # Connect edges
        weight = 1/(2*len(hyperedge) - 3)
        link(adj, hyperedge[idx[0]], hyperedge[idx[1]], weight)

        # Only for Hypergcn/FastHypergcn
        if not one:
            for i in hyperedge:
                if i not in [hyperedge[idx[0]], hyperedge[idx[1]]]:
                    link(adj, hyperedge[idx[0]], i, weight)
                    link(adj, hyperedge[idx[1]], i, weight)
                    cnt = cnt + 2
            cnt = cnt + 1

    # return graph structure
    adj = dictionary_to_sparse_mx(adj, n)
    adj = sparse_mx_to_torch_sparse_tensor(adj)
    return adj
```

Again Thank you