

Mid-term exam

1. $\epsilon_0 \vec{\nabla} \cdot \vec{E} = \rho \quad \vec{E} = -\vec{\nabla} \phi$ test particle

$$\epsilon_0 \vec{\nabla}^2 \phi = -\rho \quad \rho = Z e n_i - e n_e + Q \delta(\vec{r})$$

- Assume Boltzmann distribution for n_i, n_e

$$n_i = n_{i\infty} e^{-Ze\phi/T_i}, \quad n_e = n_{e\infty} e^{e\phi/T_e}$$

- Assume $e\phi/T_{e,i} \ll 1$ expand

$$\epsilon_0 \vec{\nabla}^2 \phi = -Z e n_{i\infty} (1 - Ze\phi/T_i) + e n_{e\infty} (1 + e\phi/T_e) - Q \delta(\vec{r})$$

- Assume quasi neutrality of $n_{e\infty} \approx T n_{i\infty}$
in the background

$$\epsilon_0 \vec{\nabla}^2 \phi - e^2 n_{e\infty} \left(\frac{Z}{T_i} + \frac{1}{T_e} \right) \phi = -Q \delta(\vec{r})$$

- In spherical geometry

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\phi}{dr} \right) - \frac{1}{\lambda_D^2} \phi = -\frac{Q}{\epsilon_0} \delta(r)$$

$$\phi = \frac{Q}{4\pi\epsilon_0 r} e^{-r/\lambda_D}$$

$$\text{where } \lambda_D = \sqrt{\frac{\epsilon_0 T_e}{e^2 n_{e\infty}} \frac{1}{1 + Z T_e / T_i}}$$

$$\text{if } T_e \gg T_i \quad \lambda_D \sim \sqrt{\frac{\epsilon_0 T_i}{Z e^2 n_{e\infty}}} \rightarrow \text{"cold" ion}$$

$$\text{not } \sim \sqrt{\frac{\epsilon_0 T_e}{e^2 n_{e\infty}}} \rightarrow \text{"fixed" ion}$$

2. drift velocity by $\vec{\nabla}B$ & \vec{K}

$$\text{due to } \vec{B}(x, z) = B_0 [\epsilon z \hat{x} + (1 + \epsilon x) \hat{z}]$$

note, $\vec{\nabla} \times \vec{B} = 0$ i.e) vacuum field

Then,

$$\vec{V}_{\nabla B} + \vec{V}_{\text{curv}} = \frac{m(V_x^2 + 2V_z^2)}{2gB} \frac{\vec{B} \times \vec{\nabla}B}{B^2}$$

$$\vec{B} \cdot \vec{B} = B_0^2 (1 + 2\epsilon x + \mathcal{O}(\epsilon^2))$$

$$B = B_0 (1 + \epsilon x + \underbrace{\mathcal{O}(\epsilon^2)})$$

$$\vec{\nabla} B = \epsilon B_0 \hat{x} + \mathcal{O}(\epsilon^2)$$

$$\begin{aligned} \vec{B} \times \vec{\nabla} B &= B_0^2 ((1 + \epsilon x) \epsilon) \hat{y} \\ &= \epsilon B_0 \hat{y} + \mathcal{O}(\epsilon^2) \end{aligned}$$

$$\vec{V}_{\nabla B} + \vec{V}_{\text{curv}} = \frac{m(V_x^2 + 2V_z^2)}{2gB_0} \epsilon \hat{y} + \mathcal{O}(\epsilon^2)$$

$$= \vec{V}_{E \times B} = \frac{\vec{E} \times B_0 \hat{z}}{B_0^2} + \mathcal{O}(\epsilon^2)$$

$$\text{if } \vec{E} = - \frac{m(V_x^2 + 2V_z^2)}{2g} \epsilon \hat{x} + \mathcal{O}(\epsilon^2)$$

$$3. \text{ note } \frac{3}{2} \frac{dP}{dt} = \frac{3}{2} n \frac{dT}{dt} + \frac{3}{2} T \frac{dn}{dt}$$

$$= \frac{3}{2} n \frac{dT}{dt} - \frac{3}{2} n T (\vec{\nabla} \cdot \vec{u})$$

$$\text{so, } \frac{3}{2} \left(\frac{d}{dt} \right)_e P_e + \frac{5}{2} P_e (\vec{\nabla} \cdot \vec{u}_e) + \vec{\nabla} \cdot \vec{g}_e$$

$$= \frac{3}{2} n_e \left(\frac{d}{dt} \right)_e T_e + P_e (\vec{\nabla} \cdot \vec{u}_e) + \vec{\nabla} \cdot \vec{g}_e = 0$$

as frequently used.

$$\text{now just use } \vec{u}_e = \vec{u} - \frac{1}{en_e} \vec{j}$$

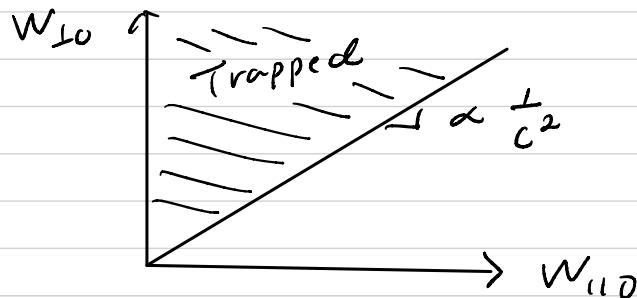
$$\left\{ \begin{array}{l} \left(\frac{d}{dt} \right)_e = \frac{d}{dt} - \frac{1}{en_e} \vec{j} \cdot \vec{\nabla} \\ \vec{\nabla} \cdot \vec{u}_e = \vec{\nabla} \cdot \vec{u} - \frac{1}{en_e} \vec{\nabla} \cdot \vec{j} + \frac{1}{en_e^2} \vec{j} \cdot \vec{\nabla} n_e \end{array} \right.$$

$$\frac{3}{2} n_e \frac{dT_e}{dt} + n_e T_e (\vec{\nabla} \cdot \vec{u}) + \frac{\vec{j}}{en_e} \cdot \left(T_e \vec{\nabla} n_e - \frac{3}{2} n_e \vec{\nabla} T_e \right) + \vec{\nabla} \cdot \vec{g}_e = 0$$

$$4. (a) W_{11} = W - W_{\perp} = W_{110} + (1-R)W_{\perp 0} \quad R \equiv B/B_0$$

$$1-R = -\frac{z^2}{L^2} \rightarrow W_{11} = W_{110} - \frac{z^2}{L^2} W_{\perp 0}$$

\therefore Trapping condition $W_{11}=0$ exists



$$W_{110} = \frac{z^2}{L^2} W_{\perp 0} < c^2 W_{\perp 0}$$

$$(b) \text{ turning point } W_{11} = 0 \rightarrow z^2 = L^2 \frac{W_{110}}{W_{\perp 0}} \equiv z_T^2$$

$$\text{so rewrite } W_{11} = W_{110} (1 - \frac{z^2}{z_T^2})$$

$$(c) B_0 \rightarrow \beta B_0 \quad W_{\perp} \rightarrow \beta W_{\perp}, \quad W_{\perp 0} \rightarrow \beta W_{\perp 0}$$

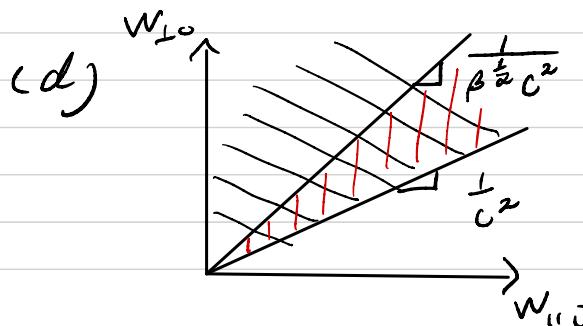
$$J = \oint V_{11} dz = \oint V_{110} (1 - \frac{z^2}{z_T^2})^{\frac{1}{2}} dz$$

$$\propto V_{110} z_T \sim \text{const}$$

$$\Rightarrow V_{110}^2 z_T^2 = L^2 \frac{W_{110}^2}{W_{\perp 0}} \sim \text{const}$$

$$\Rightarrow W_{110}^2 \rightarrow \beta W_{110}^2$$

$$W_{110} \rightarrow \beta^{\frac{1}{2}} W_{110} \quad \text{and} \quad \frac{W_{\perp 0}}{W_{110}} \rightarrow \beta^{\frac{1}{2}} \frac{W_{\perp 0}}{W_{110}}$$



so, particle with

$$\frac{1}{c^2} < \frac{W_{\perp 0}}{W_{110}} < \frac{1}{\beta^{\frac{1}{2}} c^2}$$

are trapped and then detrapped if $\beta < 1$

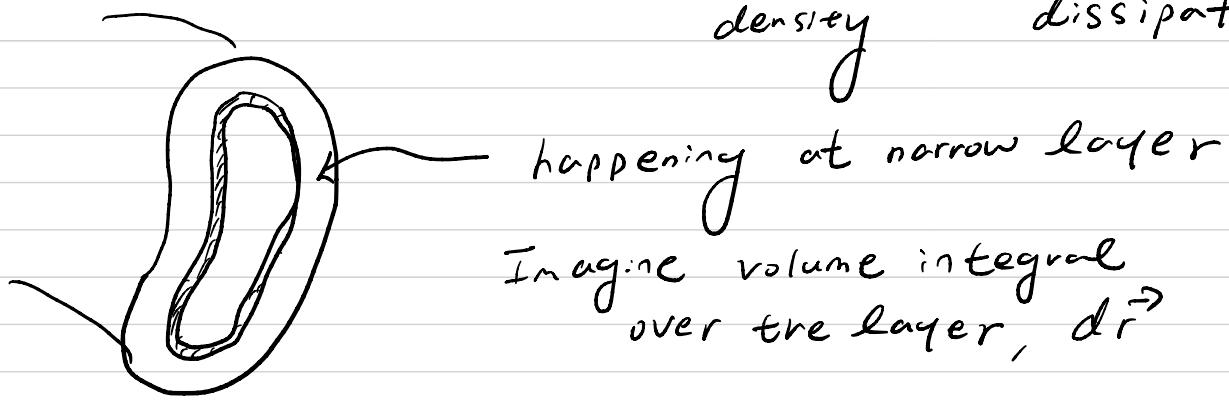
$$5. \quad \vec{E} + \vec{u} \times \vec{B} = \eta \vec{j}$$

$$(\vec{E} + \omega R \hat{\phi} \times \vec{B} = \eta \vec{j}) \cdot \vec{j}$$

$$-\vec{j} \cdot \vec{\nabla} \phi + \omega R \vec{j} \cdot (\hat{\phi} \times \vec{B}) = \eta \vec{j}^2$$

$$\vec{\nabla} \cdot (\phi \vec{j}) + \omega R \hat{\phi} \cdot (\vec{j} \times \vec{B}) = -\eta \vec{j}^2$$

toroidal torque density resistive dissipation



$$\cancel{\int d\vec{r} \vec{\nabla} \cdot (\phi \vec{j})} + \omega \underbrace{\int d\vec{r} R \hat{\phi} \cdot (\vec{j} \times \vec{B})}_{\text{Total torque } T_\phi} = - \int d\vec{r} \eta \vec{j}^2$$

$$T_\phi = - \frac{\int d\vec{r} \eta \vec{j}^2}{\omega} \leftarrow \begin{array}{l} \text{torque by dissipation} \\ \text{rotational screening} \end{array}$$