Lecture Note of Innovative Ship and Offshore Plant Design

Innovative Ship and Offshore Plant Design Part I. Ship Design

Ch. 6 Resistance Prediction

Spring 2018

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Ch. 6 Resistance Prediction

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1. Object of Resistance Prediction

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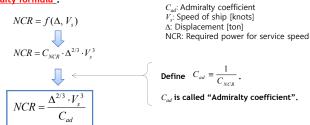
Object of Resistance Prediction (1/3)

Review) Weight Estimation: Method 4 $LWT = W_s + W_o + W_m$

$$L \cdot B \cdot T \cdot C_B \cdot \rho \cdot (1 + \alpha) = DWT + C_s \cdot L^{1.6} \cdot (B + D) + C_o \cdot L \cdot B + C_m \cdot NMCR$$

There are few data available for estimation of the *NMCR* at the early design stage. Thus, *NMCR* can be roughly estimated by 'Admiralty formula'.

Admiralty formula:



However, *NMCR* should <u>be estimated more accurately based on the prediction of resistance and propulsion power.</u>

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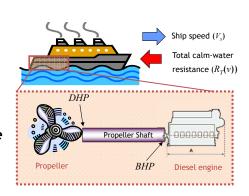
Object of Resistance Prediction (2/3)

☑ Goal: Estimation of NMCR

At first, we have to predict

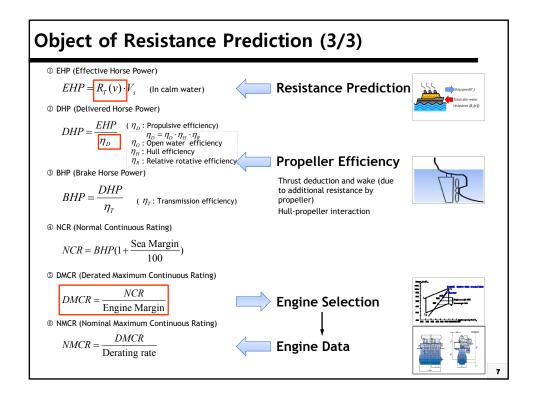


Then, by using the propulsive efficiency, shaft, and sea margin, required propulsive power can be estimated.



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2. Decomposition of Resistance and Methods of Resistance Prediction

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Definition of Resistance



☑ Resistance

- The resistance of a ship at a given speed is the force required to tow the ship at that speed in smooth water, assuming no interference from the towing ship.
- This total resistance is made up of a number of different components, which are caused by a variety of factors and which interact one with the other in an extremely complicated way.

* SNAME, Principles of Naval Architecture – Resistance, Propulsion and Vibration, Vol. 2, 1988 Inovative Ship and Offshore Plant Design, Spring 2018, Myung-II Roh ydlab 9

Types of Resistance

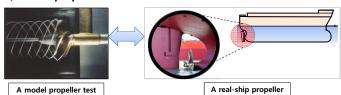
In order to deal with the question more simply, it is usual to consider the total calm water resistance as being made up of four main components.

- (a) , due to the motion of the hull through a viscous fluid.
- (b) , due to the energy that must be supplied continuously by the ship to the wave system created on the surface of the water.
- (C) , due to the energy carried away by eddies shed from the hull or appendages. Local eddying will occur behind appendages such as bossings, shafts and shaft struts, and from stern frames and rudders if these items are not properly streamlined and aligned with the flow.
- (d) experienced by the above-water part of the main hull and the superstructures due to the motion of the ship through the air.

SNAME, Principles of Naval Architecture – Resistance, Propulsion and Vibration, Vol. 2, 1988

Dimensional Analysis (1/4)

Example) Model propeller test



Dimensional Analysis

Dimensional analysis is essentially a means of utilizing a partial knowledge of a problem when the details are too obscure to permit an exact analysis.

It has the enormous advantage of requiring for its application a knowledge only of the variables which govern the result.

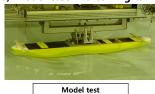
Dimensional solutions do not yield numerical answers, but they provide the **form of the** answer so that every experiment can be used to the fullest advantage in determining a general empirical solution.

SNAME, Principles of Naval Architecture - Resistance, Propulsion and Vibration, Vol. 2, 1988

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Dimensional Analysis (2/4)

Example) Model test in a towing tank





Application of dimensional analysis to a ship

To apply it to <u>the flow around ships</u> and <u>the corresponding resistance</u>, it is necessary to know only upon <u>what variables the latter depends</u>.

Applying dimensional analysis to the ship resistance problem, the resistance R could depend upon the following:

- (a) Speed, V
- (b) Size of body, which may be represented $ML/T^2 = (M/L^3)^a (L/T)^b (L)^c (M/LT)^d$ by the linear dimension, L.
- (c) Density of fluid, p (mass per unit volume)
- (d) Viscosity of fluid, µ
- (e) Acceleration due to gravity, g
- (f) Pressure per unit area in fluid, p
- $R \propto
 ho^a V^b L^c \mu^d g^e p^f$ * M: Mass, L: Length, T: Time

$$ML/T^{2} = \left(M/L^{3}\right)^{a} \left(L/T\right)^{b} \left(L\right)^{c} \left(M/LT\right)^{d}$$

$$\times \left(L/T^{2}\right)^{c} \left(M/LT^{2}\right)^{f}$$

SNAME, Principles of Naval Architecture – Resistance, Propulsion and Vibration, Vol. 2, 1988

Dimensional Analysis (3/4)

It is assumed that the resistance R can now be written in terms of unknown powers of these variables:

$$\frac{R}{1/2 \cdot \rho V^2 L^2} = f\left[\frac{\rho VL}{\mu}, \frac{gL}{V^2}, \frac{p}{\rho V^2}\right]$$

Writing v for $\mu \rho$ and remembering that for similar shapes the wetted surface S is proportional to L2, the equation may be written:

$$\frac{R}{1/2 \cdot \rho SV^2} = f\left[\frac{VL}{v}, \frac{gL}{V^2}, \frac{p}{\rho V^2}\right]$$
The 1st term is the Reynolds number R_n .
The 2nd term is related to the Froude number F_n .
The 3rd term is the Cavitation number σ_o .

The left-hand side of the equation is a non-dimensional resistance coefficient. Equation states in effect that if all the parameters on the right-hand side have the same values for two geometrically similar but different sized bodies, the flow patterns will be similar and the value of $\frac{R}{1/2\rho SV^2}$ will be the same for each.

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Dimensional Analysis (4/4)

Dimensionless number derived by dimensional analysis to a ship

$$\frac{R}{1/2\rho SV^2} = f\left[\frac{VL}{V}, \frac{gL}{V^2}, \frac{p}{\rho V^2}\right]$$

* Dimensional Homogeneity

Dimensional analysis rests on the basic principle that every equation which expresses a physical relationship must be dimensionally homogeneous.

Dimensionless Number:

: A dimensionless number that gives a measure of the ratio of inertial

$$R_n = \frac{VL}{V}$$

V: characteristic velocity of the ship L: length of the ship at the waterline level In 15 degree seawater, 10-6

 ν : In 10 degree seawater, 1.35X10⁻⁶

: A dimensionless number comparing <u>inertial and gravitational forces</u>

$$F_n = \frac{V}{\sqrt{gL}}$$

Cavitation number: A dimensionless number used in flow calculations. It expresses the relationship between the difference o a local absolute pressure from the vapor pressure and the kinetic energy per volume, and is used to characterize the potential of the flow to cavitate

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Decomposition of Resistance (1/3)

Rn (Reynolds Number): $R_n = \frac{VL}{VL}$

Fn (Froude Number): $F_n =$

The concept of resistance decomposition helps in designing the hull form as the designer can focus on how to influence individual resistance components.

Resistance decomposition by Froude

Total resistance (R_T) =

Resistance decomposition by Hughes

Total resistance (R_T) =

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Decomposition of Resistance (2/3)

Froude: $R_T = R_F + R_R + \Delta R_F$ Hughes: $R_T = R_V + R_W$

Frictional resistance prediction method

Frictional resistance is assumed to be

Frictional resistance (R_F) :

The frictional resistance is usually predicted taking the resistance of an 'equivalent' <u>flat plate</u> of the same area and length as follows: ρ : density of sea water= 1.025 (Mg/m³)

$$R_F = 1/2\rho \cdot C_F \cdot S \cdot V^2$$

 C_F : frictional resistance coefficient

V[m/s]: characteristic velocity of the ship $S[m^2]$: wetted surface

The 1957 ITTC (International Towing Tank Committee) line is expressed by the formula:

$$C_F = \frac{0.075}{(\log R_n - 2)^2}$$

 R_n (Reynolds Number): $\frac{VL}{V}$

3-dimensionalized form using the form factor

Viscous resistance (R_v) : $R_v = (1+k)R_F + \Delta R_F$

 $k: \underline{\text{form factor}} \\ \Delta R_{\scriptscriptstyle F} \text{: model-ship correlation factor}$

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Decomposition of Resistance (3/3)

Wave resistance prediction method

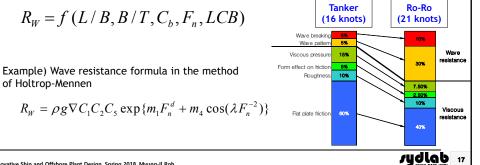
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The ship creates a typical wave system which contributes to the total resistance. For fast, slender ships this component dominates.

In addition, there are breaking waves at the bow which dominate for slow, full hulls, but may also be considerable for fast ships.

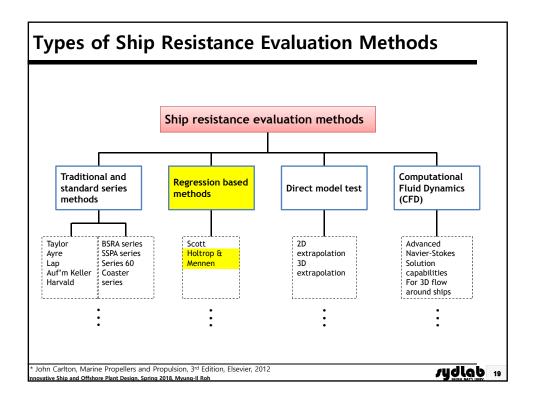
The interaction of various wave systems is complicated leading to non-monotonous function of the wave resistance coefficient C,..

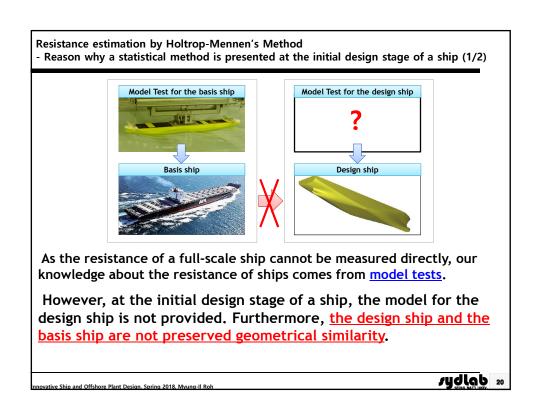
The wave resistance depends strongly on the **local shape**.



3. Resistance Prediction by Holtrop-Mennen's Method

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Resistance estimation by Holtrop-Mennen's Method

- Reason why a statistical method is presented at the initial design stage of a ship (2/2)

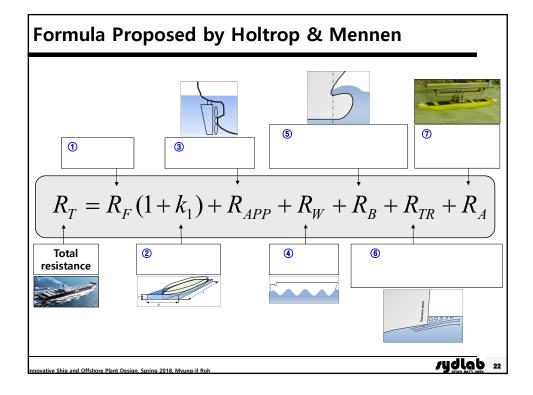
Therefore, <u>a statistical method was presented</u> for the determination of the required propulsive power at the initial design stage.

This method was developed through a <u>regression analysis of random</u> model experiments and full-scale data.

Many naval architects use the method, generally in the form presented in 1984 and find it gives acceptable results although it has to said that a number of the formula seem very complicated and the physics behind them are not at all clear, (a not infrequent corollary of regression analysis).

* Holtrop and Mennen's method, which was originally presented in the *Journal of International Shipbuilding Progress*, Vol. 25 (Oct. 1978), revised in Vol. 29 (July 1982) and again in N.S.M.B. Publication 769 (1984) and in a paper presented to SMSSH'88 (October 1988), meets all criteria with formulae derived by regression analysis from the considerable data bank of the Netherlands Ship Model Basin being provided for every variable

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4. Resistance Prediction by Holtrop-Mennen's Method for a 3,700 TEU Container Carrier

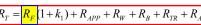
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Resistance Prediction by Holtrop and Mennen's Method Example) 3,700 TEU Container Carrier

B _{mld} 32.2 m D _{mld} 19.3 m Td /Ts (design / scantling) 10.1 / 12.5 m Deadweight (design / scantling) 34,400 / 50,200 MT(metric ton) Displacement Volume at Td 49,652.7 m³	Transverse bulb area Center of bulb area abov Transom area Wetted area appendages Stern shape parameter Propeller diameter Number of propeller blac Clearance propeller with	des	15.2 m ² 5.5 m ² 0 m ² 317.74 m ² V-shaped 7.7 m 5 0.3 m
245.24 m 239.26 m 32.2 m 32.2 m 32.2 m 10.1 / 12.5 m 246.02 m 34.400 / 50,200 MT(metric ton) 249,652.7 m ³	Transom area Wetted area appendages Stern shape parameter Propeller diameter Number of propeller blac	des	0 m ² 317.74 m ² V-shaped 7.7 m
239.26 m B_{mid}	Wetted area appendages Stern shape parameter Propeller diameter Number of propeller blad	des	317.74 m ² V-shaped 7.7 m 5
Section Sect	Stern shape parameter Propeller diameter Number of propeller blad	des	V-shaped 7.7 m 5
19.3 m 19.3 m 10.1 / 12.5 m 10.1 / 12.5 m 20.2	Propeller diameter Number of propeller blace		7.7 m 5
### Total Total (design / scantling) ### 10.1 / 12.5 m Deadweight (design / scantling) ### 34,400 / 50,200 MT(metric ton) ### 49,652.7 m³ ### LCB ### -0.531% aft of 1/2LBP ### 0.9761	Number of propeller blac		5
Deadweight (design / scantling) 34,400 / 50,200 MT(metric ton) Displacement Volume at Td 49,652.7 m³ LCB -0.531% aft of 1/2L _{BP} Midship section coefficient (C _M) 0.9761			1 -
Displacement Volume at Td $49,652.7 \text{ m}^3$ LCB -0.531% aft of $1/2L_{BP}$ Midship section coefficient (C_M) 0.9761	Clearance propeller with	h keel line	0.3 m
LCB -0.531% aft of 1/2L _{BP} Midship section coefficient (C _M) 0.9761			
Midship section coefficient (C_M) 0.9761			
·			
Waterplane are coefficient (C.) 0.7724			
waterplane are coefficient (C _W) 0.7734			
Capacity			
Container on deck / in hold 2,174 TEU / 1,565 TEU			
Ballast water 13,800 m ³			
Heavy fuel oil 6,200 m ³			
Main Engine & Speed			
M / E type Sulzer 7RTA84C			
MCR (BHP x rpm) 38,570 x 102			
NCR (BHP × rpm) 34,710 × 98.5			
Service speed at NCR (Td, 15% SM) 22.5 knots (at 11.5 m) at 30,185 BHP			
DFOC at NCR 103.2 MT			
Cruising range 20,000 N.M			
Others Complement (Crew) 30 Person			







3,700 TEU Container Carrie			
ltem	Value		
V	22.5 knots		
L _{WL}	239.26 m		
ν	1.19×10^{-6}		

 $C_{\!\scriptscriptstyle F}$: Coefficient of frictional resistance (ITTC 1957 friction formula)

$$C_F = \frac{0.075}{(\log R_n - 2)^2}$$
 $R_n = \frac{V \cdot L}{V}$ R_n is based on the waterline length (L_{WL})

$$R_n = \frac{V \cdot L}{V}$$

Example 3.700 TEU CTN Carrier)

$$R_n = \frac{V \cdot L_{WL}}{V} = \frac{11.8312 \times 239.26}{1.19 \times 10^{-6}} = 2.33 \times 10^9$$

$$C_F = \frac{0.075}{(\log R_n - 2)^2} = \frac{0.075}{(\log 2.33 \times 10^9 - 2)^2} = 1.38 \times 10^{-3}$$

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① Frictional Resistance (2/3) $R_T = \frac{|R_F|}{|R_F|} (1 + k_1) + R_{APP} + R_W + R_B + R_{TR} + R_A$

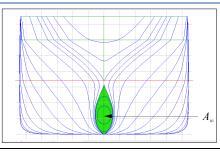
$$R_F = \frac{1}{2} \rho V^2 C_F S_{bh}$$

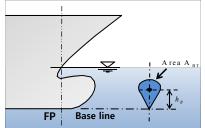
 $S_{\it bh}$: Wetted surface area of the bare hull

 $A_{\rm RT}$: Transverse bulb area

Definition of A_{BT} [L²]:

The cross sectional area (full section port and starboard) at the fore perpendicular. Where the water lines are rounded so as to terminate on the fore perpendicular A_{BT} is measured by continuing the area curve forward to the perpendicular, ignoring the final rounding (Reference: ITTC).





① Frictional Resistance (3/3) $R_T = R_F (1+k_1) + R_{APP} + R_W + R_B + R_{TR} + R_A$

$$R_T = \frac{R_F}{(1+k_1)} + R_{APP} + R_W + R_B + R_{TR} + R_T$$

$$R_F = \frac{1}{2} \rho V^2 C_F S_{bh}$$

C_F=0.001378 ρ=1.025 ton/m³

3,700 TEU Container Carrier		
Item	Value	
L (L _{WL})	239.26 m	
T	10.1 m	
В	32.2 m	
C _M	0.9761	
C _{WP}	0.6761	
A _{BT}	15.2 m²	
C _B	0.6394	

S_{bb} : Wetted surface area of the bare hull

$$S_{bh} = L(2T+B)\sqrt{C_M}\left(0.4530 + 0.4425C_B - 0.2862C_M - 0.003467B/T + 0.3696C_{WP}\right) + 2.38A_{BT}/C_B$$

In this formula, the hull form coefficients are based on the waterline length (L_{WL}) .

Example 3.700 TEU CTN Carrier)

$$S_{bh} = L(2T+B)\sqrt{C_M}(0.4530+0.4425C_B-0.2862C_M-0.003467B/T+0.3696C_{WP}) + 2.38A_{BT}/C_B$$

$$= 239.26(2\times10.1+32.2)\sqrt{0.9761}(0.4530+0.4425\times0.6394-0.2862\times0.9761-0.003467\times32.2\div10.1+0.3696\times0.6761)$$

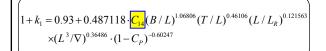
$$+2.38 \times 15.2 \div 0.6394$$

= 8,670.24[m^2]

$$\therefore R_F = \frac{1}{2} \rho V^2 C_F S_{bh} = \frac{1}{2} \times 1.025 \times 11.574^2 \times 1.38 \times 10^{-3} \times 8,670.24 = 822.61[kN]$$

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② Form Factor of the Bare $H_{R_T} = R_F (1+k_1) + R_{APP} + R_W + R_B + R_{TR} + R_A$

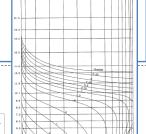


$C_{{\scriptscriptstyle 1}{\scriptscriptstyle 4}}$: The prismatic coefficient based on the waterline length

$$C_{14} = 1 + 0.011C_{stern}$$

 $C_{\it stern} \ = -25$ Pram stern with gondola $=\!-10 \;\; \text{V-shaped sections}$

Normal section shape



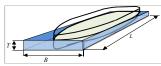
Example 3.700 TEU CTN Carrier)

$$C_{stern} = -10$$

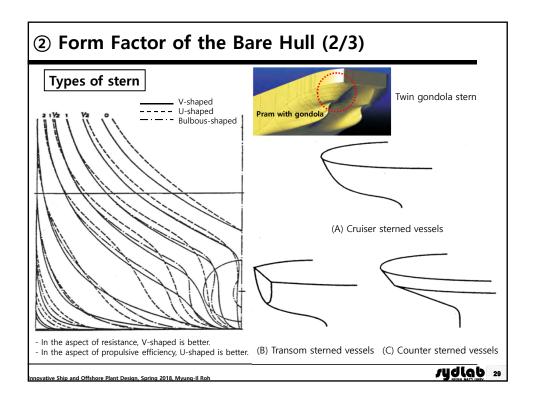
$$C_{14} = 1 + 0.011C_{stern}$$

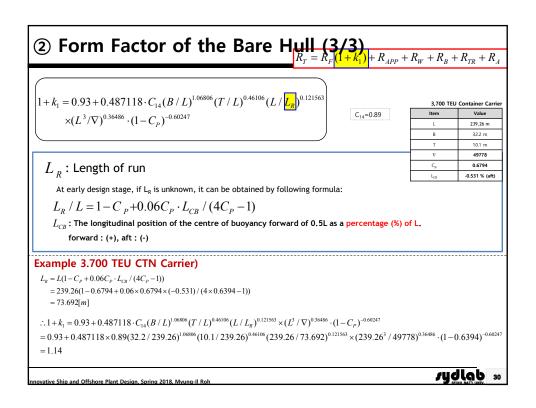
= 1 + 0.011×(-10)

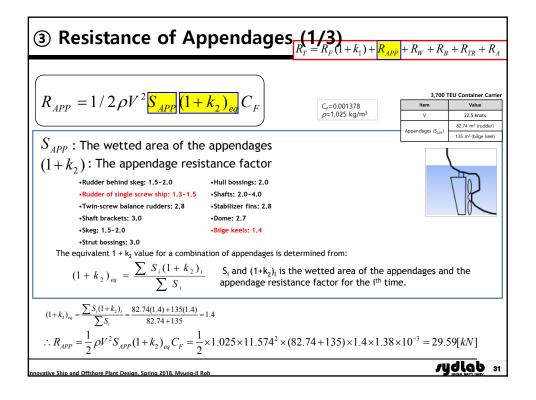
=0.89

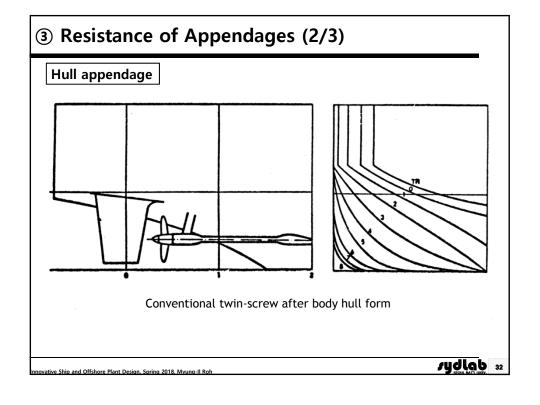


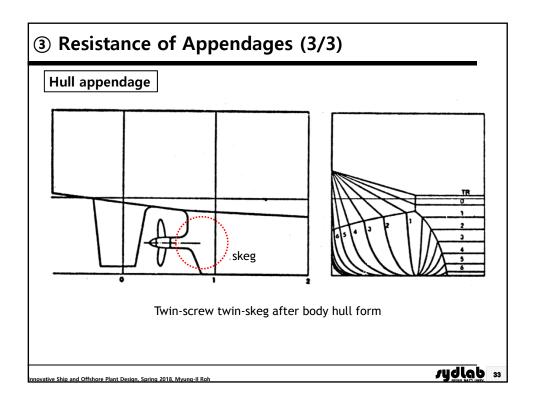
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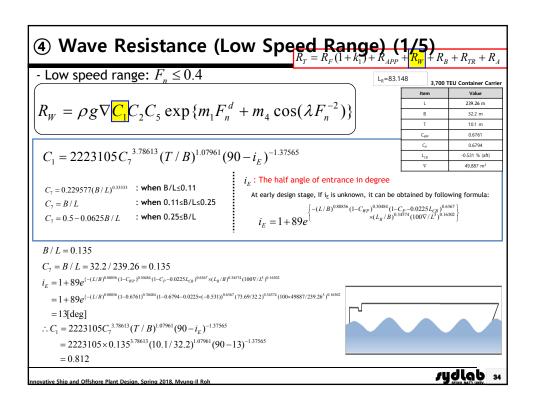






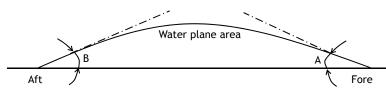






4 Wave Resistance (Low Speed Range) (2/5)

Meaning of a entrance angle

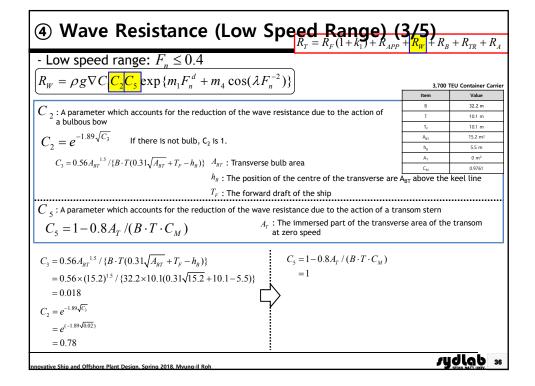


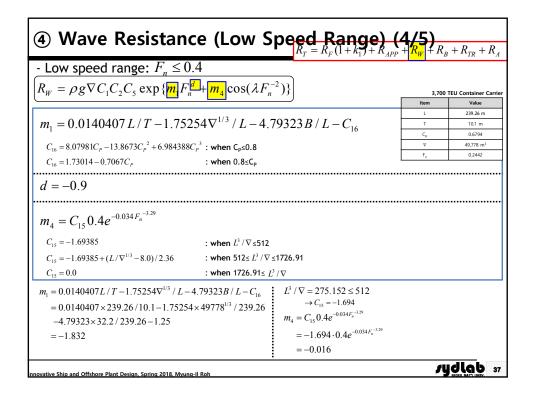
B: Angle of run of waterline

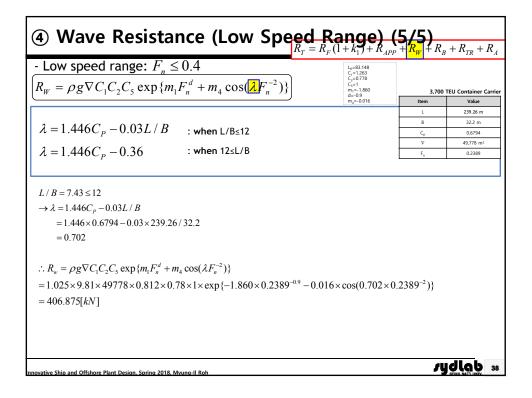
A: Angle of entrance of waterline ($i_{\rm E}$)

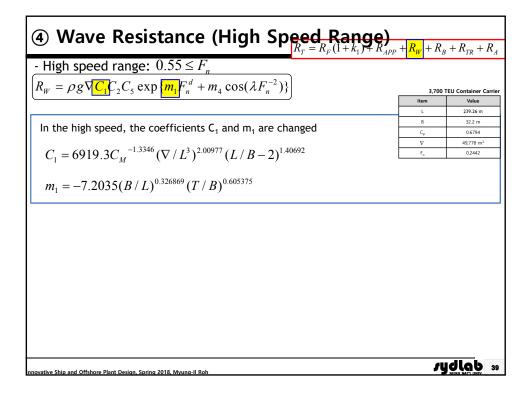
 \dot{l}_E : The half angle of entrance is the angle of the waterline at the bow in degrees with reference to the center plane but neglecting the local shape at the stem.

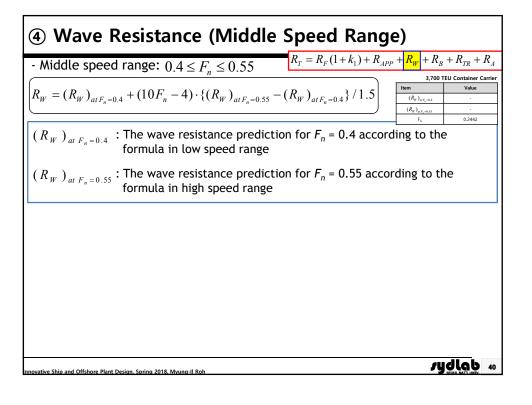
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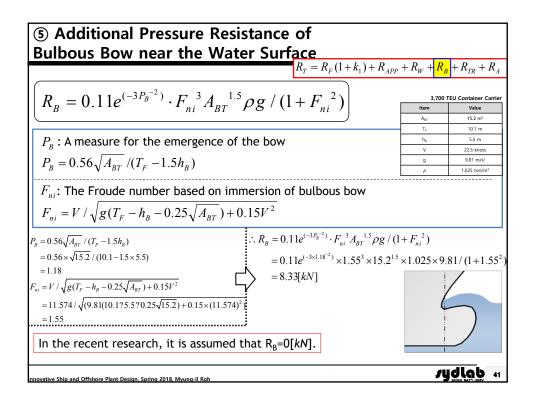


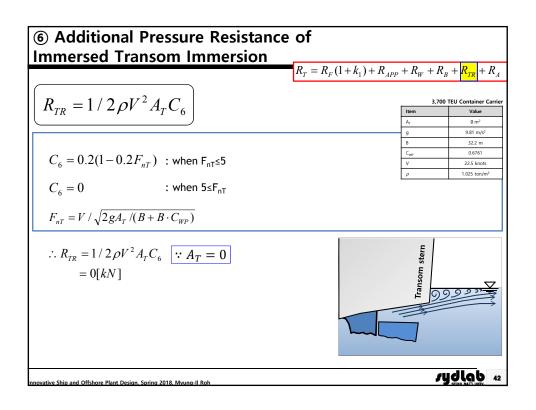












7 Model-Ship Correlation Resistance (1/2)

 $R_T = R_F (1 + k_1) + R_{APP} + R_W + R_B + R_{TR} + \frac{R_A}{R_A}$

 $R_A = 1/2\rho V^2 S_{total} C_A$

The model-ship correlation resistance R_{A} is supposed to describe primarily the effect of the hull roughness and the still-air resistance.

3,700 TEU Container Carrie			
Item	Value		
L	239.26 m		
CB	0.6394		
T _F	10.1 m		
V	22.5 knots		
ρ	1.025 ton/m ³		
S _{total}	9465.74 m ²		

 $C_A = 0.006(L+100)^{-0.16} - 0.00205 + 0.003\sqrt{L/7.5}C_B^4C_2(0.04-C_4)$

 $C_4 = T_{\scriptscriptstyle F} \, / \, L$: when $T_{\scriptscriptstyle F} \, / \, L \, \leq \! 0.04$

 $C_4 = 0.04$: when 0.04 < $T_{\scriptscriptstyle F}$ / L



 $T_F / L = T_F / L$

=10.1/239.26=0.042

Because $0.04 \le T_F/L$

$$\begin{split} C_A &= 0.006(L+100)^{-0.16} - 0.00205 + 0.003\sqrt{L/7.5}C_B^{-4}C_2(0.04 - C_4) \\ &= 0.006(239.26 + 100)^{-0.16} - 0.00205 + 0.003\sqrt{239.26/7.5}0.6241^4 \times 0.629(0.04 - 0.04) = 0.000312 \end{split}$$

 $\therefore R_A = \frac{1}{2} \rho V^2 S_{total} C_A = \frac{1}{2} \times 1.025 \times 11.574^2 \times 9625.74 \times 0.000312 = 202.705[kN]$

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Model-Ship Correlation Resistance (2/2)

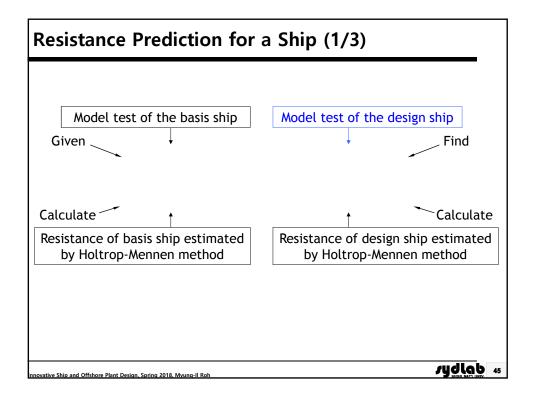
 $R_T = R_F (1 + k_1) + R_{APP} + R_W + R_B + R_{TR} + R_A$

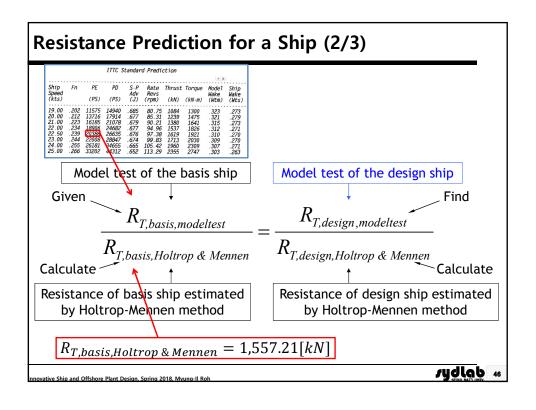
3,700 TEU Container Carrie		
Item	Value	
R _F	822.61 kN	
(1+k1)	1.14	
R _{APP}	29.59kN	
R _W	406.875 kN	
RB	0 kN	
R _{TR}	0 kN	
R _A	202.705 kN	

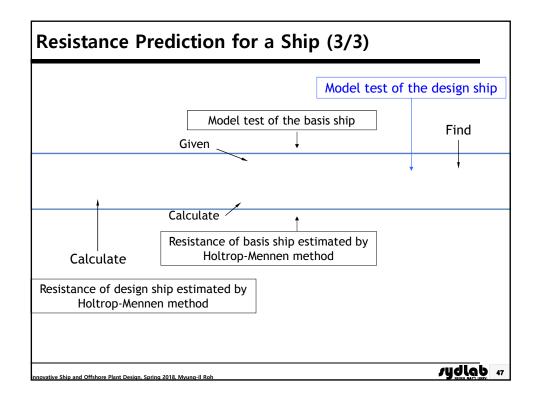
 $R_T = 822.61 \times (1.14) + 29.59 + 406.875 + 0 + 0 + 202.705 = 1,577.21$

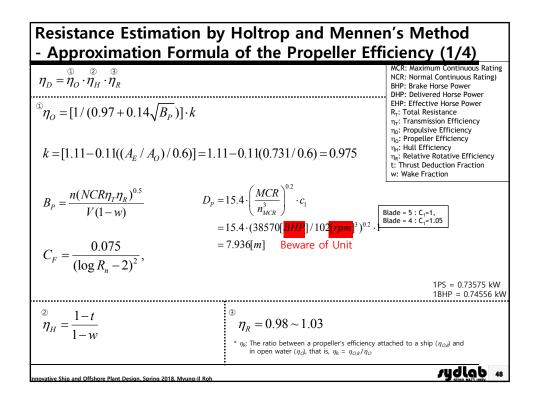
 $\therefore R_{T,basis,Holtrop \& Mennen} = 1,577.21[kN]$

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Resistance Estimation by Holtrop and Mennen's Method Approximation Formula of the Propeller Efficiency (2/4) MCR: Maximum Continuous Rating NCR: Normal Continuous Rating) $\eta_D = \stackrel{\tiny \scriptsize \textcircled{1}}{\eta_O} \cdot \stackrel{\tiny \scriptsize \textcircled{2}}{\eta_H} \cdot \stackrel{\tiny \scriptsize \textcircled{3}}{\eta_R}$ BHP: Brake Horse Power DHP: Delivered Horse Power EHP: Effective Horse Power $0.0661875 + 1.21756c_{11} \frac{C_{\gamma}}{(1 - C_{p_1})}$ R_T: Total Resistance η_T : Transmission Efficiency η_D : Propulsive Efficiency η_{O} : Propeller Efficiency η_{H} : Hull Efficiency $-\frac{0.09726}{0.95-C_{_{P}}}+\frac{0.11434}{0.95-C_{_{B}}}+0.75C_{_{\mathit{stern}}}C_{_{V}}+0.002C_{_{\mathit{stern}}}$ η_R : Relative Rotative Efficiency t: Thrust Deduction Fraction $=14.55\times0.003\frac{239.26}{10.1}\left(0.0661875+1.21756\times1.27\frac{0.003}{(1-0.682)}\right)$ 0.09726 + 0.11434 $-+0.75 \times (-10) \times 0.003 + 0.002(-10)$ 239.26(1 – 0.682) 0.95 – 0.682 0.95 – 0.6394 $c_s = BS/(LD_pT_A) = 32.2 \times 8670.24/(239.26 \times 7.936 \times 10.1) = 14.55$ (: B/T_a = 3.19) $c_{_{8}} = BS / (LD_{P}T_{_{4}})$ when $B/T_{\perp} < 5$ $c_{\circ} = S(7B/T_{\circ} - 25)/(LD_{P}(B/T_{\circ} - 3))$ when B/T > 5 $c_{\circ} = 14.55$ when $c_s < 28$ $(\because c_{_{8}} = 14.55)$ $c_9 = 32 - 16 / (c_8 - 24)$ when $c_{_8} > 28$ $c_{_{11}} = 1.27$ $c_{11} = T_A / D_P$ when $T_A / D_P < 2$ $c_{11} = 0.0833333(T_A/D)^3 + 1.33333$ when $T_A/D_P > 2$ $(:: T_1 / D_P = 1.27)$

 $C_{V} = (1+k)C_{E} + C_{A} = (1+0.975) \times 0.001378 + 0.000312 = 0.003$

 $C_{p1} = 1.45C_p - 0.315 - 0.0225LCB = 1.45 \times 0.6794 - 0.315 - 0.0224 \times (-0.531) = 0.682$

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 $C_{V} = (1+k)C_{F} + C_{A}$ $C_{P1} = 1.45C_{P} - 0.315 - 0.0225LCB$

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Resistance Estimation by Holtrop and Mennen's Method Approximation Formula of the Propeller Efficiency (3/4) MCR: Maximum Continuous Rating NCR: Normal Continuous Rating) 1 2 3 $\boldsymbol{\eta}_D = \boldsymbol{\tilde{\eta}}_O \cdot \boldsymbol{\eta}_H \cdot \boldsymbol{\eta}_R$ BHP: Brake Horse Power DHP: Delivered Horse Power EHP: Effective Horse Power $t = 0.001979L/(B - BC_{p_1}) + 1.0585c_{10}$ R_T: Total Resistance $\eta_{\text{T}}\text{:}$ Transmission Efficiency $\eta_{\text{D}}\text{:}$ Propulsive Efficiency $-0.00524 - 0.1418D^2/(BT) + 0.0015C_{stern}$ η₀: Propeller Efficiency η_{H} : Hull Efficiency η_{R} : Relative Rotative Efficiency $= 0.001979 \times 239.26 / (32.2 - (32.2 \times 0.682)) + 1.0585 \times 0.13$ t: Thrust Deduction Fraction $-0.00524 - 0.1418 \times 7.936^2 / (32.2 \times 10.1) + 0.0015 \times (-10)$ =0.141 $\eta_R = 0.9922 - 0.05908A_E / A_O + 0.07424(C_P - 0.0225LCB)$ 1 - 0.141 $= 0.9922 - 0.05908 \times 0.731 + 0.07424(0.6794 - 0.0225 \times (-0.531))$ $^{-}$ 1-0.211 =1.00=1.09If number of shaft = 2 $\eta_R = 0.9737 + 0.111(C_P - 0.0225LCB) - 0.06325P_i / D_P$ $c_{10} = 0.25 - 0.003328402 / (B / L - 0.134615385)$ when L/B < 5.2 $c_{10} = 0.13$ (:: L / B = 7.43)Thrust deduction fraction or coefficient (t): Additional resistance on the hull due to the rotation of the propeller sydlab 50 ative Ship and Offshore Plant Design, Spring 2018, Myung-II Roh

