# Aircraft Structural Analysis

#### Chapter 5 Load Transfer in Stiffened Panel Structures



Point loads acting on idealized wing and fuselage structures cannot be applied directly to the shear panels, which are capable of supporting only pure shear exerted in their plane, along and in the direction of their boundaries. In section 2.5, we studied planar assemblies of rods and shear webs. In that type of structure, the rods act as stiffeners to which direct loads are applied and by means of which the loads are diffused to the shear panels. For wing and fuselage structure, the analogous stiffening members are the rib and frame, respectively.



Cantilevered thin-walled cylinder with point load P

The load P can not be applied directly to the fragile skin, so a "hard point" must be provided.



**Figure 5.1.1** (a) Thin-walled cylinder with a point load applied to a ring stiffener. (b) Shear flow applied to the skin by the stiffener. (c) Free-body diagram of the stiffener, with the shear flow applied by the skin in equilibrium with the load *P* applied at the lug.

The formula for shear flow distribution is,

$$q = \frac{P}{\pi r} \sin \phi$$







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Figure 5.1.3

(a) Pure bending of a thin-walled box beam with a junction at section A. (b) At A, the membrane forces per unit length n in the upper and lower walls must be reacted to by the rib force p.

Force intensity 
$$p = 2n \sin \frac{\phi}{2}$$



Consider a transverse shear (a rib or a fuselage frame or bulkhead) together with the attached skin. Let loads be applied to the stiffener, in its plane, as illustrated in Figure 5.2.1

The difference in the section shear loads on each side of the stiffener is due to the load applied directly to the stiffener

$$P_y = V_y^+ - V_y^- = \Delta V_y$$
$$P_z = V_z^+ - V_z^- = \Delta V_z$$

The subscript '-' and '+' represent the positions just fore and aft of the stiffener, respectively









Difference between the shear flows fore and aft of the stiffener

The shear flow  $\tilde{q}$  which acts at on the skin along the stiffener-skin interface, where the skin is bonded to the frame



Figure 5.2.2 Shear flows immediately fore and aft of a stiffener and along the bond line.

$$\tilde{q} = q^+ - q^- \qquad \qquad \Delta \tilde{q} = \Delta q^+ - \Delta q^-$$

 $\Delta q^+$  and  $\Delta q^-$  are obtained from Eq 4.7.3

 $\Delta \tilde{q} = \frac{1}{(I_{-}I_{-} - I^{2})} \{ [I_{y}(V_{y}^{+} - V_{y}^{-}) - I_{yz}(V_{z}^{+} - V_{z}^{-})]Q_{z} + [I_{z}(V_{z}^{+} - V_{z}^{-}) - I_{yz}(V_{y}^{+} - V_{y}^{-})]Q_{y} \}$  $\Delta \tilde{q} = \tilde{q}_{2} - \tilde{q}_{1} = \frac{1}{(I_{y}I_{z} - I_{yz}^{2})} \left[ (I_{y}P_{y} - I_{yz}P_{z})Q_{z} + (I_{z}P_{z} - I_{yz}P_{y})Q_{y} \right]$ 



For idealized beams, for which, in walls joining longitudinal stiffeners, the shear flow is constant, Eq 4.8.2 and Eq 4.8.3 -for computing section shear flows-take the following form for calculating the bond line shear flow:

 $P_{x}^{\prime(f)} = \frac{1}{I_{y}I_{z} - I_{yz}^{2}} \left[ (I_{y}V_{y} - I_{yz}V_{z})y_{f} + (I_{z}V_{z} - I_{yz}V_{y})z_{f} \right]A_{f}$ Eq. 4.8.2  $P_{x}^{\prime(f)} = \sum_{i=1}^{No. \text{ of webs}} q^{(i)}$ Eq. 4.8.3

No. of webs  $\sum_{i=1}^{\text{No. of webs}} \tilde{q}^{(i)} = \tilde{P}_x^{\prime(f)}$ 

where

$$\tilde{P}_{x}^{\prime(f)} = \frac{1}{I_{y}I_{z} - I_{yz}^{2}} \left[ \left( I_{y}P_{y} - I_{yz}P_{z} \right) y_{f} + \left( I_{z}P_{z} - I_{yz}P_{y} \right) z_{f} \right] A_{f}$$

-> The jump in the frange load gradient across a stiffener

$$\widetilde{P_x}'^{(f)} = (\widetilde{P_x}'^{(f)})^+ - (\widetilde{P_x}'^{(f)})^-$$



The procedure for calculating the shear flow around a transverse stiffener.

- Remove the frame from the skin-stringer structure.
- Transfer the frame loads to the skin-stringer structure,
- Calculate statically equivalent shear flow distribution around the periphery.
- Reverse the computed shear flow directions to show them acting on the frame.







#### Example 5.2.1

Verify Equation 5.1.1 for the ring stiffener in Figure 5.1.1 There are no longitudinal stiffeners; the skin is effective in both shear and bending. Assume the thickness t of the skin is very small compared to the radius r.







The area moment of inertia about the z axis is,

$$I_{z} = \iint_{A} y^{2} dA = \int_{0}^{2\pi} (r \cos \phi)^{2} (tr d\phi) = \pi r^{3} t$$
 [a]

By symmetry,  $I_y = I_z$  ,  $I_{yz} = 0$ 

$$P_y = -P$$
 ,  $P_z = 0$ 

Thus, 
$$\Delta \tilde{q} = \frac{P_y Q_z}{I_z} = -\frac{P}{\pi r^3 t} Q_z$$

The moment of the area of an arc of the circle, starting at O and subtended by the angle  $\Phi,$  is

$$Q_z = \iint_A y dA = \int_0^\phi (r \cos \phi') (tr d\phi') = r^2 t \sin \phi$$

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[c]

[b]

[d]

Substituting Eq [c] into [b],

$$\tilde{q} = \tilde{q}_o - \frac{P}{\pi r} \sin \phi$$

The resultant moment of this shear flow about G is zero

$$\int_{0}^{2\pi} r \times (\tilde{q}rd\phi) = 0$$
$$r^{2} \int_{0}^{2\pi} \left( \tilde{q}_{o} - \frac{P}{\pi r} \sin\phi \right) d\phi = 2\pi r^{2} \tilde{q}_{o} = 0$$

 $\widetilde{q_o} = 0$  , so that eq [d] becomes

$$\tilde{q} = -\frac{P}{\pi r}\sin\phi$$



Consider the more complex situation illustrated in Figure 5.2.5 in which <u>there are five stiffeners</u>, A through E. The stiffener at D is loaded precisely as the one in Figure 5.1.1, so its peripheral shear flow distribution will be identical. By the same token, <u>in spite of the fact that loads are applied to the structure on either side of the stiffener at C, since C itself has no concentrated load, the shear flow around its perimeter is zero.</u>





Figure 5.2.5

Stiffened cylinder with several concentrated loads.



#### Example 5.2.2

Consider the cantilever box beam of square cross section illustrated in Figure 5.2.6. Point loads are applied to the frames at sections A,B,C, and D, as shown. Calculate (a) the panel shear flows in each of the two bays adjacent to section C, and (b) the shear flow around the perimeter of frame C







(a)  

$$I_y = I_z = 4[5^2(1)] = 100 \text{ in.}^4$$
  
 $P'_x(f) = \left(\frac{V_y y}{I_z} + \frac{V_z z}{I_y}\right) A_f = 0.01(V_y y + V_z z)$  [a]  
Between section B and C  
 $V_y = 1000 \text{ lb}$   $V_z = -1500 \text{ lb}$   
 $\sum q_{out} = \sum q_{in} + P'_x(f)$  [b]  
 $2 \times 50 \times (q_o + 125) + 2 \times 50 \times q_o = 0$   
 $q_o = -62.5 \text{ lb/in.}$  [C]

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비가 지방했다. 그네.

#### Between C and D



Substituting equations [c] and [d],



(a) Shear flows in the bay immediately ahead of section C.(b) Shear flows in the bay immediately aft of section C.

3000 lb

4 (-275 lb/in.)

(275 lb/in.)  $2 q_o + 125 1$  (125 lb/in.)

1000 lb  $igg q_o + 275$ 

[50 in.<sup>2</sup>]

1500 lb

 $q_{o} + 400$ 

(-125 lb/in.) 3

(b)



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in the second second

#### Example 5.2.3

Figure 5.2.13 shows a 100 in. diameter circular fuselage frame with a 1000lb Vertical load applied to the floor beam. The 24 equally spaced stringers all have the same 0.2 in. area. Calculate the shear flow distri-bution around the frame.



### Figure 5.2.13 Circular fuselage frame with a load applied to the floor beam.



Remove the frame and numbering the stringers.



$$I_{z} = \sum_{i=1}^{24} y_{i}^{2} A_{i} = A_{f} \sum_{i=1}^{24} y_{i}^{2}$$
$$I_{z} = A_{f} [2y_{1}^{2} + 4(y_{2}^{2} + y_{3}^{2} + y_{4}^{2} + y_{5}^{2} + y_{6}^{2})]$$
$$= 6000 \text{ in.}^{4}$$

 $\tilde{P}_{x}^{\prime(i)} = \frac{P_{y} y_{i}}{I_{z}} A_{i} = 0.03333 y_{i}$ 

Since the moment of the shear flows equals the moment of the vertical 1000lb load,

$$2Aq_o + 2\left(\frac{A}{24}\right) [2(1.667 + 3.277 + 4.720 + 5.898 + 6.731 + 7.163)]$$
  
-2\left(\frac{A}{24}\right) [2(1.610 + 3.053 + 4.231 + 5.064 + 5.496)] = -(20 \times 1000)]  
q\_o = -2.107 lb/in.



(a)

Shear flows exerted by the frame on the skin

Shear flows exerted by the skin on the frame

0.440 j 2.10

(b)

1.17 0.440

2.61

3.79

4.62

5.06

5.06

4.62

3.79

2.61

2.10

20"

3.72

1000 lb

5.16

6.34

7.17

7.60

7.60

7.17

6.34

5.16

3.72

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1.17



#### Example 5.2.4

A concentrated load of 5000lb is applied to the wing rib in Figure 5.2.17 at the point where the left most vertical stiffener ef joins the bottom rib flange. The area of the front and rear spar caps (6,7,1, and 12) is 0.3 in. . and the area of the eight numbered stringers is 0.1 in. Calculate the average shear flow in each of the four rib webs and the axial loads in the rib flanges at the location just to the right of the vertical stiffeners ef, cd, and ab. (The rib is bonded to the front and rear spar webs and to the wing skin along the rib flanges, whereas the spanwise stringers are bonded to the wing skin.)



Figure 5.2.17 Wing box rib with a point load applied to the leftmost vertical stiffener. National Research Laboratory for Aerospace Structures



Rib is removed and replaced by the shear flows acting around the bond line between the rib and the wing skin and spar webs.

- 1. Calculate the location of the centroid G of the flange area.
- 2. Compute the area moments of inertia  $I_y$ ,  $I_z$ , and  $I_{yz}$  relative to axes through the centroid.
- 3. Substitute the area moments of inertia, along with  $P_y = 5000 \cos 20^\circ$  and  $P_z = -5000 \sin 20^\circ$ , into Equation 5.2.4 to obtain the jump in flange load gradients, which are shown in parentheses in the figure.
- 4. Set the shear flow equal to  $q_o$  in one of the webs, say 12–1, and starting with flange 1, work your way counterclockwise around the section, applying Equation 5.2.3, "shear flow out equals shear flow in plus flange load gradient," at each flange, assuming all shear flows are counterclockwise, to calculate each of the web shear flows in terms of  $q_o$ .
- 5. Set the moment of the shear flow distribution about a point, say f, equal to the moment of the applied load about that same point. Solve the equation for the only unknown, namely  $q_o$ .
- 6. For each of the twelve skins, substitute  $q_o$  into the expression for shear flow computed in Step 4, finally yielding the shear flows shown in Figure 5.2.18.











Figure 5.2.19 Shear flows acting on the rib in reaction to the 5000 lb load.

 $\bar{q}_1 = 380.2 \times \frac{9}{8.25} = 414.8 \, \text{lb/in.}$ 











$$\sum M_c = 0: \quad 7.5P_d + 7.5 \times 5000 \sin 20^\circ + 10 \times 5000 \cos 20^\circ - 20 \times (380.2 \times 9) \\ -7.5 \times (182.4 \times 8 + 118.8 \times 8 + 57.54 \times 4) = 0$$
  
$$\sum F_z = 0: \quad P_c \cos 4.289^\circ + P_d + 5000 \sin 20^\circ + (144.7 + 73.58 - 182.4 - 118.8) \times 8 \\ + (9.762 - 57.54) \times 4 = 0$$
  
$$\sum F_y = 0: \quad -P_c \sin 4.289^\circ + 7.5q_{cd} - 5000 \cos 20^\circ + 380.2 \times 9 \\ - (144.7 + 73.58) \times (8 \tan 4.289^\circ) - 9.762 \times (4 \tan 4.289^\circ) = 0$$
  
$$P_d = 3790 \text{ lb} \qquad P_c = -4658 \text{ lb} \qquad q_{cd} = 141.6 \text{ lb/in.}$$

$$\bar{q}_3 = 141.6 \times \frac{7.5}{6.75} = 157.3$$
 lb/in.







 $\sum M_a = 0: -6.75P_b + 10 \times (221.4 \times 6) + 6.75 \times (1.462 \times 2 + 58.17 \times 8) = 0$   $\sum F_z = 0: -P_a \cos 4.289^\circ - P_b + (1.462 - 46.73) \times 2 + (58.17 - 95.89) \times 8 = 0$  $\sum F_y = 0: +P_a \sin 4.28^\circ - 6.75q_{ab} + 221.4 \times 6 + 46.73 \times (2 \tan 4.289^\circ) + 95.89 \times (8 \tan 4.289^\circ) = 0$ 

 $P_b = 2436$  lb  $P_a = -2836$  lb  $q_{ab} = 174.9$  lb/in.

$$\bar{q}_4 = 174.9 \times \frac{6.75}{6} = 221.4 \times \frac{6}{6.75} = 196.8$$
 lb/in.





Figure 5.2.23 Shear flows around the boundaries of the rib webs.

The average shear flows are shown on the nonparallel edges.



What effect do the cutouts have on the shear flow distribution?



Figure 5.3.1 Portion of a fuselage panel with regularly spaced cutouts (windows).

Assumtion : The effect of the windows on the shear flow pattern does not extend more than one shear panel beyond the top and bottom of the cutouts.





#### Figure 5.3.2

Free-body diagrams of portions of the panel: (a) Spans the midpoints of the stringer above two adjacent cutouts, the top edge extending into the uniform shear flow region and the bottom edge lying just above the top of the window line; (b) same as in (a), except the bottom edge extends into the panel between the windows; (c) the top and bottom edges extend to the uniform shear flow region; the left edge cuts through the midpoint of a window, and the right edge extends into the region between windows.



For the free-body diagram in Figure 5.3.2a, the equilibrium of forces in the horizontal direction requires that

 $q_2w + q_3d_f = q_0\left(d_f + w\right)$ 

From part (b) of the figure, we deduce similarly that

$$q_1 d_f = q_0 \left( d_f + w \right)$$

Finally, summing forces in the vertical direction in Figure 5.3.2c yields

$$q_1h - 2q_2d_s + 2q_3d_s = 0$$

The solution of these three equations for  $q_1$ ,  $q_2$ ,  $q_3$  is

$$q_1 = q_0 \left( 1 + \frac{w}{d_f} \right) \quad q_2 = q_0 \left( 1 + \frac{h}{2d_s} \right) \quad q_3 = q_0 \left( 1 - \frac{hw}{2d_f d_s} \right)$$



#### Example 5.3.1

The flat, stiffened, panel structure in Figure 5.3.3a is loaded by a uniform shear flow  $q_0 = 50 \text{ KN} / \text{m}$  on its boundary, as shown. (a) Calculate the independent shear flows  $q_1$  and  $q_2$ . (b) Find the location and value of the maximum load within the stiffeners.







We can determine the effect of a cutout on an idealized wing box or fuselage structure



Figure 5.4.1 (a) Rectangular box beam with shear flow  $q_o$  applied as shown to the vertical panel bdhf of the central bay. (b) Shear flow around a section through the central bay.



#### The net force on the stringer

$$-2(q_1L) + 2(q_0L) - 2(q_2L) = 0$$

a

 $q_1 + q_2 = q_0$ 

By symmetry,

$$q_1 = q_2 = \frac{q_o}{2}$$



Figure 5.4.2

Free-body diagram of a stringer, through which the shear flow  $q_o$  is related to the shear flow in the adjacent bays.

The axial load's maximum value P occurs at each end of the center bay.

$$P = 2 \times \left(\frac{q_o}{2}L\right) = q_o L$$





(a)

(b)

Figure 5.4.3

Free-body diagrams of segments of the stringer spanning (a) the fore bays and (b) the aft bays.





 $q_0L$ 



(b)

Figure 5.4.4

(a)

(a) Free-body diagram of a stringer segment spanning the central bay. (b) Flange load versus position within the central bay.







Figure 5.4.5 Free-body diagram of one-half of the structure, showing the shear flows in the central and forward bays.

The stringer loads are zero at each end of the figure.



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#### Example 5.4.1

Calculate the shear flows in the spar webs and cover skins of the idealized wing box shown in Figure 5.4.7. The geometric properties of the constant cross section are listed. The uniformly distributed airloads (15 lb/in, left, 3 lb/in, drag) on the wing have been lumped at the ribs, which are spaced 20 inches apart.



Figure 5.4.7 Idealized, constant-cross-section, cantilevered, multi-bay box beam with the bottom skin of bay D-E removed.



Analyze the structure as thought there were no cutout, using Beam theory and methods of Chapter 4.







 $(6q_1) \times 30 - (30 \times 10.8) \times 10 = 0$  $q_1 = 18.1$  lb/in. 1  $q_2 = 10.8$  lb/in.  $6q_1 - 4q_2 - 10q_3 = 0$  $q_3 = 6.52$  lb/in.  $20q_4 + 20q_5 - 10 \times 18.1 - 10 \times 10.8 = 0$  $-q_5 + q_7 = 0$  $-6q_4 + 4q_5 + 10q_6 = 0$  $(30q_7) \times 10 - (6q_4) \times 30 = 0$ 



 $q_4 = 9.05$  lb/in.  $q_5 = q_7 = 5.43$  lb/in.  $q_6 = 3.26$  lb/in.









D-E



D-E



Superposition of the shear flows due to the external loads (left) and those (center) arising from the reversed Figure 5.4.13 shear flow applied to bay D-E, yielding the shear flows modified by the presence of the cutout. All shear flow units are in lb/in.

