

# Mathematical Background in Aircraft Structural Mechanics

## CHAPTER 2. Basic Equations

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# 2.1 Constitutive laws for isotropic materials

## ❖ 3 types of relationships for the sol. of elasticity problems

- Equilibrium eqns
- Strain-displacement relationships
- Constitutive laws ... mechanical behavior of the material

### i) Homogeneity and isotropy

- "homogenous material" ... physical properties are identical at each point
- "isotropic material" ... physical properties are identical in all direction
  - Ex) mild steel, aluminum ... both homogeneous and isotropic
  - Composite material ... neither homogeneous nor isotropic -> heterogeneous, anisotropic
- "scale dependent" ...
  - ① At atomic level, Al is neither homogenous nor isotropic
    - > assumption of homogeneity and isotropy only hold for a very large number of atoms
  - ② High temperature turbine blade applications 

{	poly-crystalline	}	materials
	single crystal		

    - single crystal ... regular lattice structures -> homogeneous, but anisotropic
    - poly-crystalline ...

{	crystals oriented in a specific dir ->	"
	ex) forged metals	
	crystals arranged at random orientations ->	

{	homogeneous
	isotropic

      - ex) common structural metals(steel, Al)

# 2.1 Constitutive laws for isotropic materials

- ③ Composite material ... clearly anisotropic, but samples containing a very large number of fibers -> reasonably assumed as homogeneous

## ii) Material testing

- If deformation very small -> linear stress-strain relationship
- If large deformation -> material is ductile or brittle
- Tensile test ... 

strain	$\varepsilon_1 = \Delta l / l$	}	Stress-strain diagram
stress	$\sigma_1 = N / A$		

# 2.1 Constitutive laws for isotropic materials

## 2.1 Constitutive laws for isotropic materials

### ❖ 2.1.1 Homogeneous, isotropic, linearly elastic materials

- Small deformations -> linear stress-strain behavior

$$\sigma_1 = E \varepsilon_1 \quad \text{Hooke's law} \quad (2.1)$$

↑  
Young's modulus or modulus of elasticity [pa]

- Elongation of a bar ... lateral contraction

$$\varepsilon_1 = \frac{1}{E} \begin{cases} \sigma_1 \\ \sigma_2 \end{cases} \quad \varepsilon_2 = -\frac{\nu}{E} \begin{cases} \sigma_1 \\ \sigma_2 \end{cases} \quad \varepsilon_3 = -\frac{\nu}{E} \begin{cases} \sigma_1 \\ \sigma_2 \end{cases} \quad (2.2)$$

$$(2.3)$$

$\nu$  : Poisson's ratio

# 2.1 Constitutive laws for isotropic materials

## i) Generalized Hooke's law

- Deformation under 3 stress components ... sum of those obtained for each stress component

-> generalized Hooke's law

$$\varepsilon_1 = \frac{1}{E} [\sigma_1 - \nu(\sigma_2 + \sigma_3)] \quad (2.4a)$$

... extensional strains depend only on the direct stress and not on the shear stress  
<- isotropic material

## ii) Shear stress – shear strain relationships

- Pure shear state in a plane stress state

- 2 principal stresses  $\sigma_{p2} = -\sigma_{p1}, \sigma_{p3} = 0$

$$\varepsilon_1 = \frac{1+\nu}{E} \sigma_{p1}, \varepsilon_2 = -\frac{1+\nu}{E} \sigma_{p1}, \gamma_{12} = 0 \quad (2.5)$$

- on faces oriented at a 45° angle w.r.t. the principal stress directions

$$\tau_{s_{12}}^* = \sigma_{p2} = -\sigma_{p1}, \sigma_{s_1}^* = \sigma_{s_2}^* = 0 \quad (2.6)$$

\*, s: specially rotated axis with max shear stress

## 2.1 Constitutive laws for isotropic materials

$$\varepsilon_1^* = \frac{\varepsilon_1 + \varepsilon_2}{2} + \frac{\varepsilon_1 - \varepsilon_2}{2} \cos 2\theta + \frac{\gamma_{12}}{2} \sin 2\theta, \quad (1.94a)$$

$$\varepsilon_2^* = \frac{\varepsilon_1 + \varepsilon_2}{2} - \frac{\varepsilon_1 - \varepsilon_2}{2} \cos 2\theta - \frac{\gamma_{12}}{2} \sin 2\theta, \quad (1.94b)$$

$$\gamma_{12}^* = -(\varepsilon_1 - \varepsilon_2) \sin 2\theta + \gamma_{12} \cos 2\theta. \quad (1.94c)$$

$$\text{Eq.(1.94) } \rightarrow \quad \theta_s = 45^\circ, \gamma_{s12}^* = -(\varepsilon_1 - \varepsilon_2) = -\frac{2(1+\nu)}{E} \sigma_{p1}, \varepsilon_{s1}^* = \varepsilon_{s2}^* = 0 \quad (2.7)$$

$$\begin{aligned} \text{Eq.(2.6),(2.7) } \rightarrow \quad \gamma_{s12}^* &= -\frac{2(1+\nu)}{E} \sigma_{p1} = 2(1+\nu) \frac{\tau_{s12}^*}{E} = G \gamma_{s12}^* \\ \Rightarrow \quad G &= \frac{E}{2(1+\nu)} \quad \text{"shear modulus"} \end{aligned} \quad (2.8)$$

... generalized Hooke's law for shear strains

$$\gamma_{23} = \tau_{23} / G, \gamma_{13} = \tau_{13} / G, \gamma_{12} = \tau_{12} / G \quad (2.9)$$

# 2.1 Constitutive laws for isotropic materials

iii) Matrix form of the constitutive laws

➤ Compact matrix form of the generalized Hooke's law

$$\underset{=}{\mathcal{E}} = \underset{=}{S} \underset{=}{\sigma} \quad (2.10)$$

$$\underset{-}{\mathcal{E}} = \{\varepsilon_1, \varepsilon_2, \varepsilon_3, \gamma_{23}, \gamma_{13}, \gamma_{12}\}^T \quad (2.11a)$$

$$\underset{-}{\sigma} = \{\sigma_1, \sigma_2, \sigma_3, \tau_{23}, \tau_{13}, \tau_{12}\}^T \quad (2.11b)$$

# 2.1 Constitutive laws for isotropic materials

Eq(2.4)  $\rightarrow$

$$\underline{\underline{S}} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & -\nu & 0 & 0 & 0 \\ -\nu & 1 & -\nu & 0 & 0 & 0 \\ -\nu & -\nu & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2(1+\nu) & 0 & 0 \\ 0 & 0 & 0 & 0 & 2(1+\nu) & 0 \\ 0 & 0 & 0 & 0 & 0 & 2(1+\nu) \end{bmatrix}$$

Eq(2.9)  $\uparrow$

Absence of coupling between  
 { Axial stresses  
 Shear strains  
 And vice versa

(2.12)

➤ Stiffness form of the same laws

$$\underline{\underline{\sigma}} = \underline{\underline{C}} \underline{\underline{\varepsilon}} \quad (2.13)$$

$$\underline{\underline{C}} = [\cdot \cdot] \quad (2.14)$$



# 2.1 Constitutive laws for isotropic materials

iv) Plane stress state

$$\underline{\varepsilon} = \{\varepsilon_1, \varepsilon_2, \gamma_{12}\}^T \quad (2.15a)$$

$$\underline{\sigma} = \{\sigma_1, \sigma_2, \gamma_{12}\}^T \quad (2.15b)$$

$$C = \frac{E}{(1-\nu^2)} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \quad (2.16)$$

$\varepsilon_3$  does not vanish due to Poisson's ratio effect,  $\varepsilon_3 = -\nu(\sigma_1 + \sigma_2)$

v) Plane strain state

$$C = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & 0 \\ \nu & 1-\nu & 0 \\ 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix} \quad (2.17)$$

$\sigma_3$  does not vanish due to Poisson's ratio effect,  $\sigma_3 = \nu E \frac{(\varepsilon_1 + \varepsilon_2)}{(1+\nu)(1-2\nu)}$

# 2.1 Constitutive laws for isotropic materials

vi) The bulk modulus

➤ Volumetric strain ... Eq.(1.75)

$$e = \varepsilon_1 + \varepsilon_2 + \varepsilon_3 = \frac{1-2\nu}{E}(\sigma_1 + \sigma_2 + \sigma_3) = \frac{1-2\nu}{E}I_1 \quad (2.18)$$

➤ Hydrostatic pressure,  $\sigma_1 = \sigma_2 = \sigma_3 = p$

$$\rightarrow p = \kappa e, \quad (2.19)$$

$$\kappa = \frac{E}{3(1-2\nu)}: \text{"bulk modulus"} \quad (2.20)$$

When  $\nu \rightarrow \frac{1}{2}, \kappa \rightarrow \infty$  ... "incompressible material" (ex: rubber)

# 2.1 Constitutive laws for isotropic materials

## ❖ 2.1.2 Thermal effects

- Under a change in temperature, homogeneous isotropic materials will expand in all directions -> "thermal strain"

$$\varepsilon^t = \alpha \Delta T \quad (2.21)$$

- ① Thermal strains are purely extensional, do not induce shear strains
- ② Thermal strains do not generate internal stresses ... Unconfined material sample simply expands subject to a temp. change but remains unstressed

- Total strains ... mechanical strains + thermal strains

$$\varepsilon_1 = \frac{1}{E} [\sigma_1 - \nu(\sigma_2 + \sigma_3)] + \alpha \Delta T \quad (2.22a)$$

But shear stress-shear strain relationships unchanged

- Constrained material ... a bar constrained at its two ends by rigid walls

# 2.1 Constitutive laws for isotropic materials

- Constrained material ... a bar constrained at its two ends by rigid walls

$$\varepsilon_1 = \frac{1}{E}[\sigma_1] + \alpha\Delta T = 0 \rightarrow \sigma_1 = -E\alpha T$$

... temp. change -> compressive stress("thermal stress")

## ❖ 2.1.4 Ductile materials

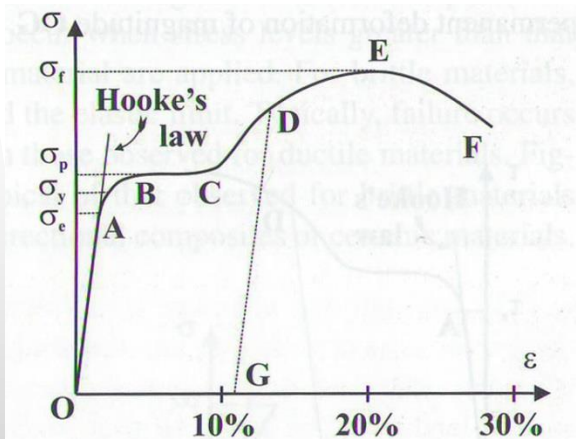
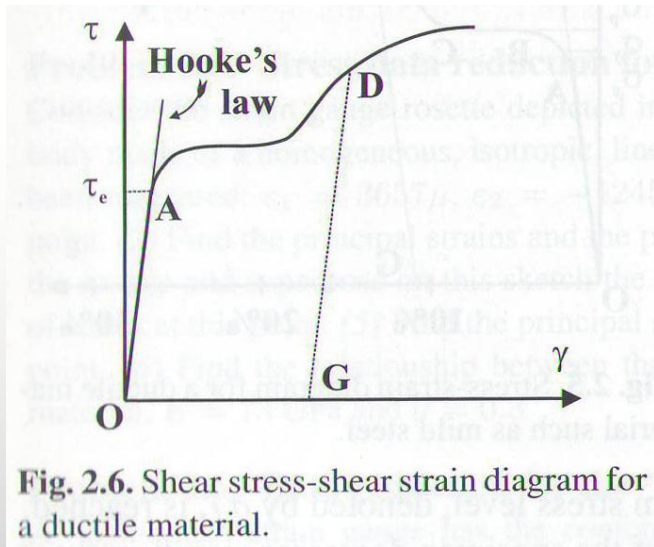


Fig. 2.5. Stress-strain diagram for a ductile material such as mild steel.

- O -> A ... Hooke's law, slope=Young's modulus
- A ... limit of proportionality,  $\sigma_e \cong \sigma_y$ ("yield stress")
- B->C ... "plastic flow" ( $\varepsilon_1 = 5 \sim 10\%$ )
- C->E ... increasing stress,  $\sigma_f = \max$
- "necking" ... x-s area decrease
- E ... "failure stress",  $\sigma_f$

# 2.1 Constitutive laws for isotropic materials

- Large deformations before failure ... B-→E
- When unloading, will follow DG//AO, with a permanent deformation OG
- When reloading, will follow GD(higher yield stress at D <- "strain hardening"), and further DEF



- Shear behavior ... similar

# 2.1 Constitutive laws for isotropic materials

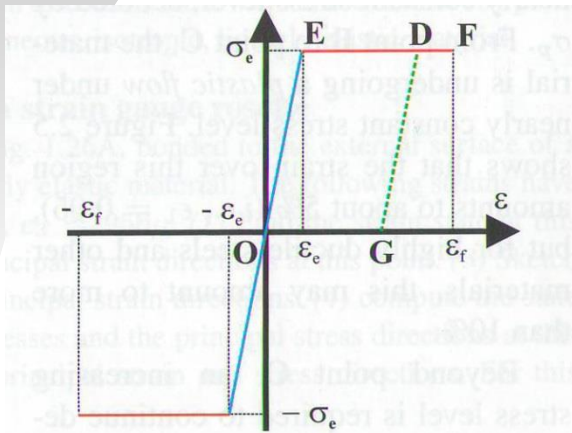


Fig. 2.7. Stress-strain diagram for an elastic-perfectly plastic material.

- Idealization ... “elastic-perfectly plastic”, mild steel, annealed Al

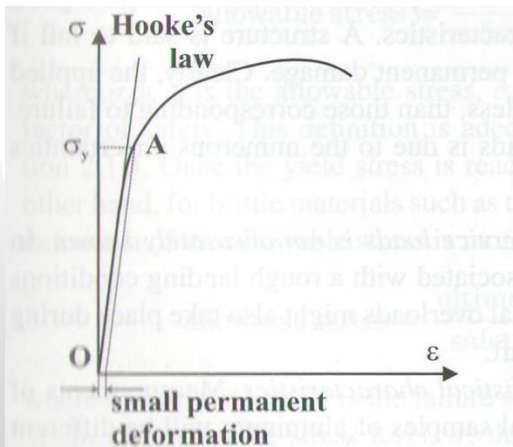


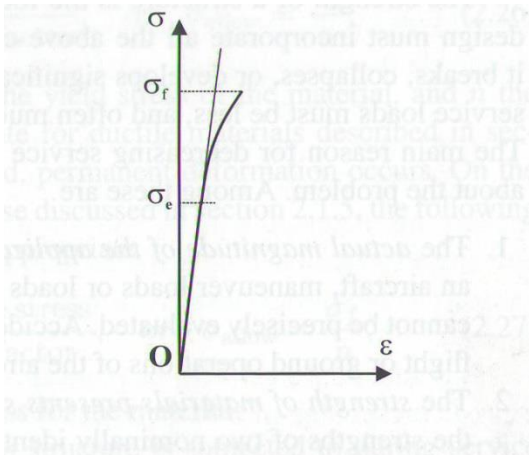
Fig. 2.8. Stress-strain diagram for a ductile material such as aluminum.

- Al, Cu, no plastic flow regime, specific permanent deformation defined for  $\sigma_y$

- $ex) \varepsilon = 0.2\%$  for Al

# 2.1 Constitutive laws for isotropic materials

## ❖ 2.1.5 Brittle materials



**Fig. 2.9.** Stress-strain diagram for a brittle material.

- Very little deformation beyond the elastic limit

Ex) glass, concrete, stone, wood, composites or ceramic

# 2.2 Allowable stress

## 2.2 Allowable stress

- Factors influencing the design
  - ① Strength of the structure <- focus of the present section
  - ② Elastic deformation of the structure
  - ③ Dynamic characteristics of the structure ... natural frequencies and resonance
  - ④ Stability characteristics of the structure ... buckling
  - ⑤ Time dependent deformations associated with creep ... turbine engine design
  
- Numerous uncertainties which decrease service loads
  - ① Actual magnitude of the applied service loads
  - ② Strength of materials ... statistical
  - ③ Manufacturing variability
  - ④ Corrosion, wear, chemically aggressive environment
  - ⑤ Predicted stresses might be very different from their actual values



## 2.2 Allowable stress

- Load factor = failure load/ service load >1, as large as 10
- Factor of safety -> allowable stress = yield stress/safety factor, or

$$\sigma_{allow} = \frac{\sigma_y}{\eta} \quad (2.26)$$

- ... adequate for ductile materials, for brittle materials, allowable stress= ultimate stress/safety factor, or

$$\sigma_{allow} = \frac{\sigma_y}{\eta} \quad (2.27)$$

# 2.3 Yielding under combined loading

## 2.3 Yielding under combined loading

- Proper yield criterion under multiple stress components acting
- Isotropic material ... no directional dependency of the yield criterion state of stress
  - 6 stress components defining the stress tensor
  - 3 principal stresses,  $\sigma_{p1}, \sigma_{p2}, \sigma_{p3}$  and the corresponding 3 orientations

No direction dependency -> only the magnitudes of the principal stress should appear

### ❖ 2.3.1 Tresca's criterion

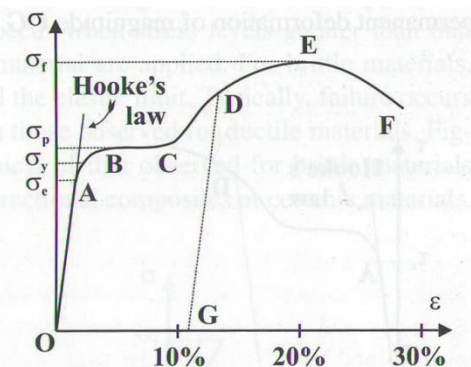


Fig. 2.5. Stress-strain diagram for a ductile material such as mild steel.

$$\left| \sigma_{p1} - \sigma_{p2} \right| \leq \sigma_y, \left| \sigma_{p2} - \sigma_{p3} \right| \leq \sigma_y, \left| \sigma_{p3} - \sigma_{p1} \right| \leq \sigma_y$$

(2.29)

$\sigma_y$  : yield stress observed in a uniaxial test

## 2.3 Yielding under combined loading

- Whenever any one of Eq.(2.29) is violated, yielding develops
- Interpretation  $\rightarrow \tau_{23\max} \leq \frac{\sigma_y}{2}, \tau_{13\max} \leq \frac{\sigma_y}{2}, \tau_{12\max} \leq \frac{\sigma_y}{2}, \text{ or } \tau_{\max} \leq \frac{\sigma_y}{2}$

...the material reaches the yield condition when the max, shear stress=half the yield stress under a uniaxial stress state.

- "max, shear stress criterion"
- Uniaxial state  $\dots \sigma_{p1} \leq \sigma_y$
- Plane state of stress  $\dots$  Eq.(2.31)
- Pure shear state  $\dots \tau \leq \sigma_y / 2$

$$2\sqrt{\left(\frac{\sigma_1 - \sigma_2}{2}\right)^2 + \tau_{12}^2} \leq \sigma_y, \left| \frac{\sigma_1 + \sigma_2}{2} \pm \sqrt{\left(\frac{\sigma_1 - \sigma_2}{2}\right)^2 + \tau_{12}^2} \right| \leq \sigma_y \quad (2.31)$$

### ❖ 2.3.2 Von Mises' criterion

$$\sigma_{eq} = \frac{1}{\sqrt{2}} \sqrt{(\sigma_{p1} - \sigma_{p2})^2 + (\sigma_{p2} - \sigma_{p3})^2 + (\sigma_{p3} - \sigma_{p1})^2} \leq \sigma_y \quad (2.32)$$

- Octahedral face  $\rightarrow$  shear stress acting on octahedral face

$$3\tau_{oc}^2 = \frac{2}{3}\sigma_{eq}^2 \quad \sigma_{eq} = \frac{3}{\sqrt{2}}\tau_{oc} \quad (2.33)$$

... "the yield coord. is reached when the octahedral shear stress

$= \frac{3}{\sqrt{2}}$  of the yield stress for a uniaxial stress state,  $\sigma_y$

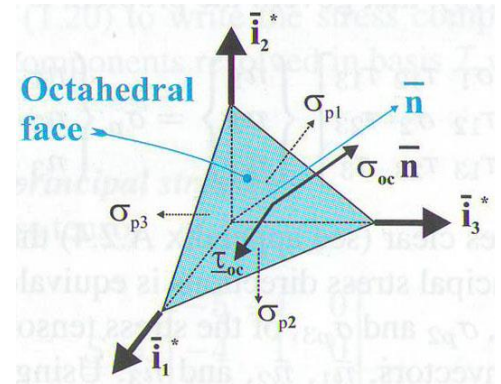


Fig. 1.8. The octahedral face.

# 2.3 Yielding under combined loading

- $\sigma_{eq}$  can be expressed in terms of the stress invariants

$$\sigma_{eq}^2 = I_1^2 - 3I_2 \quad (2.34)$$

$$\rightarrow \sigma_{eq} = \sqrt{\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - \sigma_2\sigma_3 - \sigma_3\sigma_1 - \sigma_1\sigma_2 + 3(\tau_{23}^2 + \tau_{13}^2 + \tau_{12}^2)} \leq \sigma_y \quad (2.35)$$

- ① Uniaxial stress state ...  $\sigma_{p1} \leq \sigma_y$
- ② Plane state of stress ...  $\sigma_{eq} = \sqrt{\sigma_1^2 + \sigma_2^2 - \sigma_1\sigma_2 + 3\tau_{12}^2} \leq \sigma_y \quad (2.36)$
- ③ Pure shear state ...  $\tau \leq \frac{\sigma_y}{\sqrt{3}} \cong 0.577\sigma_y (60\%)$  more accurate than that of Tresca's

## ❖ 2.3.3 Comparing Tresca's and Von Mises' criteria

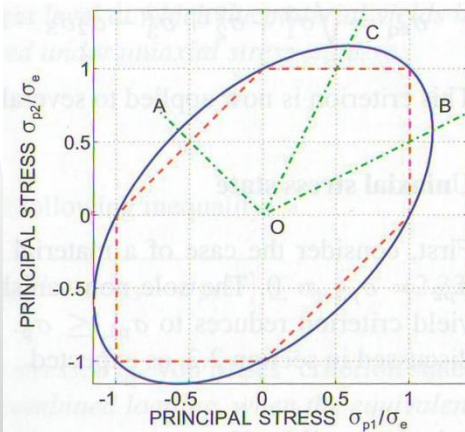


Fig. 2.10. Comparison of Tresca's and von Mises' criteria for a plane stress case.

- Plane stress problem,  $\sigma_{p3} = 0$
- Tresca's criterion ... 3 inequalities

$$\left| \frac{\sigma_{p1}}{\sigma_y} \right| < 1, \quad \left| \frac{\sigma_{p2}}{\sigma_y} \right| < 1, \quad \left| \frac{\sigma_{p2} - \sigma_{p1}}{\sigma_y} \right| < 1 \quad \dots \text{slightly more conservative}$$

-> irregular hexagon enclosed by 6 dashed line segments

## 2.3 Yielding under combined loading

- Von Mises' criterion ... oblique ellipse

$$\left(\frac{\sigma_{p1}}{\sigma_y}\right)^2 + \left(\frac{\sigma_{p2}}{\sigma_y}\right)^2 - \left(\frac{\sigma_{p1}}{\sigma_y}\right)\left(\frac{\sigma_{p2}}{\sigma_y}\right) = 1$$

... often preferred since a single analytic expression

**Table 2.1.** Comparison of the Tresca and von Mises yield criteria.

Stress state	Radial line in fig. 2.10	Tresca's yield stress	von Mises' yield stress	Percent difference
$\sigma_{p1} = -\sigma_{p2} = \sigma$	<b>OA</b>	$\sigma_y/2$	$\sigma_y/\sqrt{3}$	15.5%
$\sigma_{p1} = 2\sigma_{p2} = \sigma$	<b>OB</b>	$\sigma_y$	$2\sigma_y/\sqrt{3}$	15.5%
$\sigma_{p2} = 2\sigma_{p1} = \sigma$	<b>OC</b>	$\sigma_y$	$2\sigma_y/\sqrt{3}$	15.5%

- 3 radial lines OA, OB, OC in Fig. 2.10  
 -> max discrepancy between 2 criteria ... 15.5 %

# 2.4 Material selection for structural performance

## 2.4 Material selection for structural performance

**Table 2.2.** Physical properties of a few metals.

	Ultimate stress [MPa]	Modulus of elasticity [GPa]	Density [kg/m <sup>3</sup> ]
Aluminum	620	73	2700
Titanium	1900	115	4700
Steel	4100	210	7700

... ultimate stress  
Modulus of elasticity  
Density  
(Steel for superior, but heavier)

**Table 2.3.** Physical properties of a few fibers.

	Ultimate stress [MPa]	Modulus of elasticity [GPa]	Density [kg/m <sup>3</sup> ]
E-Glass	3400	72	2550
S-Glass	4800	86	2500
Carbon	1700	190	1410
Boron	3400	400	2570
Graphite	1700	250	1410

... fibers

- 3 categories of structural design
  - strength design
  - stiffness design
  - buckling design

# 2.4 Material selection for structural performance

## ❖ 2.4.1 Strength design

- For a given mass and geometry, the max. load it can carry

$$P_{\max} \propto \frac{\sigma_{ult}}{\rho} \quad (2.38)$$

... material performance index

## ❖ 2.4.2 Stiffness design

- Cantilevered, thin-walled beam of length L, natural freq.

$$\omega \propto \frac{h}{L^2} \left[ \frac{E}{\rho} \right]^{1/2} \quad (2.40)$$

... material performance index

## ❖ 2.4.3 Buckling design

- Critical load that will cause the plate to buckle

$$P_{cr} \propto \frac{M^2}{b^4 L^3} \frac{E}{\rho^3}$$

... material performance index

# 2.5 Composite materials

**Table 2.4.** Structural design performance indices for a few metals.

Performance index	Strength design $\sigma_{ult}/\rho$ [ $10^3$ m <sup>2</sup> /sec <sup>2</sup> ]	Stiffness design $\sqrt{E/\rho}$ [ $10^3$ m/sec]	Buckling design $E/\rho^3$ [m <sup>8</sup> /(kg <sup>2</sup> sec <sup>2</sup> )]
Aluminum	230	5.2	3.7
Titanium	405	4.9	1.1
Steel	530	5.2	0.46

**Table 2.5.** Structural design performance indices for a few fibers.

Performance Index	Strength design $\sigma_{ult}/\rho$ [ $10^3$ m <sup>2</sup> /sec <sup>2</sup> ]	Stiffness design $\sqrt{E/\rho}$ [ $10^3$ m/sec]	Buckling design $E/\rho^3$ [m <sup>8</sup> /(kg <sup>2</sup> sec <sup>2</sup> )]
E-Glass	1330	5.3	4.3
S-Glass	1920	5.9	5.5
Carbon	1200	11.6	68
Boron	1320	12.5	23
Graphite	1200	13.3	89

➤ ... performance indices for metals and fibers

strength design ... steel is the best  
Stiffness design ... 3 equally well  
Strength and buckling ... Al >> steel and Ti

Remarkably high performance indices of fibers -> potential use in structural applications



# 2.5 Composite materials

## 2.5 Composite materials

### ❖ 2.5.1 Basic characteristics

- Embedding fiber aligned in a single direction, in a matrix material
  - Matrix material ... thermostat polymeric material, ex) epoxy
- "rule of mixture" ... strength

$$S_c = V_f S_f + V_m S_m$$

S: strength, V: volume fraction,  $V_f + V_m = 1$

Ex) graphite fiber (  $V_f = 0.6$  ) embedded in an epoxy matrix (  $V_m = 0.4$  )

$$S_c = 1,700 \times 0.6 + 50 \times 0.4 = 1,040(MPa)$$

- Stiffness ... assuming that perfectly bonded together

$$\varepsilon_m = \varepsilon_f = \varepsilon_c \quad (2.47)$$

- Average stress

$$P = A_c \sigma_c = A_f \sigma_f + A_m \sigma_m \quad (2.48)$$

Dividing by

$$\sigma_c = \frac{A_f}{A_c} \sigma_f + \frac{A_m}{A_c} \sigma_m = V_f \sigma_f + V_m \sigma_m \quad (2.49)$$

## 2.5 Composite materials

- Fiber, matrix → linearly elastic, isotropic

$$\sigma_f = E_f \varepsilon_f \quad \sigma_m = E_m \varepsilon_m \quad (2.50)$$

- Modulus of elasticity for the composite,  $E_c$

$$\sigma_c = E_c \varepsilon_c \quad (2.51)$$

$$\text{Eq. (2.50), (2.51)} \rightarrow (2.49) : E_c = V_f E_f + V_m E_m \quad (2.52)$$

$$\text{Ex) graphite-epoxy: } E_c = 250 \times 0.6 + 3.5 \times 0.4 = 150 \text{ GPa}$$

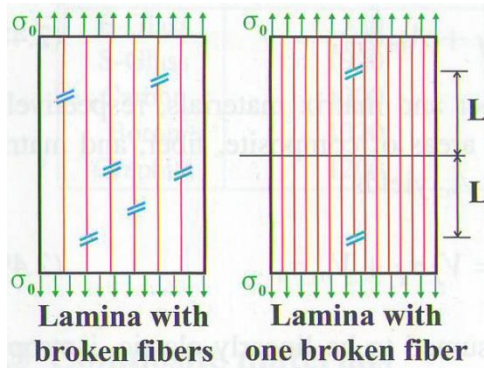
  
contributes little

- What is the role of the matrix material?
  - ① Keep all the fibers together
  - ② Diffuse the stresses among the otherwise isolated fibers

# 2.5 Composite materials

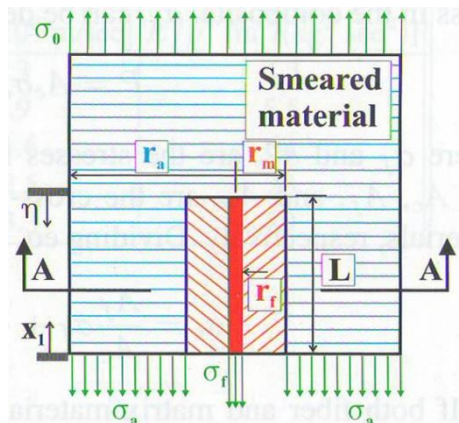
## 2.5.2 stress diffusion in composites

### ❖ Fig. 2.12: single broken fiber of length $2L$



→ Matrix material adjacent to the broken fiber will transfer stress from the surrounding material to the broken fiber  
“stress diffusion process”

### ❖ Fig. 2.13: simplified model



Assumptions

- ① Matrix carries shear stress only
- ② Axial stress in the fiber is uniformly distributed
- ③ Existence of individual fibers ignored in the remaining composite
- ④ Perfectly bonded together

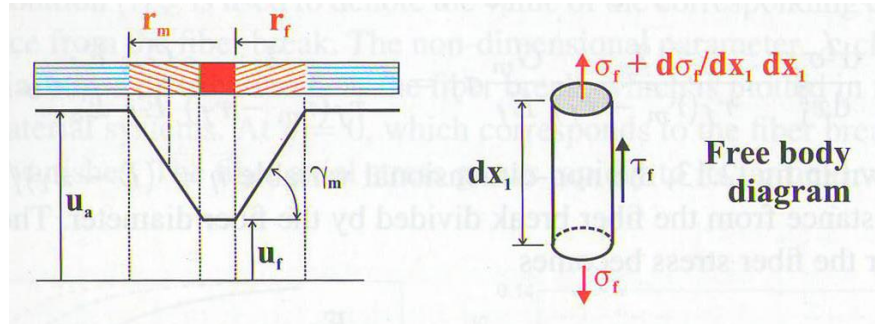
## 2.5 Composite materials

- Strain-displacement relationship

$$\varepsilon_f = \frac{du_f}{dx_1}, \quad \varepsilon_a = \frac{du_a}{dx_1}, \quad \gamma_m = \frac{u_a - u_f}{r_m - r_f} \quad (2.54)$$

- Axial force equilibrium of a differential element of fiber

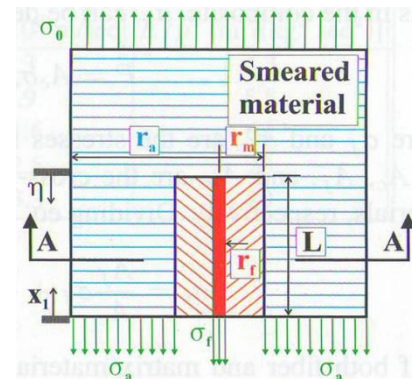
$$\frac{d\sigma_f}{dx_1} + \frac{2}{r_f} \tau_m = 0 \quad (2.55)$$



- Overall equilibrium of an entire model

$$\sigma_a = \frac{\sigma_0}{1 - \frac{r_m^2}{r_a^2}} - \frac{r_f^2}{r_a^2} \frac{\sigma_f}{1 - \frac{r_m^2}{r_a^2}} \approx \sigma_0 \quad (2.56)$$

$$\frac{r_f}{r_a} \ll 1 \rightarrow \text{2nd term negligible}, \quad \frac{r_m}{r_a} \ll 1$$



## 2.5 Composite materials

- Constitutive laws for fiber, composite, and matrix

$$\sigma_f = E_f \varepsilon_f, \quad \sigma_a = E_a \varepsilon_a, \quad \tau_m = G_m \gamma_m \quad (2.57)$$

- Eq.(2.57c), (2.54c)  $\rightarrow$  Eq.(2.55)

$$\frac{d^2 \sigma_f}{dx_1} + \frac{2G_m}{r_f(r_m - r_f)}(u_a - u_f) = 0$$

- Differentiate w.r.t.  $x_1$  and substituting Eqs. (2.54a), (2.54b), (2.57a), (2.57b)

$$\frac{d^2 \sigma_f}{dx_1} + \frac{2G_m}{r_f(r_m - r_f)} \left( \frac{\sigma_a}{E_a} - \frac{\sigma_f}{E_f} \right) = 0$$

- Since  $\sigma_a \approx \sigma_0$  (Eq.2.56),

$$\frac{d^2 \sigma_f}{dx_1^2} - \frac{2}{r_f(r_m - r_f)} \frac{G_m}{E_f} \sigma_f = - \frac{2}{r_f(r_m - r_f)} \frac{G_m}{E_f} \frac{E_f}{E_a} \sigma_0$$

## 2.5 Composite materials

- Non-dimensional variable  $\eta = (L - x_1)/(2r_f)$

- Then, the governing eqn.

$$\sigma_f'' - \lambda^2 \sigma_f = -\lambda^2 \frac{E_f}{E_a} \sigma_0 \quad ( )': \text{derivative w.r.t } \eta$$

$$\lambda^2 = 8 \frac{G_m}{E_f} \frac{r_f}{r_m} \frac{1}{1 - r_f/r_m}$$

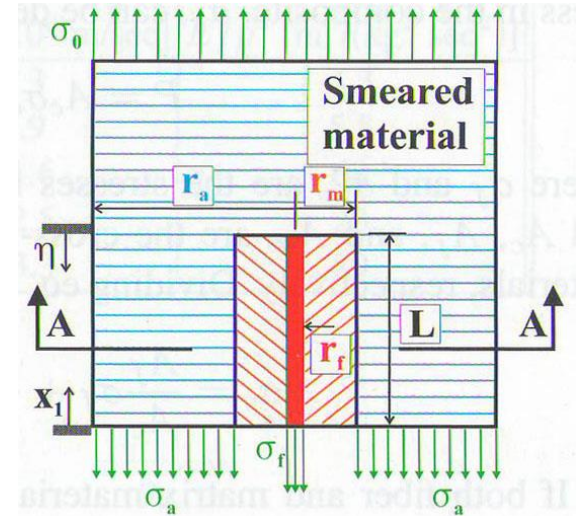
- $\frac{E_f}{E_a} = \frac{E_f}{V_f E_f + V_m E_m} \approx \frac{E_f}{V_f E_f} = \frac{1}{V_f}$  since  $E_m \ll E_f$

- Governing eqn.

$$\sigma_f'' - \lambda^2 \sigma_f = -\lambda^2 \frac{\sigma_0}{V_f} \quad (2.58)$$

$$\text{where } \lambda^2 = 8 \frac{G_m}{E_f} \frac{\sqrt{V_f}}{1 - \sqrt{V_f}} \quad (2.59)$$

$$\begin{aligned} \text{B.C.: } \sigma_f &= 0 \text{ at } \eta = 0 \text{ (broken fiber)} \\ \sigma_f' &= 0 \text{ at } \eta = L/2r_f \text{ (symmetry)} \end{aligned}$$



## 2.5 Composite materials

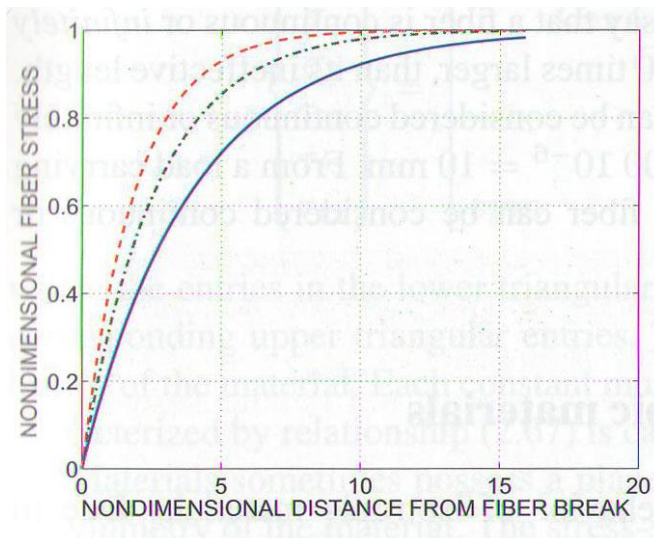
➤ Solution

$$\frac{\sigma_f}{\sigma_0} = \frac{1}{V_f} \left( 1 - \frac{\cosh \lambda (L / 2r_f - \eta)}{\cosh(\lambda L / 2r_f)} \right) \approx \frac{1}{V_f} (1 - e^{-\lambda \eta}) \quad (2.60)$$

Since  $\sigma_0 = V_f \sigma_{f\infty} + (1 - V_f) \sigma_{m\infty} \approx V_f \sigma_{f\infty}$ ,

$$\text{Eq. (2.60)} \rightarrow \frac{\sigma_f}{\sigma_{f\infty}} = 1 - e^{-\lambda \eta} \quad (2.61)$$

:fiber axial stress distribution near the fiber break



## 2.5 Composite materials

- Ineffective length  $\delta$  : the distance where the fiber stress reaches 95% of its for field value

$$0.95 = 1 - \exp(-\lambda \delta / d_f) \rightarrow \frac{\delta}{d_f} \approx \left[ \frac{E_f}{G_m} \frac{1 - \sqrt{V_f}}{\sqrt{V_f}} \right]^{1/2} \quad (2.62)$$

:length of fiber, near a fiber break, that does not carry axial stress at fully capacity

→ Matrix material transfers the load from the surrounding material to the broken fiber very rapidly ("shear lag")

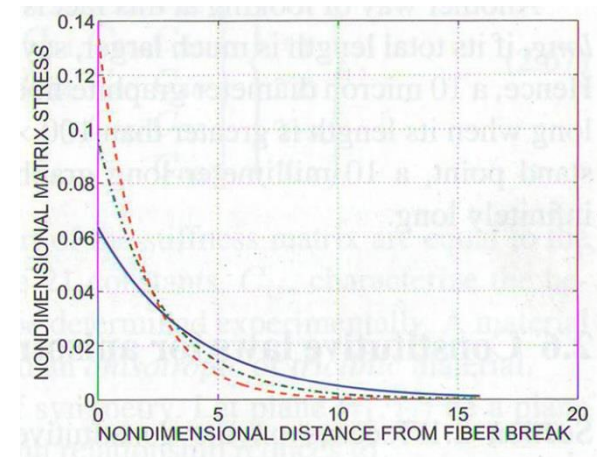
Shear stress in the matrix is effectively transferring the load to the fiber

$$\frac{\tau_m}{\sigma_{f\infty}} = \frac{\lambda}{4} e^{-\lambda \eta} \quad (2.63)$$

- Zone affected by a fiber break → about  $2\delta$  in length

Ex) graphite of dia.10micron

→ Zone of only 200 microns in length





## 2.6 Constitutive laws for anisotropic material

- ❖ **Unidirectional composite materials** → fiber dir., dominated by that of fiber  
➤ transverse to fiber, dominated by that of matrix

- ❖ **Linear relationship between the stress and strain**

$$\underline{\underline{\sigma}} = \underline{\underline{C}} \underline{\underline{\varepsilon}} : \underline{\underline{\varepsilon}} = \underline{\underline{S}} \underline{\underline{\sigma}} \quad (2.64) \qquad \underline{\underline{S}} = \underline{\underline{C}}^{-1} \quad (2.65)$$

6 x 6 stiffness    6 x 6 compliance

- Strain energy:  $A = \frac{1}{2} \underline{\underline{\varepsilon}}^T \underline{\underline{\sigma}} = \frac{1}{2} \underline{\underline{\varepsilon}}^T \underline{\underline{C}} \underline{\underline{\varepsilon}} = \frac{1}{2} \underline{\underline{\sigma}}^T \underline{\underline{S}} \underline{\underline{\sigma}}$   
→ both  $\underline{\underline{C}}$  and  $\underline{\underline{S}}$  are symm. and positive definite

## 2.6 Constitutive laws for anisotropic material

- ❖ **Due to symmetry, 6x6=36 independent consts → 21** (2.67)

“anisotropic” or “triclinic” material

- Plane of symmetry:  $(i_1, i_2)$  plane of symmetry

$$\begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & C_{16} \\ & C_{22} & C_{23} & 0 & 0 & C_{26} \\ & & C_{33} & 0 & 0 & C_{36} \\ & & & C_{44} & C_{45} & 0 \\ & & & & C_{55} & 0 \\ & & & & & C_{66} \end{bmatrix} \quad (2.68)$$

- If  $C_{14} \neq 0$ ,  $\varepsilon_1$  would give rise to  $\tau_{23} \rightarrow$  violate the symmetry of response  
→ 21-8=13 independent consts “monoclinic” material

## 2.6 Constitutive laws for anisotropic material

- 2 mutually orthogonal planes of symmetry:  $(i_1, i_2), (i_2, i_3)$

$$\begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ & C_{22} & C_{23} & 0 & 0 & 0 \\ & & C_{33} & 0 & 0 & 0 \\ & & & C_{44} & 0 & 0 \\ & & & & C_{55} & 0 \\ & & & & & C_{66} \end{bmatrix} \quad (2.69)$$

→  $21 - 12 = 9$  independent consts, "orthotropic" material

- Laminated composite material →  $\begin{cases} 2 \text{ orthogonal plane of symmetry: } (i_1, i_2), (i_2, i_3) \\ 1 \text{ plane of isotropy: } (i_2, i_3) \end{cases}$

$$\begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ & C_{22} & C_{23} & 0 & 0 & 0 \\ & & C_{22} & 0 & 0 & 0 \\ & & & \frac{C_{22} - C_{23}}{2} & 0 & 0 \\ & & & & C_{55} & 0 \\ & & & & & C_{55} \end{bmatrix} \quad (2.70)$$

→ 5 constants, "transversely isotropic"

## 2.6 Constitutive laws for anisotropic material

### ➤ Isotropic

$$\begin{bmatrix} C_{11} & C_{12} & C_{12} & 0 & 0 & 0 \\ & C_{11} & C_{12} & 0 & 0 & 0 \\ & & C_{11} & 0 & 0 & 0 \\ & & & \frac{C_{11}-C_{12}}{2} & 0 & 0 \\ & & & & \frac{C_{11}-C_{12}}{2} & 0 \\ & & & & & \frac{C_{11}-C_{12}}{2} \end{bmatrix} \quad (2.71)$$

→ 2 constants

### ➤ { Not clear about $C_{11}$ , $C_{12}$

“Engineering consts”: Young`s modulus, Poisson`s ratio

→ experimental determination and physical interpretation

# 2.6 Constitutive laws for anisotropic material

## 2.6.1 Constitutive laws for a lamina in the fiber aligned triad

### ❖ Thin sheet of composite material made of unidirectional fibers

$\bar{i}_1^*$  : fiber direction     $\bar{i}_2^*$  : transverse direction  
 $\bar{i}_3^*$  : perpendicular to the plane of thin sheet

} → “fiber aligned triad”

→ can be assumed as a homogeneous, transversely isotropic material

### ❖ Plane stress state: constitutive laws in compliance form

$$\begin{Bmatrix} \varepsilon_1^* \\ \varepsilon_2^* \\ \gamma_{12}^* \end{Bmatrix} = \begin{bmatrix} 1/E_1^* & -\nu_{21}^*/E_2^* & 0 \\ -\nu_{12}^*/E_1^* & 1/E_2^* & 0 \\ 0 & 0 & 1/G_{12}^* \end{bmatrix} \begin{Bmatrix} \sigma_1^* \\ \sigma_2^* \\ \tau_{12}^* \end{Bmatrix} \quad (2.72)$$

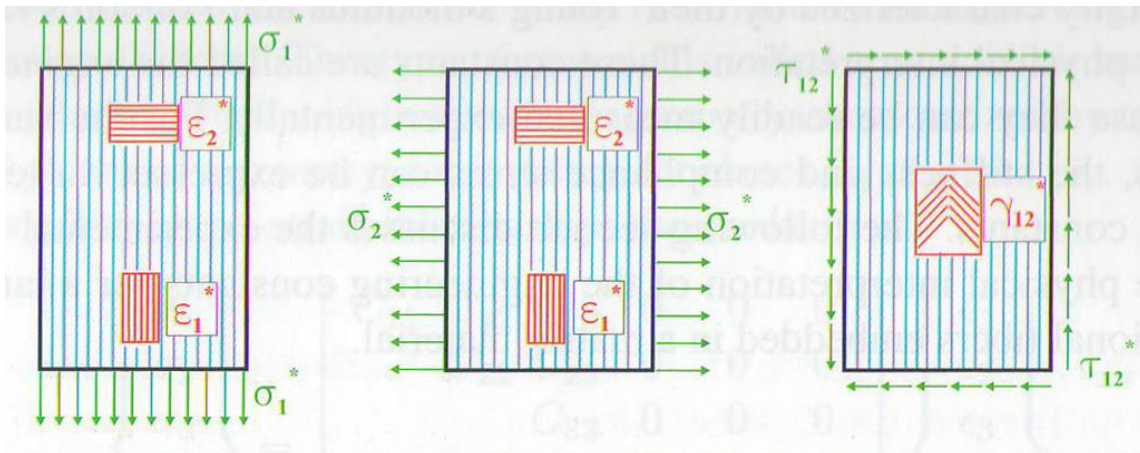
➤  $E_1^*, E_2^*, \nu_{12}^*, G_{12}^*$ : engineering consts

➤ Symm. →  $\nu_{12}^*/E_1^* = \nu_{21}^*/E_2^*$  → one of 5 consts is not an independent quantity

# 2.6 Constitutive laws for anisotropic material

- Simple test of a known stress  $\sigma_1^*$ , then  $\sigma_2^* = \tau_{12}^* = 0$ 
  - ① of Eq.(2.72)  $\rightarrow \epsilon_1^* = \sigma_1^* / E_1^*$ ,  $E_1^*$  can be determined
  - ② of Eq.(2.72)  $\rightarrow \epsilon_2^* = -\nu_{12}^* \sigma_1^* / E_1^*$ ,  $\nu_{12}^*$  can be determined
- 2nd test of a known stress  $\sigma_2^*$ , then  $\sigma_1^* = \tau_{12}^* = 0$ 

$$\epsilon_2^* = \sigma_2^* / E_2^*, E_2^* \text{ can be obtained}$$
- Last test of a known  $\tau_{12}^*$ , then  $\sigma_1^* = \sigma_2^* = 0$ 
  - ③ of Eq.(2.72)  $\rightarrow \gamma_{12}^* = \tau_{12}^* / G_{12}^*$ ,  $G_{12}^*$  can be obtained



## 2.6 Constitutive laws for anisotropic material

- Stiffness matrix: by inverting Eq. (2.72)

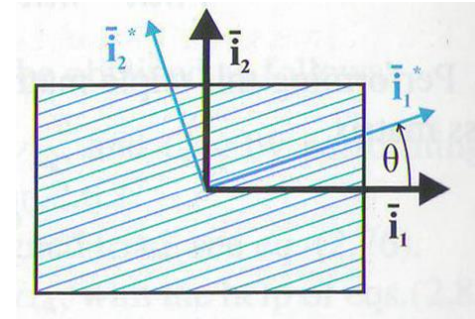
$$\begin{Bmatrix} \sigma_1^* \\ \sigma_1^* \\ \tau_{12}^* \end{Bmatrix} = \begin{bmatrix} \frac{E_1^*}{1-\nu_{12}^{*2}E_2^*/E_1^*} & \frac{\nu_{12}^*E_2^*}{1-\nu_{12}^{*2}E_2^*/E_1^*} & 0 \\ \frac{\nu_{12}^*E_2^*}{1-\nu_{12}^{*2}E_2^*/E_1^*} & \frac{E_2^*}{1-\nu_{12}^{*2}E_2^*/E_1^*} & 0 \\ 0 & 0 & G_{12}^* \end{bmatrix} \begin{Bmatrix} \varepsilon_1^* \\ \varepsilon_1^* \\ \gamma_{12}^* \end{Bmatrix} \quad (2.73)$$

# 2.6 Constitutive laws for anisotropic material

## 2.6.2 Constitutive laws for a lamina in an arbitrary triad

❖ Fig. 2.18

Lamina of a direction that might not coincide with that of fiber counterclockwise  $\theta$  orientation of fiber w.r.t. ref. direction  
 ← formulae for stresses and strains in a rotated axis system



### 1) Rotations of the stiffness matrix

- Constitutive laws for a lamina in the fiber aligned triad

$$\underline{\underline{\sigma}}^* = \underline{\underline{C}}^* \underline{\underline{\varepsilon}}^*$$

- Introducing the rotation formulae, Eqs. (1.47), (1.91)

$$\begin{bmatrix} m^2 & n^2 & 2mn \\ n^2 & m^2 & -2mn \\ -mn & mn & m^2 - n^2 \end{bmatrix} \begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{Bmatrix} = \underline{\underline{C}}^* \begin{bmatrix} m^2 & n^2 & mn \\ n^2 & m^2 & -mn \\ -2mn & 2mn & m^2 - n^2 \end{bmatrix} \begin{Bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{Bmatrix} \quad \text{where} \quad \begin{aligned} m &= \cos \theta \\ n &= \sin \theta \end{aligned}$$

- Multiplying from the left by the inverse of the rotation matrix for the stress

$$\begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{Bmatrix} = \underbrace{\begin{bmatrix} m^2 & n^2 & -2mn \\ n^2 & m^2 & 2mn \\ mn & -mn & m^2 - n^2 \end{bmatrix} \underline{\underline{C}}^*}_{\underline{\underline{C}}} \begin{bmatrix} m^2 & n^2 & mn \\ n^2 & m^2 & -mn \\ -2mn & 2mn & m^2 - n^2 \end{bmatrix} \begin{Bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{Bmatrix} \quad (2.79)$$



## 2.6 Constitutive laws for anisotropic material

- More compact manner of the relationship

$$\underline{\underline{C}}(\theta) = \underline{\underline{x}}(\theta) \underline{\underline{\alpha}} \quad (2.86)$$

where

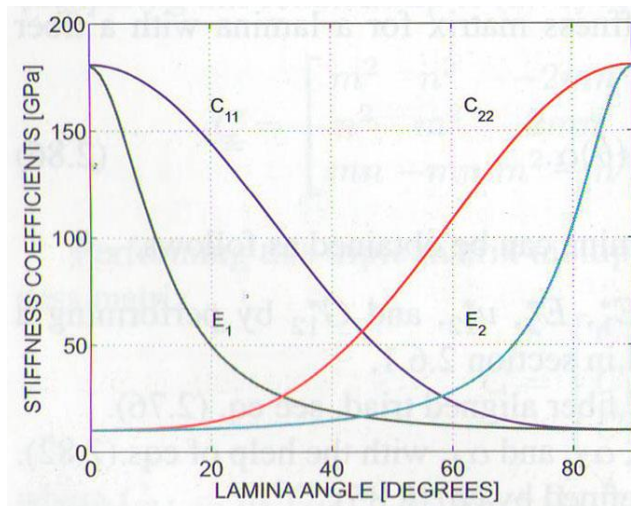
$$\underline{\underline{C}} = \{C_{11} \quad C_{22} \quad C_{12} \quad C_{66} \quad C_{16} \quad C_{26}\}^T \quad (2.84)$$

$$\underline{\underline{x}}(\theta) = \begin{bmatrix} 1 & 1 & \cos 2\theta & \cos 4\theta \\ 1 & 1 & -\cos 2\theta & \cos 4\theta \\ 1 & -1 & 0 & -\cos 4\theta \\ 0 & 1 & 0 & -\cos 4\theta \\ 0 & 0 & \frac{1}{2} \sin 2\theta & \sin 4\theta \\ 0 & 0 & \frac{1}{2} \sin 2\theta & -\sin 4\theta \end{bmatrix} \quad (2.83)$$

## 2.6 Constitutive laws for anisotropic material

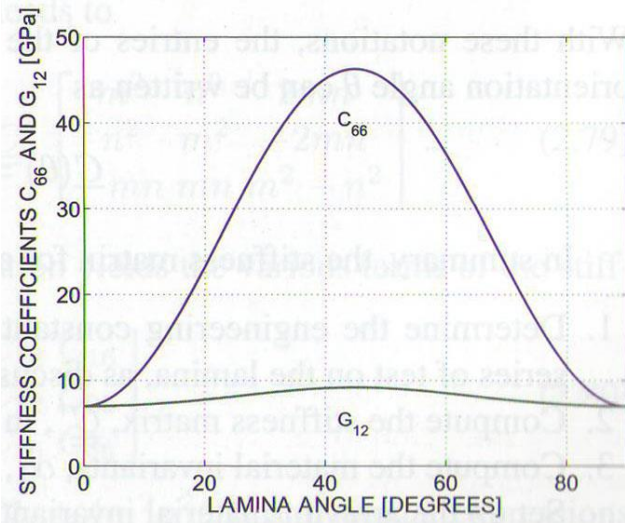
$$\underline{\alpha} = \{\alpha_1 \quad \alpha_2 \quad \alpha_3 \quad \alpha_4\}^T \quad \text{"material invariants"} \quad (2.85)$$

with Eq. (2.82)

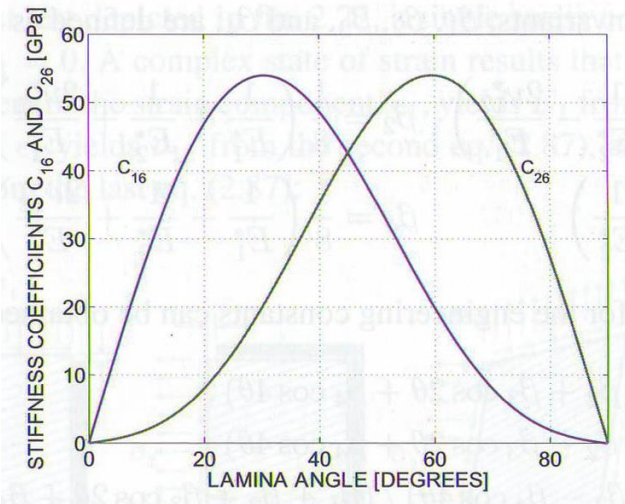


$C_{11}, C_{12}$  in terms of  $\theta$ , sharp decline  
→ high directionality

## 2.6 Constitutive laws for anisotropic material



$C_{66}$  very high near  $\theta = 45^\circ$



$C_{11}, C_{26} \neq 0$  in terms of  $\theta$ , coupling between extension and shearing

$C_{11}, C_{26} = 0$  in  $\underline{\underline{C}}^*$

← response of the systems must be symmetric precluding extension-shear couple

## 2.6 Constitutive laws for anisotropic material

2) Rotations of the compliance matrix

$$\underline{\underline{S}} = \begin{bmatrix} m^2 & n^2 & -mn \\ n^2 & m^2 & mn \\ 2mn & -2mn & m^2 - n^2 \end{bmatrix} \underline{\underline{S}}^* = \begin{bmatrix} m^2 & n^2 & 2mn \\ n^2 & m^2 & -2mn \\ -mn & mn & m^2 - n^2 \end{bmatrix} \quad (2.88)$$

$$= \begin{bmatrix} S_{11} & S_{12} & S_{16} \\ S_{12} & S_{22} & S_{26} \\ S_{16} & S_{26} & S_{66} \end{bmatrix} = \begin{bmatrix} 1/E_1 & -\nu_{21}/E_2 & \nu_{61}/G_{12} \\ -\nu_{12}/E_1 & 1/E_2 & \nu_{62}/G_{12} \\ \nu_{16}/E_1 & \nu_{26}/E_2 & 1/G_{12} \end{bmatrix}$$

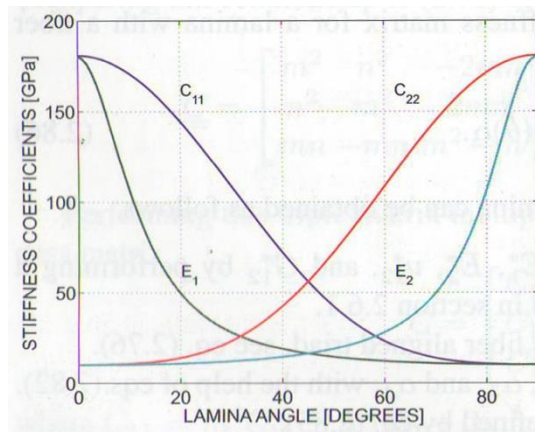
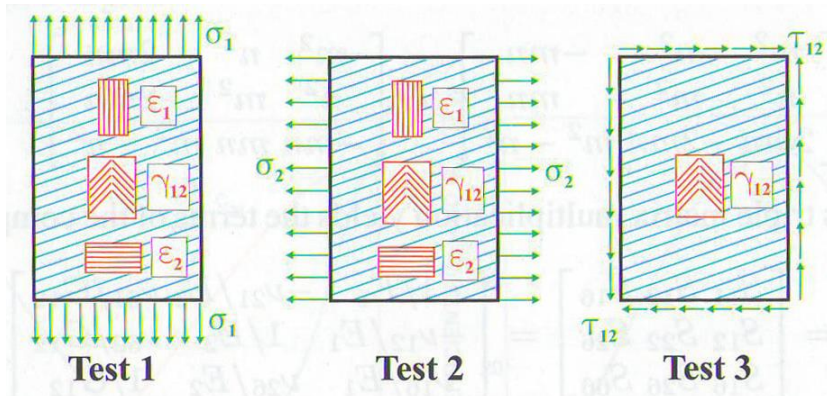
- $E_1, E_2, \nu_{12}, G_{12}, \nu_{16}, \nu_{26}$  : engineering constants in the arbitrary triad
- $\underline{\underline{S}}$  must be symmetric

## 2.6 Constitutive laws for anisotropic material

- Alternative expression for engineering const. – Eq. (2.92)

Various tests to determine the engineering const.s

Similar to those in sec 2.6.1, but currently stress is applied at  $\theta$



$E_1$  shows precipitous drop w.r.t.  $\theta$

## 2.6. Constitutive laws for anisotropic material

### ❖ Difference between $C_{11}$ and $E_1$

- $E_1 = 1/S_1$ ,  $1/S_{11} \neq C_{11}$  since the inverse of a matrix is not simply the inverse of its items

Fig. 2.22 – to measure  $E_1$ ,  $\sigma_1$  is applied,  $\sigma_2 = \tau_{12} = 0$ ,  $\varepsilon_1 \rightarrow E_1$ ,  $\varepsilon_2 \rightarrow \nu_{12}$ ,  $\gamma_{12} \rightarrow \nu_{16}$  in Eq (2.87)

Fig. 2.23 – to measure  $C_{11}$ ,  $\varepsilon_1$  is applied,  $\varepsilon_2 = \gamma_{12} = 0$

but test is very difficult to perform since would have to be constrained to prevent any deformations except  $\varepsilon_1$

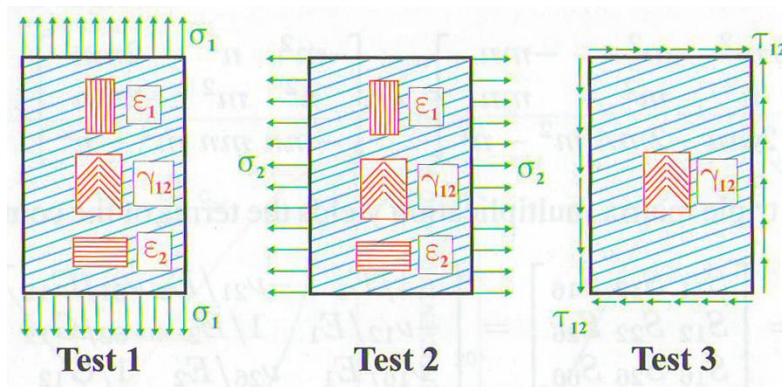


Fig. 2.22

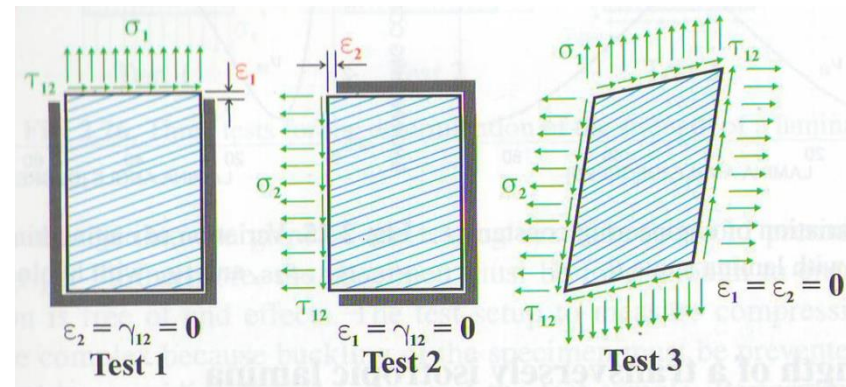
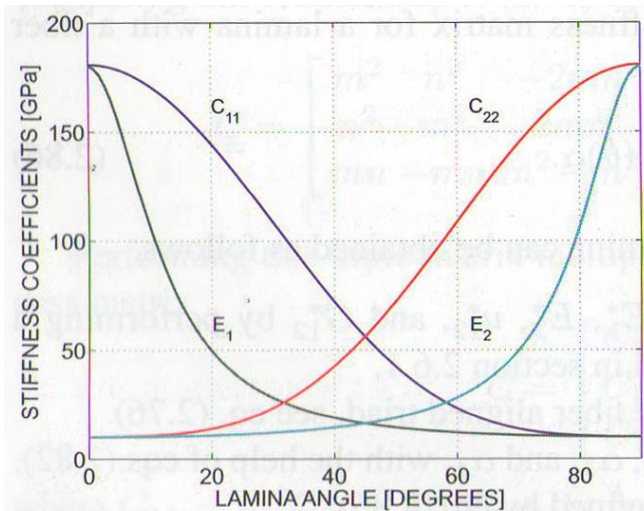


Fig. 2.23

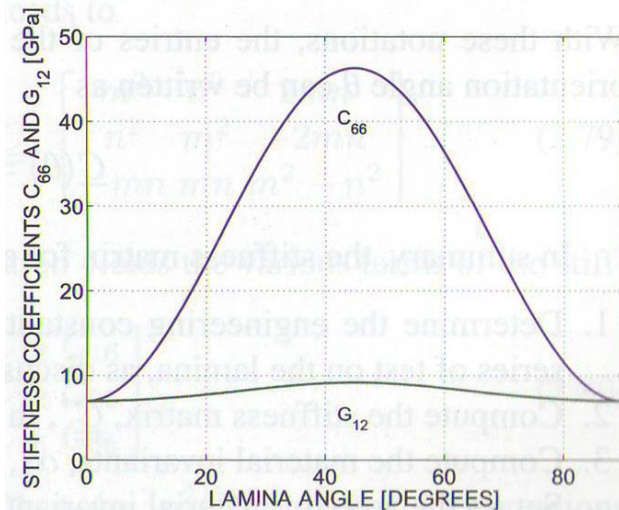


## 2.6 Constitutive laws for anisotropic material

- Effect of these constraints → considerably stiffen the material  
ex)  $C_{11} \gg E_1$  (Fig. 2.19)  
 $C_{66} \gg G_{12}$  (Fig. 2.20)



**Fig. 2.19.** Variation of the stiffness coefficients,  $C_{11}$  and  $C_{22}$ , and the engineering constants,  $E_1$  and  $E_2$ , as a function of  $\theta$ .

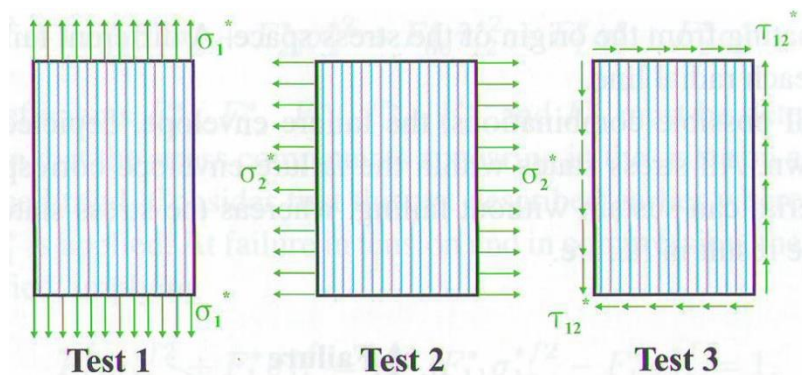


**Fig. 2.20.** Variation of the stiffness coefficient,  $C_{66}$ , and engineering constant,  $G_{12}$  as a function of  $\theta$ .

# 2.7 Strength of a transversely isotropic lamina

## 2.7.1 Strength of a lamina under simple loading condition

❖ Fig. 2.26



- ①  $\sigma_1^*$  applied in the fiber direction, and  $\sigma_2^* = \tau_{12}^* = 0$   
will provide  $\sigma_{1t}^{*f}$  and  $\sigma_{1c}^{*f}$  (not equal, generally)
- ②  $\sigma_2^*$  applied in the transverse direction, and  $\sigma_1^* = \tau_{12}^* = 0$   
will provide  $\sigma_{2t}^{*f}$  and  $\sigma_{2c}^{*f}$
- ③ Shear stress  $\tau_{12}^*$  applied and  
 $\rightarrow \tau_{12}^{*f}$ , no dependence on sign

❖ Tests can be very difficult to perform in practice

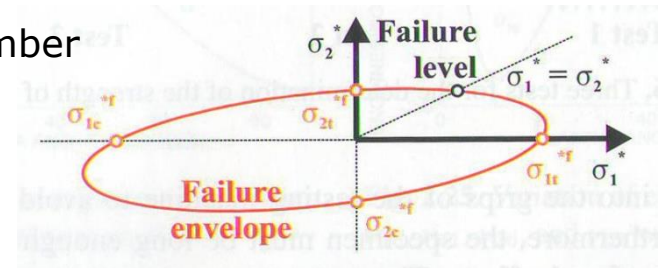


# 2.7 Strength of a transversely isotropic lamina

## 2.7.2 Strength of a lamina under combined loading conditions

### ❖ Fig. 2.27

Failure envelope, rather than performing a large number of experiments, apply a failure criterion  
→ many different failure criteria, widely used



- ❖ { **Matrix failure** – not always a catastrophic event
- ❖ { **Fiber failure** – completely eliminates load carrying capability

# 2.7 Strength of a transversely isotropic lamina

## 2.7.3 The Tsai-Wu failure criterion

### ❖ Combined stresses applied

$$F_{11}^* \sigma_1^{*2} + 2F_{12}^* \sigma_1^* \sigma_2^* + F_{22}^* \sigma_2^{*2} + F_{66}^* \tau_{12}^{*2} + F_{11}^* \sigma_1^* + F_{22}^* \sigma_2^* = 1 \quad (2.93)$$

- ① Test with a single stress component  $\sigma_1^*$  applied

$$F_{11}^* \sigma_{1t}^{*2} + F_{11}^* \sigma_{1t}^{*f} = 1, \quad F_{11}^* \sigma_{1c}^{*2} - F_{11}^* \sigma_{1c}^{*f} = 1$$

- ②  $\sigma_2^*$  only

- ③  $\tau_{12}^*$  only

→ then, can find 5 coefficients in Eq.(2.93)