

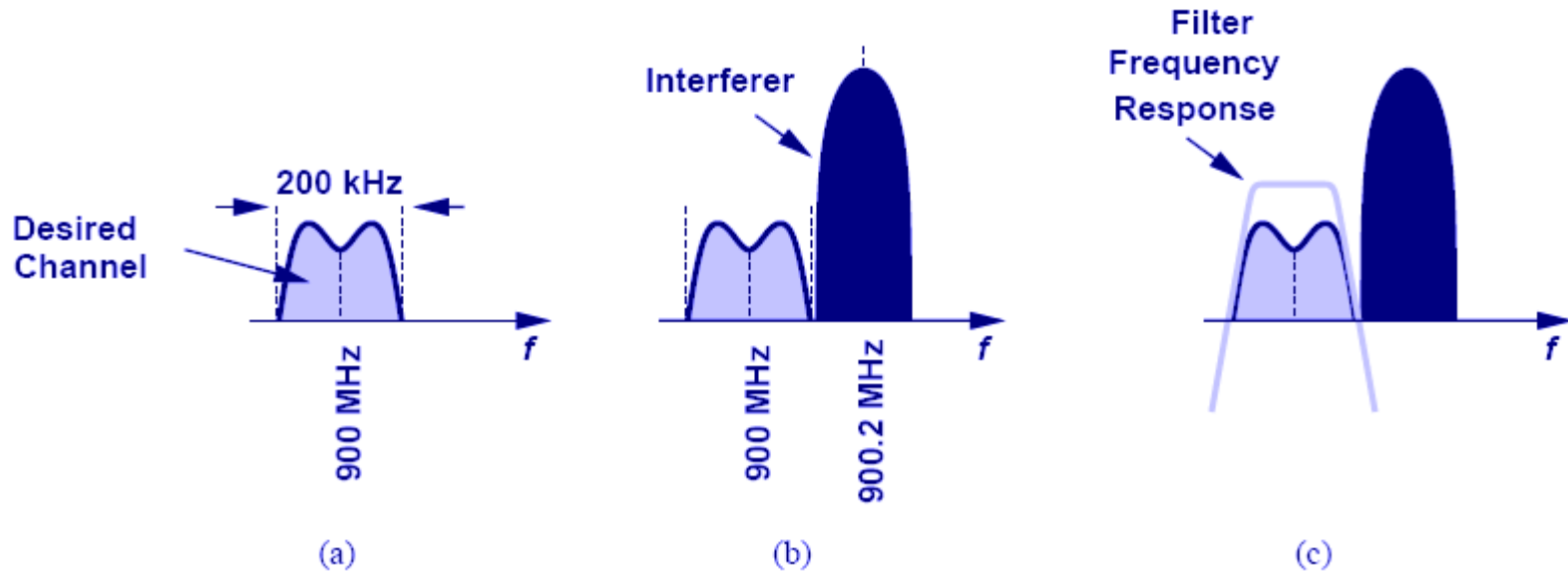
# Chapter 14 Analog Filters

- **14.1 General Considerations**
- **14.2 First-Order Filters**
- **14.3 Second-Order Filters**
- **14.4 Active Filters**
- **14.5 Approximation of Filter Response**

# Outline of the Chapter

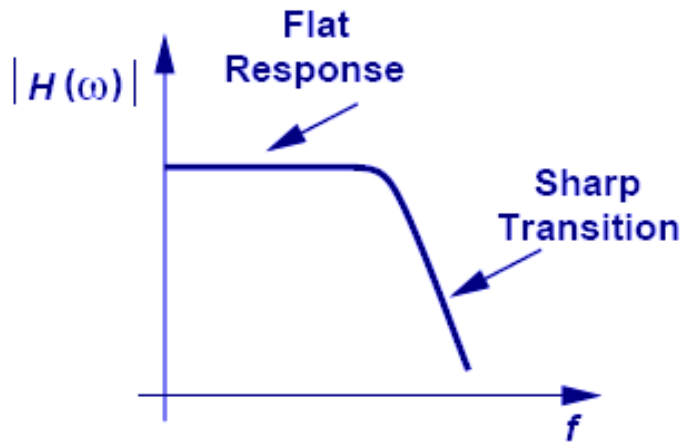


# Why We Need Filters

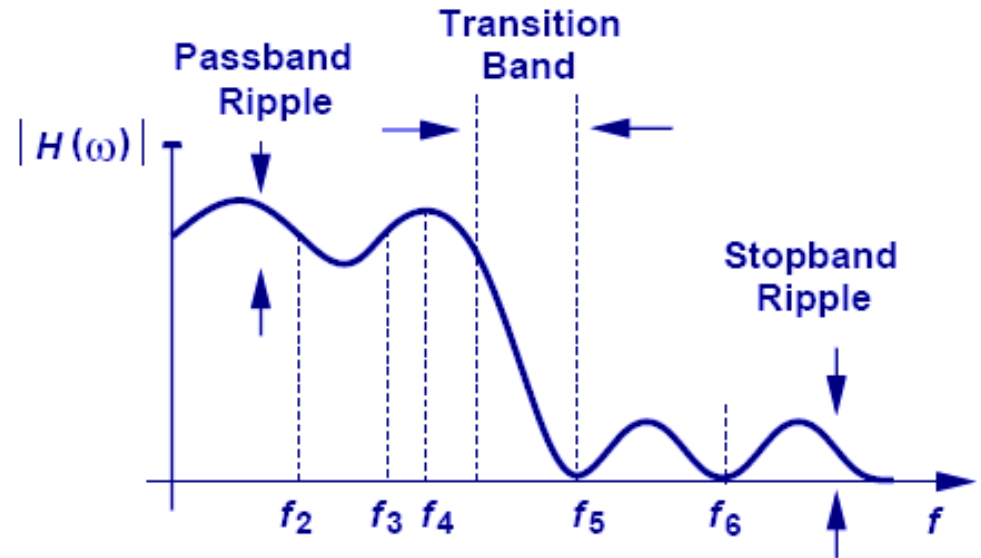


➤ In order to eliminate the unwanted interference that accompanies a signal, a filter is needed.

# Filter Characteristics



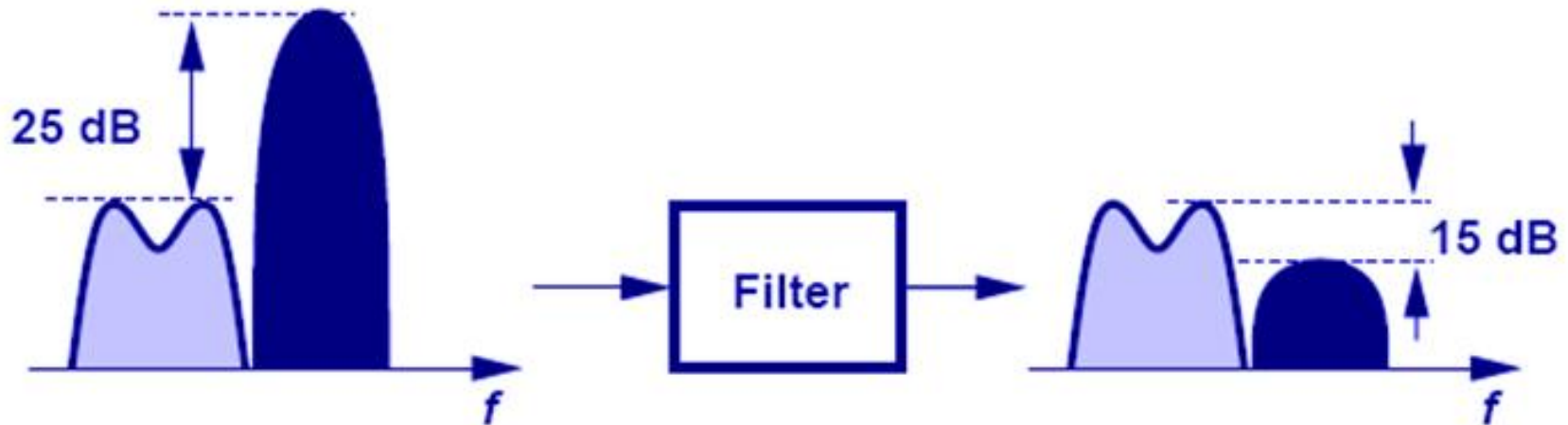
(a)



(b)

- Ideally, a filter needs to have a flat pass band and a sharp roll-off in its transition band.
- Realistically, it has a rippling pass/stop band and a transition band.

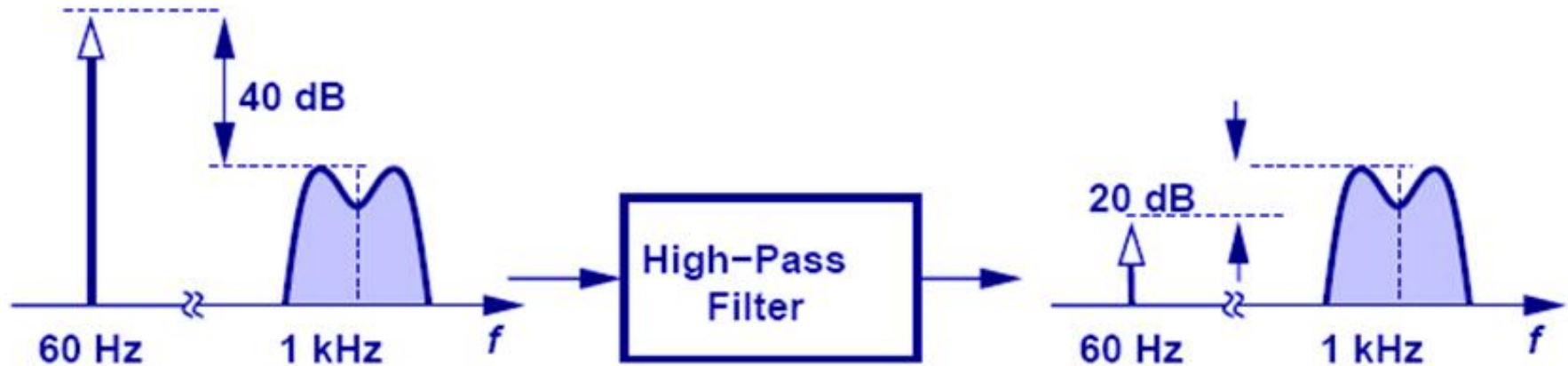
## Example 14.1: Filter I



**Problem :** Adjacent channel interference is 25 dB above the signal. Determine the required stopband attenuation if Signal to Interference ratio must exceed 15 dB.

**Solution:** A filter with stopband attenuation of 40 dB

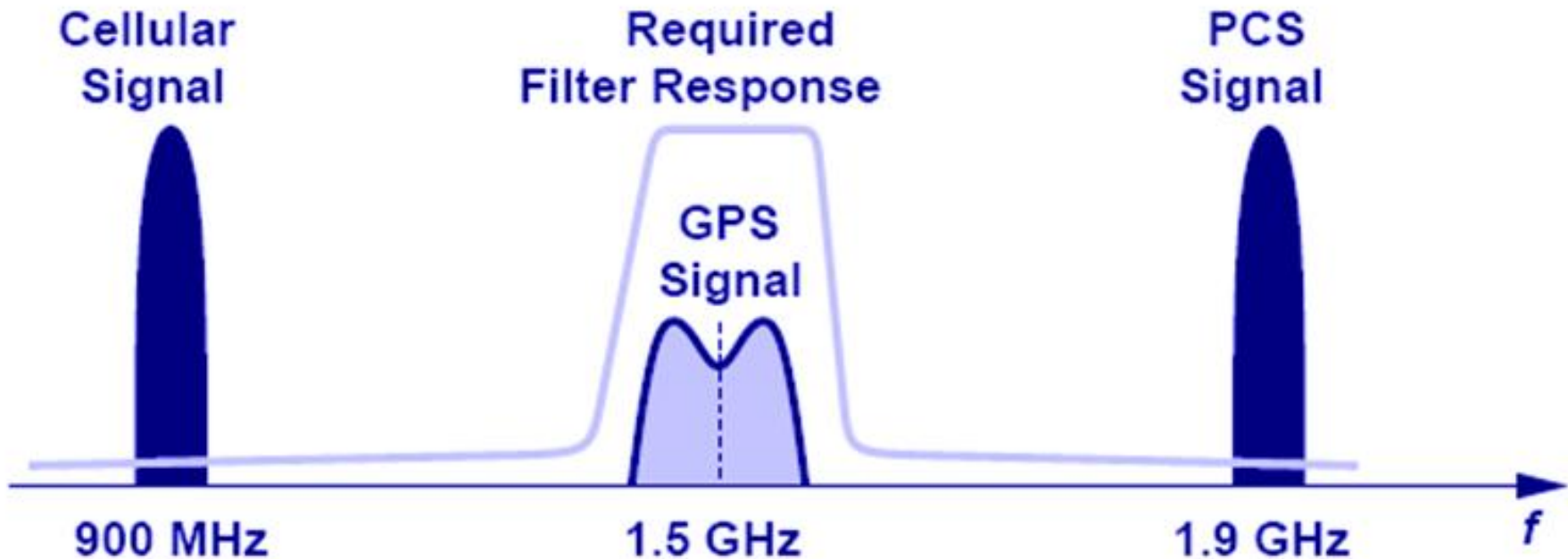
## Example 14.2: Filter II



**Problem:** Adjacent 60-Hz channel interference is 40 dB above the signal. Determine the required stopband attenuation  
To ensure that the signal level remains 20dB above the interferer level.

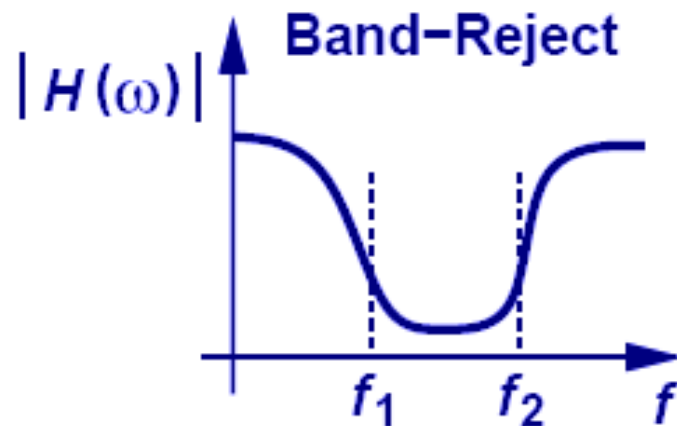
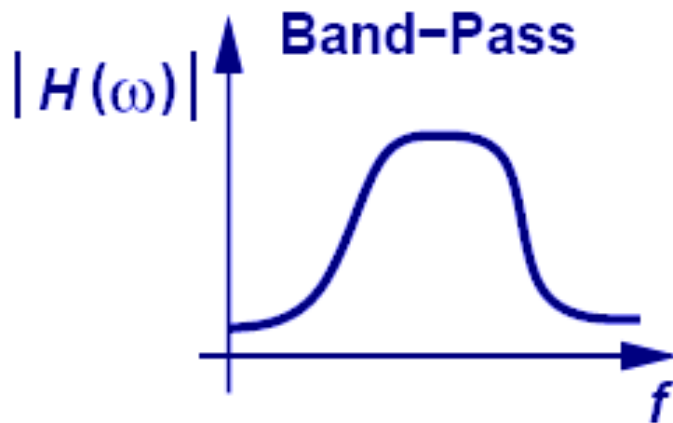
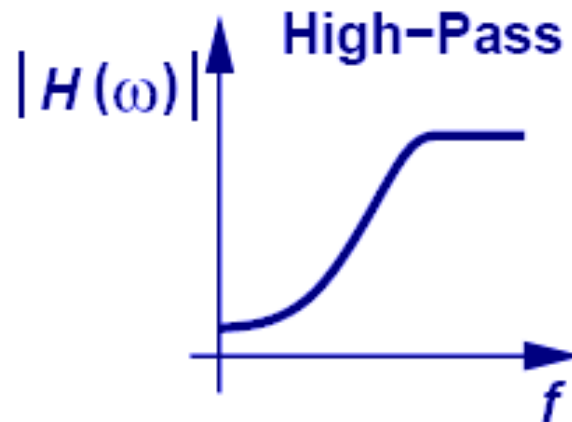
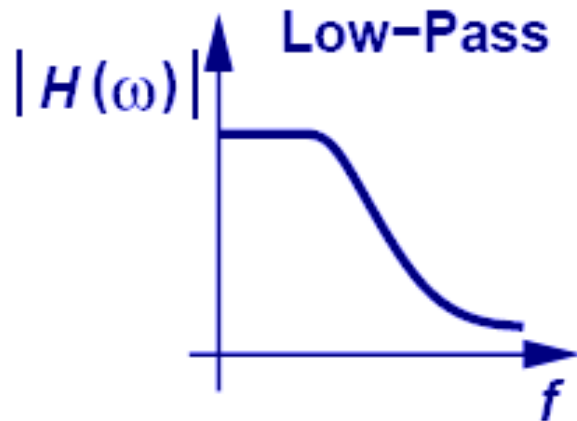
**Solution:** A high-pass filter with stopband attenuation of 60 dB at 60Hz.

## Example 14.3: Filter III

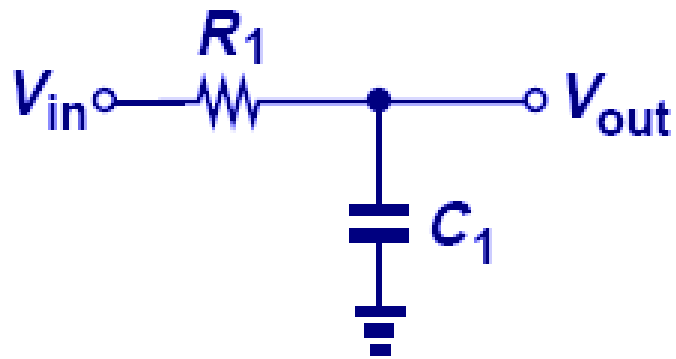


- A bandpass filter around 1.5 GHz is required to reject the adjacent Cellular and PCS signals.

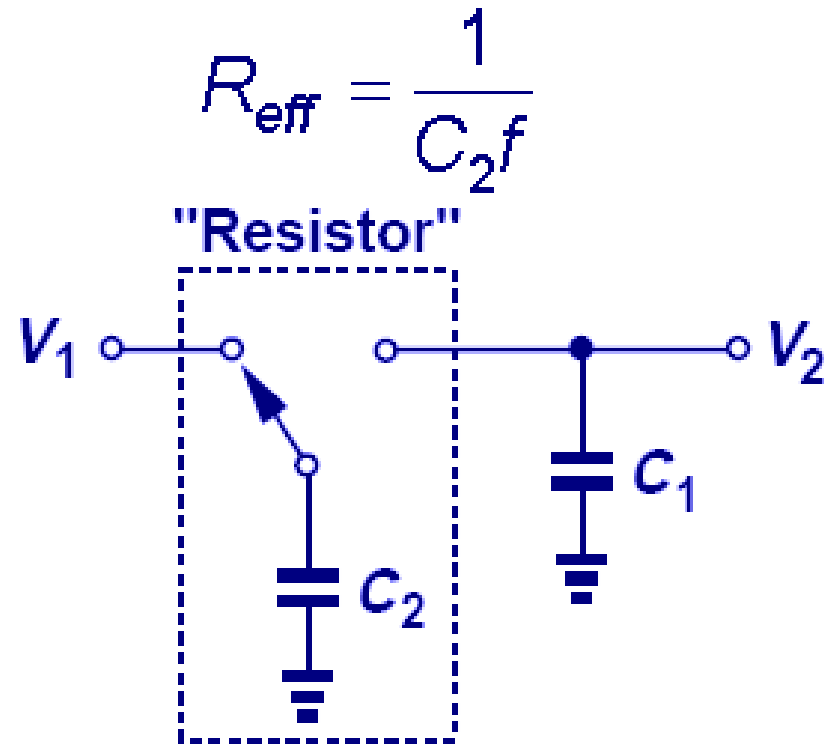
# Classification of Filters I



## Classification of Filters II

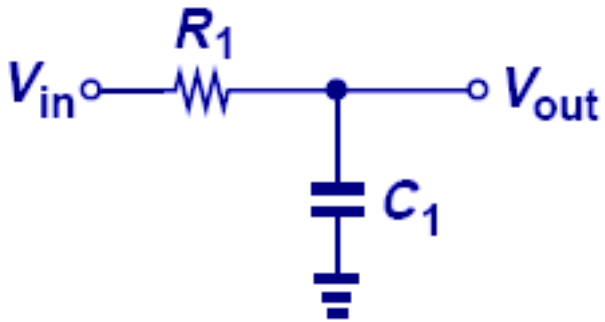


**Continuous-time**

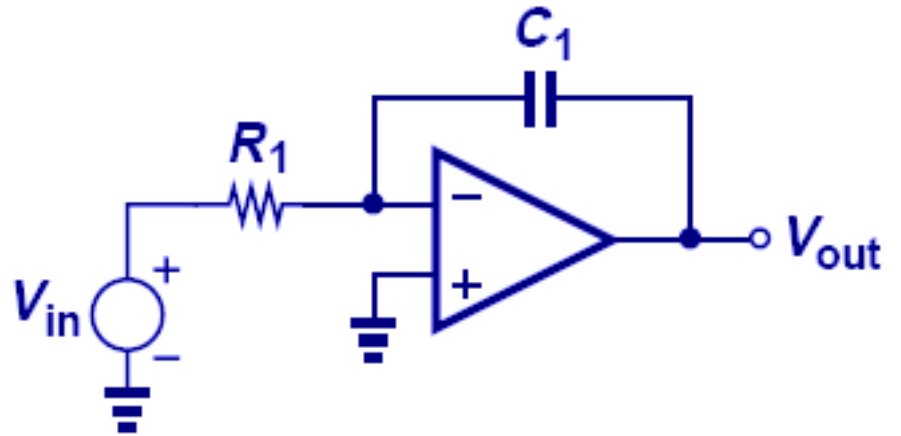


**Discrete-time**

## Classification of Filters III





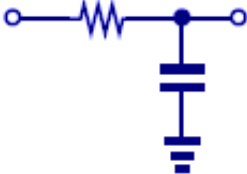
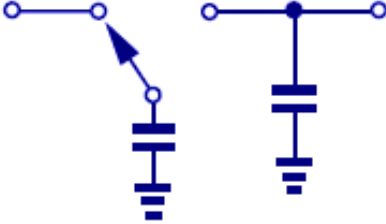
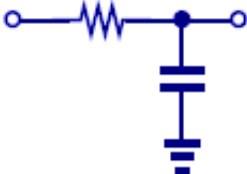
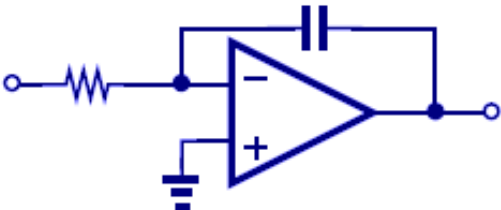


**Passive**

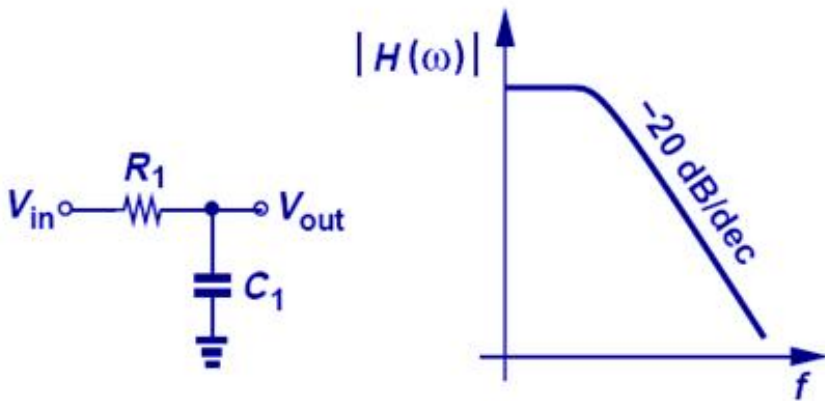


**Active**

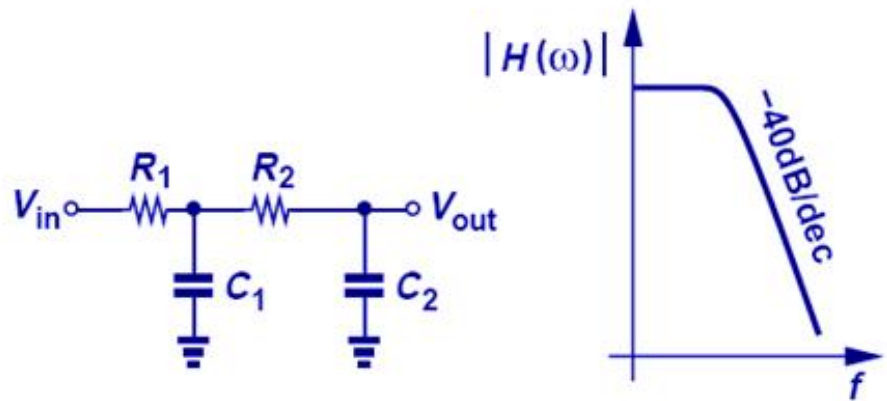
# Summary of Filter Classifications

	Low-Pass	High-Pass	Band-Pass	Band-Reject
Frequency Response				
Continuous-Time and Discrete-Time				
Passive and Active				

# Filter Transfer Function



(a)



(b)

- Filter (a) has a transfer function with  $-20 \text{ dB/dec}$  roll-off.
- Filter (b) has a transfer function with  $-40 \text{ dB/dec}$  roll-off and provides a higher selectivity.

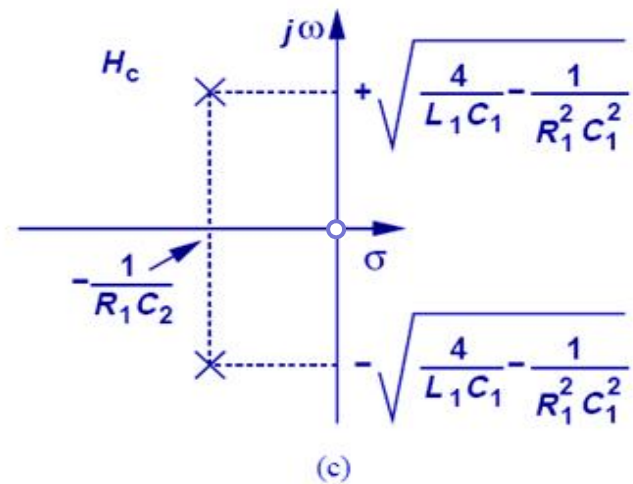
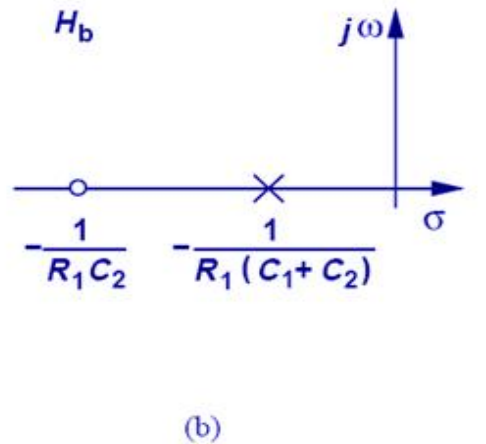
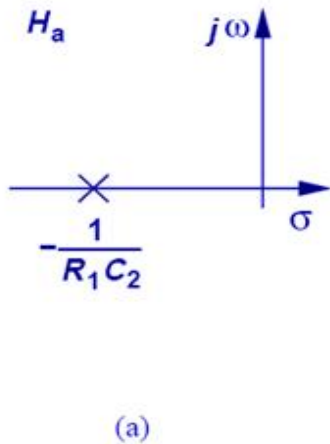
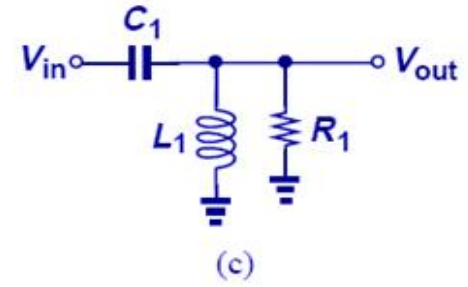
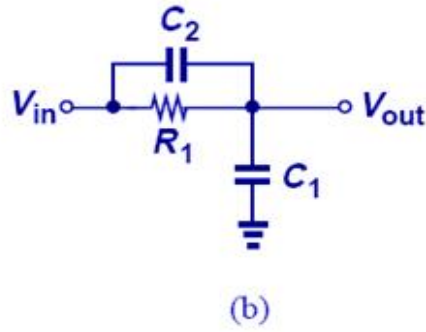
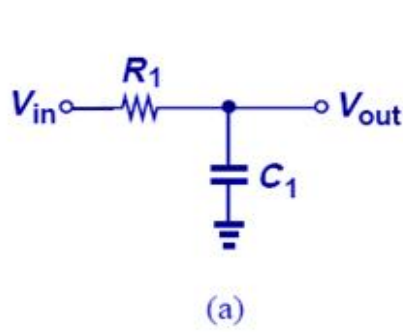
# General Transfer Function

$$H(s) = \alpha \frac{(s - z_1)(s - z_2) \cdots (s - z_m)}{(s - p_1)(s - p_2) \cdots (s - p_n)}$$

**$z_k$  = zero frequencies**

**$p_k$  = pole frequencies**

## Example 14.4 : Pole-Zero Diagram



$$H_a(s) = \frac{1}{R_1 C_1 s + 1}$$

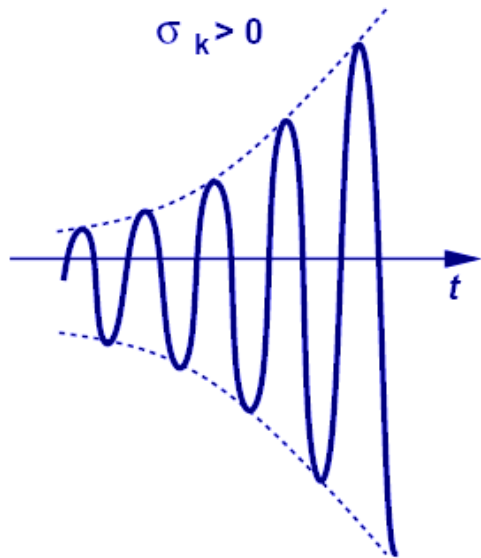
$$H_b(s) = \frac{R_1 C_2 s + 1}{R_1 (C_1 + C_2) s + 1}$$

$$H_c(s) = \frac{C_1 s}{R_1 L_1 C_1 s^2 + L_1 s + R_1}$$

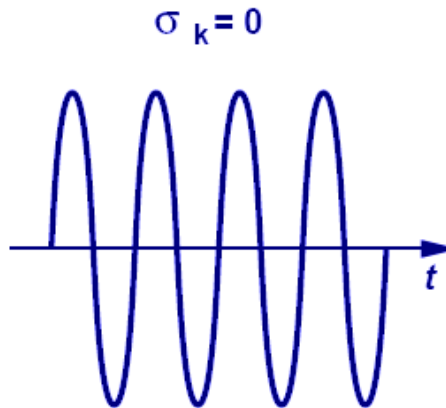
## Example 14.5: Position of the poles

Impulse response contains

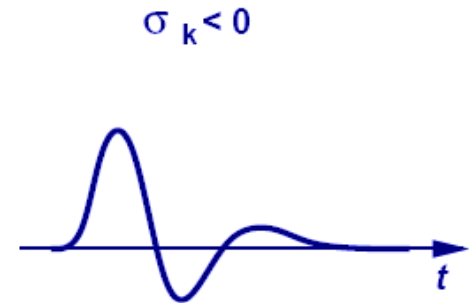
$$\exp(p_k t) = \exp(\sigma_k t) \exp(j\omega_k t)$$



Poles on the RHP  
Unstable  
(no good)



Poles on the  $j\omega$  axis  
Oscillatory  
(no good)



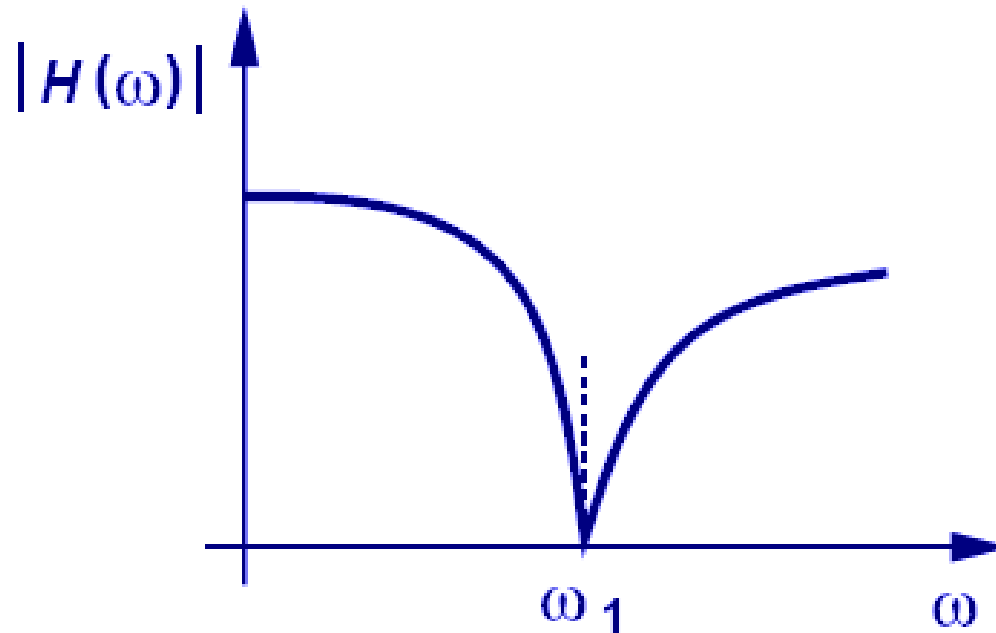
Poles on the LHP  
Decaying  
(good)

# Transfer Function

$$H(s) = \alpha \frac{(s - z_1)(s - z_2) \cdots (s - z_m)}{(s - p_1)(s - p_2) \cdots (s - p_n)}$$

- **The order of the numerator  $m \leq$  The order of the denominator  $n$   
Otherwise,  $H(s) \rightarrow \infty$  as  $s \rightarrow \infty$ .**
- **For a physically-realizable transfer function, complex zeros or poles occur in conjugate pairs.**
- **If a zero is located on the  $j\omega$  axis,  $z_{1,2} = \pm j\omega_1$ ,  $H(s)$  drops to zero at  $\omega_1$ .**

## Imaginary Zeros



- **Imaginary zero is used to create a null at certain frequency.  
For this reason, imaginary zeros are placed only in the stop band.**

# Sensitivity

$$S_C^P = \frac{dP}{P} / \frac{dC}{C}$$

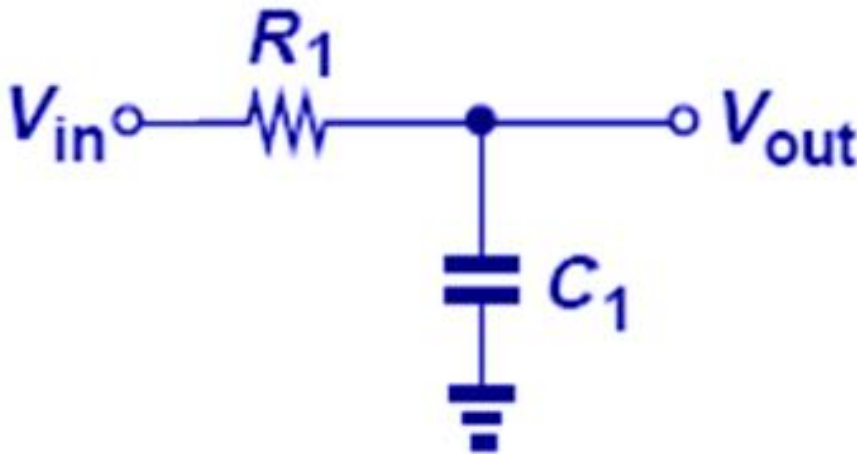
P=Filter Parameter

C=Component Value

➤ **Sensitivity indicates the variation of a filter parameter due to variation of a component value.**

## Example 14.6: Sensitivity

**Problem:** Determine the sensitivity of  $\omega_0$  with respect to  $R_1$ .



$$\omega_0 = 1/(R_1 C_1)$$

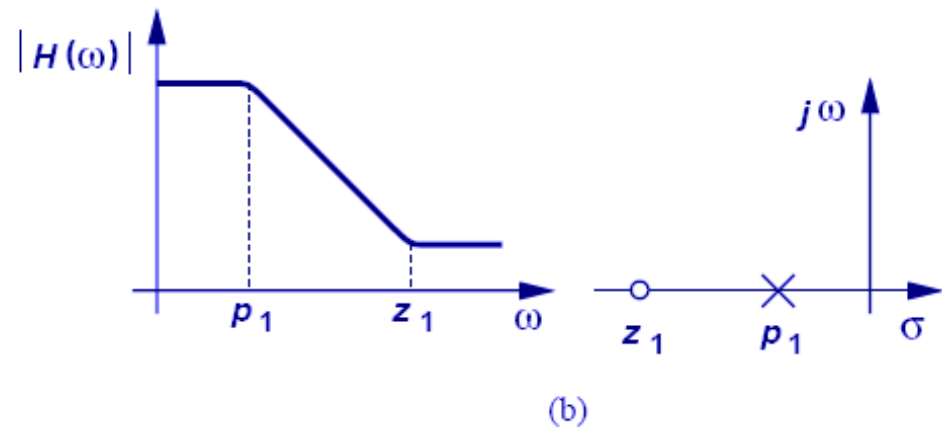
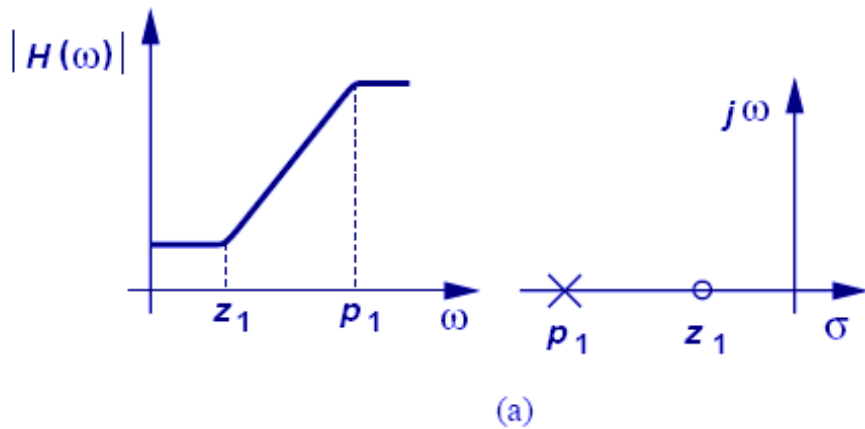
$$\frac{d\omega_0}{dR_1} = \frac{-1}{R_1^2 C_1}$$

$$\frac{d\omega_0}{\omega_0} = -\frac{dR_1}{R_1}$$

$$S_{R_1}^{\omega_0} = -1$$

➤ For example, a +5% change in  $R_1$  translates to a -5% error in  $\omega_0$ .

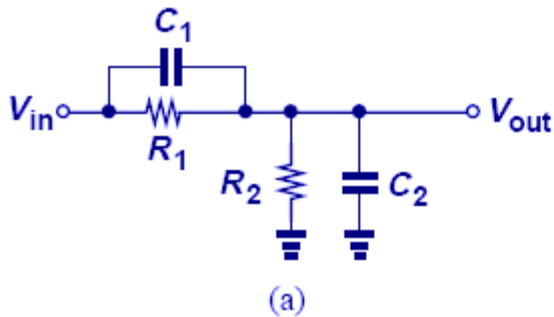
# First-Order Filters



$$H(s) = \alpha \frac{s + z_1}{s + p_1}$$

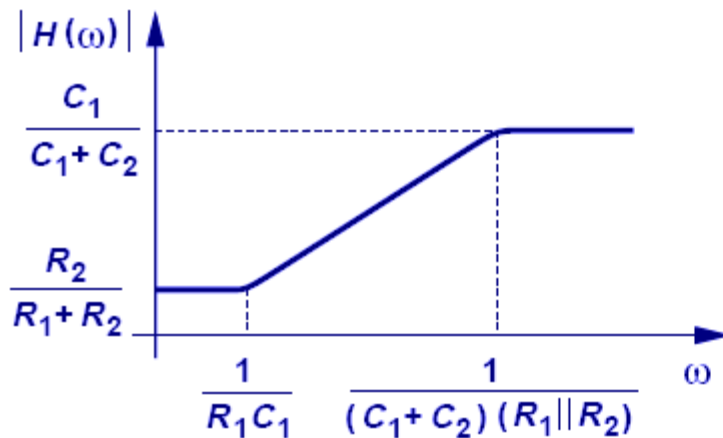
- First-order filters are represented by the transfer function shown above.
- Low/high pass filters can be realized by changing the relative positions of poles and zeros.

## Example 14.8: First-Order Filter I

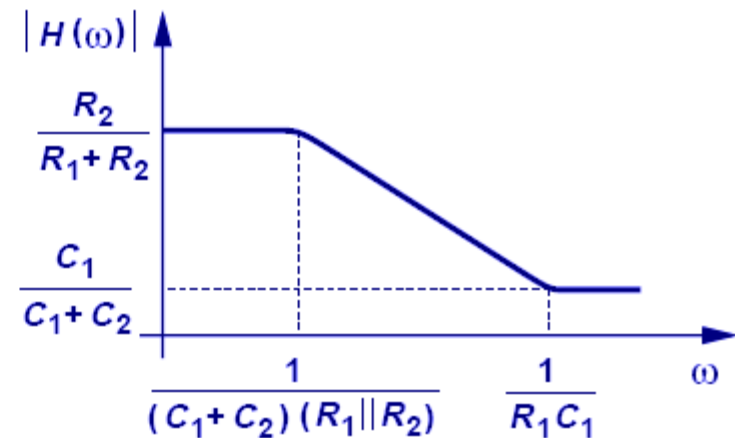


$$\frac{V_{out}}{V_{in}}(s) = \frac{R_2(R_1C_1s + 1)}{R_1R_2(C_1 + C_2)s + R_1 + R_2}$$

$$z_1 = -1/(R_1C_1), p_1 = -[(C_1 + C_2)R_1 \parallel R_2]^{-1}$$

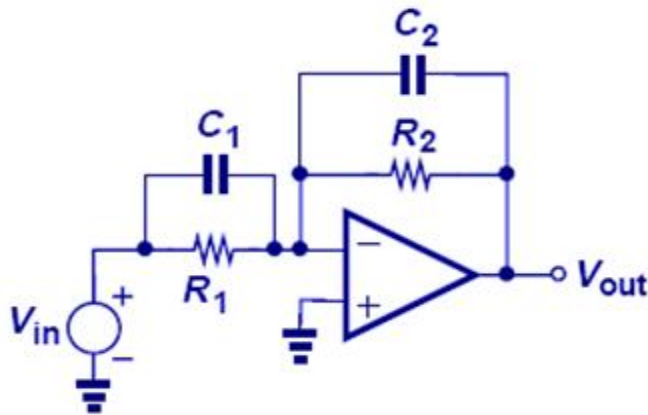


$$R_2C_2 < R_1C_1$$



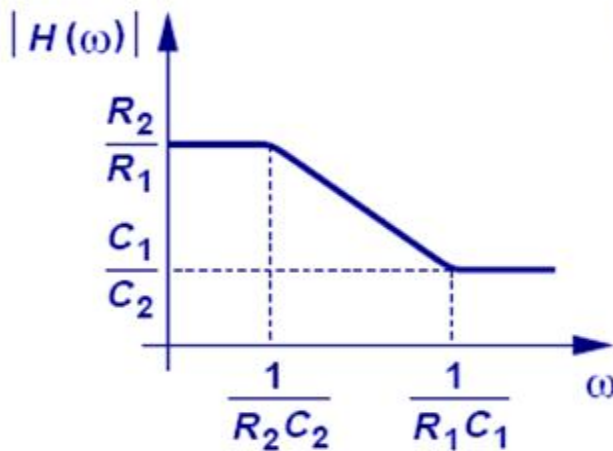
$$R_2C_2 > R_1C_1$$

## Example 14.9: First-Order Filter II



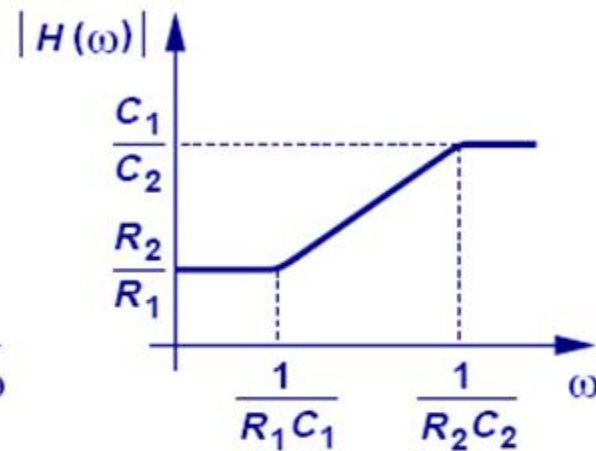
(a)

$$\begin{aligned} \frac{V_{out}}{V_{in}}(s) &= \frac{-(R_2 \parallel \frac{1}{C_2 s})}{R_1 \parallel \frac{1}{C_1 s}} \\ &= -\frac{R_2}{R_1} \cdot \frac{R_1 C_1 s + 1}{R_2 C_2 s + 1} \end{aligned}$$



(b)

$$\mathbf{R_2 C_2 < R_1 C_1}$$



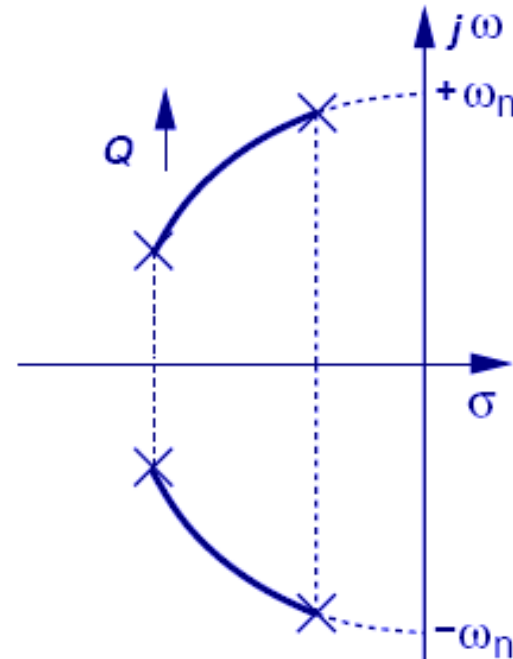
(c)

$$\mathbf{R_2 C_2 > R_1 C_1}$$

## Second-Order Filters

$$H(s) = \frac{\alpha s^2 + \beta s + \gamma}{s^2 + \frac{\omega_n}{Q} s + \omega_n^2}$$

$$p_{1,2} = -\frac{\omega_n}{2Q} \pm j\omega_n \sqrt{1 - \frac{1}{4Q^2}}$$

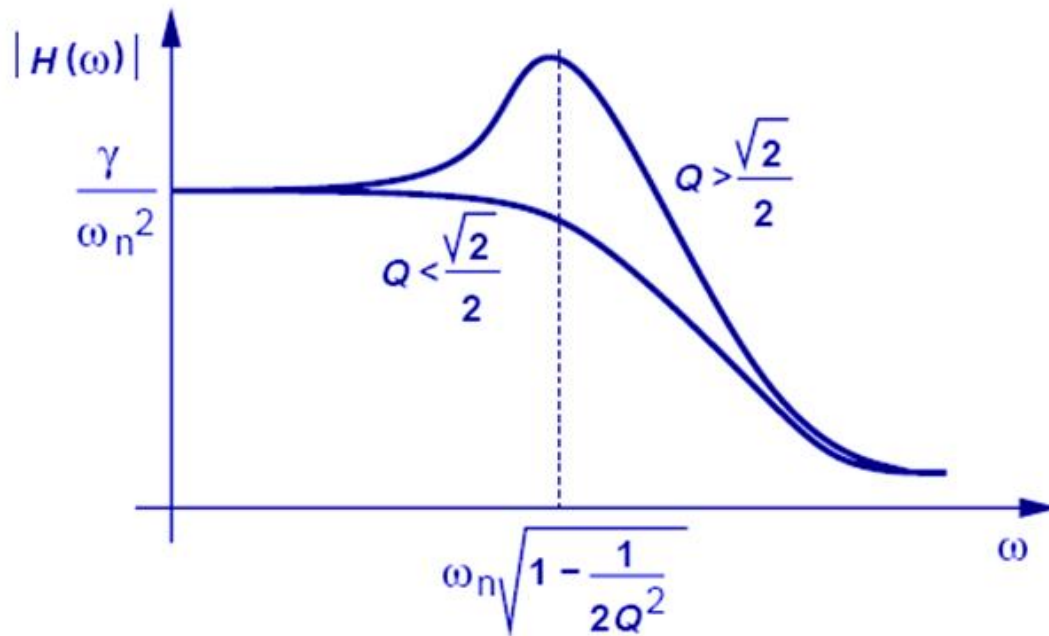


- Second-order filters are characterized by the “biquadratic” equation with two complex poles shown above.
- When  $Q$  increases, the real part decreases while the imaginary part approaches  $\pm \omega_n$ .  
=> the poles look very imaginary thereby bringing the circuit closer to instability.

# Second-Order Low-Pass Filter

$$\alpha = \beta = 0$$

$$|H(j\omega)|^2 = \frac{\gamma^2}{\left(\omega_n^2 - \omega^2\right)^2 + \left(\frac{\omega_n}{Q} \omega\right)^2}$$

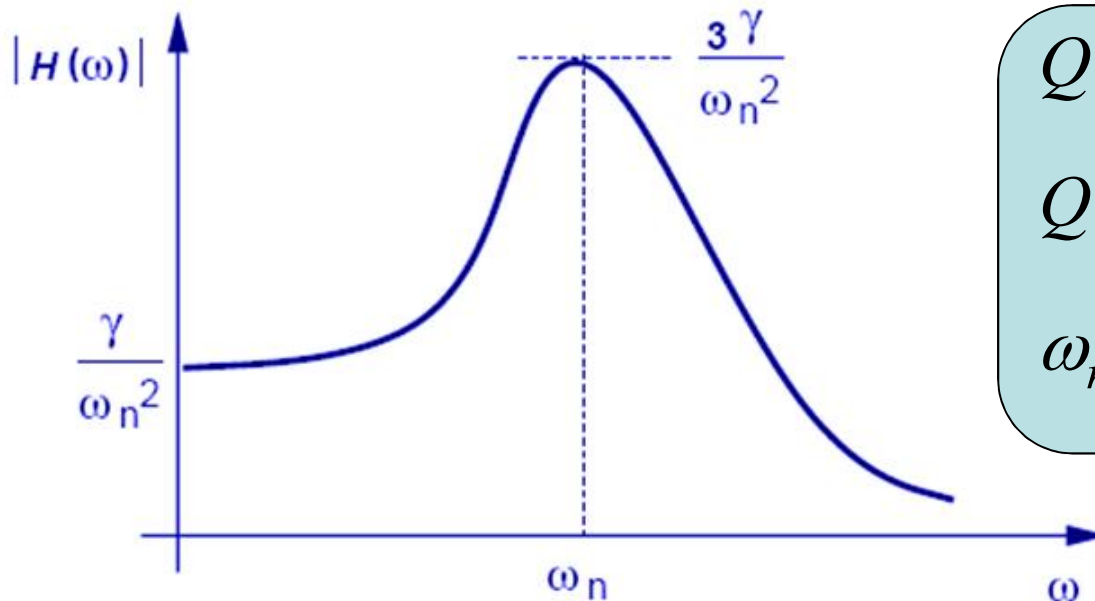


Peak magnitude normalized to the passband magnitude:  $Q/\sqrt{1 - (4Q^2)^{-1}}$

## Example 14.10: Second-Order LPF

**Problem:**  $Q$  of a second-order LPF = 3.

**Estimate the magnitude and frequency of the peak in the frequency response.**



$$Q = 3$$

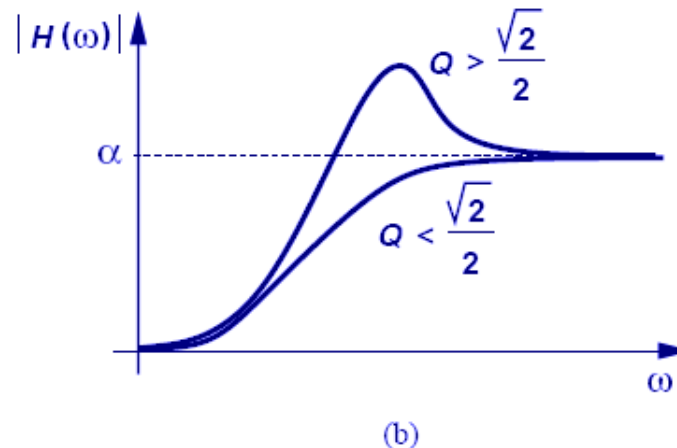
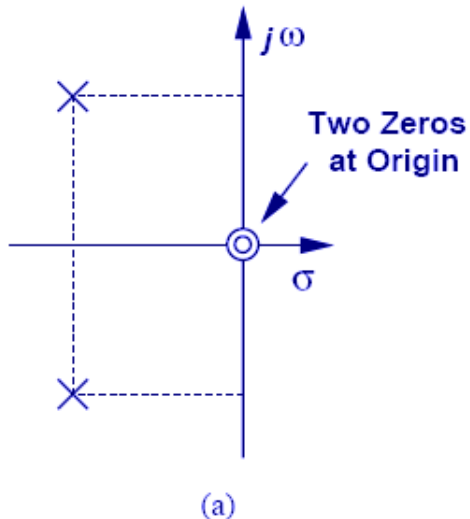
$$Q / \sqrt{1 - 1/(4Q^2)} \approx 3$$

$$\omega_n \sqrt{1 - 1/(2Q^2)} \approx \omega_n$$

# Second-Order High-Pass Filter

$$H(s) = \frac{\alpha s^2}{s^2 + \frac{\omega_n}{Q}s + \omega_n^2}$$

$$\beta = \gamma = 0$$



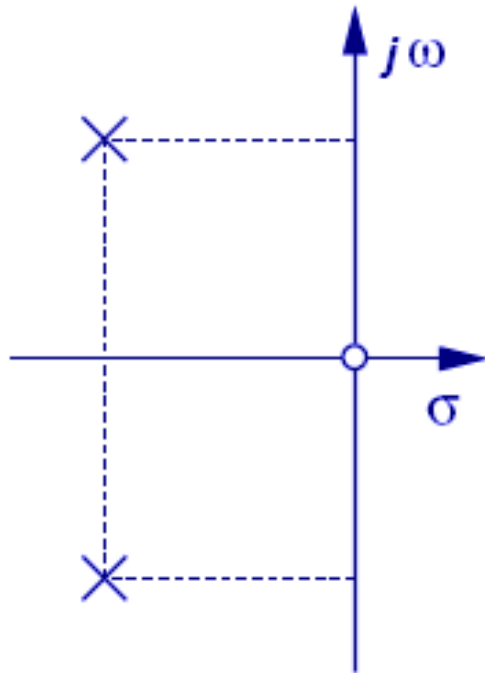
Frequency of the peak:  $\omega_n / \sqrt{1 - 1/(2Q^2)}$

Peak magnitude normalized to the passband magnitude:  $Q / \sqrt{1 - (4Q^2)^{-1}}$

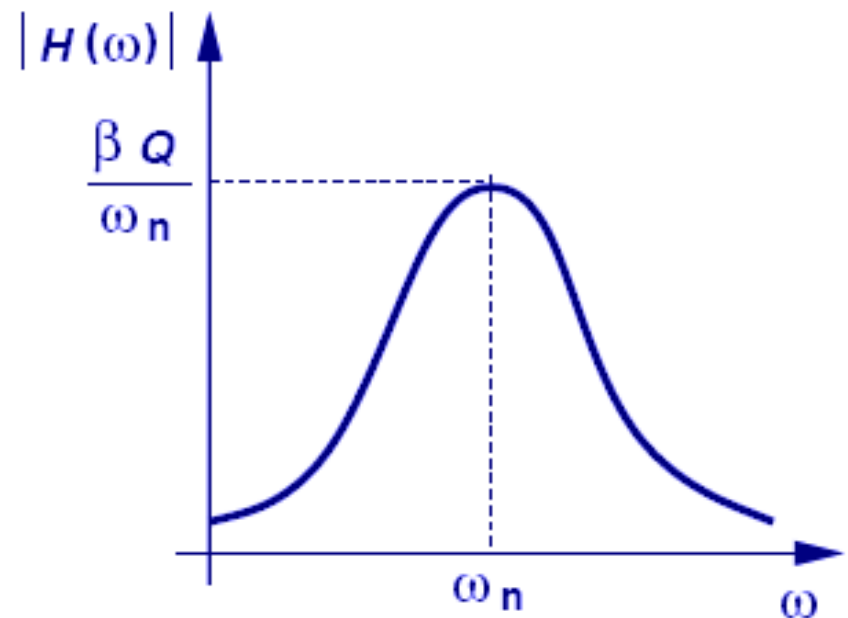
## Second-Order Band-Pass Filter

$$H(s) = \frac{\beta s}{s^2 + \frac{\omega_n}{Q}s + \omega_n^2}$$

$$\alpha = \gamma = 0$$



(a)

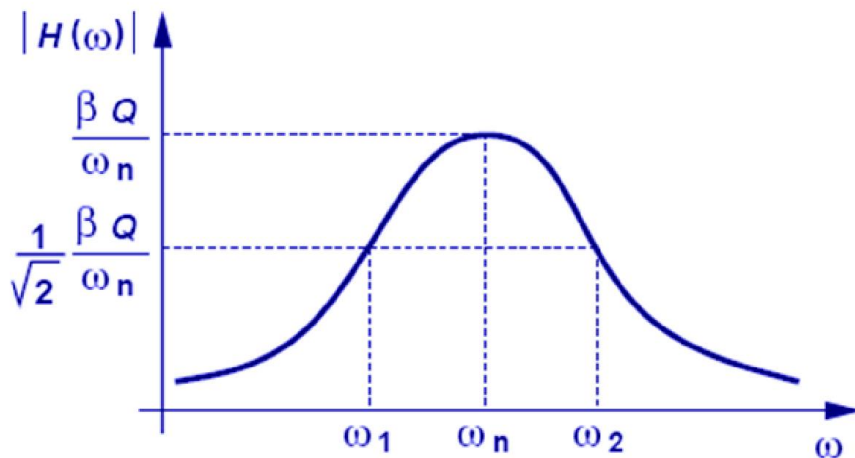


(b)

## Example 14.2: -3-dB Bandwidth

Problem: Determine the -3dB bandwidth of a band-pass response.

$$H(s) = \frac{\beta s}{(s^2 + \frac{\omega_n}{Q}s + \omega_n^2)}$$

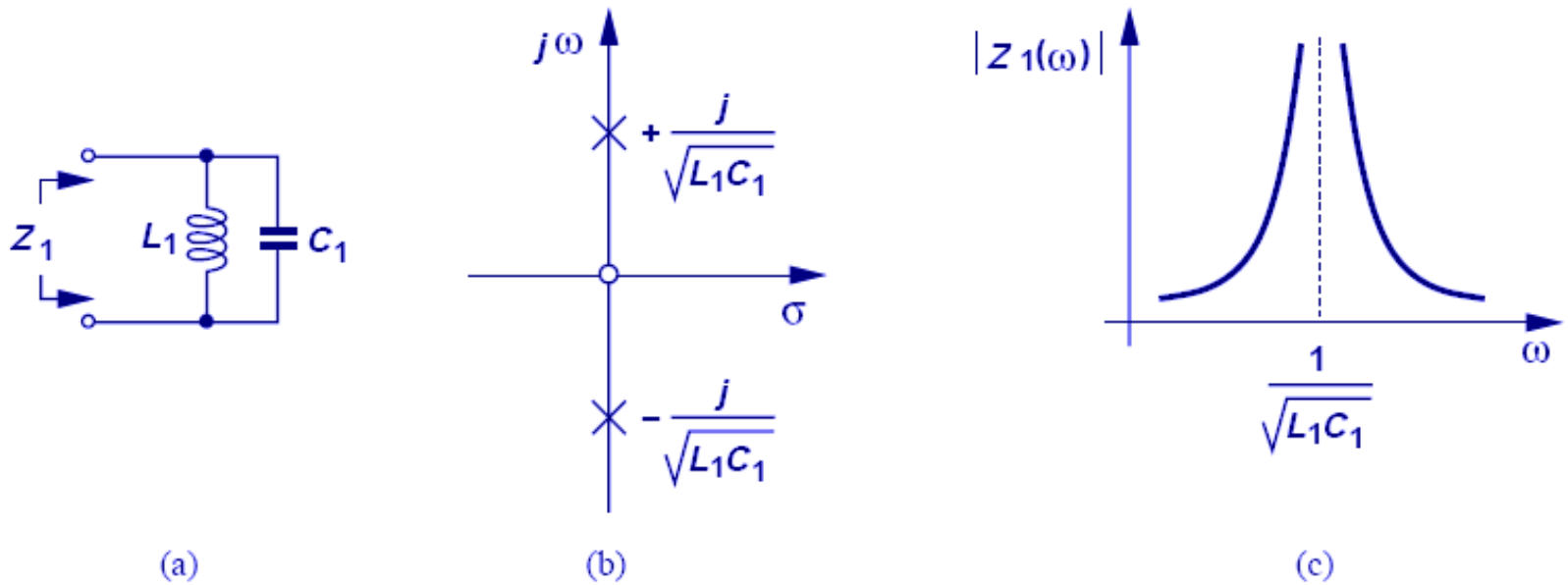


$$\frac{\beta^2 \omega^2}{(\omega_n^2 - \omega^2)^2 + (\frac{\omega_n}{Q} \omega)^2} = \frac{\beta^2 Q^2}{2\omega_n^2}$$

$$\omega_{1,2} = \omega_0 \left[ \sqrt{1 + \frac{1}{4Q^2}} \pm \frac{1}{2Q} \right]$$

$$BW = \frac{\omega_0}{Q}$$

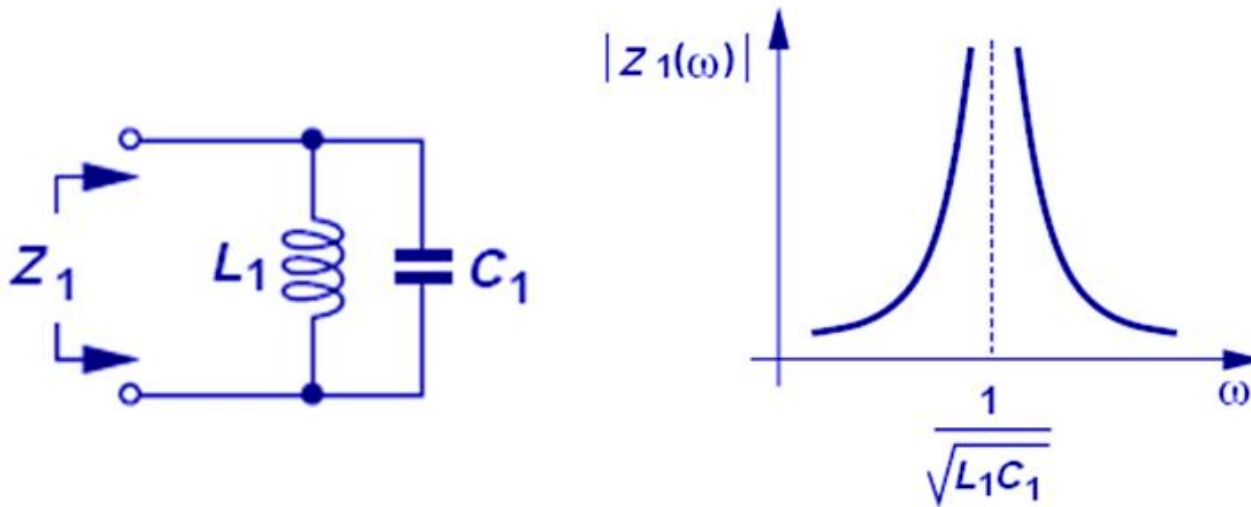
# LC Realization of Second-Order Filters



$$Z_1 = (L_1 s) \parallel \frac{1}{C_1 s} = \frac{L_1 s}{L_1 C_1 s^2 + 1}$$

➤ An LC tank realizes a second-order band-pass filter with two imaginary poles at  $\pm j/(L_1 C_1)^{1/2}$ , which implies infinite impedance at  $\omega = 1/(L_1 C_1)^{1/2}$ .

## Example 14.13: LC Tank

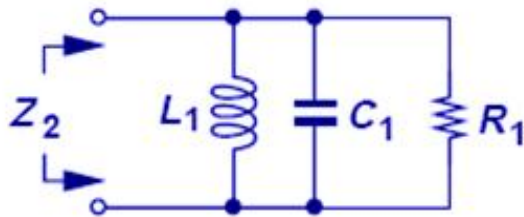


$$Z_1 = (L_1 s) \parallel \frac{1}{C_1 s} = \frac{L_1 s}{L_1 C_1 s^2 + 1}$$

- At  $\omega=0$ , the inductor acts as a short.
- At  $\omega=\infty$ , the capacitor acts as a short.

# RLC Realization of Second-Order Filters

$$\begin{aligned}
 Z_2 &= R_1 \parallel \frac{L_1 s}{L_1 C_1 s^2 + 1} = \frac{R_1 L_1 s}{R_1 L_1 C_1 s^2 + L_1 s + R_1} \\
 &= \frac{R_1 L_1 s}{R_1 L_1 C_1 (s^2 + \frac{1}{R_1 C_1} s + \frac{1}{L_1 C_1})} = \frac{R_1 L_1 s}{R_1 L_1 C_1 (s^2 + \frac{\omega_n}{Q} s + \omega_n^2)}
 \end{aligned}$$



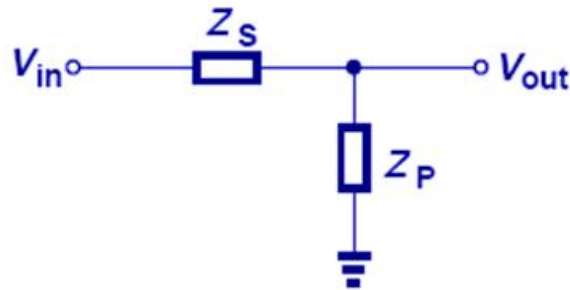
$$\omega_n = \frac{1}{\sqrt{L_1 C_1}}, \quad Q = R_1 \sqrt{\frac{C_1}{L_1}}$$

$$p_{1,2} = -\frac{\omega_n}{2Q} \pm j\omega_n \sqrt{1 - \frac{1}{4Q^2}}$$

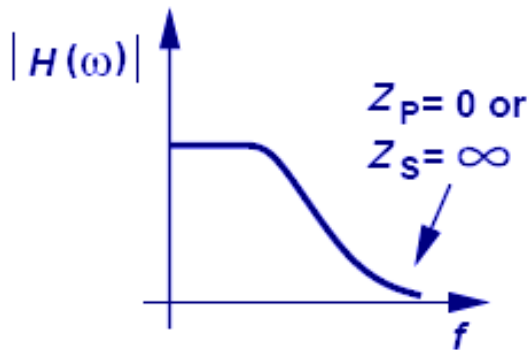
$$= -\frac{1}{2R_1 C_1} \pm j \frac{1}{\sqrt{L_1 C_1}} \sqrt{1 - \frac{L_1}{4R_1^2 C_1}}$$

➤ **With a resistor, the poles are no longer pure imaginary which implies there will be no infinite impedance at any  $\omega$ .**

# Voltage Divider Using General Impedances

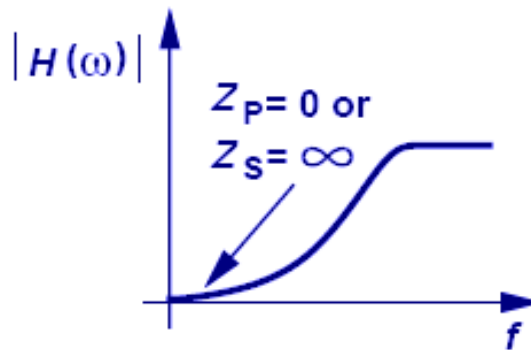


$$\frac{V_{out}}{V_{in}}(s) = \frac{Z_P}{Z_S + Z_P}$$



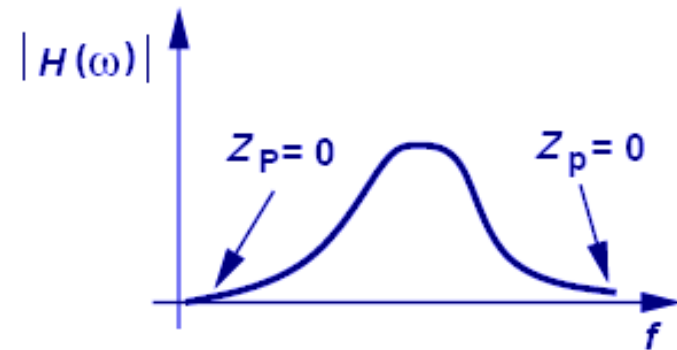
(a)

**Low-pass**



(b)

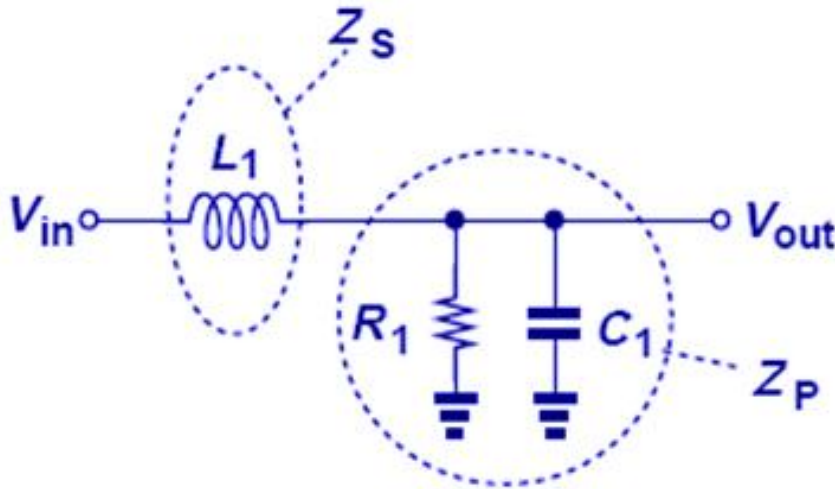
**High-pass**



(c)

**Band-pass**

# Low-pass Filter Implementation with Voltage Divider

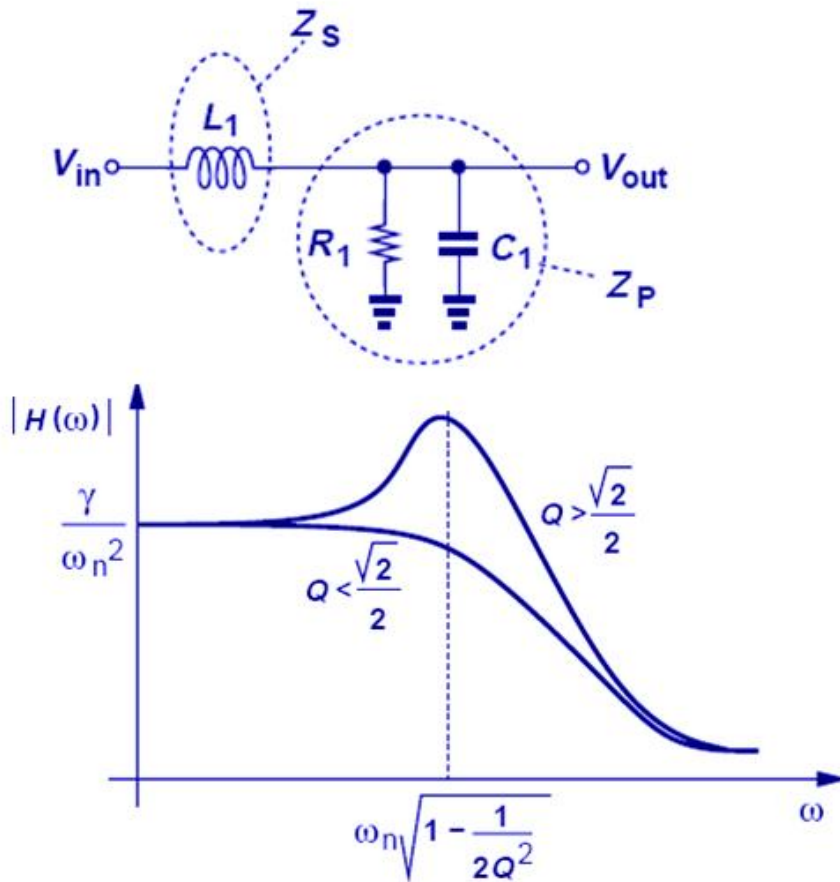


$$Z_S = L_1 s \rightarrow \infty \text{ as } s \rightarrow \infty$$

$$Z_P = \frac{1}{C_1 s} \parallel R_1 \rightarrow 0 \text{ as } s \rightarrow \infty$$

$$\frac{V_{out}}{V_{in}}(s) = \frac{R_1}{R_1 C_1 L_1 s^2 + L_1 s + R_1}$$

## Example 14.14: Frequency Peaking



$$\frac{V_{out}}{V_{in}}(s) = \frac{R_1}{R_1 C_1 L_1 s^2 + L_1 s + R_1}$$

$$\text{Let } |D|^2 = (R_1 - R_1 C_1 L_1 \omega^2)^2 + L_1^2 \omega^2$$

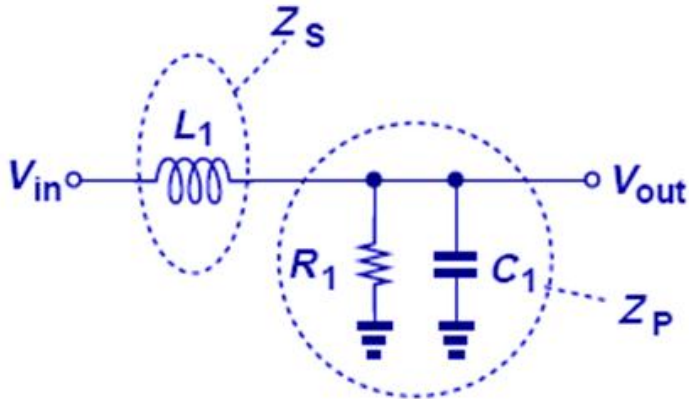
Voltage gain greater than unity (peaking) occurs when a solution exists for

$$\begin{aligned} \frac{d|D|^2}{d(\omega^2)} &= 2(-R_1 C_1 L_1)(R_1 - R_1 C_1 L_1 \omega^2) + L_1^2 \\ &= 0 \end{aligned}$$

Thus, when  $Q = R_1 \cdot \sqrt{\frac{C_1}{L_1}} > \frac{1}{\sqrt{2}}$ ,

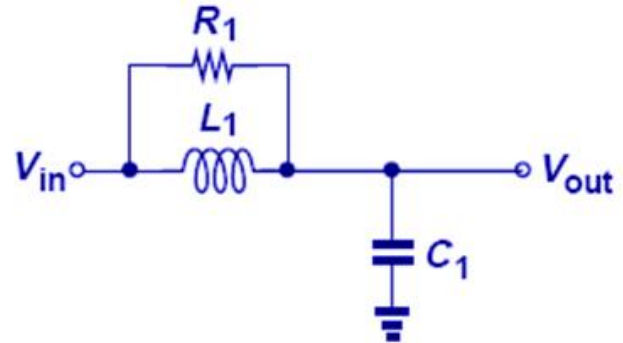
peaking occurs.

## Example 14.15: Low-pass Circuit Comparison



(a)

Good

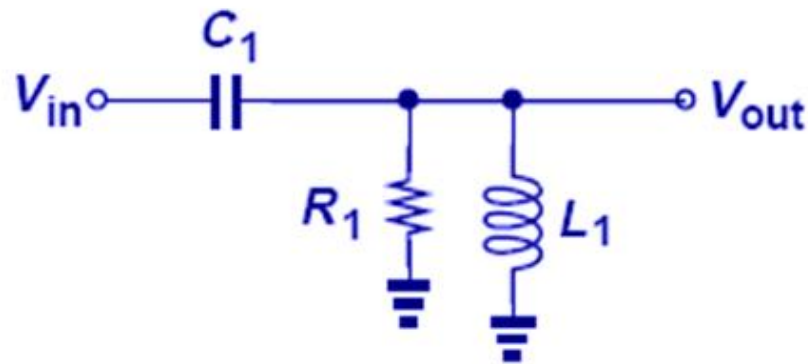


(b)

Bad

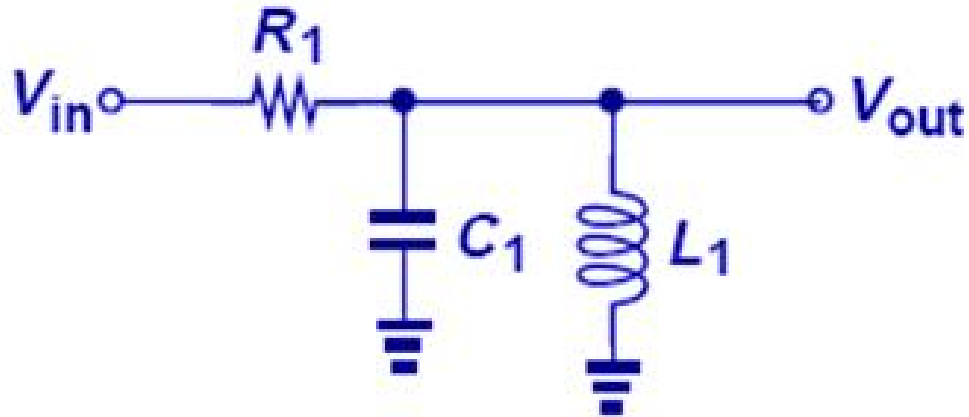
- The circuit (a) has a -40dB/dec roll-off at high frequency.
- However, the circuit (b) exhibits only a -20dB/dec roll-off since the parallel combination of  $L_1$  and  $R_1$  is dominated by  $R_1$  because  $L_1\omega \rightarrow \infty$ , thereby reducing the circuit to  $R_1$  and  $C_1$ .

# High-pass Filter Implementation with Voltage Divider



$$\frac{V_{out}}{V_{in}}(s) = \frac{(L_1 s) \parallel R_1}{(L_1 s) \parallel R_1 + \frac{1}{C_1 s}} = \frac{L_1 C_1 R_1 s^2}{R_1 C_1 L_1 s^2 + L_1 s + R_1}$$

## Band-pass Filter Implementation with Voltage Divider

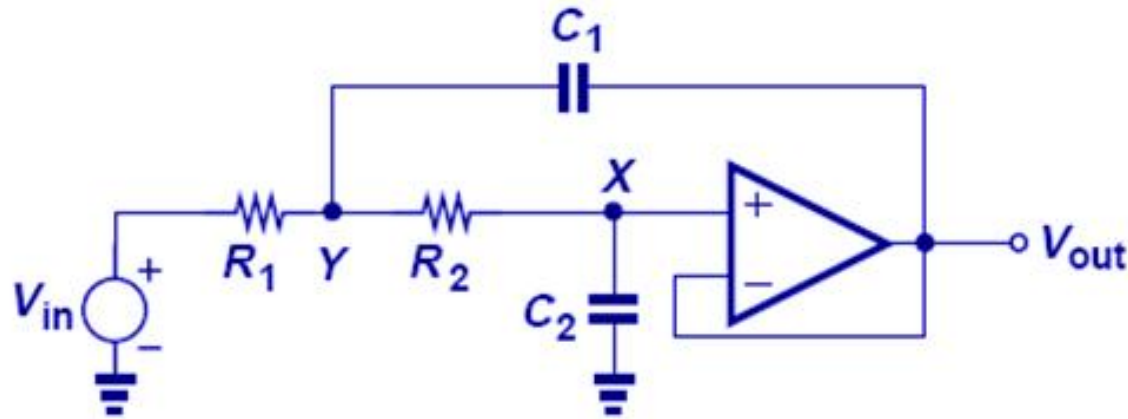


$$\frac{V_{out}}{V_{in}}(s) = \frac{(L_1 s) \parallel \frac{1}{C_1 s}}{(L_1 s) \parallel \frac{1}{C_1 s} + R_1} = \frac{L_1 s}{R_1 C_1 L_1 s^2 + L_1 s + R_1}$$

## Why Active Filter?

- **Passive filters constrain the type of transfer function.**
- **They may require bulky inductors.**

## Sallen and Key (SK) Filter: Low-Pass



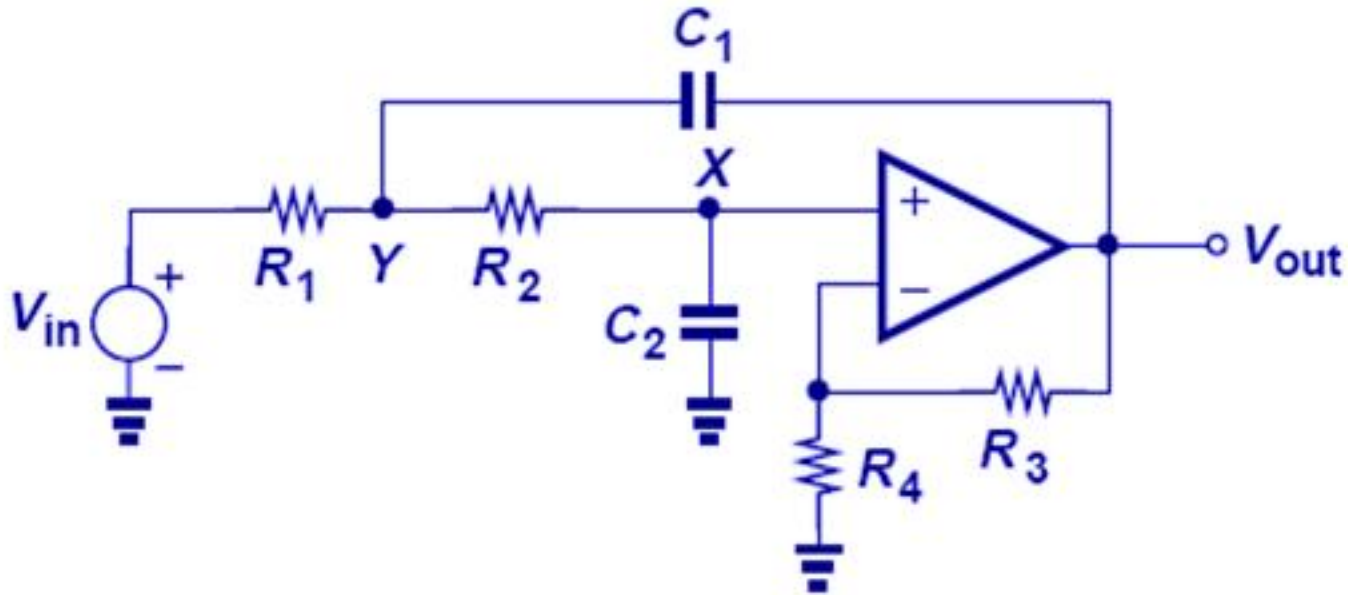
$$\frac{V_{out}}{V_{in}}(s) = \frac{1}{R_1 R_2 C_1 C_2 s^2 + (R_1 + R_2) C_2 s + 1}$$

$$Q = \frac{1}{R_1 + R_2} \sqrt{R_1 R_2 \frac{C_1}{C_2}}$$

$$\omega_n = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

- **Sallen and Key filters are examples of active filters. This particular filter implements a low-pass, second-order transfer function.**

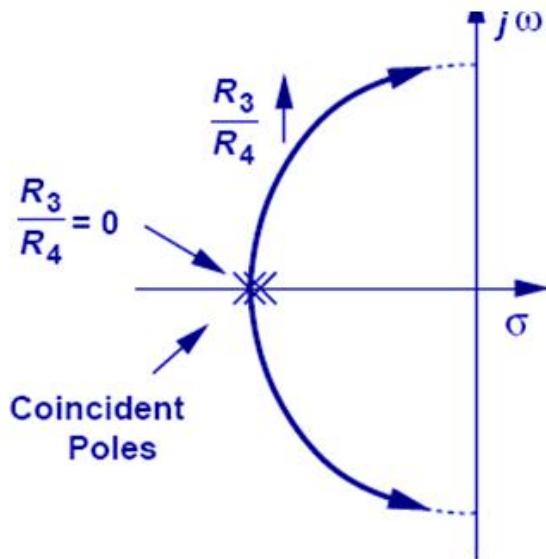
## Example 14.16: SK Filter with Voltage Gain



$$\frac{V_{out}}{V_{in}}(s) = \frac{1 + \frac{R_3}{R_4}}{R_1 R_2 C_1 C_2 s^2 + \left( R_1 C_2 + R_2 C_2 - R_1 \frac{R_3}{R_4} C_1 \right) s + 1}$$

## Example 14.17: SK Filter Poles

Problem: Assuming  $R_1=R_2$ ,  $C_1=C_2$ , Does such a filter contain complex poles?



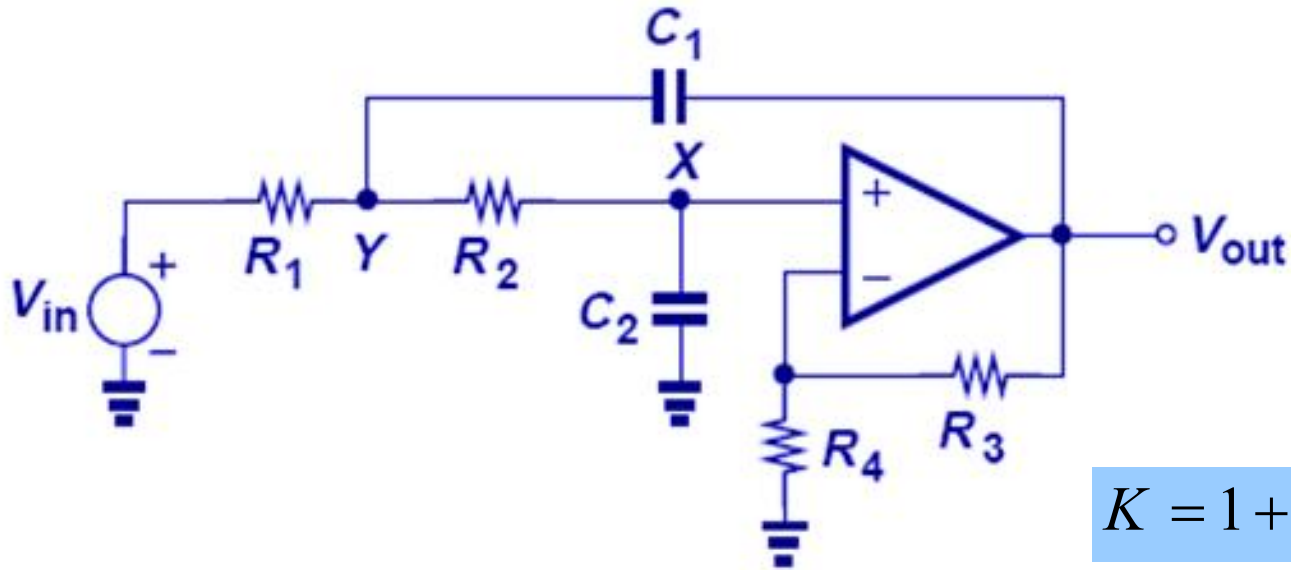
$$\frac{V_{out}}{V_{in}}(s) = \frac{1 + \frac{R_3}{R_4}}{R_1 R_2 C_1 C_2 s^2 + (R_1 C_2 + R_2 C_2 - R_1 \frac{R_3}{R_4} C_1) s + 1}$$

$$\frac{1}{Q} = \sqrt{\frac{R_1 C_2}{R_2 C_1}} + \sqrt{\frac{R_2 C_2}{R_1 C_1}} - \sqrt{\frac{R_1 C_1}{R_2 C_2}} \frac{R_3}{R_4}$$

$$Q = \frac{1}{2 - \frac{R_3}{R_4}}$$

➤ The poles begin with real, equal values for  $R_3/R_4 = 0$  and become complex for  $R_3/R_4 > 0$ .

# Sensitivity in Low-Pass SK Filter



$$K = 1 + R_3/R_4$$

$$S_{R_1}^{\omega_n} = S_{R_2}^{\omega_n} = S_{C_1}^{\omega_n} = S_{C_2}^{\omega_n} = -\frac{1}{2}$$

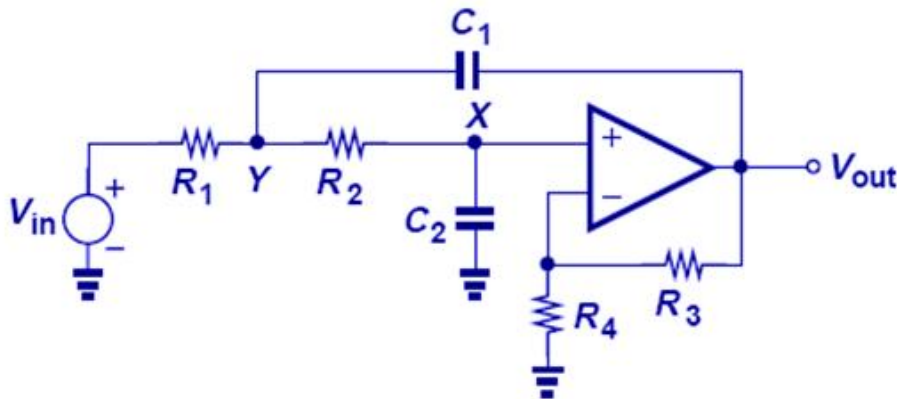
$$S_{C_1}^Q = -S_{C_2}^Q = -\frac{1}{2} + Q \left( \sqrt{\frac{R_2 C_2}{R_1 C_1}} + \sqrt{\frac{R_1 C_2}{R_2 C_1}} \right)$$

$$S_{R_1}^Q = -S_{R_2}^Q = -\frac{1}{2} + Q \sqrt{\frac{R_2 C_2}{R_1 C_1}}$$

$$S_K^Q = QK \sqrt{\frac{R_1 C_1}{R_2 C_2}}$$

## Example 14.18: SK Filter Sensitivity I

Problem: Determine the Q sensitivities of the SK filter for the common choice  $R_1=R_2=R$ ,  $C_1=C_2=C$ .



$$S_{R_1}^Q = -S_{R_2}^Q = -\frac{1}{2} + \frac{1}{3-K}$$

$$S_{C_1}^Q = -S_{C_2}^Q = -\frac{1}{2} + \frac{2}{3-K}$$

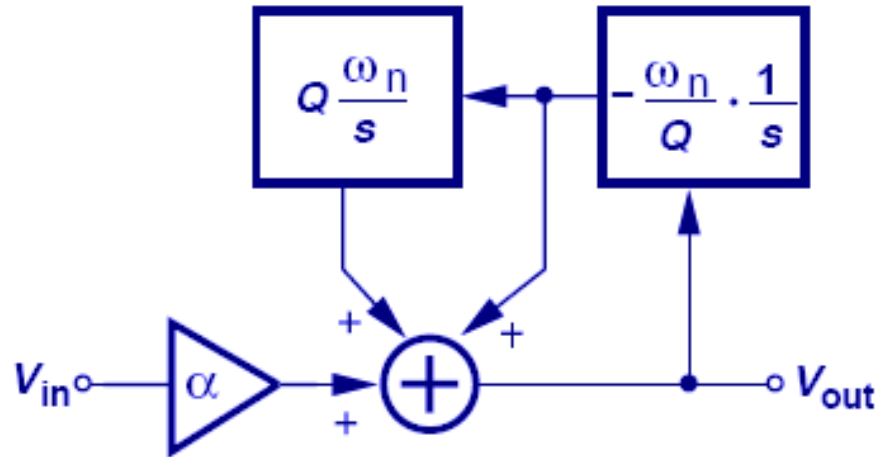
$$S_K^Q = \frac{K}{3-K}$$

With  $K=1$ ,

$$\left| S_{R_1}^Q \right| = \left| S_{R_2}^Q \right| = 0$$

$$\left| S_{C_1}^Q \right| = \left| S_{C_2}^Q \right| = \left| S_K^Q \right| = \frac{1}{2}$$

# Integrator-Based Biquads

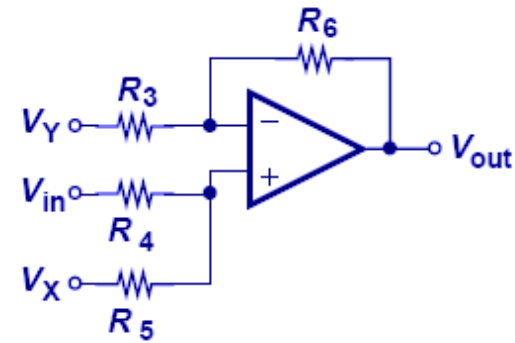
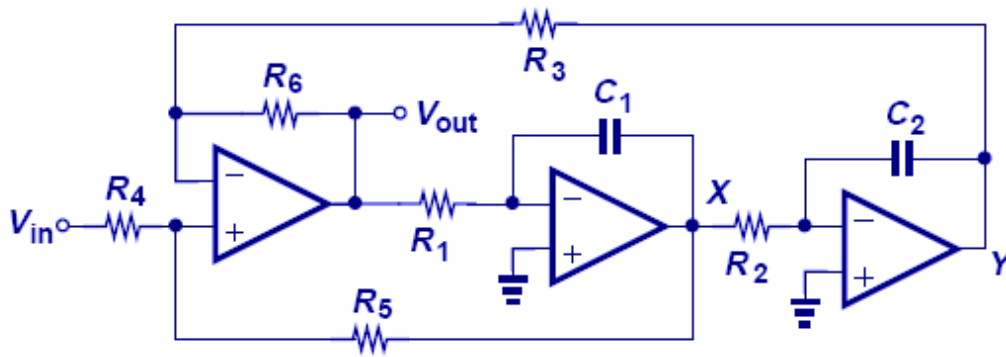


$$\frac{V_{out}}{V_{in}}(s) = \frac{\alpha s^2}{s^2 + \frac{\omega_n}{Q}s + \omega_n^2}$$

$$V_{out}(s) = \alpha V_{in}(s) - \frac{\omega_n}{Q} \cdot \frac{1}{s} V_{out}(s) - \frac{\omega_n^2}{s^2} V_{out}(s)$$

➤ It is possible to use integrators to implement biquadratic transfer functions.

# KHN (Kerwin, Huelsman, and Newcomb) Biquads



$$V_X = -\frac{1}{R_1 C_1 s} V_{out}, \quad V_Y = -\frac{1}{R_2 C_2 s} V_X = \frac{1}{R_1 R_2 C_1 C_2 s^2} V_{out}$$

$$V_{out} = \frac{V_{in} R_5 + V_X R_4}{R_4 + R_5} \left( 1 + \frac{R_6}{R_3} \right) - V_Y \frac{R_6}{R_3}$$

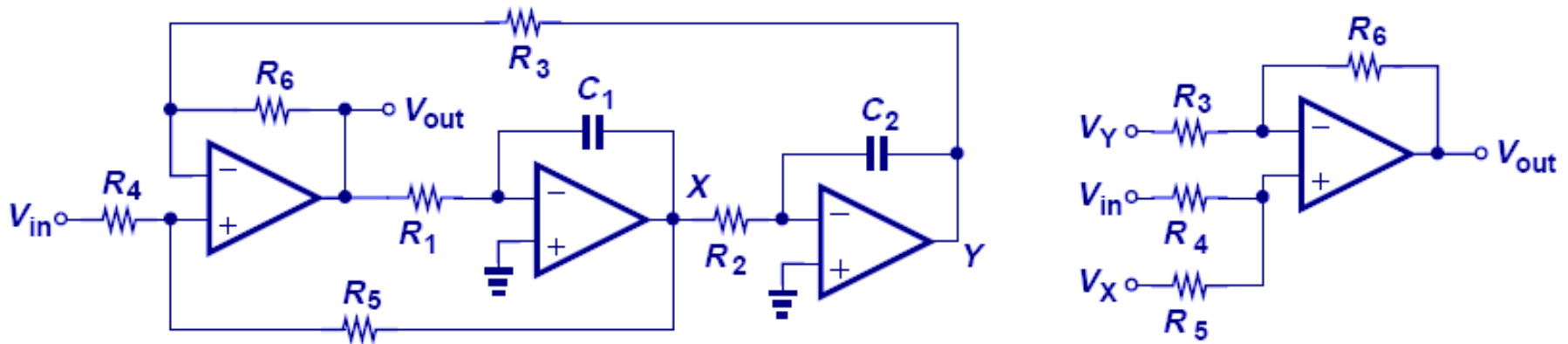
Comparing with  $V_{out}(s) = \alpha V_{in}(s) - \frac{\omega_n}{Q} \cdot \frac{1}{s} V_{out}(s) - \frac{\omega_n^2}{s^2} V_{out}(s)$

$$\alpha = \frac{R_5}{R_4 + R_5} \left( 1 + \frac{R_6}{R_3} \right)$$

$$\frac{\omega_n}{Q} = \frac{R_4}{R_4 + R_5} \cdot \frac{1}{R_1 C_1} \cdot \left( 1 + \frac{R_6}{R_3} \right)$$

$$\omega_n^2 = \frac{R_6}{R_3} \cdot \frac{1}{R_1 R_2 C_1 C_2}$$

# Versatility of KHN Biquads

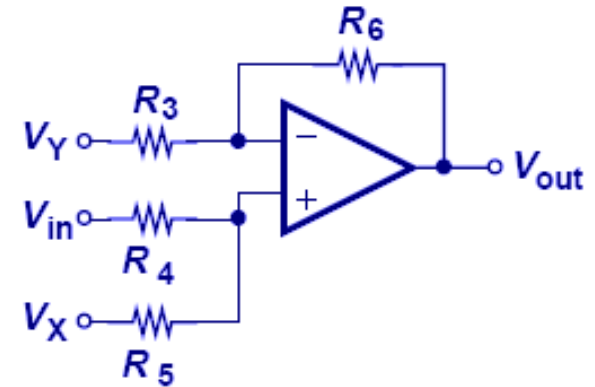
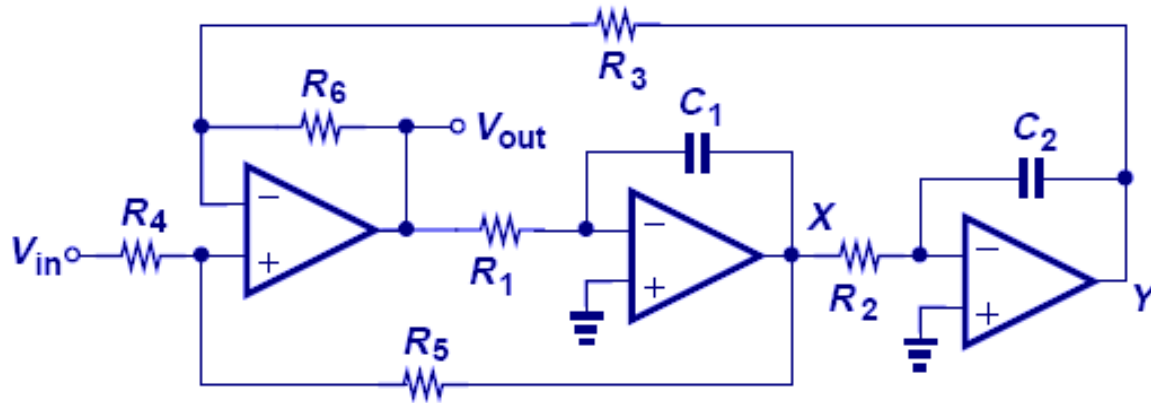


$$\text{High-pass: } \frac{V_{out}}{V_{in}}(s) = \frac{\alpha s^2}{s^2 + \frac{\omega_n}{Q}s + \omega_n^2}$$

$$\text{Band-pass: } \frac{V_X}{V_{in}}(s) = \frac{\alpha s^2}{s^2 + \frac{\omega_n}{Q}s + \omega_n^2} \cdot \frac{-1}{R_1 C_1 s}$$

$$\text{Low-pass: } \frac{V_Y}{V_{in}}(s) = \frac{\alpha s^2}{s^2 + \frac{\omega_n}{Q}s + \omega_n^2} \cdot \frac{1}{R_1 R_2 C_1 C_2 s^2}$$

# Sensitivity in KHN Biquads

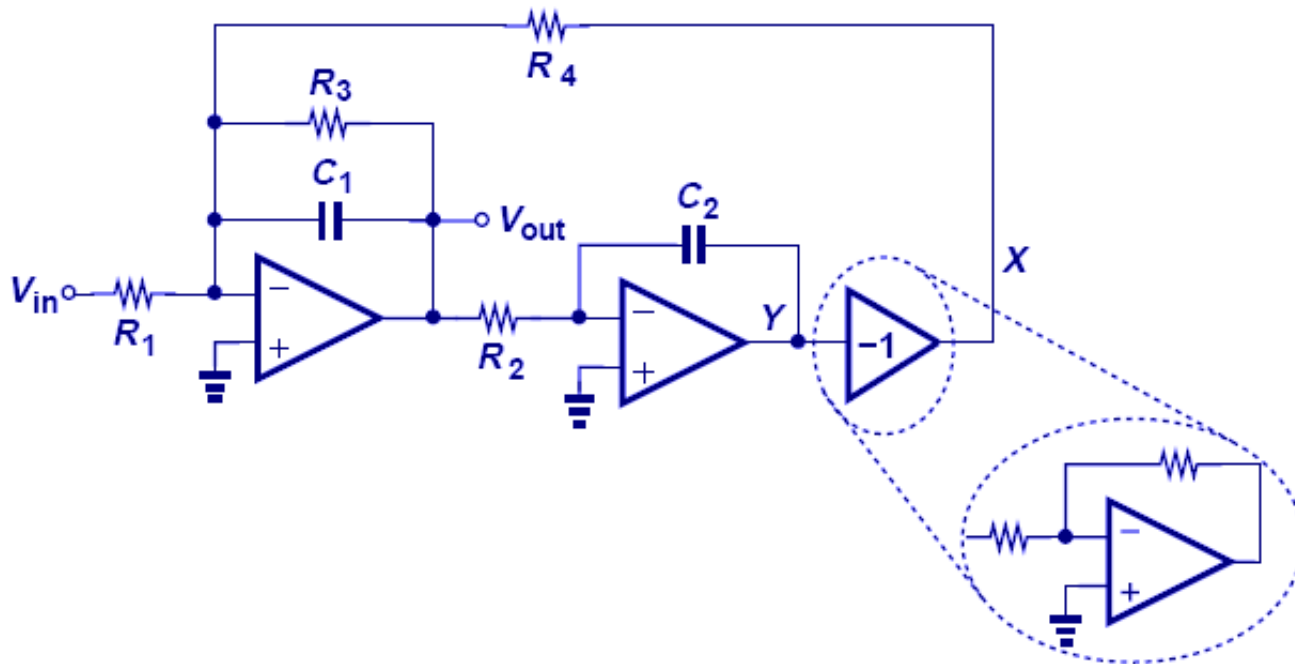


$$\left| S_{R_1, R_2, C_1, C_2, R_4, R_5, R_3, R_6}^{\omega_n} \right| = 0.5$$

$$\left| S_{R_1, R_2, C_1, C_2}^Q \right| = 0.5, \quad \left| S_{R_4, R_5}^Q \right| = \frac{R_5}{R_4 + R_5} < 1,$$

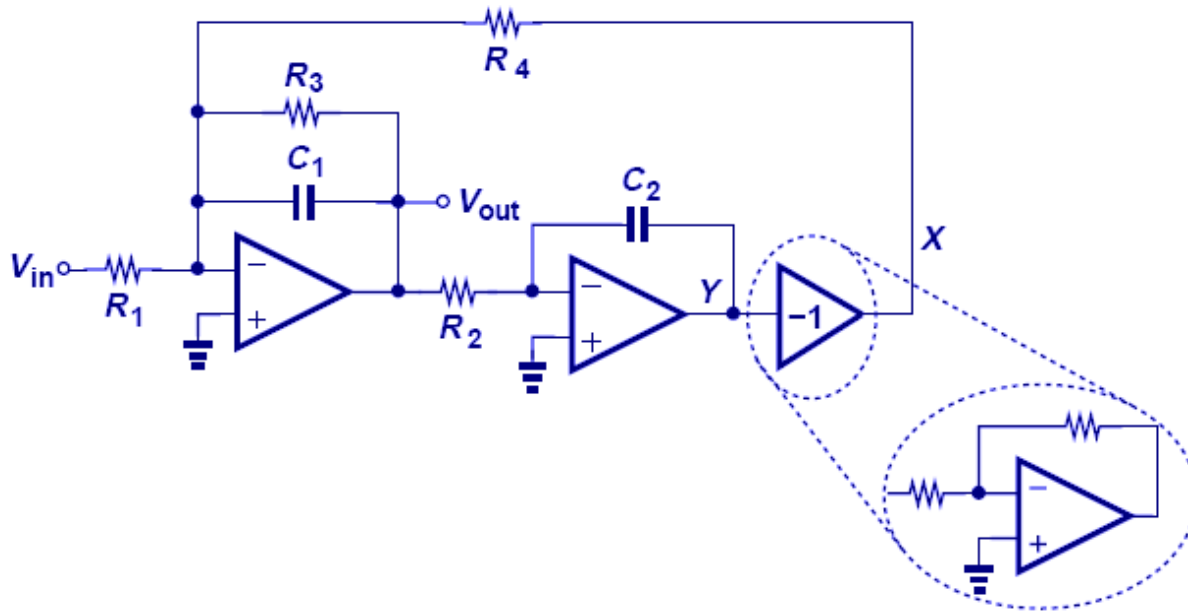
$$\left| S_{R_3, R_6}^Q \right| = \frac{Q}{2} \frac{|R_3 - R_6|}{1 + \frac{R_5}{R_4}} \sqrt{\frac{R_2 C_2}{R_3 R_6 R_1 C_1}}$$

# Tow-Thomas Biquad



$$\left( \frac{V_{out}}{R_2 C_2 s} \cdot \frac{1}{R_4} + \frac{V_{in}}{R_1} \right) \left( R_3 \parallel \frac{1}{s C_1} \right) = -V_{out}$$

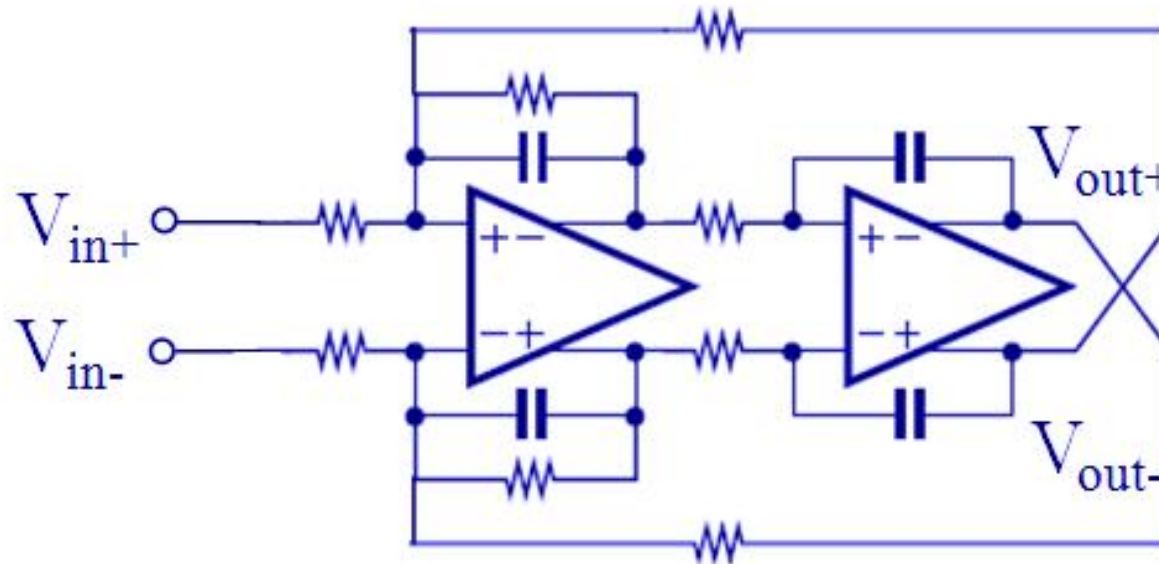
# Tow-Thomas Biquad



$$\text{Band-pass: } \frac{V_{out}}{V_{in}} = -\frac{R_2 R_3 R_4}{R_1} \cdot \frac{C_2 s}{R_2 R_3 R_4 C_1 C_2 s^2 + R_2 R_4 C_2 s + R_3}$$

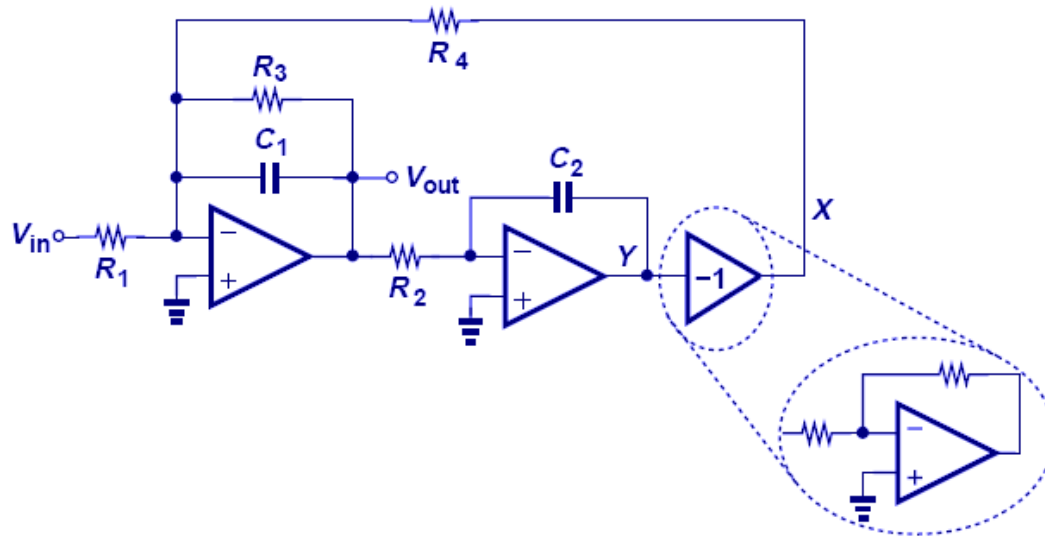
$$\text{Low-pass: } \frac{V_Y}{V_{in}} = \frac{R_3 R_4}{R_1} \cdot \frac{1}{R_2 R_3 R_4 C_1 C_2 s^2 + R_2 R_4 C_2 s + R_3}$$

# Differential Tow-Thomas Biquads



- An important advantage of this topology over the KHN biquad is accrued in integrated circuit design, where differential integrators obviate the need for the inverting stage in the loop.

## Example 14.20: Tow-Thomas Biquad



Note that  $\omega_n$  and  $Q$  of the Tow-Thomas filter can be adjusted (tuned) independently.

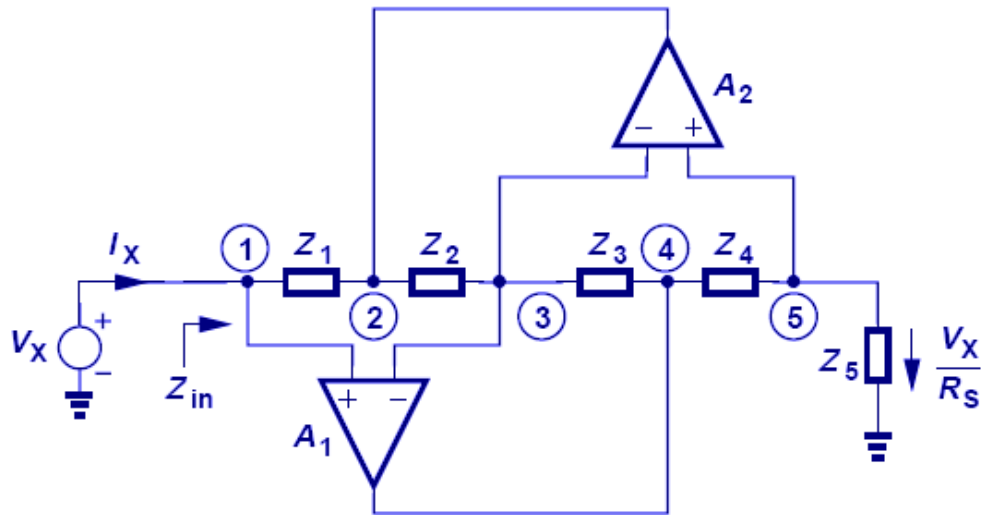
$$\omega_n = \frac{1}{\sqrt{R_2 R_4 C_1 C_2}}$$

**Adjusted by  $R_2$  or  $R_4$**

$$Q^{-1} = \frac{1}{R_3} \sqrt{\frac{R_2 R_4 C_2}{C_1}}$$

**Adjusted by  $R_3$**

# Antoniou General Impedance Converter



$$Z_{in} = \frac{Z_1 Z_3}{Z_2 Z_4} Z_5$$

$$V_1 = V_3 = V_5 = V_X$$

$$V_4 = \frac{V_X}{Z_5} Z_4 + V_X$$

$$I_{Z3} = \frac{V_4 - V_3}{Z_3}$$

$$= \frac{V_X}{Z_5} \cdot \frac{Z_4}{Z_3}$$

$$V_2 = V_3 - Z_2 I_{Z3}$$

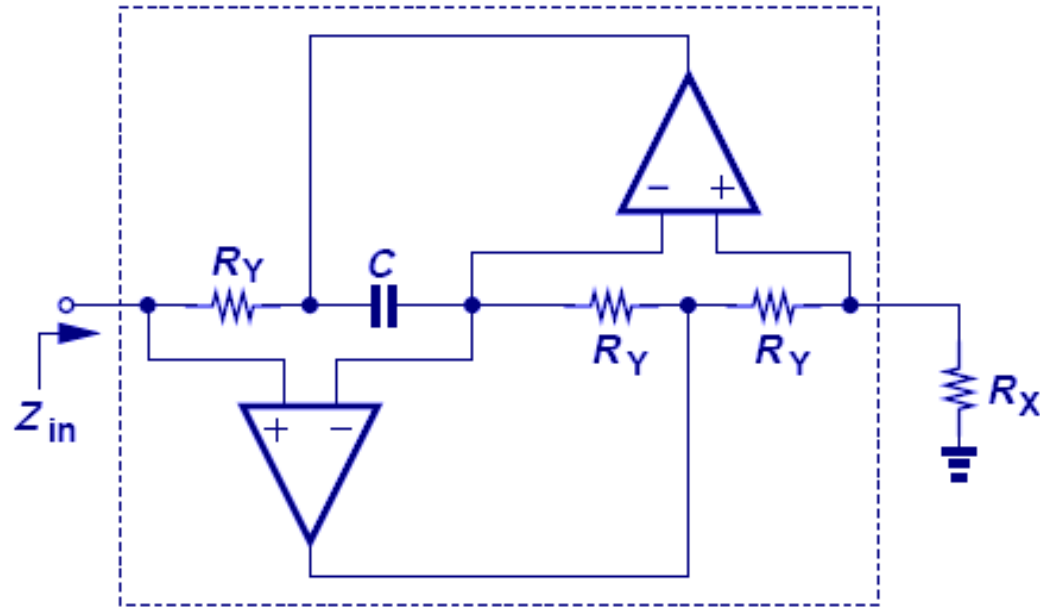
$$= V_X - Z_2 \cdot \frac{V_X}{Z_5} \cdot \frac{Z_4}{Z_3}$$

$$I_X = \frac{V_X - V_2}{Z_1}$$

$$= V_X \frac{Z_2 Z_4}{Z_1 Z_3 Z_5}$$

➤ It is possible to simulate the behavior of an inductor by using active circuits in feedback with properly chosen passive elements.

# Simulated Inductor

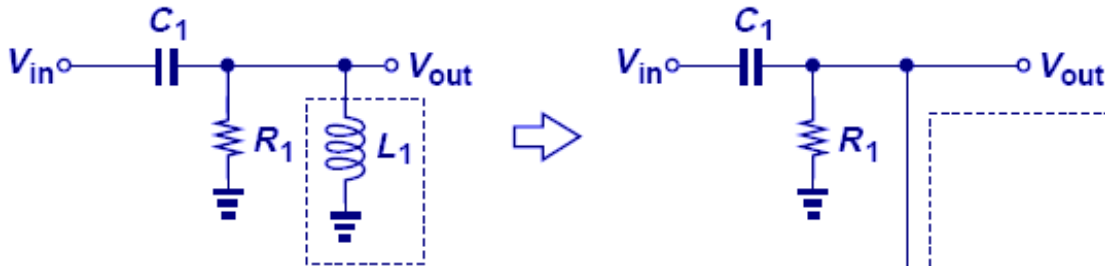


$$Z_{in} = R_X R_Y C s$$

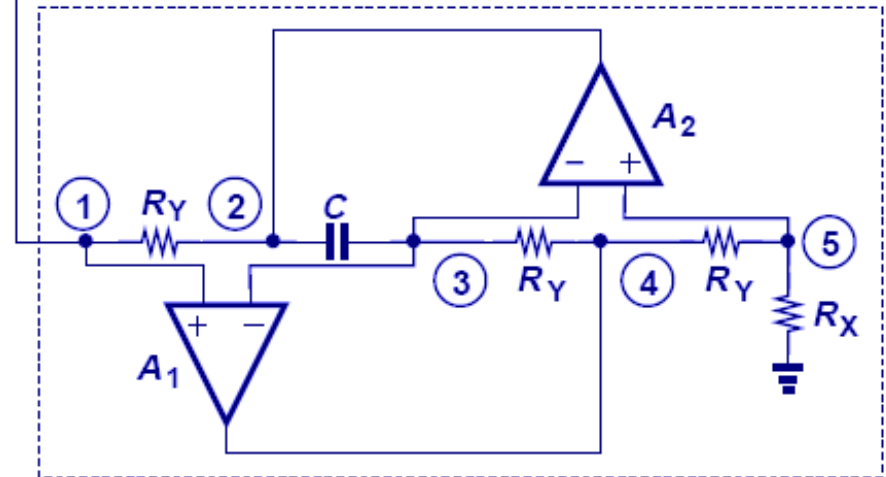
$$\text{Thus, } L_{eq} = R_X R_Y C$$

➤ By proper choices of  $Z_1$ - $Z_4$ ,  $Z_{in}$  has become an impedance that increases with frequency, simulating inductive effect.

# High-Pass Filter with SI

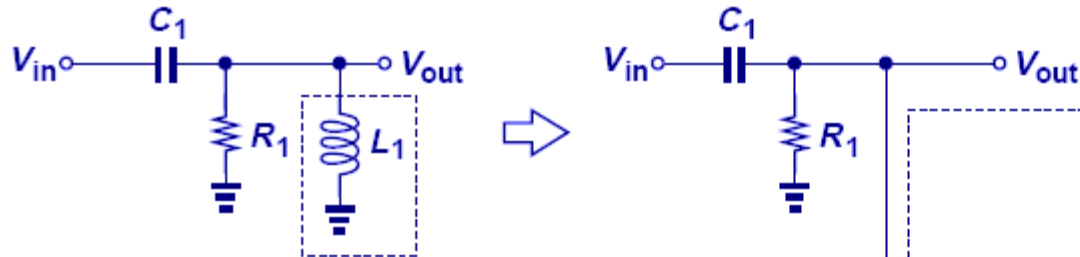


$$\frac{V_{out}}{V_{in}}(s) = \frac{L_1 s^2}{R_1 C_1 L_1 s^2 + L_1 s + R_1}$$

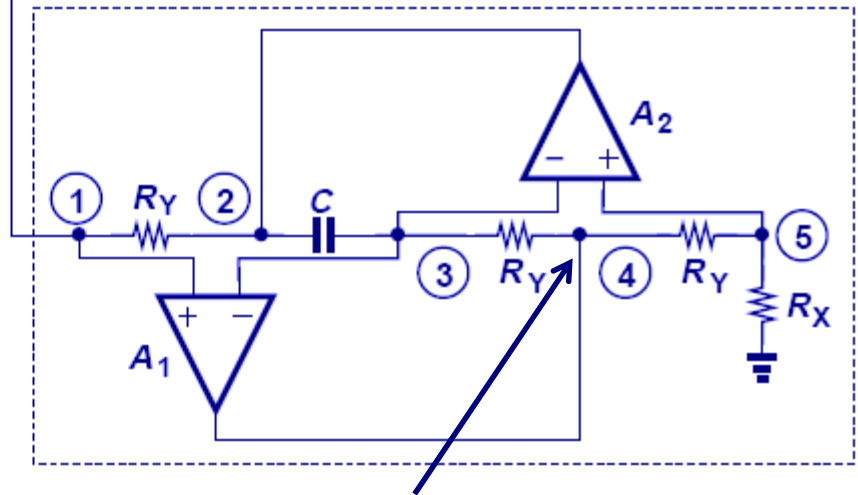


- With the inductor simulated at the output, the transfer function resembles a second-order high-pass filter.

## Example 14.22: High-Pass Filter with SI



Node 4 can also serve as an output.

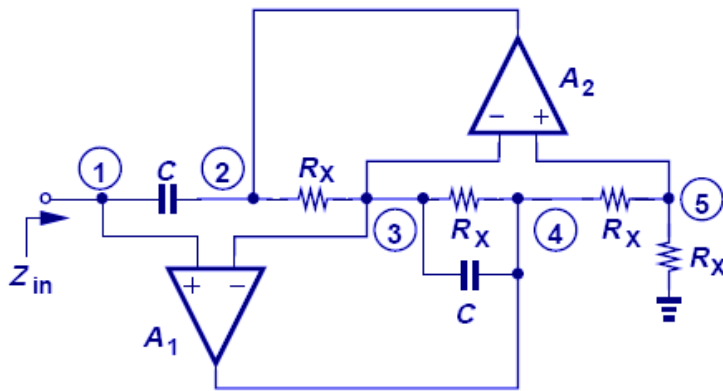


$$V_4 = V_{out} \left( 1 + \frac{R_Y}{R_X} \right)$$

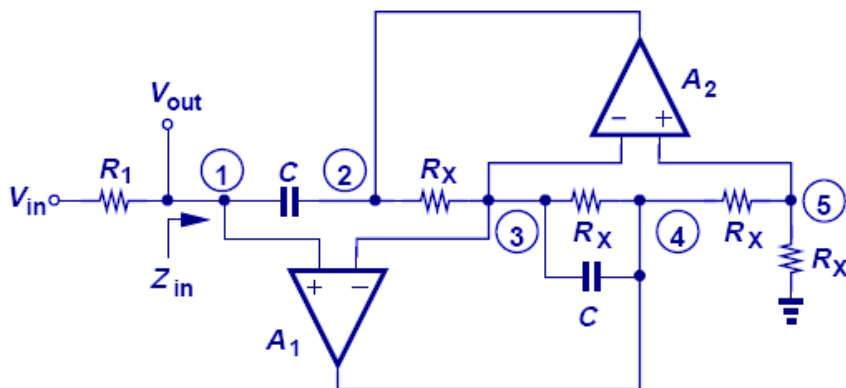
➤  $V_4$  is better than  $V_{out}$  since the output impedance is lower.

# Low-Pass Filter with Super Capacitor

- How to build a floating inductor to derive a low-pass filter?  
Not possible. So use a super capacitor.

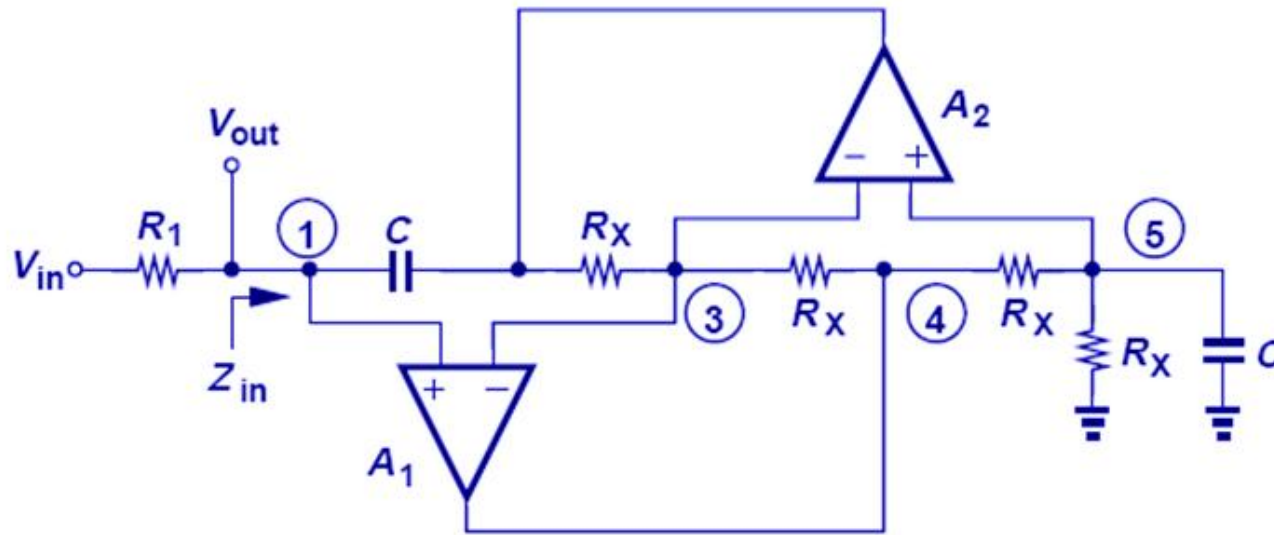


$$Z_{in} = \frac{1}{Cs(R_X Cs + 1)}$$



$$\begin{aligned} \frac{V_{out}}{V_{in}} &= \frac{Z_{in}}{Z_{in} + R_1} \\ &= \frac{1}{R_1 R_X C^2 s^2 + R_1 C s + 1} \end{aligned}$$

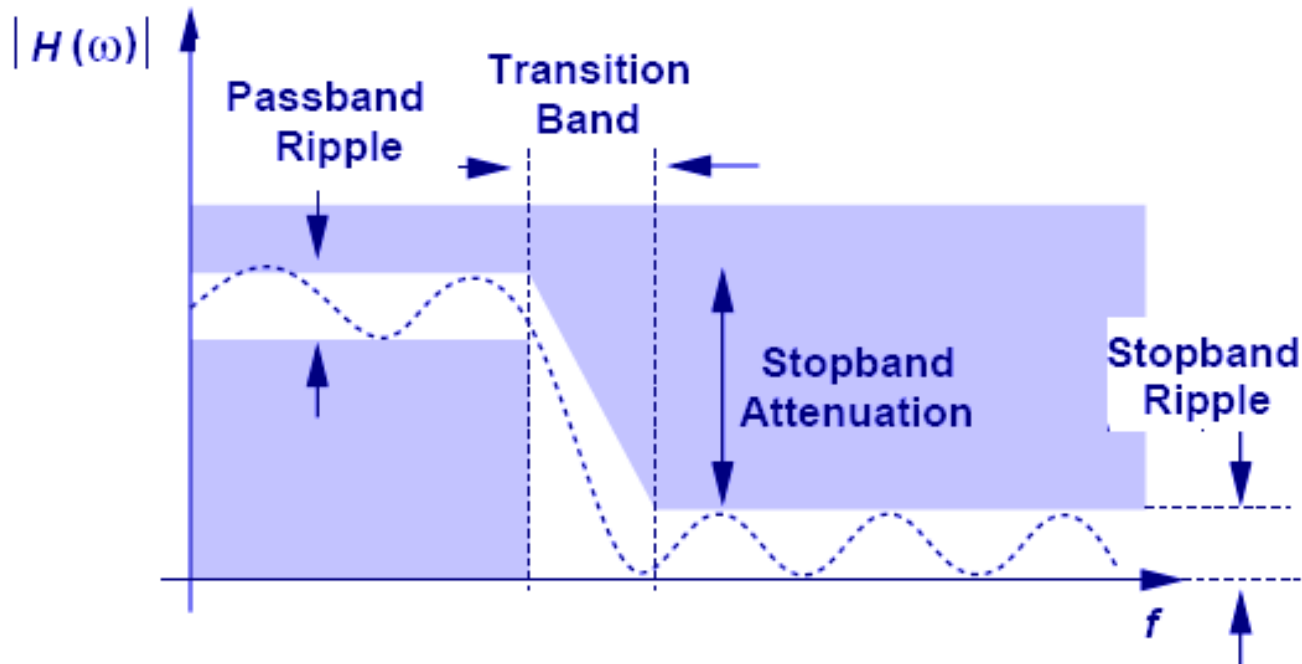
## Example 14.24: Poor Low-Pass Filter



$$V_4 = \left[ V_{out} \left( \frac{1}{R_X} + Cs \right) \right] R_X + V_{out} = V_{out} (2 + R_X Cs)$$

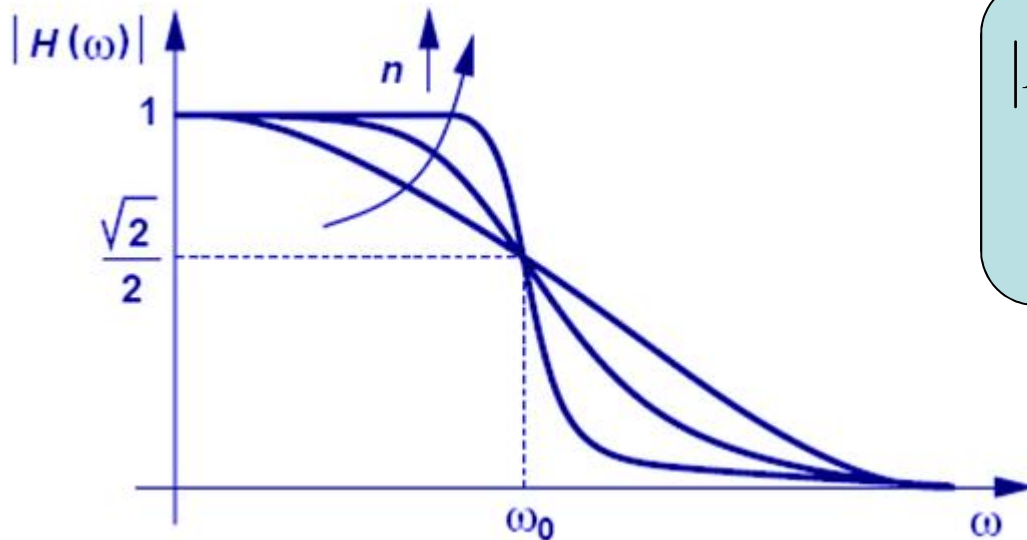
➤ **Node 4 is no longer a scaled version of the  $V_{out}$ . Therefore the output can only be sensed at node 1, suffering from a high impedance.**

# Frequency Response Template



- With all the specifications on pass/stop band ripples and transition band slope, one can create a filter template that will lend itself to transfer function approximation.

# Butterworth Response



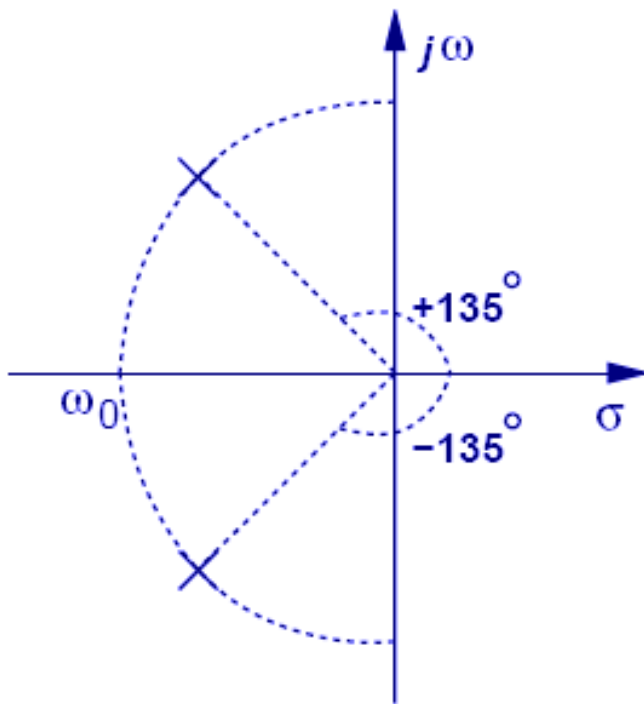
$$|H(j\omega)| = \frac{1}{\sqrt{1 + \left(\frac{\omega}{\omega_0}\right)^{2n}}}$$

$$\omega_{-3\text{dB}} = \omega_0, \text{ for all } n.$$

- The Butterworth response completely avoids ripples in the pass/stop bands at the expense of the transition band slope.

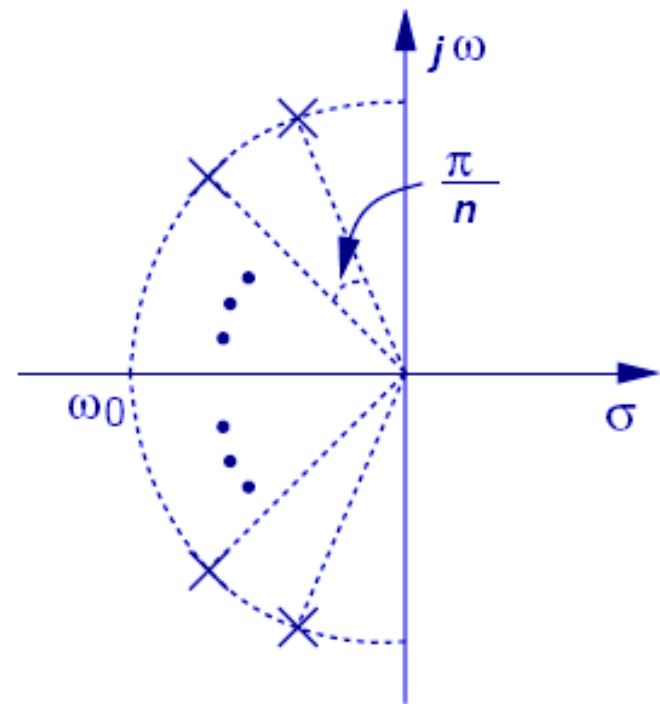
# Poles of the Butterworth Response

$$p_k = \omega_0 \exp \frac{j\pi}{2} \exp \left( j \frac{2k-1}{2n} \pi \right), k = 1, 2, \dots, n$$



(a)

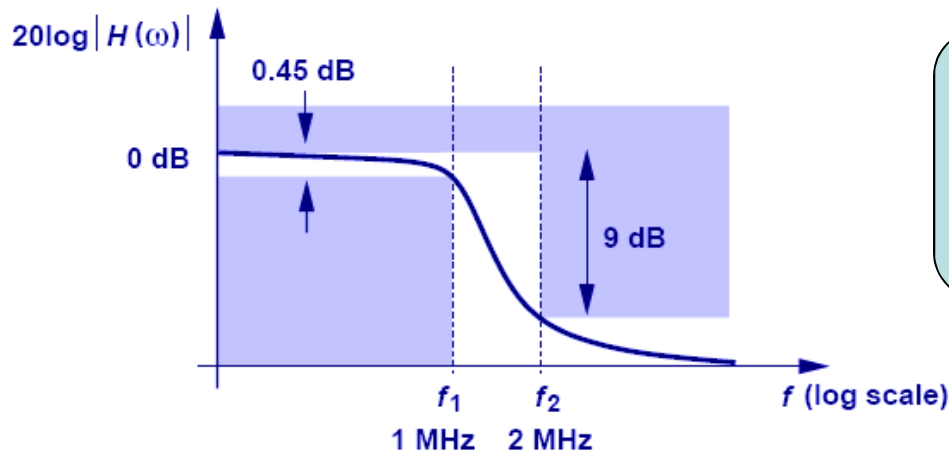
2<sup>nd</sup>-Order



(b)

nth-Order

## Example 14.24: Order of Butterworth Filter



Specification: passband flatness of 0.45 dB for  $f < f_1 = 1$  MHz, stopband attenuation of 9 dB at  $f_2 = 2$  MHz.

$$|H(f_1 = 1\text{MHz})| = 0.95$$

$$\frac{1}{1 + \left(\frac{2\pi f_1}{\omega_0}\right)^{2n}} = 0.95^2$$

$$|H(f_2 = 2\text{MHz})| = 0.355$$

$$\frac{1}{1 + \left(\frac{2\pi f_2}{\omega_0}\right)^{2n}} = 0.355^2$$

$$\left(\frac{f_2}{f_1}\right)^{2n} = 64.2$$



$$f_2 = 2f_1$$

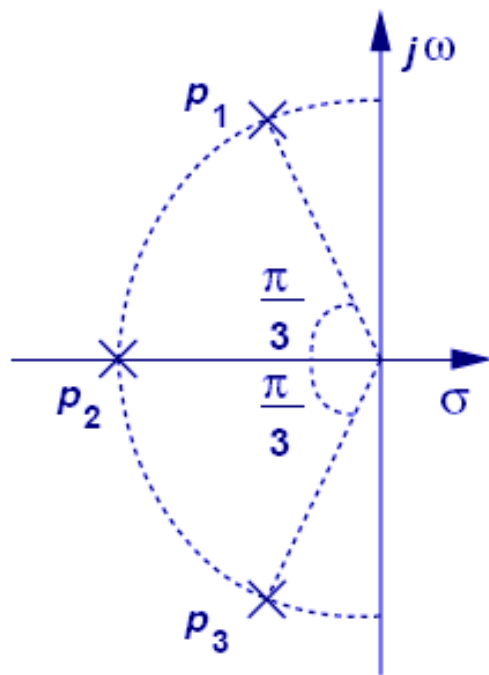


$$n = 3, \quad \omega_0 = 2\pi \times (1.45\text{MHz})$$

➤ **The minimum order of the Butterworth filter is three.**

## Example 14.25: Butterworth Response

Using a Sallen and Key topology, design a Butterworth filter for the response derived in Example 14.24.



$$p_1 = 2\pi * (1.45\text{MHz}) * \left( \cos \frac{2\pi}{3} + j \sin \frac{2\pi}{3} \right)$$

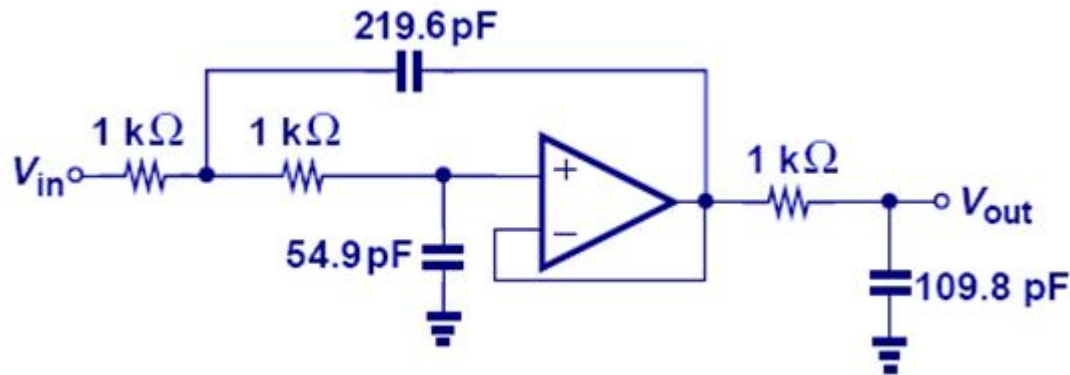
$$p_3 = 2\pi * (1.45\text{MHz}) * \left( \cos \frac{2\pi}{3} - j \sin \frac{2\pi}{3} \right)$$

$$p_2 = 2\pi * (1.45\text{MHz})$$

**2<sup>nd</sup>-order SK**

**RC section**

## Example 14.25: Butterworth Response (cont'd)



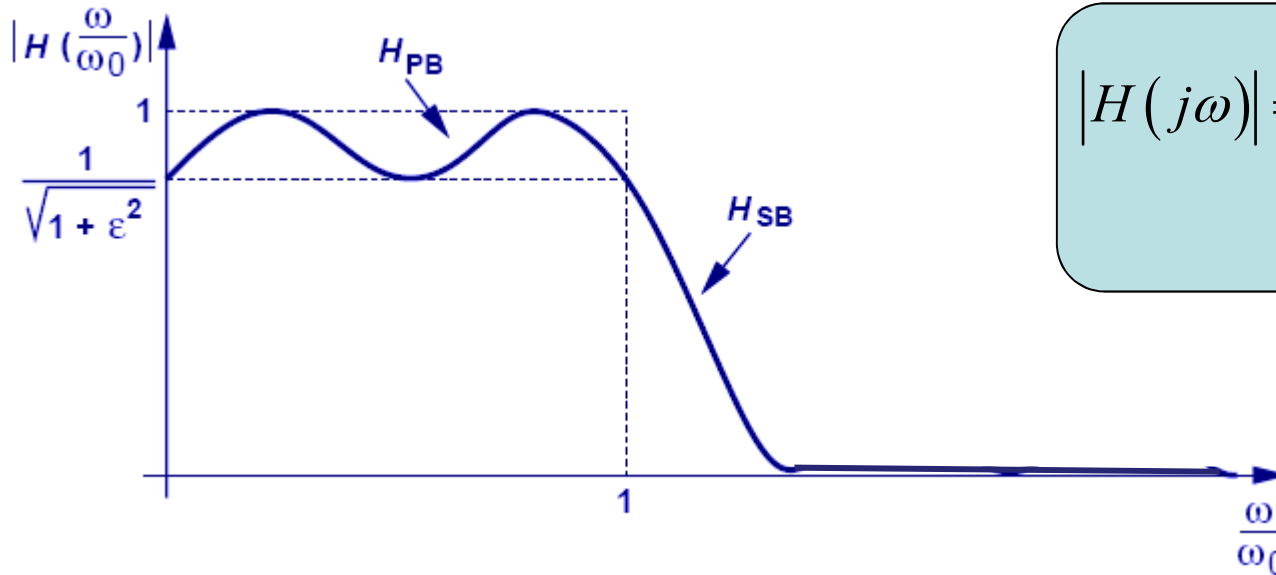
$$H_{SK}(s) = \frac{(-p_1)(-p_3)}{(s - p_1)(s - p_3)} = \frac{[2\pi \times (1.45\text{MHz})]^2}{s^2 - [4\pi \times (1.45\text{MHz}) \cos(2\pi / 3)]s + [2\pi \times (1.45\text{MHz})]^2}$$

$$\omega_n = 2\pi \times (1.45\text{MHz}) \text{ and } Q = 1 / 2 \cos \frac{2\pi}{3} = 1 \rightarrow$$

$$R_1 = R_2 = 1\text{k}\Omega, C_2 = 54.9\text{pF}, \text{ and } C_1 = 4C_2$$

$$\frac{1}{R_3 C_3} = 2\pi \times (1.45\text{MHz}) \rightarrow R_3 = 1\text{k}\Omega \text{ and } C_3 = 109.8\text{pF}$$

# Chebyshev Response

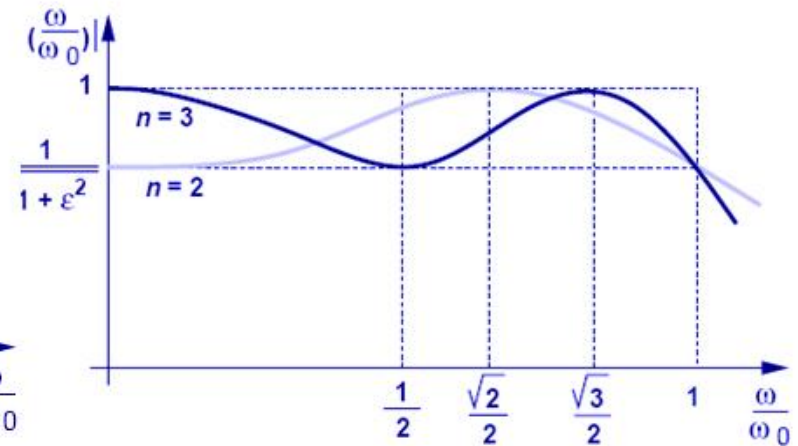
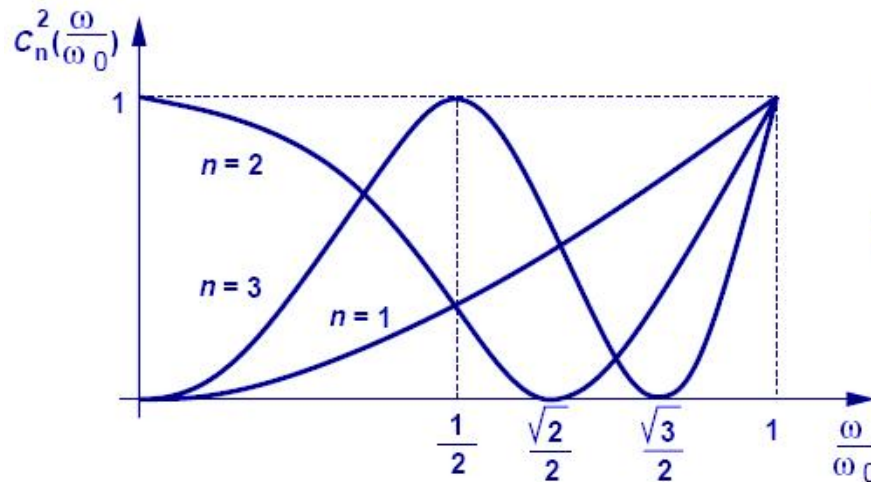


$$|H(j\omega)| = \frac{1}{\sqrt{1 + \epsilon^2 C_n^2\left(\frac{\omega}{\omega_0}\right)}}$$

Chebyshev Polynomial

- The Chebyshev response provides an “equiripple” pass/stop band response.

# Chebyshev Polynomial



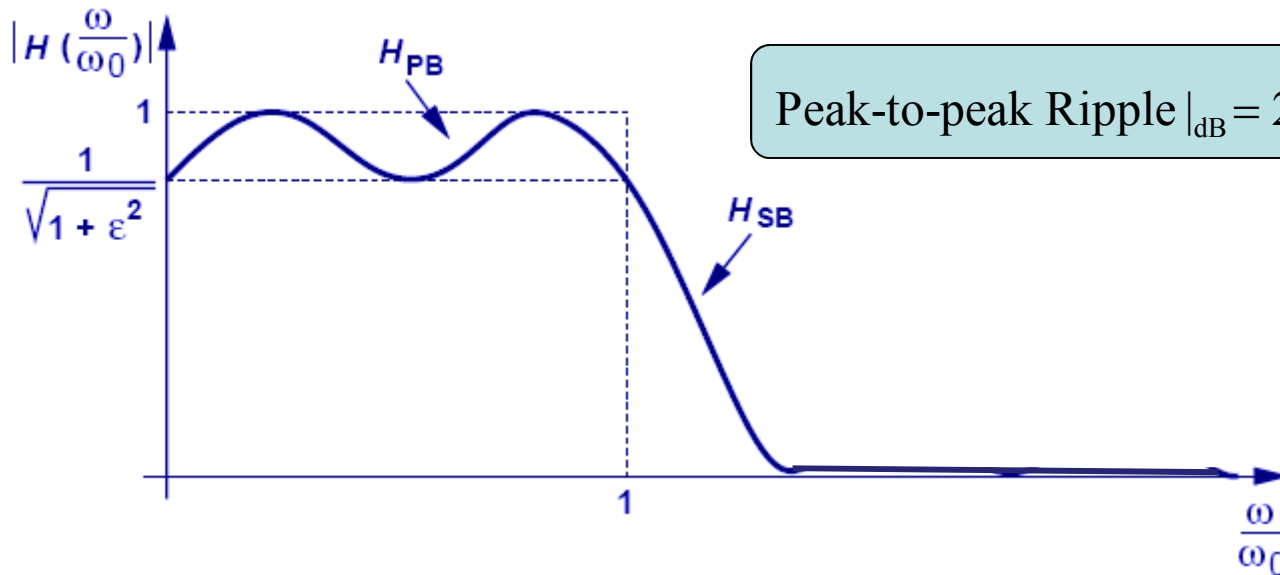
**Chebyshev polynomial for  
 $n=1,2,3$**

**Resulting transfer function for  
 $n=2,3$**

$$C_n\left(\frac{\omega}{\omega_0}\right) = \cos\left(n \cos^{-1} \frac{\omega}{\omega_0}\right), \quad \omega < \omega_0$$

$$= \cosh\left(n \cosh^{-1} \frac{\omega}{\omega_0}\right), \quad \omega > \omega_0$$

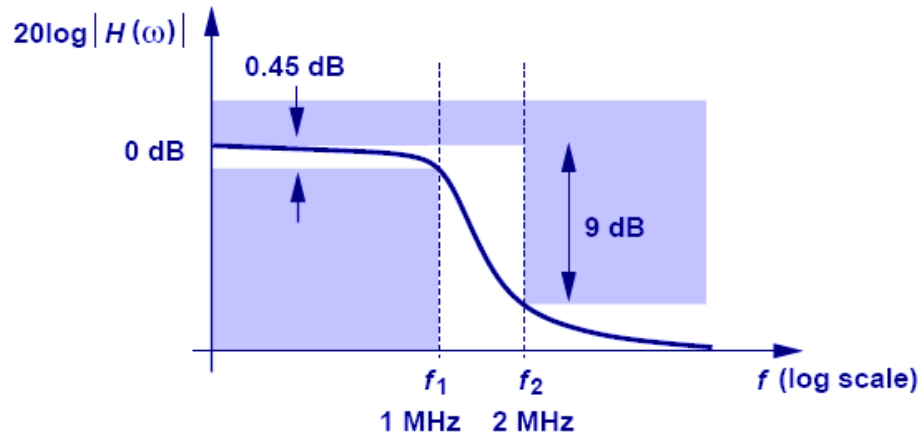
# Chebyshev Response



$$|H_{PB}(j\omega)| = \frac{1}{\sqrt{1 + \varepsilon^2 \cos^2 \left( n \cos^{-1} \frac{\omega}{\omega_0} \right)}}$$

$$|H_{SB}(j\omega)| = \frac{1}{\sqrt{1 + \varepsilon^2 \cosh^2 \left( n \cosh^{-1} \frac{\omega}{\omega_0} \right)}}$$

## Example 14.26: Chebyshev Response



Suppose the filter required in Example 14.24 is realized with third-order Chebyshev response. Determine the attenuation at 2MHz.

$$\frac{1}{\sqrt{1+\varepsilon^2}} = 0.95 \rightarrow \varepsilon = 0.329$$

$$\omega_0 = 2\pi (1\text{MHz})$$

$$|H(j\omega)| = \frac{1}{\sqrt{1+\varepsilon^2 \left[ 4\left(\frac{\omega}{\omega_0}\right)^3 - 3\frac{\omega}{\omega_0} \right]^2}}$$

$$|H(j2\pi(2\text{MHz}))| = 0.116 = -18.7\text{dB}$$

➤ **A third-order Chebyshev response provides an attenuation of -18.7 dB at 2MHz.**

## Example 14.27: Order of Chebyshev Filter

Specification:

Passband ripple: 1 dB

Bandwidth: 5 MHz

Attenuation at 10 MHz: 30 dB

What's the order?

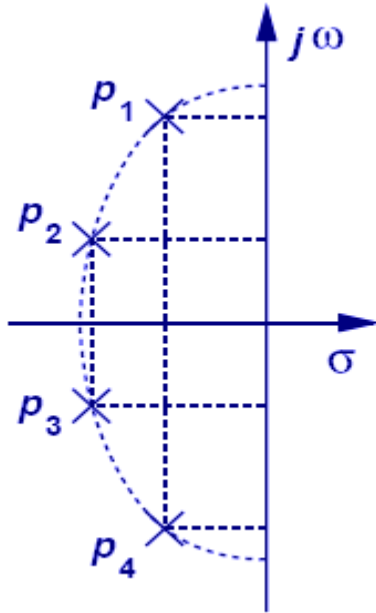
$$1 \text{ dB} = 20 \log \sqrt{1 + \varepsilon^2} \rightarrow \varepsilon = 0.509$$

Attenuation at  $\omega = 2\omega_0 = 10 \text{ MHz}$ : 30 dB

$$\frac{1}{\sqrt{1 + 0.509^2 \cosh^2(n \cosh^{-1} 2)}} = 0.0316$$

$$\cosh^2(1.317n) = 3862 \rightarrow n > 3.66 \rightarrow n = 4$$

## Example 14.28: Chebyshev Filter Design



Using two SK stages, design a filter that satisfies the requirements in Example 14.27.

$$p_k = -\omega_0 \sin \frac{(2k-1)\pi}{2n} \sinh \left( \frac{1}{n} \sinh^{-1} \frac{1}{\varepsilon} \right) + j\omega_0 \cos \frac{(2k-1)\pi}{2n} \cosh \left( \frac{1}{n} \sinh^{-1} \frac{1}{\varepsilon} \right)$$

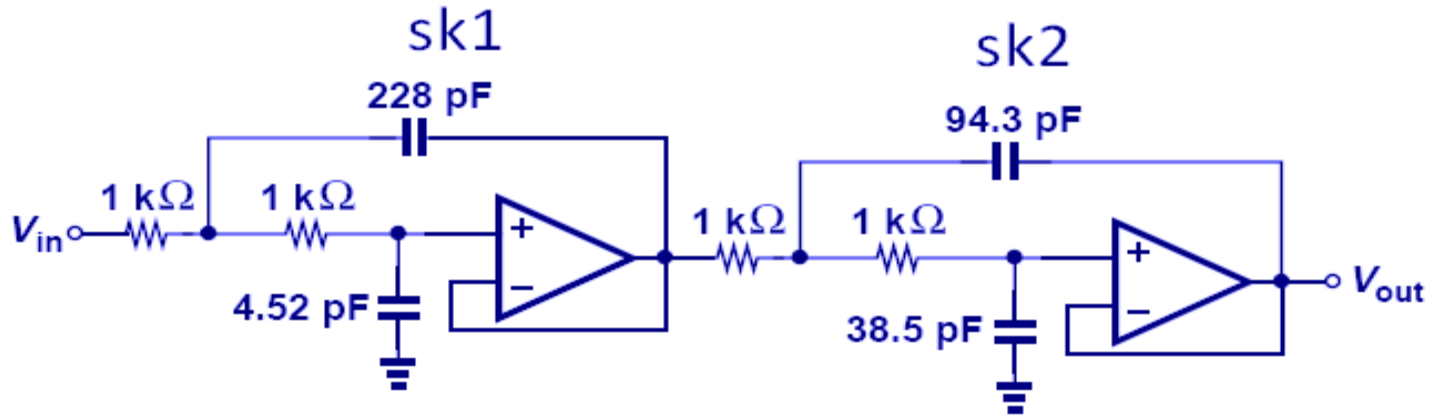
$$p_{1,4} = -0.140\omega_0 \pm 0.983j\omega_0$$

**SK1**

$$p_{2,3} = -0.337\omega_0 \pm 0.407j\omega_0$$

**SK2**

## Example 14.28: Chebyshev Filter Design (cont'd)



$$H_{SK1}(s) = \frac{(-p_1)(-p_4)}{(s - p_1)(s - p_4)}$$

$$= \frac{0.986\omega_0^2}{s^2 + 0.28\omega_0 s + 0.986\omega_0^2}$$

$$\omega_{n1} = 0.993\omega_0 = 2\pi \times (4.965\text{MHz})$$

$$Q_1 = 3.55$$

$$R_1 = R_2 = 1\text{ k}\Omega, C_1 = 50.4C_2$$

$$\frac{1}{\sqrt{50.4}R_1C_2} = 2\pi \times (4.965\text{MHz})$$

$$\rightarrow C_2 = 4.52\text{ pF}, C_1 = 227.8\text{ pF}$$

$$H_{SK2}(s) = \frac{(-p_2)(-p_3)}{(s - p_2)(s - p_3)}$$

$$= \frac{0.279\omega_0^2}{s^2 + 0.674\omega_0 s + 0.279\omega_0^2}$$

$$\omega_{n2} = 0.528\omega_0 = 2\pi \times (2.64\text{MHz})$$

$$Q_2 = 0.783.$$

$$R_1 = R_2 = 1\text{ k}\Omega, C_1 = 2.45C_2$$

$$\frac{1}{\sqrt{2.45}R_1C_2} = 2\pi \times (2.64\text{ MHz})$$

$$\rightarrow C_2 = 38.5\text{ pF}, C_1 = 94.3\text{ pF}$$