

Dynamic Binary Optimization

Contents

- Overview of Applying Optimization on VMs
- Dynamic Program Behavior
- Profiling
- Optimizing Translation Blocks

Classical Optimizations

```
addl    %edx, 4(%eax)
movl    4(%eax), %edx
```



Translation from IA-32 to PowerPC code.

```
addi    r16, r4, 4          ; add 4 to %eax
lwzlx   r17, r2, r16        ; load operand from memory
add     r7, r17, r7         ; perform add of %edx
addi    r16, r4, 4          ; add 4 to %eax
stwx    r7, r2, r16         ; store %edx value into memory
```



Common Subexpression Elimination (CSE)

```
addi    r16, r4, 4          ; add 4 to %eax
lwzlx   r17, r2, r16        ; load operand from memory
add     r7, r17, r7         ; perform add of %edx
stwx    r7, r2, r16         ; store %edx value into memory
```

Optimization Based on Profiling

Basic Block A

...
...
R3 ← ...
R7 ← ...
R1 ← R2 + R3
Br L1 if R3 == 0

Basic Block B

...
R6 ← R1 + R6
...
...

Basic Block C

L1: R1 ← 0
...
...

Basic Block A

...
...
R3 ← ...
R7 ← ...
Br L1 if R3 == 0

Basic Block B

...
R6 ← R1 + R6
...
...

Basic Block C

L1: R1 ← 0
...
...

Basic Block A

...
...
R3 ← ...
R7 ← ...
Br L1 if R3 == 0

Compensation code
R1 ← R2 + R3

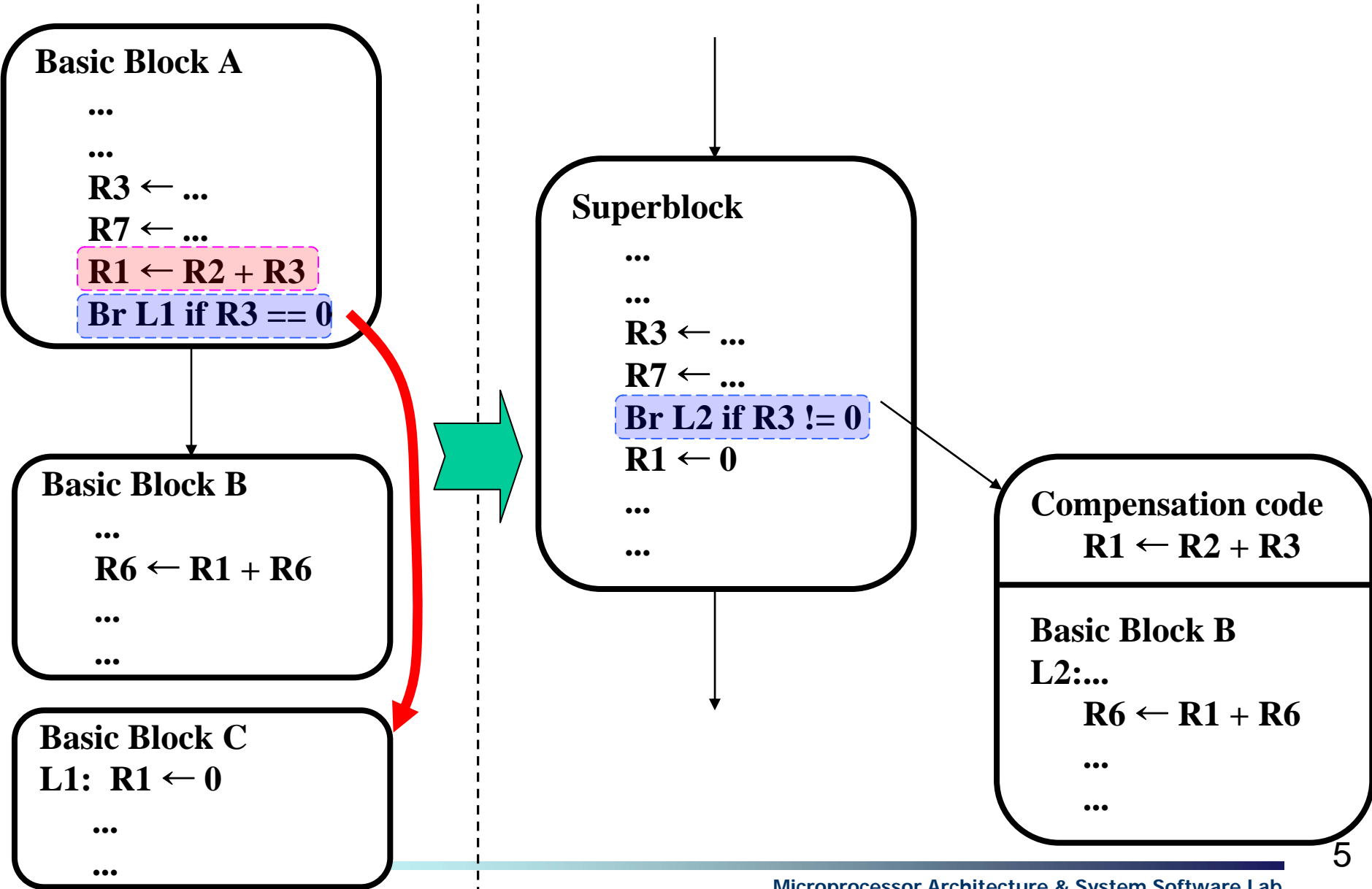
Basic Block B

...
R6 ← R1 + R6
...
...

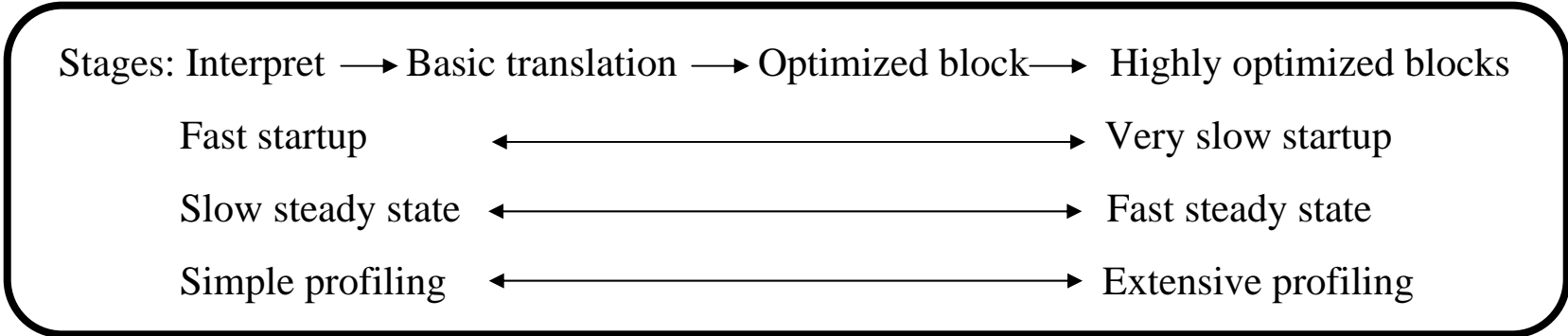
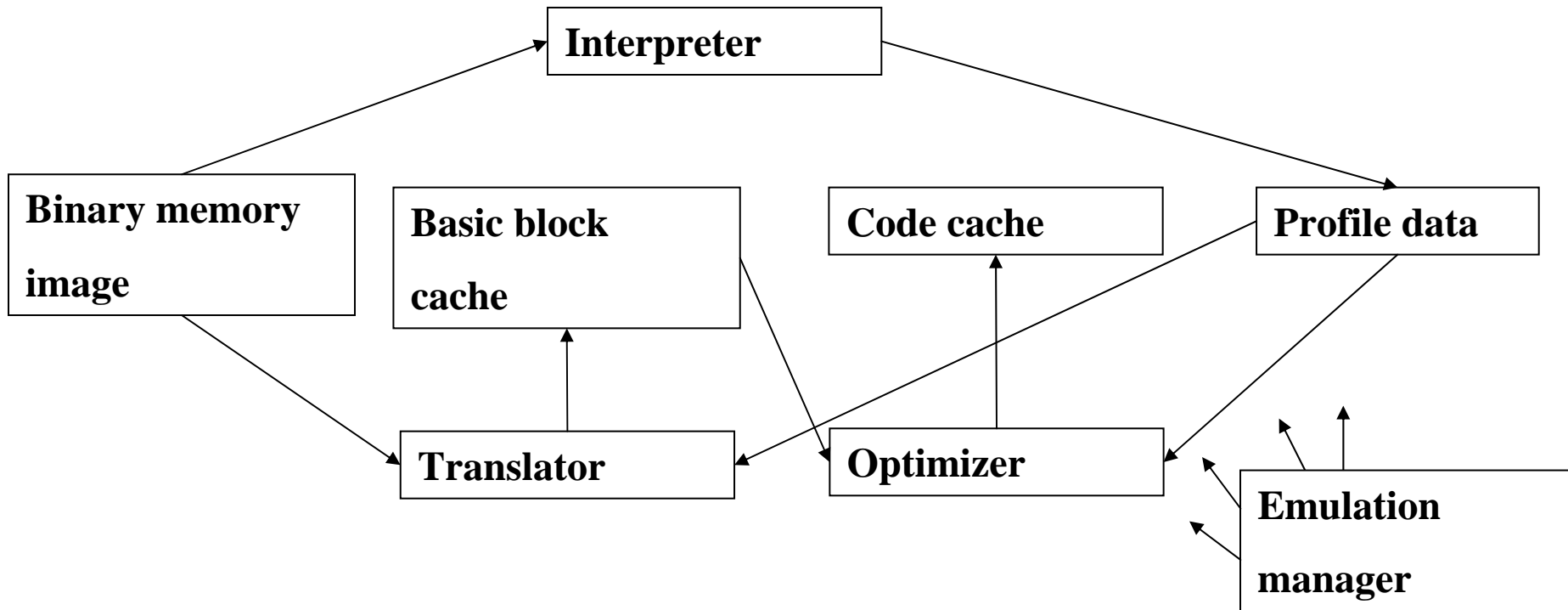
Basic Block C

L1: R1 ← 0
...
...

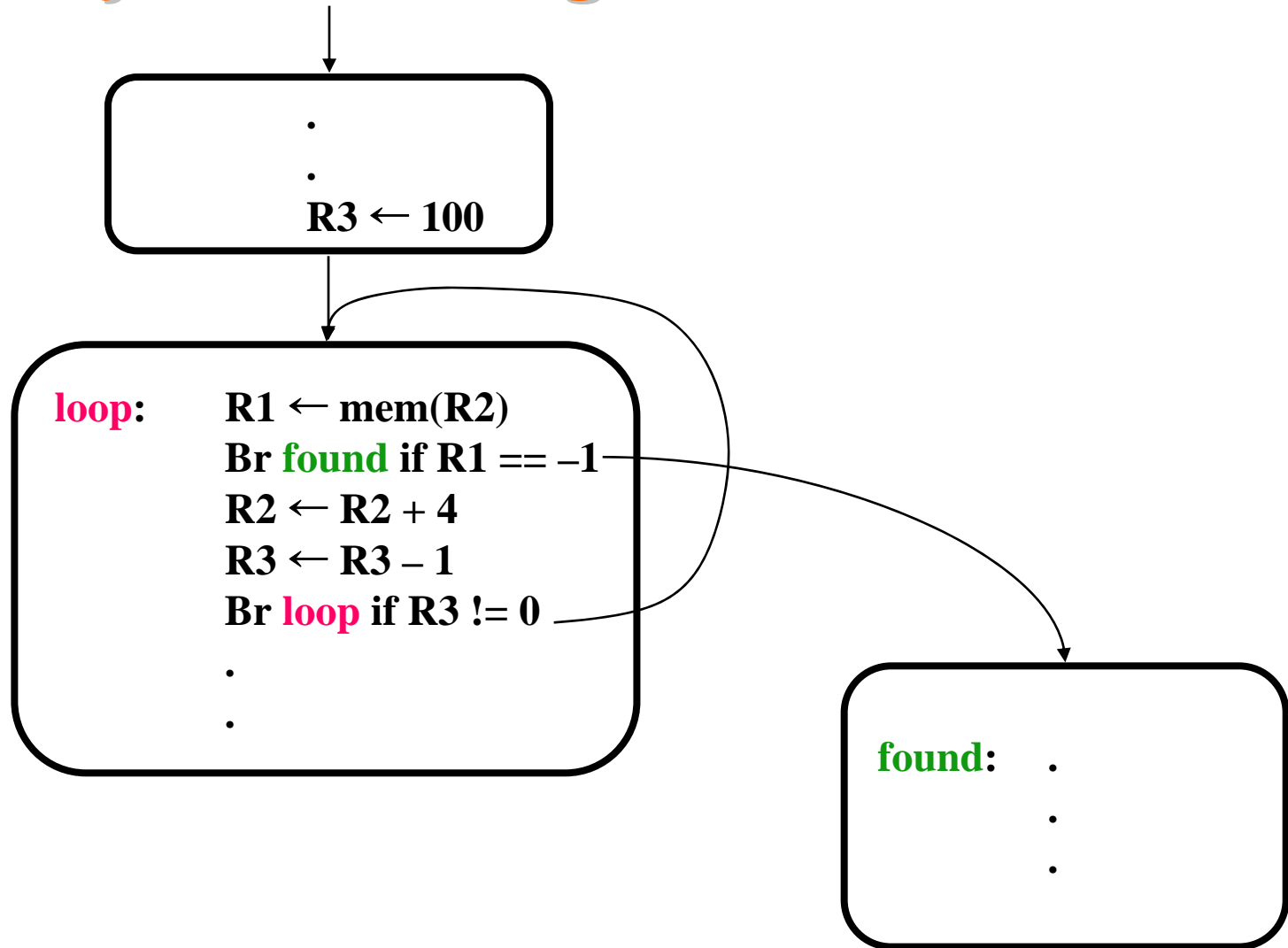
Optimization Based on Profiling



A staged optimization system



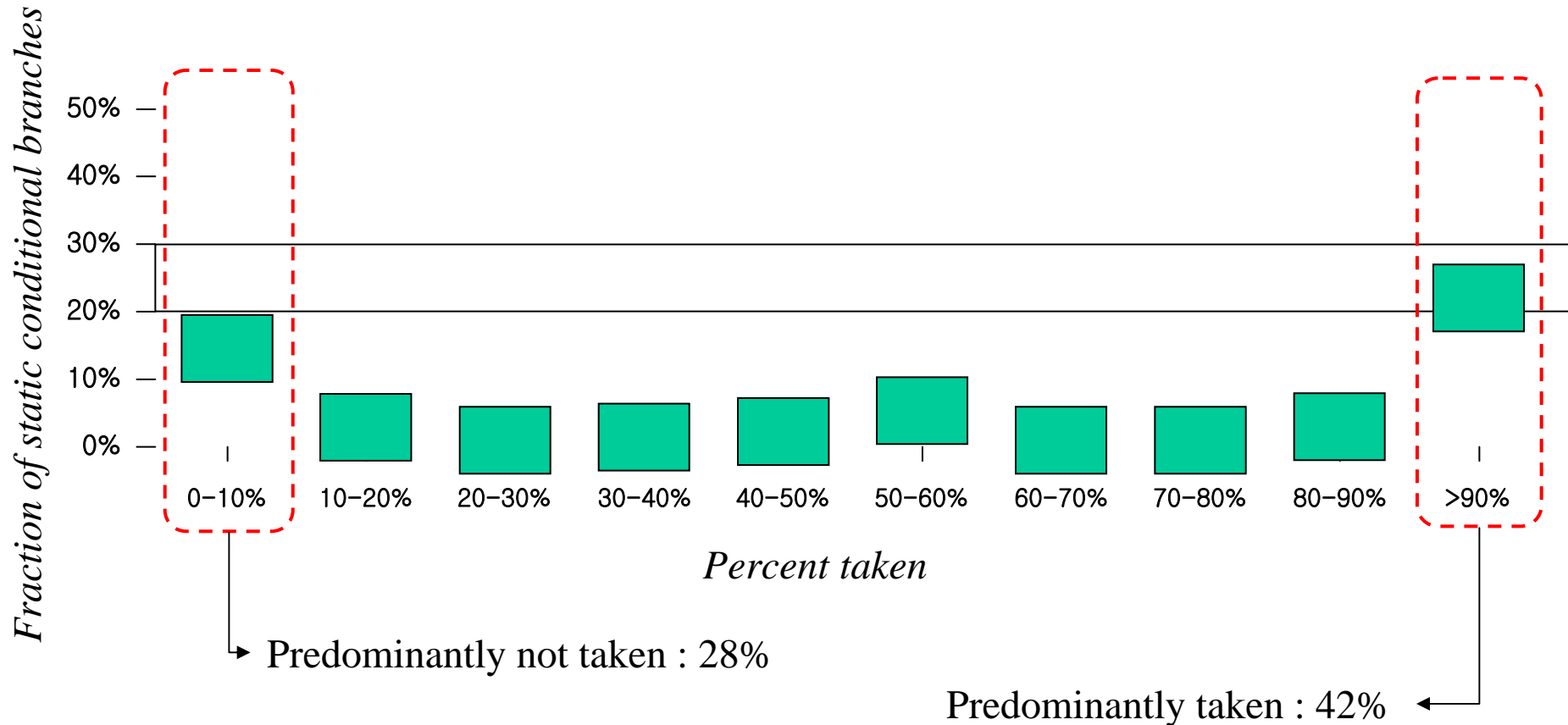
Dynamic Program Behavior



- Dynamic control flow is **highly predictable**

Dynamic Program Behavior

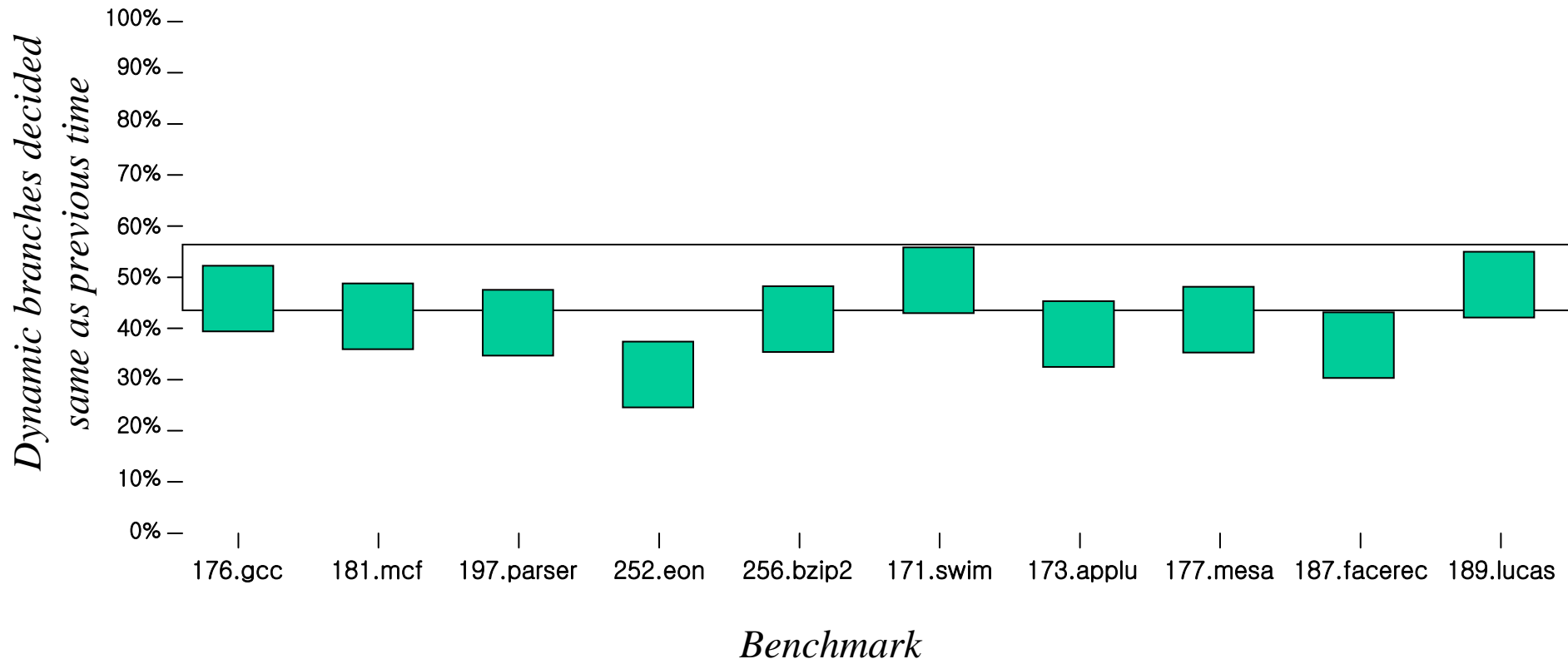
- Distribution of taken conditional branches



Back...

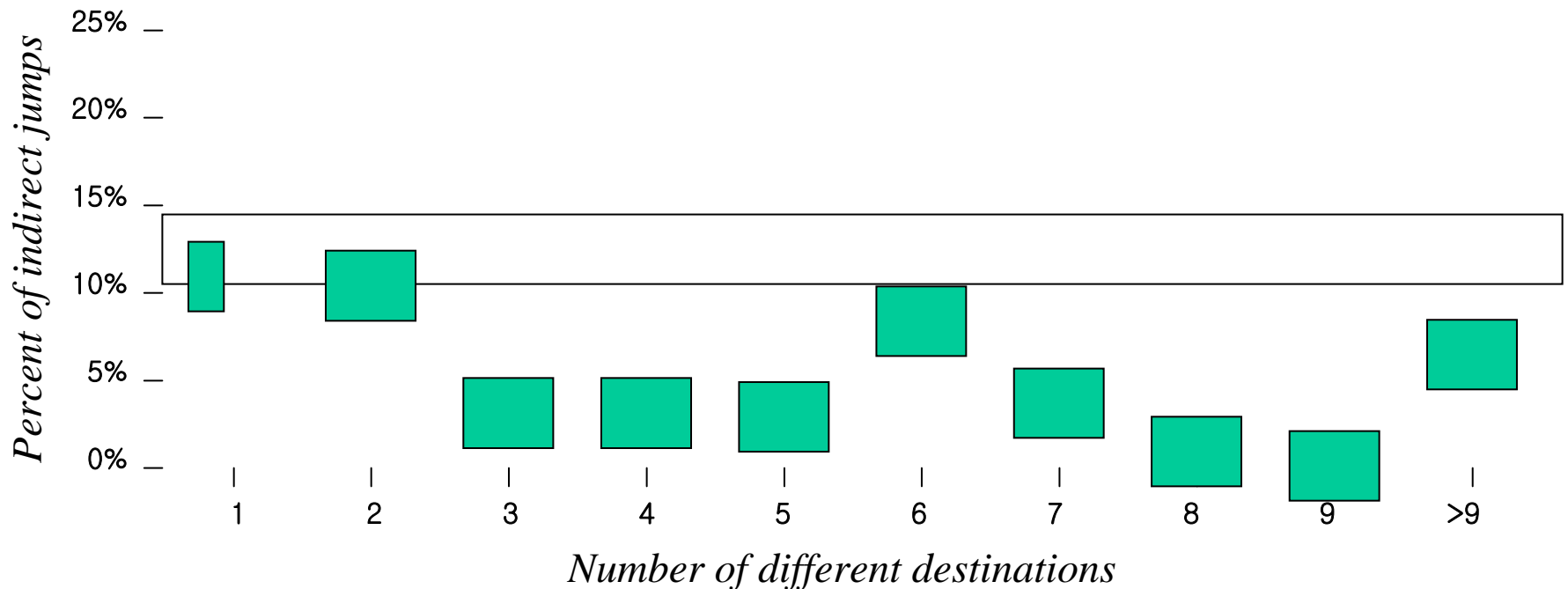
Dynamic Program Behavior

- Consistency of conditional branches
 - The high percentage consists of backward branches



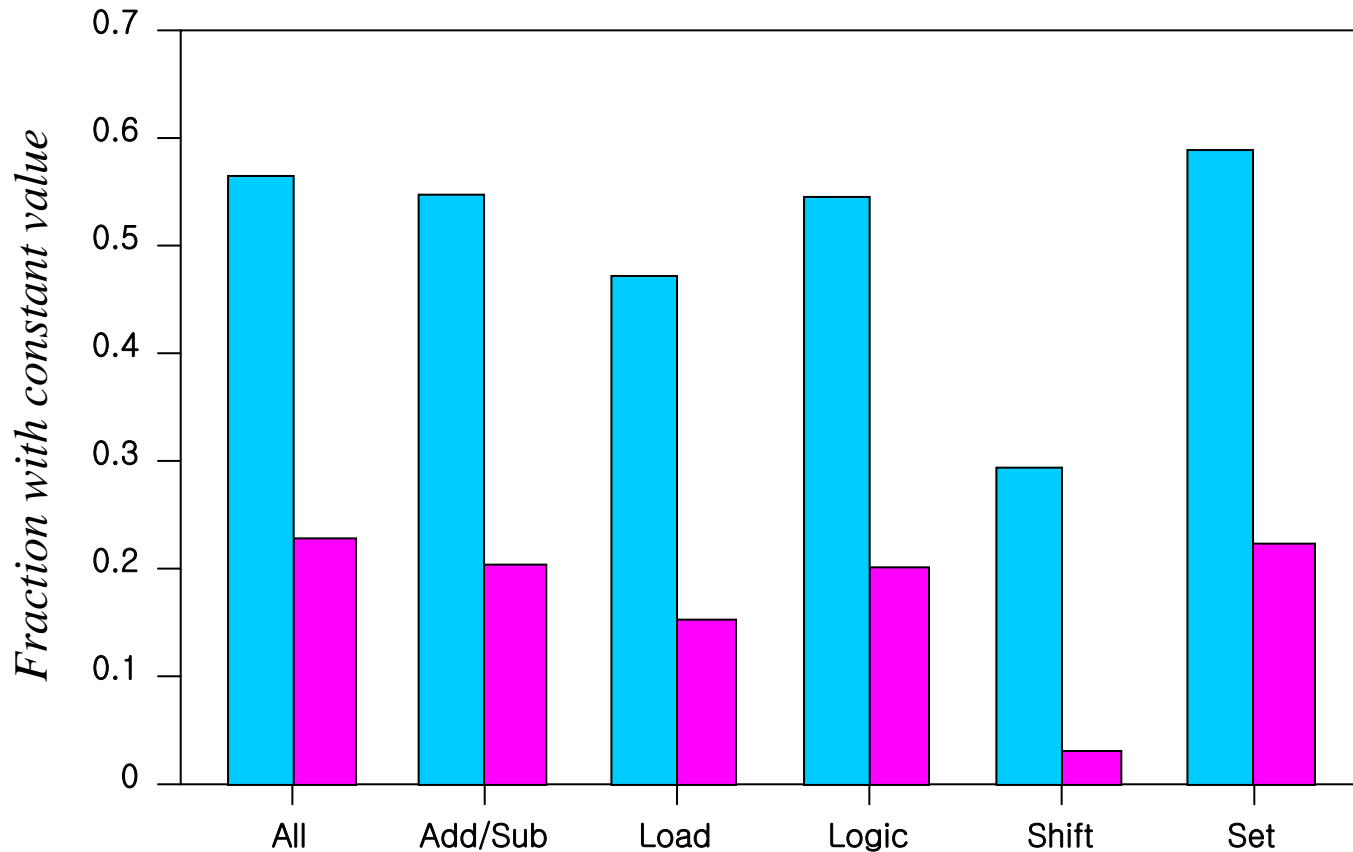
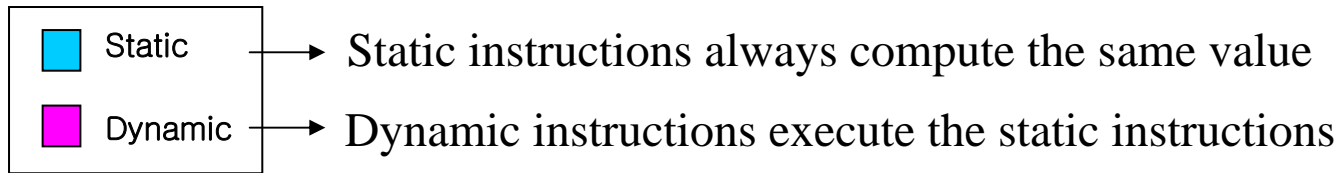
Dynamic Program Behavior

- The predictability of indirect jumps
 - Some jump destination addresses seldom change



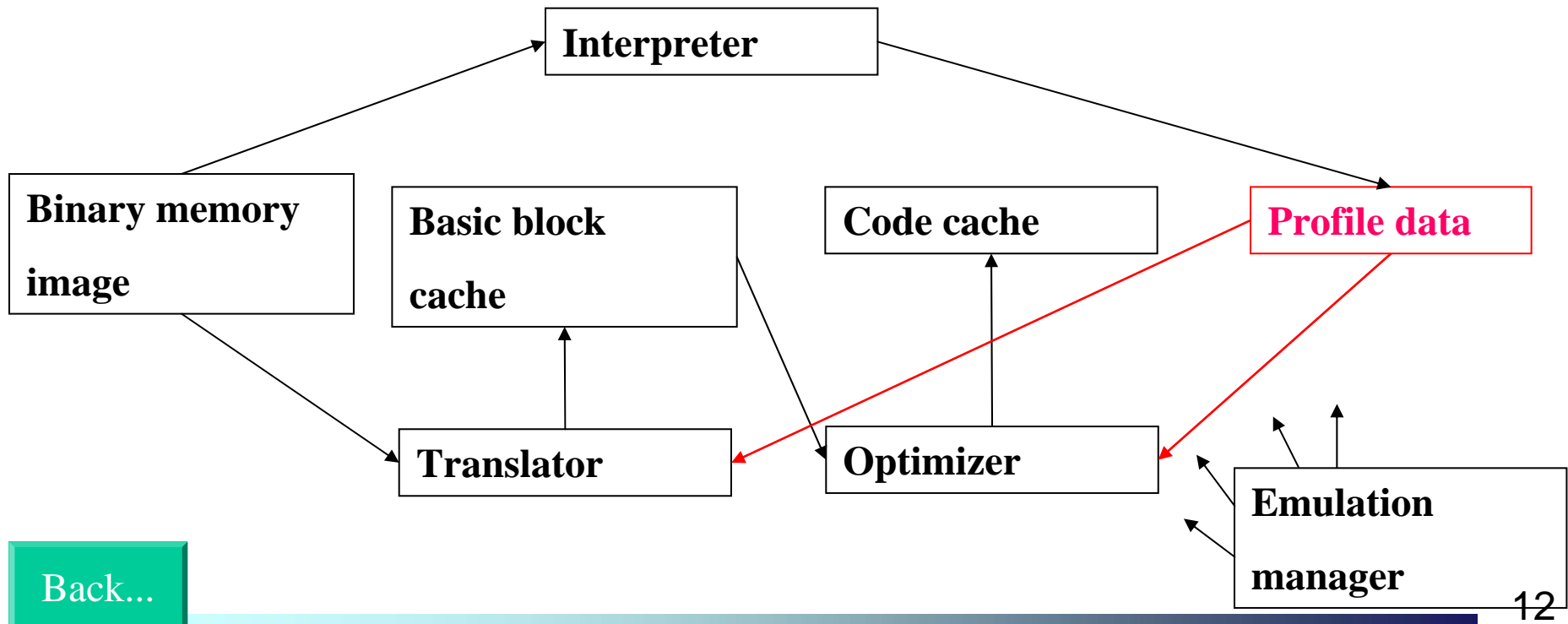
Dynamic Program Behavior

- The predictability of data value



Profiling

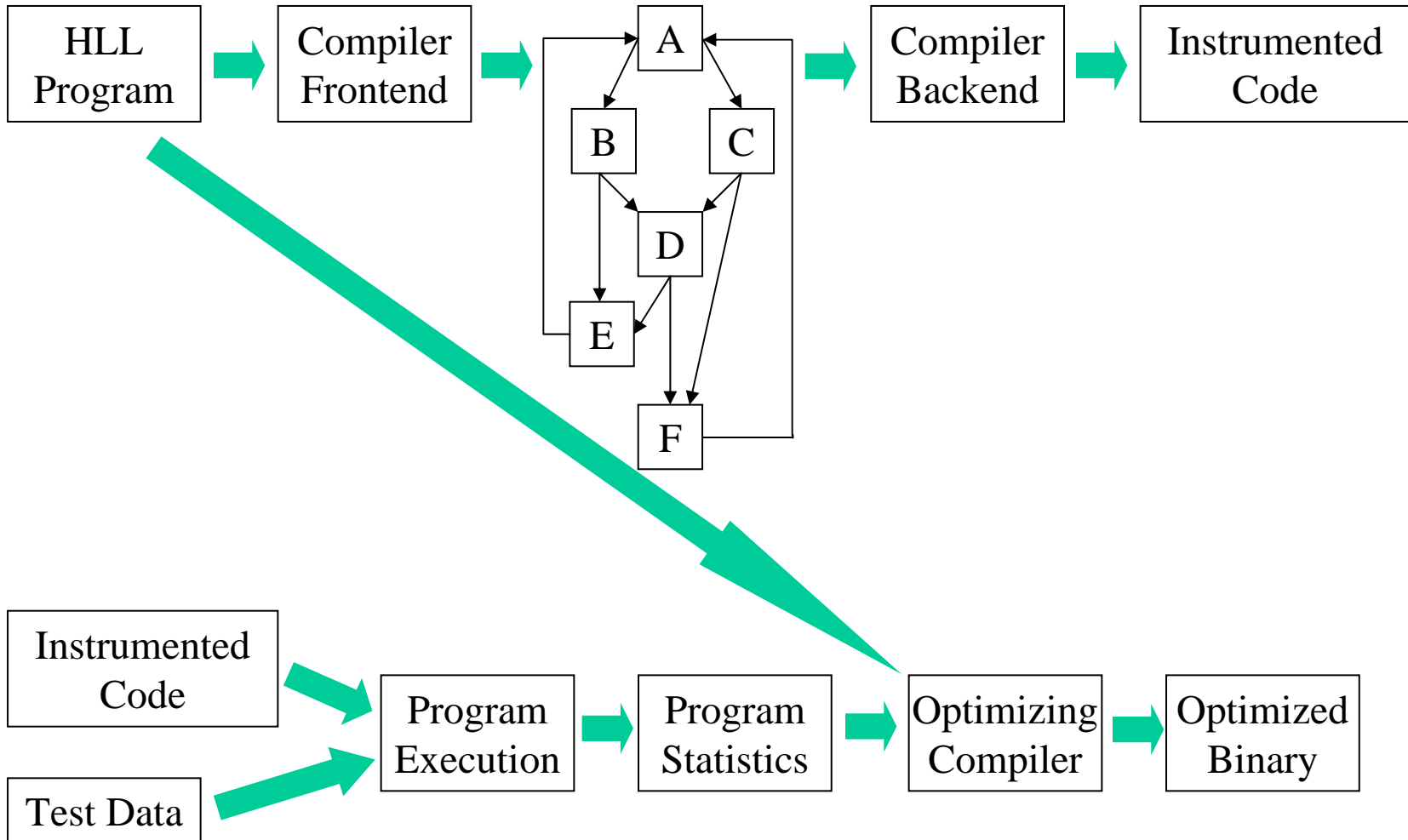
- The process of **collecting instruction and data statistics** for an executing program
- Optimization based on profiling work



Back...

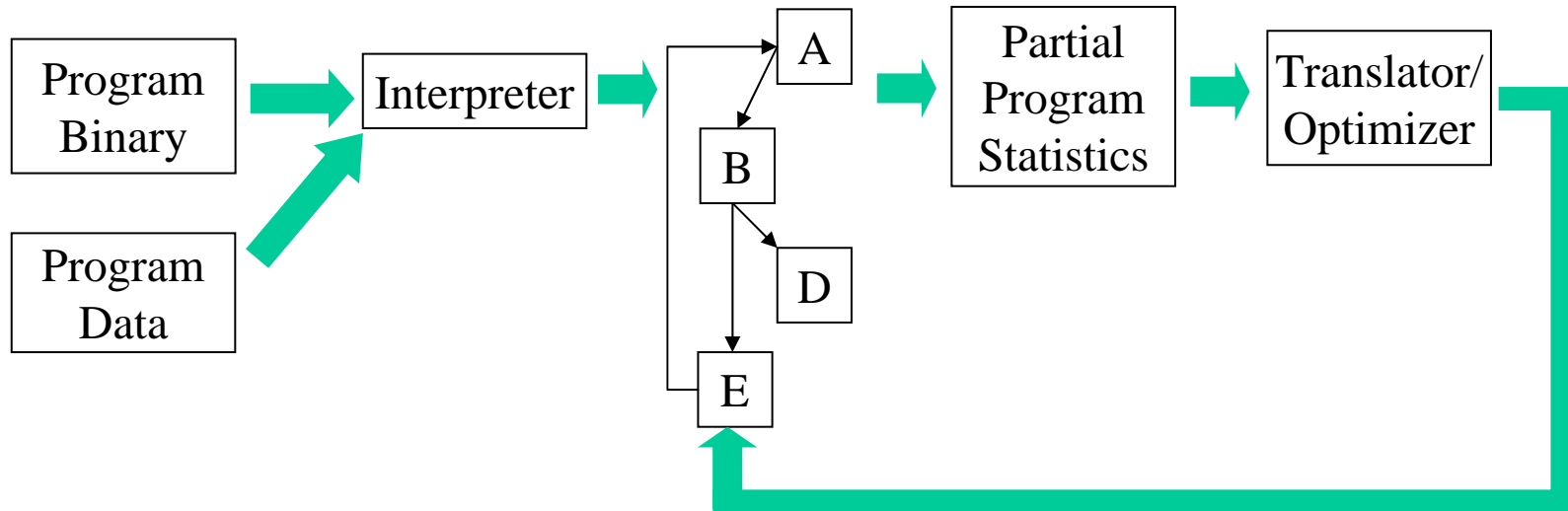
The Role of Profiling

- Traditional profiling



The Role of Profiling

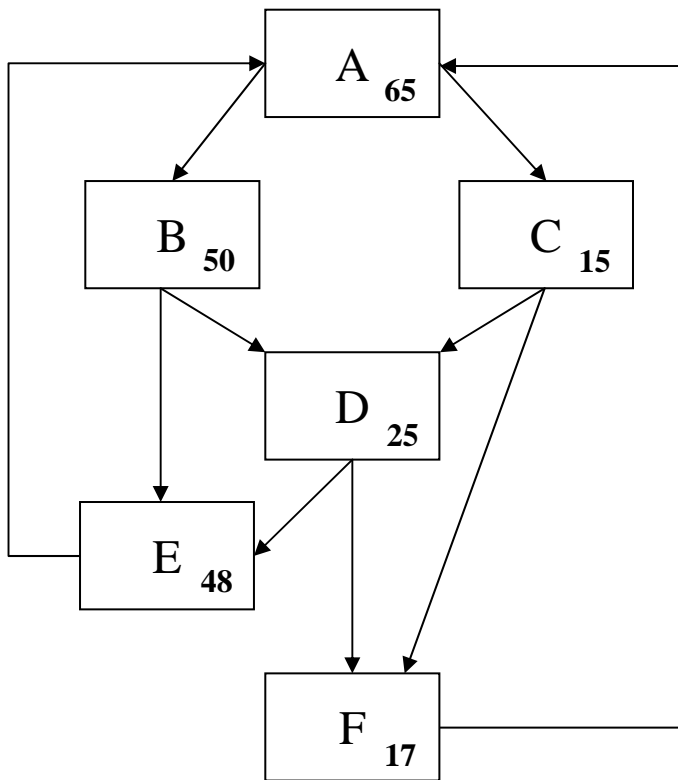
- On-the-fly profiling in a dynamic optimizing VM



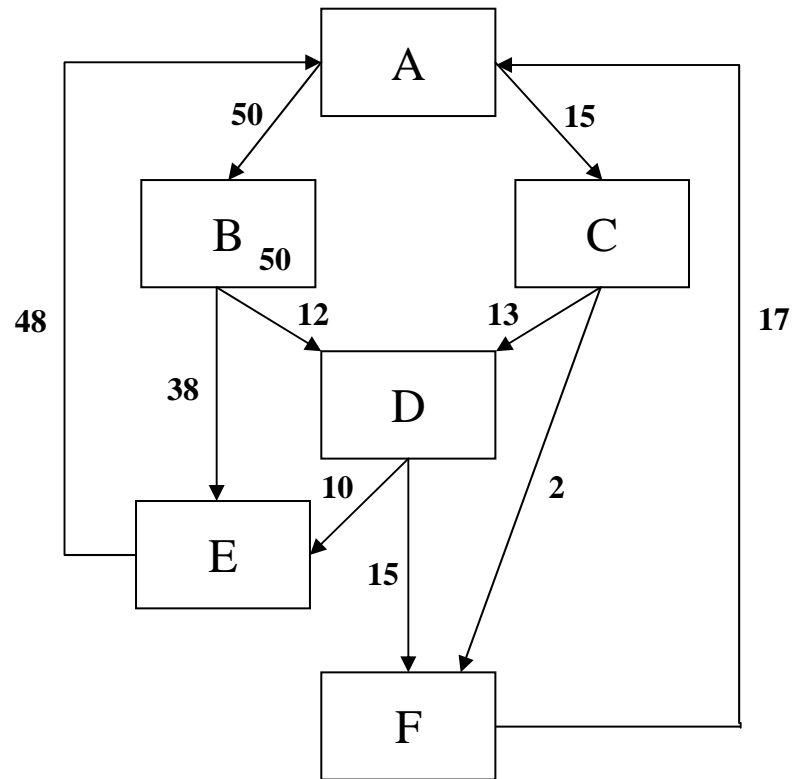
Types of Profiles

- Several types of profile data
 - How frequently code regions are being executed?
 - Can be used to decide the level of optimization
 - Often represented by **basic block profile**
 - Control flow statistics
 - May be used for rearranging basic blocks into superblocks, for example
 - Often represented by **edge profile**
 - Edge profile gives more information
 - Edge profile is more expensive, but there is an efficient algorithm [Ball & Larus 1994]
 - There is an efficient algorithm for a **path profile**

Types of Profiles



A basic block profile



A edge profile

Collecting Profiles

- Instrumentation-based profiling
 - Specific **program-related** events and counts all instances of the events being profiled
 - Software-based Vs hardware-based
 - Speed, Support, Flexibility?
- Sampling-based profiling
 - Program runs in its unmodified form, the program is interrupted and event is captured
- Instrumentation compared to sampling
 - Can collect profile data in a shorter time
 - Slow down program more
 - Sampling in fact is also costly due to trap

Profiling During Interpretation

Instruction function list

```
.  
.br/>branch_conditional(inst) {  
    BO  = extract(inst, 25, 5);  
    BI  = extract(inst, 20, 5);  
    displacement = extract(inst, 15, 14) * 4;  
    .  
    .  
    // code to compute whether branch should be taken  
    .  
    .  
    profile_addr = lookup(PC);  
    if (branch_taken)  
        profile_cnt(profile_addr, taken);  
        PC = PC + displacement;  
    Else  
        profile_cnt(profile_addr, nottaken);  
        PC = PC + 4;  
}
```

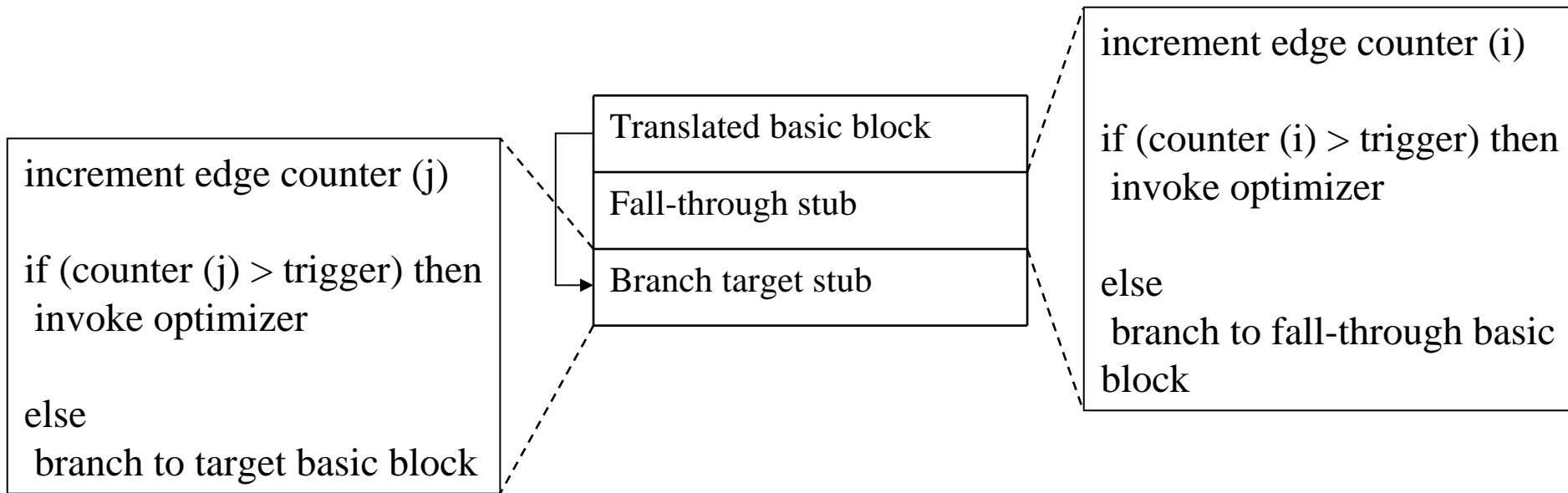
Branch PC → HASH

PC	Taken count	Not-taken count

Profile Table for Collecting an Edge Profile During Interpretation

PowerPC Branch Conditional Interpreter Routine

Profiling Translated Code



Edge Profiling Code Inserted into Stubs of a Binary Translated Basic Block

Emulation Stages

Profiling Overhead

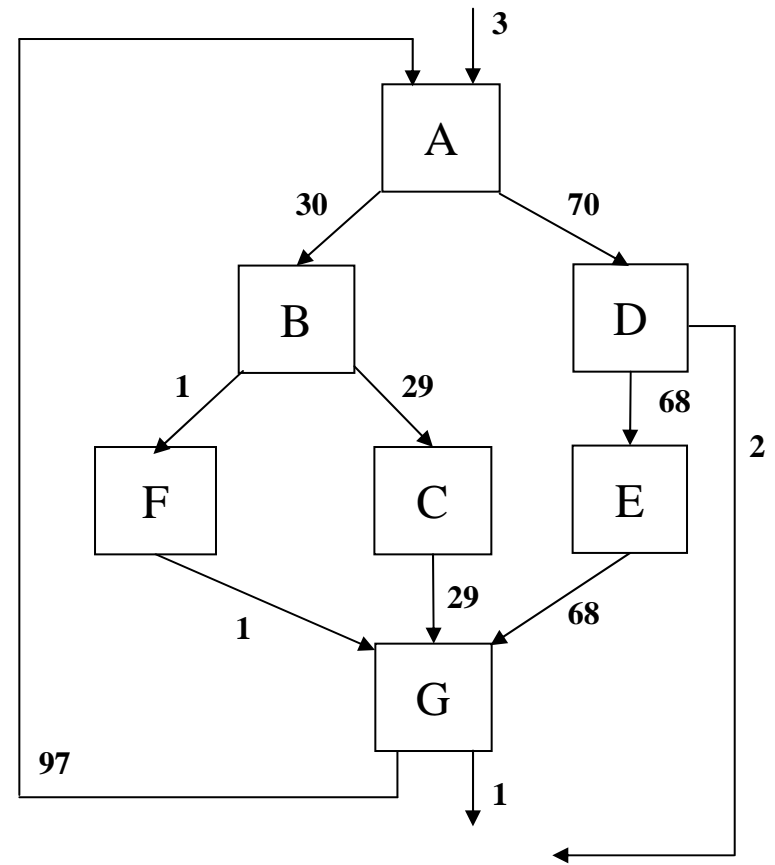
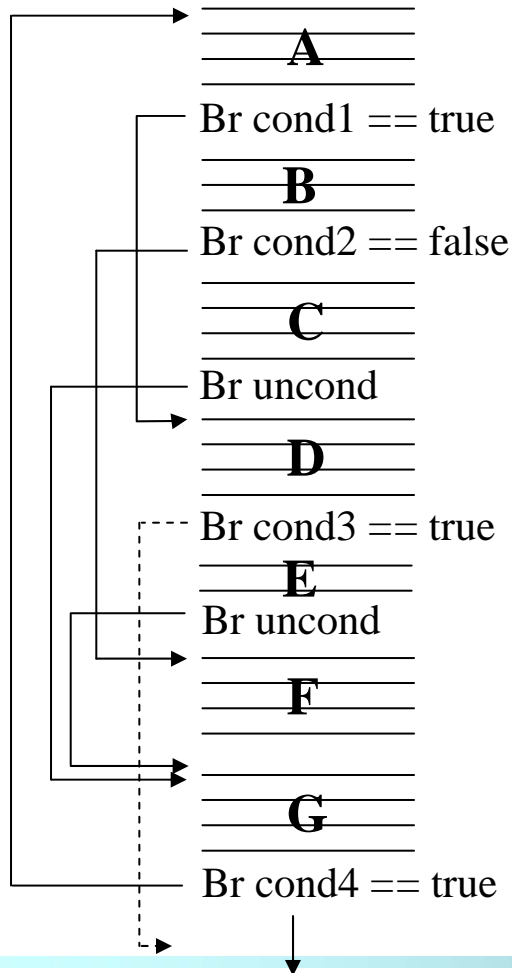
- For profiling during interpretation, occurring 10-20% overhead
- Less for translated code

Optimizing Translation Blocks

- Two-part strategy for optimizations
 - Improving spatial locality
 - Rearrange the layout of blocks
 - Inlining
 - ✓ Which also removes call-return code
 - Optimizing enlarged translated blocks
 - Traces, superblocks, tree groups
 - Unit for code optimization

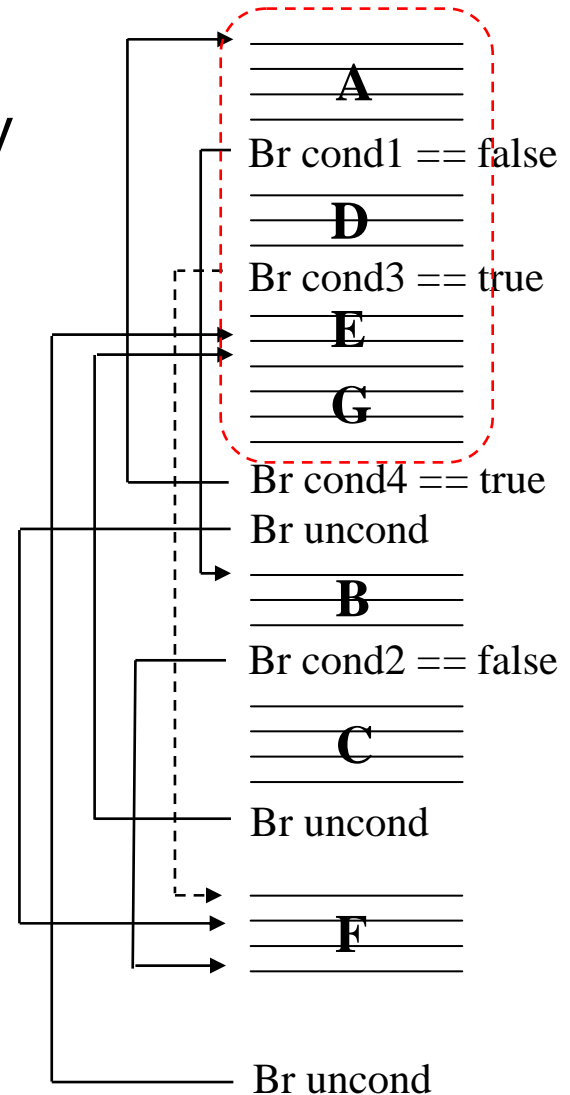
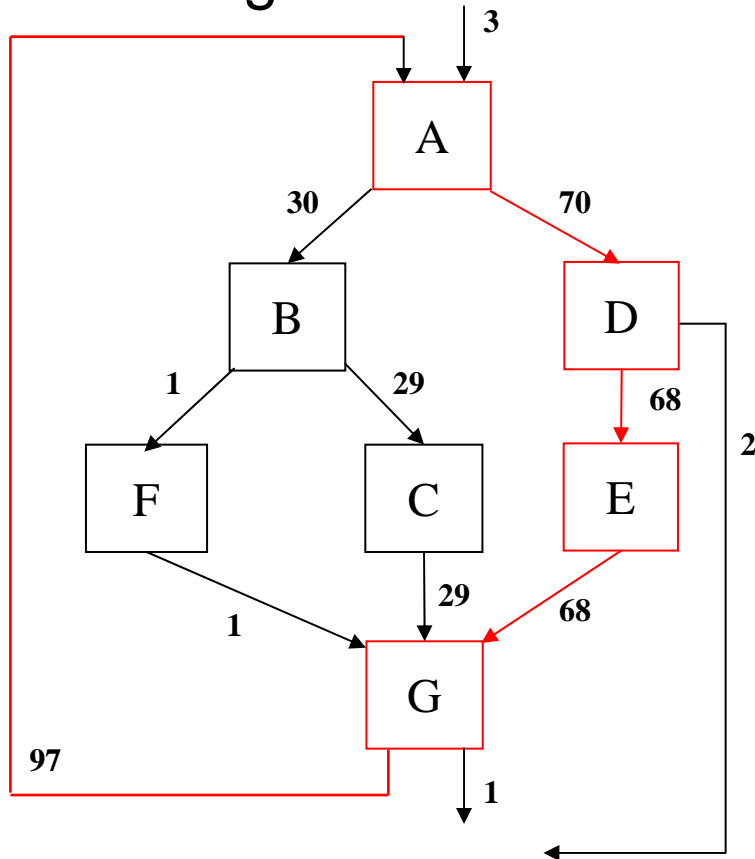
Improving Locality

- Example code sequence



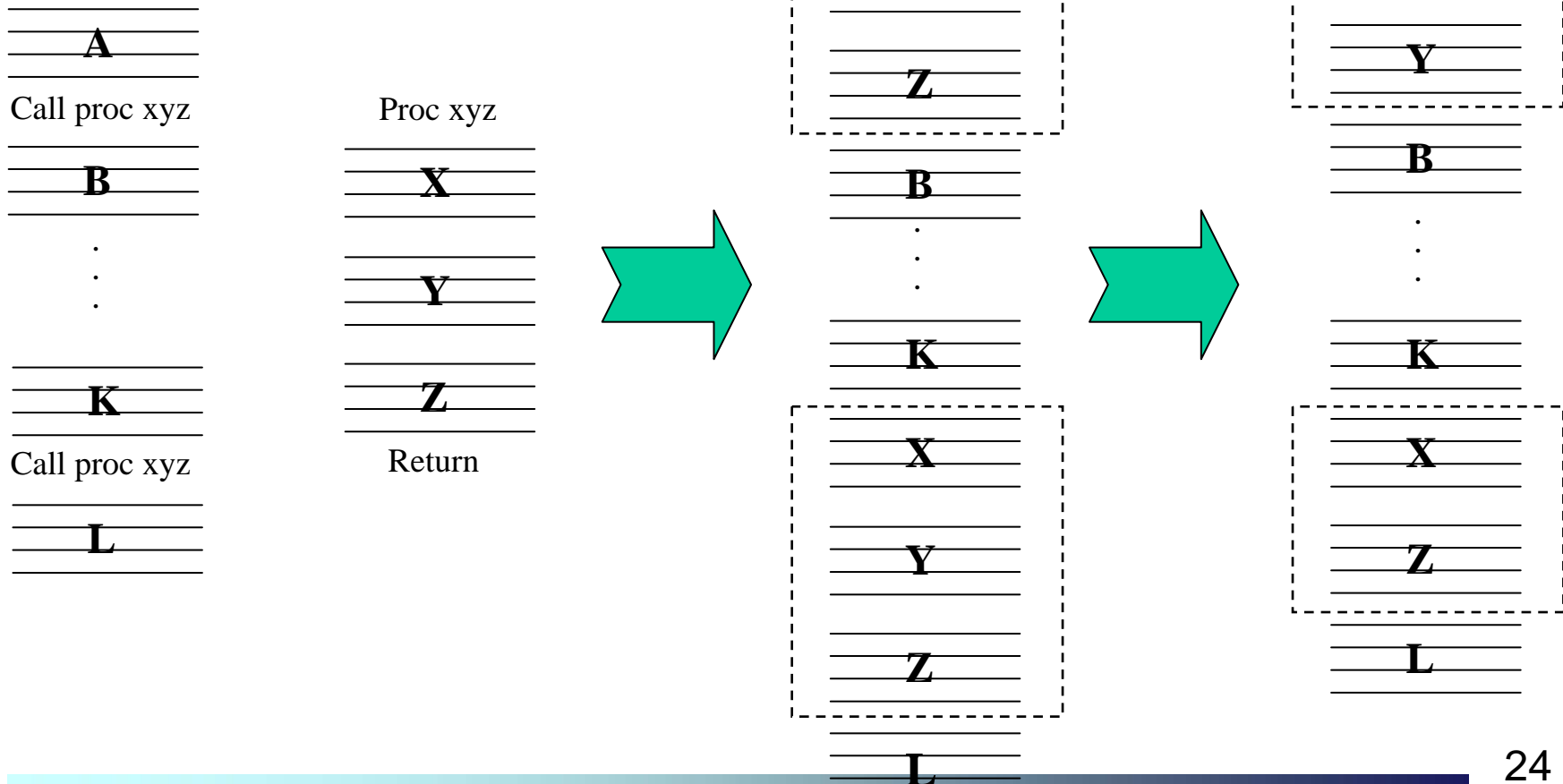
Improving Locality

- Rearrange the blocks in memory



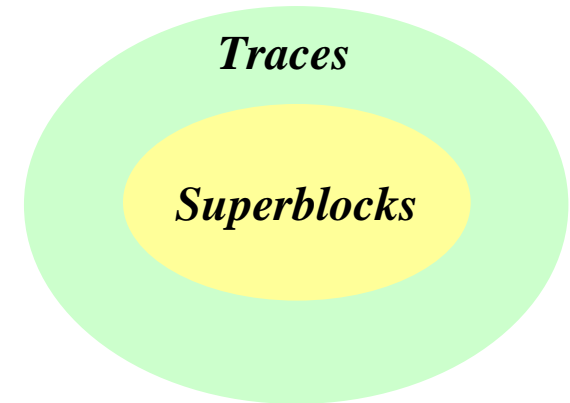
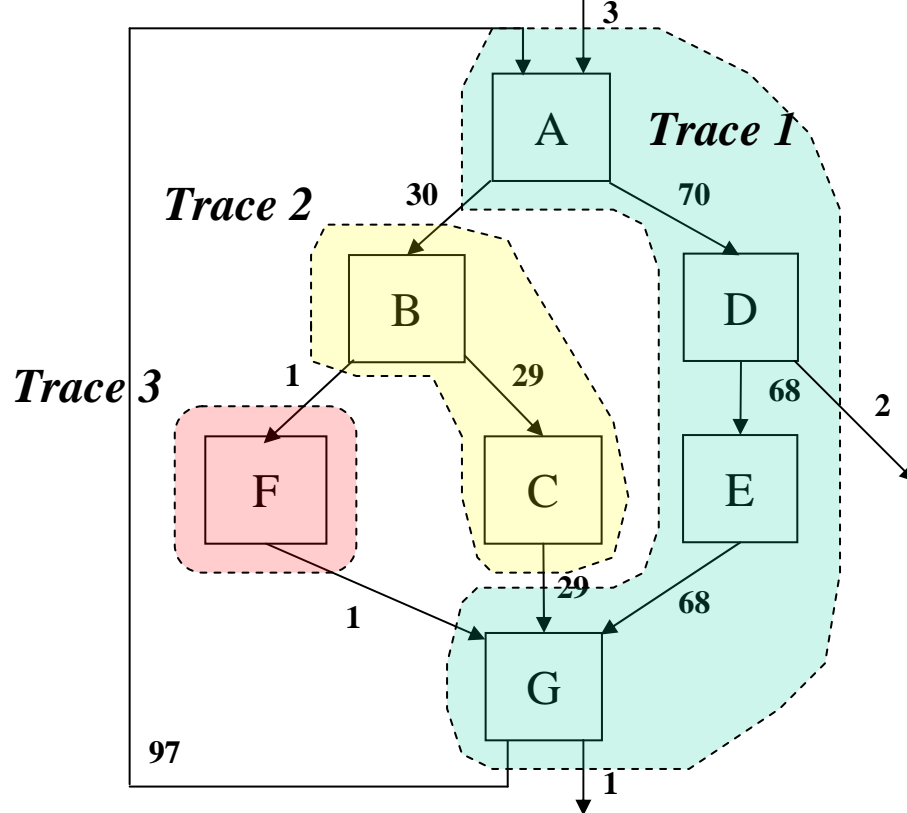
Improving Locality

- Procedure Inlining



Traces

- Trace
 - A contiguous sequence
 - Both side entrances and side exits

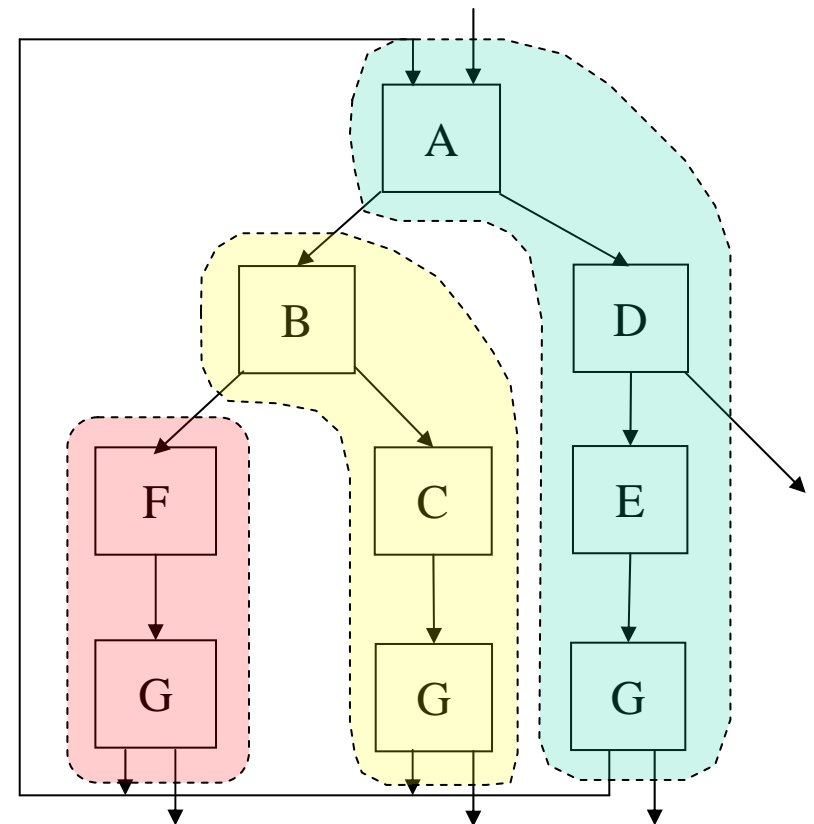
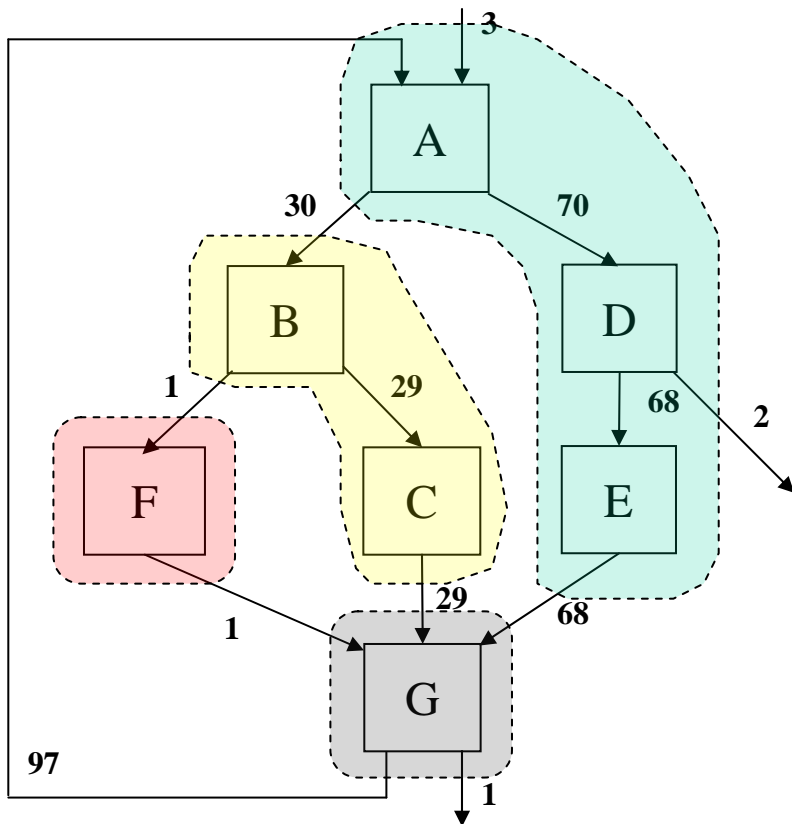


Relations between Superblocks and Traces

Superblocks

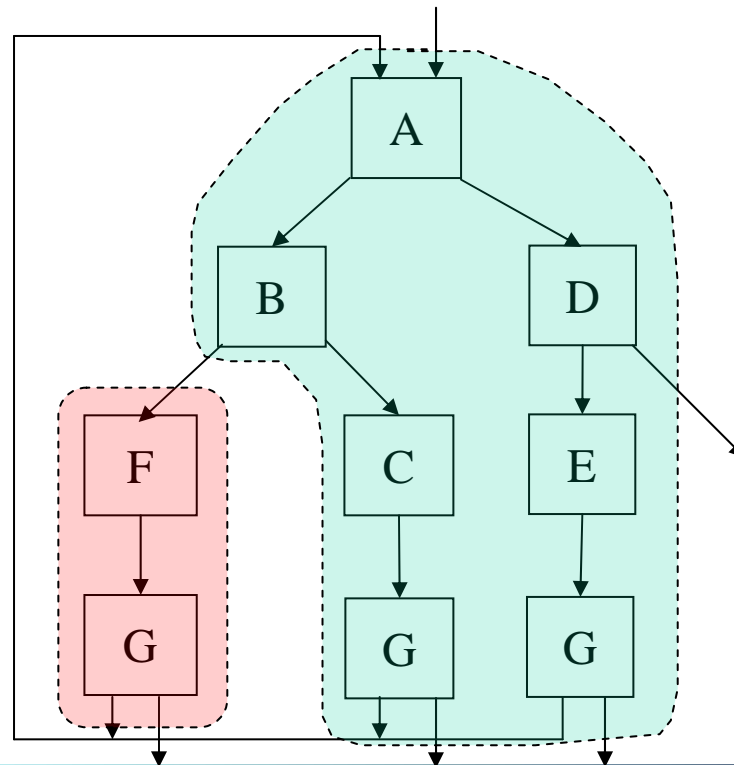
- Superblocks

- Regions of code with only one entry and one or more exit points, often formed by tail duplication



Tree Groups

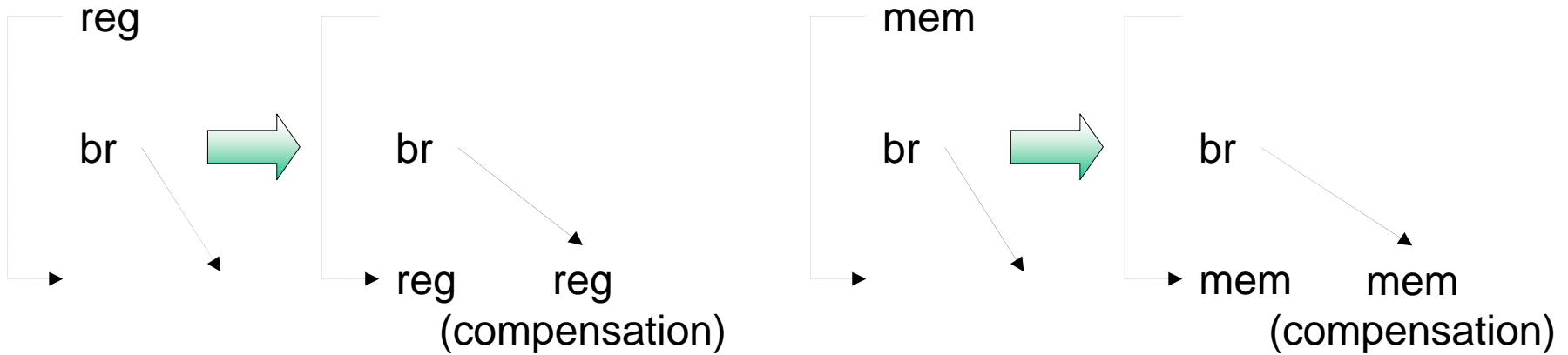
- Tree groups
 - Regions of code with only one entry and one or more exit points
 - Useful when branches arbitrarily



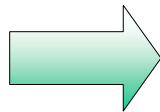
Code Reordering and Trap Handling

- For higher performance dynamic optimizers reorder instructions a lot
 - To exploit instruction-level parallelism
 - To reduce stalls
 - To optimize the code
- Reordering examples
- Reordering raises an issue of trap compatibility and state compatibility

Move instruction around branch



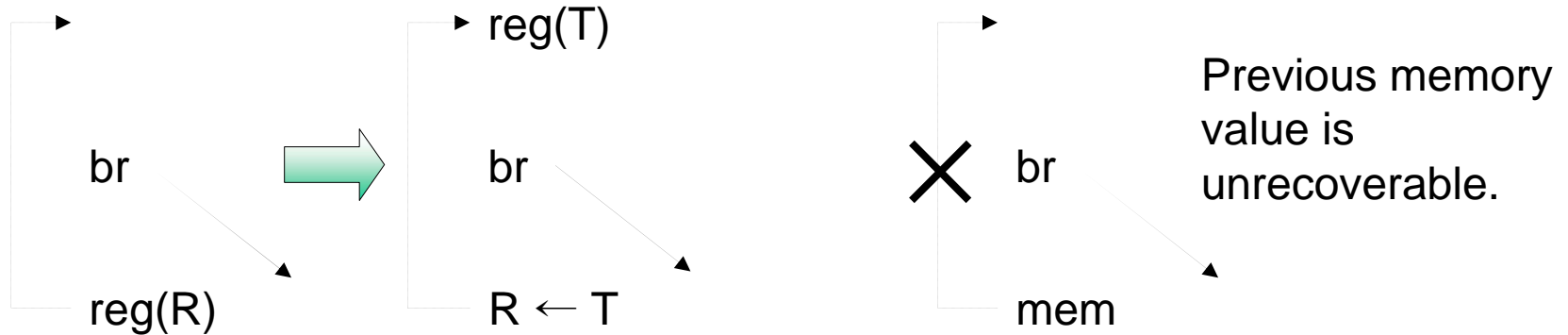
```
R1 ← mem(R6)
R2 ← mem(R6+4)
R3 ← R1 + 1
R4 ← R1 << 2
br exit if R7 == 0
R7 ← R7 + 1
mem(R6) ← R3
```



```
R1 ← mem(R6)
R2 ← mem(R6+4)
R3 ← R1 + 1
br exit if R7 == 0
R4 ← R1 << 2
R7 ← R7 + 1
mem(R6) ← R3
```

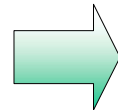
```
R4 ← R1 << 2
```

Speculative code motion above branch



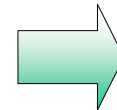
```

R2 ← R1 << 2
br exit if R8 == 0
R6 ← R7 * R2
mem(R6) ← R3
R6 ← R2 + 2
    
```



```

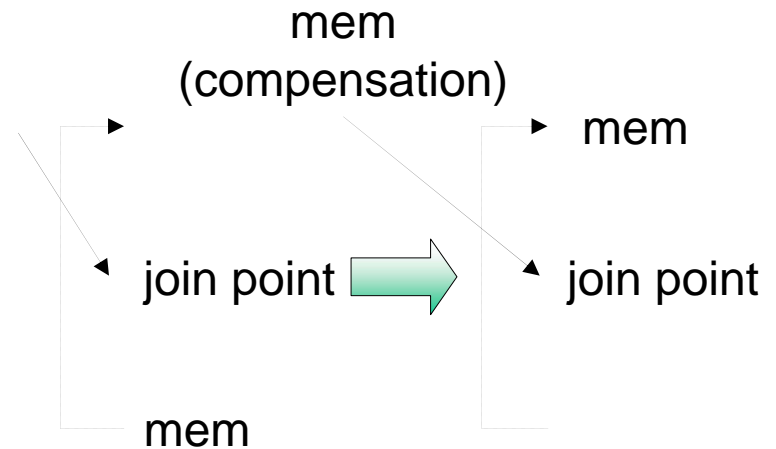
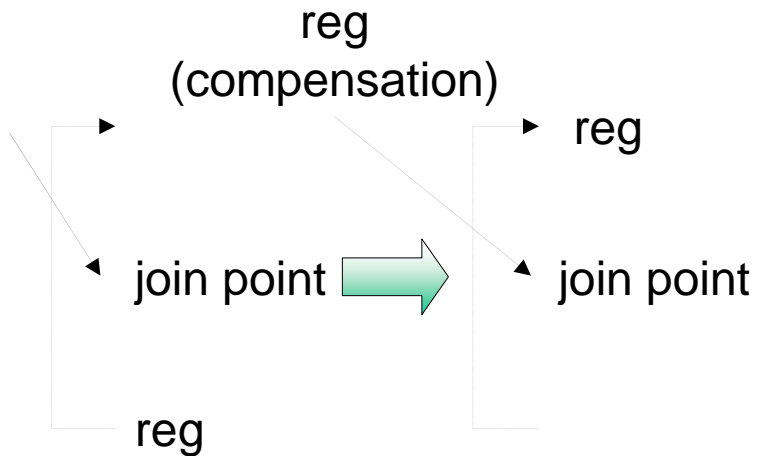
R2 ← R1 << 2
T1 ← R7 * R2
br exit if R8 == 0
R6 ← T1
mem(T1) ← R3
R6 ← R2 + 2
    
```



```

R2 ← R1 << 2
T1 ← R7 * R2
br exit if R8 == 0
mem(T1) ← R3
R6 ← R2 + 2
    
```

Move instructions above join point

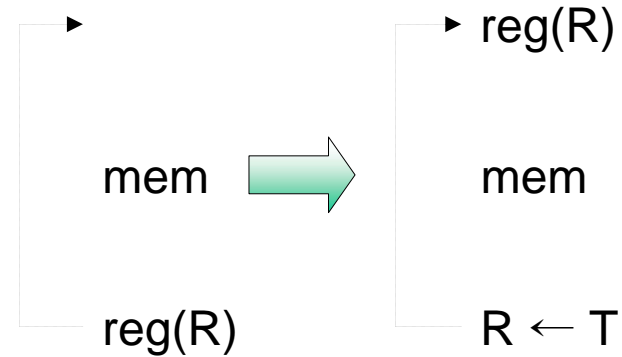
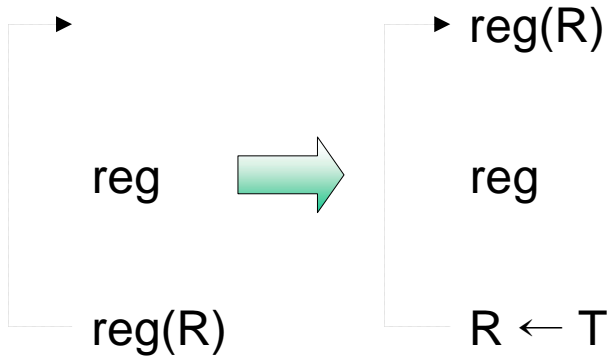


```
R1 ← R1 + 1  
R7 ← mem(R6)  
R7 ← R7 + 1
```

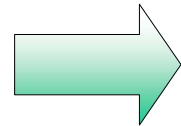
```
R7 ← mem(R6)
```

```
R1 ← R1 + 1  
R7 ← mem(R6)  
R7 ← R7 + 1
```

Move instructions in straight-line code



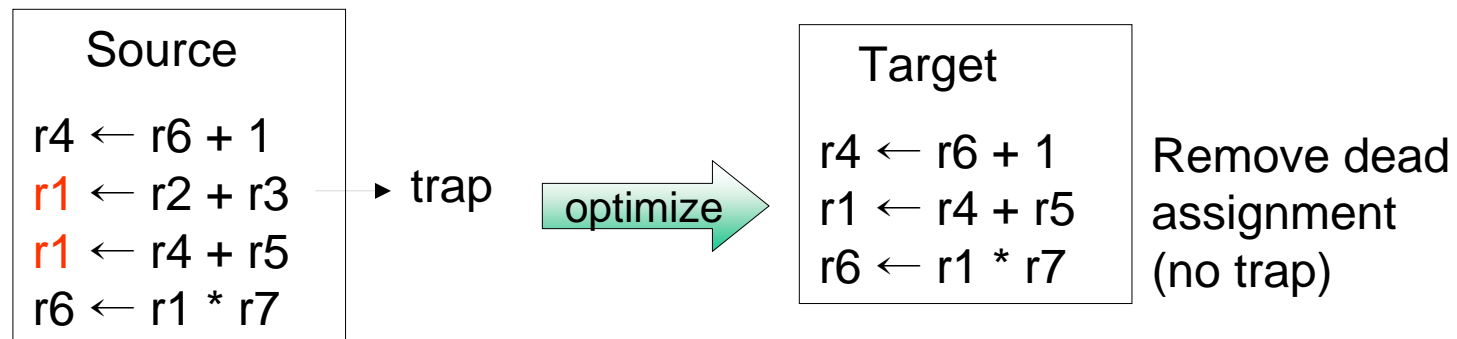
```
R1 ← R1 * 3  
mem(R6) ← R1  
R7 ← R7 << 3  
R9 ← R7 + R2
```



```
R1 ← R1 * 3  
T1 ← R7 << 3  
mem(R6) ← R1  
R7 ← T1  
R9 ← R7 + R2
```


Compatibility Issues

- Trap compatibility
 - Any trap in native execution should be observed during emulation and any trap observed during emulation should also occur in native execution



Compatibility Issues

- Memory and state compatibility
 - At trap point, if runtime can reconstruct the state of memory and registers at the native platform

