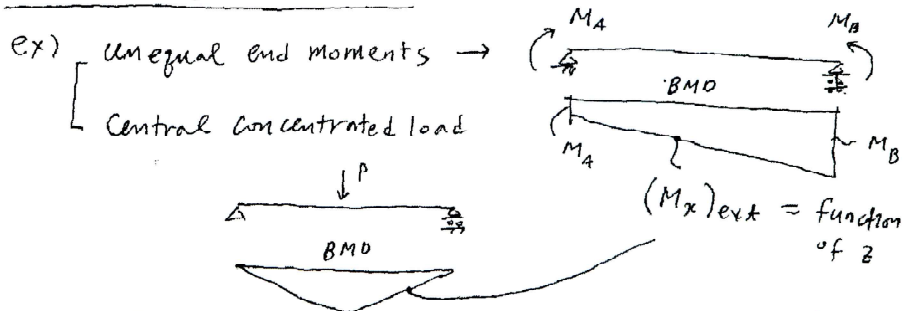


5.5 Beams with other loading conditions



(1) Beams in practical situations will be subjected to a wide variety of loading, thus producing non-uniform moment along the length of the beam

$\rightarrow$ the resulting governing D.E.

= Linear differential equations with variable coefficients (not constant coefficient)

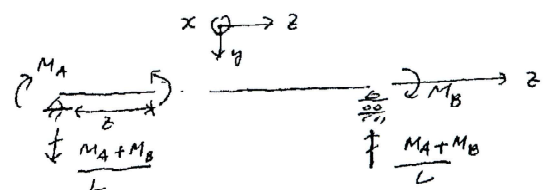
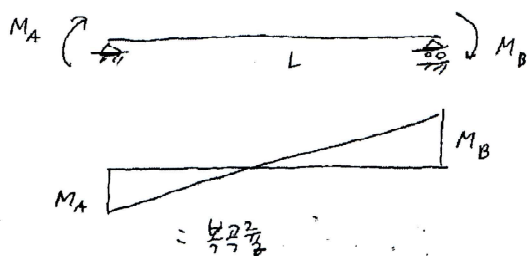
$\rightarrow$ 일반적인 해석적 정해가 존재하지 않으므로 수치해석적 근사법이 위해 M 값을 산정해야

(Timoshenko and Gere 1961, Massonet 1947, Horne 1954, Salvadori 1955)

(2) A simple but effective method

$\rightarrow$ equivalent moment concept (변-기동 복제리 등가균등모멘트 개념이라 함사)

5.5.1 Unequal End Moments



$$(M_x)_{ext} = M_A - \left(\frac{M_A + M_B}{L}\right)z \quad \leftrightarrow \quad M_0$$

그러나 (5.4.21) 식의 미분 방정식은
이를 더 높은 꼴로 수렴한다:

$$EI \frac{d^4 y}{dz^4} - GJ \frac{d^2 \theta}{dz^2} - \frac{1}{EI} \left\{ M_A - \left(\frac{M_A + M_B}{L}\right)z \right\}^2 \cdot y = 0$$

a variable coeff.

$\rightarrow$ Solution 형태를 유한함수 형태로 표시한 후

ex) (Bessel function) $\rightarrow$ 근사해를 만들 수 밖에 없게 됨

(또는 Galerkin method ...)

$\rightarrow$ "quite cumbersome".

For design purposes, the effect of moment gradient on the critical moment can easily be accounted for by the use of an equivalent moment factor C_b (Salvadori 1955):

↗ Bending Coefficient

$$M_{cr} = C_b \times M_{ocr} \quad \text{--- (5.5.1)}$$

$$\text{Where } M_{ocr} = \frac{\pi}{L} \sqrt{EI_y GJ} \sqrt{1 + W^2} \quad \leftarrow (5.4.34)$$

$$C_b = 1.75 + 1.05 \left(\frac{M_A}{M_B} \right) + 0.3 \left(\frac{M_A}{M_B} \right)^2 \leq 2.3$$

지금도
쓰이고
있음!
How replaced.

$$\left\{ \begin{array}{l} |M_B| > |M_A| \\ \frac{M_A}{M_B} = \text{positive for double curvature bending} \\ \frac{M_A}{M_B} = \text{negative for single " " " "} \end{array} \right.$$

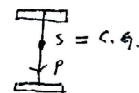
마치 AISC 접근법과 비슷

* Fig. 5.14 (p. 329) : 이공간의 M_A/M_B (5.5.1) 비교 $\rightarrow C_b = 1.0$

- (1) Uniform moment의 경우 ($\frac{2}{3} M_A = M_B$, 단곡률)가 가장 불리
- (2) $M_A = M_B$ 이고, 불곡률의 경우는 2.3 이하의 구간 내 2.3 증가를 인정
upper bound

5.5.2 Central Concentrated Load

Fig. 5.16 (p. 329) 참조:



- (1) 집중하중이 shear center에 작용하는 상황
- (2) 보라거나 수직 반경 $P/2$ 라면 $\frac{1}{2} (P u_m)$ 크기의 비틀림 반경이 발생함
→ 보 중앙부에서 항변위

External moment components w. r. t. the x-y-z coord. $\rightarrow$

$$\begin{cases} (M_x)_{ext} = \frac{P}{2} \left(\frac{L}{2} - z \right) \\ (M_y)_{ext} = 0 \\ (M_z)_{ext} = -\frac{P}{2} (u_m - u(z)) \end{cases}$$

비틀림모멘트 $\hookrightarrow$ 확인요

부호는 외순은 내사 제약이 아닐
Eqs. (5.5.3) ~ (5.5.5)

HW

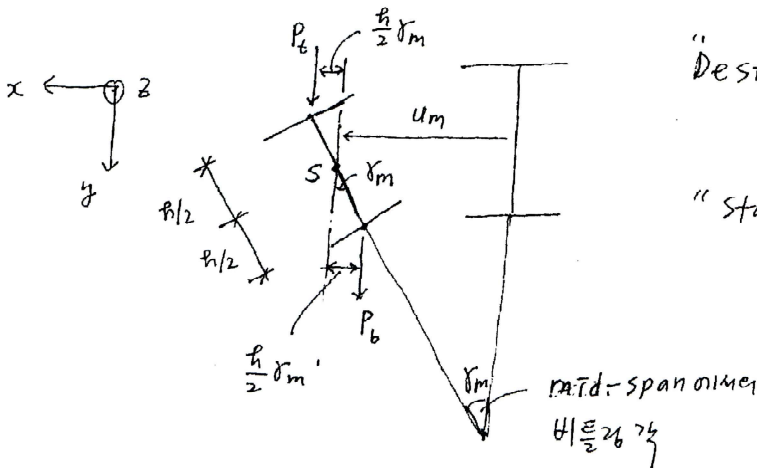
(17)

(1) (5.5.3) ~ (5.5.5) 식이 표시된 'undeformed 라플레'에 대한 external moment components 중 'deformed 라플레'로 projection 하여 (5.5.6) ~ (5.5.8) 식이 얻어짐을 확인함 것 $\leftarrow$ Fig. 5.17

참조

(2) (1)에서 얻어진 'deformed 라플레'에 대한 'external moment components' 중 'Internal moment components' 와 등치시킨 후 형변위 정보 등을 소개하여, 최종적으로 governing D.E. 가 (5.5.15) 식과 같이 얻어짐을 확인함 것. $\hookrightarrow$ 제 3항 계속: Variable 무한급수해법 불가피

* 가역점의 라플레 하중의 영향: Fig. 5.18 참조 (p. 332) (Timoshenko-Gere)



$$\text{"Destabilizing" moment} = P_b \times \left(\frac{h}{2} \right)$$

$\hookrightarrow$ (5.5.16)

$$\text{"Stabilizing" moment} = P_b \times \left(\frac{h}{2} \right)$$

$\hookrightarrow$ (5.5.17)

이항을

(17)에 반영하여

(5.5.14) 식을 수정하여 처리

* Nethercot and Rockey's Approximate Equation for the purpose of design (1991)

현존 Europe

최고 Steel

researcher

$$M_{ch} = \frac{P_{cr} L}{4} = C_b \times M_{ocr} \quad \dots (5.5.18)$$

$\hookrightarrow$ base strength

$$C_b = A \times B \quad \text{for the bottom flange loading}$$

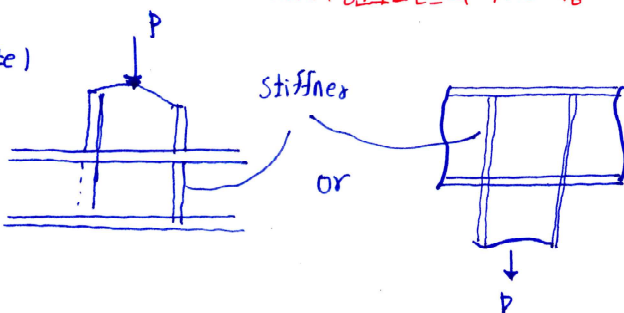
$$= A \quad \text{for the shear center loading}$$

$$= A/B \quad \text{for the top flange loading}$$

$$(A = 1.35 ; B = 1 + 0.649 \bar{\omega} - 0.180 \bar{\omega}^2 ; \bar{\omega} = \pi/L \sqrt{EC_w/GJ})$$

Note: 등분포모멘트의 1.35 배

Note)

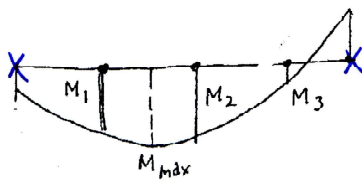
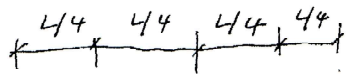


그리고 반드시
가력점 부근 형지지
해야 현명!

5.5.3 Other loading conditions

- (1) Table 5.2 (a): based on numerical results by a number of researchers
 ↳ shear center loading의 편차 (2, 8, 9, 10 ~ 15)

- ★ (2) Table 5.2 (b): Unified (approximate) formula by Kirby and Nethercot (1979)

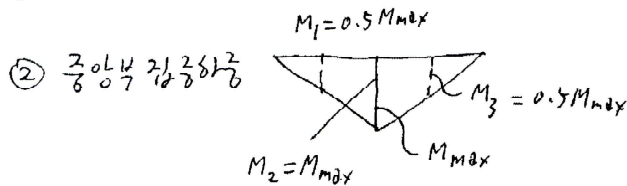


X: brace point

= BMD

$$C_b = \frac{12}{3\left(\frac{M_1}{M_{max}}\right) + 4\left(\frac{M_2}{M_{max}}\right) + 3\left(\frac{M_3}{M_{max}}\right) + 2} \quad \dots (5.5.22)$$

EX) ① Uniform moment case: $M_1 = M_2 = M_3 = M_{max} \rightarrow C_b = \frac{12}{3+4+3+2} = 1.0 \text{ (OK)}$



$$C_b = \frac{12}{3(0.5) + 4 + 3(0.5) + 2} = \frac{12}{9} = \frac{4}{3} = 1.33 \approx 1.35$$

Table 5.2 (a)

HW #

↳ (5.5.22) 식을 사용하여 C_b 를 계산하고

이 결과가 Table 5.2 (a)의 값과 잘 일치함을 확인한 것.

- (3) Table 5.3 (p. 335) 및 Fig. 5.19 (p. 336)

↳ 중등분로하중 및 등분로하중에 2가지 경우가 해당,

가장자리에 대한 좌굴하중 산정 방법식 (Nethercot and Rockey 1971)

↳ 사실은

가력점 횡지하는

것이 타당

가력점

- ① 기둥계기
- ② 양방향성
- ③ 기하
- ④ 연속

5.6 Beams with other "support" conditions

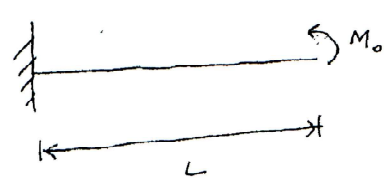
(1) The discussion so far pertains only to beams that are torsionally simply supported.

↳ (The ends of the beams are free to rotate and warp about the weak axis, but are restrained against rotation about the centroidal axis.

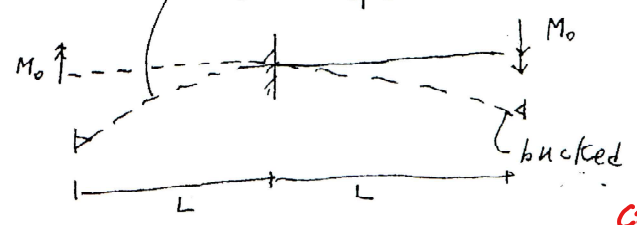
(2) The effective length concept to account for the support conditions.
 유효길과 끝길이 적용가능 (지리)

5.6.1 Cantilever Beams

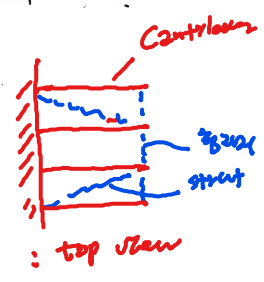
(a) Uniform moment (가장 불리)



side view



top view



top view

Thus, from Eq (5.4.34) M_{cr}

$$M_{cr} = \frac{\pi}{2L} (\sqrt{EI_y GJ}) \sqrt{1 + \frac{\pi^2 E C_w}{(2L)^2 GJ}} \quad (5.6.1)$$

수치해석 필요

(b) For other loadings, recourse must be made to numerical procedures to obtain solutions (e.g., Anderson and Trahair 1972, Nethercot 1973)

특수한 경우의 design aids

↳ (실제론 힙을 방지할 것임) → diagonal strut

- ① Fig. 20 ← Cantilever beam with a concentrated load at the free end
- Fig. 21 ← " " " " " " uniform load

② For other support conditions (Nethercot 1983),

(5.4.34) 식의 일반화에 불과 (P. 324) (5.6.2)

$$M_{cr} = \left(\frac{\pi}{KL} \right) \sqrt{EI_y GJ} \sqrt{1 + \frac{\pi^2 E C_w}{(KL)^2 GJ}}$$

In which K is the effective length factor of the beam

↳ Table 5.4 (p. 329) 참조 ← conservative estimate (완전 집중하중 또는 등분포하중이 적용가능)

↳ 물리적 의미와 부합하는가? (다음 쪽)

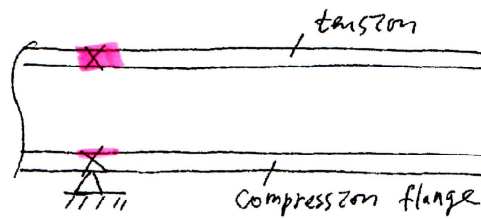
Several observations from Table 5.4



가령
실물
설계
유의

가장 profitable
리자본

(1)



x = lateral support

p (top flange
loading or 가중)

(20)

No lateral support
($k = 2.5$)

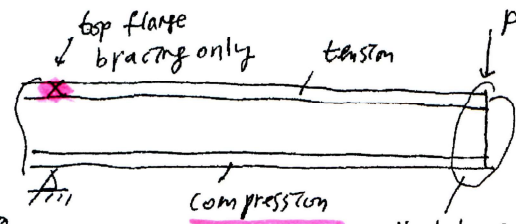
top flange
lateral bracing only
($k = 2.5$)

both top and
bottom flange
bracing

($k = 1.5$)

2.5 vs.
1.5

(2)



하단부 압축 flange
형상 지지

No lateral
restraint
($k = 7.5$)

$k = 4.5$

$k = 7.5$

1.5 vs. 4.5

2.5 vs. 7.5

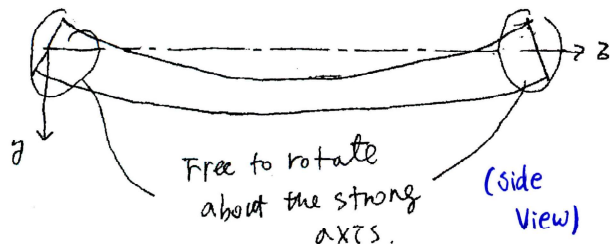
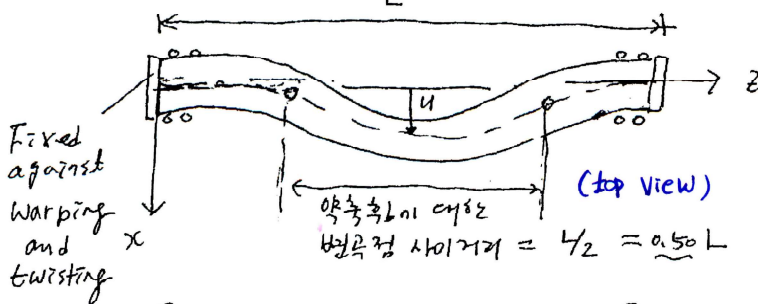
(가장 profitable
리자본)

Top flange
loading
마지막
 $k \leq 1.0$

"Fundamentals of lateral bracing" ← 압축 flange의 형상 지지가 중요

5.6.2 Fixed End Beams

Totally



"가장 profitable" For lateral
bending

$$u|_{z=0} = u|_{z=L} = u'|_{z=0} = u'|_{z=L} = 0$$

For twisting

$$\phi|_{z=0} = \phi|_{z=L} = 0$$

For warping

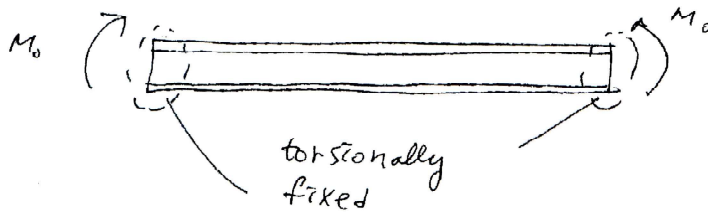
$$\frac{dw}{dz}|_{z=0} = \frac{dw}{dz}|_{z=L} = 0$$

왜 이러했는가?

$$\therefore \text{강성 모멘트 } T_{sv} = GJ \frac{d\phi}{dz} = 0 \text{ 이므로}$$

가장 profitable

"Under a uniform moment"



5.4 절의 동일한 편차 방정식. 지지사 (or $(M_z')_{int} = (M_z)_{ext}$)

$$\frac{d^4 \delta}{dz^4} - 2q \cdot \frac{d^2 \delta}{dz^2} - b\delta = 0 \quad \dots (5.4.23)$$

In which $q = \frac{GJ}{2EC_w}$; $b = \frac{M_0^2}{EC_y EC_w}$

일반해는 $\delta = A \sinh mz + B \cosh mz + C e^{mz} + D e^{-mz} \dots (5.4.24)$

In which $m = \sqrt{-q + \sqrt{q^2 + b}}$; $n = \sqrt{q + \sqrt{q^2 + b}}$

(5.4.24)에 경계조건 4가지, $\frac{\delta}{L} \Big|_{z=0} = \delta \Big|_{z=L} = \delta' \Big|_{z=0} = \delta' \Big|_{z=L} = 0$ 를 대입하여 정리하면, 다음의 특성방정식이 얻어짐.

$$\left(\frac{m^2 - n^2}{2mn} \right) \sinh mL \sinh nL + \cosh mL \cosh nL - 1 = 0 \quad \dots (5.6.5)$$

이 특성방정식은 간단히 풀리지 않음
(시행 24쪽 계산 참조)

* 횡단축에 대한 등가회전극성 지지계약을 도입하여 하한

$$KL = 0.50 L \quad (\text{앞의 20쪽 2회 참조})$$

$$\therefore M_{cr} = \frac{\pi}{(L/2)} \sqrt{EC_y GJ} \sqrt{1 + \frac{\pi^2 EC_w}{(L/2)^2 GJ}} \quad \dots (5.6.6)$$

↳ The critical moment for a fixed end beam is considerably higher than that of a simply supported beam (Fig. 5.2 참조)

(양단 고정 지지) →

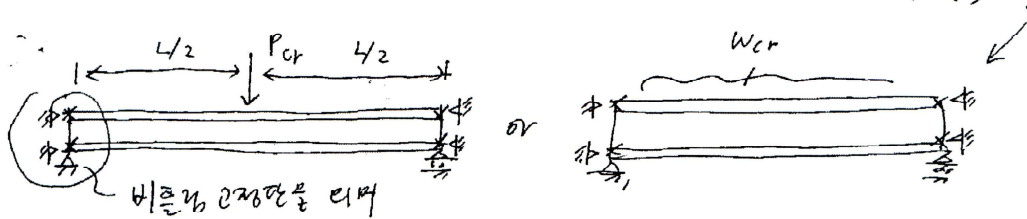
(22)

"For other types of loading" (producing non-uniform distribution of moments along the length of the beam)

→ The D.E will have variable coefficients and recourse to numerical procedure is inevitable.

(5.5절 및 15절 16절 26절)

✓ Nethercot and Rackey (1971)



$$M_{cr} = C_{bs} (M_{ocr}) \quad (5.4.34) \text{ or } \dots (5.6.7)$$

where $M_{cr} = \frac{P_{cr}}{4} \times L \quad \text{or} \quad \frac{W_{cr} L^2}{8} \quad \dots (5.6.8)$

and $C_{bs} = A \times B$ (for bottom flange loading)
 $= A$ (for shear center "
 $= A/B$ (for upper flange "

→ the expressions of A and B (Table 5.5 262, p.342)

The effective length factor K for the beams shown in Table 5.5 can be obtained by equating (5.6.7) with (5.6.2).

$$\frac{\pi}{KL} \sqrt{EI_y GJ} \sqrt{1 + \frac{\pi^2 ECW}{(KL)^2 GJ}} = \frac{C_{bs} M_{ocr}}{(5.6.7)}$$

(5.6.2)

Solving for K,

$$K = \frac{\pi \sqrt{EI_y GJ}}{\sqrt{2L} (C_{bs} M_{ocr})} \left\{ 1 + \sqrt{\frac{4(C_{bs} M_{ocr})^2}{EI_y GJ} \frac{EC_w}{GJ} + 1} \right\} \dots (5.6.10)$$

K 값에 영향을 미치는 인자들: L, E, G, C_w, J
 ↳ 결론 (Simplistic)
 실험 설계에 (5.6.10) 식을 사용하기에는 너무 번거롭기 때문에
 등식 $K=1.0$ (보수적 값) 을 사용함

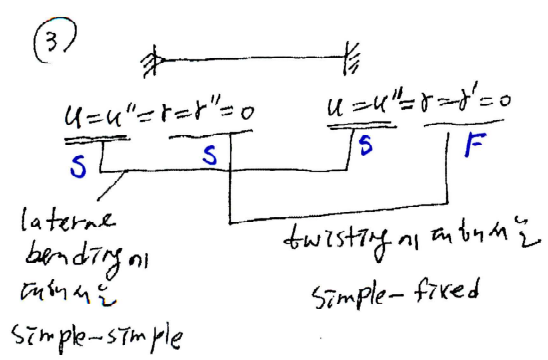
the types of loading, 전단응력이
 대한 하중: 작용성의 상태에 따라 등등.

* 만약 회전방향 (u) 와 비틀림 (r) 에 대한 구속조건이 서로 다르다면, lateral bending에 대한 K_b 값과 twisting에 대응되는 K_t 값은 서로 달라질 것이다.
 Uniform moment를 받는 경우 (Vlasov 1959), 러시아연방

$$M_{ocr} = \frac{\pi \sqrt{EI_y GJ}}{K_b L} \sqrt{1 + \frac{\pi^2 EC_w}{(K_t L)^2 GJ}} \dots (5.6.11)$$

K_b 및 K_t 값 → Table 5.6 참고 (P. 343)

Note: ① $u=u''=r=r''=0$ ← torsionally simple support 조건에 해당
 (양단 모두) ⇌ 따라서 $K_b=1.0$; $K_t=1.0$ (한정된 값)
 ② $u=u'=r=r'=0$ ← torsionally fixed support 조건에 해당
 (양단 모두) ⇌ 따라서 $K_b=K_t=0.492 \approx 0.50$
 (한정된 값)



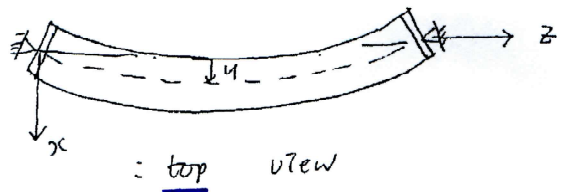
$K_b = 0.904 \approx 1.0$
 $K_t = 0.697 \approx 0.70$
 (한정된 값)
 For simplicity
 S-S → 1.0
 S-F → 0.70
 F-F → 0.50
 Bending 이든
 twisting 이든.
 (In short)

However, If the degree of end fixity is questionable, a conservative measure is to use one for the effective length factor.
 $K=1.0$ at $\frac{L}{2}$

5.6.3 Other End Conditions.

(to make engineer's life easier)

- ✓ (1) The ends of the beams prevented from warping, but unrestrained in bending about weak axis (Fig. 5.24)



The out-of-plane conditions for lateral bending; $u|_{z=0} = u|_{z=L} = 0$

$$\frac{d^2 u}{dz^2} \Big|_{z=0} = \frac{d^2 u}{dz^2} \Big|_{z=L} = 0$$

$\uparrow M_f = 0$

For twisting; $\theta|_{z=0} = \theta|_{z=L} = 0$

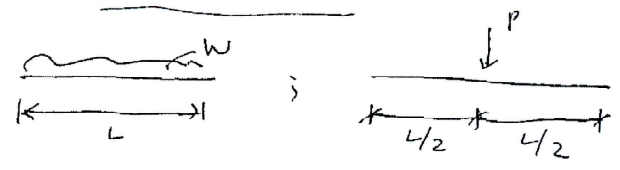
For warping; $\frac{dw}{dz} \Big|_{z=0} = \frac{dw}{dz} \Big|_{z=L} = 0$
 $\uparrow T_{sv} = 0$

$$M_{cr} = C_{bs} M_{ocr} \quad \dots (5.6.7)$$

where $M_{cr} = \frac{P_{cr} \cdot L}{4}$ or $M_{cr} = \frac{W_{cr} L^2}{8} \quad \dots (5.6.8)$

and $C_{bs} = \begin{cases} A \cdot B & \text{for bot. flange loading} \\ A & \text{for shear center} \\ A/B & \text{for top flange} \end{cases}$

"Expressions of A and B" $\rightarrow$ See Table 5.7 (p.344)



- ✓ (2) The ends of the beams prevented from bending about weak axis, but free to warp (Fig. 5.25) $\rightarrow$ See Table 5.8 (p.346)

$$u|_{z=0} = u|_{z=L} = \frac{du}{dz} \Big|_{z=0} = \frac{du}{dz} \Big|_{z=L} = 0; \quad \theta|_{z=0} = \theta|_{z=L} = \frac{d^2 \theta}{dz^2} \Big|_{z=0} = \frac{d^2 \theta}{dz^2} \Big|_{z=L} = 0$$

(3) An alternative approach to calculate the M_{cr} for beams of doubly symm. sections with out-of-plane bending and torsional simply supported as well as fixed end conditions by Clark and Hall (1962):

$$M_{cr} = \frac{C_4}{L} \sqrt{EI_y GJ} \quad \leftarrow \text{more simple form} \quad \text{--- (5.6.16)}$$

$$C_4 = C_1 \frac{\pi}{K} \left\{ \sqrt{1 + \left(\frac{\pi}{KL}\right)^2 \left(\frac{EC_w}{GJ}\right) (C_2^2 + 1)} \pm C_2 \left(\frac{\pi}{KL}\right) \sqrt{\frac{EC_w}{GJ}} \right\} \quad \text{--- (5.6.17)}$$

지점 조건 및 하중 패턴에 따라

K, C_1, C_2 값은 Table 5.9 (p. 347 참조)

See Table 5.9

C_1 = the coefficient accounting for the type of load and support conditions

C_2 = the coefficient accounting for the location of the load vertically w.r.t. the shear center of the cross section;

the plus sign $\rightarrow$ the bottom flange loading
the minus sign $\rightarrow$ the top flange loading
 $C_2 = 0 \rightarrow$ the shear center loading or an end moment loading

EX)
Double check

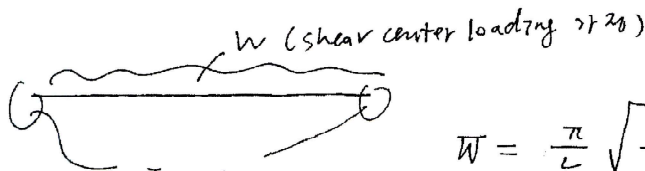


Fig. 5.22

$$\begin{cases} u = u' = 0 \\ r = r' = 0 \end{cases}$$

$$W = \frac{\pi}{L} \sqrt{\frac{EC_w}{GJ}} = 1.0 \text{ of } \pi$$

무엇을 얻었는지?

(i) Solution by Nethercot and Rockey's approach

$$C_{bs} = A = 1.643 + 1.771 - 0.405 = 3.009 \quad (\text{from Table 5.5})$$

$$\frac{w_{cr} L^2}{8} = C_{bs} M_{ocr} = 3.009 \xrightarrow{M_{ocr}} w_{cr} = \frac{8}{L^2} \times 3.009 M_{ocr} = \frac{24}{L^2} M_{ocr}$$

$$= \frac{24}{L^2} \left\{ \frac{\pi}{L} \sqrt{EI_y GJ} \times \sqrt{1 + 1^2} \right\}$$

$$\therefore w_{cr} = \frac{24\sqrt{2}\pi}{L^3} \sqrt{EI_y GJ}$$

$$= \frac{33.9\pi}{L^3} \sqrt{EI_y GJ}$$

(ii) Solution by Clark and Hill's approach "not case 7"

(26)

↳ Table 5.9 이 "Case No. 6" 이므로 (Fixed)

why? (78% from 214m) simple!)

$K = 0.5$; $C_1 = 1.0$; $C_2 = 0$ (shear center loading $\rightarrow z_0$)

$$M_{cr} = \frac{C_4}{L} \sqrt{EI_y GJ} \leftarrow \text{Eq. (5.6.16)}$$

$$\left\{ \begin{aligned} C_4 &= C_{1.0} \left(\frac{\pi}{0.50} \right) \left\{ \sqrt{1 + (2)^2 \times \frac{W^2}{L^2} \times (0^2 + 1)} \right\} \leftarrow \text{Eq. (5.6.17)} \\ &= 2\pi \sqrt{5} = 4.47\pi \end{aligned} \right.$$

$$\frac{W_{cr} L^2}{8} = \left(\frac{4.47\pi}{L} \right) \sqrt{EI_y GJ}$$

$$\therefore W_{cr} = \frac{35.8\pi}{L^3} \sqrt{EI_y GJ} \approx \frac{33.9\pi}{L^3} \sqrt{EI_y GJ}$$

Note : 판의 강성이 커지면 양방향으로의 변형이 증가된다고
 Vertical bending in y-z plane Table 5.9 이 Case no. 7 이
 해당되는 것임.

이제 $K = 0.5$; $C_1 = 0.9$ 이므로

$$M_{cr} = \frac{W_{cr} L^2}{12} = \frac{(0.90) \times 4.47\pi}{L} \sqrt{EI_y EC_w}$$

$$\therefore W_{cr} = \frac{48.3\pi}{L^3} \sqrt{EI_y EC_w} \leftarrow \frac{48.3}{35.8} = 1.35$$

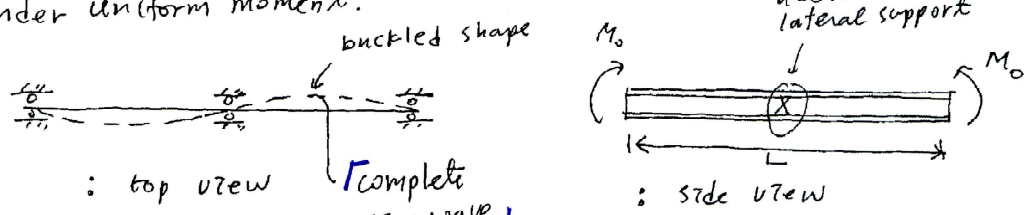
(35% Increase)
 큰 값인가?

HW #

↳ 판의 강성이 증가하면 2차원 하중 P_{cr} 이
 커지고 1차원 하중 P_{cr} 이
 감소하는 비로써 볼 것. (Shear center 하중 / 단축지지 가정)
 비례

5.6.4 Continuous Beam

(1) Under uniform moment.



$$m = \sqrt{-a + \sqrt{a^2 + b}} = \frac{2\pi}{L}$$

where

$$a = GJ / 2ZC_w$$

$$b = \frac{M_o^2}{EI_y C_w}$$

$$\sin mL = 0 \quad \text{--- (5.4.31)}$$

$mL = 2\pi \leftarrow$ the second lowest value of m

Eigenproblem of simply supported I-section under pure bending (P.322) (P.324)

$$M_{ocr} = \frac{\pi}{(L/2)} \sqrt{EI_y GJ} \sqrt{1 + \frac{\pi^2 E C_w}{(L/2)^2 GJ}} \quad \text{--- (5.6.19)}$$

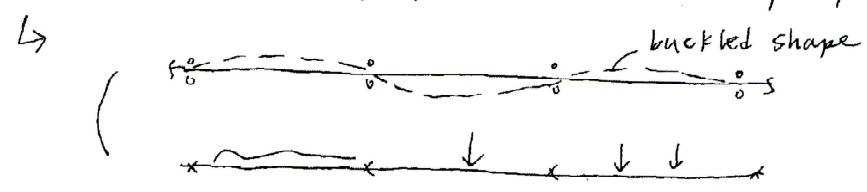
∴ 여기서 $K = 0.50$ 사용하는 것만 동일.

(2) For other types of loadings, numerical solutions for the critical loads are available (for example, Timoshenko and Gere (961).

↳ Table 5.10 참조 (two-span continuous beam)

↳ Eqs. (5.6.7) ~ (5.6.9) 중 A, B 값만 이용

(3) For a continuous beam with more than two spans,



Influencing factors; 구간별 상하강비, 하중 패턴 및 상하 크기, 중간 횡지지점의 구속상태 --- (참고문헌 리 ~ 24)

For design purposes, it is common to evaluate the critical load for each span separately by assuming the ends of the span are simply supported.

↳ 각 스파에서 얻어진 임계하중 가운데 최소치를 택하여

(보수적) 평가 연결속보의 좌굴하중으로 취급

Conservative

이러한
limitation을
잘 인지하고
있어야

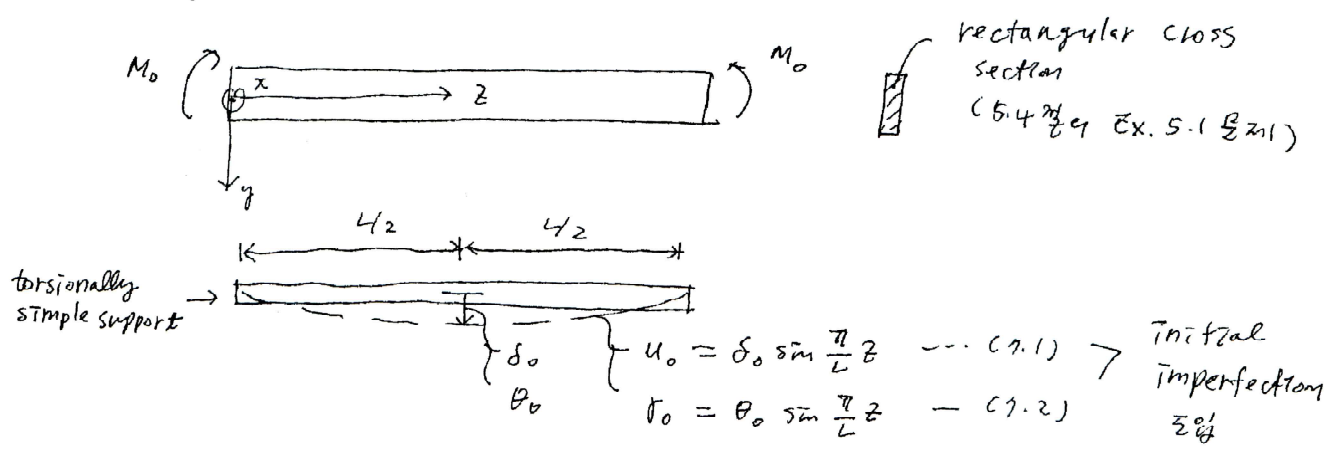
5.7 Initially Crooked Beams

Real beams are seldom perfect.

↑ The presence of initial curvature and twist will cause them to bend and twist at the beginning of loading

↳ Load - deflection problem

"Case study"



Equating the corresponding external and internal moments,

Eg. (5.4.8) $\rightarrow EI_y \frac{d^2 u}{dz^2} + (\tau + v_0) M_0 = 0 \quad \dots (7.3)$ } External moments 만 수정됨

Eg. (5.4.9) $\rightarrow GJ \frac{d\tau}{dz} - (\frac{du}{dz} + \frac{dv_0}{dz}) M_0 = 0 \quad \dots (7.4)$

(7.4) 식을 (7.3) 식에 대입하여 \$u\$ 를 제거하면

$$EI_y GJ \frac{d^2 \tau}{dz^2} + \tau M_0^2 = EI_y M_0 \frac{d^2 u_0}{dz^2} - v_0 M_0^2$$

$$= -EI_y M_0 \delta_0 \left(\frac{\pi}{L}\right)^2 \sin \frac{\pi}{L} z \left[\frac{M_{ocr}}{\pi^2 EI_y / L^2} \right] \times \theta_0$$

$$- \theta_0 M_0^2 \sin \frac{\pi}{L} z \quad \dots (5.7.6)$$

"중기 불완전 변형률과 변형률 변위로 인한 비틀림 모멘트를 가함"

$$\delta_0 : \theta_0 = \frac{M_{ocr}}{\pi^2 EI_y / L^2} = \frac{1}{\pi^2 EI_y / L^2} : \frac{1}{M_{ocr}} \quad \dots (5.7.7)$$

↑ reasonable 한 것일까?

$$\delta_0 = \left(\frac{M_{ocr}}{\pi^2 EI_y / L^2} \right) \times \theta_0 \quad (5.7.6) \text{ 식에 대입하여 정리하면,}$$

Constant, anyway 그래프

↳ 전체적 경향 파악의 일반성 있기 있음.

$$EI_y GJ \frac{d^2 r}{dz^2} + r M_o^2 = - M_o \cdot M_{ocr} \cdot \theta_o \sin \frac{\pi}{L} z - M_o^2 \theta_o \sin \frac{\pi}{L} z$$

$$= - M_o^2 \left(\frac{M_{ocr}}{M_o} + 1 \right) \cdot \theta_o \sin \frac{\pi}{L} z \quad (29)$$

$$\frac{d^2 r}{dz^2} + k^2 r = -k^2 \theta_o \left(\frac{M_{ocr}}{M_o} + 1 \right) \sin \frac{\pi}{L} z \quad \text{--- (5.7.9)}$$

where $k^2 = M_o^2 / EI_y GJ$ $\rightarrow r_p = C \cos \left(\frac{\pi}{L} z \right) + D \sin \left(\frac{\pi}{L} z \right)$

2) r_0 미지수인 r 의 particular solution r_p 구하기

$$r_p = \left[\frac{-k^2 \theta_o \left(\frac{M_{ocr}}{M_o} + 1 \right)}{k^2 - \left(\frac{\pi}{L} \right)^2} \right] \sin \frac{\pi}{L} z \quad \text{--- (5.7.15)}$$

$$\hookrightarrow k^2 = \frac{M_o^2}{EI_y GJ} ; M_{ocr} = \frac{\pi}{L} \sqrt{EI_y GJ} \text{ 인 } \frac{M_o}{M_{ocr}}$$

$$= \left[\frac{\theta_o \times \frac{M_o}{M_{ocr}}}{1 - \frac{M_o}{M_{ocr}}} \right] \sin \frac{\pi}{L} z \quad \text{--- (5.7.16)}$$

Note: $\frac{r_p}{r_e} \leftrightarrow \frac{M_o}{M_{ocr}}$

그러므로 인수분해

$$r = A \sin k z + B \cos k z + r_p \quad \text{--- (5.7.17)}$$

$\hookrightarrow$ (5.7.16)을

경계조건: $r(0) = 0 ; r(L) = 0$

$$\begin{array}{l} \cancel{B=0} \quad \hookrightarrow \quad A \sin k L = 0 \end{array}$$

$$A = 0 \text{ or } \sin k L = 0$$

$\hookrightarrow$ 이 때 M_{ocr} 이 임의적인
모든 값에 대해 대응이 안함

그러므로 $A = 0$ and $B = 0$

$$\therefore r = \left[\frac{\theta_o \times \left(\frac{M_o}{M_{ocr}} \right)}{1 - \left(\frac{M_o}{M_{ocr}} \right)} \right] \sin \left(\frac{\pi}{L} z \right) \quad \text{--- (5.7.18)}$$

(5.7.18)을 (5.7.3) 및 (5.7.4)에 대입하고 u 를 구하면

"HW # $\hookrightarrow$ r 과 u "

$$\left\{ \begin{array}{l} u = \frac{\delta_o \times \left(\frac{M_o}{M_{ocr}} \right)}{1 - (M_o/M_{ocr})} \times \sin \left(\frac{\pi}{L} z \right) \quad \text{--- (5.7.19)} \\ r_{total} = r_o + r = \left[\frac{1}{1 - M_o/M_{ocr}} \right] \times \left(\theta_o \sin \frac{\pi z}{L} \right) = A_F \times r_o \quad \text{--- (20)} \\ u_{total} = u_o + u = \left[\frac{1}{1 - M_o/M_{ocr}} \right] \times \left(\delta_o \sin \frac{\pi z}{L} \right) = A_F \times u_o \quad \text{--- (21)} \\ \text{where } A_F = \left[\frac{1}{1 - M_o/M_{ocr}} \right] \quad \text{--- (22)} \end{array} \right.$$

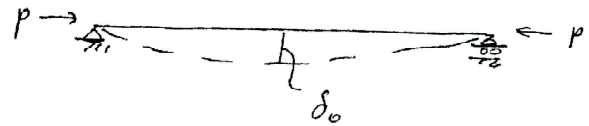
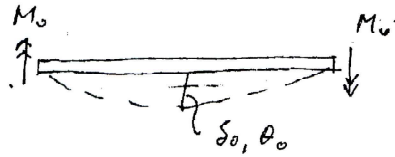
Notes: 1) $\overline{Eq. (5.7.22)}$

$$A_F = \frac{1}{1 - M_o/M_{ocr}}$$

$\longleftrightarrow \overline{Eq. (2.6.20)}$

$$A_F = \frac{1}{1 - P/P_e}$$

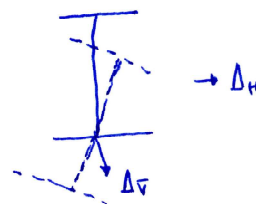
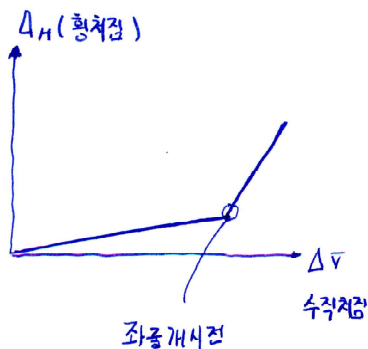
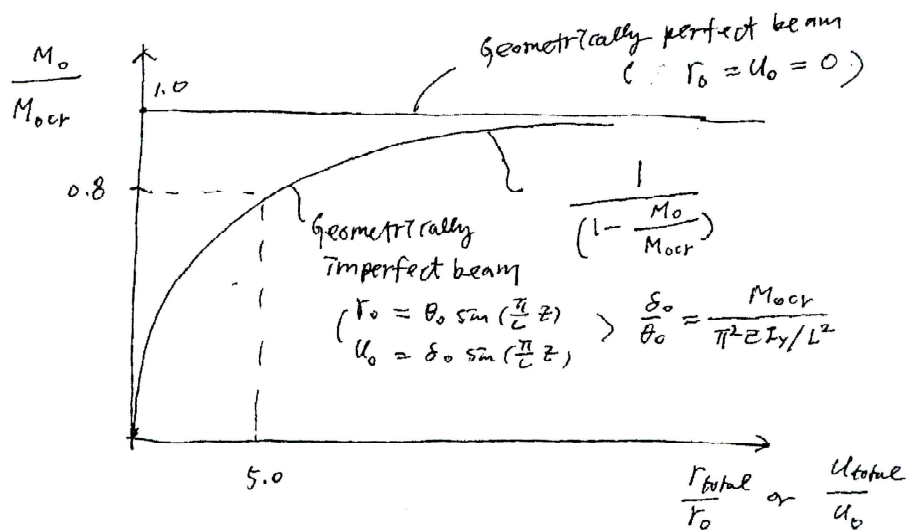
(30)



- The similarity of $\overline{Eq. (5.7.22)}$ and $\overline{Eq. (2.6.20)}$ should be noted.
- An expression similar to that of $\overline{Eq. (5.7.22)}$ can be derived for a geometrically imperfect I-beam under a uniform moment.

2) Load-deflection relationship of an initially crooked beam ($\overline{Fig. 5.26}$)

실측시
이런정도
인지해야



- (3) For simply supported I-beams subjected to equal and opposite end moments, if there are no residual stresses the distribution of yielding across the section is symmetric about the horizontal principal axes and is constant along the entire length of the beam.



$$M_{ocr} = \frac{\pi}{L} \sqrt{(EI_y)_e (GJ)_e} \sqrt{1 + \frac{\pi^2 (EC_w)_e}{L^2 (GJ)_e}} \quad \dots (5.8.1) \quad \star$$

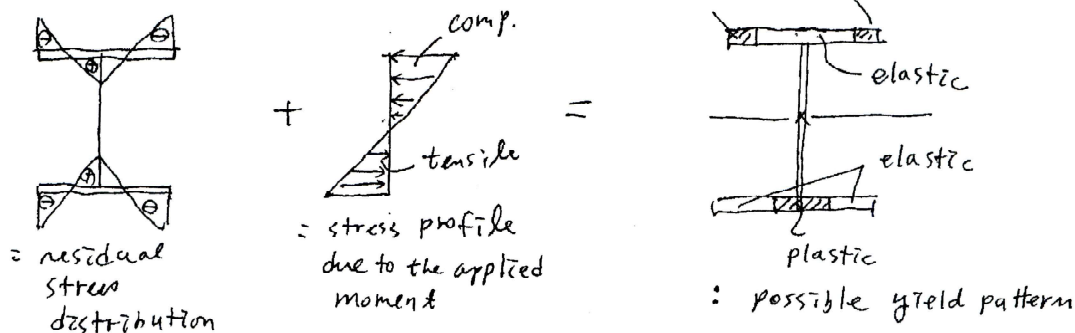
EH
Section
Approach

→ where $(EI_y)_e$, $(GJ)_e$, and $(EC_w)_e$ are the effective bending rigidity, torsional rigidity, and warping rigidity, respectively.

(Flint 1953, 2.10 of elastic core theory 1871)

- (4) However, the presence of residual stress greatly reduces the lateral torsional buckling strength of the beam in the inelastic range. (Fig. 5.27 (b) 1/3)

- (5) Eq. (5.8.1) is not applicable for beams with residual stresses, since this equation is only valid doubly symmetric sections. If residual stresses are considered in the analysis, the distribution of yielding across the cross section will not be symmetric about the horizontal principal axis.

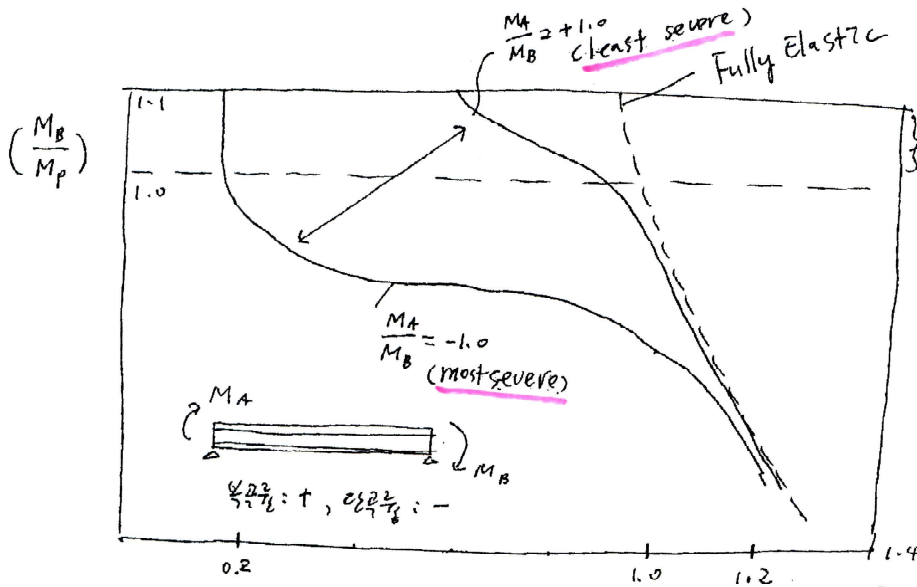


The discussions of this type of section → Johnston (1976)

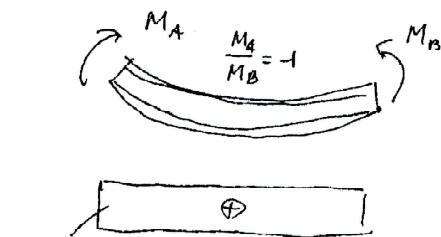
- (6) To obtain the inelastic buckling loads for beams with a more general loading case other than that of equal and opposite end moments, recourse must be had to numerical methods (Chen-Austa 1977; Galambos 1963; Lay-Galambos 1967).
↳ The in-plane bending moment will vary along the beam, so the distribution of yielding will also vary from cross section to cross section.

(7) Fig. 5.28 (P. 354)

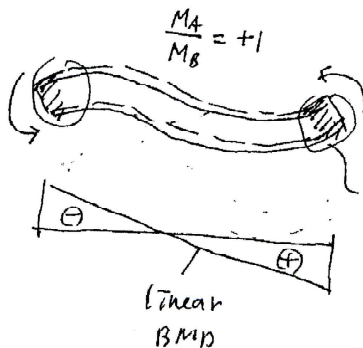
↑ Numerical solutions for some hot-rolled I-beams
With a number of different loading arrangement
(by Nethercot and Trahair (1976))



변형행위 한이 따른
강도증진분 복각
설계강도를 무시 가능
(2차 정해석
설계에는 고려하지 않,
Capacity design)



Constant BMD
(모의 전구간이 겹쳐서
항상이 일어난다)
∴ most severe moment
gradient



∴ least severe moment
gradient.

modified slenderness
I (3) 쪽의 (X)와 (Y)로

confined
yielding

↪ 재축방향으로

(EI)_e, (GJ)_e ... 값이 변동!

★ It is quite evident that the lateral instability behavior of
real beams is complex.

↳ Certain simplifying assumptions are inevitable
to make use of the analytical results for design purposes.

Note: 현재 실무설계에서 탄성해석에 의한
C_b factor를 비탄성 LTB의 강도에도
그대로 사용 → 확인해 볼 문제???

"C_b to be constant"

5.9 Design curves for steel Beams.

Some of the important parameters of the LTB behavior

elastic vs.
↓ inelastic

- ↳ (1) L_b , (2) the cross-sectional geometry, (3) the material behavior, (4) the magnitude, type, and location of the applied loads, and (5) the type of lateral supports, as well as the end conditions of the beam, etc.

↳ Simplifying inevitable for design purposes

5.9.1 AISC-ASD

5.9.2 AISC-PD

> 사용 (2241 7.9.5)

5.9.3 AISC-LRFB ← limit state-based

Three possible types of failure limits

- (1) plastic yielding
- (2) lateral instability
- (3) local buckling

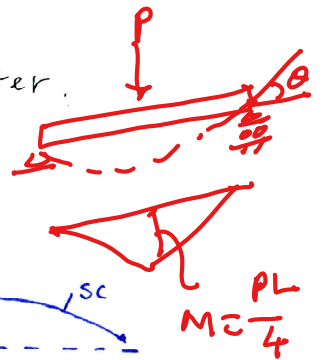
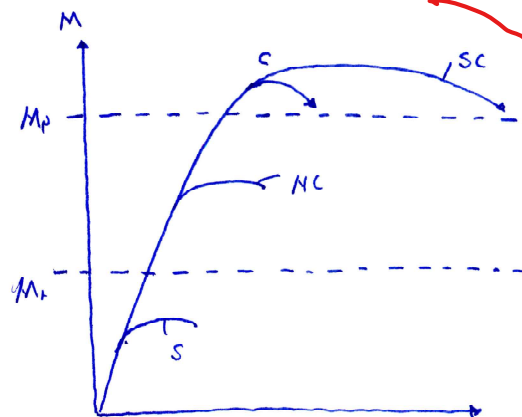
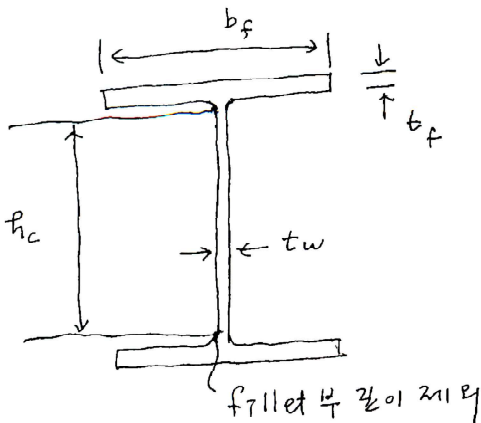
"Global" buckling

(1) To avoid local buckling,

$$FLB \leftarrow \frac{b_f}{2t_f} \leq \frac{65}{\sqrt{F_y}} \quad \dots (5.9.31)$$

$$WLB \leftarrow \frac{h_c}{t_w} \leq \frac{640}{\sqrt{F_y}} \quad \dots (5.9.32)$$

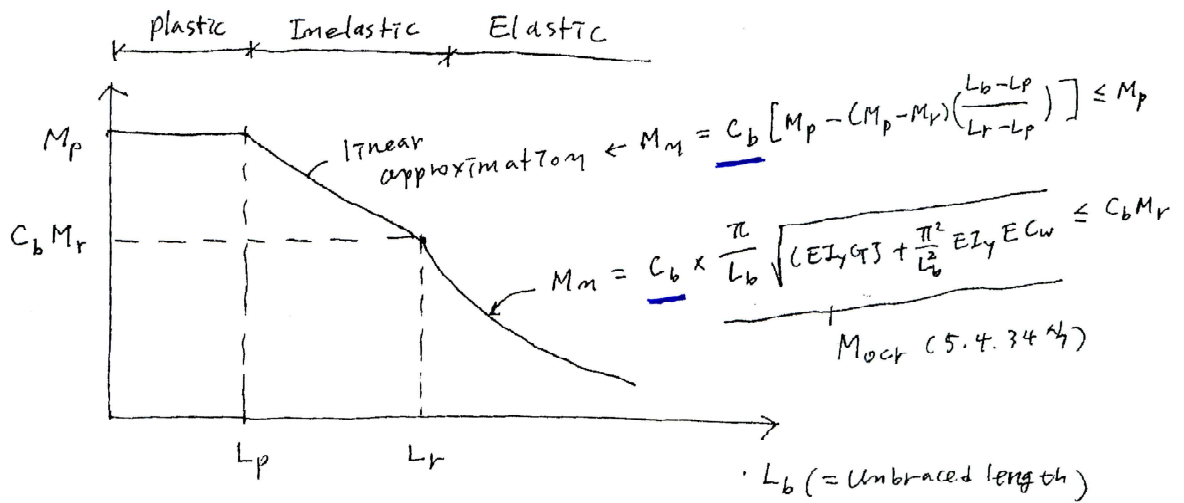
compact section criterion



"60 to 65" range

이이 "기둥 및 보의 안정성" 부분은 ppt에서
삭제

(2) LTB limit state strength (H강의 강도 설계) (35)



$$L_p = \frac{300 r_y}{\sqrt{F_y}} \quad ; \quad L_r = \frac{r_y X_1}{(F_y - F_r)} \sqrt{1 + \sqrt{1 + X_2 (F_y - F_r)^2}} \quad \text{--- (5.9.34)}$$

$\uparrow (5.9.33)$

$$C_b = 1.75 + 1.05 \left(\frac{M_A}{M_B} \right) + 0.3 \left(\frac{M_A}{M_B} \right)^2 \leq 2.3 \quad \text{--- (5.5.2)}$$

$\uparrow$ Equivalent (uniform) moment factor by Salvadori (1955)

Now
Replaced by
Kirby
- Nethercot

$M_r = S_x (F_y - F_r) \leftarrow$ the transition moment from elastic to inelastic behavior to account for the presence of residual stress (F_r).

(1979)
P.333

$\uparrow$ "탄성 한계 항복강도 모멘트"

Notes : i) L_r 값은 $C_b = 1.0$ 으로 하여 "보수적" 산정됨.

$$M_r = S_x (F_y - F_r) = \frac{\pi}{L_r} \sqrt{EI_y GJ + \frac{\pi^2}{L_r^2} EI_y EC_w}$$

위식에서 L_r 이

M_{ocr} (균등모멘트를 받는 경우의 탄성 항복강도 모멘트)

이하의 풀이 $L_r =$  --- (5.9.34)

$\uparrow$
교차식
(5.4.34) 식

ii) C_b factor는 양단부 모멘트의 크기 및 부호가

다른 경우 이룰 등가치 : 균등모멘트로 변환해 주는 계수임.

HW#

(5.9.34)의

L_r, X_1, X_2

(1.5023)

expression 구할 것.

$\rightarrow$ 이미 안됨

$\rightarrow$ "최초의 AISI-LRFD 1999"에서는 고려

일반화 했는 5.5.22 식 (P.333) 으로 대체

$\uparrow$ Kirby-Nethercot (1979)"

ALSC-LRFD 최신판 (3rd ed.) : ALSC-LRFD 1999

(36)

CHAPTER F

BEAMS AND OTHER FLEXURAL MEMBERS

2이오도

본질적으로

동일

This chapter applies to compact and noncompact prismatic members subject to flexure and shear. For members subject to combined flexure and axial force, see Section H1. For members subject to fatigue, see Section K3. For members with slender compression elements, see Appendix B5. For web-tapered members, see Appendix F3. For members with slender web elements (plate girders), see Appendix G.

F1. DESIGN FOR FLEXURE

The nominal flexural strength M_n is the lowest value obtained according to the limit states of: (a) yielding; (b) lateral-torsional buckling; (c) flange local buckling; and (d) web local buckling. For laterally braced compact beams with $L_b \leq L_p$, only the limit state of yielding is applicable. For unbraced compact beams and noncompact tees and double angles, only the limit states of yielding and lateral-torsional buckling are applicable. The lateral-torsional buckling limit state is not applicable to members subject to bending about the minor axis, or to square or circular shapes.

This section applies to homogeneous and hybrid shapes with at least one axis of symmetry and which are subject to simple bending about one principal axis. For simple bending, the beam is loaded in a plane parallel to a principal axis that passes through the shear center or the beam is restrained against twisting at load points and supports. Only the limit states of yielding and lateral-torsional buckling are considered in this section. The lateral-torsional buckling provisions are limited to doubly symmetric shapes, channels, double angles, and tees. For lateral-torsional buckling of other singly symmetric shapes and for the limit states of flange local buckling and web local buckling of noncompact or slender-element sections, see Appendix F1. For unsymmetric shapes and beams subject to torsion combined with flexure, see Section H2. For biaxial bending, see Section H1.

1. Yielding $L_b \leq L_p$ for compact sections.

The flexural design strength of beams, determined by the limit state of yielding, is $\phi_b M_n$:

$$\phi_b = 0.90$$

$$M_n = M_p \quad (F1-1)$$

where

M_p = plastic moment ($= F_y Z \leq 1.5 M_y$ for homogeneous sections), kip-in. (N-mm)
 M_y = moment corresponding to onset of yielding at the extreme fiber from an elastic stress distribution ($= F_y S$ for homogeneous section and $F_{yf} S$ for hybrid sections), kip-in. (N-mm)

See Section B10 for further limitations on M_n where there are holes in the tension flange. (37)

2. Lateral-Torsional Buckling LTB

This limit state is only applicable to members subject to major axis bending. The flexural design strength, determined by the limit state of lateral-torsional buckling, is $\phi_b M_n$:

$$\phi_b = 0.90$$

M_n = nominal flexural strength determined as follows

2a. Doubly Symmetric Shapes and Channels with $L_b \leq L_r$

The nominal flexural strength is:

$$M_n = C_b \left[M_p - (M_p - M_r) \left(\frac{L_b - L_p}{L_r - L_p} \right) \right] \leq M_p \quad (\text{F1-2})$$

where

L_b = distance between points braced against lateral displacement of the compression flange, or between points braced to prevent twist of the cross section, in. (mm) } Simplistic 하게 규정하고 있음.

L_p = limiting laterally unbraced length as defined below, in. (mm)

L_r = limiting laterally unbraced length as defined below, in. (mm)

M_r = limiting buckling moment as defined below, kip-in. (N-mm)

In the above equation, C_b is a modification factor for non-uniform moment diagrams where, when both ends of the beam segment are braced:

$$C_b = \frac{12.5 M_{\max}}{2.5 M_{\max} + 3 M_A + 4 M_B + 3 M_C} \quad (\text{F1-3})$$

where

↑ Kirby-Nethercot (1999)

$M_{\max}$ = absolute value of maximum moment in the unbraced segment, kip-in. (N-mm)

M_A = absolute value of moment at quarter point of the unbraced segment, kip-in. (N-mm)

M_B = absolute value of moment at centerline of the unbraced beam segment, kip-in. (N-mm)

M_C = absolute value of moment at three-quarter point of the unbraced beam segment, kip-in. (N-mm)

✓ C_b is permitted to be conservatively taken as 1.0 for all cases. Equations F1-4 and F1-6 are conservatively based on $C_b = 1.0$. For cantilevers or overhangs where the free end is unbraced, $C_b = 1.0$. ✓ Very Conservative

The limiting unbraced length, L_p , shall be determined as follows. L See Table 5.4 in the text

(a) For I-shaped members including hybrid sections and channels:

$$L_p = \frac{300 r_y}{\sqrt{F_y}} \quad (\text{in ksi}) \quad \leftarrow L_p = 1.76 r_y \sqrt{\frac{E}{F_y}} \quad \leftarrow \text{AISC-LRFD 1999}$$

(F1-4)

(한글) 미러
복합하중
표준을 사용)

(b) For solid rectangular bars and box sections:

$$L_p = \frac{0.13 r_y E}{M_p} \sqrt{JA} \quad (F1-5)$$

where

A = cross-sectional area, in.² (mm²)

J = torsional constant, in.⁴ (mm⁴)

The limiting laterally unbraced length L_r and the corresponding buckling moment M_r shall be determined as follows.

(a) For doubly symmetric I-shaped members and channels:

$$L_r = \frac{r_y X_1}{F_L} \sqrt{1 + \sqrt{1 + X_2 F_L^2}} \quad (F1-6)$$

$$M_r = F_L S_x \quad (F1-7)$$

where

$$X_1 = \frac{\pi}{S_x} \sqrt{\frac{E G J A}{2}} \quad (F1-8)$$

$$X_2 = 4 \frac{C_w}{I_y} \left(\frac{S_x}{G J} \right)^2 \quad (F1-9)$$

S_x = section modulus about major axis, in.³ (mm³)

E = modulus of elasticity of steel, 29,000 ksi (200 000 MPa)

G = shear modulus of elasticity of steel, 11,200 ksi (77 200 MPa)

F_L = smaller of $(F_y - F_r)$ or F_{yw} , ksi (MPa)

F_r = compressive residual stress in flange; 10 ksi (69 MPa) for rolled shapes, 16.5 ksi (114 MPa) for welded built-up shapes

F_y = yield stress of flange, ksi (MPa)

F_{yw} = yield stress of web, ksi (MPa)

I_y = moment of inertia about y-axis, in.⁴ (mm⁴)

C_w = warping constant, in.⁶ (mm⁶)

(b) For solid rectangular bars and box sections:

$$L_r = \frac{2 r_y E \sqrt{JA}}{M_r} \quad (F1-10)$$

40
Warping

$$M_r = F_y S_x \quad (F1-11)$$

(39)

2b. Doubly Symmetric Shapes and Channels with $L_b > L_r$

The nominal flexural strength is:

$$M_n = M_{cr} \leq M_p \quad (F1-12)$$

where M_{cr} is the critical elastic moment, determined as follows.

(a) For doubly symmetric I-shaped members and channels:

$$M_{cr} = C_b \frac{\pi}{L_b} \sqrt{EI_y GJ + \left(\frac{\pi E}{L_b} \right)^2 I_y C_w} \quad (F1-13)$$

$$= \frac{C_b S_x X_1 \sqrt{2}}{L_b / r_y} \sqrt{1 + \frac{X_1^2 X_2}{2(L_b / r_y)^2}}$$

(b) For solid rectangular bars and symmetric box sections:

$$M_{cr} = \frac{57000 C_b \sqrt{JA}}{L_b / r_y} \quad (F1-14)$$

2c. Tees and Double Angles

For tees and double-angle beams loaded in the plane of symmetry:

$$M_n = M_{cr} = \frac{\pi \sqrt{EI_y GJ}}{L_b} \left[B + \sqrt{1 + B^2} \right] \quad (F1-15)$$

where

$$M_n \leq 1.5M_y \text{ for stems in tension}$$

$$M_n \leq 1.0M_y \text{ for stems in compression}$$

$$B = \pm 2.3(d/L_b) \sqrt{I_y / J} \quad (F1-16)$$

The plus sign for B applies when the stem is in tension and the minus sign applies when the stem is in compression. If the tip of the stem is in compression anywhere along the unbraced length, use the negative value of B .

3. Design by Plastic Analysis→ 최대 허용 모멘트 (철골강의 소트, 대학원)

Design by plastic analysis, as limited in Section A5.1, is permitted for a compact section member bent about the major axis when the laterally unbraced length L_b of the compression flange adjacent to plastic hinge locations associated with the failure mechanism does not exceed L_{pd} , determined as follows.

(a) For doubly symmetric and singly symmetric I-shaped members with the compression flange equal to or larger than the tension flange (including hybrid members) loaded in the plane of the web:

$$L_{pd} = \left[0.12 + 0.076 \left(\frac{M_1}{M_2} \right) \right] \left(\frac{E}{F_y} \right) r_y \quad (\text{F1-17})$$

where

F_y = specified minimum yield stress of the compression flange, ksi (MPa)

M_1 = smaller moment at end of unbraced length of beam, kip-in. (N-mm)

M_2 = larger moment at end of unbraced length of beam, kip-in. (N-mm)

r_y = radius of gyration about minor axis, in. (mm)

(M_1 / M_2) is positive when moments cause reverse curvature and negative for single curvature

(b) For solid rectangular bars and symmetric box beams:

$$L_{pd} = \left[0.17 + 0.10 \left(\frac{M_1}{M_2} \right) \right] \left(\frac{E}{F_y} \right) r_y \geq 0.10 \left(\frac{E}{F_y} \right) r_y \quad (\text{F1-18})$$

There is no limit on L_b for members with circular or square cross sections nor for any beam bent about its minor axis.

In the region of the last hinge to form, and in regions not adjacent to a plastic hinge, the flexural design strength shall be determined in accordance with Section F1.2.

F2. DESIGN FOR SHEAR

This section applies to unstiffened webs of singly or doubly symmetric beams, including hybrid beams, and channels subject to shear in the plane of the web. For the design shear strength of webs with stiffeners, see Appendix F2 or Appendix G3. For shear in the weak direction of the shapes above, pipes, and unsymmetric sections, see Section H2. For web panels subject to high shear, see Section K1.7. For shear strength at connections, see Sections J4 and J5.

1. Web Area Determination

The web area A_w shall be taken as the overall depth d times the web thickness t_w .

2. Design Shear Strength

The design shear strength of unstiffened webs, with $h / t_w \leq 260$, is $\phi_v V_n$,

where

$$\phi_v = 0.90$$

V_n = nominal shear strength defined as follows.

(a) For $h / t_w \leq 2.45 \sqrt{E / F_{yw}}$

$$V_n = 0.6 F_{yw} A_w \quad (\text{F2-1})$$

(b) For $2.45 \sqrt{E / F_{yw}} < h / t_w \leq 3.07 \sqrt{E / F_{yw}}$

(대선 뒤로 넘겨주세요)

(41)

5.10 Other design approaches

→ 권익동 (SSRC, European ...)

← Eq. (2.11.17)

... Ramtal-Mazhar form 이거나

(보의 횡관성률 I_x 증가 시 I_x 의 stability 계수 K 를

증가시키는 것과 같이 $\frac{P}{P_y} \leq \frac{M_x}{M_p}$ 이다

대처하는 형식을 제안)

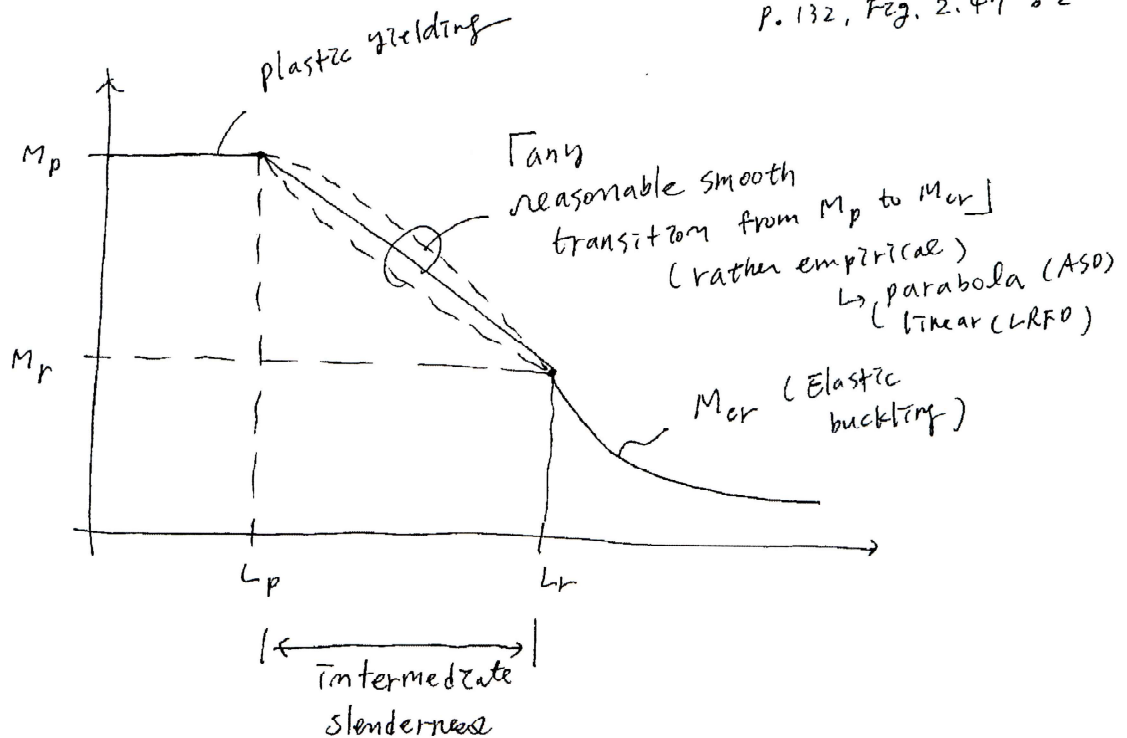
→ Eq. (5.10.1)

and $\gamma = \alpha (\lambda - 0.15)$

$\alpha = 0.293$ (SSRC curve 2)

P. 132, Fig. 2.47 참조

Note:



* The LRFD beam curve is generally more "liberal" and much simpler than that of the ASD beam curve.

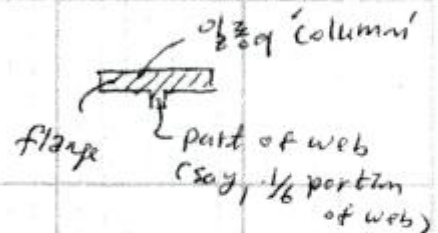
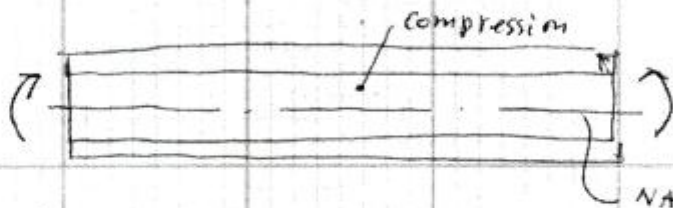
< 비탄성 보강자료 Inelastic LTB 보강자료 >

- The same concepts of extending the "elastic buckling theory" for axially loaded members to the cases where portions of the column cross section are yielded also apply to the LTB of beams.

→ Effective section approach

- The theoretical relationships between the tangent modulus, the reduced modulus, and the ultimate loads are also valid for perfectly straight beams, as are the effects of initial imperfections of geometry and of residual stresses.

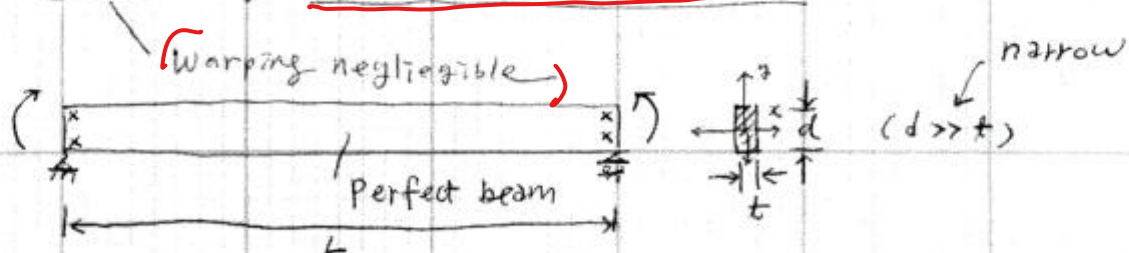
ex)



- Far more difficult because of the more complex geometry and the presence of both lateral and torsional deformations

→ Inelastic LTB studies (for example, Galambos 1988, Trahair 1993)

- A simple analytical solution of thin rectangular beam using "effective section concept".

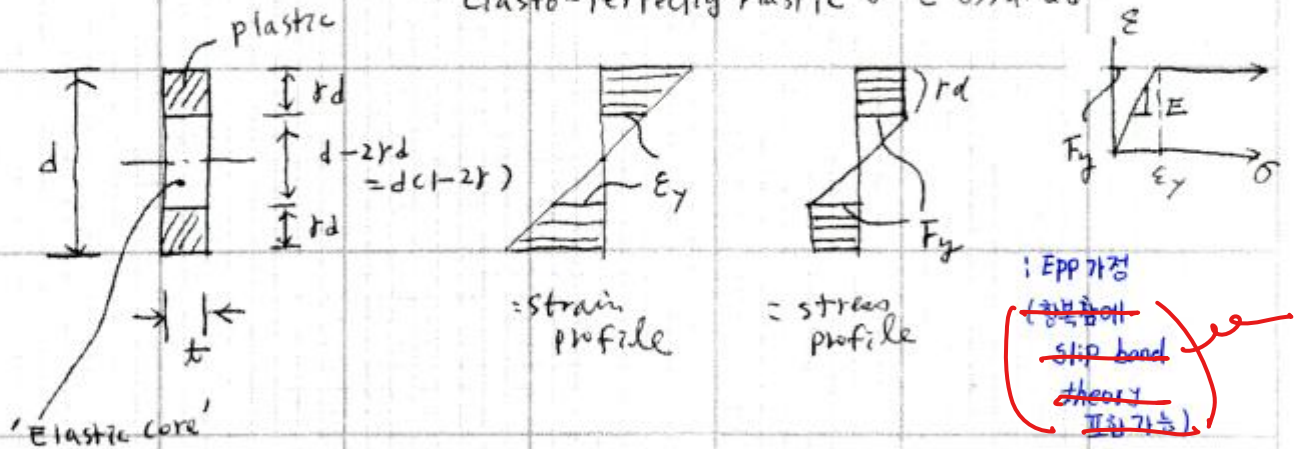


(1)

$M_{cr} (= \text{elastic LTB strength})$
 $= \frac{\pi}{L} \sqrt{EI_y GJ} \quad \dots (1)$

(7i) Concept of elastic core (or effective section)

"Elasto-Perfectly Plastic σ - ϵ assumed"



M_p (= partially plastic strength)

$$= 2 \times t \left[\underbrace{rd \left(\frac{d}{2} - rd \right)}_{\text{plastic}} + \underbrace{\frac{1}{2} \left(\frac{d}{2} - rd \right) \times \left\{ \frac{2}{3} \times \frac{1}{2} \right\} \left(\frac{d}{2} - rd \right)}_{\text{elastic}} \right] F_y$$

$$= (1 + 2r - 2r^2) \left(\frac{t d^2}{6} F_y \right) = M_y = (1 + 2r - 2r^2) M_y$$

기호 혼동치 말것

$$\text{When } r=0, M_p = M_y = \frac{t d^2}{6} F_y (= S \cdot F_y)$$

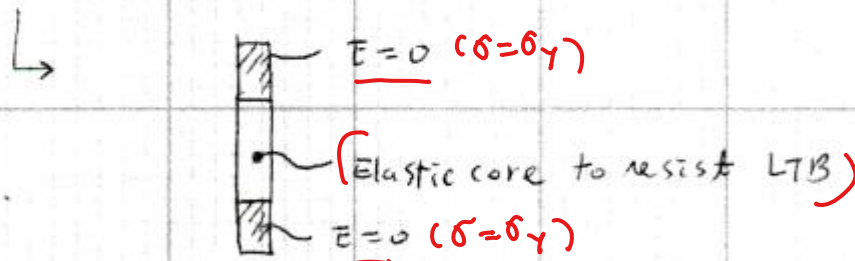
$$r=0.5, M_p = M_p = \frac{t d^2}{4} F_y (= Z \cdot F_y) = \left(\frac{3}{2} \right) M_y$$

shape factor

$$\therefore \frac{M_p}{M_y} = \frac{2}{3} [1 + 2r(1-r)] \quad \text{--- (1)}$$

to resist

The cross section available for LTB will be the elastic core.



$\frac{L}{t}$, $(I_y)_e$ 및 $(J)_e$ 는 단면적 제곱의 값을 사용할 수 있으므로

(즉 $r=0$ 인 경우의 사용하므로)

(2) 식에서 $r=0$ 을 대입하면 식 ;

$$\frac{M_{cr}}{M_p} = \frac{1.30(E/F_y)(t/d)}{(L/t)} \quad \text{if } \frac{L}{t} \geq 1.95 \left(\frac{E}{F_y} \right) \left(\frac{t}{d} \right) \quad (14)$$

(::) $(L/t) < (L/t)_{limit}$ 이면 'Inelastic' LTB가 발생하므로
'공' $0 < r \leq 0.5$ 인 경우 에 사용한다.

(2) 식을 적용한다

목재원시강비 (L/t) 대 목재원시강비강도 (M_{cr}/M_p) 의 관계는
항상 2가지 유형으로 나누어지는데 (2) 식을 적용할 수 있어야 한다.

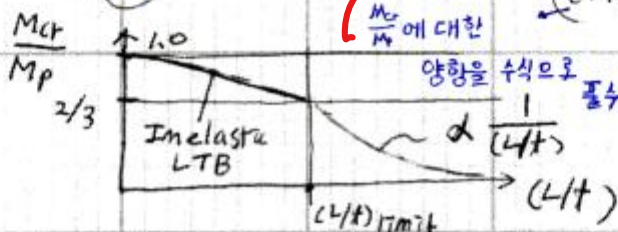
(1) 식의 분자 M_r 는 순모멘트가 r 만큼 진행되었을 때의 LTB 강도에
대응하는 값이므로 $(M_r = M_{cr})$ (1) 식을 r 이 대입할 수 있다,

$$r = \frac{1}{2} \left[1 - \sqrt{3 - 3 \left(\frac{M_{cr}}{M_p} \right)} \right] \quad (5)$$

(5) $\rightarrow$ (2) 이 대입하면 (L/t) 이 대입할 수 있다

$$\frac{2}{3} \leq \frac{M_{cr}}{M_p} \leq 1.0$$

$$\left(\frac{L}{t} \right) = 1.30 \left(\frac{F_y}{E} \right) \left(\frac{t}{d} \right) \frac{\sqrt{3 - 3 \left(\frac{M_{cr}}{M_p} \right)}}{\left(\frac{M_{cr}}{M_p} \right)} \quad \text{if } \frac{L}{t} < 1.95 \left(\frac{E}{F_y} \right) \left(\frac{t}{d} \right) \quad (6)$$



ex) $E/F_y = 29000/50$, $d/t = 10$
 $(L/t)_{limit} \approx 115$