

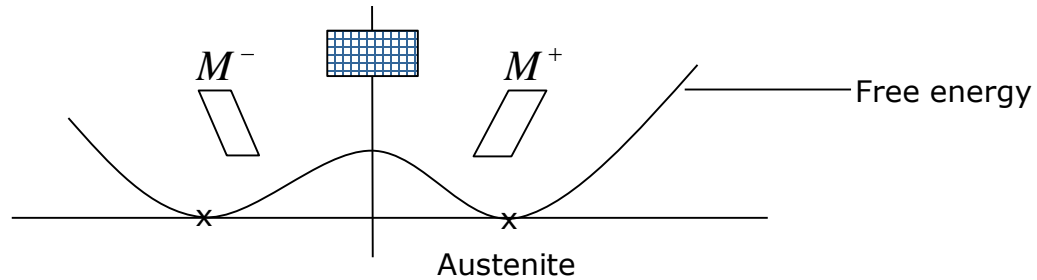
Shape memory alloys

❖ Shape Memory Alloys

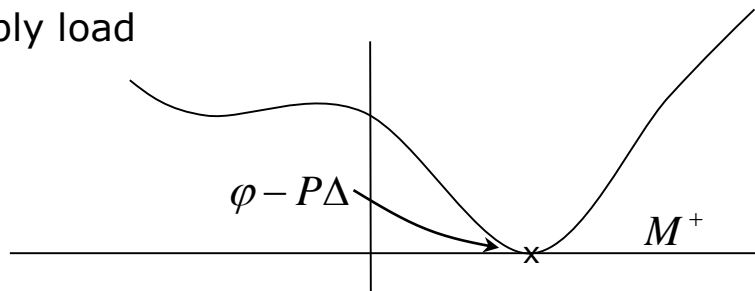
- has an internal solid state phase transformation mechanisms which allows 2 stable states depending on of applied stress and temperatures
- Nickel – Titanium (“Nitinol”)
 - utilized in robot applications –
hose clamps
Large space structure vibration control
adaptive acoustics
 - current :
 - Slow adoptive structures
 - twist control of rotors & propellers
 - adoptive fixed-wing lifting surfaces
 - airfoil twist control
- The phenomena
 - stress + temperature induced martensitic phase transformation
 - depends on comp, temperature, stress, history temperature

Shape memory alloys

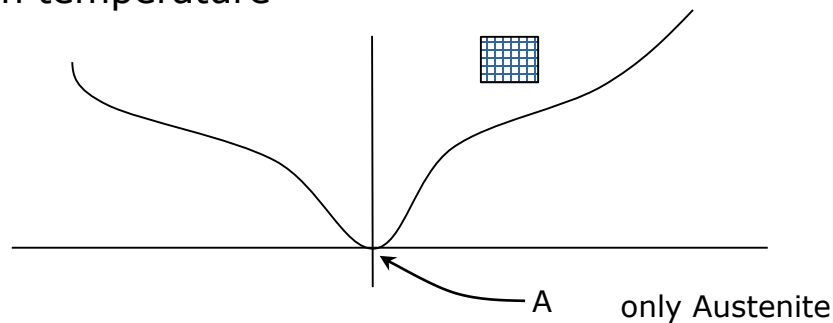
- Heuristic phenomenology
 - room temperature



- apply load



- high temperature



Shape memory alloys

- Temperature + stress induced phase transformation
- constitutive Relation

$$\sigma - \sigma_0 = d(\varepsilon - \varepsilon_0) + \theta(T - T_0) + \Omega(\xi - \xi_0)$$

↓
Mechanical

↓
Thermal

↓
Phase change

ξ = % of martensite

- martensite function

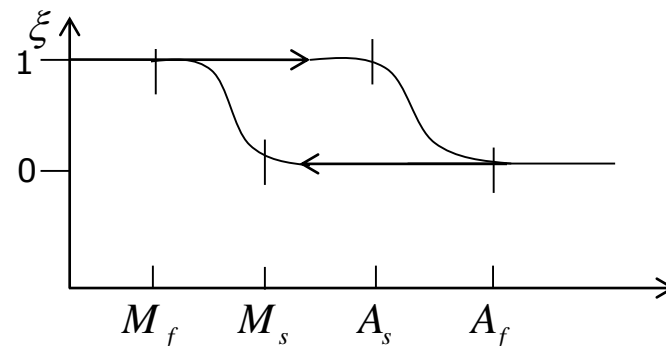
$$\begin{cases} \xi = 1 & \text{All martensite} \\ \xi = 0 & \text{All austenite} \end{cases}$$

- look at phase transformation

$$\xi = f(T, \sigma)$$

First, $\xi = f(T)$

Transformation is characterized by 4 temperatures



M_f : martensite finish

M_s : martensite start

A_s : Austenite start

A_f : Austenite finish

Shape memory alloys

two types of material

$$1) A_s > M_s$$

$$2) A_s < M_s$$

where, in room temperature

$$M \rightarrow A : \xi = \frac{1}{2} \left\{ \cos \left[a_A (T - A_s) \right] + 1 \right\}$$

$$A \rightarrow M : \xi = \frac{1}{2} \left\{ \cos \left[a_M (T - M_f) \right] + 1 \right\}$$

$$A_s < T < A_f$$

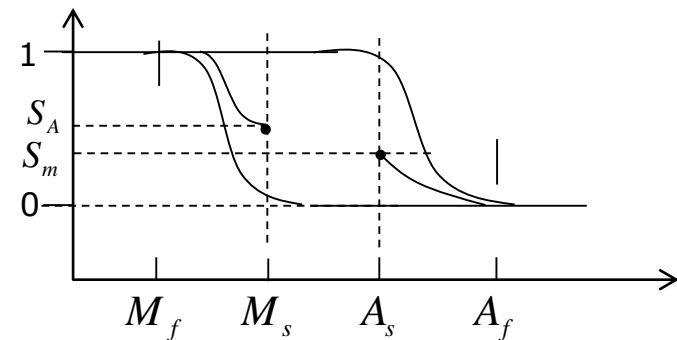
$$M_f < T < M_s$$

say $M - A \quad \xi_0 = \xi_m$

$$\xi = \frac{\xi}{2} \left\{ \cos \left[a_A (T - A_s) \right] + 1 \right\}$$

$A - M \quad \xi_0 = \xi_m$

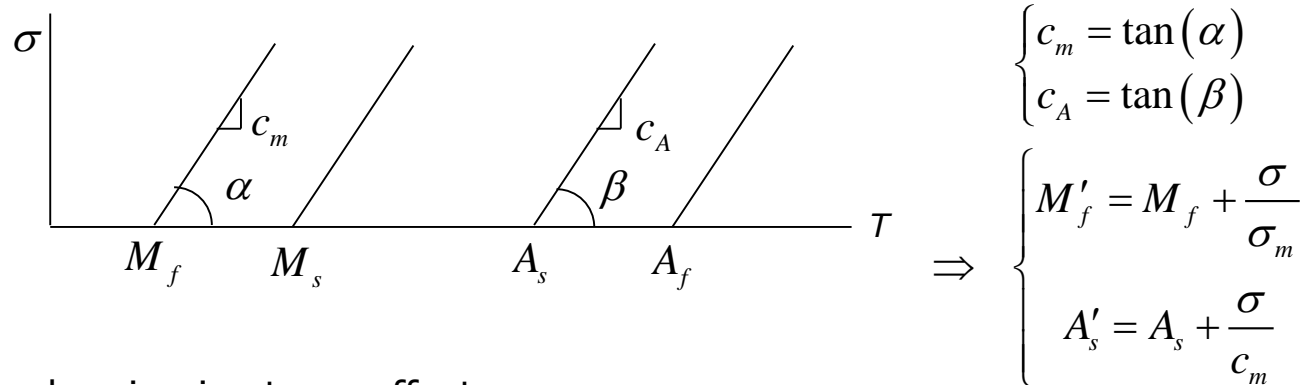
$$\xi = \frac{1 - \xi_A}{2} \left\{ \cos \left[a_M (T - M_f) \right] \right\} + \frac{1 + \xi_A}{2}$$



Shape memory alloys

➤ Stress dependence of ξ

- Transformation temperatures increased with applied stress



plugging in stress effects

$$M - A \quad \zeta = \frac{\zeta_m}{2} \left\{ \cos \left[a_A (T - A_s) - b_A \sigma \right] + 1 \right\}$$

$$A - M \quad \zeta = \frac{1 - \zeta_A}{2} \cos \left[a_M (T - M_f) + b_M \sigma \right] + \frac{1 + \zeta_A}{2}$$

$$b_A = -\frac{a_A}{c_A}, \quad b_M = -\frac{a_M}{c_A}$$

$$M - A \quad c_A (T - A_s) - \frac{\pi}{|b_A|} \leq \sigma \leq c_A (T - A_s)$$

$$A - M \quad c_M (T - M_f) - \frac{\pi}{|b_M|} \leq \sigma \leq c_M (T - M_f)$$

$$c_M (T - M_s)$$

Shape memory alloys

Constitutive Modeling

1-D

Assume $M_f < M_s < T_R < A_S < A_f$

- Case A

- Isothermal loading

- all austenite ($S=0$)

- initial conditions

$$\sigma_0 = 0, \quad \zeta_0 = 0, \quad \zeta = 0, \quad T = T_0 \text{ isothermal}$$

$$\sigma - \sigma_0 = d(\varepsilon - \varepsilon_0) + \theta(T - T_0) + \Omega(\zeta - \zeta_0)$$

to start

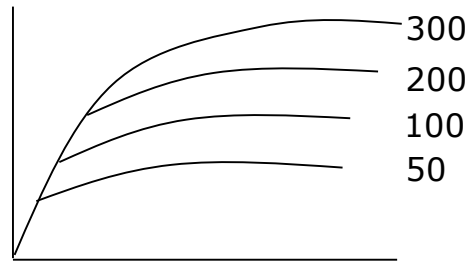
$$\sigma = D\varepsilon : \text{linear elastic Austenite}$$

→ fire until stresses reaches range where martensite start

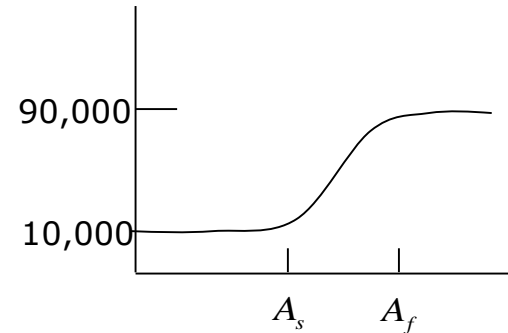
$$\sigma_{1,M} = c_M (T_0 - M_s) \rightarrow \varepsilon_{1,M} = \sigma_{1,M} / D$$

Shape memory alloys

Stress-strain



Yield strength



Transformation

once it begins, $\sigma - \sigma_0 = D(\varepsilon - \varepsilon_0) + \Omega(\zeta - \zeta_0)$

$$\begin{cases} \sigma_0 = \sigma_{\text{lim}} \\ \varepsilon = \varepsilon_{\text{lim}} \\ \zeta_0 = 0 \end{cases} \Rightarrow \sigma = D\varepsilon + \Omega(\zeta)$$

where,

$$\zeta = \frac{1 - \zeta_A}{2} \cos \left[a_M \left(T - \left(M_f + \frac{\sigma}{c_M} \right) \right) \right] + \frac{1 + S_A}{2}$$

This progresses until $\zeta = 1$ or wherever

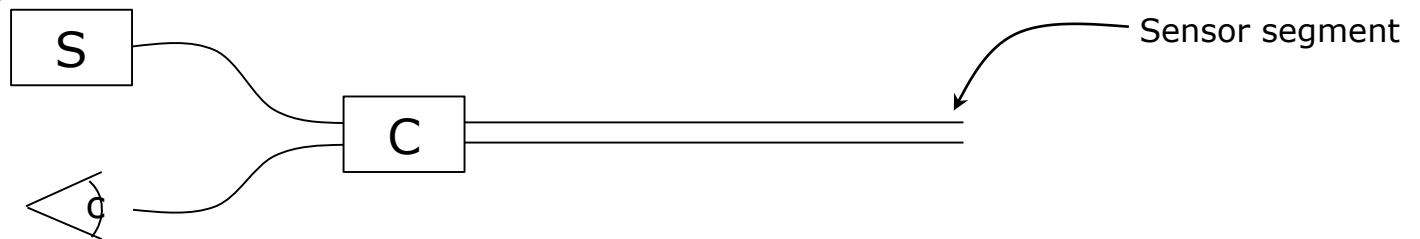
$$\zeta = 1 \Rightarrow \sigma = c_M (T_0 - M_f)$$

Fiber Optics Sensor

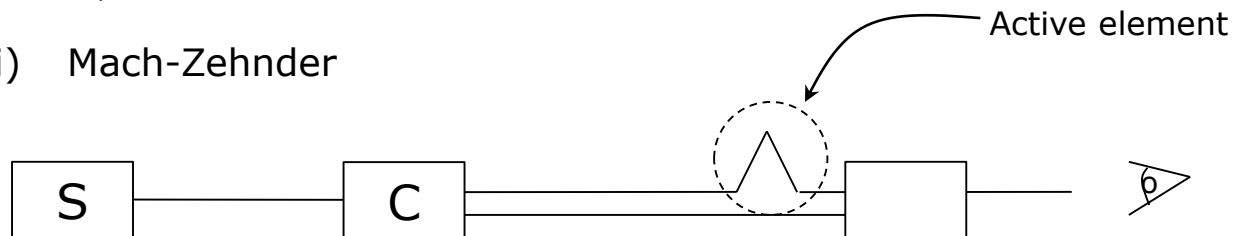
Fiber optic sensor

- Intensometric
- Interferometric
- Polarimetric
- Modalmetric
- Spectral
- OTDR
- Interferometric
 - 3 types

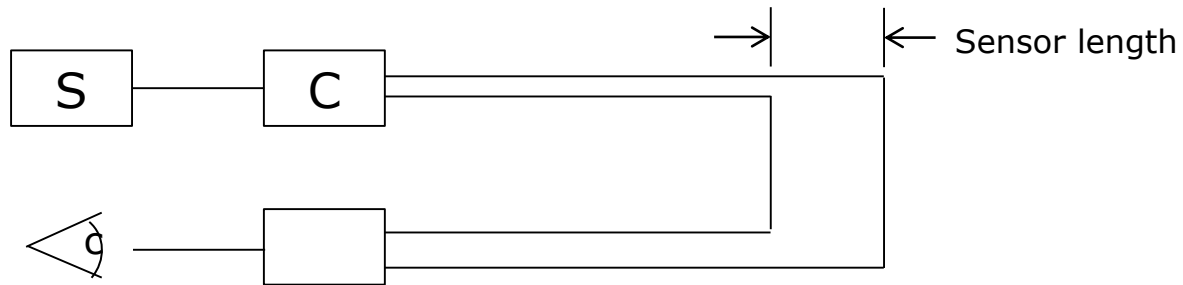
i) Michelson



ii) Mach-Zehnder



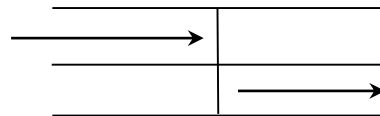
Fiber Optics Sensor



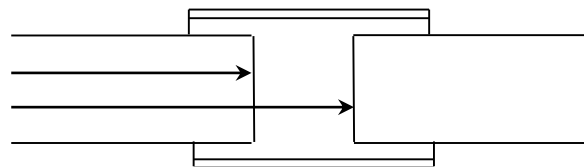
iii) Fabrey-Revot



- intrinsic



- extrinsic

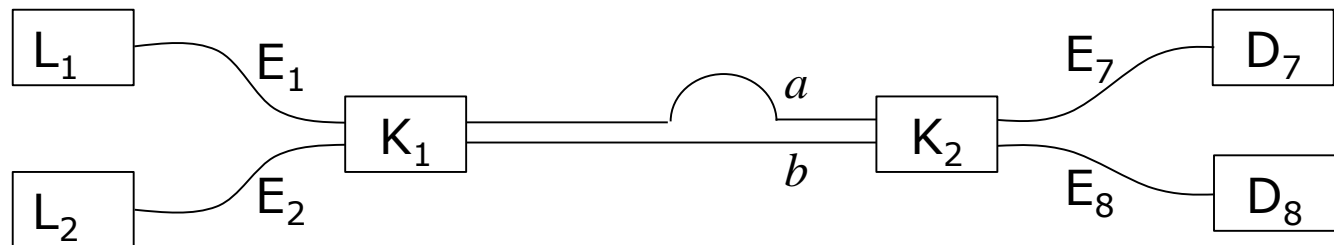


Reference logic fiber microlength

Fiber Optics Sensor

Simple model

Model of Interferometric Sensor



Transmission matrices

$$E_{in} = \begin{bmatrix} E_1 \\ E_2 \end{bmatrix}, \quad E_{out} = \begin{bmatrix} E_7 \\ E_8 \end{bmatrix} = \underset{2 \times 2}{[K_2]} \underset{2 \times 2}{[T]} \underset{2 \times 2}{[K_1]} E_{in}$$

For standard 3db coupler,

- coupler

$$K_1 = K_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & i \\ i & 1 \end{bmatrix}$$

- path (no attenuation)

$$T = \begin{bmatrix} e^{i\varphi_A} & 0 \\ 0 & e^{i\varphi_B} \end{bmatrix}$$

φ_A : phase difference through path a

φ_B : phase difference through path b

Fiber Optics Sensor

Substitution

- $E_2 = 0$

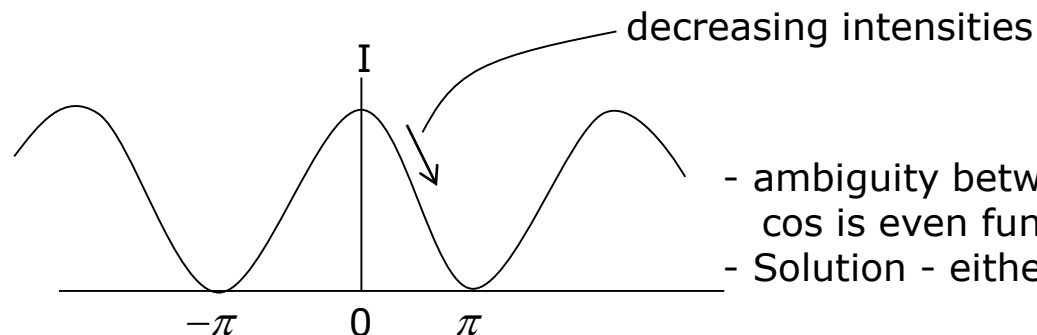
$$\begin{bmatrix} E_7 \\ E_8 \end{bmatrix} = \begin{bmatrix} E_1 \{ e^{i\varphi_A} - e^{i\varphi_B} \} / 2 \\ iE_1 \{ e^{i\varphi_A} - e^{i\varphi_B} \} / 2 \end{bmatrix}$$

intensities ↖ u (for attenuation)

$$I_7 = I_1 \left[1 - \cos(\varphi_A - \varphi_B) \right] / 2 = I_1 \sin^2 \left(\frac{\Delta\varphi}{2} \right)$$

$$I_8 = I_1 \left[1 + \cos(\varphi_A - \varphi_B) \right] / 2 = I_1 \cos^2 \left(\frac{\Delta\varphi}{2} \right)$$

↖ u



- ambiguity between $+\varphi$ and $-\varphi$
- \cos is even function
- Solution - either

Slope + sensitivity as well as mean

$\Delta\varphi$

- how changes in environment effect $\Delta\varphi$

$$\Delta\varphi = K \left[n\Delta L + L\Delta n \right]$$

↖ $\frac{\lambda}{2\pi}$

Fiber Optics Sensor

Effects

$$\Delta L = \varepsilon_{11} L : \text{elongation in change in path length}$$

$$\Delta \varphi = K_n \Delta L$$

2) $\Delta n = f(\varepsilon)$: photoelastic effect

$$\Delta n = -n^3 [P_{11}\varepsilon_{33} + P_{12}\varepsilon_{22} + P_{12}\varepsilon_{11}] / 2$$

→ Photoelastic constants

putting it together

$$\Delta \varphi = K_n \Delta L \left\{ \underset{\substack{\uparrow \\ \text{long strain}}}{\varepsilon_{11}^f} - \frac{1}{2} n^2 \underbrace{[P_{11}\varepsilon_{33}^f + P_{12}\varepsilon_{22}^f + P_{12}\varepsilon_{11}^f]}_{\text{photoelastic}} + \underbrace{\alpha \Delta T}_{\text{thermal}} \right\}$$

- Typical : silica core fibers

$$P_{11} = 0.113, \quad P_{12} = 0.252$$

$$\varepsilon_{22} = \varepsilon_{33} = \nu \varepsilon_{11}$$

$$\Delta \varphi = K n L \varepsilon_{11} \left[1 - \frac{n^2}{2} \{ (1 - \nu) P_{12} - \nu P_{11} \} \right]$$

$$\Delta \varphi = S L \varepsilon_{11}, \quad S = 1.13 \times 10^7 \text{ rad/strain-m}$$

→ Scale factor

Fiber Optics Sensor

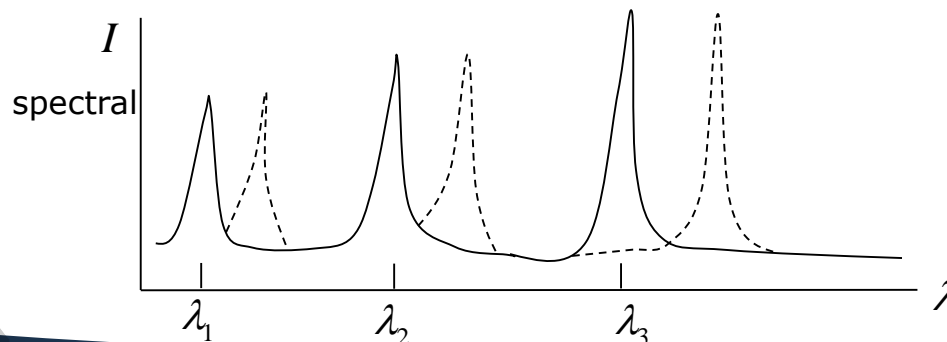
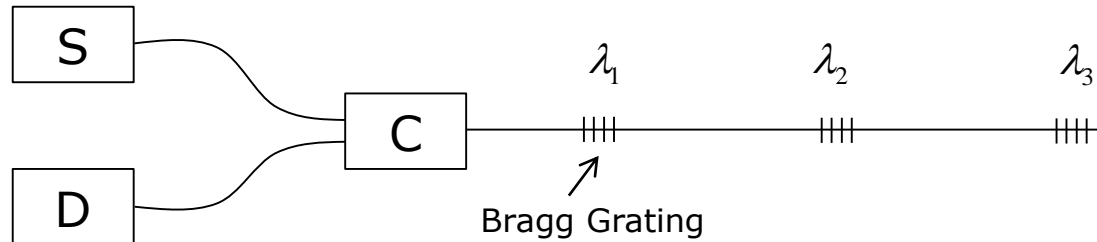
1 cm given length

1 at $\frac{I_8}{I_1} = 0.9975$

other application - polimetry + multi-mode fibers

- ... 2 orthogonal polarization
- 2 propagating modes
- ... beating

- Bragg Grating Based sensors



- Changes in grating wavelengths due to strain
- Multiplexing