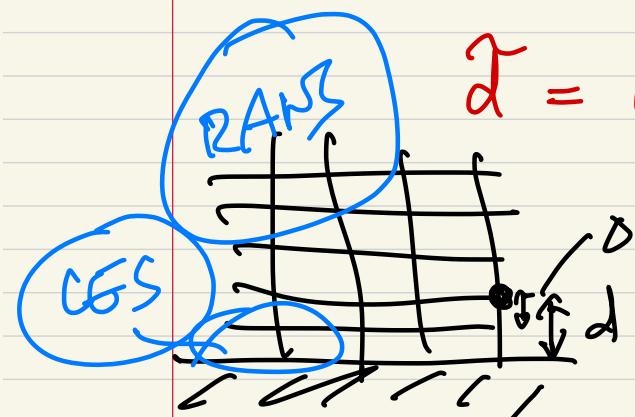


- ① DES (detached eddy simulation) - hybrid RANS/LES
  - ↳ single turbulence model acts as RANS and LES models for near-wall and detached regions, respectively, by adjusting the wall distance fn. (Spalart et al., 1997)

$$v_T = \tilde{D} f_{v_T}, \quad f_{v_T} = \frac{x^3}{x^3 + C_{v_T}^3}, \quad x = \frac{y}{\delta}$$

$$\frac{D\tilde{\delta}}{Dt} = C_{b_1} \tilde{S} \tilde{\delta} + \frac{1}{\delta} \left\{ \nabla \cdot [C_D (\nu + \tilde{\delta}) \nabla \tilde{\delta}] + C_{b_2} (\nabla \tilde{\delta})^2 \right\}$$

prod.  $- C_{w_1} f_w [\tilde{\delta}/\tilde{\delta}]^2$  destruction



$$d = \min(d_{RANS}, d_{LES})$$

$$(d_{RANS} = d : \text{wall distance})$$

$$d_{LES} = C_{DES} \Delta$$

$$C_{DES} = 0.65$$

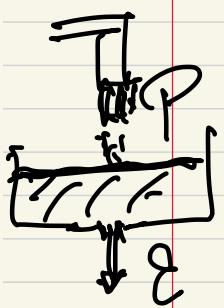
$$\Delta = \max(\Delta_x, \Delta_y, \Delta_z)$$

$$\text{or } (\Delta_x \Delta_y \Delta_z)^{1/3} \text{ or } \dots$$

problems  $\rightarrow$  DDES  $\rightarrow$  DDDES ...  $\rightarrow$  DES + k- $\omega$  model

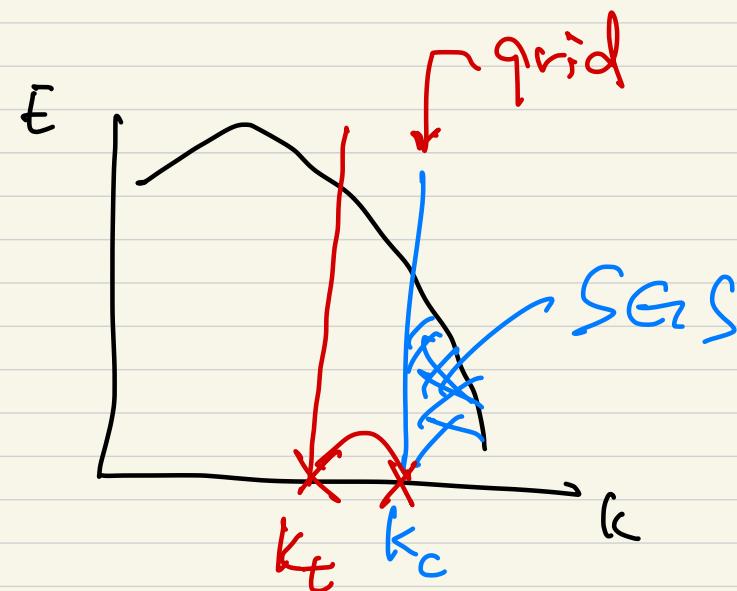
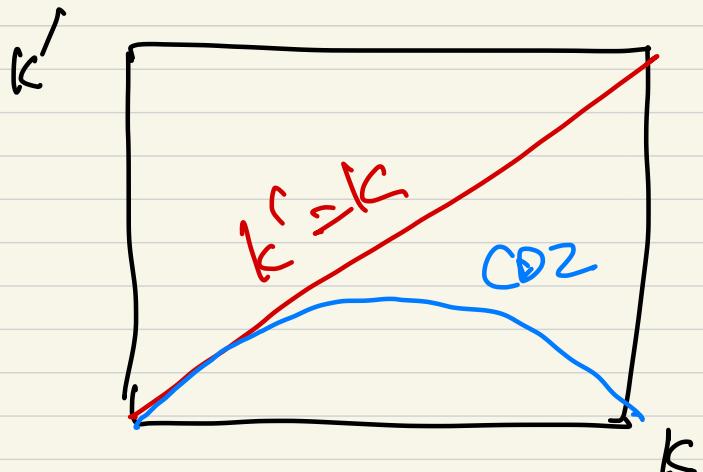
## ⑥ Numerical methods for spatial derivatives

- 2nd-order central difference scheme  $\rightarrow$  no dissipation error  
↓  
successful results.
- upwind-type schemes are not recommended  
 $\rightarrow$  numerical dissipation  $\gg$  turbulent dissipation produced by SGS model



Park et al. (JCP, 2004)

- modified wave number



- Number of grid points requirement for LES  
(Chapman 1979)  
revisited by Choi & Moin (2012)

for boundary layer flow

$$N_{DNS} \sim Re^{\frac{37}{14}}$$

$$N_{LES} \sim Re^{\frac{3}{7}} \Leftarrow \text{very high}$$

$$\underbrace{N_{LES} \text{ w/ wall modeling}}_{L} \sim Re^{\frac{1}{7}} \text{ much better}$$

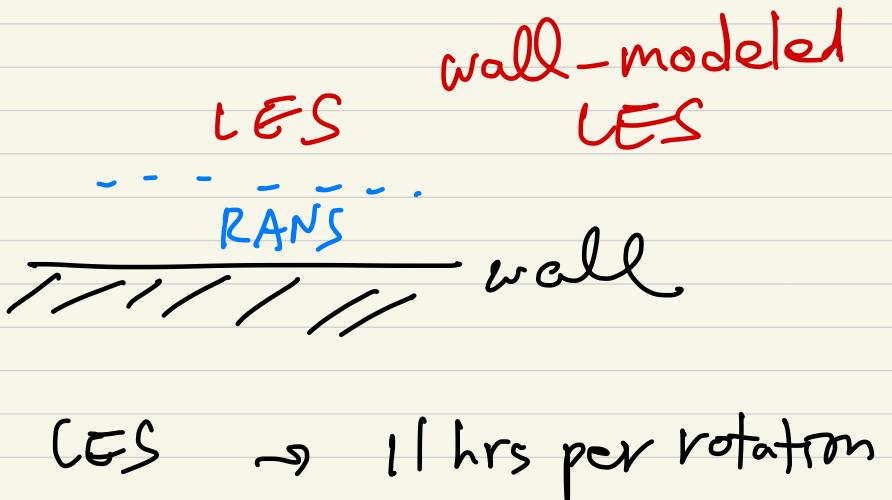


$$Re = 547,000$$

$$N = 800M$$

2048 processors

MPI



# ④ RANS - (Reynolds-averaged N-S eqs)

book: Turbulence models and their applications in hydraulics  
by Wolfgang Rodi (1984)

$$\left\{ \begin{array}{l} \frac{\partial \tilde{u}_c}{\partial x_c} = 0 \\ \frac{\partial \tilde{u}_c}{\partial t} + \tilde{u}_j \frac{\partial \tilde{u}_c}{\partial x_j} = - \frac{1}{\rho_r} \frac{\partial \tilde{p}}{\partial x_c} + \nu \nabla^2 \tilde{u}_c + g_i \frac{\tilde{p} - p_r}{\rho_r} \\ \frac{\partial \tilde{\phi}}{\partial t} + \tilde{u}_j \frac{\partial \tilde{\phi}}{\partial x_j} = \lambda \nabla^2 \tilde{\phi} + S_{\phi} \end{array} \right.$$

$\tilde{u}_c$ : inst. velocity

$$\frac{\tilde{p} - p_r}{\rho_r}$$

↑ buoyancy term

↑ source term

$\tilde{\phi}$ : inst. temperature or concentration  $\rightarrow$  passive scalar

$$\tilde{u}_0 = U_i + u_i$$

$$\tilde{p} = P + p$$

$$\tilde{\phi} = \Phi + \phi$$

$$\rightarrow \begin{cases} \frac{\partial U_i}{\partial x_i} = 0 \\ \frac{\partial U_i}{\partial t} + U_j \frac{\partial U_i}{\partial x_j} = -\frac{1}{\rho_r} \frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} \left( \nu \frac{\partial U_i}{\partial x_j} \right) - \overline{U_i U_j} + S_i \frac{f - f_r}{\rho_r} \\ \frac{\partial \Phi}{\partial t} + U_j \frac{\partial \Phi}{\partial x_j} = \frac{\partial}{\partial x_j} \left( \chi \frac{\partial \Phi}{\partial x_j} \right) - \overline{U_j \Phi} + S_\Phi \end{cases}$$

closure problem

• eddy-viscosity concept by Boussinesq (1877)

$$-\overline{U_i U_j} = \nu_t \left( \frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - \frac{2}{3} k \delta_{ij}$$

$k$ : kinetic energy

furn. v. viscosity

eddy "

$$j \rightarrow i : -\overline{U_i U_j} = r_E \left( \frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \left( -\frac{2}{3} k \delta_{ij} \right) = -2k$$

$$K = \frac{1}{2} \overline{U_i U_j}$$

$$\frac{\partial}{\partial x_j} (-\overline{U_i U_j}) = \frac{\partial}{\partial x_j} \left[ \nu_t \left( \frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - \frac{2}{3} k \delta_{ij} \right]$$

$$\frac{\partial}{\partial x_i} \left( -\frac{2}{3} k \right)$$

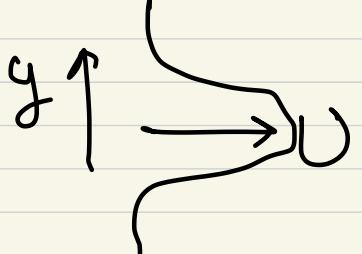
$$\Rightarrow -\frac{\partial}{\partial x_i} \left( \frac{P}{\rho_r} + \frac{2}{3} k \right) = -\frac{\partial}{\partial x_i} \left( \frac{P}{\rho_r} \right)$$

$\therefore$  the appearance of  $k$  does not necessitate the determination of  $k$ .

$$\nu_t \propto \tilde{V} L$$

↑      ↑  
vel. scale   length. scale

2D thin shear layer  $\frac{\partial U}{\partial y}$



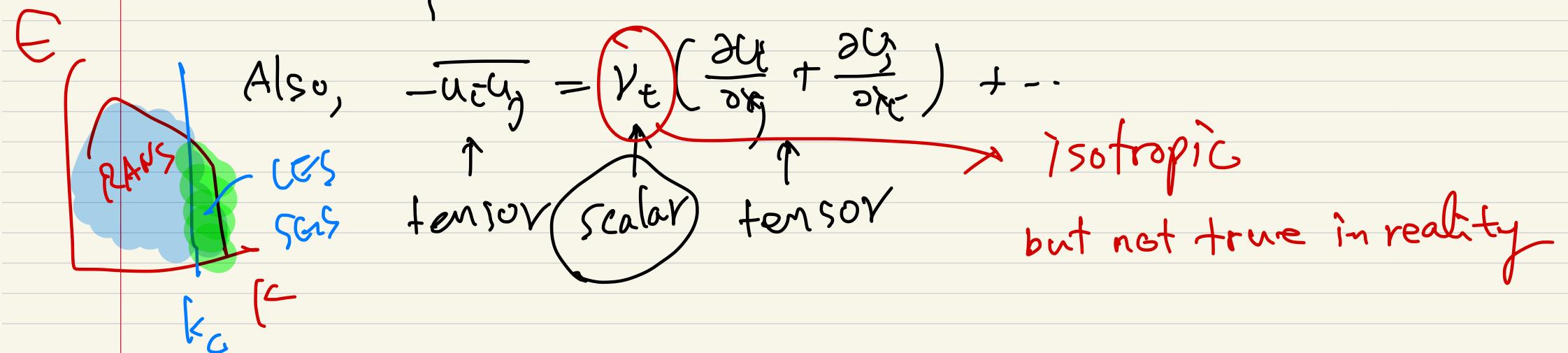
$$\tau = \rho \nu_t \frac{\partial U}{\partial y}$$

in some cases,

$$\tau \cdot \frac{\partial U}{\partial y} < 0 \rightarrow$$

eddy viscosity  
concept  
breaks down.

$$\nu_t < 0$$



In spite of all its shortcomings, the eddy viscosity concept has proven successful in many practical calculations and is still the basis of most turb. models in use today

• eddy diffusivity  $-\bar{u}_j \phi = \Gamma \frac{\partial \Phi}{\partial x_j}$   $\Gamma$ : turb. diffusivity  
 $\Gamma = \nu_t / \sigma_t$   $\sigma_t$ : turb. Pndtl number <sup>eddy</sup>,  
" Schmidt "

exp. results:  $\sigma_t$  varies only little across any flow and also little from flow to flow

→ Many models assume  $\sigma_t$  as a constant, Buoyancy and streamline curvature affect the value of  $\sigma_t$ .