

$$\tau_{ij} = 2 \nu_T S_{ij}$$

$\sqrt{k} \cdot L$

$\ln : \text{zero-eq.}$

$\frac{dk}{dt} + \dots$

$\epsilon \rightarrow \frac{d\epsilon}{dt} + \dots$

$k - \epsilon \text{ eq.}$

$2-\text{eq. model}$

① Turbulent stress / flux - equation models

So far, local state of turb. is assumed to be characterized by one vel. scale, and the individual Reynolds stresses τ_{ij} are related to this scale.

→ transport of the individual stresses is not adequately assessed.

$$\overline{u_i u_j}$$

→ transport eqs. for $\overline{u_i u_j}$

• Reynolds - stress eqs.

$$\frac{\partial}{\partial t} \overline{u_i u_j} + U_e \underbrace{\frac{\partial}{\partial x_e} \overline{u_i u_j}}_{\text{conv.}} = - \underbrace{\frac{\partial}{\partial x_e} \overline{u_e u_i u_j}}_{\text{diff.}} - \frac{1}{\rho} \left(\frac{\partial \overline{u_j P}}{\partial x_i} + \frac{\partial \overline{u_i P}}{\partial x_j} \right) \\ - \overline{u_i u_e} \frac{\partial U_e}{\partial x_e} - \overline{u_j u_e} \frac{\partial U_e}{\partial x_e} - \beta \left(g_i \overline{u_j \phi} + g_j \overline{u_i \phi} \right) + \overline{\frac{P}{\rho} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)} \\ - 2D \underbrace{\frac{\partial u_i}{\partial x_e} \frac{\partial u_j}{\partial x_e}}_{\text{vis. dissipation}} \underbrace{\rho_{ij}}_{\text{"prod."}} \underbrace{\text{buoyancy prod.}}_{\frac{g_i}{\rho_{ij}}} \underbrace{\text{press-strain corr.}}_{\frac{1}{\rho_{ij}}}$$

- at high Re, turb. is locally isotropic

$$\frac{\partial u_i}{\partial x_e} \frac{\partial u_j}{\partial x_e} = 0 \quad \text{for } i \neq j \Rightarrow \varepsilon_{ij} = \frac{2}{3} \epsilon \delta_{ij}$$

- press-strain corr. modelling : eliminate P via Poisson eq.

$$\pi_{ij,1} = -C_1 \frac{\epsilon}{k} \left(\overline{u_i u_j} - \frac{2}{3} \delta_{ij} k \right)$$

$$\pi_{ij,2} = -\delta \left(\rho_{ij} - \frac{2}{3} \delta_{ij} P \right)$$

- diff. transport = $C_s \frac{\partial}{\partial x_l} \left(\frac{k}{\epsilon} \bar{u_k} \bar{u_l} \frac{\partial \bar{u_i} u_j}{\partial x_k} \right)$
 - $\epsilon \rightarrow \epsilon_{eq}$: diffusion term in ϵ_{eq}
 $\rightarrow C_\epsilon \frac{\partial}{\partial x_l} \left(\frac{k}{\epsilon} \bar{u_l} \bar{u_k} \frac{\partial \epsilon}{\partial x_k} \right)$
 - wall & free-surface effect
 - low Re
 - wall-block effect (damping)
 - need corr.
-

\Rightarrow Launder - Reece - Rodi model
 (LRR)

good for wall jet, tail-driven secondary flow
 bad for round jet, swirl, wake
 not very popular these days.

- Algebraic stress/flux models

$\overline{u_i u_j} \rightarrow 6$ PDEs \rightarrow too much

neglect the rate of change & transport terms

\rightarrow sufficiently accurate in many cases

$$\overline{u_i u_j} = k \left[\frac{2}{3} \delta_{ij} + \frac{(1-\gamma) \left(\frac{P_{ij}}{\varepsilon} - \frac{2}{3} \delta_{ij} \frac{P}{\varepsilon} \right) + (1-c_3) \left(\frac{G_{ij}}{\varepsilon} - \frac{2}{3} \delta_{ij} \frac{G}{\varepsilon} \right)}{c_1 + \frac{P+G}{\varepsilon} - 1} \right]$$

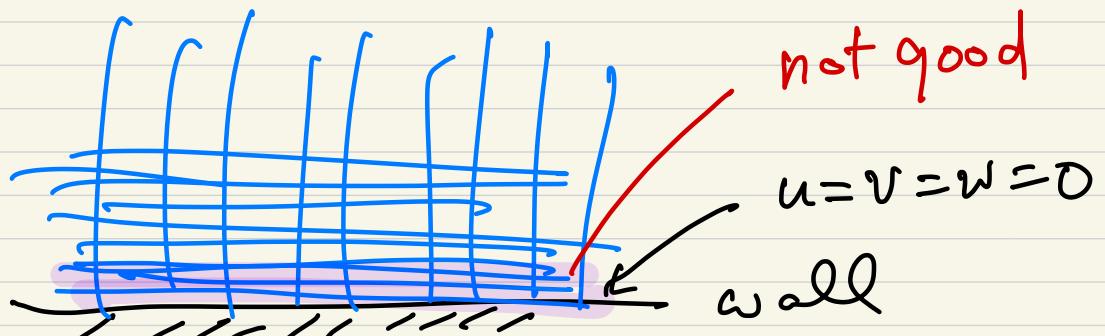
use this eq. together with $k-\varepsilon$ eqs.

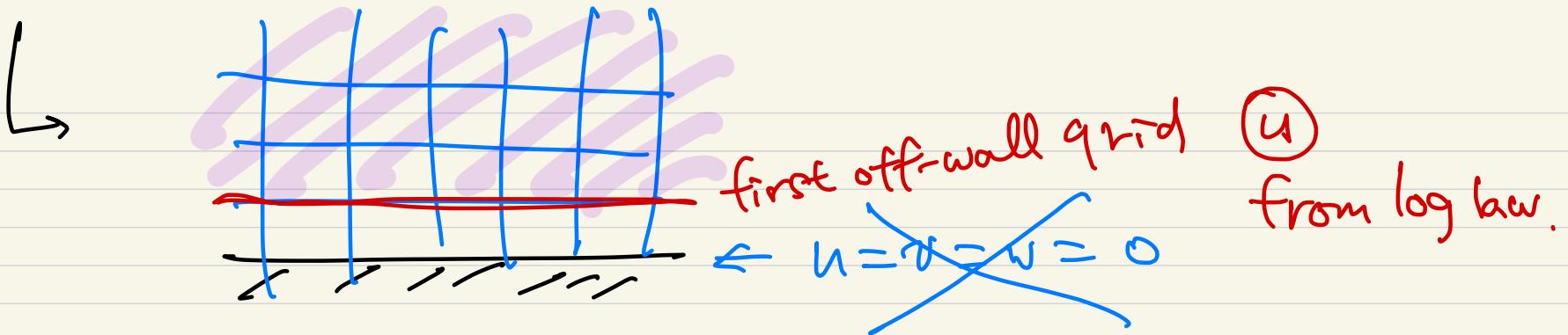
$\checkmark \varepsilon$ -eq. has problems

- boundary condns.

$k-\varepsilon$ model

$k-\text{eq}$]
 $\varepsilon-\text{eq}$.]

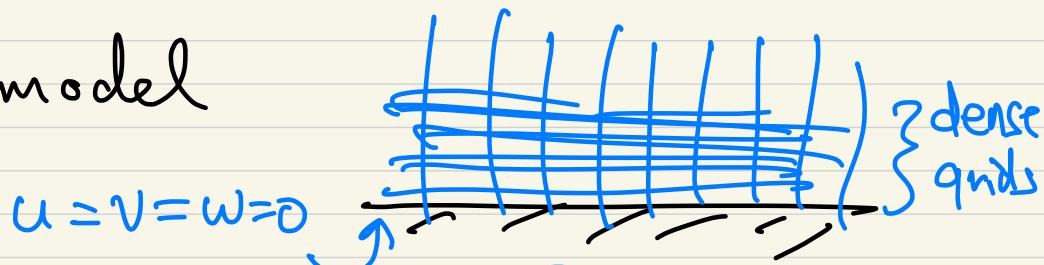




Other turbulence models

- Low Reynolds number k-ε model

Launder - Sharma (1974)



- k-ω shear stress transport (SST) model

Menter (AIAA T. 1994)

$$\frac{\partial}{\partial t} (\rho k) + \frac{\partial}{\partial x_j} (\rho u_j k) = C_k \frac{\partial u_i}{\partial x_j} - \beta^* \rho w k + \frac{\partial}{\partial x_j} \left[(\mu + \delta_k \mu_c) \frac{\partial k}{\partial x_j} \right]$$

$$\frac{\partial}{\partial t} (\rho \omega) + \frac{\partial}{\partial x_j} (\rho u_j \omega) = \frac{1}{g_c} C_\omega \frac{\partial u_i}{\partial x_j} - \beta \rho \omega^2 + \frac{\partial}{\partial x_j} \left[(\mu + \delta_\omega \mu_c) \frac{\partial \omega}{\partial x_j} \right]$$

$$+ 2(1-F_1) \rho \frac{\delta \omega_2}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}$$

$$\tau_{ij} = \mu_t \left[2 \bar{\epsilon}_{ij} - \frac{2}{3} \frac{\partial u_k}{\partial x_k} \delta_{ij} \right] - \frac{2}{3} g k \delta_{ij}$$

$$\bar{\epsilon}_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

$$F_i = \tanh(\arg_i^4)$$

$$\mu_t = g a_i k / \max(a_i \omega, \Omega F_i)$$

$$\arg_i = \min \left[\max \left(\frac{\sqrt{k}}{\beta \epsilon \omega d}, \frac{500d}{d^2 \omega} \right), \frac{4 g \delta \omega_2 k}{C D_{k \omega} d^2} \right]$$

$$CD_{k \omega} = \max \left(2 g \delta \omega \omega \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}, 10^{-20} \right)$$

- $k-\epsilon-\nu^2-f$ model (V2F model)

Durbin (1991)

Helmholtz eq.

$\downarrow v$

wall \downarrow blocking effect

$$k - \epsilon \text{ egs} + \frac{\partial \vec{v}}{\partial t} - \vec{g} + f$$

$$\rho u_j \frac{\partial \bar{v}^2}{\partial x_j} = k f - \bar{v}^2 \frac{\epsilon}{k} + \frac{\partial}{\partial x_j} \left[(\mu + \frac{\mu_t}{\sigma_k}) \frac{\partial \bar{v}^2}{\partial x_j} \right]$$

$$L^2 \nabla^2 f - f = (1 - c_1) \left[\frac{2}{3} - \frac{\bar{v}^2}{k} \right] / T - c_2 \frac{P}{k}$$

- - -

- - -

- Spalart - Allmaras model (1994) - 1-eq model
quite successful for aerodynamic flows

✓ June 12 6:30 pm Final exam

✓ June 22 Schedule Term project presentation (zoom)
TBA