

Markov inequality $P(X \geq c^2) \leq \frac{EX}{c^2}$

$P(X \geq 0) = 1.$

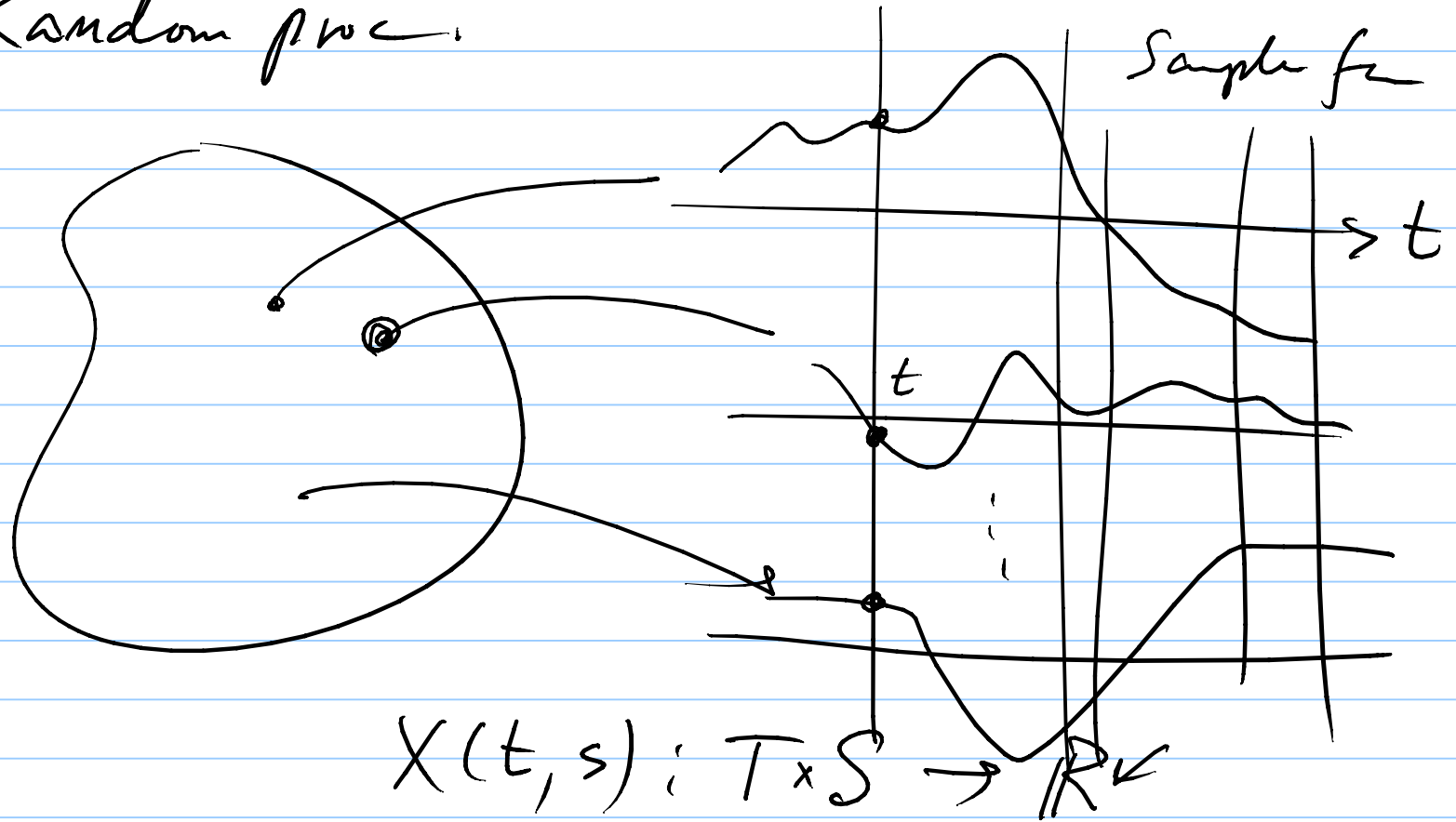
Chebyshev inequality $P(|Y - \mu_Y| \geq c) \leq \frac{\text{Var}(Y)}{c^2}$

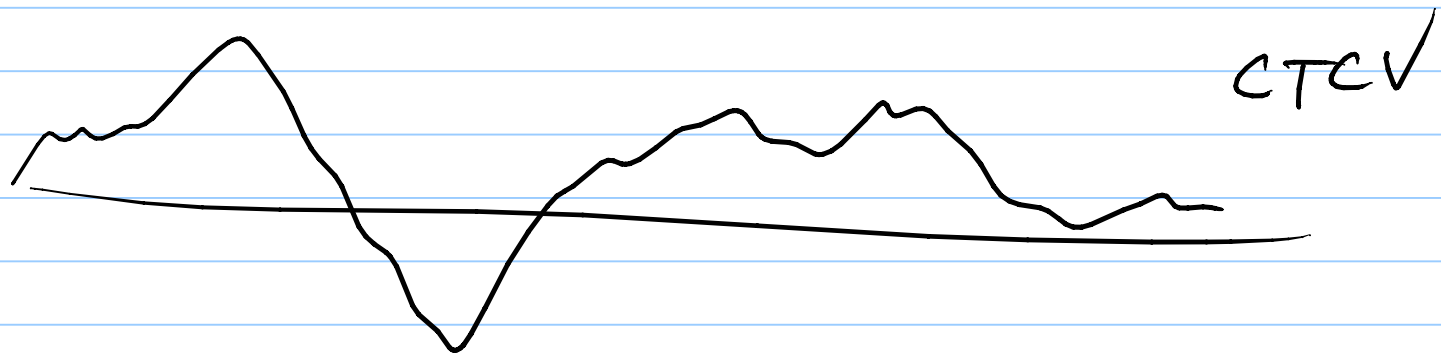
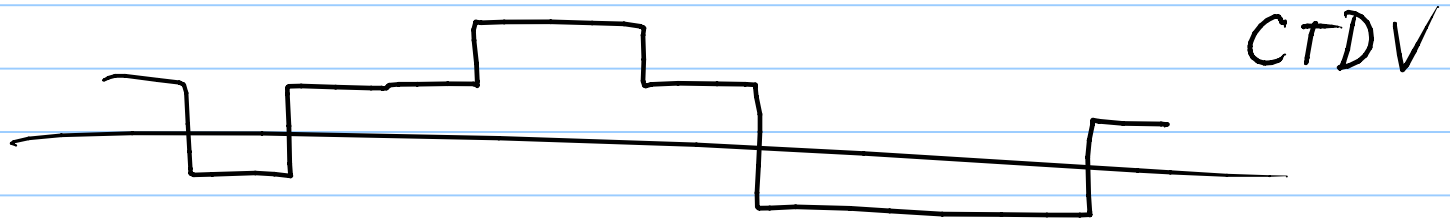
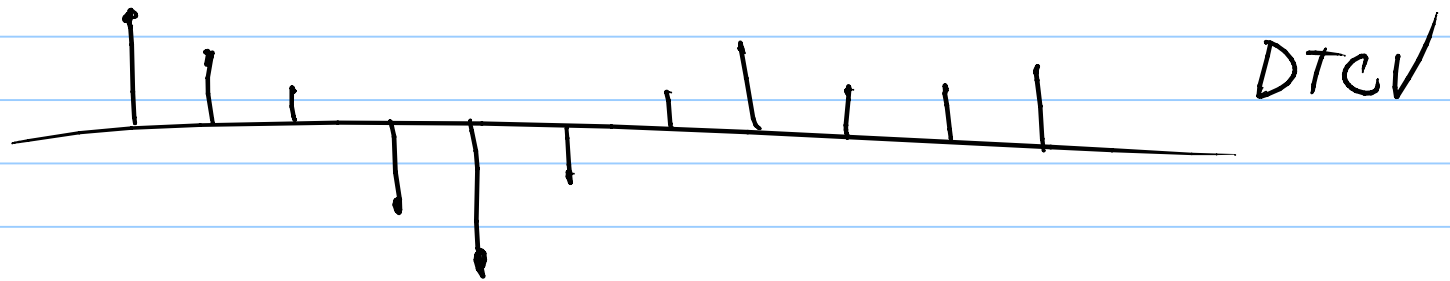
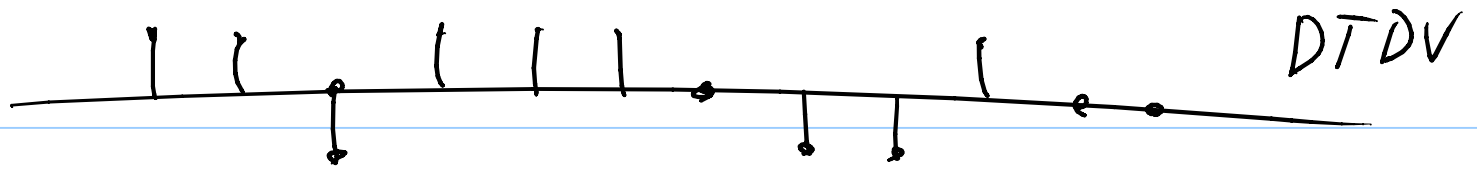


Chernoff bd.

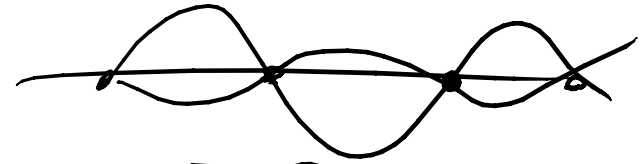
$$P(X \geq c) \leq \min_{s \geq 0} e^{-sc} \phi_X(s) \leq e^{-sc} \underset{\substack{\uparrow \\ \text{mgf}}}{\phi_X(s)}$$

Random proc.

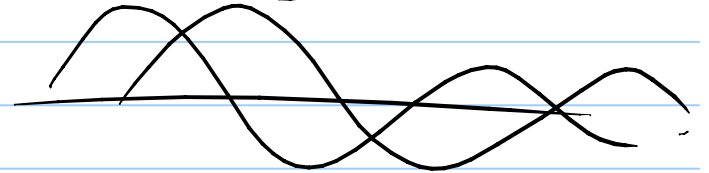




$$X(t) = A \cos 2\pi t$$

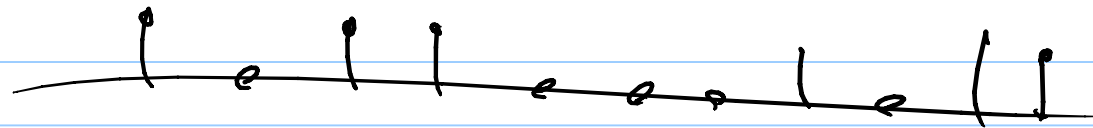


$$X(t) = \cos 2\pi(t + \theta)$$

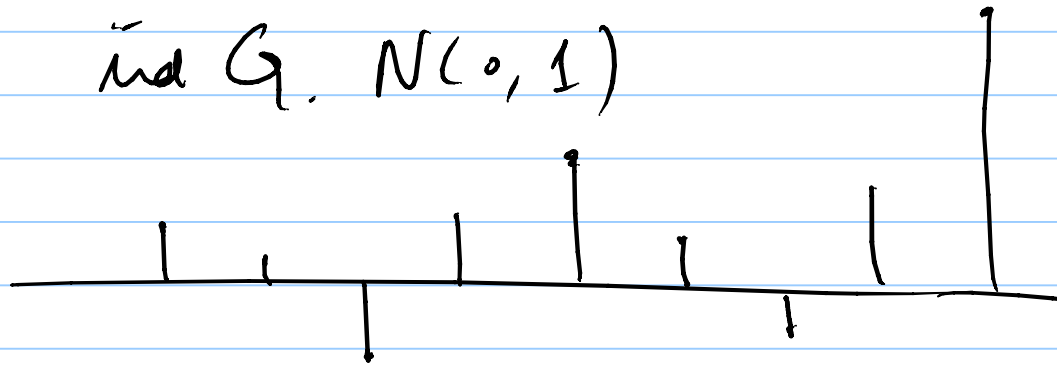


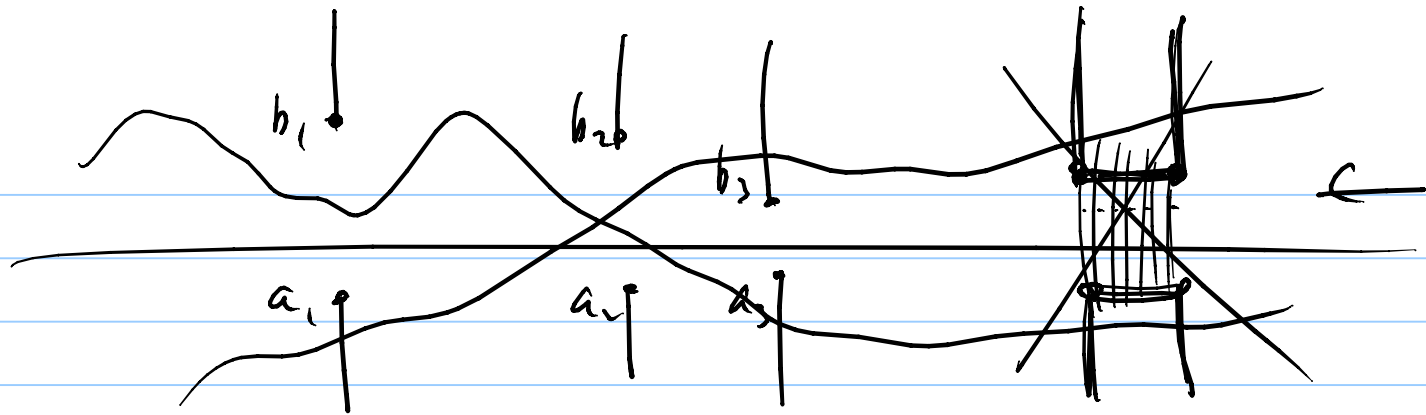
Weg von $[-\pi, \pi]$

$$X(t) = \dot{X}_t \quad \text{ind Bar } v_{v_s} = \text{Bar } v_p.$$



ind $G, N(0, 1)$





$$P(a_1 \leq X(t_1) \leq b_1, a_2 \leq X(t_2) \leq b_2, a_3 \leq X(t_3) \leq b_3)$$

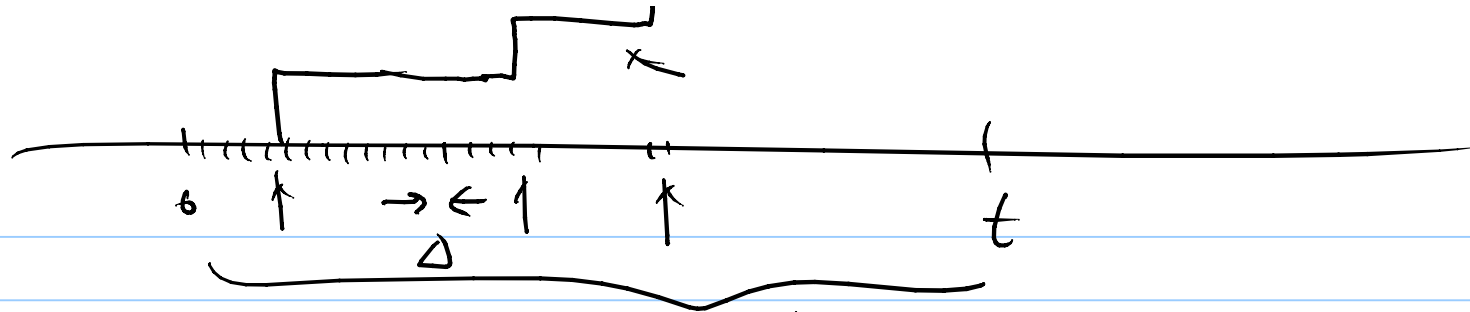
$$\int_{X(t_1)} \int_{X(t_2)} \int_{X(t_3)} f(x_1, x_2, x_3)$$

Poisson Ctg Proc. $N(t)$

(1) $N(t_1) - N(t_0)$ is Poi w/ mean $\lambda(t_1 - t_0)$

(2) non overlapping $[t_0, t_1]$ & $[t'_0, t'_1]$

$N(t_1) - N(t_0)$ & $N(t'_1) - N(t'_0)$ indep



$$P(X(t) = n) = \binom{m}{n} p^n (1-p)^{m-n}$$

$$\Delta \rightarrow 0 \quad \lambda \Delta = p \quad \lambda = \frac{p}{\Delta}$$

$$\rightarrow \frac{(\lambda t)^n}{n!} e^{-\lambda t}$$

Indep increment condition

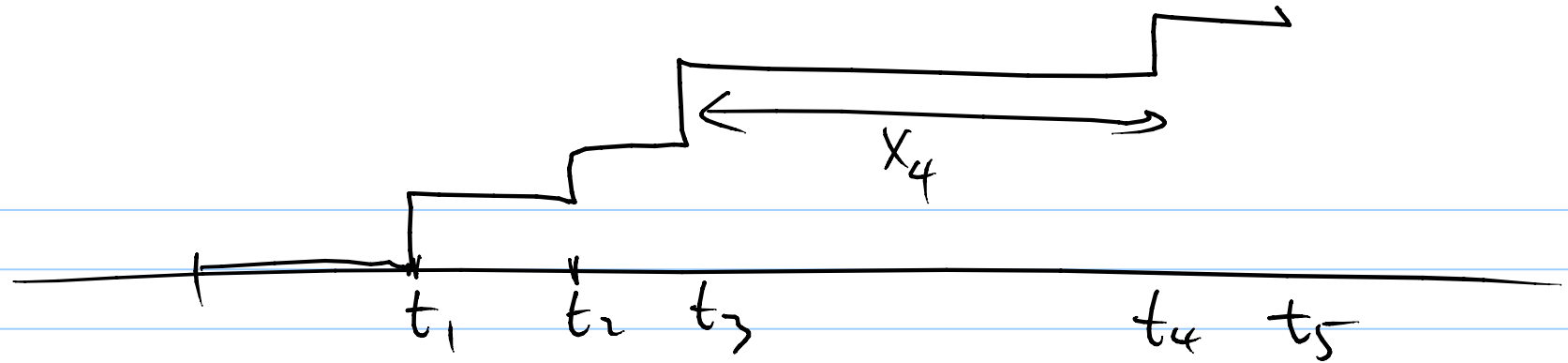
indep time proc

$$P_{N(t_1) \dots N(t_k)} \binom{n_1, \dots, n_k}{\uparrow \quad \quad \quad \uparrow} \quad N(0) = 0$$

$$= P_{\binom{n_1-0, \dots, n_k-n_{k-1}}{\uparrow \quad \quad \quad \uparrow}} \binom{N(t_1)-N(0), \dots, N(t_k)-N(t_{k-1})}{\uparrow \quad \quad \quad \uparrow}$$

$$\left(\begin{array}{l} P(X+Y=a, X=b) \\ = P(Y=a-b, X-0=b-0) \end{array} \right)$$

$$= \frac{(\lambda(t_1-0))^{(n_1-0)}}{(n_1-0)!} e^{-\lambda(t_1-0)} \dots \frac{(\lambda(t_k-t_{k-1}))^{n_k-n_{k-1}}}{(n_k-n_{k-1})!} e^{-\lambda(t_k-t_{k-1})}$$



Point process: $\underline{T_1} < \underline{T_2} < \underline{T_3} < \underline{T_4} < \underline{T_5}$

Inter-arrival
time proc. $X_1 \quad X_2 \quad X_3 \quad \dots \quad X_4 \quad X_5$
 $T_1 - T_0 \quad T_2 - T_1 \quad T_3 - T_2 \quad \dots \quad T_5 - T_4$
 $T_0 = 0$

X_i 's are iid Expon.

$$\left(\text{NLT}, 0 \leq t < \infty \right) \sim (T_1, T_2, \dots)$$

$$\sim (X_1, X_2, \dots)$$

$$T_m - T_{m-1}$$

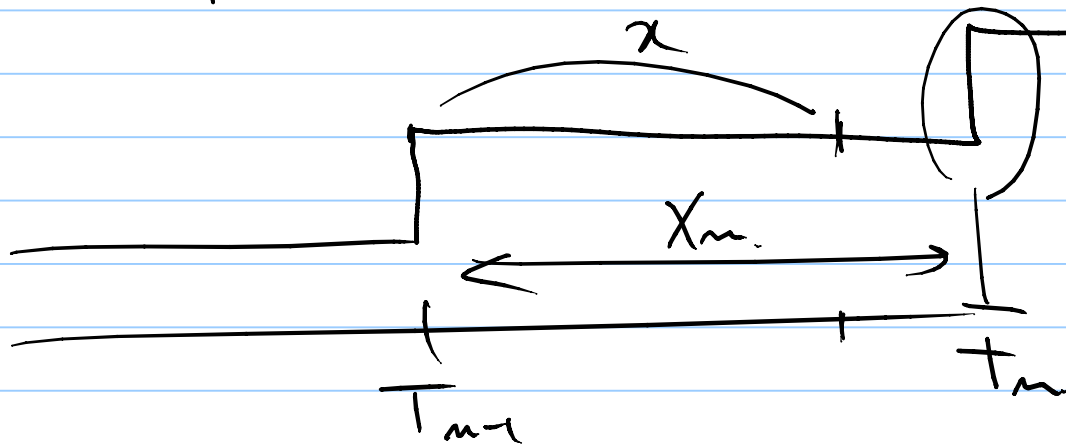
"

$$T_1 = X_1, T_2 = X_1 + X_2, T_3 = X_1 + X_2 + X_3 \dots$$

$$P(X_m \leq x) = 1 - P(X_m > x)$$

$$= 1 - P(\underline{X_m > x} \mid \underline{X_1 = x_1, \dots, X_{m-1} = x_{m-1}})$$

$$= 1 - P(N(t_{m-1} + \underline{x}) - N(\underline{t_{m-1}}) = 0 \mid X_1 = x_1, \dots, X_{m-1} = x_{m-1})$$

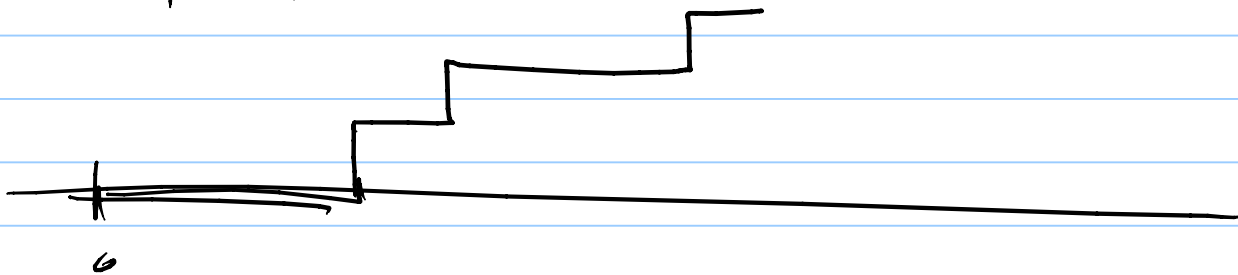


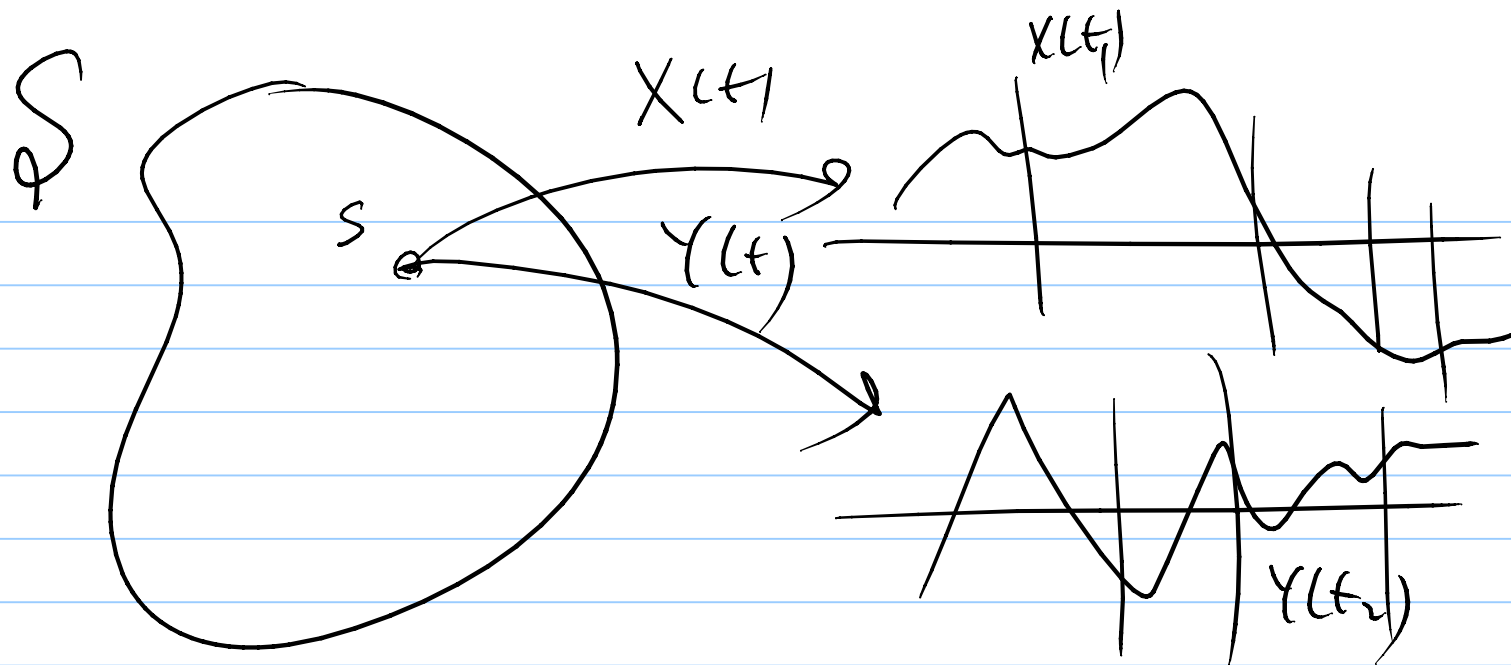
$$= 1 - P(N(t_{n-1} + x) - N(t_{n-1}) = 0)$$

$$= \begin{cases} (\lambda x)^0 e^{-\lambda x} = e^{-\lambda x}, & x > 0 \\ 0, & x \leq 0 \end{cases}$$

$$= \begin{cases} 1 - e^{-\lambda x}, & x > 0 \\ 0, & \text{else.} \end{cases} \quad \text{expon cdf}$$

X_1, X_2, \dots





$$\left(\underline{X(t_1) \ X(t_2) \ Y(u_1) \ Y(u_2) \ Y(u_3)} \right)$$

$$\underline{X(t), \ Y(t)}$$

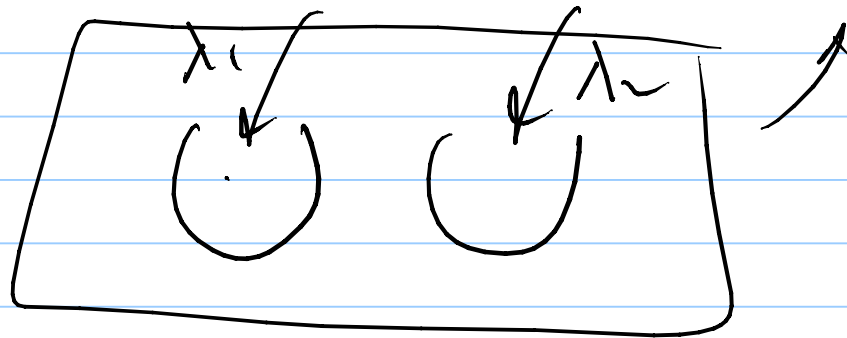
$$\int \underline{X(t_1) \dots X(t_m) \ Y(u_1) \dots Y(u_m)} \quad (x_1, \dots, x_m, y_1, \dots, y_m)$$

$$= \int_{X(t_1), \dots, X(t_n)}^{(x_1, \dots, x_n)} \int_{Y(u_1), \dots, Y(u_m)}^{(y_1, \dots, y_m)}$$

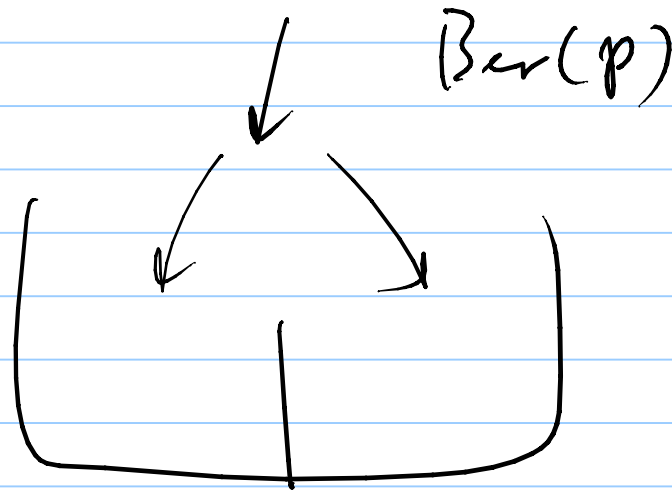
$X(t)$ & $Y(t)$ are indep.

$$\begin{array}{l} N_1(t) \sim \text{Poi}(\lambda_1) \\ N_2(t) \sim \text{Poi}(\lambda_2) \end{array} \left. \vphantom{\begin{array}{l} N_1(t) \\ N_2(t) \end{array}} \right\} \text{indep.}$$

$$N_1(t) + N_2(t) \sim \text{Poi}(\lambda_1 + \lambda_2)$$



$$N(t) \sim \text{Poi}(\lambda) \begin{cases} \rightarrow N_1(t) \sim \text{Poi}(\lambda p) \\ \rightarrow N_2(t) \sim \text{Poi}(\lambda(1-p)) \end{cases}$$



Moments of a rp.

$$\bar{E}X(t) = \mu_x(t) \quad \text{mean function.}$$

$$R_x(\underline{t}_1, \underline{t}_2) = \bar{E}X(t_1)X(t_2) \quad \underline{\underline{\text{auto-correlation}}}$$

$$C_x(\underbrace{t_1}_{\uparrow}, \underbrace{t_2}_{\uparrow}) = E((X(t_1) - \mu_x(t_1))(X(t_2) - \mu_x(t_2)))$$

auto-covarian.



$$\underbrace{t_1 - t_2}_{\tau} \quad \underbrace{(t_1 + \tau) - (t_2 + \tau)}$$

Example: $X(t) = A \cos \omega t$.

$$\mu_x(t) = \mu_A \cos \omega t$$

$$R_x(t_1, t_2) = E A \cos \omega t_1 A \cos \omega t_2$$

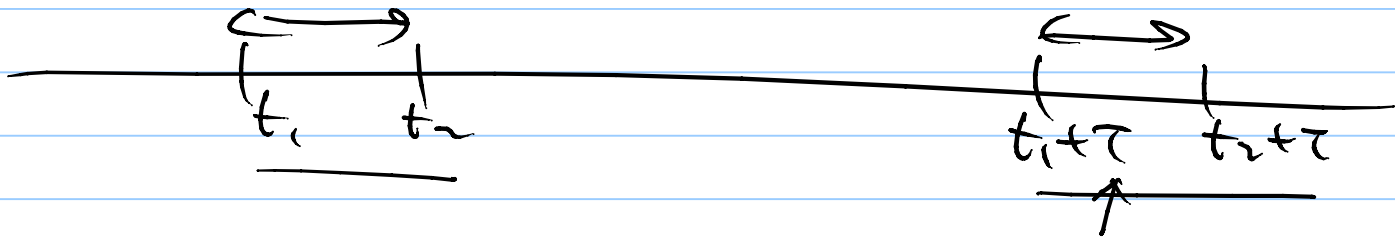
$$= (EA^2) \frac{1}{2} \left(\cos \omega \underline{t_1 - t_2} + \cos \omega \underline{t_1 + t_2} \right)$$

$$X(t) = \cos \underline{2\pi} (t + \theta) \quad \text{auf } \left(-\frac{1}{2}, \frac{1}{2}\right]$$

$$\begin{aligned} \underline{\underline{M_x(t)}} &= \int_{-1/2}^{1/2} \cos 2\pi (t + \theta) \cdot 1 \cdot d\theta = 0 \\ &= \int_{-1/2}^{1/2} \cos 2\pi (t + \theta) \cdot 1 \cdot d\theta = 0 \end{aligned}$$

$$\begin{aligned} \underline{\underline{R_x(t_1, t_2)}} &= \int_{-1/2}^{1/2} \cos 2\pi (t_1 + \theta) \cos 2\pi (t_2 + \theta) \cdot 1 \cdot d\theta \\ &= \frac{1}{2} \cos 2\pi (t_1 - t_2) \end{aligned}$$

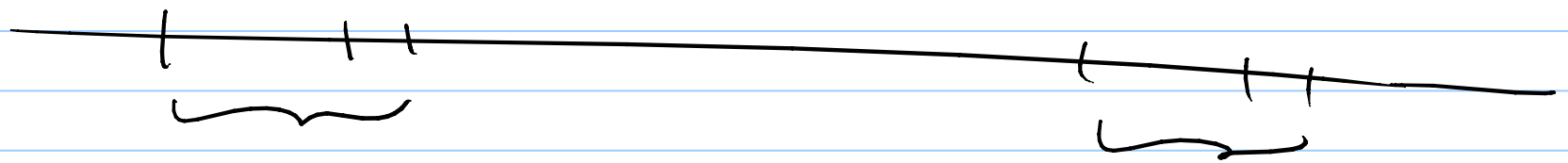
Shift invariant



Stationary Process.

$$f_{X(t_1), \dots, X(t_m)}(x_1, \dots, x_m)$$

$$= f_{X(t_1+\tau), \dots, X(t_m+\tau)}(x_1, \dots, x_m)$$



i.i.d rps.