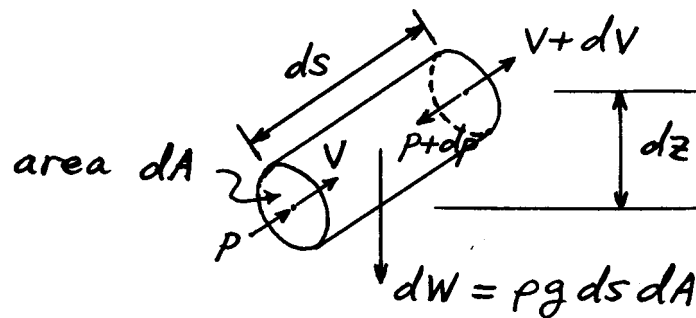


Chap.5 Flow of an Incompressible Ideal Fluid

- Ideal fluid (or inviscid fluid) \rightarrow viscosity=0
 \rightarrow no friction b/w fluid particles
or b/w fluid and boundary walls
- Incompressible fluid $\rightarrow \rho = \text{const}, dp/dt = 0$

5.1 Euler's Equation (1-D steady flow)



- pressure force: $p dA - (p + dp) dA = -dp dA$
- body force: $-\rho g ds dA \left(\frac{dz}{ds} \right) = -\rho g dA dz$
- acceleration: $a = \frac{dV}{dt} = \frac{\partial V}{\partial t} + V \frac{\partial V}{\partial s} = V \frac{dV}{ds}$

Newton's 2nd law: $F = ma$

$$-dp dA - \rho g dA dz = \rho dA ds V \frac{dV}{ds}$$

$$\boxed{\frac{dp}{\rho} + g dz + V dV = 0} \leftarrow \text{1-D Euler's equation}$$

$$\frac{dp}{\gamma} + dz + \frac{V}{g} dV = 0$$

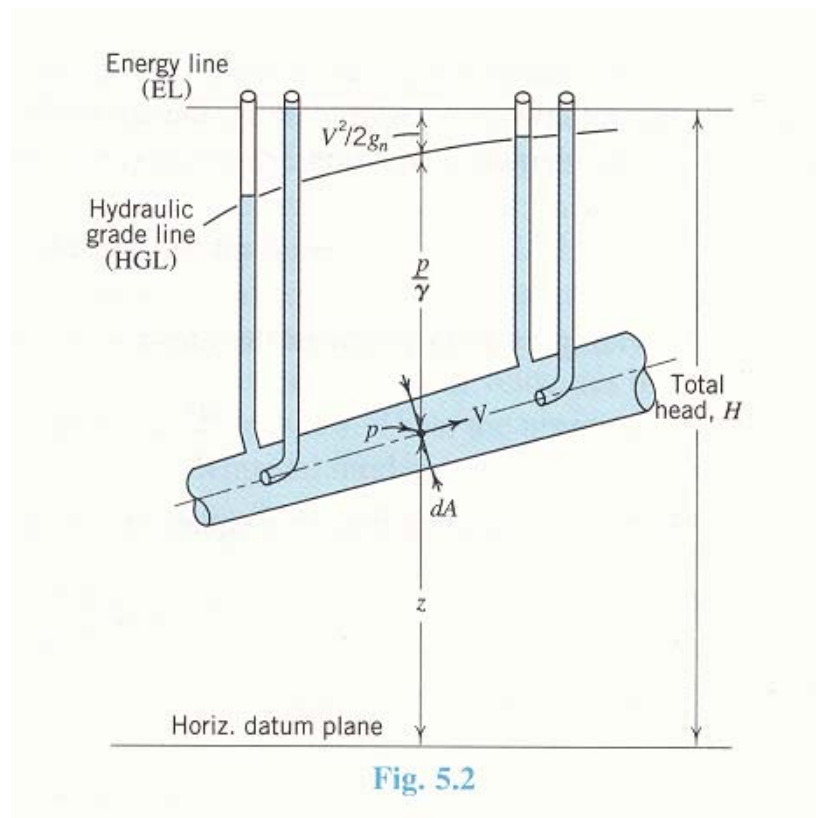
$$d\left(\frac{p}{\gamma} + z + \frac{V^2}{2g}\right) = 0 \rightarrow \frac{p}{\gamma} + z + \frac{V^2}{2g} = \text{const}$$

5.2 Bernoulli's Equation with Energy and Hydraulic Grade Lines

For 1-D steady flow of incompressible and uniform density fluid, integration of the Euler equation gives the Bernoulli equation as follows:

$$\underbrace{\frac{p}{\gamma}}_{\text{pressure head}} + \underbrace{\frac{V^2}{2g}}_{\text{velocity head}} + \underbrace{z}_{\text{elevation head}} = \underbrace{H}_{\text{total head}} = \text{const (along a streamline)}$$

정지유체 ($V = 0$): $\frac{p}{\gamma} + z = \text{const} \quad (2.6)$



Assumption: The stream tube is infinitesimally thin, so that it can be assumed to be a streamline.

$$EL = z + \frac{p}{\gamma} + \frac{V^2}{2g} = H$$

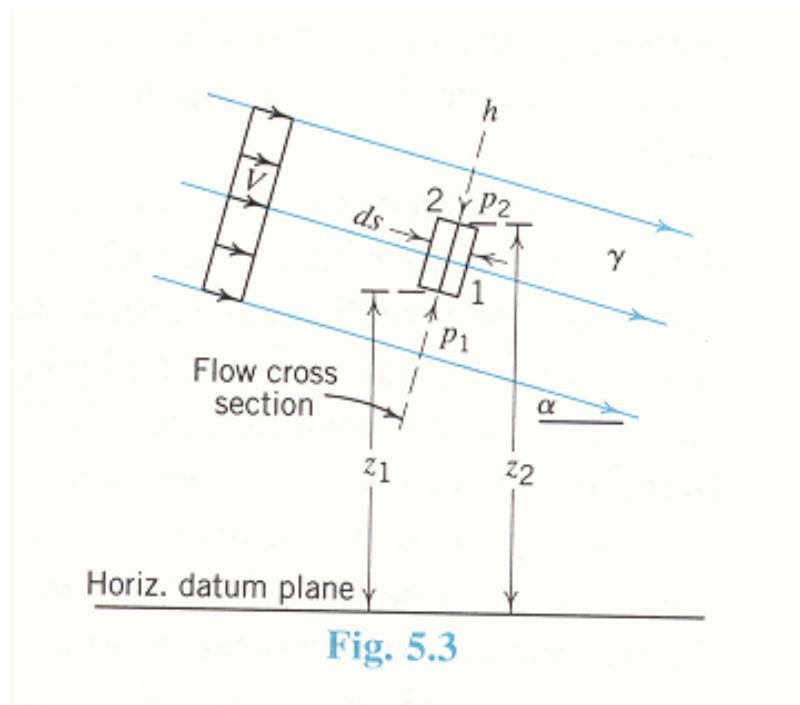
$$HGL = z + \frac{p}{\gamma}$$

$$EL - HGL = \frac{V^2}{2g}$$

5.3 1-D Assumption for Streamtubes of Finite Cross Section

Assumptions:

1. Streamlines are straight and parallel.
2. $V = \text{constant}$ across a cross section
(ideal fluid \rightarrow no friction)



Straight and parallel streamlines

\rightarrow No cross-sectional velocity

\rightarrow No cross-sectional acceleration

Newton's 2nd law in x-sectional direction:

$$F_c = \text{pressure force} + \text{body force} = 0$$

(\because no x-sectional acceleration)

Read text

$$\frac{p_1}{\gamma} + z_1 = \frac{p_2}{\gamma} + z_2$$

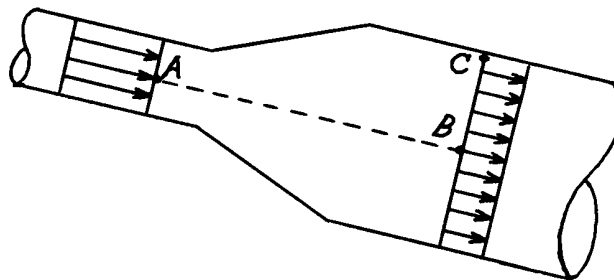
or $\frac{p}{\gamma} + z = \text{constant}$ across the x-section

Ex) Ideal fluid flowing in a pipe (IP 5.1)

$$\frac{p_A}{\gamma} + z_A + \frac{V_A^2}{2g} = \frac{p_B}{\gamma} + z_B + \frac{V_B^2}{2g} \quad (\because \text{same streamline})$$

$$\frac{p_B}{\gamma} + z_B + \frac{V_B^2}{2g} = \frac{p_C}{\gamma} + z_C + \frac{V_C^2}{2g} \quad (\because V_B = V_C)$$

Therefore, the Bernoulli's equation can be applied not only between A and B (on the same streamline) but also between A and C (on different streamlines) in the pipe shown below.

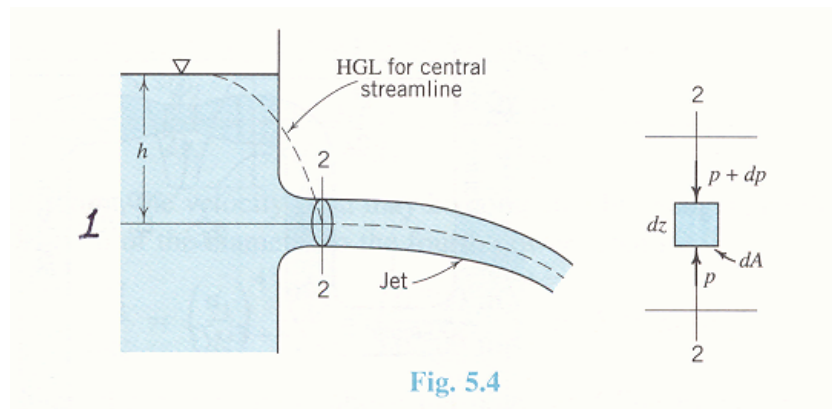


5.4 Applications of Bernoulli's Equation

(1) If $z \approx \text{const}$, $\frac{p}{\gamma} + \frac{V^2}{2g} \approx \text{const}$

\therefore high velocity \rightarrow low pressure

(2) Torricelli's equation



Bernoulli equation b/w 1 and 2:

$$\frac{p_1}{\gamma} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{\gamma} + \frac{V_2^2}{2g} + z_2$$

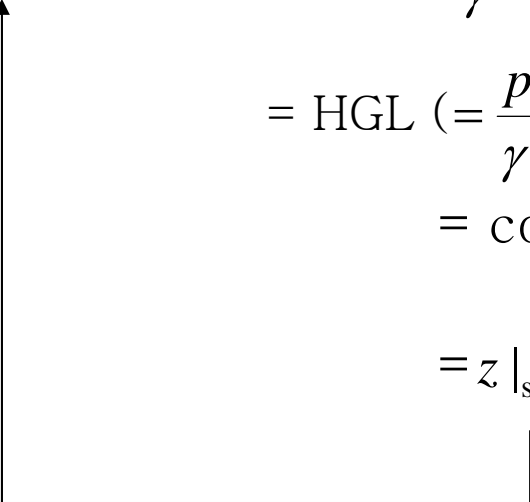
Using $z_1 = z_2$, $p_1 = \gamma h$, $p_2 = 0$, $V_1 \approx 0$,

$$h = \frac{V_2^2}{2g} \rightarrow \boxed{V_2 = \sqrt{2gh}} \leftarrow \text{Torricelli equation}$$

For application of Torricelli's equation, see IP 5.2 in text.

Note:

In the reservoir ($V = 0$),

$$\begin{aligned}
 \text{Water surface} &= \text{EL} \left(= \frac{p}{\gamma} + \cancel{\frac{V^2}{2g}} + z \right) = 0 \\
 &= \text{HGL} \left(= \frac{p}{\gamma} + z \right) \\
 &= \text{const. in static fluid} \\
 &\quad \text{(reservoir)} \\
 &= z \big|_{\text{surface}} \quad (\because p = 0 \text{ at surface})
 \end{aligned}$$


(3) Cavitation

Cavitation occurs if $p_{\text{abs}} = p_{\text{gage}} + p_{\text{atm}} \leq p_v$

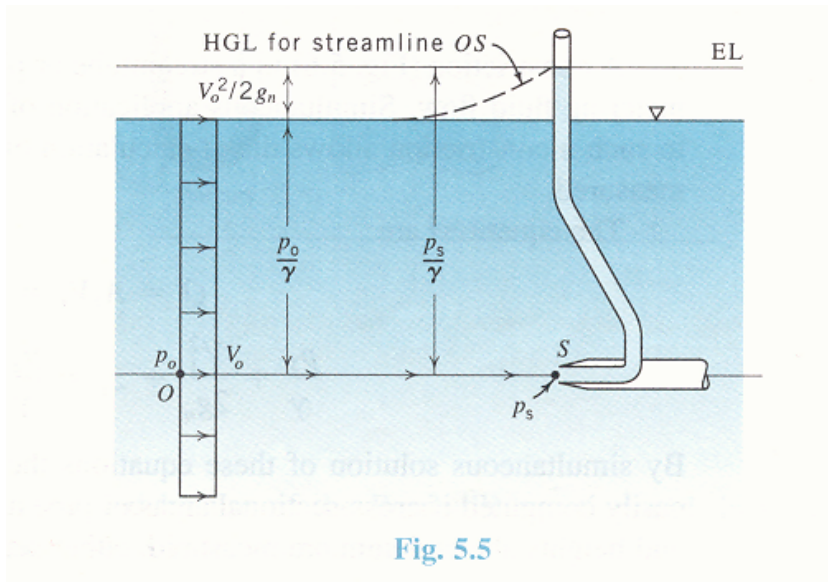
$$\text{or } p_{\text{gage}} \leq -(p_{\text{atm}} - p_v)$$

At initiation of cavitation,

$$p_{\text{gage}} = -(p_{\text{atm}} - p_v)$$

↑
 p_c (critical gage pressure in text p. 134)

(4) Pitot tube (for measuring velocity)



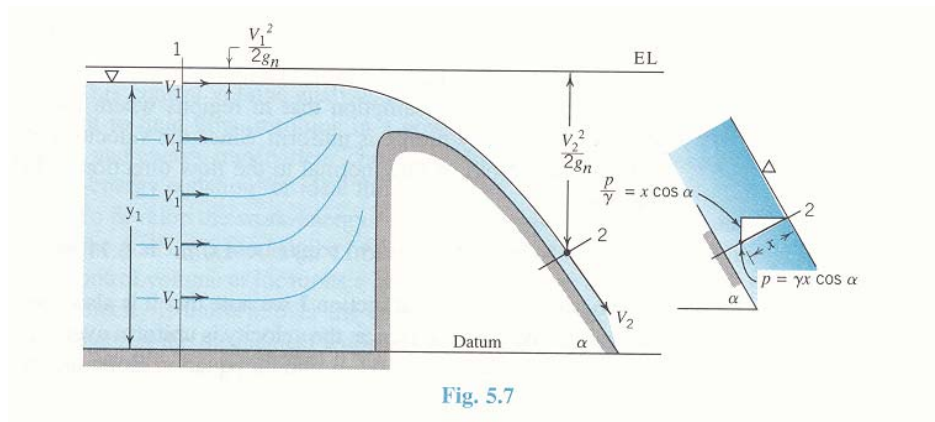
$$\frac{p_o}{\gamma} + \frac{V_o^2}{2g} + z_o = \frac{p_s}{\gamma} + \frac{V_s^2}{2g} + z_s = H (= EL)$$

$$V_o = \sqrt{2g \left(\frac{p_s}{\gamma} - \frac{p_o}{\gamma} \right)}$$

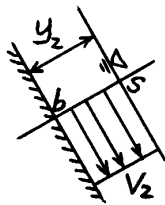
can be measured

$\therefore V_o$ can be known.

(5) Overflow structure (e.g. spillway of a dam)



Pressure and velocity on the spillway surface at 2?



$$V_s = V_b = V_2 (\because \text{ideal fluid})$$

Bernoulli equation at points s and b :

$$\frac{p_s}{\gamma} + \frac{V_s^2}{2g} + z_s = \frac{p_b}{\gamma} + \frac{V_b^2}{2g} + z_b \quad \leftarrow \text{See also § 5.3}$$

$$p/\gamma + z = \text{const}$$

$$\therefore p_b = \gamma(z_s - z_b) \quad \text{across a x-section}$$

Continuity: $V_1 y_1 = V_2 y_2$

Bernoulli equation at water surfaces at 1 and 2

$$\frac{p_1}{\gamma} + \frac{V_1^2}{2g} + y_1 = \frac{p_2}{\gamma} + \frac{V_2^2}{2g} + z_s$$

2 equations for 2 unknowns (y_1 and V_1)

→ can be solved for y_1 and V_1 .

5.5 Work-Energy Equation

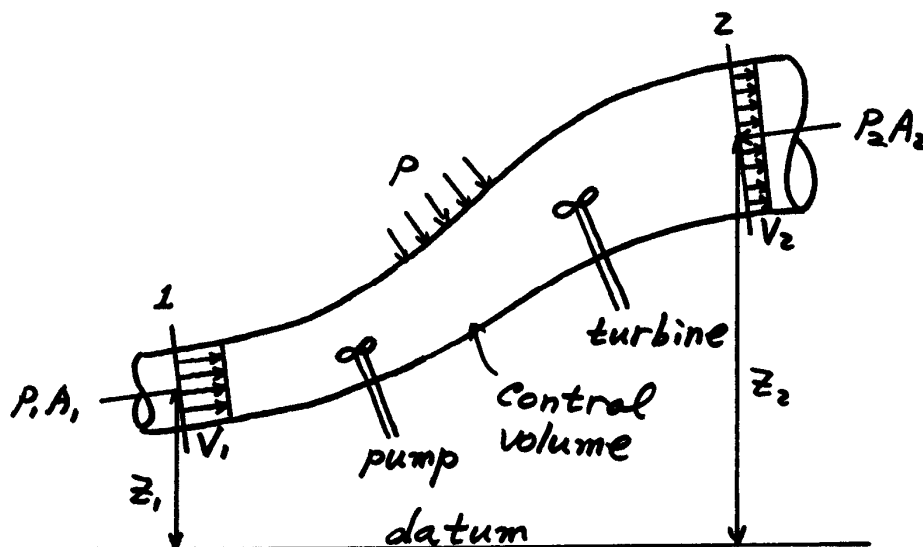
- Addition or extraction of energy by flow machines
 - pump: add energy to flow system
(or a pump does work on fluid)
 - turbine: extract energy from flow system
(or fluid does work on a turbine)
- Mechanical work-energy principle

Work done on a fluid system is equal to the change in the mechanical energy (potential + kinetic energy) of the system

$$dW = dE \rightarrow \frac{dW}{dt} = \frac{dE}{dt}$$

Note: Work, energy, and heat have the same unit ($J=N \cdot m$)

- Control volume analysis (Reynolds transport theorem)



Reynolds transport theorem for mechanical energy:

$$\begin{aligned}
 \frac{dE}{dt} &= \frac{\partial}{\partial t} \left(\iiint_{CV} \rho \left(gz + \frac{V^2}{2} \right) dV \right) \\
 &\quad + \iint_{CS_{out}} \rho \left(gz + \frac{V^2}{2} \right) \vec{v} \cdot \vec{n} dA + \iint_{CS_{in}} \rho \left(gz + \frac{V^2}{2} \right) \vec{v} \cdot \vec{n} dA \\
 &= \rho \left(gz_2 + \frac{V_2^2}{2} \right) V_2 A_2 - \rho \left(gz_1 + \frac{V_1^2}{2} \right) V_1 A_1 \\
 &= \left(z_2 + \frac{V_2^2}{2g} \right) \rho g V_2 A_2 - \left(z_1 + \frac{V_1^2}{2g} \right) \rho g V_1 A_1 \\
 &= Q\gamma \left[\left(z_2 + \frac{V_2^2}{2g} \right) - \left(z_1 + \frac{V_1^2}{2g} \right) \right]
 \end{aligned}$$

Rate of work done on the flow system $\left(\frac{dW}{dt} = ? \right)$

1. flow work rate done by pressure force

$$= \iint_{CS} \vec{p} \cdot \vec{v} dA = p_1 A_1 V_1 - p_2 A_2 V_2 = Q\gamma \left(\frac{p_1}{\gamma} - \frac{p_2}{\gamma} \right)$$

2. machine work rate done by pumps or turbines

$$= Q\gamma (E_p - E_t)$$

E_p, E_t = work rate per unit weight of fluid

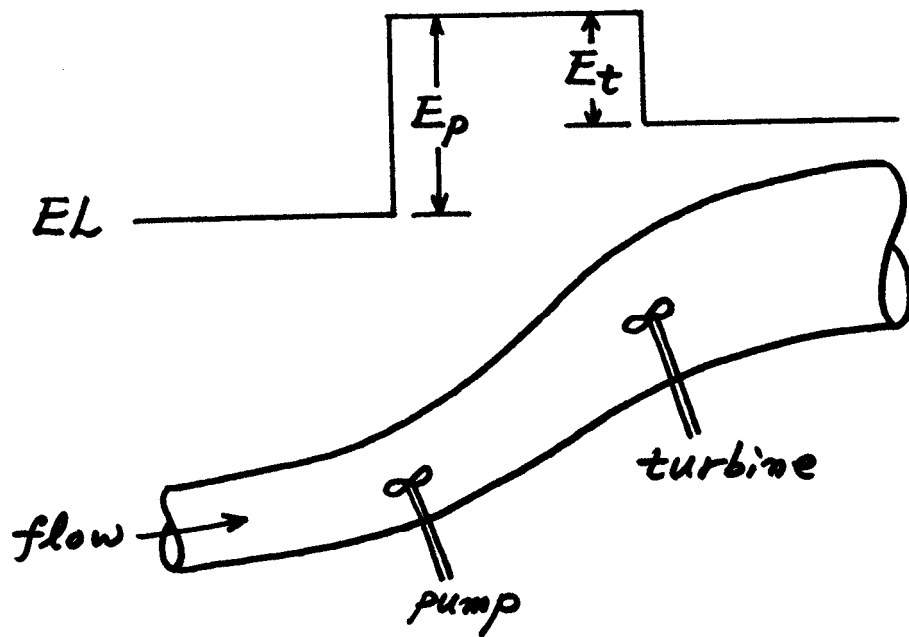
3. Shear work rate done by shearing forces on the control surface = 0 (\because ideal fluid)

$$\therefore \frac{dW}{dt} = Q\gamma \left(\frac{p_1}{\gamma} - \frac{p_2}{\gamma} + E_p - E_t \right)$$

Since $\frac{dW}{dt} = \frac{dE}{dt}$, we get

$$\boxed{\frac{p_1}{\gamma} + z_1 + \frac{V_1^2}{2g} + E_p - E_t = \frac{p_2}{\gamma} + z_2 + \frac{V_2^2}{2g}}$$

Work-energy equation (per unit weight of fluid)



- Power of pump or turbine

Power = rate of work done

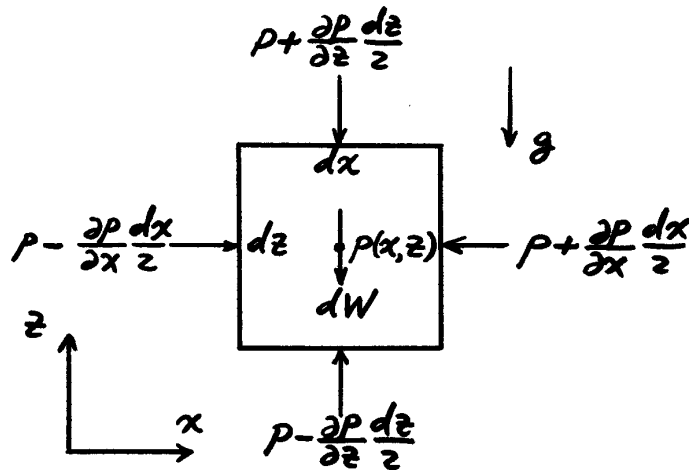
E_p, E_t = rate of work done per unit weight of fluid

\therefore Power of pump or turbine

$$= (E_p \text{ or } E_t) \times Q\gamma \quad (\text{ft}\cdot\text{lb/s or J/s=W})$$

\nwarrow total weight of fluid passing the
x-section per unit time

5.6 Euler's Equations (2-D Steady Flow)



Newton's 2nd law:

x -direction:

$$\left(p - \frac{\partial p}{\partial x} \frac{dx}{2} \right) dz - \left(p + \frac{\partial p}{\partial x} \frac{dx}{2} \right) dz = \rho dx dz \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} \right)$$

$$\boxed{-\frac{1}{\rho} \frac{\partial p}{\partial x} = u \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z}}$$

z -direction:

$$\left(p - \frac{\partial p}{\partial z} \frac{dz}{2} \right) dx - \left(p + \frac{\partial p}{\partial z} \frac{dz}{2} \right) dx - \rho g dx dz = \rho dx dz \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + w \frac{\partial w}{\partial z} \right)$$

$$\boxed{-\frac{1}{\rho} \frac{\partial p}{\partial z} = u \frac{\partial w}{\partial x} + w \frac{\partial w}{\partial z} + g}$$

Continuity: $\frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0$

3 equations for 3 unknowns (p, u, w)

5.7 Bernoulli's Equation

Euler's equations:

$$\left(\begin{aligned} &\left(-\frac{1}{\rho} \frac{\partial p}{\partial x} = u \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} \right) \times dx \\ &\left(-\frac{1}{\rho} \frac{\partial p}{\partial z} = u \frac{\partial w}{\partial x} + w \frac{\partial w}{\partial z} + g \right) \times dz \end{aligned} \right) +$$

$$\begin{aligned} -\frac{1}{\rho} \left(\frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial z} dz \right) &= u \frac{\partial u}{\partial x} dx + w \frac{\partial u}{\partial z} dx + u \frac{\partial w}{\partial x} dz + w \frac{\partial w}{\partial z} dz + g dz \\ &= \left(u \frac{\partial u}{\partial x} dx + w \frac{\partial w}{\partial x} dx \right) + \left(u \frac{\partial u}{\partial z} dz + w \frac{\partial w}{\partial z} dz \right) \\ &\quad + (u dz - w dx) \left(\frac{\partial w}{\partial x} - \frac{\partial u}{\partial z} \right) + g dz \end{aligned}$$

Using

$$\begin{aligned} dp &= \frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial z} dz \\ d(u^2 + w^2) &= \frac{\partial(u^2 + w^2)}{\partial x} dx + \frac{\partial(u^2 + w^2)}{\partial z} dz \\ &= 2u \frac{\partial u}{\partial x} dx + 2w \frac{\partial w}{\partial x} dx + 2u \frac{\partial u}{\partial z} dz + 2w \frac{\partial w}{\partial z} dz \end{aligned}$$

we get

$$\frac{dp}{\rho g} + \frac{d(u^2 + w^2)}{2g} + dz = \frac{1}{g} (w dx - u dz) \xi$$

Let $X_1 = (x_1, z_1)$ and $X_2 = (x_2, z_2)$.

Integrating from X_1 to X_2 ,

$$\left(\frac{p}{\gamma} + \frac{u^2 + w^2}{2g} + z \right) \Bigg|_{X_1}^{X_2} = \frac{1}{g} \int_{X_1}^{X_2} \xi (w dx - u dz)$$

If the path between X_1 and X_2 is a streamline ($u = dx/dt$, $w = dz/dt$), the RHS vanishes so that

$$\left(\frac{p}{\gamma} + \frac{u^2 + w^2}{2g} + z \right) \Bigg|_{X_1}^{X_2} = 0$$

Therefore,

$$\frac{p}{\gamma} + \frac{u^2 + w^2}{2g} + z = \text{const}(C) \text{ along a streamline.}$$

But, in general, the constant(C) may be different for different streamlines.

On the other hand, for an irrotational flow, $\xi = 0$, thus

$$\left(\frac{p}{\gamma} + \frac{u^2 + w^2}{2g} + z \right) \Bigg|_{X_1}^{X_2} = 0$$

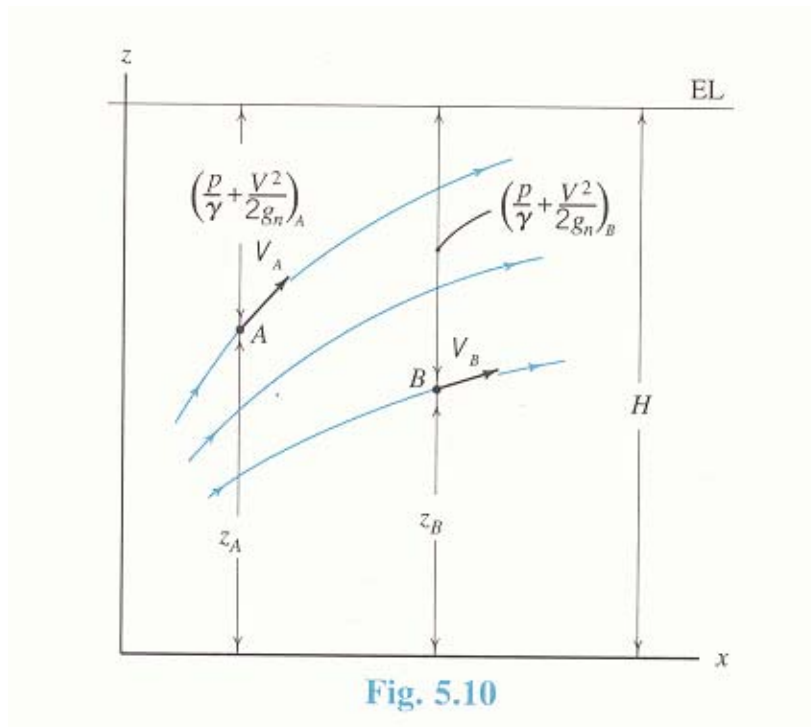
for any two points in the flow. Thus

$$\frac{p}{\gamma} + \frac{V^2}{2g} + z = H(\text{const})$$

over the whole flow field for irrotational flow.

5.8 Applications of Bernoulli's Equation

For irrotational flow of ideal incompressible fluid, the Bernoulli's equation applies over the whole flow field with a single energy line.



$$H = \frac{p}{\gamma} + \frac{V^2}{2g} + z$$

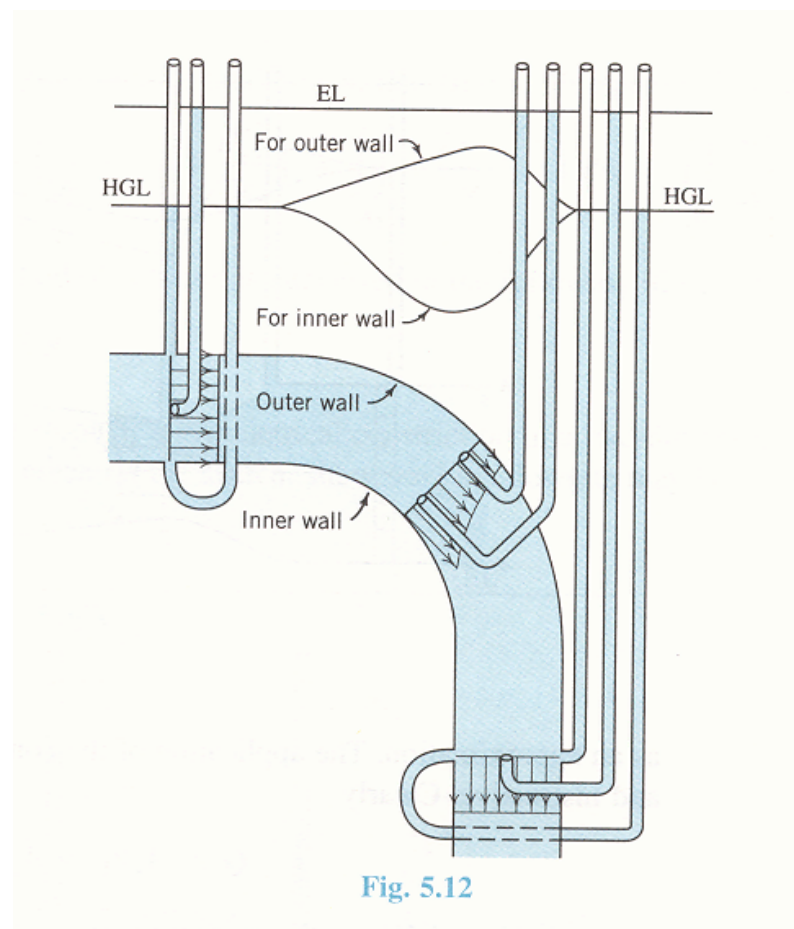
We are interested in p and V at a point.

Exact velocity field → Exact pressure

→ Difficult to solve

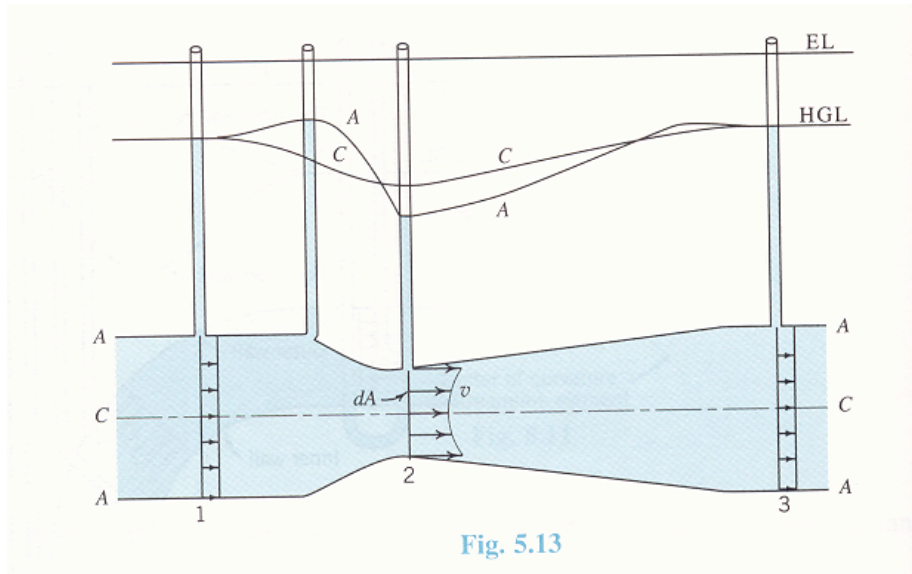
↓
Semi-quantitative (approximate) approach

- (1) Tornado or bathtub vortex: Higher pressure and lower velocity outwards from the center (Read text)
- (2) Flow in a curved section in a vertical plane (Fig. 5.12)



- gravity effect \gg centrifugal force (low velocity)
- outer wall: sparse streamlines \rightarrow lower velocity
 \rightarrow higher pressure
- inner wall: dense streamlines \rightarrow higher velocity
 \rightarrow lower pressure

(3) Flow in a convergent-divergent section



At section 2:

Center: sparse streamlines → lower velocity
→ higher pressure

Wall: dense streamlines → higher velocity
→ lower pressure

$$\frac{p_U}{\gamma} + z_U + \frac{V_U^2}{2g} = \frac{p_L}{\gamma} + z_L + \frac{V_L^2}{2g}$$

$$V_U = V_L \rightarrow \frac{p_U}{\gamma} + z_U = \frac{p_L}{\gamma} + z_L$$

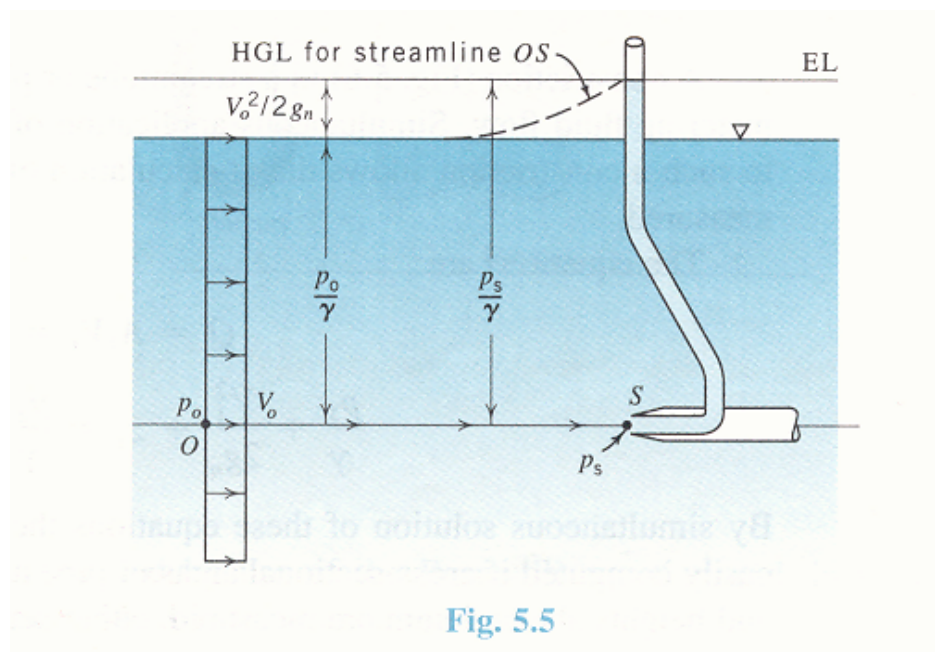
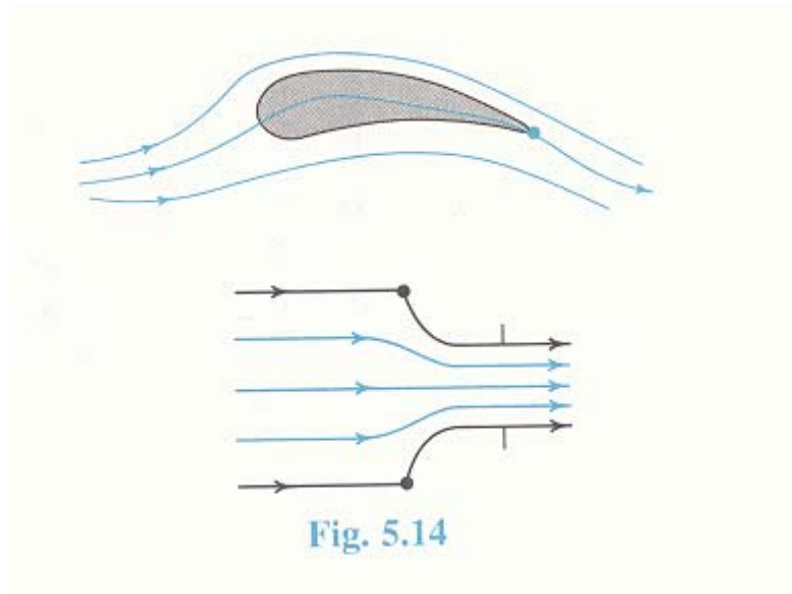
$$z_L < z_U \rightarrow p_U < p_L$$

If cavitation occurs, it will occur first at the upper wall.

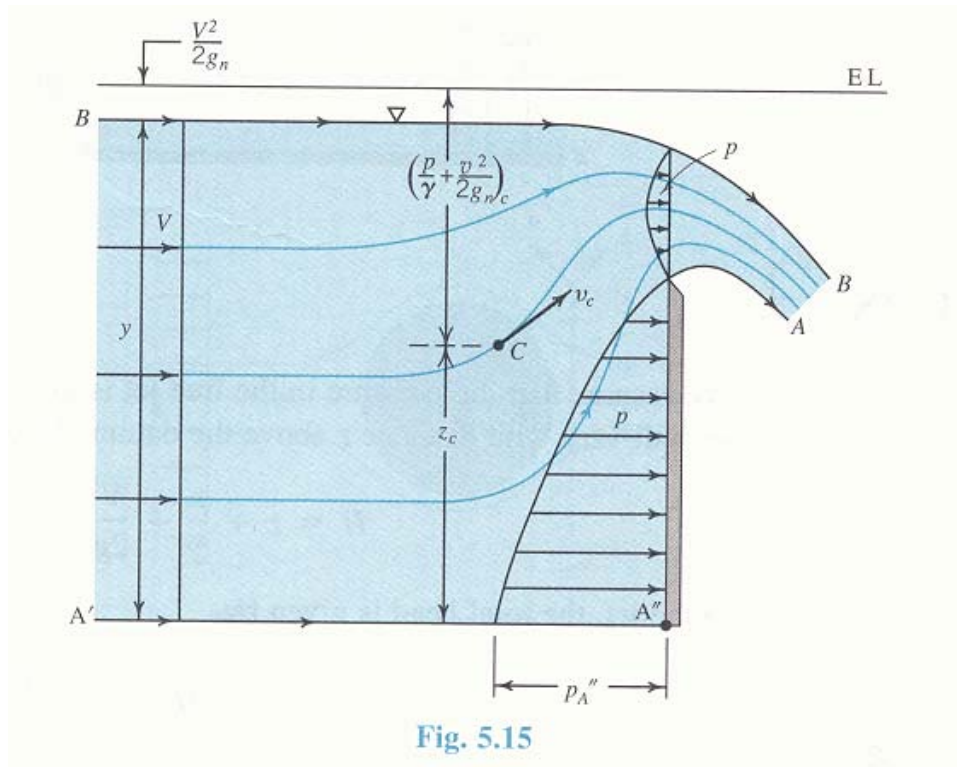
(4) Stagnation points

Sharp corner of a surface $\rightarrow V = 0$ (stagnation point)

At stagnation point, $EL = HGL (\because V = 0)$



(5) Sharp-crested weir



At upstream side, pressure is hydrostatic.

$$\therefore p_{A'} = \gamma y$$

At point A'' (stagnation point), $\frac{p_{A''}}{\gamma} = y + \frac{V^2}{2g}$

Pressure distribution above the weir:

Near free streamlines: dense streamlines

→ higher velocity

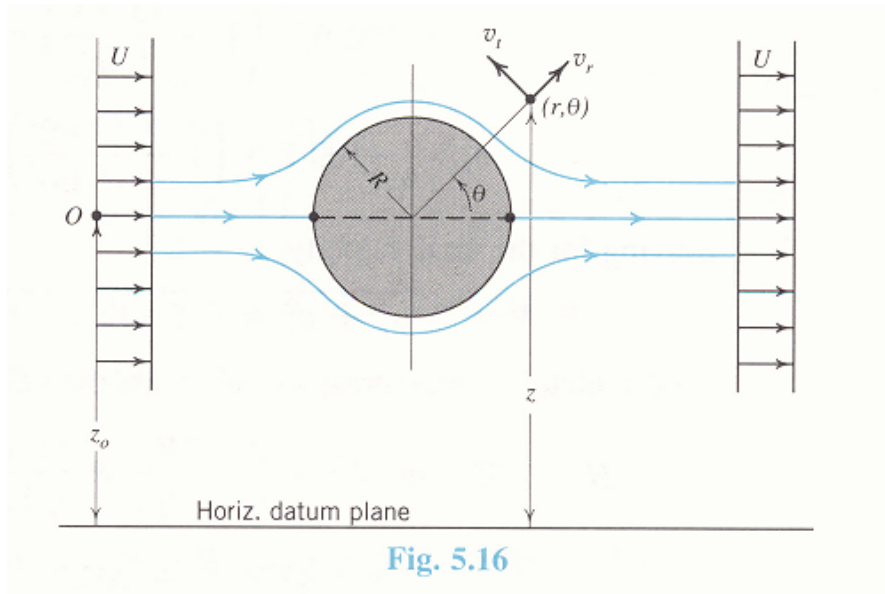
→ lower pressure

Near center: sparse streamlines → lower velocity

→ higher pressure

Note: $p = 0$ along free streamlines

(6) Flow past a circular cylinder



$$v_r = U \left(1 - \frac{R^2}{r^2} \right) \cos \theta, \quad v_t = -U \left(1 + \frac{R^2}{r^2} \right) \sin \theta$$

At windward stagnation point:

$$r = R \rightarrow v_r = 0, \quad \theta = \pi \rightarrow v_t = 0$$

At leeward stagnation point:

$$r = R \rightarrow v_r = 0, \quad \theta = 0 \rightarrow v_t = 0$$

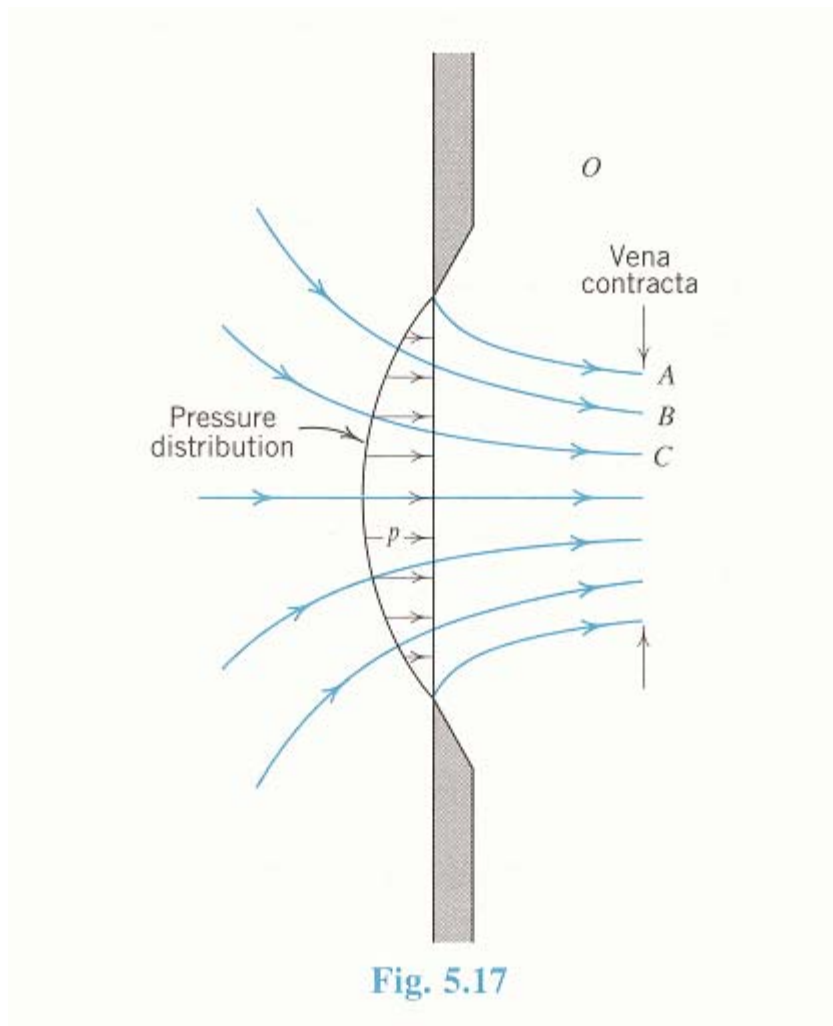
At surface of the cylinder ($r = R$):

$$v_r = 0, \quad v_t = -2U \sin \theta$$

$$\therefore \frac{p_o}{\gamma} + \frac{U^2}{2g} + z_o = \frac{p}{\gamma} + z + \frac{(-2U \sin \theta)^2}{2g}$$

$$\therefore \frac{p}{\gamma} + z = fn(p_o, z_o, U, \theta)$$

(7) Flow through an orifice

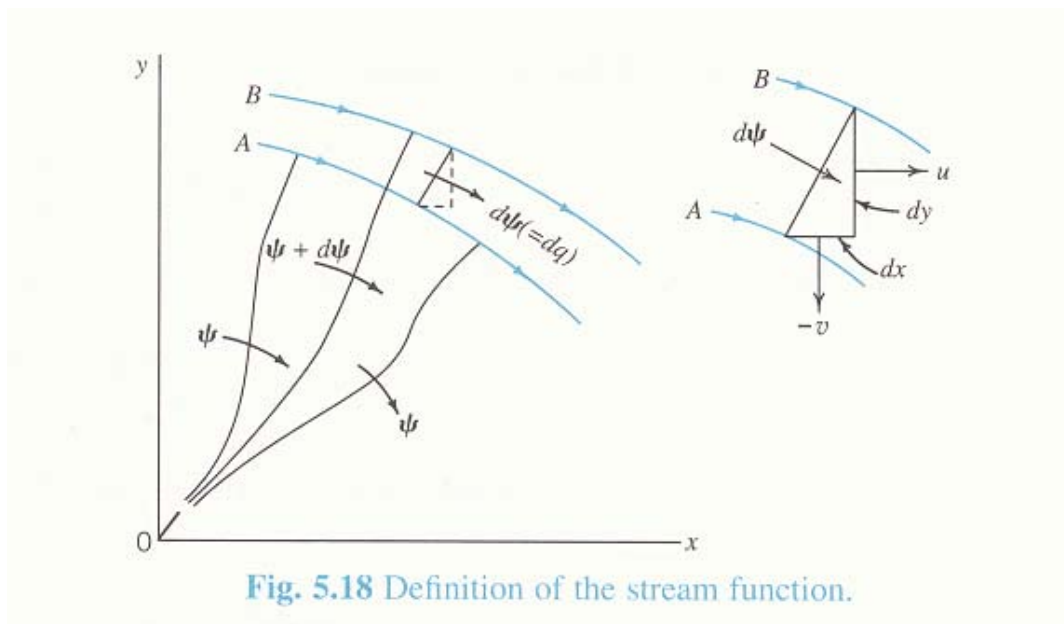


Streamlines are straight and parallel in the vena contracta. $p = 0$ everywhere in the jet, but v varies across the jet (Read page 131).

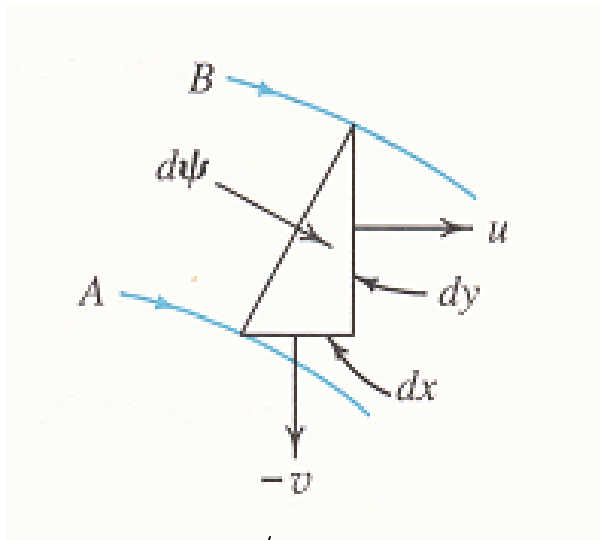
5.9 Stream Function and Velocity Potential

- Bernoulli equation \rightarrow Relationship b/w p , V and z
- z is known. Therefore, if V (u and v) can be calculated, then p can be calculated by the Bernoulli equation.
- Introduce stream function (ψ) and velocity potential (ϕ), which are related to the velocity field (u and v).
- PDE for $\psi(x,y)$ or $\phi(x,y)$ + boundary conditions \rightarrow solve for ψ or $\phi \rightarrow u$ and $v \rightarrow p$

(1) Stream function



- ψ = flowrate b/w 0 and a streamline
- Flowrate ψ b/w 0 and any point on streamline A is the same (\because no flow across a streamline) $\rightarrow \psi = \text{const}$ on streamline A
- Flowrate b/w 0 and streamline $B = \psi + d\psi \rightarrow d\psi(=dq) = \text{flowrate b/w streamlines } A \text{ and } B$



physically

$$d\psi = udy - vdx = \frac{\partial \psi}{\partial x} dx + \frac{\partial \psi}{\partial y} dy$$

by definition

$$\therefore u = \frac{\partial \psi}{\partial y}, \quad v = -\frac{\partial \psi}{\partial x}$$

$$\text{Now } \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = \frac{\partial^2 \psi}{\partial x \partial y} - \frac{\partial^2 \psi}{\partial y \partial x} = 0$$

$\therefore \psi$ (stream function) satisfies continuity equation for incompressible fluid.

$$\text{For irrotational flow, } \xi = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = 0$$

$$\text{or } \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = \nabla^2 \psi = 0 \leftarrow \text{Laplace equation for } \psi(x, y)$$

$\psi(x, y)$ can be solved with proper boundary conditions.

(2) Velocity potential

Define the velocity potential, $\phi(x, y)$, so as to satisfy

$$u = -\frac{\partial \phi}{\partial x}, \quad v = -\frac{\partial \phi}{\partial y}$$

Plug in continuity equation:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 = -\frac{\partial^2 \phi}{\partial x^2} - \frac{\partial^2 \phi}{\partial y^2}$$

$$\therefore \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = \nabla^2 \phi = 0 \leftarrow \text{Laplace equation for } \phi(x, y)$$

Vorticity:

$$\xi = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = -\frac{\partial^2 \phi}{\partial x \partial y} + \frac{\partial^2 \phi}{\partial y \partial x} = 0 \rightarrow \text{irrotational flow}$$

$\therefore \phi$ (velocity potential) is defined only in the irrotational flow.

Note:

1. irrotational flow = potential flow
(\because velocity potential exists in irrotational flow)
2. ψ satisfies continuity for incompressible fluid
 \rightarrow For irrotational flow, $\nabla^2 \psi = 0$
3. ϕ satisfies irrotationality
 \rightarrow For incompressible fluid, $\nabla^2 \phi = 0$

(3) Relationship between ϕ and ψ

$$\left. \begin{aligned} u &= -\frac{\partial \phi}{\partial x} = \frac{\partial \psi}{\partial y} \rightarrow \frac{\partial \phi}{\partial x} = -\frac{\partial \psi}{\partial y} \\ v &= -\frac{\partial \phi}{\partial y} = -\frac{\partial \psi}{\partial x} \rightarrow \frac{\partial \phi}{\partial y} = \frac{\partial \psi}{\partial x} \end{aligned} \right\} \begin{array}{l} \text{Cauchy-Riemann} \\ \text{Conditions} \end{array}$$

Streamlines ($\psi = \text{const}$) and equipotential lines ($\phi = \text{const}$) are orthogonal (Read text p. 167–168).

