

1.6 Linear ^{ODEs} Differential Eq: Bernoulli eq.

• - Linear first-order diff. eq.

$$y' + p(x)y = r(x)$$

= linear in y & y'

$$\begin{cases} r(x) = 0 & : \text{homogeneous} \\ r(x) \neq 0 & : \text{nonhomogeneous} \end{cases}$$

- General solution of LFODE

(1) homogeneous

$$y' + p(x)y = 0$$

$$\frac{dy}{dx} = -p(x)y \quad \ln|y| = -\int p(x)dx + c^*$$

$$\text{i) } y > 0: \ln y = ~~c^*~~ - \int p(x)dx + c^*$$

~~$$y = c^* e^{-\int p(x)dx}$$~~

$$y = c \exp[-\int p(x)dx] \quad c > 0$$

$$\text{ii) } y < 0: \ln(-y) = -\int p(x)dx + c^*$$

$$-y = \tilde{c} \exp[-\int p(x)dx]$$

$$y = c \exp[-\int p(x)dx] \quad c < 0.$$

* what if $c = 0$? $y(x) \equiv 0$ for all x
: trivial solution

(2) Nonhomogeneous

$$\frac{dy}{dx} + p(x)y = r(x)$$

$$\frac{dy}{dx} = r - py$$

$$(py - r) dx + dy = 0$$

$$\left[\begin{array}{l} P dx + Q dy = 0 \quad : \quad P = py - r, \quad Q = 1 \end{array} \right.$$

integrating factor F
 $* \text{always exist!} *$
 $F P dx + F Q dy = du = 0$
 $\underbrace{FP dx}_{\frac{\partial u}{\partial x}} + \underbrace{FQ dy}_{\frac{\partial u}{\partial y}} = du = 0$

$$\frac{\partial}{\partial y}(FP) = \frac{\partial}{\partial x}(FQ)$$

$$\frac{1}{F} \frac{dF}{dx} = \frac{1}{Q} \left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) = p(x)$$

$$F = e^{\int p dx}$$

$F(x)$ indeed!

Following the standard method,

$$\frac{\partial u}{\partial x} = (py - r) e^{\int p dx}$$

$$\left(\frac{\partial u}{\partial y} = e^{\int p dx} + \dots \right)$$

$$u = \int e^{\int p dx} dy + k(x)$$

$$u = \int (py - r) e^{\int p dx} dx + k(y)$$

$$\frac{\partial u}{\partial x} = \int p e$$

$$= y \int p e^{\int p dx} dx - \int r e^{\int p dx} dx + k(y)$$

$$\frac{\partial u^*}{\partial y} = \int p e^{\int p dx} dx + k'(y) = e^{\int p dx}$$

$$\int p dx e^{\int p dx} = \int p e^{\int p dx} \int p dx dx$$

$$k'(y) = 0 \quad k(y) = c$$

$$e^h - \int p e^h \cdot h dx = e^h \quad \left. \begin{array}{l} y \int p e^{\int p dx} dx - \int r e^{\int p dx} dx = c \end{array} \right\}$$

$$y \int p e^{\int p dx} dx = \int r e^{\int p dx} dx + c$$

$$e^h \int p e^h dx + c = 0$$

$$\frac{\partial u}{\partial x} = FP = (py-r)e^{\int p dx}, \quad \frac{\partial u}{\partial y} = FQ = e^{\int p dx}$$

$$\text{let } h = \int p dx$$

$$\frac{\partial u}{\partial x} = (py-r)e^h, \quad \frac{\partial u}{\partial y} = e^h$$

$$\hookrightarrow u = e^h y + k(x)$$

$$\frac{\partial u}{\partial x} = h' e^h y + k'(x)$$

$$= p e^h y + k'(x) = p e^h y - r e^h$$

$$\therefore k'(x) = -r e^h$$

$$k(x) = -\int r e^h dx + C$$

$$u = \underline{e^h y - \int r e^h dx} = C$$

$$\boxed{y = e^{-h} \left[\int e^h r dx + C \right] \quad h = \int p(x) dx}$$

Ex1. $y' - y = e^{2x}$ (1st-order!
linear!)

$$y' + p(x)y = r(x)$$

$$p = -1, \quad r = e^{2x}$$

procedure $P dx + Q dy = 0 \xrightarrow{\text{i.f.f. } \mu} F P dx + \mu Q dy = du = 0 \quad \underline{u = \text{const.}}$

Using the general solution $h = \int -1 dx = -x$

$$y = e^x \left[\underbrace{\int e^{2x} dx}_{e^x} + C \right] = e^{2x} + C e^x$$

In the textbook, interesting rule: $e^{\int p dx} (y' + py) = (ye^{\int p dx})'$ (see)

* Reduction to Linear Form. (Bernoulli Eq)

Consider $y' + p(x)y = g(x)y^a$ (a: real)
Bernoulli eq.

if $a=0$: $y' + p(x)y = g(x)$
 $a=1$: $y' + (p(x) - g(x))y = 0$ } linear
 otherwise, "not linear"
 then how? \hookrightarrow linear

set $u(x) = [y(x)]^{1-a}$

eliminate y

$u' = (1-a)y^{-a} y'$
 $y' = gy^a - py$

$u' = (1-a)y^{-a}(gy^a - py)$
 $= (1-a)(g - py^{1-a})$
 $\underbrace{py^{1-a}} = u$

$u' = (1-a)(g - pu)$

$u' + (1-a)pu = (1-a)g$: linear.

Ex. $y' - Ay = -By^2$: Logistic eq

$y' + py = gy^a$ $a=2 \Rightarrow u = y^{-1}$

$$u' = -y^2 y' = -y^2 (-By^2 + Ay) = B - Ay \quad \underbrace{y^{-1}}_u$$

$$u' + Au = B.$$

$u' + pu = r$: standard linear form

recalling that $u = e^{-h} [\int e^h r dx + c]$, $h = \int p dx$

here $p = A$, $r = B$

$$h = Ax$$

$$u = e^{-Ax} [\int e^{Ax} B dx + c]$$

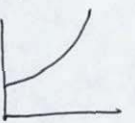
$$= e^{-Ax} (B \frac{1}{A} e^{Ax} + c)$$

$$y^{-1} = u = \frac{B}{A} + ce^{-Ax}$$

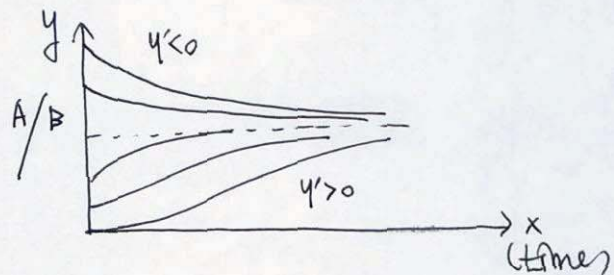
$$\therefore y = \frac{1}{\left(\frac{B}{A}\right) + ce^{-Ax}} \quad : \text{logistic law}$$

Population dynamics \Rightarrow ~~useful in~~ modeling human/animal populations

if $B > 0$. $y' = Ay$ $y = ce^{Ax}$



$-By^2$: braking term



* basic problem in nonlinear dynamics

logistic equation : $y' = f(y)$

t does not occur explicitly

\Rightarrow autonomous ODE

equilibrium solutions

$$y' = 0 \Rightarrow f(y) = 0.$$

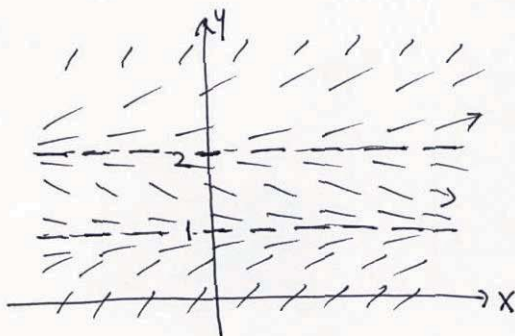
$y = \text{const.}$ \therefore zeros. : critical pts

Ex. 5. $y' = \frac{dy}{dt} = (y-1)(y-2)$

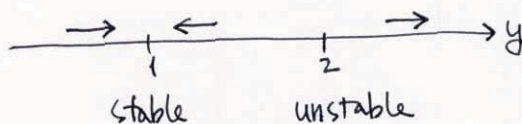
$$= y^2 - 3y + 2$$

$$y' + 3y = y^2 + 2 \quad \nsubseteq \text{Bernoulli eq.}$$

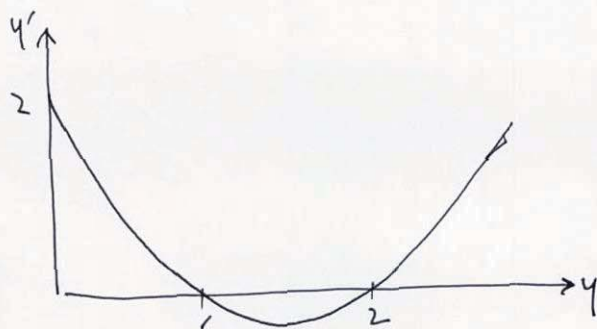
(A) Direction field



(B) Phase line

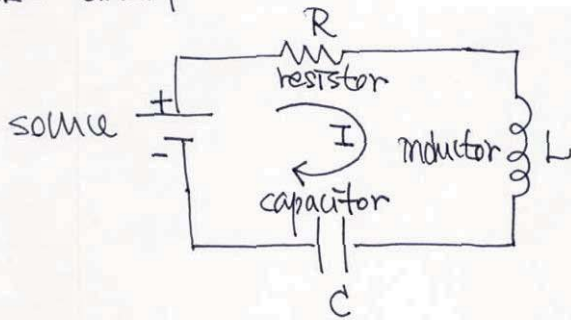


(C)



1.7. Modeling : Electric circuits *ll*

-RLC circuit

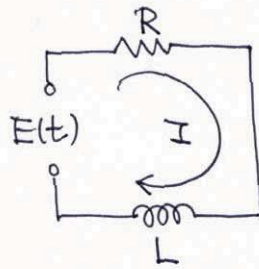


element	voltage drop
R	IR
L	$L \frac{dI}{dt}$
C	$\frac{1}{C} \int_{t_0}^t I dt$

· Kirchhoff's voltage law

$$\text{in closed loop, } \sum_i (\text{voltage drop})_i = 0.$$

Ex. 1. RL-circuit



$$I(t) = ?$$

$$E(t) = \begin{cases} \text{const} = E_0 \\ \text{periodic} = E_0 \sin \omega t \end{cases}$$

$$\text{i) modeling : } E - IR - L \frac{dI}{dt} = 0.$$

$$L \frac{dI}{dt} + RI = E(t)$$

ii) solution

$$\frac{dI}{dt} + \frac{R}{L} I = \frac{E(t)}{L}$$

∴ linear, first-order DE.

$$\text{Using } y' + p y = r$$

$$y_{qs} = e^{-h} \left[\int e^h r dx + c \right]$$

$$h = \int p dx$$

$$I = e^{-\alpha t} \left[\int e^{\alpha t} \frac{E(t)}{L} dt + c \right].$$

$$\alpha = \frac{R}{L}$$

* special case 1

$$L \frac{dI}{dt} + RI = E_0$$

$$L \frac{dI}{dt} = -RI + E_0$$

$$\frac{dI}{-RI + E_0} = \frac{dt}{L}$$

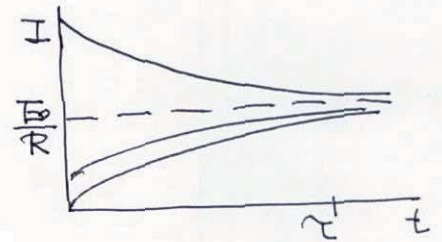
$$\frac{-R dI}{-RI + E_0} = -\frac{R}{L} dt$$

$$\ln|-RI + E_0| = -\frac{R}{L} t + c^*$$

$$-RI + E_0 = \tilde{c} e^{-\frac{R}{L} t}$$

$$RI = E_0 - \tilde{c} e^{-\frac{R}{L} t}$$

$$I = \frac{E_0}{R} + c e^{-\frac{R}{L} t}$$

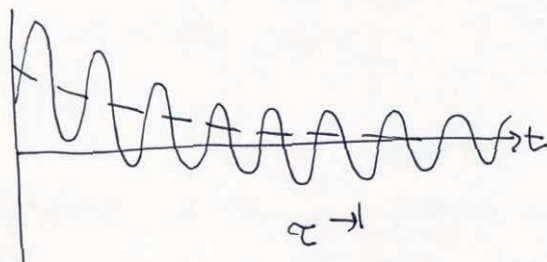


* Special case 2

$$L \frac{dI}{dt} + RI = E_0 \sin \omega t$$

$$\text{G.S. } I = c e^{-(R/L)t} + \frac{E_0}{\sqrt{R^2 + \omega^2 L^2}} \sin(\omega t - \delta)$$

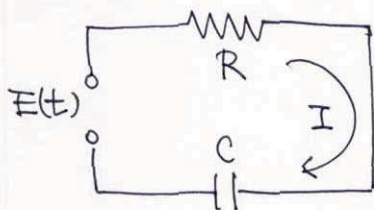
$$\delta = \tan^{-1} \frac{\omega L}{R}$$



time constant

$$\tau = \frac{L}{R}$$

Ex. 2 RC-circuit



$$I(t) = ?$$

i) modeling

$$RI + \frac{1}{C} \int I dt = E(t)$$

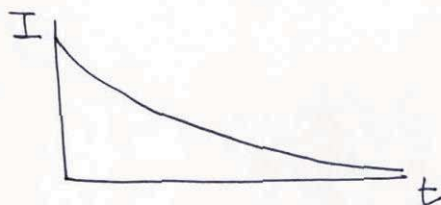
$$R \frac{dI}{dt} + \frac{1}{C} I = \frac{dE}{dt} \quad \text{linear first-order DE}$$

ii) solution

$$\text{G.S. } I = e^{-t/(RC)} \left[\frac{1}{R} \int e^{t/(RC)} \frac{dE}{dt} dt + C \right]$$

* special case 1. $E = E_0$

$$I = c e^{-t/(RC)} = e^{-t/\tau_c} \quad \tau_c = RC$$



* case 2 $E = E_0 \sin \omega t$

$$\frac{dE}{dt} = \omega E_0 \cos \omega t$$

$$I = c e^{-t/(RC)} + \frac{\omega E_0 C}{\sqrt{1 + (\omega RC)^2}} \sin(\omega t - \delta)$$

$$\delta = \tan^{-1} \left(\frac{-1}{\omega RC} \right)$$