

characteristic eq

$$\det(A - \lambda I) = 0.$$

$$\begin{vmatrix} -\lambda & 1 \\ -\frac{k}{m} & -\frac{c}{m} - \lambda \end{vmatrix} = \lambda^2 + \frac{c}{m}\lambda + \frac{k}{m} = 0.$$

§ 2. Basic ~~concepts~~ and Theory of systems of ODEs

General first-order systems

$$\begin{cases} y_1' = f_1(t, y_1, \dots, y_n) \\ y_2' = f_2(t, y_1, \dots, y_n) \\ \vdots \\ y_n' = f_n(t, y_1, \dots, y_n) \end{cases} \quad (1)$$

$$\bar{y}' = \bar{f}(t, \bar{y})$$

solution vector

$$\bar{y} = \bar{h}(t)$$

IVP - IC's

$$y_1(t_0) = K_1$$

$$y_2(t_0) = K_2$$

⋮

$$y_n(t_0) = K_n$$

$$\bar{y}(t_0) = \bar{K}$$

Theorem 1. Existence and Uniqueness

(1) $\rightarrow f_1, \dots, f_n$: continuous. $\frac{\partial f_1}{\partial y_1}, \dots, \frac{\partial f_1}{\partial y_n}, \dots, \frac{\partial f_n}{\partial y_1}, \dots, \frac{\partial f_n}{\partial y_n}$: continuous

IVP \exists unique sol.

⊗ Linear Systems

$$\begin{cases} y_1' = a_{11}(t)y_1 + \dots + a_{1n}(t)y_n + g_1(t) \\ \vdots \\ y_n' = a_{n1}(t)y_1 + \dots + a_{nn}(t)y_n + g_n(t) \end{cases}$$

$$\bar{y}' = A\bar{y} + \bar{g}$$

$$\bar{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \quad A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \quad \bar{g} = \begin{bmatrix} g_1 \\ \vdots \\ g_n \end{bmatrix}$$

homogeneous: $\bar{g} = 0$, $\bar{y}' = A\bar{y}$
 nonhomogeneous: $\bar{g} \neq 0$

Theorem 2

$$\frac{\partial f_i}{\partial y_j} = a_{ij}, \dots, \frac{\partial f_n}{\partial y_n} = a_{nn} \quad (\text{from Thm 1})$$

Ask. g_j : continuous \rightarrow unique sol.

Theorem 3 : Superposition principle

$\bar{y}^{(1)}, \bar{y}^{(2)}$: solutions of homogeneous linear system

$$\rightarrow \bar{y} = c_1 \bar{y}^{(1)} + c_2 \bar{y}^{(2)} \quad (\text{linear combination}): \text{sol.}$$

pf.) " $\bar{y}' = A\bar{y}$ "

$$\begin{aligned} [c_1 \bar{y}^{(1)} + c_2 \bar{y}^{(2)}]' &= c_1 \bar{y}^{(1)'} + c_2 \bar{y}^{(2)'} = c_1 A\bar{y}^{(1)} + c_2 A\bar{y}^{(2)} \\ &= A [c_1 \bar{y}^{(1)} + c_2 \bar{y}^{(2)}] \end{aligned}$$

BASIS / G.S / W

homogeneous system $y' = Ay$

basis: linearly independent set of n solutions $y^{(1)}, \dots, y^{(n)}$

G.S.: $y = c_1 y^{(1)} + \dots + c_n y^{(n)}$

$Y = [y^{(1)} \dots y^{(n)}]$: $n \times n$ matrix
fundamental matrix

$$\det(Y) = W(y^{(1)}, \dots, y^{(n)}) = \begin{vmatrix} y_1^{(1)} & y_1^{(2)} & \dots & y_1^{(n)} \\ y_2^{(1)} & y_2^{(2)} & \dots & y_2^{(n)} \\ \vdots & \vdots & \ddots & \vdots \\ y_n^{(1)} & y_n^{(2)} & \dots & y_n^{(n)} \end{vmatrix}$$

" $W \neq 0 \Rightarrow y^{(1)}, \dots, y^{(n)}$ basis."

2nd-order homogeneous linear diff. eq

$$y'' + p(x)y' + q(x)y = 0$$

basis: y, z

$$W(y, z) = \begin{vmatrix} y & z \\ y' & z' \end{vmatrix}$$

$\cdot y_1' = y_2$

$y_2' + p y_2 + q y_1 = 0$

$\cdot y_2' = -p y_2 - q y_1$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}' = \begin{bmatrix} 0 & 1 \\ -q & -p \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$\bar{y} = \begin{bmatrix} y \\ y' \end{bmatrix}, \begin{bmatrix} z \\ z' \end{bmatrix}$$

\therefore consistent

4.3 3.3 Homogeneous Systems with Constant-Coefficient Systems

$$\bar{y}' = A\bar{y} \quad \text{entries of } A : \text{const.}$$

Recall : $y' = ky$
 $y = ce^{kt}$

$$\therefore \bar{y} = \bar{x}e^{\lambda t}$$

$$\left[\begin{array}{l} \bar{y}' = \lambda \bar{x} e^{\lambda t} \\ A\bar{y} = A\bar{x} e^{\lambda t} \end{array} \right]$$

$$\boxed{A\bar{x} = \lambda \bar{x}}$$

eigenvalue problem
(λ : eigenvalue
 \bar{x} : eigenvector.)

Assume A has a basis of n eigenvectors $\bar{x}^{(1)}, \dots, \bar{x}^{(n)}$
corresponding to eigenvalues $\lambda_1, \dots, \lambda_n$

sol.: $\bar{y}^{(1)} = \bar{x}^{(1)} e^{\lambda_1 t}, \dots, \bar{y}^{(n)} = \bar{x}^{(n)} e^{\lambda_n t}$

$$W(\bar{y}^{(1)}, \dots, \bar{y}^{(n)}) = \begin{vmatrix} x_1^{(1)} e^{\lambda_1 t} & \dots & x_1^{(n)} e^{\lambda_n t} \\ x_2^{(1)} e^{\lambda_1 t} & \dots & x_2^{(n)} e^{\lambda_n t} \\ \vdots & & \vdots \\ x_n^{(1)} e^{\lambda_1 t} & \dots & x_n^{(n)} e^{\lambda_n t} \end{vmatrix}$$

$$= e^{\lambda_1 t + \dots + \lambda_n t} \begin{vmatrix} x_1^{(1)} & \dots & x_1^{(n)} \\ \vdots & & \vdots \\ x_n^{(1)} & \dots & x_n^{(n)} \end{vmatrix} \neq 0 \quad \neq 0.$$

Theorem 1. $y' = Ay$

if const matrix A has a linearly independent set of n eigenvectors ($Ax = \lambda x$).

$\rightarrow y^{(1)} = x^{(1)} e^{\lambda_1 t}, \dots, y^{(n)} = x^{(n)} e^{\lambda_n t}$: basis of solutions

g.s: $y = c_1 x^{(1)} e^{\lambda_1 t} + \dots + c_n x^{(n)} e^{\lambda_n t}$

Ex. 1.

$y' = Ay$. $A = \begin{bmatrix} -0.02 & 0.02 \\ 0.02 & -0.02 \end{bmatrix}$

Try. $y = x e^{\lambda t}$

$y' = \lambda x e^{\lambda t} = Ax e^{\lambda t}$

$Ax - \lambda x = 0$

$(A - \lambda I)x = 0$

To get nontrivial solutions,

$\det(A - \lambda I) = 0$.

$\det(A - \lambda I) = \begin{vmatrix} -0.02 - \lambda & 0.02 \\ 0.02 & -0.02 - \lambda \end{vmatrix}$

$= (0.02 + \lambda)^2 - 0.02^2$

$= \lambda(\lambda + 0.04) = 0$

$\lambda = 0, \lambda = -0.04$: eigenvalues

$\begin{bmatrix} -0.02 - \lambda & 0.02 \\ 0.02 & -0.02 - \lambda \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$

$\lambda = 0 \rightarrow -0.02 x_1 + 0.02 x_2 = 0 : x_1 = x_2$

$\lambda = -0.04 \rightarrow 0.02 x_1 + 0.02 x_2 = 0 : x_1 = -x_2$

take $\begin{cases} x_1=1, x_2=1 & (\lambda=0) \\ x_1=1, x_2=-1 & (\lambda=-0.04) \end{cases}$

eigenvectors $\vec{x}^{(1)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\vec{x}^{(2)} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$.

g.s. $\vec{y} = c_1 \vec{x}^{(1)} e^{\lambda_1 t} + c_2 \vec{x}^{(2)} e^{\lambda_2 t}$
 $= c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-0.04t}$

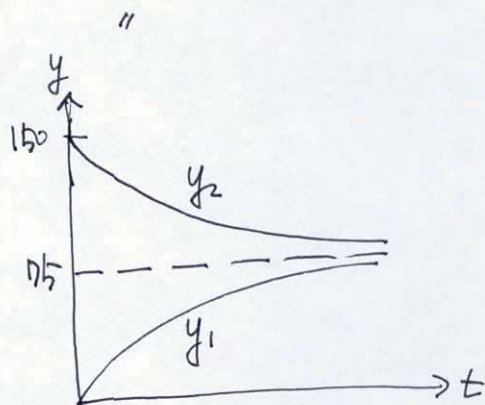
I.C. $\vec{y}(0) = \begin{bmatrix} 0 \\ 150 \end{bmatrix}$ [lb] fertilizer

$\vec{y}(0) = \begin{bmatrix} c_1 + c_2 \\ c_1 - c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 150 \end{bmatrix}$ $c_1 = 75$, $c_2 = -75$

$\vec{y} = 75 \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 75 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-0.04t}$

In components

$\begin{cases} y_1(t) = 75 - 75e^{-0.04t} \\ y_2(t) = 75 + 75e^{-0.04t} \end{cases}$

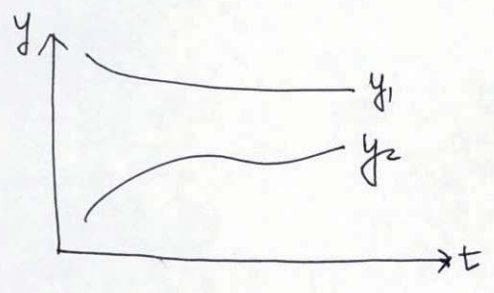


⊗ How to graph ~~plot~~ solutions in the Phase Plane

Consider $y_1' = a_{11}y_1 + a_{12}y_2$

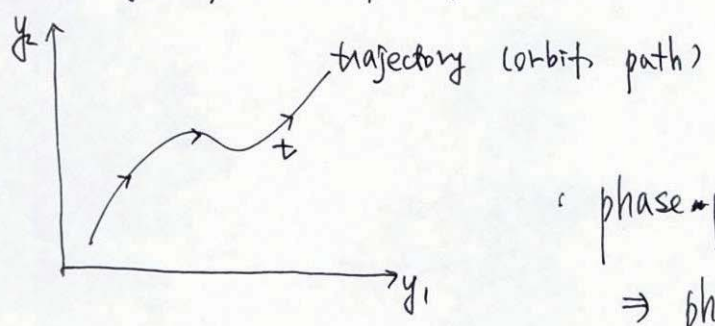
$y_2' = a_{21}y_1 + a_{22}y_2$

$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}' = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \quad \therefore \vec{y}' = A\vec{y}$



↓

y_1, y_2 -plane : phase-plane



phase-plane + trajectory
 ⇒ phase portrait

Ex. 1. Phase portrait

$$\vec{y}' = A\vec{y} = \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} \vec{y}$$

$$\text{Try } \vec{y} = \vec{x}e^{\lambda t} \Rightarrow A\vec{x} = \lambda\vec{x}$$

$$\det(A - \lambda I) = \begin{vmatrix} -3-\lambda & 1 \\ 1 & -3-\lambda \end{vmatrix} = \lambda^2 + 6\lambda + 8 = 0$$

$$(\lambda + 2)(\lambda + 4) = 0$$

$\lambda_1 = -2, \lambda_2 = -4$: eigenvalues

$$(A - \lambda I)\vec{x} = \begin{bmatrix} (-3-\lambda)x_1 + x_2 \\ x_1 - (3+\lambda)x_2 \end{bmatrix} = 0$$

$\lambda = -2$: $-x_1 + x_2 = 0$ $x_1 = x_2$ $x_1 = 1, x_2 = 1$

$$\vec{x}^{(1)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$\lambda = -4$: $x_1 + x_2 = 0$ $x_1 = -x_2$ $x_1 = 1, x_2 = -1$

$$\vec{x}^{(2)} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\bar{y} = c_1 \bar{x}^{(1)} e^{\lambda_1 t} + c_2 \bar{x}^{(2)} e^{\lambda_2 t} = c_1 \bar{y}^{(1)} + c_2 \bar{y}^{(2)}$$

$$= c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-4t}$$

$$\begin{cases} y_1 = c_1 e^{-2t} + c_2 e^{-4t} \\ y_2 = c_1 e^{-2t} - c_2 e^{-4t} \end{cases}$$

$$c_1 = 0: \begin{cases} y_1 = c_2 e^{-4t} \\ y_2 = -c_2 e^{-4t} \end{cases} > \begin{cases} y_2 = -y_1 \end{cases}$$

$$c_2 = 0: \begin{cases} y_1 = c_1 e^{-2t} \\ y_2 = c_1 e^{-2t} \end{cases} > \begin{cases} y_2 = y_1 \end{cases}$$

